

Topics

Numerical Methods

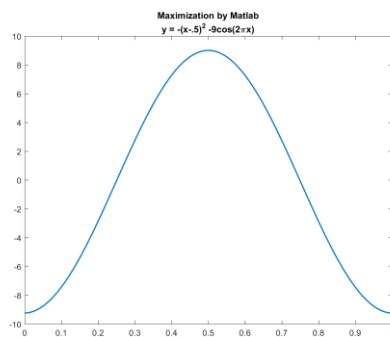
- Optimization
- Integration

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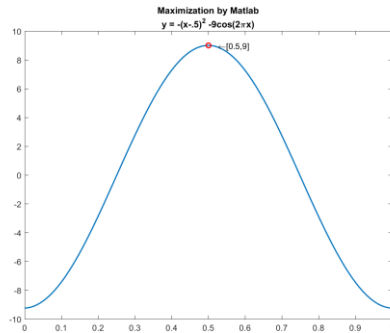
```
function illustrateMax
figure;
x=0:0.01:1;
plot(x,y(x),'linewidth',1.5);
title(['Maximization by Matlab','y = -(x-.5)^2 -9cos(2\pi x)']);
print -dpng max1

figure;
[xOpt,fval] = fminunc(@negY,0);
plot(x,y(x),xOpt,-fval,'or','linewidth',1.5);
title(['Maximization by Matlab','y = -(x-.5)^2 -9cos(2\pi x)']);
text(xOpt,-fval,[' \leftarrow',num2str(xOpt),',',num2str(-fval),'\n']);
print -dpng max2

end

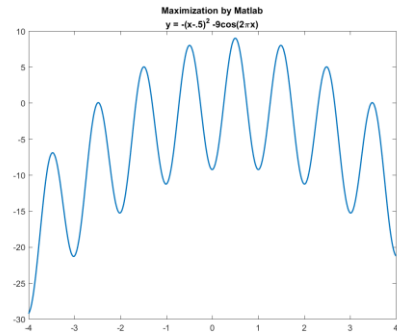
function negY = negY(x)
negY = -y(x);
end

function y = y(x)
y = -(x-.5).^2 -9*cos(2*pi*x);
end
```



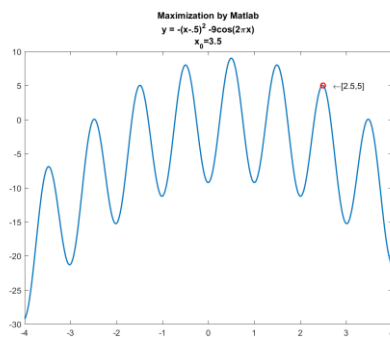
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Search algorithms

Objectives:

- Get close to the *global* right answer
- Compute as few objective functions as possible

Algorithms:

- Grid search
- Hill climbing

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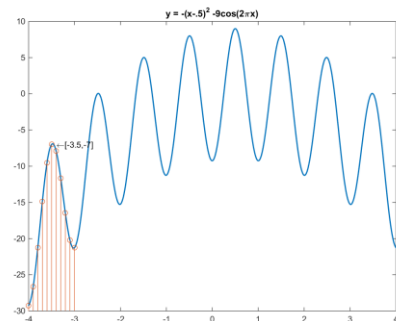
Methods

Grid search

- How fine a grid?
- Where to locate grid?
- *How many* function evaluations did you say?

Hill climbing

- Global vs local optimum
- Pick search direction
- Choose step size
- Stopping rule

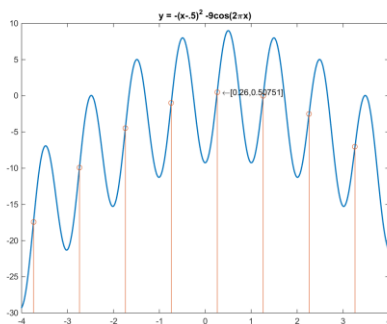


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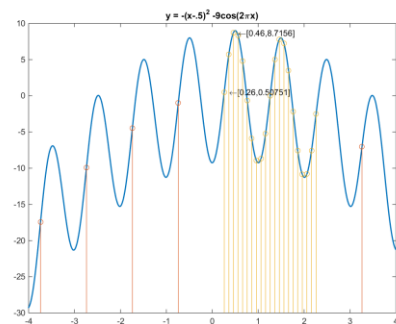
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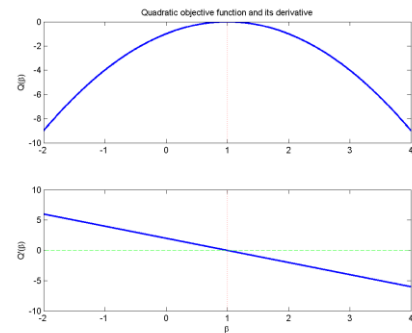
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Curse of dimensionality

1,000 grid points per dimension

- 2 parameters → 1 million function evaluations
- 10 parameters → 10^{30} function evaluations



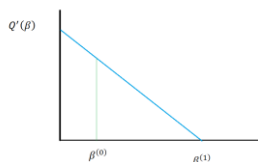
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First derivative



$$Q''(\beta^{(0)}) = \frac{Q'(\beta^{(0)}) - 0}{\beta^{(0)} - \beta^{(1)}}$$

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Finding maximum

$$Q''(\beta^{(0)}) = \frac{Q'(\beta^{(0)}) - 0}{\beta^{(0)} - \beta^{(1)}}$$

Newton's method

$$\beta^{(1)} = \beta^{(0)} - \frac{Q'(\beta^{(0)})}{Q''(\beta^{(0)})}$$

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Least squares by Newton's method

$$\begin{aligned}
 -ssr(\hat{\beta}) &= -\sum (y - \hat{\beta}x)^2 \\
 -ssr'(\hat{\beta}) &= -2\sum (y - \hat{\beta}x)(-x) \\
 &= 2(\sum yx - \hat{\beta}\sum x^2) \\
 -ssr''(\hat{\beta}) &= -2\sum x^2 \\
 \beta^{(1)} &= \beta^{(0)} - \frac{2(\sum yx - \beta^{(0)}\sum x^2)}{-2\sum x^2} \\
 \beta^{(1)} &= \beta^{(0)} + \frac{\sum yx}{\sum x^2} - \beta^{(0)}
 \end{aligned}$$

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Newton's method example

$$\begin{aligned}
 Q(x) &= -(x - .5)^2 - 9 \cos(2\pi x) \\
 Q'(x) &= -2(x - .5) + 2 \cdot 9 \cdot \pi \cdot \sin(2\pi x) \\
 Q''(x) &= -2 + (2\pi)^2 \cdot 9 \cdot \cos(2\pi x)
 \end{aligned}$$

$$\begin{aligned}
 x^{(j+1)} &= x^{(j)} - \frac{Q'(x^{(j)})}{Q''(x^{(j)})} \\
 x^{(j+1)} &= x^{(j)} - \frac{-2(x - .5) + 2 \cdot 9 \cdot \pi \cdot \sin(2\pi x)}{-2 + (2\pi)^2 \cdot 9 \cdot \cos(2\pi x)}
 \end{aligned}$$

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Matlab snippet

```

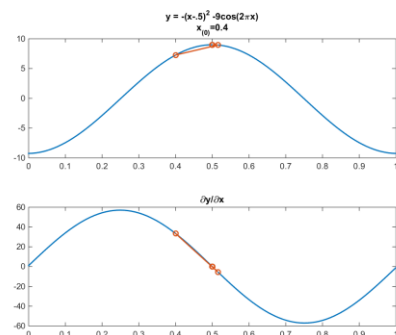
xGuess(1) = 0.4;
yGuess(1) = y(xGuess(1));

for it = 2:nIter
    xGuess(it) = xGuess(it-1) -
        dy(xGuess(it-1))/d2y(xGuess(it-1));
    yGuess(it) = y(xGuess(it));
end

```

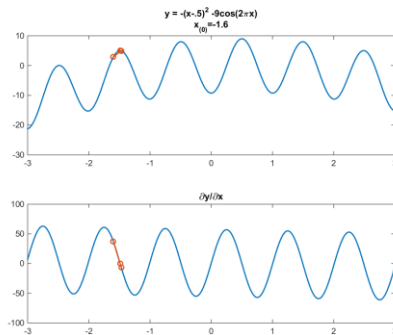
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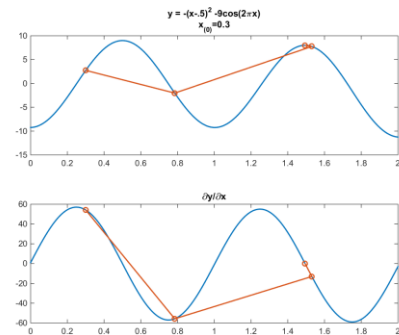
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Step-size adjustment

$$\alpha^{(j)} = 1$$

$$\beta^{(j+1)} = \beta^{(j)} - \alpha^{(j)} \frac{Q'(\beta^{(j)})}{Q''(\beta^{(j)})}$$

If $Q^{(j+1)} < Q^{(j)}$, $\alpha^{(j)} = \alpha^{(j)}/2$ (If α gets too small, punt.)

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Quasi-Newton in matrix form

$$\beta^{(j+1)} = \beta^{(j)} - [Q''(\beta^{(j)})]^{-1} Q'(\beta^{(j)})$$

$$\beta^{(j+1)} = \beta^{(j)} - D_{(j)}^{-1} Q'(\beta^{(j)})$$

- $D \approx Q''$, but guaranteed negative definite

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Berndt-Hall-Hall-Hausman (BHHH)

$$I \equiv E \left(\left(\frac{\partial}{\partial \theta} \log f(x|\theta) \right)^2 \right) = -E \left(\frac{\partial^2}{\partial \theta^2} \log f(x|\theta) \right)$$

$$D = - \sum_{i=1}^n \left(\frac{\partial}{\partial \theta} \log f(x_i|\theta) \right) \left(\frac{\partial}{\partial \theta} \log f(x_i|\theta) \right)'$$

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Gauss-Newton Regression

$$y_i = g(x_i, \beta) + \varepsilon_i$$

$$Q(\beta) = - \sum (y_i - g(x_i, \beta))^2$$

$$e_i(\beta) \approx e_i(\beta^{(j)}) - \frac{\partial g(x_i, \beta^{(j)})}{\partial \beta} (\beta - \beta^{(j)})$$

$$e_i(\beta^{(j)}) = \frac{\partial g(x_i, \beta^{(j)})}{\partial \beta} \Delta + v$$

$$\beta^{(j+1)} = \beta^{(j)} + \hat{\Delta}$$

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Stopping rules

- $Q(\beta^{(j+1)}) - Q(\beta^{(j)})$ is small
- $Q(\beta^{(j)})'$ is small
- $\beta^{(j+1)} - \beta^{(j)}$ is small

Always: **Stop if too many iterations and computer is overheating.**

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Matlab integral

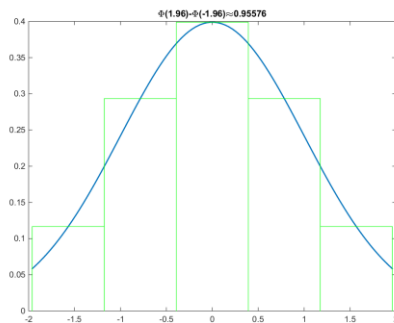
```
>> integral(@normpdf,-1.96,1.96)
```

```
ans =
```

```
0.9500
```

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Numerical quadrature

$$F = \int_l^u f(x) dx$$

$$A_i \approx (a_i - a_{i-1}) f\left(\frac{a_i + a_{i-1}}{2}\right)$$

$$F \approx \sum_{i=1}^n A_i$$

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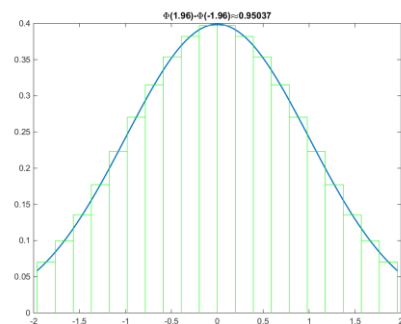
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```
nRectangles = 5;
endPoints =
linspace(1,u,nRectangles+1);

width = endPoints(2)-endPoints(1);
height =
normpdf((endPoints(2:end)+endPoints(1
:end-1))/2);
F = sum(width*height);
```

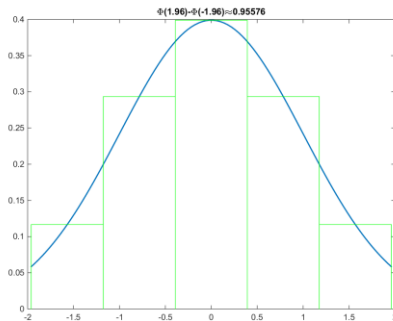
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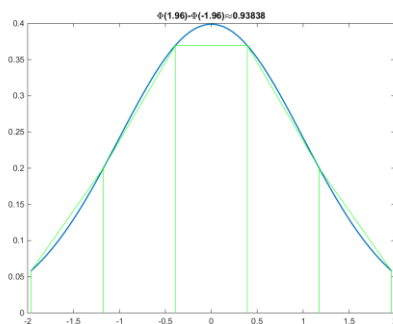
Trapezoidal rule

Using the formula for the area of a trapezoid which is the rectangle (base times height) plus the triangle (1/2 base times height.)

$$\begin{aligned}
 A_i &\approx (a_i - a_{i-1})f(a_i) \\
 &\quad + \frac{1}{2}(a_i - a_{i-1})(f(a_{i-1}) - f(a_i)) \\
 &= \frac{a_i - a_{i-1}}{2} (f(a_{i-1}) + f(a_i))
 \end{aligned}$$

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Simpson's rule

Parabola through $f(a_{i-1})$, $f(a_i)$, and the midpoint $f\left(\frac{a_{i-1}+a_i}{2}\right)$.

$$\begin{aligned}
 A_i &\approx \frac{a_i - a_{i-1}}{6} \left(f(a_{i-1}) + 4f\left(\frac{a_{i-1} + a_i}{2}\right) \right. \\
 &\quad \left. + f(a_i) \right)
 \end{aligned}$$

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Matlab integral

`integral(fun,a,b)`

uses an adaptive quadrature to integrate the function “fun” between the points a and b.

`integral2(fun,xmin,xmax,ymin,ymax)`

does the same thing in two dimensions

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Integrate multiple dimensions

$$\begin{aligned} & \iint_{l_y, l_x}^{u_y, u_x} f(x, y) dx dy \\ & \int_{l_y}^{u_y} \left[\int_{l_x}^{u_x} f(x, y) dx \right] dy \\ & A(y) \approx \int_{l_x}^{u_x} f(x, y) dx \\ & A \approx \int_{l_y}^{u_y} A(y) dy \end{aligned}$$

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Question for class

Compute an estimate of π by the following technique of Monte Carlo integration. Draw random $\{x, y\}$ pairs uniform between 0 and 1. Then decide if the point is inside or outside the unit circle. Since the fraction of points inside the unit circle corresponds to the area of a quarter unit circle, you can estimate π by four times the fraction inside the circle. Do this for a various numbers of random draws and plot the estimates of π against the number of draws.

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One example of Monte Carlo Integration

$$\int_l^u f(x) dx \approx \frac{u-l}{n} \sum f(\tilde{x})$$

where \tilde{x} is drawn randomly.

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```

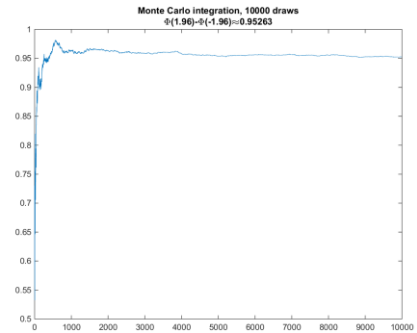
reset(RandStream.getGlobalStream);
l = norminv(.025);
u = norminv(.975);

nPoints = 10000;
x = l + (u-l)*rand(nPoints,1);
width = (u-l)./(1:nPoints)';
estimate =
width.*cumsum(normpdf(x));

```

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