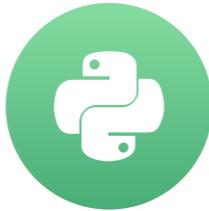


Image restoration

IMAGE PROCESSING IN PYTHON



Rebeca Gonzalez
Data Engineer

Restore an image

Image to restore

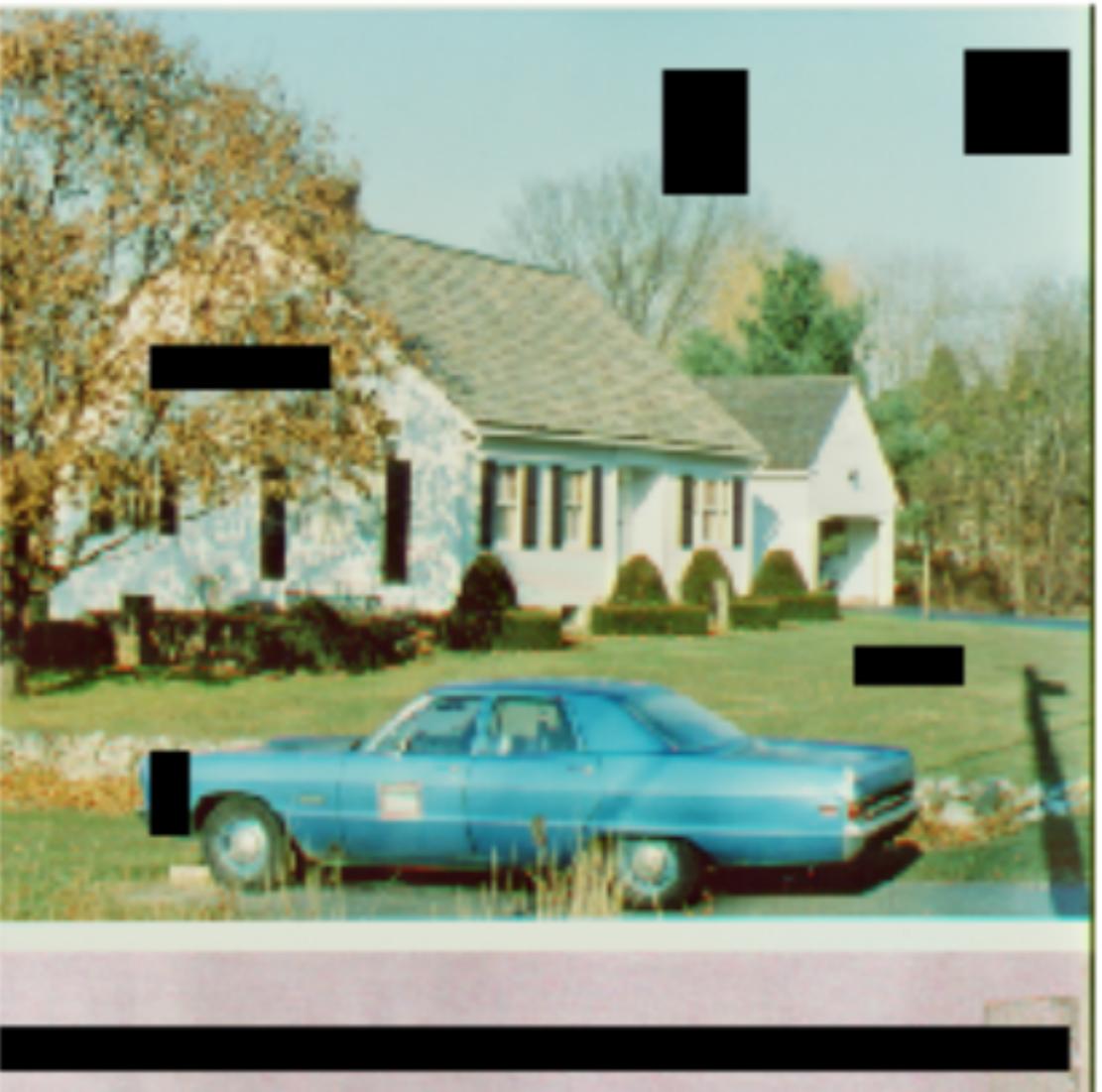


Image restored



Image reconstruction

- Fixing damaged images
- Text removing
- Logo removing
- Object removing



Image reconstruction

Inpainting

- Reconstructing lost parts of images
- Looking at the non-damaged regions

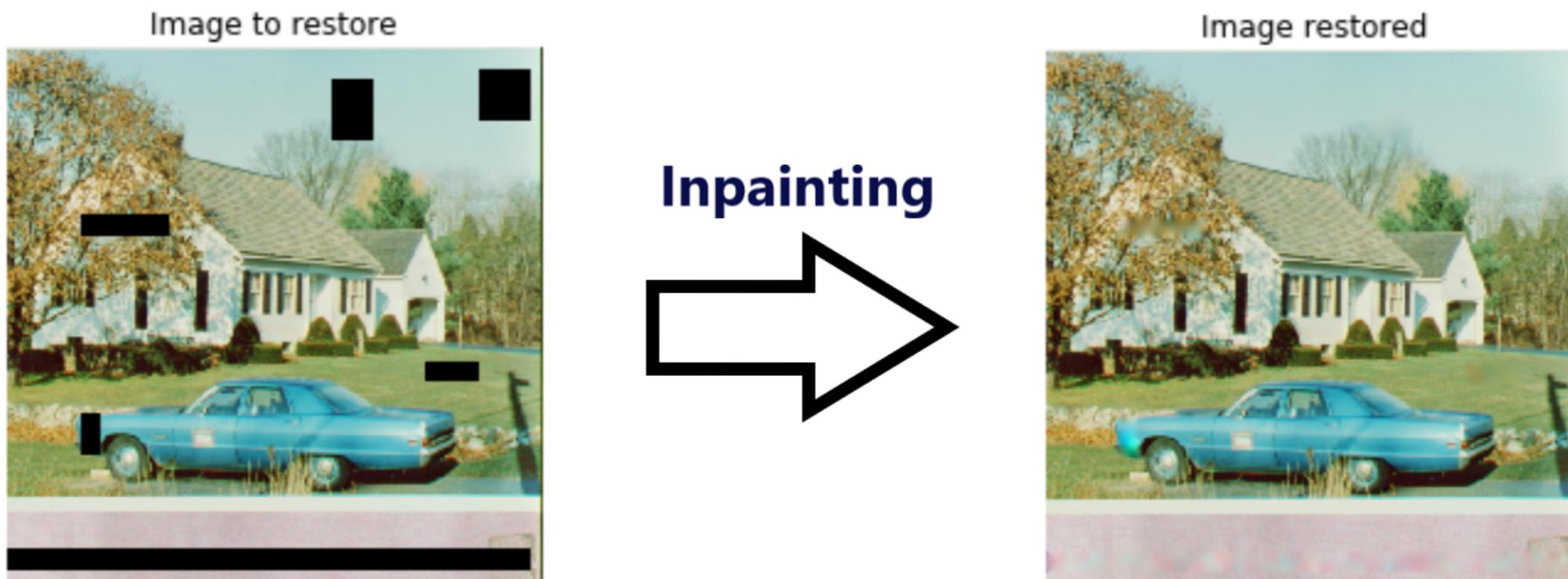
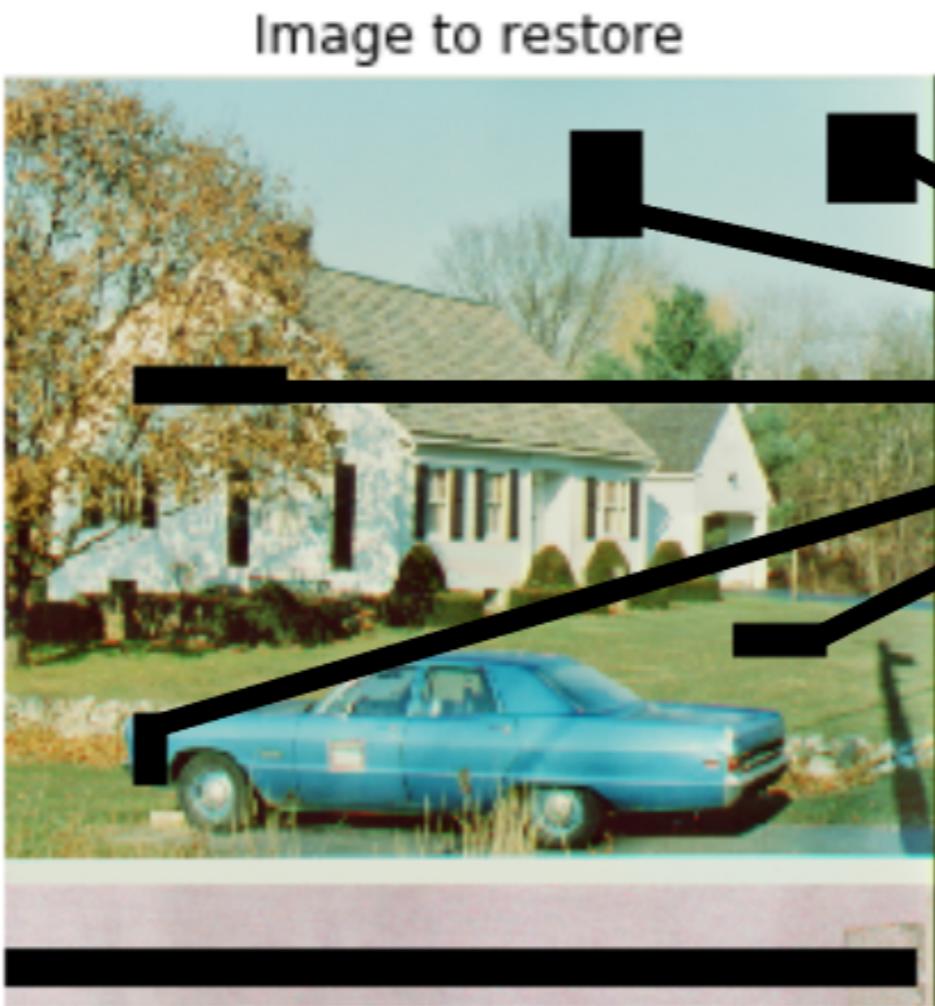


Image reconstruction



Damaged pixels



Set as a mask

Image reconstruction in scikit-image

```
from skimage.restoration import inpaint

# Obtain the mask
mask = get_mask(defect_image)

# Apply inpainting to the damaged image using the mask
restored_image = inpaint.inpaint_biharmonic(defect_image,
                                             mask,
                                             multichannel=True)

# Show the resulting image
show_image(restored_image)
```

Image reconstruction in scikit-image

```
# Show the defect and resulting images  
show_image(defect_image, 'Image to restore')  
show_image(restored_image, 'Image restored')
```

Image to restore



Image restored



Masks

Image to restore



Mask



Masks

```
def get_mask(image):
    ''' Creates mask with three defect regions '''
    mask = np.zeros(image.shape[:-1])

    mask[101:106, 0:240] = 1

    mask[152:154, 0:60] = 1
    mask[153:155, 60:100] = 1
    mask[154:156, 100:120] = 1
    mask[155:156, 120:140] = 1

    mask[212:217, 0:150] = 1
    mask[217:222, 150:256] = 1

    return mask
```

Let's practice!

IMAGE PROCESSING IN PYTHON

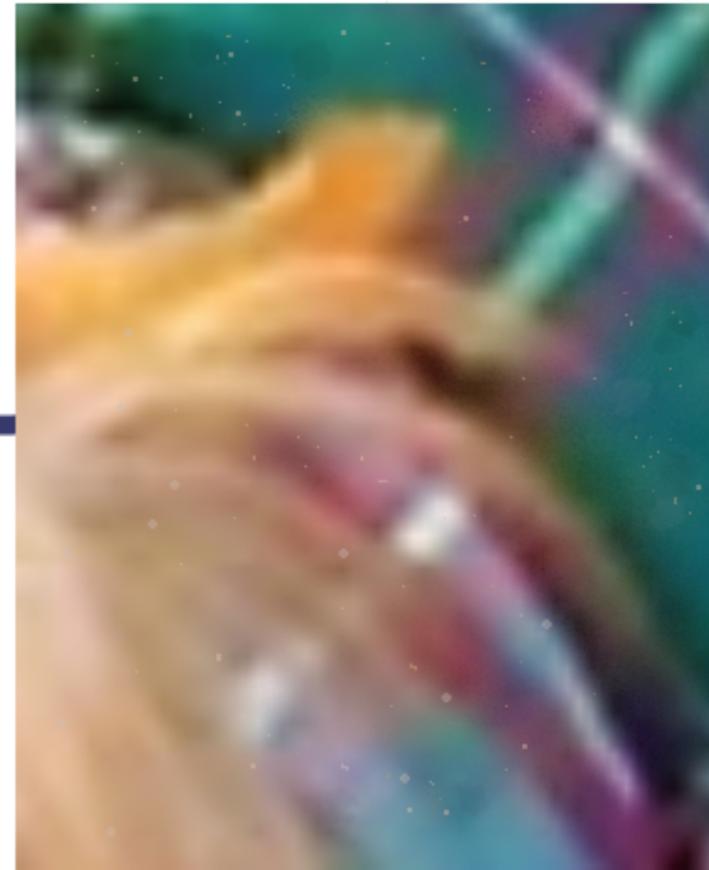
Noise

IMAGE PROCESSING IN PYTHON

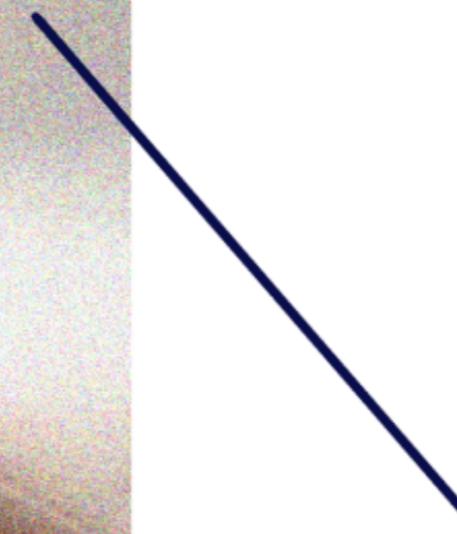


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Data Engineer

Noise



Noise



Apply noise in scikit-image

```
# Import the module and function  
from skimage.util import random_noise  
  
# Add noise to the image  
noisy_image = random_noise(dog_image)  
  
# Show original and resulting image  
show_image(dog_image)  
show_image(noisy_image, 'Noisy image')
```

Apply noise in scikit-image

Original

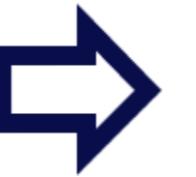


Noisy image



Reducing noise

Noisy image



Denoised



Denoising types

- Total variation (TV)
- Bilateral
- Wavelet denoising
- Non-local means denoising



Denoising

Using total variation filter denoising

```
from skimage.restoration import denoise_tv_chambolle

# Apply total variation filter denoising
denoised_image = denoise_tv_chambolle(noisy_image,
                                         weight=0.1,
                                         multichannel=True)

# Show denoised image
show_image(noisy_image, 'Noisy image')
show_image(denoised_image, 'Denoised image')
```

Denoising

Total variation filter

Noisy image



Denoised image



Denoising

Bilateral filter

```
from skimage.restoration import denoise_bilateral

# Apply bilateral filter denoising
denoised_image = denoise_bilateral(noisy_image, multichannel=True)

# Show original and resulting images
show_image(noisy_image, 'Noisy image')
show_image(denoised_image, 'Denoised image')
```

Denoising

Bilateral filter

Noisy image



Denoised image

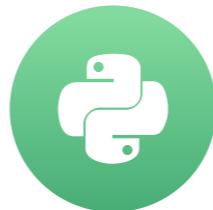


Let's practice!

IMAGE PROCESSING IN PYTHON

Superpixels & segmentation

IMAGE PROCESSING IN PYTHON



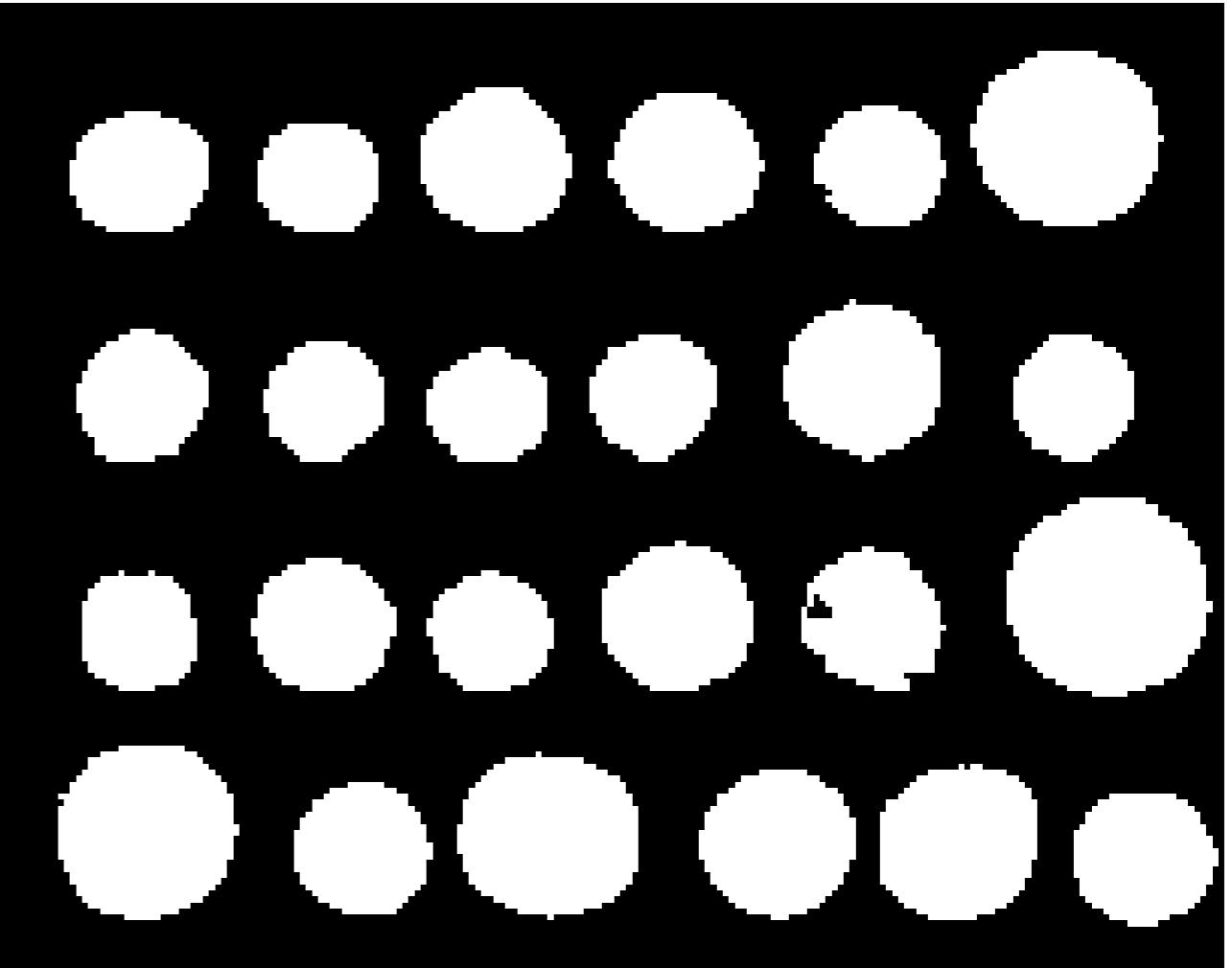
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Segmentation

Original

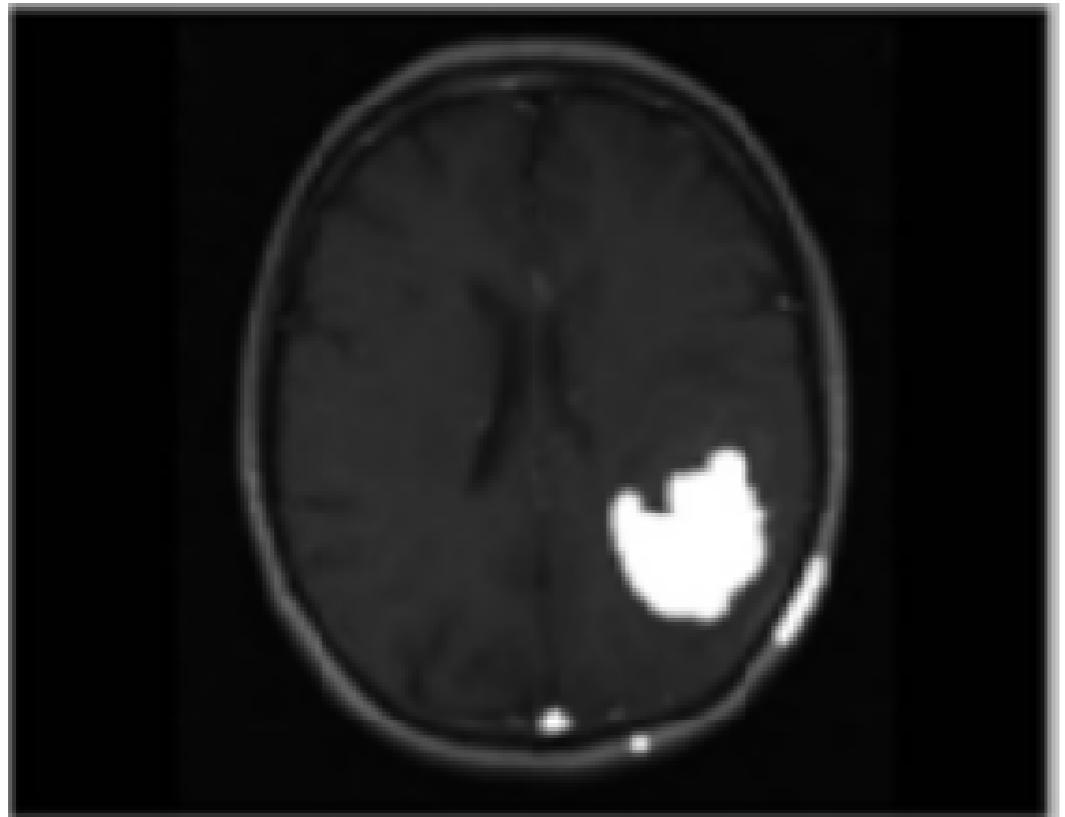


Segmented image



Segmentation

Segmented



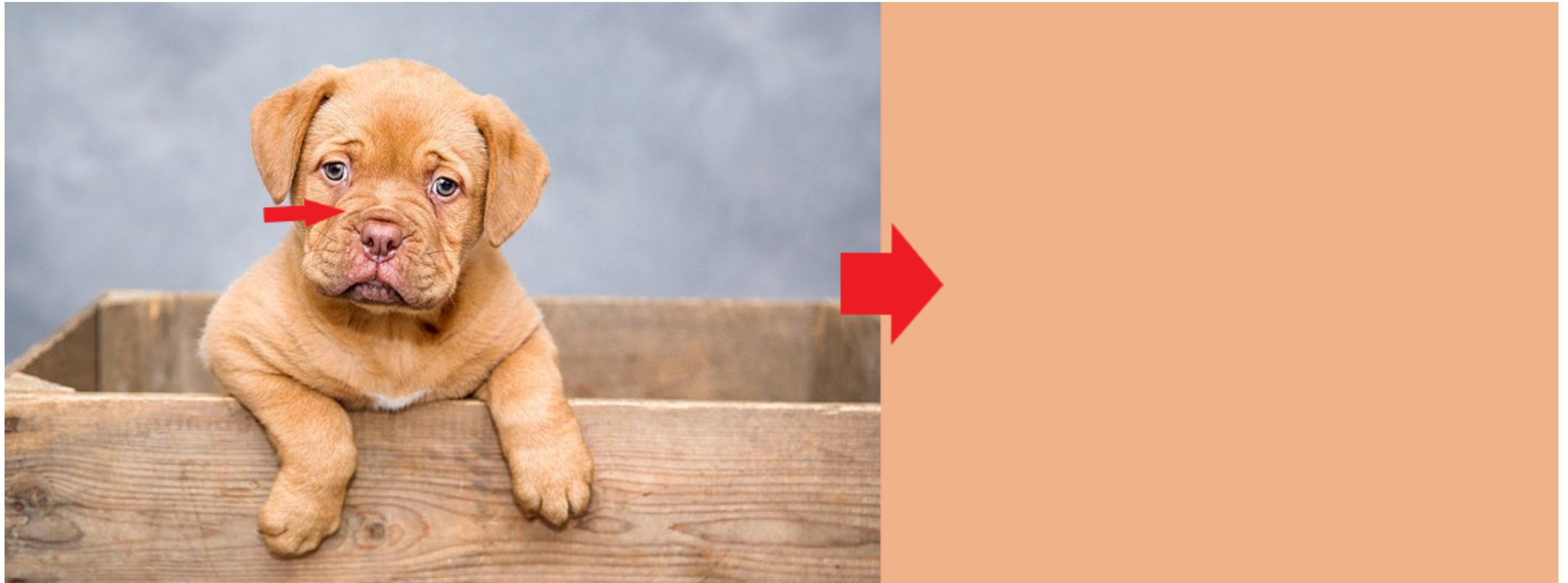
Original



Segmented

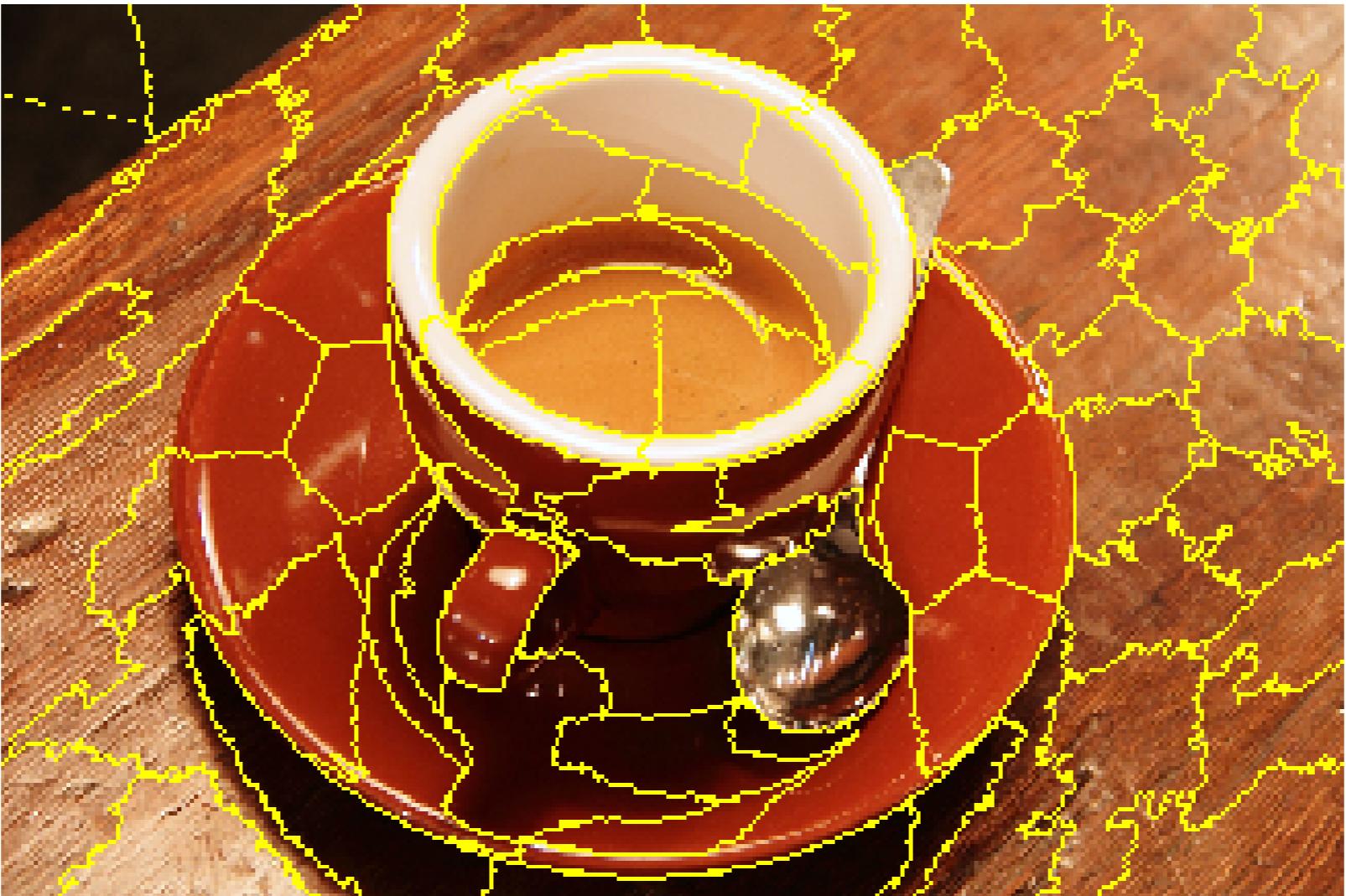


Image representation



Superpixels

Superpixel segmentation, 100 segments



Benefits of superpixels

- More meaningful regions
- Computational efficiency

Segmentation

- Supervised
- Unsupervised

Supervised thresholding



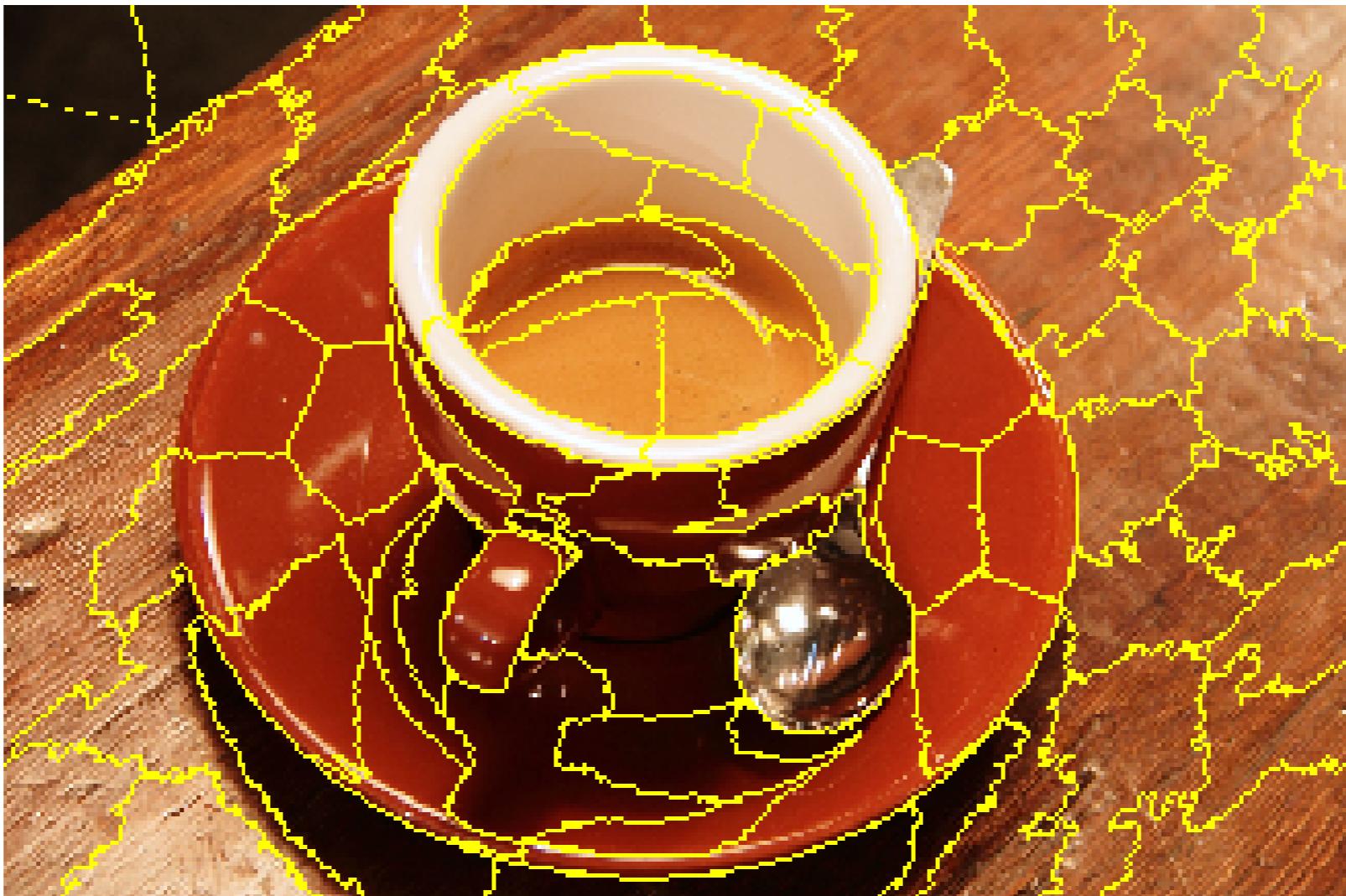
Unsupervised thresholding



Unsupervised segmentation

Simple Linear Iterative Clustering (SLIC)

Superpixel segmentation, 100 segments



Unsupervised segmentation (SLIC)

```
# Import the modules
from skimage.segmentation import slic
from skimage.color import label2rgb

# Obtain the segments
segments = segmentation.slic(image)

# Put segments on top of original image to compare
segmented_image = label2rgb(segments, image, kind='avg')

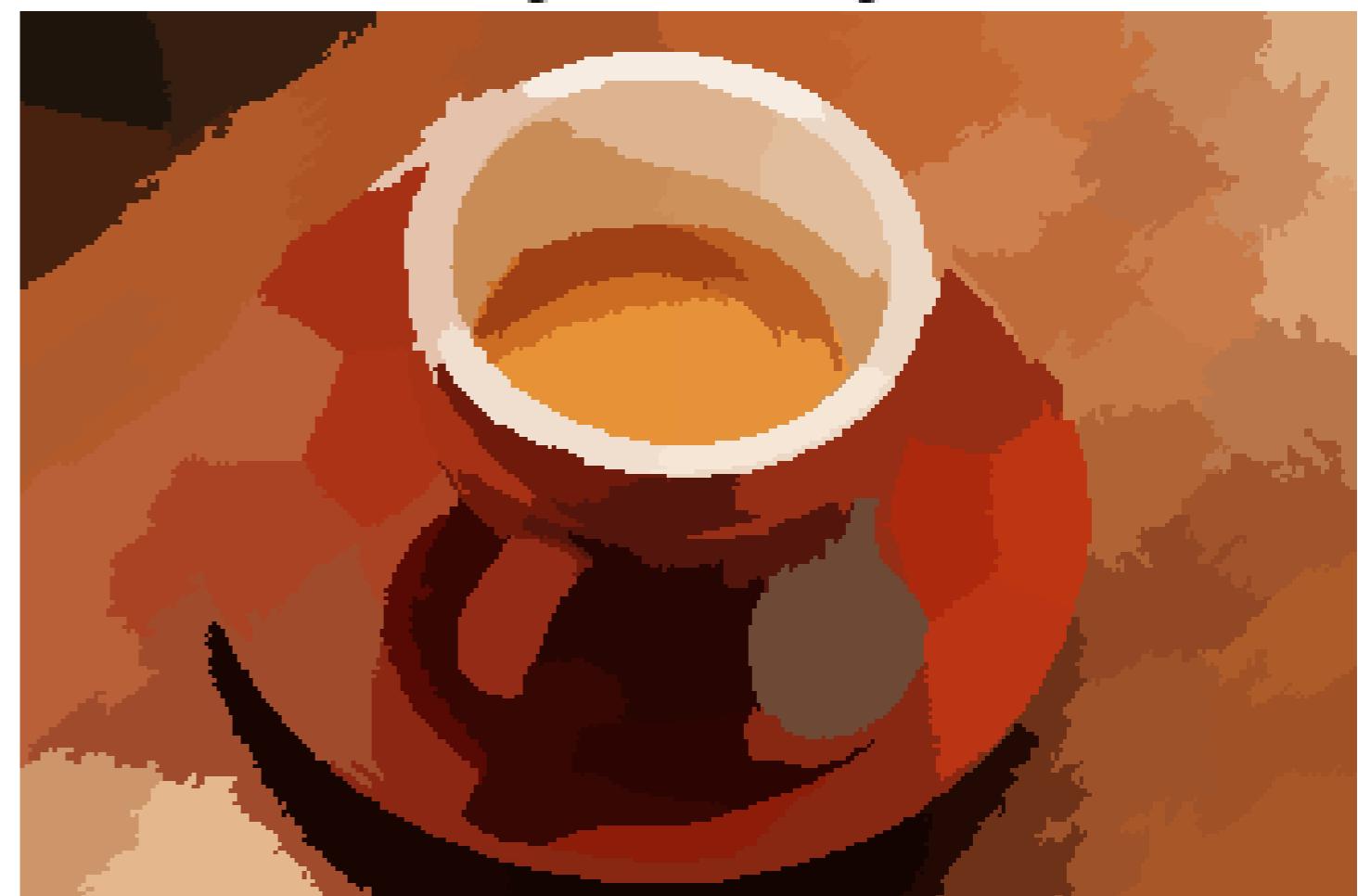
show_image(image)
show_image(segmented_image, "Segmented image")
```

Unsupervised segmentation (SLIC)

Original



Segmented image



More segments

```
# Import the modules
from skimage.segmentation import slic
from skimage.color import label2rgb

# Obtain the segmentation with 300 regions
segments = slic(image, n_segments= 300)

# Put segments on top of original image to compare
segmented_image = label2rgb(segments, image, kind='avg')

show_image(segmented_image)
```

More segments

Original



Segmented image

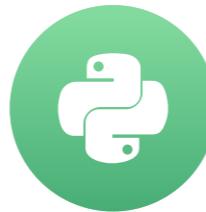


Let's practice!

IMAGE PROCESSING IN PYTHON

Finding contours

IMAGE PROCESSING IN PYTHON



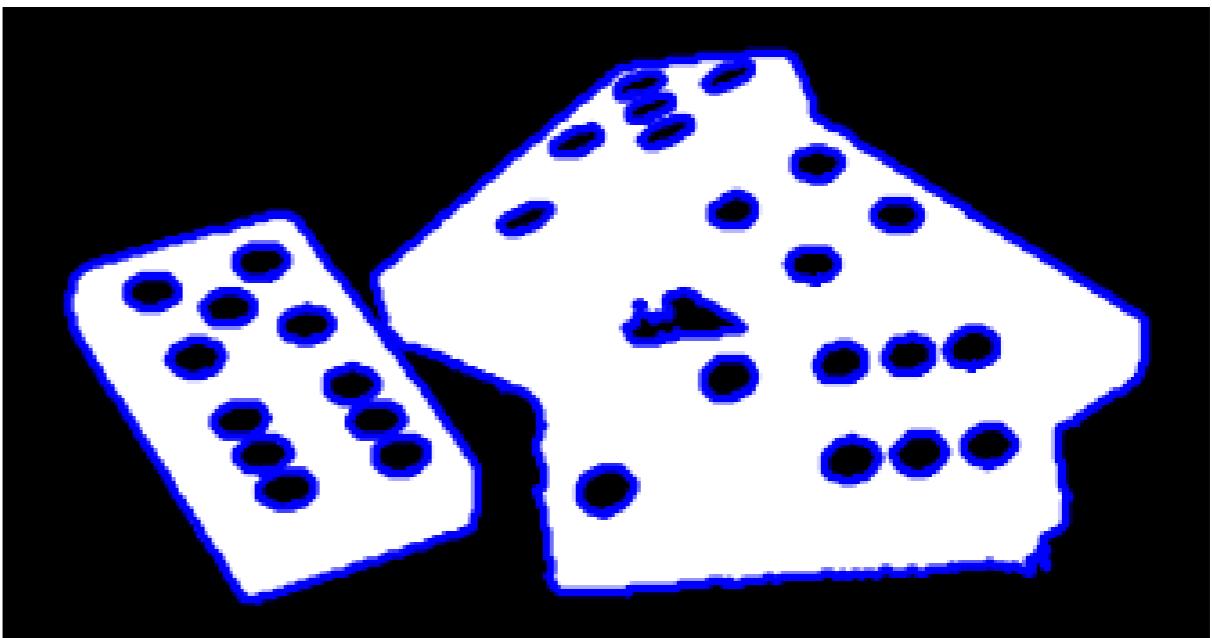
Rebeca Gonzalez
Data Engineer

Finding contours

Original image



Contours



- Measure size
- Classify shapes
- Determine the number of objects

Total points in domino tokens: 35.

Binary images

Thresholded Image



Contours



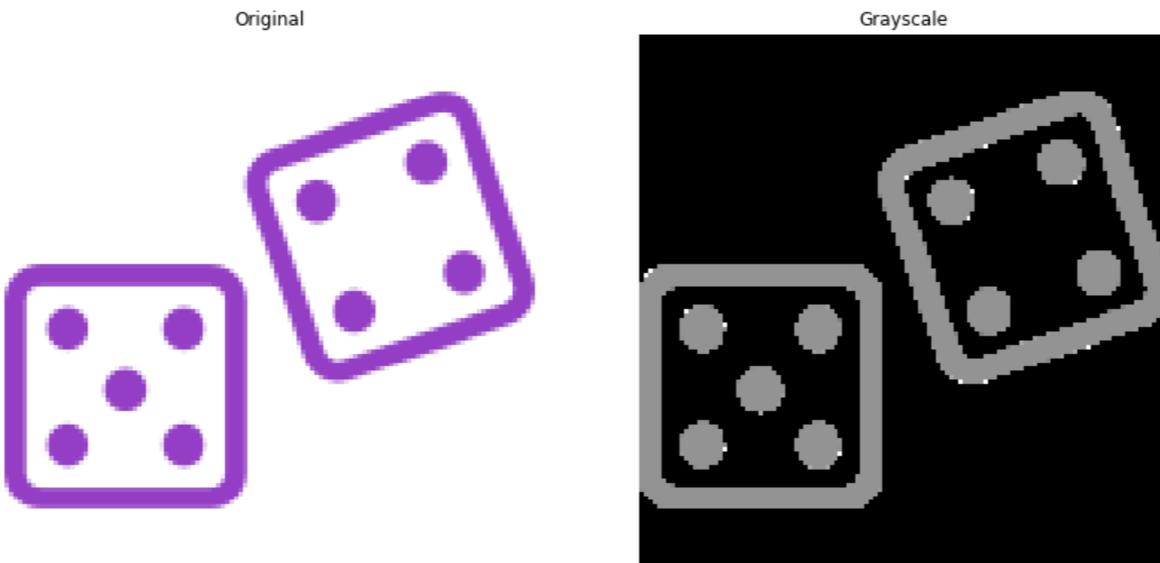
We can obtain a binary image applying
thresholding or using edge detection

Find contours using scikit-image

PREPARING THE IMAGE

Transform the image to 2D grayscale.

```
# Make the image grayscale  
image = color.rgb2gray(image)
```

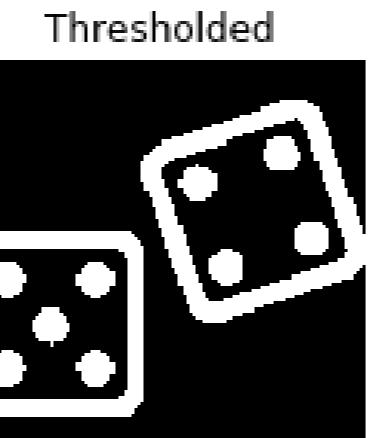


Find contours using scikit-image

PREPARING THE IMAGE

Binarize the image

```
# Obtain the thresh value  
thresh = threshold_otsu(image)  
  
# Apply thresholding  
thresholded_image = image > thresh
```

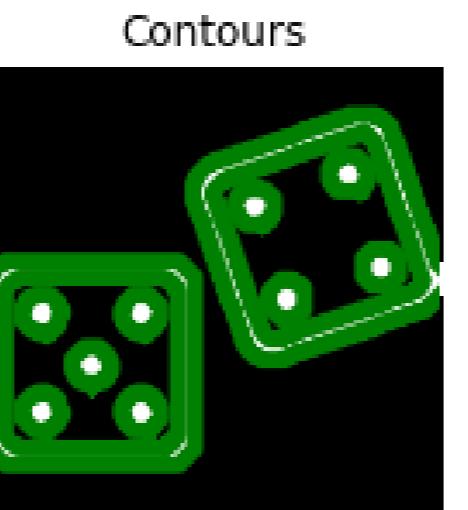


Find contours using scikit-image

And then use `findContours()`.

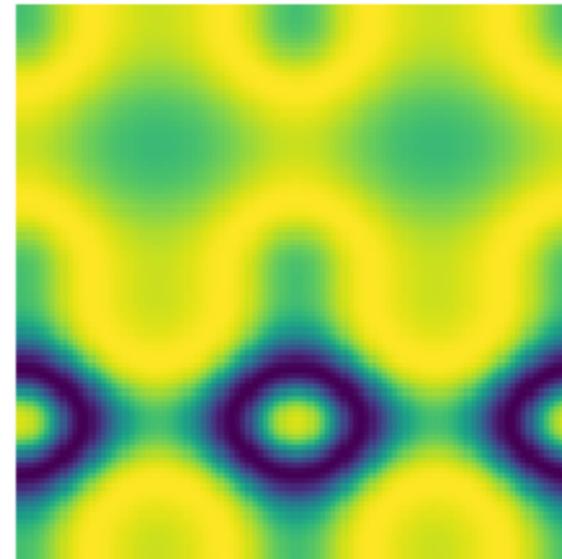
```
# Import the measure module
from skimage import measure

# Find contours at a constant value of 0.8
contours = measure.find_contours(thresholded_image, 0.8)
```

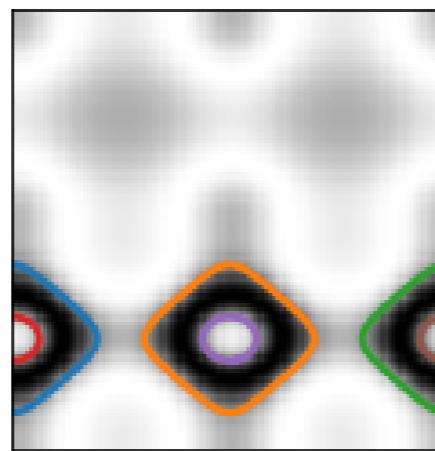


Constant level value

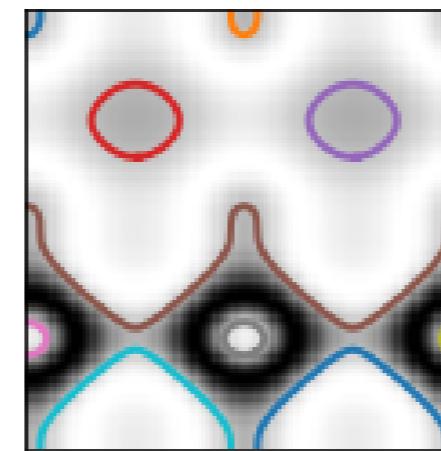
Original



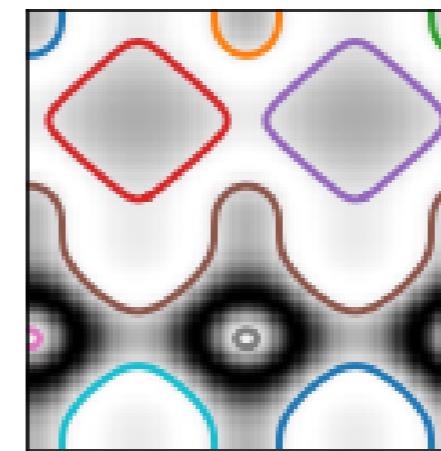
Level value of 0.1



Level value of 0.5



Level value of 0.8



The steps to spotting contours

```
from skimage import measure
from skimage.filters import threshold_otsu

# Make the image grayscale
image = color.rgb2gray(image)

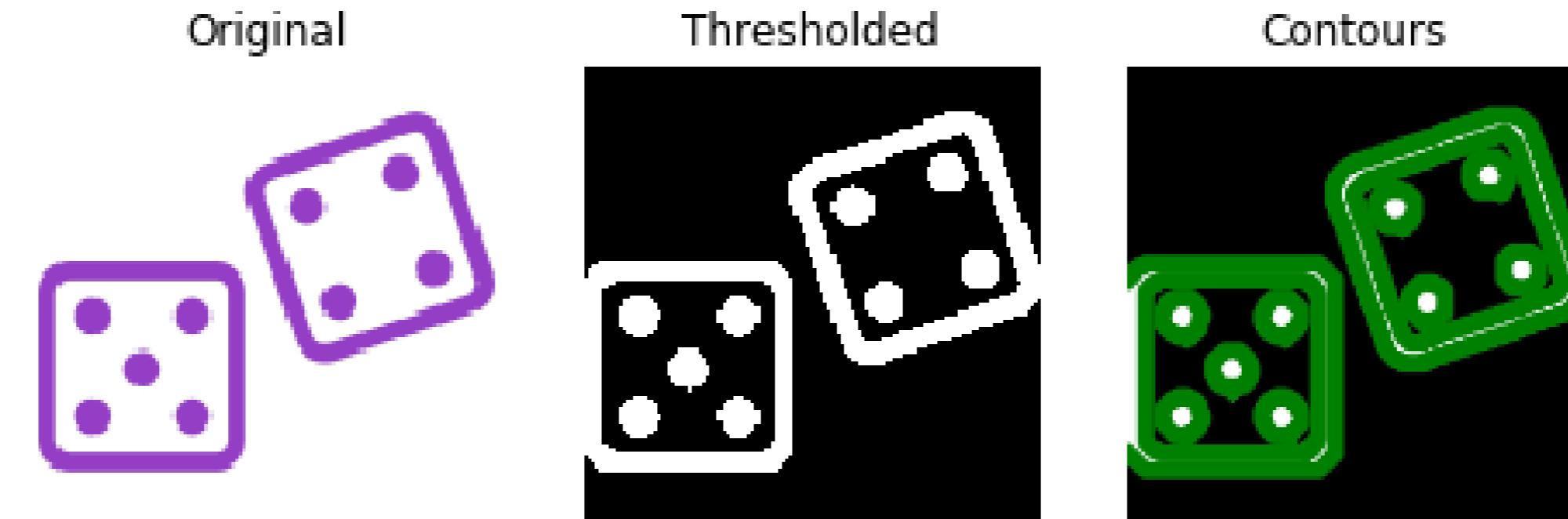
# Obtain the optimal thresh value of the image
thresh = threshold_otsu(image)

# Apply thresholding and obtain binary image
thresholded_image = image > thresh

# Find contours at a constant value of 0.8
contours = measure.find_contours(thresholded_image, 0.8)
```

The steps to spotting contours

Resulting in

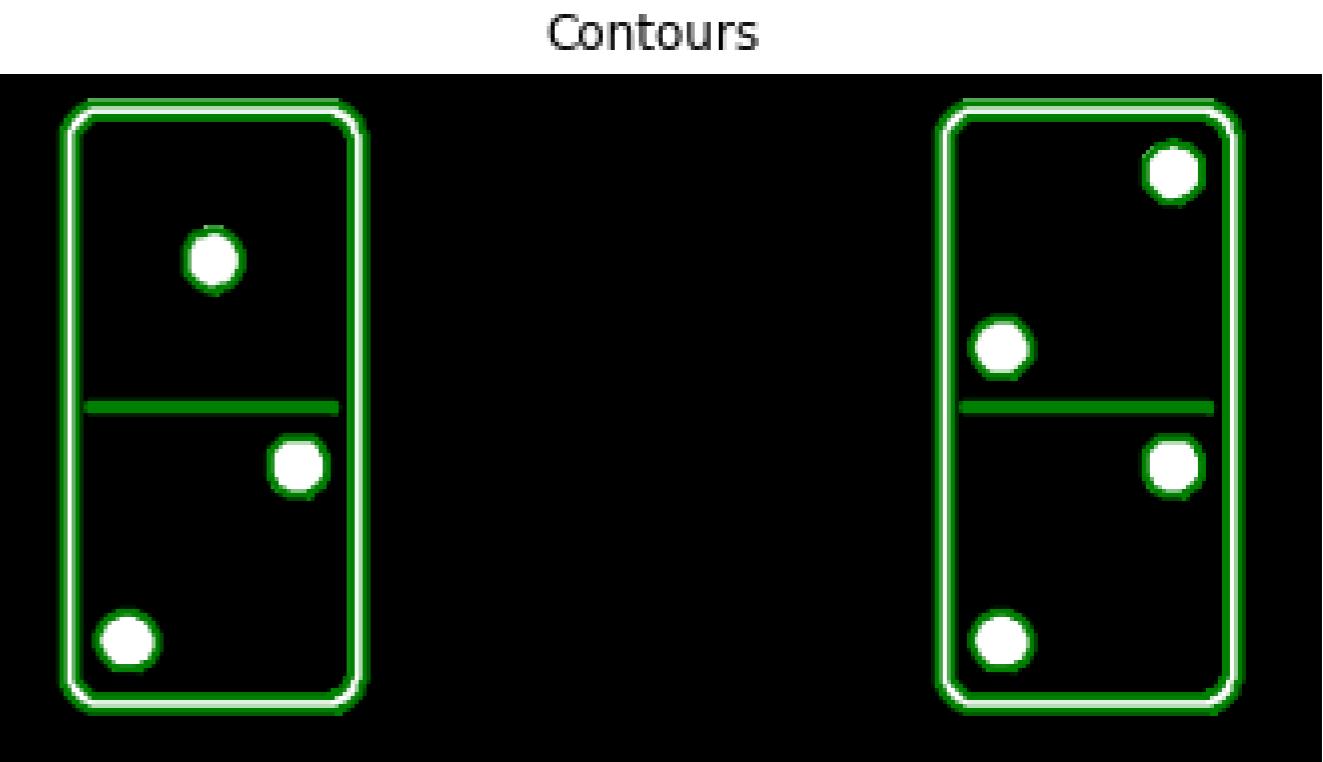


A contour's shape

Contours: list of (n,2) - ndarrays.

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2)  
(401, 2)  
(401, 2)  
(123, 2)  
(123, 2)  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)
```

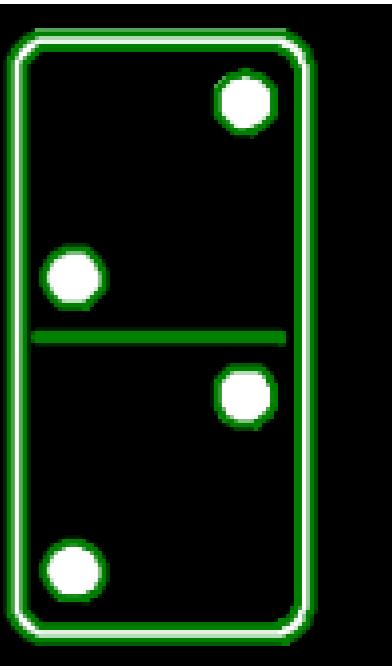
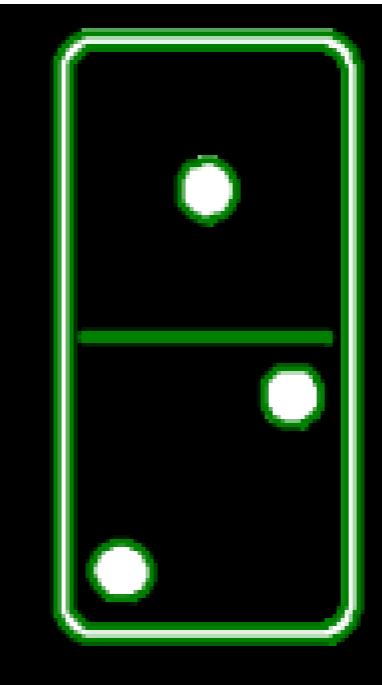


A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2)  
(123, 2)  
(123, 2)  
( 59, 2)  
( 59, 2)  
( 59, 2)  
( 57, 2)  
( 57, 2)  
( 59, 2)  
( 59, 2)
```

Contours

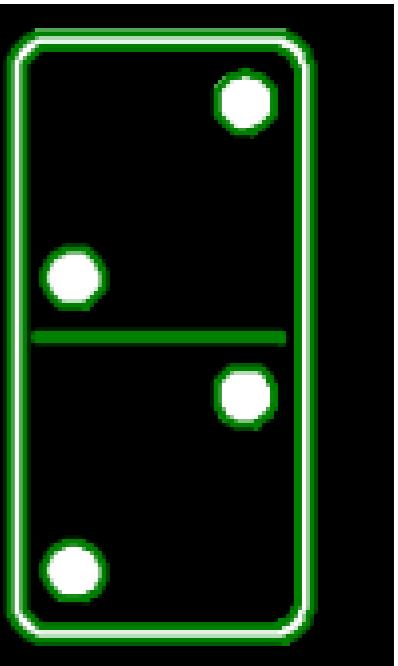
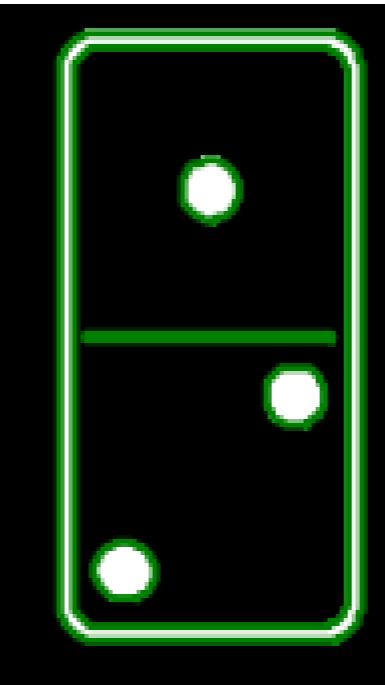


A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2)  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2)
```

Contours

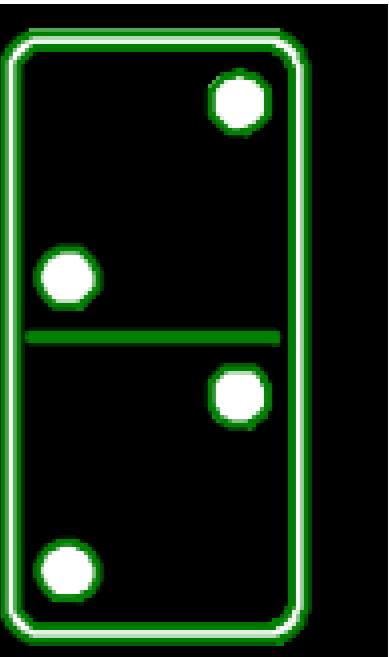
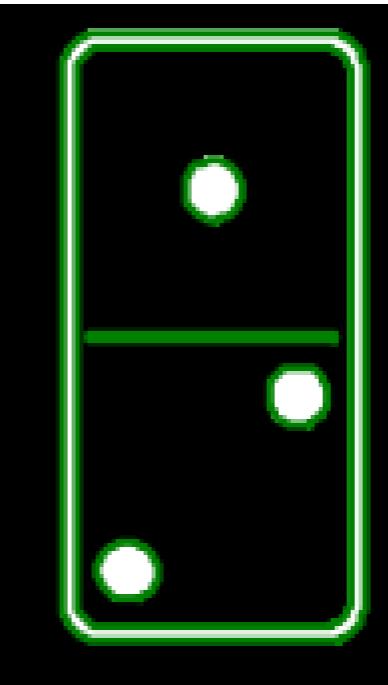


A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2) --> Divisory line of tokens  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2)
```

Contours

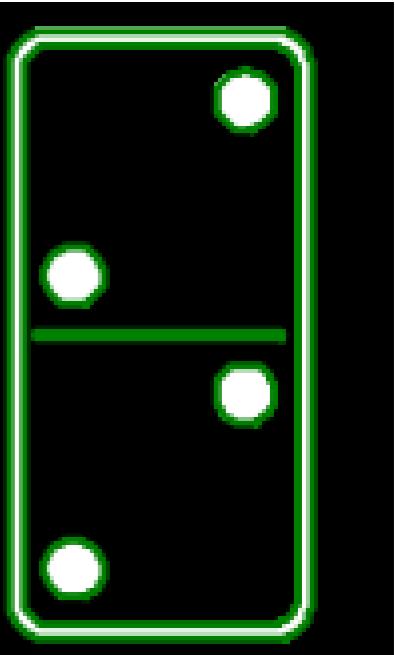
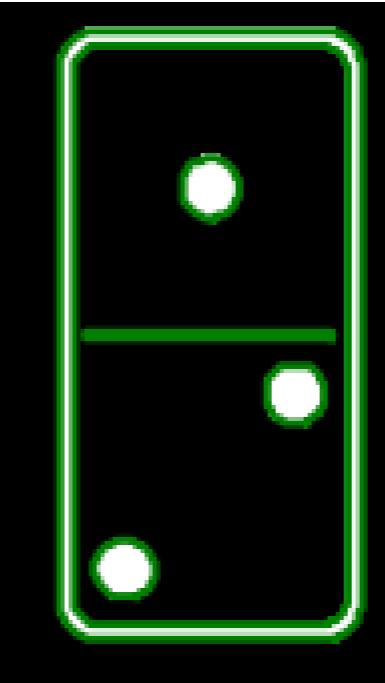


A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2) --> Divisory line of tokens  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2) --> Dots
```

Contours



Number of dots: 7.

Let's practice!

IMAGE PROCESSING IN PYTHON