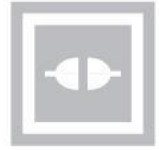




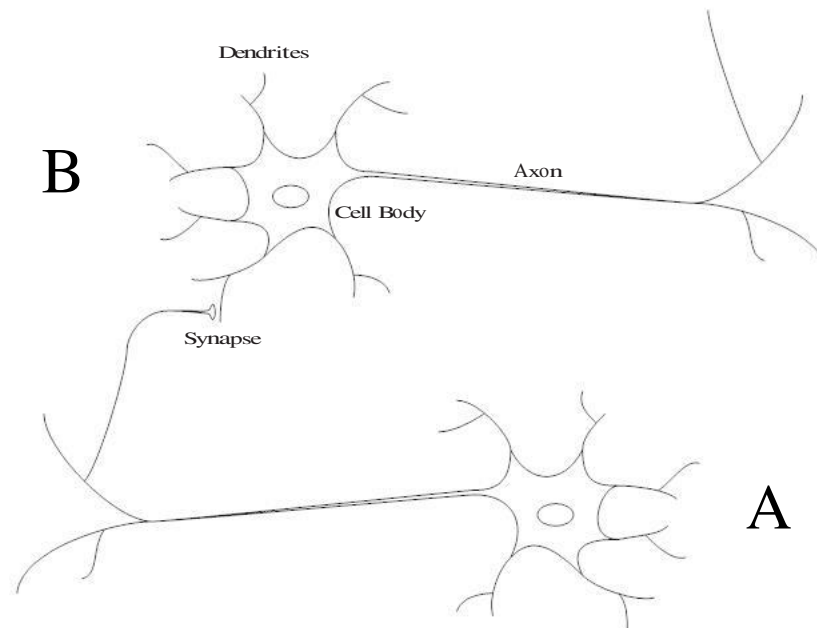
Eğitici Hebbian Öğrenme (Supervised Hebbian Learning)

Hebb Doğru Varsayımı (Hebb's Postulate)

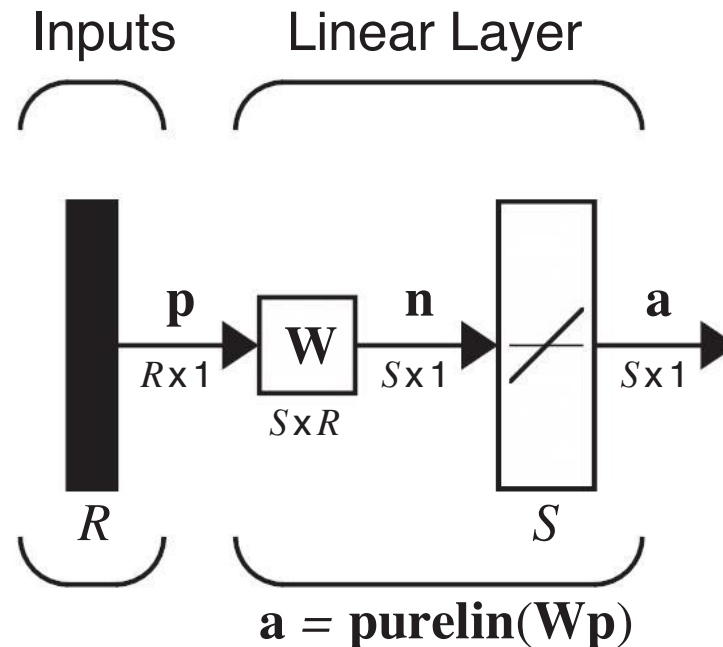


“When an axon of cell A is near enough to excite a cell B and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A's efficiency, as one of the cells firing B, is increased.”

D. O. Hebb, 1949



Lineer Birleřtirici (Linear Associator)



$$\mathbf{a} = \mathbf{Wp} \qquad a_i = \sum_{j=1}^R w_{ij} p_j$$

Training Set:

$$\{\mathbf{p}_1, \mathbf{t}_1\}, \{\mathbf{p}_2, \mathbf{t}_2\}, \dots, \{\mathbf{p}_Q, \mathbf{t}_Q\}$$

Hebb Kuralı (Hebb Rule)



$$w_{ij}^{new} = w_{ij}^{old} + \alpha f_i(a_{iq}) g_j(p_{jq})$$

↑ Postsynaptic Signal ↑ Presynaptic Signal

Simplified Form:

$$w_{ij}^{new} = w_{ij}^{old} + \alpha a_{iq} p_{jq}$$

Supervised Form:

$$w_{ij}^{new} = w_{ij}^{old} + t_{iq} p_{jq}$$

Matrix Form:

$$\mathbf{W}^{new} = \mathbf{W}^{old} + \mathbf{t} \mathbf{p}_q^T$$



Yığın Operasyon (Batch Operation)



$$\mathbf{W} = \mathbf{t}_1 \mathbf{p}_1^T + \mathbf{t}_2 \mathbf{p}_2^T + \cdots + \mathbf{t}_Q \mathbf{p}_Q^T = \sum_{q=1}^Q \mathbf{t}_q \mathbf{p}_q^T \quad (\text{Zero Initial Weights})$$

Matrix Form:

$$\mathbf{W} = \begin{bmatrix} \mathbf{t}_1 & \mathbf{t}_2 & \cdots & \mathbf{t}_Q \end{bmatrix} \begin{bmatrix} \mathbf{p}_1^T \\ \mathbf{p}_2^T \\ \vdots \\ \mathbf{p}_Q^T \end{bmatrix} = \mathbf{T} \mathbf{P}^T$$
$$\mathbf{P} = \begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_Q \end{bmatrix}$$
$$\mathbf{T} = \begin{bmatrix} \mathbf{t}^1 & \mathbf{t}^2 & \cdots & \mathbf{t}_Q \end{bmatrix}$$

Performance Analysis

$$\mathbf{a} = \mathbf{W}\mathbf{p}_k = \left(\sum_{q=1}^Q \mathbf{t}_q \mathbf{p}_q^T \right) \mathbf{p}_k = \sum_{q=1}^Q \mathbf{t}_q (\mathbf{p}_q^T \mathbf{p}_k)$$

Case I, input patterns are orthogonal.

$$\begin{aligned} (\mathbf{p}_q^T \mathbf{p}_k) &= 1 & q &= k \\ &= 0 & q &\neq k \end{aligned}$$

Therefore the network output equals the target:

$$\mathbf{a} = \mathbf{W}\mathbf{p}_k = \mathbf{t}_k$$

Case II, input patterns are normalized, but not orthogonal.

$$\mathbf{a} = \mathbf{W}\mathbf{p}_k = \mathbf{t}_k + \underbrace{\sum_{q \neq k} \mathbf{t}_q (\mathbf{p}_q^T \mathbf{p}_k)}_{\text{Error}}$$

Example



Banana	Apple	Normalized Prototype Patterns	
$\mathbf{p}_1 = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}$	$\mathbf{p}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$	$\left\{ \mathbf{p}_1 = \begin{bmatrix} -0.5774 \\ 0.5774 \\ -0.5774 \end{bmatrix}, \mathbf{t}_1 = [-1] \right\}$	$\left\{ \mathbf{p}_2 = \begin{bmatrix} 0.5774 \\ 0.5774 \\ -0.5774 \end{bmatrix}, \mathbf{t}_2 = [1] \right\}$

Weight Matrix (Hebb Rule):

$$\mathbf{W} = \mathbf{T}\mathbf{P}^T = \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} -0.5774 & 0.5774 & -0.5774 \\ 0.5774 & 0.5774 & -0.5774 \end{bmatrix} = \begin{bmatrix} 1.1548 & 0 & 0 \end{bmatrix}$$

Tests:

Banana $\mathbf{W}\mathbf{p}_1 = \begin{bmatrix} 1.1548 & 0 & 0 \end{bmatrix} \begin{bmatrix} -0.5774 \\ 0.5774 \\ -0.5774 \end{bmatrix} = \begin{bmatrix} -0.6668 \end{bmatrix}$

Apple $\mathbf{W}\mathbf{p}_2 = \begin{bmatrix} 1.1548 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.5774 \\ 0.5774 \\ -0.5774 \end{bmatrix} = \begin{bmatrix} 0.6668 \end{bmatrix}$

Pseudoinverse Rule - (1)

Performance Index: $\mathbf{W}\mathbf{p}_q = \mathbf{t}_q \quad q = 1, 2, \dots, Q$

$$F(\mathbf{W}) = \sum_{q=1}^Q \|\mathbf{t}_q - \mathbf{W}\mathbf{p}_q\|^2$$

Matrix Form:

$$\mathbf{W}\mathbf{P} = \mathbf{T}$$

$$\mathbf{T} = [\mathbf{t}_1 \ \mathbf{t}_2 \ \dots \ \mathbf{t}_Q] \quad \mathbf{P} = [\mathbf{p}_1 \ \mathbf{p}_2 \ \dots \ \mathbf{p}_Q]$$

$$F(\mathbf{W}) = \|\mathbf{T} - \mathbf{W}\mathbf{P}\|^2 = \|\mathbf{E}\|^2$$

$$\|\mathbf{E}\|^2 = \sum_i \sum_j \sum_e e_{ij}^2$$

Pseudoinverse Rule - (2)

$$\mathbf{W}\mathbf{P} = \mathbf{T}$$

Minimize:

$$F(\mathbf{W}) = \|\mathbf{T} - \mathbf{W}\mathbf{P}\|^2 = \|\mathbf{E}\|^2$$

If an inverse exists for \mathbf{P} , $F(\mathbf{W})$ can be made zero:

$$\mathbf{W} = \mathbf{T}\mathbf{P}^{-1}$$

When an inverse does not exist $F(\mathbf{W})$ can be minimized using the pseudoinverse:

$$\mathbf{W} = \mathbf{T}\mathbf{P}^+$$

$$\mathbf{P}^+ = (\mathbf{P}^T\mathbf{P})^{-1}\mathbf{P}_T$$

Relationship to the Hebb Rule

Hebb Rule

$$\mathbf{W} = \mathbf{T}\mathbf{P}^T$$

Pseudoinverse Rule

$$\mathbf{W} = \mathbf{T}\mathbf{P}^+$$

$$\mathbf{P}^+ = (\mathbf{P}^T\mathbf{P})^{-1}\mathbf{P}^T$$

If the prototype patterns are orthonormal:

$$\mathbf{P}^T\mathbf{P} = \mathbf{I}$$

$$\mathbf{P}^+ = (\mathbf{P}^T\mathbf{P})^{-1}\mathbf{P}^T = \mathbf{P}^T$$

Example



$$\left\{ \mathbf{p}_1 = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}, \mathbf{t}_1 = [-1] \right\} \quad \left\{ \mathbf{p}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \mathbf{t}_2 = [1] \right\} \quad \mathbf{W} = \mathbf{TP}^+ = [-1 \ 1] \left(\begin{bmatrix} -1 & 1 \\ 1 & 1 \\ -1 & -1 \end{bmatrix} \right)^+$$

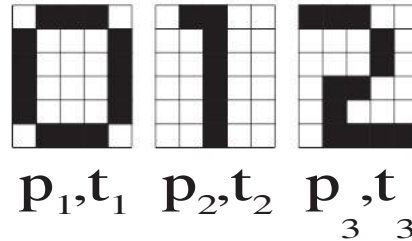
$$\mathbf{P}^+ = (\mathbf{P}^T \mathbf{P})^{-1} \mathbf{P}^T = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} -1 & 1 & -1 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -0.5 & 0.25 & -0.25 \\ 0.5 & 0.25 & -0.25 \end{bmatrix}$$

$$\mathbf{W} = \mathbf{TP}^+ = [-1 \ 1] \begin{bmatrix} -0.5 & 0.25 & -0.25 \\ 0.5 & 0.25 & -0.25 \end{bmatrix} = [1 \ 0 \ 0]$$

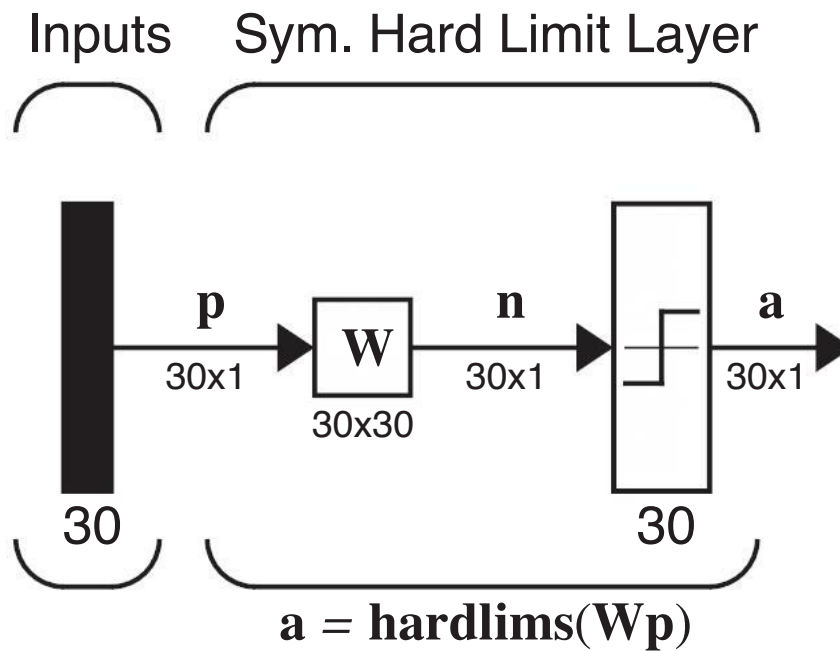
$$\mathbf{Wp}_1 = [1 \ 0 \ 0] \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} = [-1]$$

$$\mathbf{Wp}_2 = [1 \ 0 \ 0] \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = [1]$$

Autoassociative Memory



$$\mathbf{p}_1 = [-1 \ 1 \ 1 \ 1 \ 1 \ -1 \ 1 \ -1 \ -1 \ -1 \ -1 \ 1 \ 1 \ -1 \ \dots \ 1 \ -1]^T$$



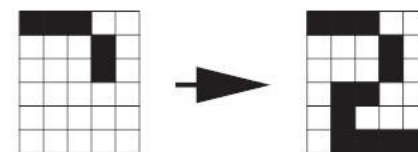
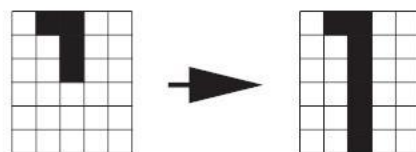
$$\mathbf{W} = \mathbf{p}_1 \mathbf{p}_1^T + \mathbf{p}_2 \mathbf{p}_2^T + \mathbf{p}_3 \mathbf{p}_3^T$$



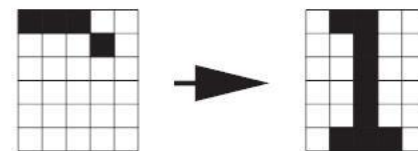
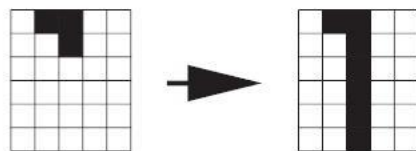
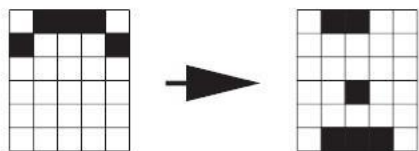
Tests



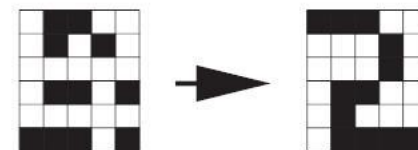
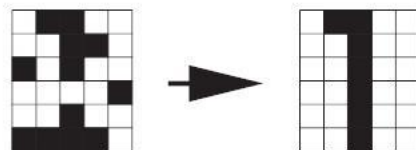
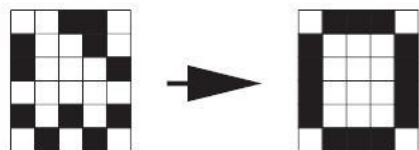
50% Occluded



67% Occluded



Noisy Patterns (7 pixels)



Variations of Hebbian Learning

Basic Rule: $\mathbf{W}^{new} = \mathbf{W}^{old} + \mathbf{t}_q \mathbf{p}_q^T$

Learning Rate: $\mathbf{W}^{new} = \mathbf{W}^{old} + \alpha \mathbf{t}_q \mathbf{p}_q^T$

Smoothing: $\mathbf{W}^{new} = \mathbf{W}^{old} + \alpha \mathbf{t}_q \mathbf{p}_q^T - \gamma \mathbf{W}^{old} = (1 - \gamma) \mathbf{W}^{old} + \alpha \mathbf{t}_q \mathbf{p}_q^T$

Delta Rule: $\mathbf{W}^{new} = \mathbf{W}^{old} + \alpha (\mathbf{t}_q - \mathbf{a}_q) \mathbf{p}_q^T$

Unsupervised: $\mathbf{W}^{new} = \mathbf{W}^{old} + \alpha \mathbf{a}_q \mathbf{p}_q^T$