

Problem Module Iv1

General info

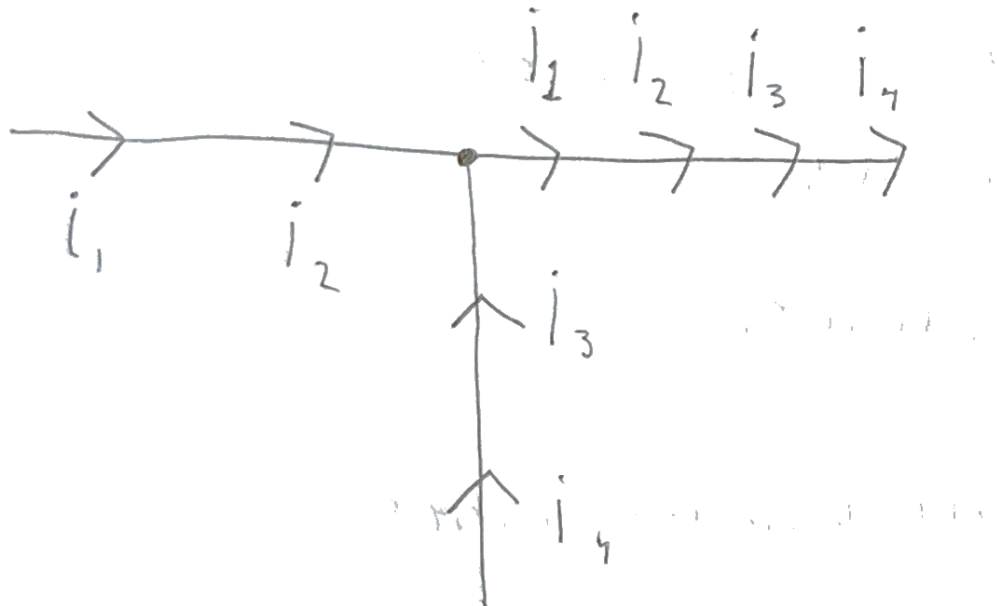
- FIRE group number 75
- module number 1
- By
 - Oskar Wallgren, 960107-2292, IT, oskarwallgren@icloud.com
 - Hugo Cliffordson, 970917-5799, IT, cliffords.contact@gmail.com
- "We hereby declare that we have both actively participated in solving every exercise. All solutions are entirely our own work, without having taken part of other solutions.
- the number of hours spent for each one of you
 - 14h
- the number of hours your group has been present in supervision for this module
 - 4h

1. Formulas Problem

- How do we know it's reasonable?
- How well can it be expected to fit with reality? (exact or aprox)
- Pythagoras theorem: $a^2 + b^2 = c^2$
 - Pythagoras theorem gets me thinking about distance between objects
 - If either a or b is 0, we end up with $a^2 = c^2$ (the same line are equal lengths) which we know to be true.
 - If we sum the quadrat of both catheters $3^2 + 4^2 = 5^2$
- Stock index = $2045 + 0.0034t$
 - since this is made up index we don't bother about the 2045 or 0.0034. What we know is that it is an approximation because we cannot predict the future. There's one unrealistic part of the equation. A stock index cannot be linear since a percental increase every year results in a exponetial curve.
- Population = $C * a^t$ where t = time in years
 - This is also an approximation since we're trying to predict the future.
 - It is realistic since it's an exponential equation and population has a percental increase every year.
- Gravity between bodies: $F = \frac{Gm_1m_2}{r^2}$
 - What this equation is telling us is that when distance increases (r^2), F decreases, when m_1 or m_2 increases, F increases. It seems realistic that the force between objects should decrease when the distance between them increases. It also seems right that the

force between objects should increase as the mass increases. We can only assume that it is exact since it's based on experiments by experienced professors and backed up by a science community.

- Newton's force: $F = ma$
 - This is an equation with existing measurable parameters that exists in time and space. Therefore we can assume it's exact. Reasonably the F should increase as both mass (m) and acceleration (a) increases. Considering the example of me pushing something. If I want it to accelerate, it's going need more force applied if it's heavier.
- Parcel max size: $100 * weight + length < 320$
 - We know the equation is reasonable as a parcel has a measurable weight and a length. The constant multiplier also seems reasonable as we then exclude something with extreme low weight and then large length.
 - It's an exact equation as the parameters are measurable.
 - This is a linear equation.
- $presentStudents + absentStudents = allStudents$
 - We know this is true as students can only exist in two states, present or absent. The sum of these are all students.
 - It's an exact equation as we can count the number in each group.
- Electric current: $I_1 + I_2 + I_3 = 0$ in a circuit knot
 - This feels reasonable as we assume current are preserved and that the input are constants. Since the current entering is positive and the current leaving is negative and we know that the parameters are constant. The sum of all current will be equal to zero.



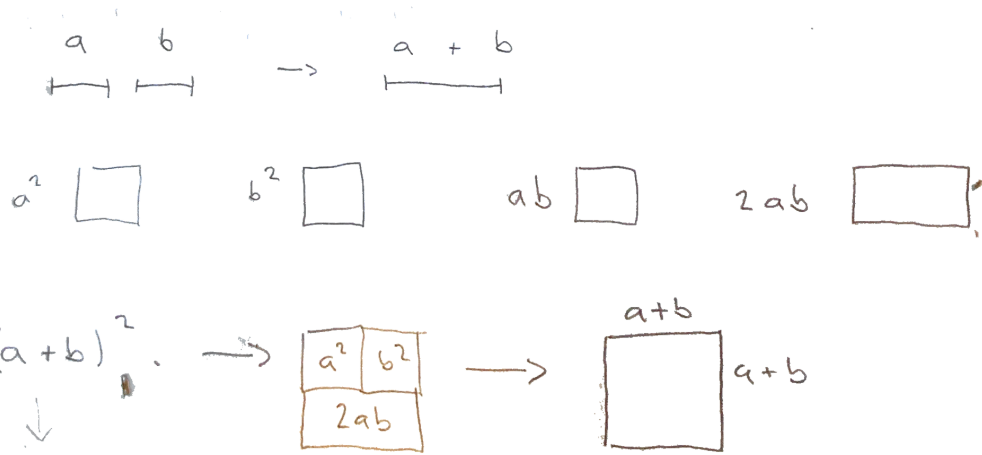
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- An exact equation as long as we assume that it's preserved
- Insurance rebate in percentage = $insurances * 2 + 0.2 * \min(7, \text{years customer})$
 - Given the standard case with one insurance and 7 as a multiplier we get 3.4% rebate. As the description says, a good customer should get a lower rate. But a one year customer

gets a lower rate than a 30 year old customer according to this equation, which seems wrong.

- It's an exact equation as we're working with measurable parameters.
- Linear equation

- $(a + b)^2 = a^2 + 2ab + b^2$

- This is realistic with this image as proof and if one or both of the parameters are zero. The corresponding expression remains true.



- It's an exact equation as parameters are measurable
- this is a quadratic equation

- $A \geq 0.8L * I$ (dimensioning requirement for 12V cables if you have a current $I[A]$, cable length $L[m]$ and cable area $A[mm^2]$)

- It's reasonable that we need more cable area if length of the cable increases. It's also reasonable that we need a thicker cable if current increases and therefore more cable area.
- We feel it's more of an approximation than an exact equation because to get the area of a cylinder, we would need to involve π . 0.8 is an approximation.
- This equation is linear because we have two unknown

- air drag force = $C * v^2 * A$

- it's reasonable that drag increases as both velocity and cross section area increases. The same as feeling more air force drag with hand opened than closed. It's also reasonable that we would need a constant as shape of the object has an impact on the air force drag.
- This seems like an approximate equation as the equation is very simple and a calculation like this should be more advanced. Especially considering the shape of the object.
- this is a quadratic equation.

- $weight = C * length^3$ (the constant C should be chosen depending on type of object e.g. persons, dogs, cars)

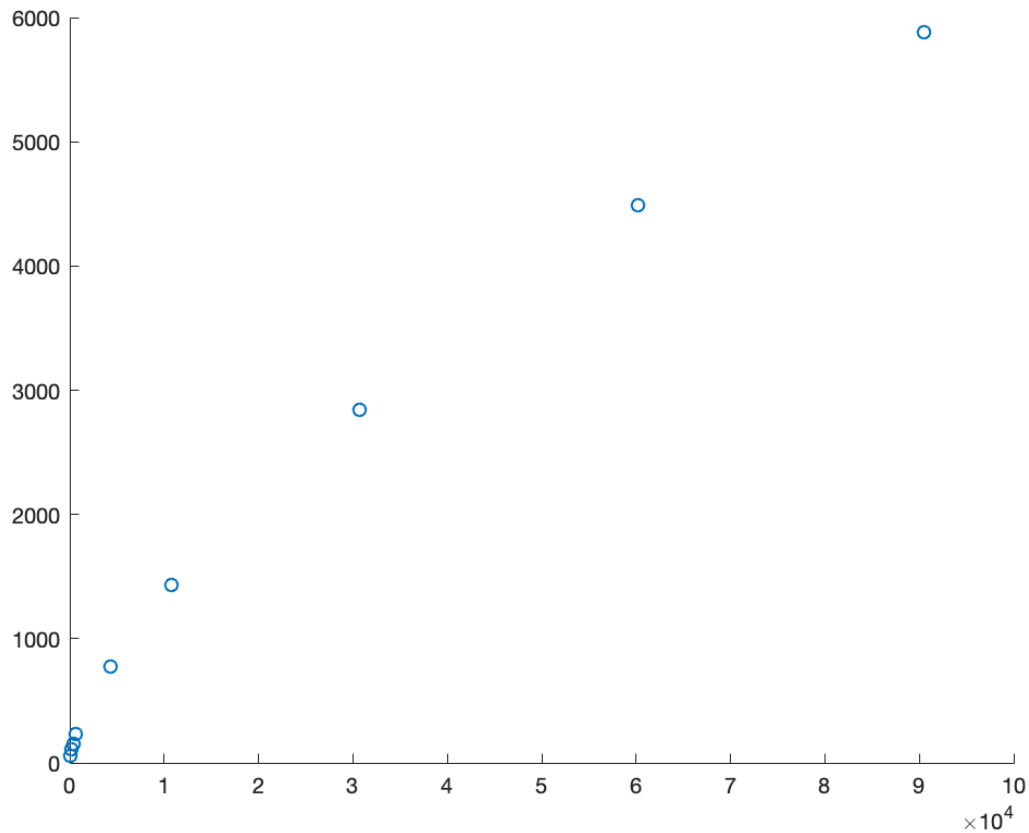
- Feels like a weak estimate of a weight. Especially considering the constant C. For example. compare a chihuahua and a pug. They are both the same length but obviously not the same weight.
- Since the length is cubed, the weight will have a large variance for change in length.

- $P[\text{getting heads when tossing a coin}] = 1/2$

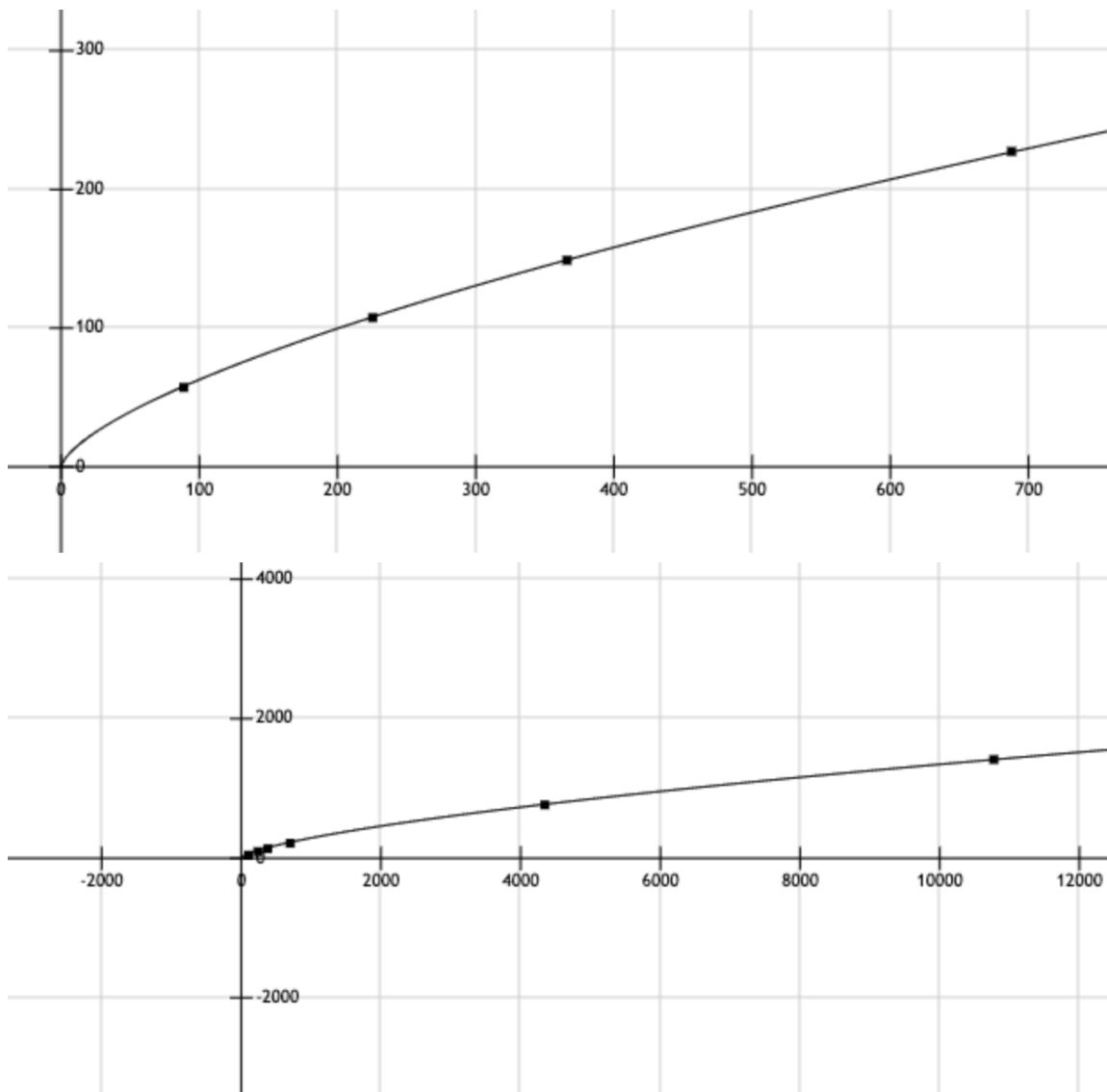
- This we know to be true as long it is a fair coin. It has two sides with equal chance of getting chosen. Since we're dealing with probability, testing this out would probably not result in a 50/50 result. But as sample size increases we would get closes to $1/2$.

2

Plotting the points in a graph we get:



- By looking at the data in the plot we noticed that a linear equation would not do. By regonizing the patterns of the data plots we tried plotting functions on the form $y = C * x^a$
- We noticed that the functions we tested followed the data points rather well. So we created an equation system using distance as the value y and time as the value for x and solved it for C and a .
- C resulted in 2.94136 and a resulted in 0.665185.
- By plotting the function $y = 2.94136 * x^{0.665185}$ with the data points we can see that the model is highly accurate.



- The deviations from the known entries are small when using the model and since the data is not that proportional the deviation can be justified. Getting the distance from only the parameter time will lead to some deviation.
- We are confident that model could calculate the distance given other values of T that are not in the table. There would still be a deviation in accuracy especially when the t increases.

3 Pendulum

We're thinking that the period should only be affected by length of the rope L and the acceleration which is gravity in this case g . It is not affected by drop angle because a larger drop angle would give it more speed but more distance to cover, in comparison with a small drop angle which has a low speed but also less distance to cover. Reasonably then time T is an expression dependent on L and g . The mass is also a parameter that doesn't affect the period as a large mass gives it more speed on the way down but then also slows it down more on the way up. This can also be backed up by this equation.

$$\text{We know that } F = mg \text{ and that } F = \frac{mL}{T^2}.$$

$$\text{Setting these equal to each other we get: } mg = \frac{mL}{T^2}$$

$$\text{Resulting in: } g = \frac{L}{T^2}$$

g is only affected by length L and time T . This results in the expression for T

$$T^2 = \frac{L}{g} \Rightarrow T = \sqrt{\frac{L}{g}}$$

If we do a dimensional analysis of this we know that g is in the unit form m/s^2 and that L is m . This means that we get $T = \sqrt{\frac{m}{m/s^2}}$. Cross out the m and we get $T = \sqrt{s^2} = s$.

Let's try an experiment. Dropping with a line length 1 we get that

$$T = \sqrt{\frac{1}{9.82}} = 0.32 \text{ seconds.}$$

Then we tried with a physical pendulum and got the time 2.6 seconds.

Let's try another one, this time with $L = 0.5$

$$T = \sqrt{\frac{0.5}{9.82}} = 0.23 \text{ seconds}$$

testing this again with a physical pendulum we got 1.83 seconds. To get this right we need a constant.

$$T = C * \sqrt{\frac{L}{g}}$$

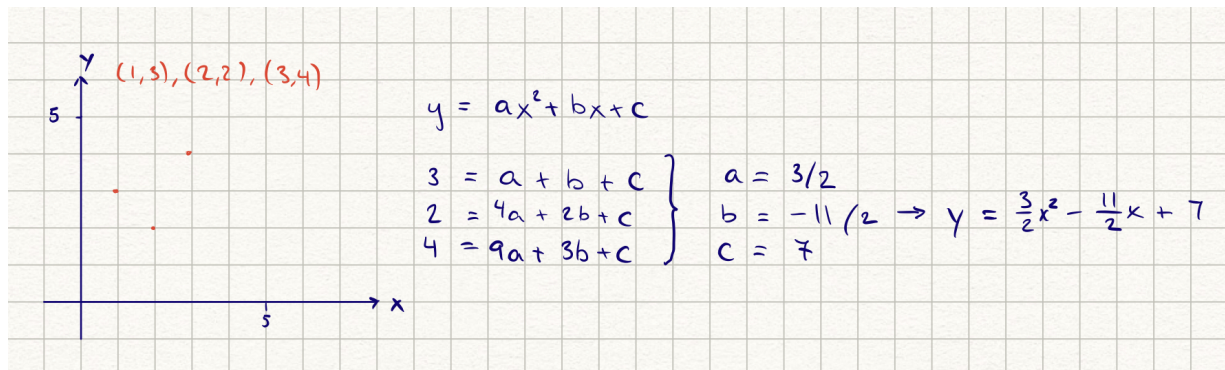
$$2.6 = C * \sqrt{\frac{1}{9.82}} \text{ and } 1.83 = C * \sqrt{\frac{0.5}{9.82}}$$

For the first equation we get $C = 8.15$ and the second we get $C = 8.11$. This gives us this approxiamte equation

$$T = 8 * \sqrt{\frac{L}{g}}$$

4 Bicycle Breaking Problem

a)



With a simple equation system we get an equation that fits the points. But when adding $(4, 5)$ we see that it doesn't fit the curve of the function anymore. We would have to redo all the work and create another equation. This would have to be done for all new points pivoting from the function curve.

Least squares method

The least squares method takes the error from each points in relation to the line, squares each error and then adds them all together. The "error" in this case is each point's y -distance from the linear approximation.

The least square method is only useful when we have more data points than parameters, that is, when we have a overdetermined system because it gives an approximation to a system that rarely has a solution. When the data points are too inconsistent and more than the parameters, we get this overdetermined system that has to be approximated to be described. If the case were that we had fewer data points than parameters, the system becomes under constraint and we would have an infinite number of solutions to describe it. Therefore making an approximation using the least squares method meaningless.

The Mathematica Fit function finds the line that best fits the data.

b)

To fit the points we use the formula for $\hat{Y} = \beta_0 + \beta_1 x$

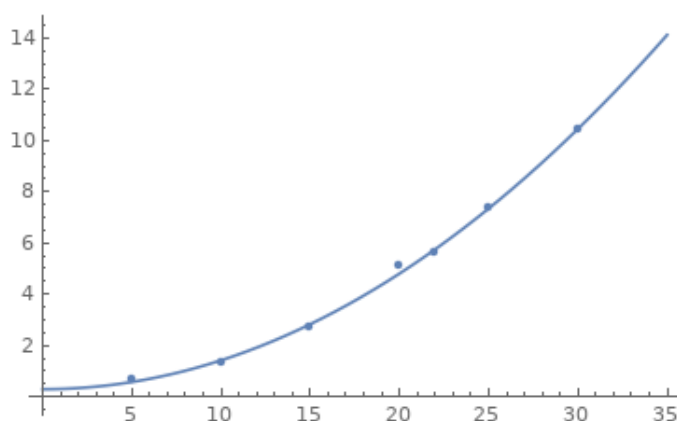
$$\beta_1 = \frac{n \sum^n xy - \sum^n x \sum^n y}{n \sum^n x^2 - (\sum^n x)^2}$$

$$\beta_0 = \bar{Y} - \beta_1 \bar{x}$$

This gives us the values $\beta_1 = 0.39$ and $\beta_0 = -2.34$.

We believe the quality of the model is acceptable considering the approximation is done with a linear equation. We know that this is a good way to get a good linear approximation. However because it's linear there can be large deviations.

We start by plotting the points in a coordinate system. Instantly we feel that a quadratic equation would fit these points better. To find this equation we use mathematica Fit function and get the result $0.28612 - 0.000305635x + 0.0113034x^2$. We can motivate that this approximation fits better than the linear .with the least squares method. We see that the least squares sum for a quadratic equation is less than for a linear.



As the image shows, a quadratic fit is much better than a linear fit.

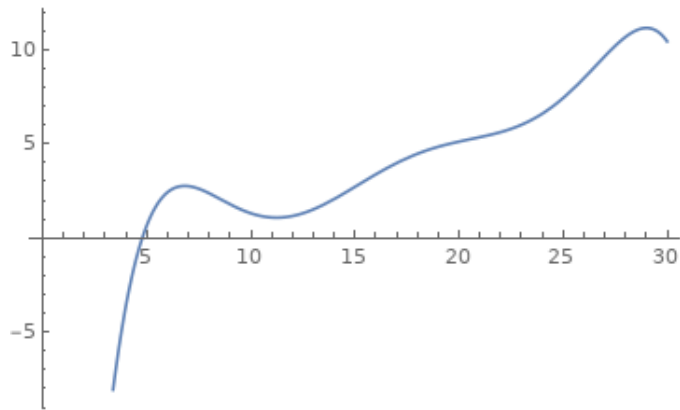
Since the data is somewhat inconsistent between two points, it's hard to find a function that fits all points exactly. However, our model does a pretty good job. Because most points in the table are consistent with our model, we can assume that it also is reliable for new points with small deviations. Conclusion is that there is a correlation between speed and breaking distance on a bicycle and that it is exponential.

5 Splines

a)

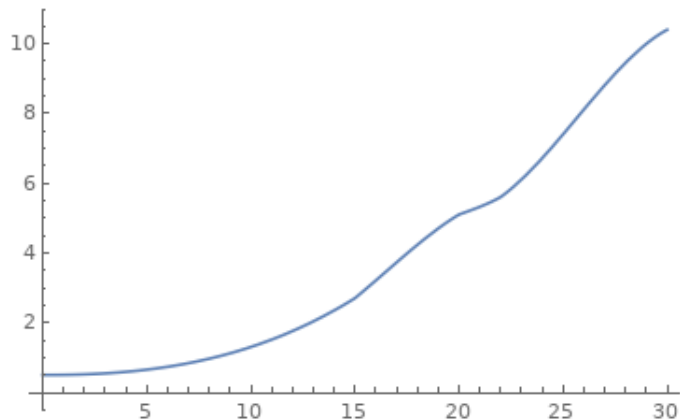
Because we have seven data points we will reasonably need 7 unknown variables like $y = ax^6 + bx^5 + cx^4 + dx^3 + ex^2 + fx + g$ and therefore an equation with degree 6. When we try this in mathematica with the function Fit we get the equation

$$-80.371 + 39.4161x - 7.19884x^2 + 0.64613x^3 - 0.0304009x^4 + 0.000720529x^5 - 6.77965 * 10^{-6}x^6$$



b)

The result looks like this.



The idea of spline interpolation is to describe the data points with concatenated functions. If some points in the dataset could be described by a simple low order function but some points after these points cannot, the idea is to create separate functions that bridges the gap of inconsistency that is between the two data points, creating a smooth curve that can describe all these datapoints.

Since spline interpolation can create different functions between data points, the functions used would be of a lower order than if we were to describe them with a single polynomial series. The resulting curve will also be smoother than if a polynomial series of a high order was used. It also seems it is better for evaluating values not in the table entries.

c)

Two situations: Many accurate data points, few low quality data points.

We first consider the situation with many accurate data points. If we use exact curve fitting we will get a very advanced function of a really high order. If we use least squares method we will get an approximation which would deviate more but more accurately describe data points that are outside

the table. If the data quality is high and the use of the data is of great importance it seems reasonable to prioritize accuracy (splining) more than approximation (least squares). However, if the data points are of low quality, an approximation seems more justified as long as there is some consistency within the data.

If we have fewer data points it is not as obvious which is better. Let's consider the situation with three data points. If the points are in a triangle a linear approximation would have a large deviation and tell very little about any possible pattern. Here, exact curve fitting could tell more about missing data.

6 Surprise

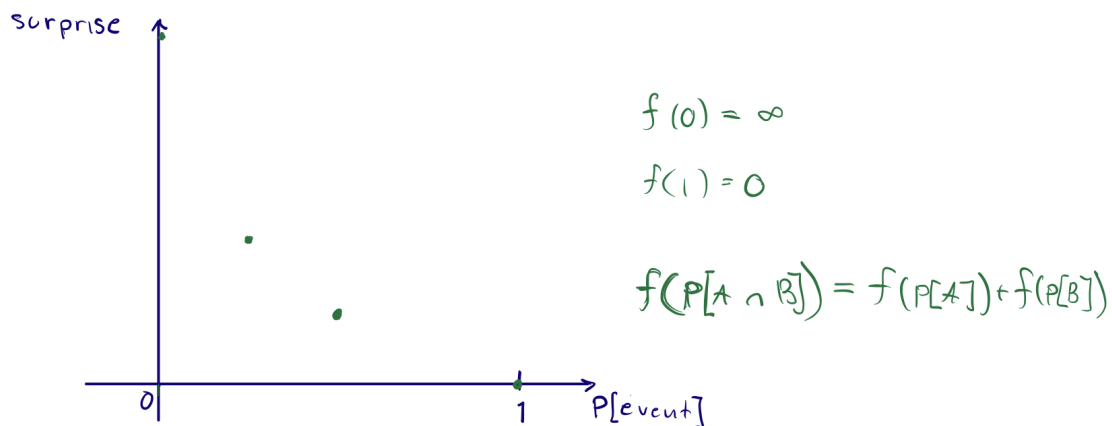
a)

The level of surprise is going to start from "not surprised at all" to an extreme level of surprise. The function should reasonably return 0 in the event of "not surprised" level from an event that is 100% chance of happening. Example: $P[\text{getting heads or tails when flipping a coin}]$. However we believe that it doesn't exist a maximum level of surprise with the philosophy "one could always be more surprised".

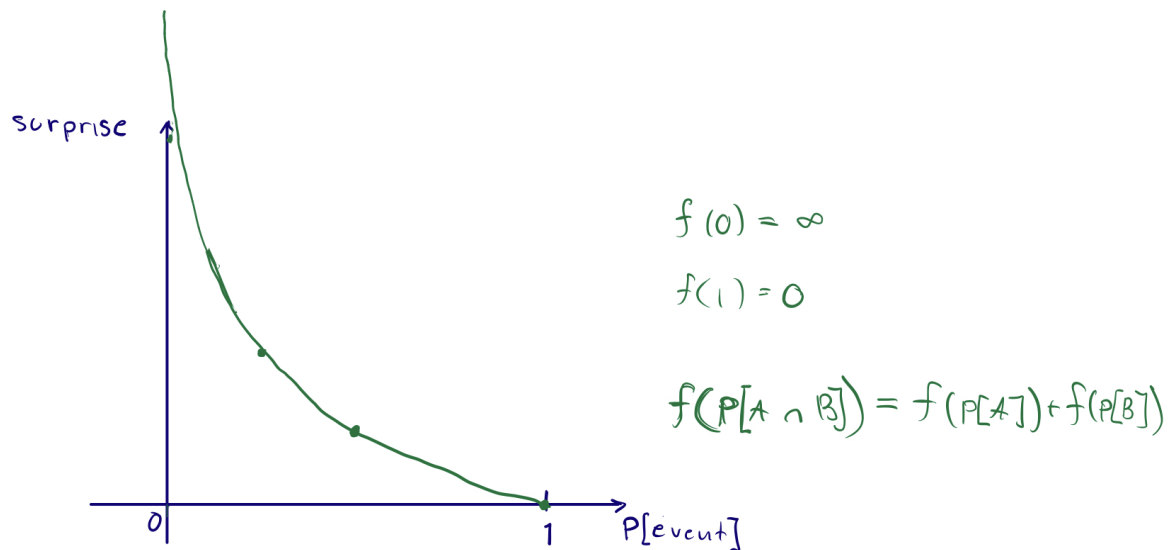
The function for surprise should return a high value for a low input, something that is unlikely should lead to a bigger surprise. We first believed that the relation should be linear, that only the unlikelyness determines the surprise in a linear relation. However there are a lot of factors making us believe that the function should not be linear. Given the example that something unlikely happens to you and that we would expect a big surprise, that doesn't say that this unlikely event haven't happened to you many times before. Therefore the surprise might not be as high as one might think.

b)

Considering the graph we these few examples for one and two events with probability 50%.



You can see in this figure that the points don't follow a linear model. We know as the figure says that $f(0) = \infty$, that $f(1) = 0$ and that $f(P[A \cap B]) = f(P[A]) + f(P[B])$. With these we try different points and plot them in a graph. When we connect the points we get something like:



. The only function we can find that fulfill all these criteria is $\text{surprise}(p) = -\log(p)$. This makes sense as we know according to the logarithmic law $\log(a * b) = \log(a) + \log(b)$. and that $\log(1) = 0$ and $\log(p)_{p \rightarrow (-0)} = \infty$.

Reflection module 1

I. WEEKLY MEETING AND FOLLOW-UP LECTURE

a) Did you have your compulsory weekly meeting with a supervisor?

Yes, we attended a supervision twice during the week and discussed our methods for approaching the solution.

b) Did both of you attend the compulsory follow-up lecture? If you already talked to us about this, please explain.

Yes we did attend the follow-up lecture. At this lecture we learnt that there is no "right" answer but rather good techniques to use to get a qualitative conclusion to a question. We also learnt how to reflect on the process of solving the problems.

c) If you were asked to talk to a supervisor about the main submission, who did you talk to?

Due to changes in schedule and late feedback on the module we have not had time to talk to a supervisor about problem 1 and 6.

II. WHAT DID YOU EXPERIENCE AND LEARN?

From the first problem we were introduced to a new way of approaching well known formulas and think about them in a different way. We learned to prove and justify the equations and formulate arguments based on proof and logic to back these up. We learned to think twice about what it actually means if something is exact or if it is an approximation.

For problem two we used mathematica to plot points in order to find a correlation between data points. This problem taught us to use mathematica functions combined with past experience in plotting curves and use a system of equations to find the curve that fit the points perfectly.

In the next problem we learned how powerful dimensional analysis can be and that it's mostly easy to use. We also learned what is meant by a period in a pendulum.

The Bicycle Breaking problem was a relatively easy problem with focus on finding correlation between data points that don't necessarily fit a simple curve. We noted that there are several ways to find a "solution" to the problem. But just because one finds a solution, doesn't mean it's the best one.

The surprise problem was mostly time spent discussing how to interpret a personal reaction mathematically. We learned from the follow up lecture that this is a question with several "right" answers as we ended up with a different one than from the lecture. What we should have done here though is to start by setting up a graph before trying to discuss the requirements of a function.

As this was the first module, most time was spent interpreting both the question and coming up with a method that is within boundaries for the task. It's was easy to fall back into old math-habits but we eventually found a way to approach the problems in an effective way.

III. HOW WELL DID YOU SOLVE THE PROBLEMS?

We believe that we solved the problems good. We always read the instructions thoroughly and discussed before trying to actually solve it. Many times we tried one thing and on the way found a better way of doing it. We solved all the questions to the best of our ability and made sure to answer all the parts of the problem.