



BIOMEDICAL IMAGE ANALYSIS IN PYTHON

# **Intensity Values**

Stephen Bailey Instructor



#### Pixels and voxels

- Pixels are 2D picture elements
- Voxels are 3D volume elements
- Two properties: intensity and location





#### Data types and image size

Array's data type controls range of possible intensities

Data Type	Range	No. Values
uint8	0, 255	256
int8	-128, 127	256
uint16	0, 2 <sup>16</sup>	<b>2</b> <sup>16</sup>
int16	-2 <sup>15</sup> , 2 <sup>15</sup>	<b>2</b> <sup>16</sup>
float16	~-2 <sup>16</sup> , ~2	>>216
	16	

```
import imageio
im=imageio.imread('foot-xray.jpg')
im.dtype
    dtype('uint8')

im.size
    153600

im_int64 = im.astype(np.uint64)

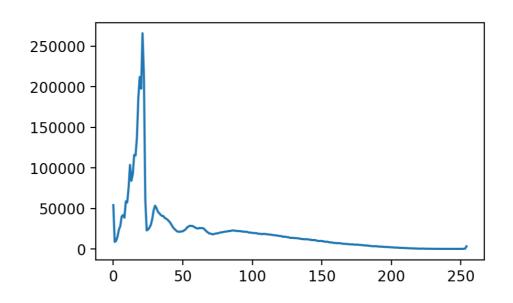
im_int64.size
    1228800
```



#### Histograms

- Histograms: count number of pixels at each intensity value.
- Implemented in scipy.ndimage
  - higher-dimensional arrays
  - masked data
- Advanced techniques and functionality in scikit-image.

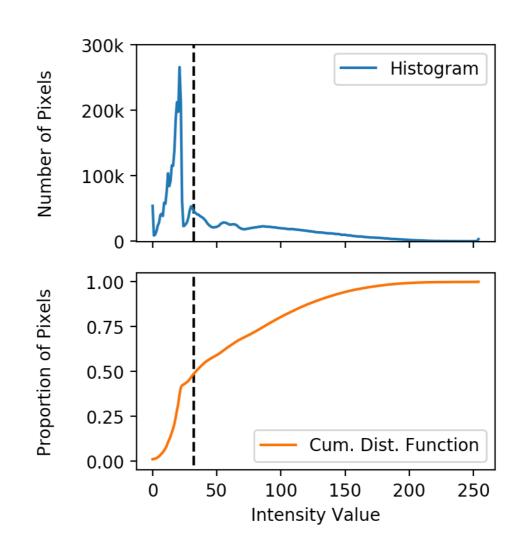
```
plt.plot(hist)
plt.show()
```





#### Equalization

- Distributions often skewed toward low intensities (background values).
- **Equalization**: redistribute values to optimize full intensity range.
- Cumulative distribution function:
   (CDF) shows proportion of pixels in range.

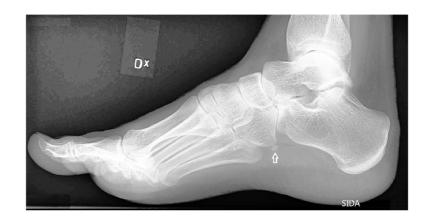




#### Equalization

```
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im)
axes[1].imshow(im_equalized)
plt.show()
```









# Let's practice!





#### BIOMEDICAL IMAGE ANALYSIS IN PYTHON

### Masks

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### Masks

#### Raw image

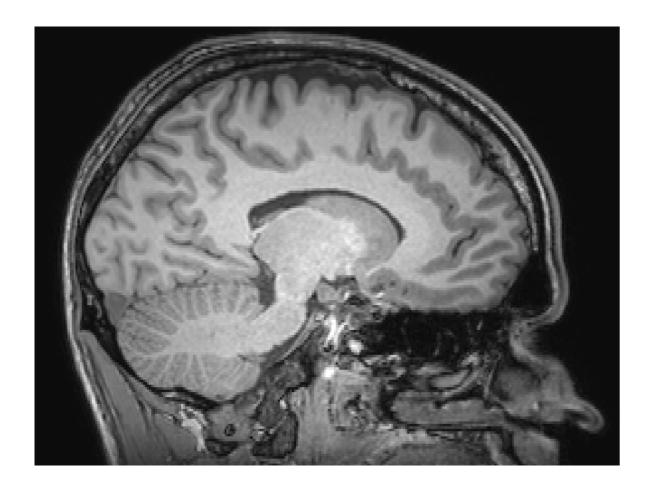


Image mask





#### Creating masks

Logical operations result in True / False at each pixel

#### Sample Operations

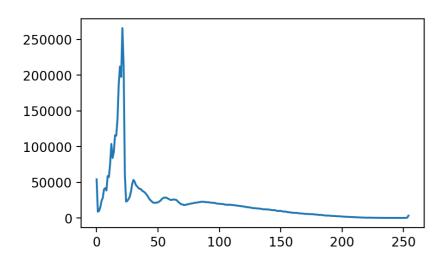
Operation	Example	
Greater	im > 0	
Equal to	im == 1	
X and Y	(im > 0) & (im < 5)	
X or Y	(im > 10)   (im < 5)	

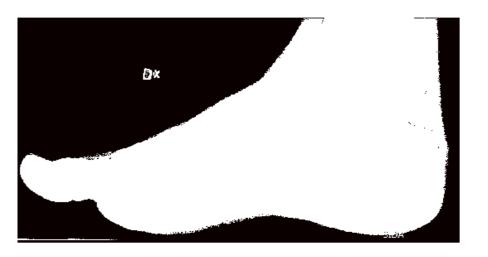


### Creating masks

hist=ndi.histogram(im, 0, 255, 256)



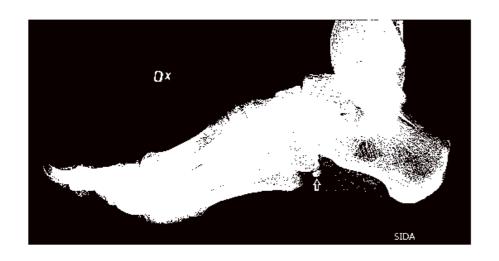






# Creating masks

```
mask2 = im > 64
```



 $mask3 = mask1 \& \sim mask2$ 





#### Applying masks

np.where(condition, x, y): control what data passes through the mask.

```
import numpy as np
im_bone = np.where(im > 64, im, 0)

plt.imshow(im_bone, cmap='gray')
plt.axis('off')
plt.show()
```

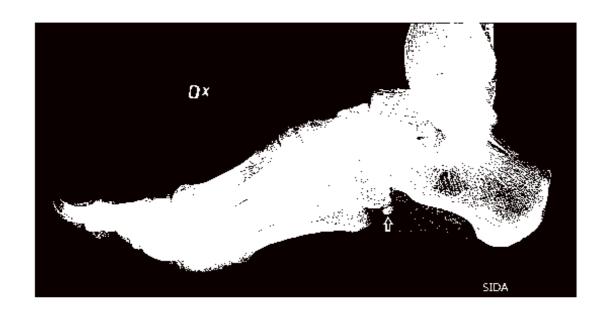




## Tuning masks

```
m = np.where(im > 64, 1, 0)
```

ndi.binary\_dilation(m,iterations=5)







# Tuning masks

ndi.binary\_erosion(m,iterations=5)







# Let's practice!





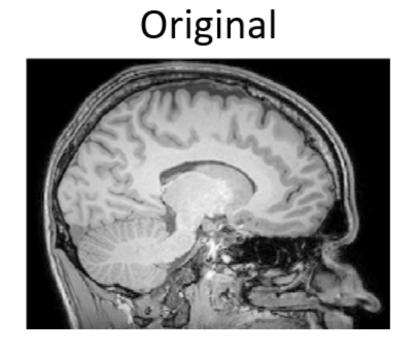
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### **Filters**

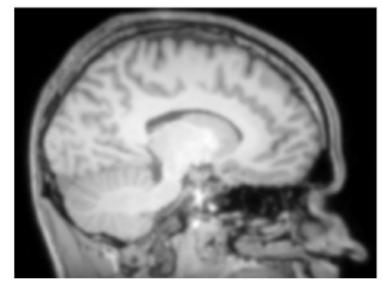
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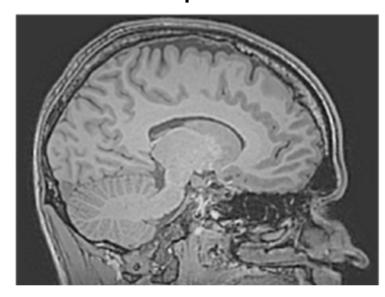
#### **Filters**



Smoothed

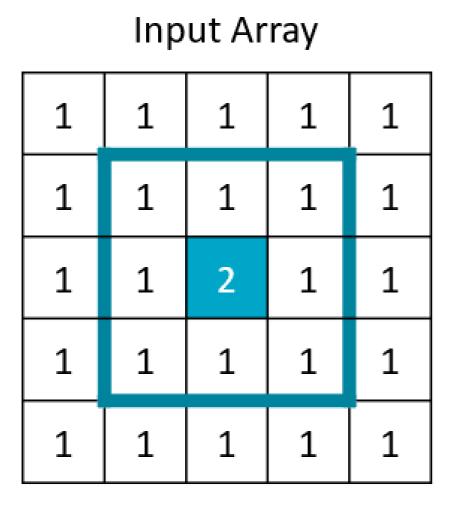


Sharpened





## Convolution with a sharpening filter



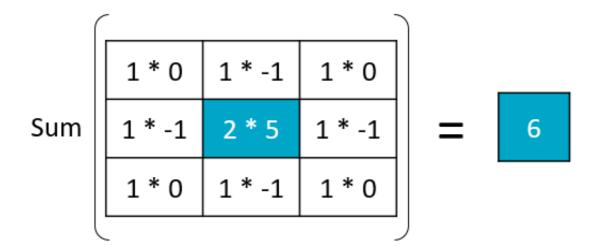
Filter Weights / Kernel

0	-1	0
-1	5	-1
0	-1	0

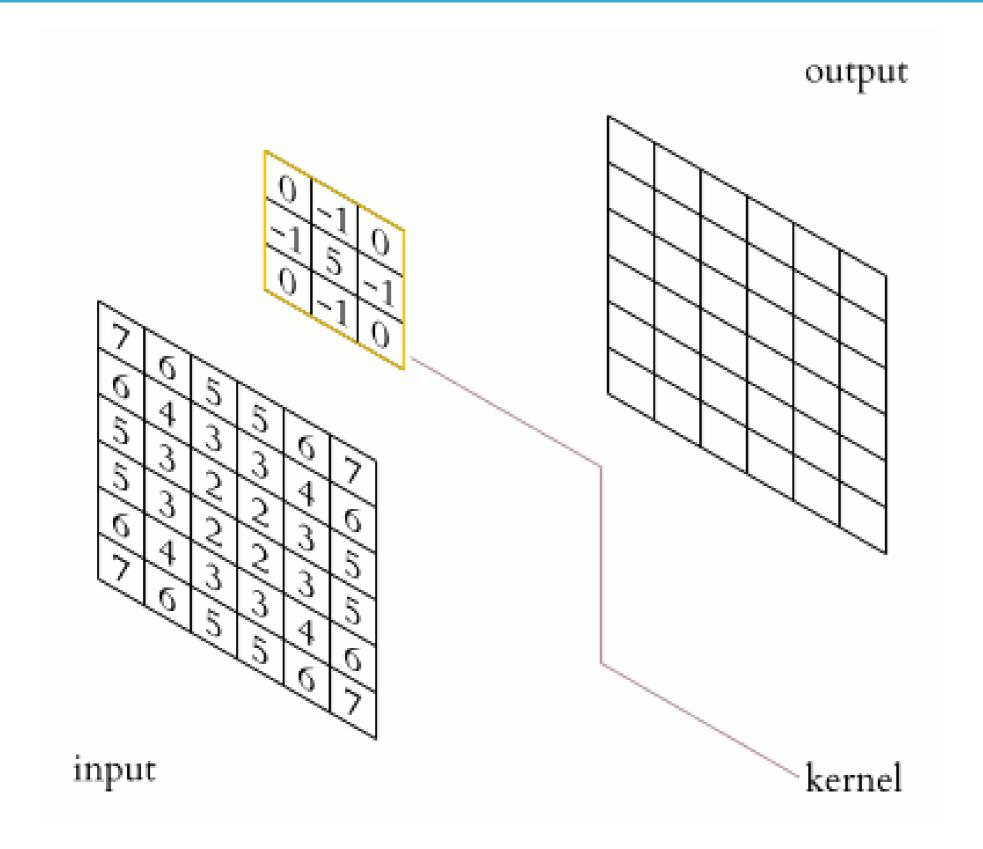
\*



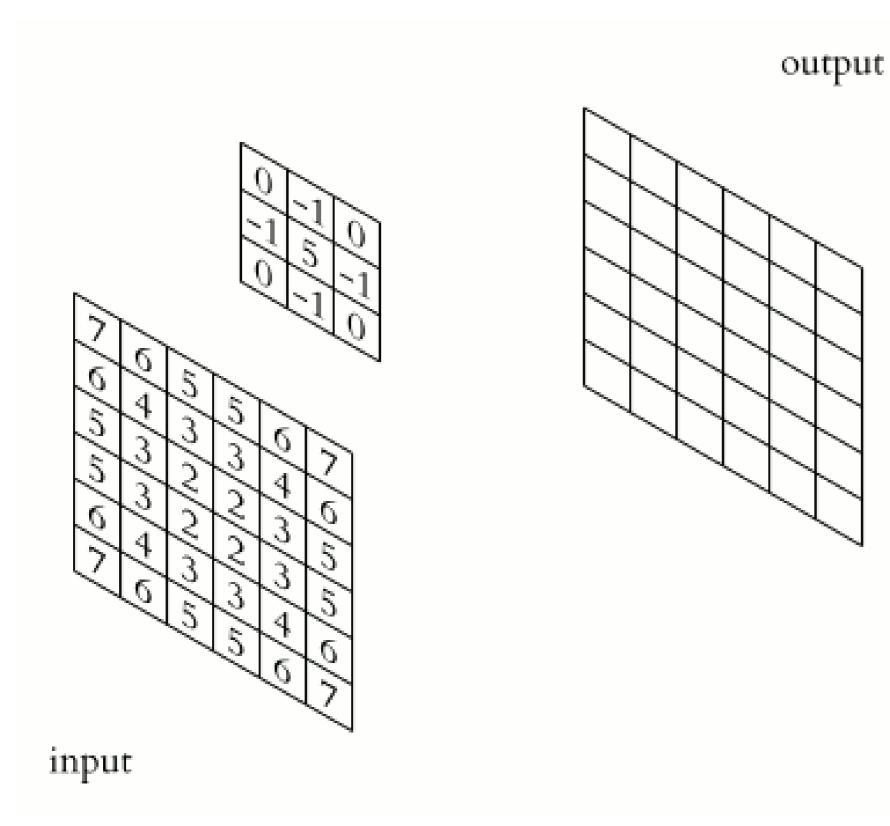
# Convolution with a sharpening filter













#### Image convolution

```
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im, cmap='gray')
axes[1].imshow(im_filt,cmap='gray')
plt.imshow()
```







#### Filtering functions

scipy.ndimage.filters includes:

- median\_filter()
- uniform\_filter()
- maximum\_filter()
- percentile\_filter()

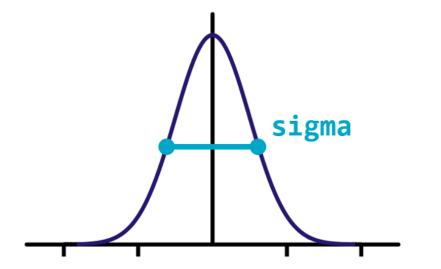
ndi.median\_filter(im, size=10)





### Gaussian filtering

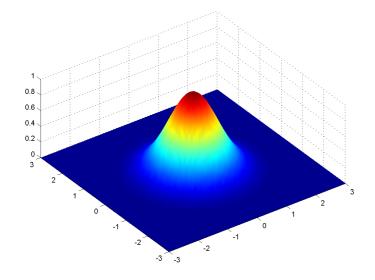
Gaussian distribution in 1 dimension



ndi.gaussian\_filter(im, sigma=5)



Gaussian distribution in 2 dimensions



ndi.gaussian filter(im, sigma=10)







# Let's practice!





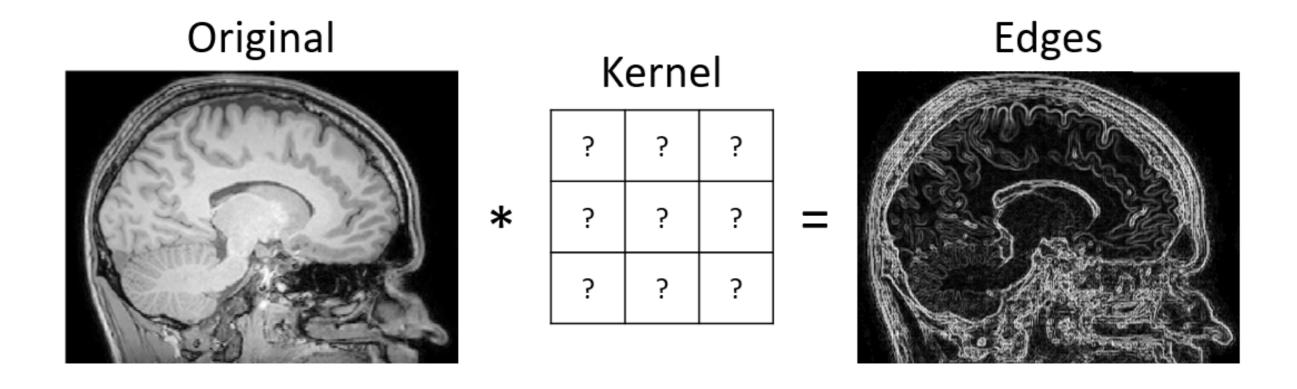
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### **Feature Detection**

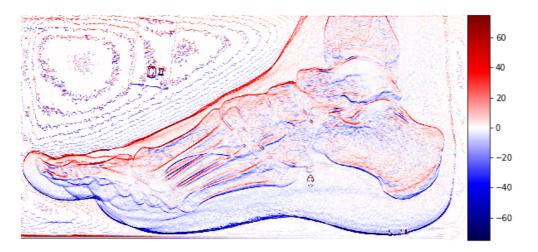
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# Edges: sharp changes in intensity



#### Edge detection





#### Sobel filters

# Sobel (H)

1	2	1
0	0	0
-1	-2	-1

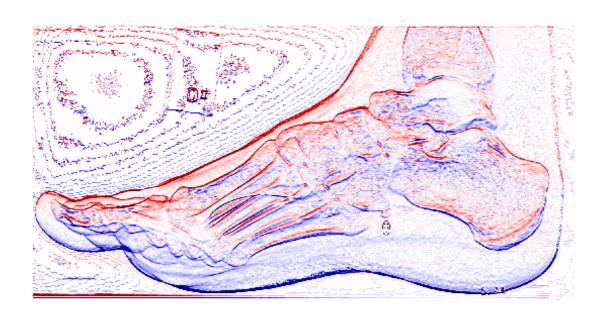
# Sobel (V)

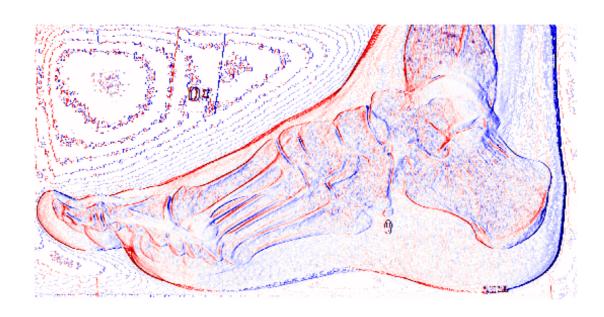
1	0	-1
2	0	-2
1	0	-1

#### Sobel filters

ndi.sobel(im, axis=0)

ndi.sobel(im, axis=1)



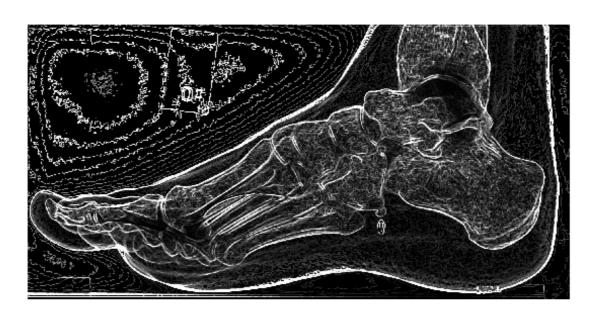


#### Sobel filter magnitude

Combine horizontal and vertical edge data by calculating distance:

$$z=\sqrt{x^2+y^2}$$

plt.imshow(edges, cmap='gray')







# Let's practice!