



# Positive-Sum Impact of Multistakeholder Recommender Systems for Urban Tourism Promotion and User Utility

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## ABSTRACT

When a multistakeholder recommender system (MRS) is designed to produce sustainable urban tourism promotion, two conflicting goals are of practical interest: (i) to cut down the number of visitors at popular sites and (ii) to satisfy tourists' preferences, often biased towards popular sites. By modelling the tourists' limited knowledge of the visited city — an important but often overlooked detail — we simulate interactions between tourists and an MRS that jointly optimises tourist's utility and promotes less popular sites. Experiments based on data logs collected in three tourist cities reveal that such an MRS can lift tourist's utility and at the same time reduce the number of visitors at popular sites, manifesting a so-called positive-sum impact. However, a delicate balance is crucial; under- or over-promotion of unpopular sites in the recommendation lists can be adverse to both destination and tourist's utility.

## CCS CONCEPTS

• **Information systems** → **Recommender systems**; • **Computing methodologies** → **Simulation evaluation**.

## KEYWORDS

Stakeholders, Simulations, Uplift, Sustainability, Limited Awareness

### ACM Reference Format:

Pavel Merinov and Francesco Ricci. 2024. Positive-Sum Impact of Multistakeholder Recommender Systems for Urban Tourism Promotion and User Utility. In *18th ACM Conference on Recommender Systems (RecSys '24)*, October 14–18, 2024, Bari, Italy. ACM, New York, NY, USA, 6 pages. <https://doi.org/10.1145/3640457.3688173>

## 1 INTRODUCTION

In sustainable tourism promotion, destination managers aim to prevent popular points of interest (POIs) from being overly crowded [5, 15, 18]. Various urban strategies suggest to spread tourism outside the city and de-market crowded locations [16, 28]. At the same time, personalisation is a crucial criterion in any tourism promotion campaign. Motivated by these conflicting requirements, we analyse how MRSs, acting as tools to personalise information [22] and mediate the goals of multiple stakeholders [1], can generate a sustainable tourism promotion. By addressing the conflicting goals

of (i) reducing crowding at popular POIs and (ii) recommending personalised POIs to users, often biased towards popular sites, we focus on the following research questions:

- RQ1.** Is it possible to achieve a positive outcome for both goals?
- RQ2.** How can the promotion of less popular POIs impact on the destination and tourist's utility?

A direct research method would require the launch of multiple A/B online tests. Yet, deploying a system, without precise confidence on its potential negative effects, is risky. Therefore, researchers opt to pre-test it offline. The offline approach, however, has its own challenges. The key issue is that it is not straightforward to correctly estimate user response to recommended items, especially those not matching their preferences. This mismatch is inevitable when the MRS promotes less popular POIs, i.e., it favours the destination manager's stakeholder goal of reducing crowding at popular POIs.

Hence, we model and simulate user choices in response to sustainable recommendations, which include less popular POIs. To ensure reliability, we base our simulation assumptions on established marketing research literature. Our tourists/users are stochastic decision-makers who have limited awareness of the full POIs catalogue. In this setup, by using a simple (yet commonly used in industry) MRS that properly mediates the above mentioned conflicting goals, we try to spread demand outside the centrally crowded part of the city. We evaluate the impact of this MRS on tourists and destination goals, by analysing simulated tourists' choices.

The simulation approach was chosen for its versatility in testing different (what-if?) hypotheses offline. By leveraging domain knowledge about individual-level user behaviour [8, 9, 11, 29], simulations help to uncover the impact of recommendations on a population of users. In previous studies, simulations were employed to reveal long-term properties in metrics such as accuracy [32], additional consumption, profit and demand [10, 12], diversity [3, 4, 8, 9, 11], and popularity bias [35], that are not observable with a simple train-test split evaluation approach.

**First contribution.** We extend the research on MRSs with a more reliable evaluation protocol. While existing multistakeholder studies [1, 19, 24, 31] typically assess properties of the recommendations (exposure), we focus on properties of users' (simulated) choices, influenced by the recommendation exposure, and their impact on all the stakeholders. Moreover, a few existing studies on choice simulation consider the multistakeholder settings [10], and they strictly constrain the user choices to be in the recommendation lists. In contrast, we explicitly model prior user knowledge of a limited part of the catalogue, and user's propensity to keep their choice outside the recommended items (stick with their preferences). In addition, we calibrate our evaluation protocol with real data, to perform simulation bias reduction.



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RecSys '24, October 14–18, 2024, Bari, Italy  
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ACM ISBN 979-8-4007-0505-2/24/10  
<https://doi.org/10.1145/3640457.3688173>

**Second contribution.** Drawing from simulations, we provide practical guidelines for tourism destination managers. Related to our research questions, we observe that a properly tuned MRS can lift both destination management effectiveness and tourist utility. This positive-sum impact can be achieved because tourists, by means of the MRS recommendations, become aware of new and less popular (sustainable) POIs (if they were not already), and can make even better-match choices, i.e., can discover POIs with larger utility, compared to those they already know. This is an important result, since common expectation is that there is a trade-off between stakeholders and there is no room for a joint benefit, i.e., a positive sum effect. Moreover, we find that by heavily favouring only one stakeholder's goal results in either an even larger consumption of popular POIs or compromising user utility, compared to the baseline scenario where no recommendations are served at all.

## 2 METHODOLOGY

We here describe the simulation protocol, which includes: the MRS, the user-MRS interaction model, and a calibration step to adapt our protocol to a data log. The terms user, tourist, and decision-maker are used interchangeably, as are item, POI, and product.

### 2.1 Multistakeholder Recommender System

In order to generate recommendations, the MRS jointly optimises user  $n$ ,  $u_n^t = \sum_j x_j u_{nj}^t$ , and destination,  $v = \sum_j x_j v_j$ , utilities under the constraint to offer a typically small number,  $B = \sum_j x_j$ , of recommendations (also known as a bundle) per user. Here, the optimisation variable  $x_j$  equals 1 if the bundle contains item  $j$ , and 0 otherwise. The  $u_{nj}^t \in [0, 1]$  utility is a score that the MRS assigns to a particular user-item pair  $(n, j)$  based on information  $t$  about that user. We discuss later the recommendation algorithms that the MRS may alternatively use to estimate the user utility. In our experiments,  $t$  reflects the number of items (per user) for which the system has collected user feedback (preferences). The  $v_j \in \{0, 1\}$  utility is a proxy of the sustainable destination management goal. With a “vital few” 20% threshold rule — the top 20% popular items plus those located within 20% of the city centre's distance — we define a list of items,  $V_-$ , that should not be recommended ( $v_j = 0$ ). The remaining items,  $V_+$ , are considered to be sustainable and are promoted ( $v_j = 1$ ) by the MRS. Consequently, the destination stakeholder receives a positive reward when tourists choose to visit peripheral and less popular POIs.

Known in the optimisation literature as multi-objective optimisation, solutions to such a problem occupy a Pareto frontier in the Euclidean space  $(u_n^t, v)$ , and many incomparable bundles reach an optimum [17]. To recover the full Pareto frontier, in this paper we investigate a standard linear combination:

$$R_n(\lambda) = \arg \max_{(x_1, \dots, x_J) : \sum x_i = B} \sum_j x_j ((1 - \lambda) u_{nj}^t + \lambda v_j). \quad (1)$$

Parameter  $\lambda \in [0, 1]$  governs the trade-off between the two utilities: higher  $\lambda$  values favour destination utility, while lower values favour user utility. For a given  $\lambda$  the recommendation set  $R_n(\lambda)$  is obtained by sorting the items with respect to their  $(1 - \lambda) u_{nj}^t + \lambda v_j$  scores, and selecting the top- $B$  ones.

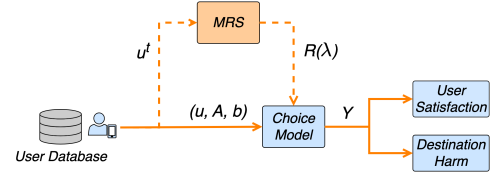


Figure 1: User choices generation and simulation protocol.

### 2.2 Interactions Protocol

In order to understand how the MRS may impact user choices, we model the system/decision-maker interaction (see Figure 1).

**User choice model.** A choice model determines how users make decisions about which POIs to visit. The model used in this paper is drawn from the marketing literature [2, 7, 23] and specifically addresses the issue of limited products awareness:

$$A_n \xrightarrow{\{P_{nj}\}} Y_n. \quad (2)$$

The fundamental premise is that user  $n$ , being initially aware only of the items in  $A_n$ , can assess the utility of item  $j$ ,  $u_{nj} \in [0, 1]$ , only if  $j \in A_n$ , and then applies a  $\{P_{nj}\}$  rule in order to make the  $Y_n$  choices. In this paper, grounded in previous research, we assume that users behave according to the well-known multinomial model:

$$P_{nj} = e^{\beta_n u_{nj}} / \sum_{i \in A_n} e^{\beta_n u_{ni}}. \quad (3)$$

This model assigns to each item in the awareness set a probability  $P_{nj}$  to be chosen. Parameter  $\beta_n > 0$  tunes how users make choices: higher values of  $\beta_n$  characterise users focusing more on items with the largest utility, while lower values characterise more exploratory (random) behaviours. If a user consumes a bundle of items, as in our scenario, the user will select the necessary number of distinct items according to this model.

**User-recommender system interactions.** Users come one after the other to the MRS (see Figure 1) and are not aware of all the  $J$  items in the catalogue (the list of all POIs): each user has only knowledge about items in his/her awareness set  $A_n$ . User  $n$  is willing to choose  $b_n$  items in  $A_n$ . This outlines a tourist who aims to visit  $b_n$  POIs, but have not yet decided which. Before these choices are made, the recommendation set  $R_n(\lambda)$  is generated. User becomes aware also of the recommended items  $R_n(\lambda)$  and makes proper choices based on their quality. User makes  $b_n$  decisions based on his/her choice model. After that we can record (simulated) choices, experienced utility (user satisfaction), and the effect of these choices on the destination stakeholder utility.

**Multistakeholder recommender system impact.** User becomes aware of the recommended items and obtains a larger pool of alternatives to choose from:

$$R_n(\lambda) \xrightarrow{\text{MRS}} A_n \xrightarrow{\{P_{nj}\}} Y_n. \quad (4)$$

To compute recommendations, the MRS approximates the true user preferences  $u_n$  with predicted ones  $u_n^t$ . Onward, the MRS solves the optimisation problem “ $(1 - \lambda) u_n^t + \lambda v$ ” to recommend a bundle that is good for both stakeholders. Hereby, there is a free parameter  $\lambda$ , which can alter user behaviour and need to be investigated.

### 2.3 Interactions Protocol Calibration

For generating reliable simulations, we need  $u_n$ ,  $A_n$ ,  $b_n$ , and  $\beta_n$  for each user  $n$ . Collecting real user preferences and awareness set data incurs significant costs. Therefore, we opt to estimate them, as  $u_n^*$ ,  $A_n^*$ ,  $b_n^*$ , and  $\beta_n^*$ , based on available tourist behaviour data.

**Data.** Our data logs consist of implicit user feedback, collected in three popular tourist cities: Rome [6], Florence [6], and Istanbul [34]. Data was gathered through two sources: Flickr<sup>1</sup> photo logs, and Foursquare<sup>2</sup> check-in logs.

Flickr data from two major Italian touristic cities, Rome and Florence, contain a temporally ordered sequence of POIs (trajectory) visited by each user  $n$ . These data logs were created in a fully automated process using geo-tagged photos from Flickr, a photo-sharing portal, and Wikipedia to gather information regarding POIs. The assumption the authors in [6] made is that photo albums populated by Flickr users implicitly represent tourist itineraries within a given city. Furthermore, these temporally ordered POIs' trajectories were independently segmented based on macroscopic user behaviour by analysing the inter-arrival time of each pair of consecutive photos taken in different POIs. Two consecutive POIs were grouped into the same segment (session) if the time distance between them was less than 5 and 6 hours in Rome and Florence, respectively. So, each user can be represented as an ordered list of sessions.

Foursquare data provide long-term history of check-ins, globally in the world, made public by the authors [34]. Within each city of interest, we consider all the temporally ordered sequences (one per user  $n$ ) of POIs check-in. Then, we cluster independently each sequence into sessions, based on 8 hours threshold distance (depicted as  $dt$  in Figure 2) between consecutive check-ins. This approach is aligned with previous research, where authors clustered Flickr data. We only consider POI categories of the type Arts and Cultural Entertainment, excluding hotels and restaurants. So, even in this case, each user can be represented as an ordered list of sessions, similar to the dataset from Flickr.

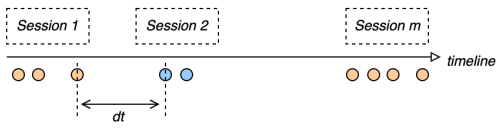


Figure 2: User trajectory segmentation schema.

**Tourists vs. locals classification.** The ordered list of sessions can be attributed to either a local resident or a tourist. Since our model focuses on tourists' behaviour, we implement a filtering strategy to separate local residents from tourists. We outline the ad-hoc behaviour discrimination rule used to identify tourists:

$$\text{tourist} = (m \leq 14) \text{ and } \left( \frac{1}{m} \sum_{i=1}^m \text{Session}[i].\text{size} > 1.25 \right).$$

Thus, tourist are those having relatively short interaction histories of  $m$  sessions in the city ( $m \leq 14$ ) and actively participate in logging their visits (we require at least 1.25 photos or check-ins

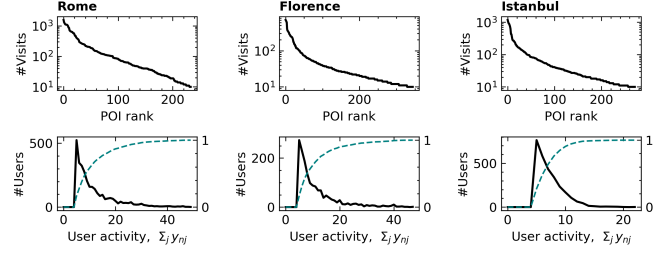


Figure 3: Tourists population-level properties.

on average in each session). Foursquare dataset is heavily biased towards locals. Hence, after applying the above mentioned filter, we were able to identify a convenient number of tourists trajectories only for Istanbul city.

Then, for each tourist in the data sets, there is a collection of visited POIs represented as a binary vector  $y_n$ , where each  $y_{nj} \in \{0, 1\}$  encodes whether or not a particular POI  $j$  was visited by user  $n$  during his/her visit in the city. Finally, in order to address data sparsity, we apply Core-5 user filtering and Core-10 item filtering for each dataset. Similar approach is prevalent in recommendation literature for implicit feedback datasets [14, 21]. Basic data statistics are presented in Table 1 and in Figure 3. In order to ensure the reproducibility, we have made our code publicly accessible<sup>3</sup>.

Table 1: Statistics regarding the three datasets.

City	Data source	#Users	#POIs	#Sessions
Rome	Flickr	3,150	234	16,857
Florence	Flickr	1,628	345	7,864
Istanbul	Foursquare	2,783	272	32,494

**Preferences estimation.** We estimate user utility  $u_n^*$  from implicit feedback [13, 20] observational data  $y_n$ . We initially considered five algorithms specifically designed for such data type: WMF [13], BPR [21], VAE [14], NGCF [33], and EASE [30]. In Section 3, is shown that one algorithm per data set is selected as providing the most reliable (with the least bias) estimate of user preferences. For all the considered algorithms the best parameters are selected with a 33/67% (per user) random test/train split. Subsequently, each algorithm is retrained on 100% data with the best-searched parameters. We rely on Cornac<sup>4</sup> framework [27] for reproducibility.

**Awareness set estimation.** The awareness set contains the items that the user knows and can choose from. We adopt the approach proposed in [9], where the authors estimate awareness set as a mixture of items that reflect user interests and popular items. We approximate user interests with observed user feedback  $y_n$ , and enlarge this set with popular items based on a  $k$  times sampling with replacement from a distribution  $\hat{p}_j \propto m_j$ , where  $m_j$  is the total number of times item  $j$  was chosen in data:

$$A_n^* = \{i : y_{ni} = 1\} \cup \{i : i \sim \hat{p}\}_{r=1}^k. \quad (5)$$

Sampling with replacement mimics how information spreads via external ad channels: the more popular an item, the more likely a user is aware about it. Parameter  $k$  — how many samples from  $\hat{p}$

<sup>1</sup><https://github.com/igobrilhante/TripBuilder>

<sup>2</sup><https://sites.google.com/site/yangdingqi/home/foursquare-dataset>

<sup>3</sup><https://github.com/pashaPASHaa/recsys>

<sup>4</sup><https://github.com/PreferredAI/cornac>

are taken — controls the size of awareness for a population of users and is not known in advance. We considered a grid of values for  $k$ , to test different regimes in our experiments.

**Calibration.** In order to ensure that the simulated users (Figure 1 schema without recommendation block) accurately represent real tourists in data logs, we set  $b_n^* = \sum_j y_{nj}$  and calibrate the choice model by maximising the log-likelihood:

$$\beta_n^* = \arg \max_{\beta_n} \sum_j y_{nj} \log P_{nj}. \quad (6)$$

In order to calibrate the parameters  $\beta_n$  that adjust the multinomial users choice model to data  $y_n$ , we solve an iterative gradient ascent optimisation problem for each user independently. For estimated user preferences  $u_n^*$  and sampled user awareness  $A_n^*$  the gradient for the  $\beta_n$  parameter is:

$$\frac{\partial}{\partial \beta_n} = \sum_{j=1}^J y_{nj} \left( u_{nj}^* - \frac{\sum_{i \in A_n^*} u_{ni}^* e^{\beta_n u_{ni}^*}}{\sum_{i \in A_n^*} e^{\beta_n u_{ni}^*}} \right).$$

We make sure, that the parameter is non-negative during optimisation. We observe (not discussed here due to space constraints, but reproducible in our code repository) a considerable heterogeneity across users in the estimated  $\beta_n^*$  values, reflecting the differences in choice behaviour.

### 3 EXPERIMENTAL RESULTS

The overall goal of our experiments is to simulate how MRSs can impact on tourist behaviour. We address RQ1 and RQ2 here. In this section, we first describe the evaluation setup and success metrics. In the second part, we report results of our simulation experiments.

#### 3.1 Setup

We investigate a range of realistic scenarios, where users have limited catalogue awareness,  $k$  ( $=4/8/\dots/20$ ), a usual condition for tourists who are visiting a city, and the MRS has only knowledge<sup>5</sup> of a small number of liked items per user,  $t$  ( $=2/3/4$ ), i.e., close to cold-start. We employ a list of recommendation algorithms in the MRS: WMF, BPR, VAE, NGCF, and EASE. They are responsible for personalisation by estimating  $u_n^t$ . Moreover, the MRS also aims to cut down crowding at  $V_-$  sites by promoting  $V_+$  sustainable sites.

**Counterfactual (what-if) experiment design.** We are interested in analysing the distribution of tourists in a city, and their experienced utility, if they are exposed to the designed MRS. We therefore sample  $N$  ( $=10,000$ ) users from a city data log in order to bootstrap a large population of tourists. We estimate  $u_n^*$ ,  $A_n^*$ ,  $b_n^*$ , and  $\beta_n^*$  for a particular value of  $k$  (see Equation 5) and preferences learning algorithm. Next, we observe these users in two parallel counterfactual universes: with and without being exposed to an MRS that operates with a particular personalised recommender system, fixed  $t$ , fixed  $\lambda$ , and recommends  $B$  ( $=8$ ) items to each user. Finally, we estimate the incremental effect (caused by the action) of applying this MRS policy on all stakeholders. See details in Algorithm 1.

**Uplift metrics.** Incremental (or uplift) metrics are a gold standard in uplift [26] and causal research [25] literature. Here, we

<sup>5</sup>Estimated  $u_n^t$  based on only  $t$  sampled choices from the set of all visited items  $y_n$

#### Algorithm 1 Procedure to simulate $(\hat{\tau}, \hat{\eta})$ uplift

**Require:**  $N = 10000$ ;  $B = 8$ ; Alist = {WMF, BPR, VAE, NGCF, EASE}  
**Require:**  $V_+ = \{i : \text{rank}(i) > 0.2J\} \cap \{i : \rho(i, \text{center}) > 0.2 \text{ radius}\}$

```

1: err ← inf
2: for RecSys in Alist do
3:    $(b_\tau, b_\eta) \leftarrow$  mean bias of RecSys w.r.t.  $\{y_n\}$  over  $k$  in  $\{4, 8, 12, 16, 20\}$ 
4:   if  $|b_\tau| + |b_\eta| < \text{err}$  then
5:     (Oracle, err) ← (RecSys,  $|b_\tau| + |b_\eta|$ )
6:
7: for  $k$  in  $\{4, 8, 12, 16, 20\}$  do
8:    $\{u_n^*, A_n^*, b_n^*, \beta_n^*\} \leftarrow$  Oracle( $\{y_n\}, k$ )
9:   for  $t$  in  $\{2, 3, 4\}$  do
10:     $\{y_n^t\} \leftarrow$  sample  $t$  choices from  $\{y_n\}$ 
11:    for RecSys in Alist \ Oracle( $\{y_n\}, k$ ) do
12:       $\{u_n^t\} \leftarrow$  RecSys( $\{y_n^t\}$ )
13:      for  $\lambda$  in linspace(0, 1) do
14:         $(\hat{\tau}, \hat{\eta}) \leftarrow$  simulate  $N$  users  $\{u_n^*, A_n^*, b_n^*, \beta_n^*\}$  at MRS( $\{u_n^t\}, V_+, \lambda$ )

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evaluate uplift metrics by comparing the simulated outcomes obtained with an MRS policy ( $\pi = R$ ) and without (also known as a control policy). Note that the control policy ( $\pi = 0$ ) runs in the same simulation environment, but does not provide any recommendations; it therefore mimics the observed user behaviour in the data. We define two uplift metrics. Let denote  $s_n^\pi = \sum_j u_{nj}^* y_{nj}^\pi$  a total user utility, and  $h^\pi = \sum_n \sum_{j \in V_-} y_{nj}^\pi$  a total destination harm, when policy  $\pi$  is employed and user  $n$  makes choices  $y_{nj}^\pi \in \{0, 1\}$ . The recommendation uplift on the population of simulated users  $\hat{\tau} = 1/N \sum_n (s_n^R - s_n^0)/s_n^0$  is the increase in experienced utility produced by the recommendations. Likewise, we define the destination uplift  $\hat{\eta} = -(h^R - h^0)/h^0$  as the reduction of visits in  $V_-$  sites during simulation period. Both  $\hat{\tau}$  and  $\hat{\eta}$ , have a “more is better” semantic.

Table 2: Bias in control policy.

City	Type	Bias $\times 100$ , mean(sd) over a grid of $k$ values				
		WMF	BPR	VAE	NGCF	EASE
Rome	$b_\tau$	-3.1(0.2)	-3.0(0.2)	-7.4(1.0)	-2.3(0.1)	-1.9(0.4)
	$b_\eta$	-1.3(0.6)	-3.1(1.1)	-0.5(0.3)	-2.5(0.9)	-0.0(0.1)
Florence	$b_\tau$	1.0(0.6)	1.9(0.5)	1.4(0.5)	-2.8(0.1)	1.5(0.4)
	$b_\eta$	0.1(0.2)	-0.7(0.3)	0.3(0.2)	-3.3(1.2)	0.5(0.3)
Istanbul	$b_\tau$	-2.5(0.1)	-1.8(0.1)	-2.1(0.7)	-3.1(0.2)	-3.4(0.9)
	$b_\eta$	-7.3(2.2)	-5.7(1.9)	-1.4(0.4)	-9.4(2.9)	-0.9(0.3)

Table 3: Experiments summary regarding the three datasets.

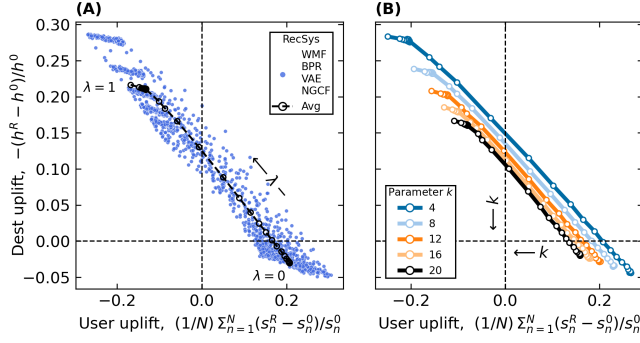
City	# $V_+$	$u_n^*$	$u_n^t$	$\mathbb{E}[\hat{\tau}   \hat{\eta} = 0]$	$\mathbb{E}[\hat{\eta}   \hat{\tau} = 0]$
Rome	117(50%)	EASE	all w/o EASE	0.155	0.131
Florence	158(46%)	WMF	all w/o WMF	0.203	0.139
Istanbul	194(71%)	VAE	all w/o VAE	0.295	0.195

**Bias in control policy.** Uplift metrics  $\hat{\tau}$  and  $\hat{\eta}$  depend on the control policy, hence such a policy must be unbiased, i.e., the calibrated multinomial choice model without recommendations, must replicate observational data  $y_n$ . Similarly to the success metrics, we define user utility bias and destination harm bias,  $b_\tau = 1/N \sum_n (s_n^0 - s_n)/s_n$  and  $b_\eta = -(h^0 - h)/h$ , with  $s_n$  and  $h$  recorded in data. Table 2 shows biases of each algorithm. Both  $b_\tau$  and  $b_\eta$  are important, for each dataset, we model tourist preferences  $u_n^*$  by using only the algorithm that minimises  $|b_\tau| + |b_\eta|$  (see Table 3).

#### 3.2 Results

Due to space limit, we comment only the results obtained with the Rome data set<sup>6</sup>. With a simulation setup explained above, we

<sup>6</sup>The results for the other two datasets are similar and are summarised in Table 2,3



**Figure 4: Rome experiments with EASE. (A) Simulated uplift scatter distribution. (B) Simulated uplift frontier for each  $k$ .**

reconstruct uplift frontiers in the space  $(\hat{\tau}, \hat{\eta})$  as a function of the  $\lambda$  parameter by probing different values for  $k$ ,  $t$ , and the recommender system used for personalisation: WMF, BPR, VAE, NGCF. In the Rome case we omit EASE in the role of recommendation algorithm, because we use it for true preferences estimation; we don't want to introduce unwanted shift in metrics due to usage of one algorithm in both roles. Selected results are presented in Figure 4 and Table 3. Because there is a significant difference in results with respect to the parameter  $k$ , the uplift frontiers are analysed both: jointly (A) and separately (B) for each  $k$ .

**Figure 4(A).** Each blue dot is a simulated uplift  $(\hat{\tau}, \hat{\eta})$  for concrete  $k$ ,  $t$ ,  $\lambda$ , and recommender system. Black dots (and their connecting line) represent averaged uplift (expected) over  $k$ ,  $t$  and recommender systems, given a fixed  $\lambda$ . Progression along the frontier, starting from the lower right corner, shows the impact of increasing the  $\lambda$  value. Position (0, 0) is the control policy uplift. Three regimes, stable with respect to  $k$ ,  $t$ , and recommender system changes, can be observed:

- (1) With small  $\lambda$  values the MRS recommends mostly  $(\hat{\tau} > 0)$  un-sustainable items that favour user utility. This leads to even worse overcrowding  $(\hat{\eta} < 0)$  of central POIs, compared to the no-recommendation case.
- (2) With large  $\lambda$  values the MRS aggressively promotes  $(\hat{\eta} > 0)$  sustainable (less crowded) but not the personalised items; hence users may behave exploratively (low  $\beta_n^*$ ), making sub-optimal  $(\hat{\tau} < 0)$  choices. Due to over-promotion, users experience less utility compared to the no-recommendation case.
- (3) With a balanced  $\lambda$  value, approx. in range  $[0.2, 0.4]$ , simulations reveal the positive-sum impact  $(\hat{\tau} > 0 \text{ and } \hat{\eta} > 0)$  that is beneficial for both stakeholders. This regime exists because users have initially limited awareness, and the MRS discovers items that are both sustainable and “good enough” for users to be considered as likely choice in the multinomial choice model.

**Figure 4(B).** The same experiment with aggregated results. To reveal expected trend, each frontier is the simulated uplift for a particular value  $k$ , averaged over the  $t$  ( $=2/3/4$ ) values and the recommender systems ( $=$ WMF/BPR/VAE/NGCF). Progression along the frontier, starting from the lower right corner, shows the impact of increasing  $\lambda$ . Position (0, 0) is the control policy uplift. Parameter

$k$ , is modelling the population awareness level, and directly impacts the effectiveness of an MRS. In fact, larger values of  $k$  leave less room for sustainable behaviour manipulation in all the observed regimes: under-, balanced- and over-promotion. Very similar results are obtained for the Florence and Istanbul (Table 3) data.

## 4 LIMITATIONS

We acknowledge that is impossible to learn a perfect model of user behaviour from implicit feedback data. As a consequence, we can not achieve zero bias in our control policy, that is, we can not precisely simulate the environment. Moreover, our assumptions about users reaction on proposed recommendations are simplified. Nevertheless, some aspects of user behaviour can be explained by our simulations. In fact, here we rely on choice models, that have been validated in the behavioural studies literature for decades. Additionally, we explicitly model users' prior knowledge of the catalogue of POIs, typically biased towards overly advertised and popular sites. Finally, to improve reliability, we calibrate our simulation protocol with real data, and perform bias reduction for each tested city. Our approach, like other offline evaluations, does not completely solve the offline-online mismatch issue. However, it improves on previous simulations in multistakeholder studies, by explicitly modelling awareness and relying on a calibrated stochastic user behaviour. In order to estimate the offline-online real mismatch, we would need to conduct online tests (A/B or user studies). This is beyond the scope of this paper.

## 5 CONCLUSION AND FUTURE WORKS

We have analysed the impact of linear MRSs, i.e., a class of recommendation models that linearly balance multiple objectives, on tourist behaviour and sustainable urban promotion. In urban tourism, a typical user has a limited knowledge of the catalogue of POIs. This important property, often overlooked in other papers, has been considered and explicitly modelled here. Moreover, with a simulation protocol, we have shown that by altering the  $\lambda$  parameter, which balances stakeholders' goals, the MRS can alter the POI recommendations, and produce a positive-sum impact (see RQ1), i.e., can benefit all the stakeholders. This is achieved by using a range of personalisation algorithms that operate close to cold-start. In addition, we have discussed the negative consequences of over-promotion (see RQ2) and concluded that the less users know about the POIs catalogue, the easier is for the MRS mediation to achieve a positive sum effect. These effects are stable with respect to the usage of alternative recommender systems and cold-start levels.

As future research directions, we highlight three aspects. Firstly, to better target a segment of tourists for a particular promotion campaign is worth analysing the variation of the positive-sum effect among different groups of tourists. Secondly, it is important to investigate alternative multistakeholder policies beyond the linear approach explored in this study. In fact, since the MRS model is an external block for our simulations pipeline, our framework can easily adopt other multistakeholder mechanisms. Third, we plan to conduct user studies to better understand the mismatch between the presented simulation and the actual user behaviour.

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