

# Properties of OLS Estimators

## Econometrics II

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# Overview

Reference: B. Hansen Econometrics Chapter 4.1-4.7

- Conditional Distribution of OLSE
  - ▶ mean
  - ▶ variance
- Unconditional Distribution of OLSE
  - ▶ mean
- Optimality of Least Squares Estimators
- Conditional moments of residuals and standardized residuals

# Mean and Variance of Estimators

- begin with simple setting

$$y_i = \mu + u_i$$

- ▶  $\mathbb{E}(u_i) = 0$  by construction ( $u_i = e_i$ )
- ▶ corresponds to a model with a single covariate  $x_i = 1$

- OLS estimator is  $\bar{y}$
- mean of  $\bar{y}$

$$\mathbb{E}(\bar{y}) = \frac{1}{n} \sum_{i=1}^n \mathbb{E}(y_i) = \mu$$

- ▶ required assumption:  $\mathbb{E}(y_i) = \mu$
- ▶ the sample mean is unbiased, and hence the OLSE, is unbiased

An estimator  $\hat{\theta}$  for  $\theta$  is (mean) **unbiased** if  $\mathbb{E}(\hat{\theta}) = \theta$ .

# Variance: Sample Mean

- begin with

$$\begin{aligned}y_i - \mu &= u_i \\ \bar{y} - \mu &= \frac{1}{n} \sum_{i=1}^n u_i\end{aligned}$$

- variance of  $\bar{y}$

$$\mathbb{E} (\bar{y} - \mu)^2 = \frac{1}{n^2} \sum_{i=1}^n \text{Var} (u_i) = \frac{1}{n} \sigma^2$$

- ▶ required assumption:  $\text{Var} (u_i) = \sigma^2$
- ▶ required assumption:  $\text{Cov} (u_i, u_j) = 0$

# OLSE General Setting

- general setting,  $k$  explanatory variables

*Assumption 1 (Linear Regression Model).*

*The observations  $(y_i, x_i)$  come from a random sample and satisfy the linear regression equation*

$$\begin{aligned}y_i &= x_i^T \beta + u_i \\ \mathbb{E}(u_i | x_i) &= 0.\end{aligned}$$

*The variables have finite second moments*

$$\mathbb{E}(y_i^2) < \infty$$

$$\mathbb{E} \|x_i\| < \infty,$$

*and an invertible design matrix*

$$\mathbb{E}(x_i x_i^T) > 0.$$

# Mean: OLSE Summation Notation (Student Annotation)

## Mean: OLSE Matrix Notation (Student Annotation)

## Mean: OLS Matrix Notation - Decomposition

- insert  $y = X\beta + u$  into the formula for  $\hat{\beta}$

$$\begin{aligned}\hat{\beta} &= (X^T X)^{-1} X^T (X\beta + u) \\ &= \beta + (X^T X)^{-1} X^T u\end{aligned}$$

- ▶ useful linear decomposition of the estimator into  $\beta$  and stochastic component,  $(X^T X)^{-1} X^T u$

- again we calculate

$$\mathbb{E}(\hat{\beta} - \beta | X) = (X^T X)^{-1} X^T \mathbb{E}(u | X)$$

$$\text{▶ } \mathbb{E}(u | X) = \begin{pmatrix} \vdots \\ \mathbb{E}(u_i | X) \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \mathbb{E}(u_i | x_i) \\ \vdots \end{pmatrix} = \mathbf{0}$$

$$\star \mathbb{E}(\hat{\beta} - \beta | X) = \mathbf{0}$$



# Unbiasedness of the OLS Estimator

- applying the law of iterated expectations

$$\mathbb{E}(\hat{\beta}) = \mathbb{E}\left(\mathbb{E}(\hat{\beta}|X)\right) = \beta$$

- we have shown the following theorem

*Theorem (Mean of OLSE).*

*In the linear regression model of Assumption 1:*

1.  $\mathbb{E}(\hat{\beta}) = \beta;$
2.  $\mathbb{E}(\hat{\beta}|X) = \beta.$

- 1) says the distribution of  $\hat{\beta}$  is centered at  $\beta$
- 2) a stronger result,  $\hat{\beta}$  is unbiased for any realization of  $X$

# Variance and Conditional Variance Matrices

- for  $Z$  an  $r \times 1$  random vector, define the  $r \times r$  covariance matrix

$$\begin{aligned}\text{Var}(Z) &= \mathbb{E} \left( (Z - \mathbb{E}Z) (Z - \mathbb{E}Z)^T \right) \\ &= \mathbb{E}ZZ^T - \mathbb{E}Z (\mathbb{E}Z)^T\end{aligned}$$

- for any pair  $(Z, X)$  define the conditional covariance matrix

$$\text{Var}(Z|X) = \mathbb{E} \left( (Z - \mathbb{E}(Z|X)) (Z - \mathbb{E}(Z|X))^T | X \right)$$

- conditional covariance matrix of the OLSE

$$V := \text{Var}(\hat{\beta}|X)$$

# Error Variance Assumptions

- we consider the general case of heteroskedastic regression

$$\mathbb{E} (u_i^2 | x_i) = \sigma^2 (x_i) = \sigma_i^2$$

- we also consider the specialized case of homoskedastic regression

*Assumption 2 (Homoskedastic Linear Regression Model).*

*In addition to Assumption 1,*

$$\mathbb{E} (u_i^2 | x_i) = \sigma^2 (x_i) = \sigma^2,$$

*is independent of  $x_i$ .*

## Conditional Covariance Matrix of the Error

- conditional covariance matrix of  $n \times 1$  error  $u$  is the  $n \times n$  matrix

$$D = \mathbb{E} \left( uu^T | X \right)$$

- $i$ 'th diagonal element  $\mathbb{E} \left( u_i^2 | X \right) = \mathbb{E} \left( u_i^2 | x_i \right) = \sigma_i^2$
- $ij$ 'th off-diagonal element  $\mathbb{E} \left( u_i u_j | X \right) = \mathbb{E} \left( u_i | x_i \right) \mathbb{E} \left( u_j | x_j \right) = 0$

- $D$  is a diagonal matrix

$$D = \text{diag}(\sigma_1^2, \dots, \sigma_n^2) = \begin{pmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n^2 \end{pmatrix}$$

- under homoskedasticity

$$\begin{aligned} \mathbb{E} \left( u_i^2 | x_i \right) &= \sigma^2(x_i) = \sigma^2 \\ D &= I_n \sigma^2 \end{aligned}$$

# Conditional Variance of Linear Combinations

- for any  $n \times r$  matrix  $A = A(X)$

$$\text{Var} \left( A^T y | X \right) = \text{Var} \left( A^T u | X \right) = A^T D A$$

- in particular  $\hat{\beta} = A^T y$

- ▶  $A = X (X^T X)^{-1}$

$$V = \text{Var} \left( \hat{\beta} | X \right) = A^T D A = \left( X^T X \right)^{-1} X^T D X \left( X^T X \right)^{-1}$$

- ▶ sandwich form

- ▶  $X^T D X = \sum_{i=1}^n x_i^2 \sigma_i^2$

- ★ weighted version of  $X^T X$

- under homoskedasticity,  $D = I_n \sigma^2$

$$\begin{aligned} X^T D X &= X^T X \sigma^2 \\ V &= \left( X^T X \right)^{-1} \sigma^2 \end{aligned}$$

# Variance of OLSE

*Theorem (Variance of the OLSE).*

*In the linear regression model of Assumption 1:*

$$V := \text{Var} \left( \hat{\beta} | X \right) = (X^T X)^{-1} X^T D X (X^T X)^{-1}$$

*with  $D = \text{diag}(\sigma_1^2, \dots, \sigma_n^2)$ .*

*In the homoskedastic linear regression model of Assumption 2*

$$V = (X^T X)^{-1} \sigma^2.$$

# Gauss-Markov Theorem: Linear Unbiased Estimators

- consider the class of estimators of  $\beta$  that are linear functions of  $y$

$$\tilde{\beta} = A^T y$$

- ▶  $A$  an  $n \times k$  function of  $X$
  - ▶ OLS is a special case with  $A = (X^T X)^{-1} X$
- what is the best choice of  $A$ ?
  - ▶ best means smallest variance
- Gauss-Markov Theorem:  $A = (X^T X)^{-1} X$  is the best choice for unbiased, homoskedastic models

*Theorem (Gauss-Markov).*

*1. In the linear regression model of Assumption 1:  
The best linear unbiased estimator is*

$$\tilde{\beta} = (X^T D^{-1} X)^{-1} X^T D^{-1} y.$$

*2. In the homoskedastic linear regression model of  
Assumption 2:*

*The best linear unbiased estimator is the OLSE*

$$\hat{\beta} = (X^T X)^{-1} X^T y.$$



# Gauss-Markov Theorem Interpretation

- ① for linear (heteroskedastic) regression models
  - ① BLUE is  $\tilde{\beta}$  - the Generalized LSE (not OLSE)
  - ② infeasible as  $D$  is unknown
  - ③ need an estimator of  $D$  to have a practical alternative to  $\hat{\beta}$
- ② for linear homoskedastic regression models
  - ① BLUE is  $\hat{\beta}$ 
    - ① special case of  $\tilde{\beta}$  with  $D = I_n\sigma^2$
  - ② limited efficiency result
    - ① restricted to homoskedastic models and linear unbiased estimators
    - ② could be biased or nonlinear estimators with lower MSE

## Proof of Gauss-Markov Theorem

# Residuals

- residuals

$$\begin{aligned}\hat{u}_i &= y_i - x_i^T \hat{\beta} \\ \hat{u} &= My = Mu\end{aligned}$$

- ▶  $M = I_n - X(X^T X)^{-1} X^T$  and  $MX = \mathbf{0}$

- conditional mean

$$\mathbb{E}(\hat{u}|X) = \mathbb{E}(Mu|X) = M\mathbb{E}(u|X) = \mathbf{0}$$

- conditional variance

$$\text{Var}(\hat{u}|X) = M \cdot \text{Var}(u|X) \cdot M = MDM$$

# Conditional Variance of Residuals

- under conditional homoskedasticity (Assumption 2)

$$\begin{aligned}\mathbb{E}(u_i^2|x_i) &= \sigma^2 \\ \text{Var}(\hat{u}|X) &= M\sigma^2\end{aligned}$$

- ▶ this follows from the fact that  $M$  is idempotent (and symmetric)
- $u$  is homoskedastic but  $\hat{u}$  is heteroskedastic
  - ▶ conditional variance equals  $M$  not  $I_n\sigma^2$
- $i$ 'th diagonal element of  $M\sigma^2$  is  $\text{Var}(\hat{u}_i|X)$

$$\text{Var}(\hat{u}_i|X) = \mathbb{E}(\hat{u}_i^2|X) = (1 - h_{ii})\sigma^2$$

- ▶  $h_{ii} = x_i^T (X^T X)^{-1} x_i$ 
  - ★ a function of  $x_i$ , therefore residuals are heteroskedastic even if errors are homoskedastic

# Standardized Residuals

- rescale to get constant conditional variance

$$\bar{u}_i = (1 - h_{ii})^{-1/2} \hat{u}_i$$

$$\text{Var}(\bar{u}_i | X) = \sigma^2$$

- standardized residuals have conditional mean and conditional variance that are identical to the conditional mean and conditional variance of the errors  $u$

# Error Variance Estimator

- error variance  $\sigma^2 := \mathbb{E}(u_i^2)$
- method-of-moments estimator

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n \hat{u}_i^2$$

- ▶ MLE for normal regression model

$$\hat{\sigma}^2 = \frac{1}{n} \hat{u}^T \hat{u} = \frac{1}{n} u^T M u = \frac{1}{n} \text{tr}(u^T M u) = \frac{1}{n} \text{tr}(M u u^T)$$

- conditional expectation

$$\begin{aligned} \mathbb{E}(\hat{\sigma}^2 | X) &= \frac{1}{n} \text{tr}(\mathbb{E}(M u u^T | X)) \\ &= \frac{1}{n} \text{tr}(M \mathbb{E}(u u^T | X)) \\ &= \frac{1}{n} \text{tr}(M D) \end{aligned}$$

## Error Variance Estimator Bias

- under conditional homoskedasticity  $D = I_n \sigma^2$

$$\begin{aligned}\mathbb{E}(\hat{\sigma}^2 | X) &= \frac{1}{n} \text{tr}(M \sigma^2) \\ &= \left( \frac{n-k}{n} \right) \sigma^2\end{aligned}$$

- another way to see this

$$\begin{aligned}\mathbb{E}(\hat{\sigma}^2 | X) &= \frac{1}{n} \sum_{i=1}^n \mathbb{E}(\hat{u}_i^2 | X) \\ &= \frac{1}{n} \sum_{i=1}^n (1 - h_{ii}) \sigma^2 \\ &= \left( \frac{n-k}{n} \right) \sigma^2\end{aligned}$$

$\hat{\sigma}^2$  is biased toward zero by a factor of  $\frac{k}{n}$

# Unbiased Error Variance Estimation

- bias takes scale form, therefore rescale to get unbiased estimator

$$s^2 = \frac{n}{n-k} \hat{\sigma}^2 = \frac{1}{n-k} \sum_{i=1}^n \hat{u}_i^2$$

- ▶ by the earlier calculation  $\mathbb{E}(s^2|X) = \sigma^2$  so  $\mathbb{E}(s^2) = \sigma^2$

★ bias-corrected estimator, widely used

- bias-corrected estimator can also be constructed from standardized residuals

$$\begin{aligned}\bar{\sigma}^2 &= \frac{1}{n} \sum_{i=1}^n \bar{u}_i^2 = \frac{1}{n} \sum_{i=1}^n (1 - h_{ii})^{-1} \hat{u}_i^2 \\ \mathbb{E}(\bar{\sigma}^2|X) &= \sigma^2 \text{ so } \mathbb{E}(\bar{\sigma}^2) = \sigma^2\end{aligned}$$

- if  $n$  is not large relative to  $k$ , use a bias-corrected estimator

# Proof of Gauss-Markov Theorem

- let  $A$  be any  $n \times k$  function of  $X$  with  $\tilde{\beta} = A^T y$ 
  - ▶ under Assumption 2 ,  $\text{Var}(A^T y | X) = A^T A \sigma^2$
  - ▶  $\hat{\beta}$  is efficient if  $A^T A - (X^T X)^{-1}$  is a positive semi-definite matrix
  - ▶ let  $C = A - X(X^T X)^{-1}$
- $A^T A - (X^T X)^{-1}$  equals
- $= (C + X(X^T X)^{-1})^T (C + X(X^T X)^{-1}) - (X^T X)^{-1}$
- $= C^T C - C^T X(X^T X)^{-1} - (X^T X)^{-1} X^T C + (X^T X)^{-1} - (X^T X)^{-1}$ 
  - ▶ note  $\mathbb{E}(\tilde{\beta} | X) = A^T X \beta + A^T \mathbb{E}(u | X) = A^T X \beta$
  - ▶  $\tilde{\beta}$  unbiased  $\Rightarrow A^T X = I_k \Rightarrow C^T X = 0$
- $A^T A - (X^T X)^{-1} = C^T C$ 
  - ▶ if  $M = C^T C$  then  $M$  is positive semi-definite, as required

Return to Gauss-Markov Theorem