

Projections and Influence

Econometrics II

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Overview

Reference: B. Hansen Econometrics Chapter 3.10-3.18

- Projection Matrix (Hat Matrix)
- Orthogonal Projection Matrix (Annihilator Matrix)
- How do we estimate σ^2 ?
- Predicted Values
- Leverage and Influence

Projection Matrix

- projection (hat) matrix

$$P_{n \times n} = X \left(X^T X \right)^{-1} X^T$$

- why projection?

- ▶ $PX = X \left(X^T X \right)^{-1} X^T X = X$

- ★ holds for any matrix in the range space of X

- why hat?

- ▶ $P_y = X \left(X^T X \right)^{-1} X^T y = X \hat{\beta} := \hat{y}$

- ★ creates fitted values

- ★ $X = \mathbf{1}$ (n vector of ones) $P = \frac{1}{n} \mathbf{1} \mathbf{1}^T$

- ★ $P_y = \mathbf{1} \bar{y}$ (fitted value is the sample mean)

Projection Matrix Properties

- range space of X consists of matrices formed from columns of X
 - ▶ $Z = X\Gamma$ for some matrix Γ

$$PZ = PX\Gamma = X\Gamma = Z$$

- important example, partition $X = [X_1 \ X_2]$
 - ▶ $PX_1 = X_1$
- projection matrix is symmetric

$$P^T = P$$

- projection matrix is idempotent

$$PP = P$$

- ▶ $PX = X$ implies

$$PP = PX \left(X^T X \right)^{-1} X^T = P$$

Projection Matrix Symmetry (Student Annotation)

Leverage

- i^{th} diagonal element of P

$$h_{ii} = x_i^T (X^T X)^{-1} x_i$$

- ▶ *leverage* of observation i
- ▶ property 1: $0 \leq h_{ii} \leq 1$
- ▶ property 2: $\sum_{i=1}^n h_{ii} = k$

Proof of Property 2

Orthogonal Projection

- orthogonal projection matrix (annihilator matrix)

$$M = I_n - P$$

- why orthogonal projection?
 - ▶ $MX = 0$ therefore M and X are orthogonal
- why annihilator matrix?
 - ▶ for any matrix Z in the range space of X
 - ★ $MZ = Z - PZ = 0$
 - ▶ examples
 - ★ $MX_1 = 0$
 - ★ $MP = 0$
- M creates least squares residuals

$$My = y - Py = y - \hat{y} = \hat{u}$$

Properties of Orthogonal Projection

- M satisfies:

- ▶ symmetric $M^T = I_n^T - P^T = M$
- ▶ idempotent $MM = M(I_n - P) = M$
- ▶ $\text{tr}(M) = n - k$

- special example $X = \mathbf{1}$

- ▶ $M_1 y = \left(I_n - \frac{1}{n} \mathbf{1} \mathbf{1}^T \right) = \mathbf{y} - \mathbf{1} \bar{y}$

- ★ demeaned values

- $\hat{u} = My = M(X\beta + u) = Mu$

- ▶ free of dependence on the regression coefficient β

Estimation of the Error Variance (Student Annotation)

An Interesting Fact Regarding the Variance Estimator

consider

$$\begin{aligned}\tilde{\sigma}^2 - \hat{\sigma}^2 &= n^{-1} u^T u - n^{-1} \hat{u}^T \hat{u} \\ &= n^{-1} u^T (I_n - M) u \\ &= n^{-1} u^T P u \\ &\geq 0\end{aligned}$$

- the last inequality holds because
 - ▶ P is positive semidefinite
 - ▶ $u^T P u$ is a quadratic form
- feasible estimator is numerically smaller than ideal estimator

Analysis of Variance: Orthogonal Decomposition

- orthogonal decomposition

$$y = Py + My := \hat{y} + \hat{u}$$

- ▶ orthogonal because $\hat{y}^T \hat{u} = y^T P M y = 0$

- it follows that

$$y^T y = \hat{y}^T \hat{y} + \hat{u}^T \hat{u}$$

- ▶ or

$$\sum_{i=1}^n y_i^2 = \sum_{i=1}^n \hat{y}_i^2 + \sum_{i=1}^n \hat{u}_i^2$$

Analysis of Variance Formula

- subtracting \bar{y} from both sides of the decomposition

$$y - 1\bar{y} = (\hat{y} - 1\bar{y}) + \hat{u}$$

- orthogonal decomposition when X contains a constant: $1^T \hat{u} = 0$
- $(y - 1\bar{y})^T (y - 1\bar{y}) = (\hat{y} - 1\bar{y})^T (\hat{y} - 1\bar{y}) + \hat{u}^T \hat{u}$
- analysis of variance formula for LS regression

$$\sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n (\hat{y}_i - \bar{y})^2 + \sum_{i=1}^n \hat{u}_i^2$$

- coefficient of determination (algebraic measure of fit, we have better measures that require statistical derivation)

$$R^2 = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2} = 1 - \frac{\sum_{i=1}^n \hat{u}_i^2}{\sum_{i=1}^n (y_i - \bar{y})^2}$$

Regression Components

- partition $X = [X_1 \ X_2]$
- OLS regression of y on X yields
 - ▶ $y = X_1\hat{\beta}_1 + X_2\hat{\beta}_2 + \hat{u}$
- algebraic expressions for $\hat{\beta}_1$ and $\hat{\beta}_2$ identical to algebra for population coefficients

$$\hat{\beta}_1 = (X_1^T M_2 X_1)^{-1} (X_1^T M_2 y)$$

$$\hat{\beta}_2 = (X_2^T M_1 X_2)^{-1} (X_2^T M_1 y)$$

- ▶ $M_1 = I_n - X_1 (X_1^T X_1)^{-1} X_1^T$
- ▶ $M_2 = I_n - X_2 (X_2^T X_2)^{-1} X_2^T$
- ▶ $\hat{\beta}_1$ - projection onto M_2 removes component correlated with X_2
 - ★ in essence, "holding X_2 constant"

Matrix Algebra Derivation

Residual Regression

First recognized by Frisch and Waugh (1933)

- because $M_1 = M_1 M_1$

$$\begin{aligned}\hat{\beta}_2 &= \left(X_2^T M_1 M_1 X_2 \right)^{-1} \left(X_2^T M_1 M_1 y \right) \\ &= \left(\tilde{X}_2^T \tilde{X}_2 \right)^{-1} \left(\tilde{X}_2^T \bar{u}_1 \right)\end{aligned}$$

- ▶ $\tilde{X}_2 = M_1 X_2$ $\bar{u}_1 = M_1 y$
- ▶ proves the following theorem

Theorem (Frisch-Waugh-Lovell). In the linear model $y = X_1\beta_1 + X_2\beta_2 + u$ the OLS estimator of β_2 and the OLS residuals \hat{u} may be equivalently computed by either the OLS regression or via the following algorithm:

1. *Regress y on X_1 , obtain residuals \bar{u}_1 ;*
2. *Regress X_2 on X_1 , obtain residuals \tilde{X}_2 ;*
3. *Regress \bar{u}_1 on \tilde{X}_2 , obtain OLSE $\hat{\beta}_2$ and residuals \hat{u} .*

Residual Regression Continued

- the estimated coefficient $\hat{\beta}_2$ numerically equals the regression of y on the covariates X_2 after the covariates X_1 have been linearly projected out
- important example (deviations from means): $X_1 = 1$ X_2 the observed covariates
 - $M_1 = I_n - 1(1^T 1)^{-1} 1^T$
 - $\tilde{X}_2 = X_2 - \bar{X}_2 \quad \bar{u}_1 = y - \bar{y}$

$$\hat{\beta}_2 = \left(\sum_{i=1}^n (x_{2i} - \bar{x}_2) (x_{2i} - \bar{x}_2)^T \right)^{-1} \left(\sum_{i=1}^n (x_{2i} - \bar{x}_2) (y_i - \bar{y}) \right)$$

- Ragnar Frisch:
 - co-winner (with Jan Tinbergen) of 1st Nobel prize in Economics in 1969
 - formalized consumer, producer, and business cycle theory

Prediction Errors

- \hat{u}_i constructed from full sample, including y_i
 - ▶ not a prediction error
 - ▶ proper prediction should exclude y_i
- leave-one-out estimator excludes y_i

$$\begin{aligned}\hat{\beta}_{(-i)} &= \left(\frac{1}{n-1} \sum_{j \neq i} x_j x_j^T \right)^{-1} \left(\frac{1}{n-1} \sum_{j \neq i} x_j y_j \right) \\ &= \left(X_{(-i)}^T X_{(-i)} \right)^{-1} \left(X_{(-i)}^T y_{(-i)} \right) \quad \text{note } X_{(-i)} \text{ excludes row } i\end{aligned}$$

- leave-one-out predicted value $\tilde{y}_i = x_i^T \hat{\beta}_{(-i)}$
- prediction error (residual) $\tilde{u}_i = y_i - \tilde{y}_i$
- sample mean squared prediction error $n^{-1} \sum_{i=1}^n \tilde{u}_i^2$

Prediction Error Construction

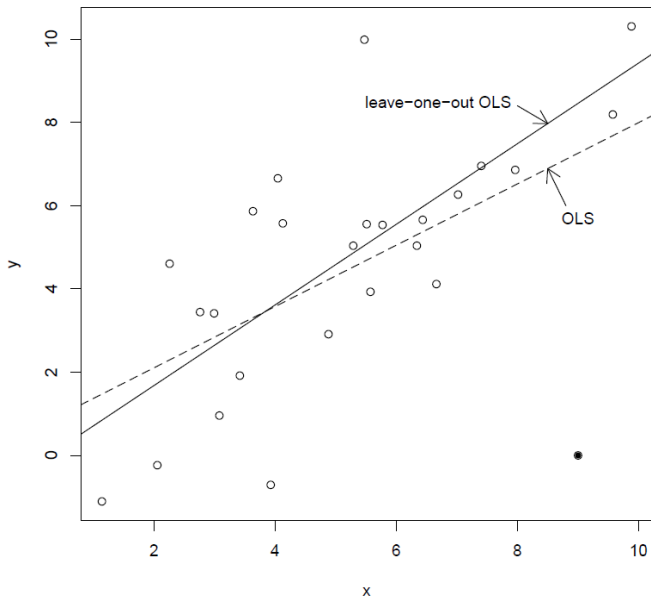
- convenient expression: $\hat{\beta}_{(-i)} = \hat{\beta} - (1 - h_{ii})^{-1} (X^T X)^{-1} x_i \hat{u}_i$
 - ▶ recall, leverage value (scalar) $h_{ii} = x_i^T (X^T X)^{-1} x_i$
- resulting simplified expression for prediction error, $\tilde{u}_i =$
 - ▶ $= y_i - x_i^T \hat{\beta}_{(-i)}$
 - ▶ $= y_i - x_i^T \hat{\beta} + (1 - h_{ii})^{-1} x_i^T (X^T X)^{-1} x_i \hat{u}_i$
 - ▶ $= \left(1 + (1 - h_{ii})^{-1} h_{ii}\right) \hat{u}_i$
 - ▶ $= (1 - h_{ii})^{-1} \hat{u}_i$
- for $M^* \stackrel{\text{def}}{=} \text{diag} \left\{ (1 - h_{11})^{-1}, \dots, (1 - h_{nn})^{-1} \right\}$

$$\tilde{u} = M^* \hat{u}$$

- ▶ computation of \tilde{u} does not require n estimations

Influential Observations

- influential if omission of observation induces a substantial change in the estimate
- example: consider the following figure with data generated as
 - ▶ $x_i \sim U[1, 10]$ $y_i \sim \mathcal{N}(x_i, 4)$
 - ▶ outlier $x_{26} = 9$ $y_{26} = 0$
 - ▶ note: must examine joint behavior to detect outlier
 - ★ neither x_{26} nor y_{26} are unusual relative to their marginal distributions



Calculation of Influence

- for coefficients of interest, calculate for each i

- ▶ $\hat{\beta} - \hat{\beta}_{(-i)} = (X^T X)^{-1} x_i \tilde{u}_i \quad \tilde{u}_i = (1 - h_{ii}) \hat{u}_i$

- ★ DFBETA - post estimation diagnostic in STATA
 - ★ Is there a meaningful change? (no magic threshold)
 - ★ hard to recommend other proposed diagnostics (DFITS, Cook's Distance, Welsch Distance) - not based on statistical theory

- for general assessment, study predicted value

- ▶ $Influence = \max_{1 \leq i \leq n} |\hat{y}_i - \tilde{y}_i|$

- ▶ $\hat{y}_i - \tilde{y}_i = x_i^T \hat{\beta} - x_i^T \hat{\beta}_{(-i)} = h_{ii} \tilde{u}_i$

- ▶ observation i is influential for the predicted value if h_{ii} and $|\tilde{u}_i|$ are large

- ★ h_{ii} large - x_i is far from its sample mean, leverage point
 - ★ leverage points are not necessarily influential

What to do with Influential Observations?

- due to data entry error, delete, termed "cleaning the data"
 - ▶ e.g. individual who is employed but has \$0 earnings
 - ▶ requires judgement, therefore proper empirical practice
 - ★ keep: source data in original form, revised data after cleaning, record describing the cleaning process
- not due to data entry error
 - ▶ do nothing, or alter the specification to properly model the influential observation
 - ▶ delete the observation - reduces the integrity of the results (viewed skeptically)

Influential Observation Example

- log wage regression for single Asian males
- $n = 268$ *Influence* = 0.29
 - ▶ most influential observation, when included, changes a fitted value of log wage by 0.29, or the wage by 29%!
- for this observation $h_{ii} = 0.33$ (recall, h_{ii} positive and sum to 1)
 - ▶ 1/3 of the leverage for the entire sample is contained in this observation
 - ▶ individual is 65 years old, 8 years of education, thus 51 years of (potential) experience
 - ▶ next highest level of experience is 41 years
- essentially estimating the conditional mean of *experience*=51 with only 1 observation
 - ▶ solution, estimate over a smaller range of experience, restrict sample to $\widehat{\text{experience}} \leq 45$
 - ▶ $\log \text{wage} = 0.144ed + 0.043exp - 0.095exp^2/100 + 0.531$
 - ▶ coefficient on exp and exp^2 increase slightly and *Influence* = 0.11
 - ▶ more robust estimate of conditional mean for most levels of experience
- Which to report? A matter of judgement

Normal Regression Model

- linear regression model with u_i independent of x_i with a normal distribution
 - ▶ $u_i|x_i \sim \mathcal{N}(0, \sigma^2)$ which implies $y_i|x_i \sim \mathcal{N}(x_i^T \beta, \sigma^2)$
- log-likelihood function

$$\begin{aligned}\log L(\beta, \sigma^2) &= \sum_{i=1}^n \log \frac{1}{(2\pi\sigma^2)^{\frac{1}{2}}} \exp \left(\frac{-1}{2\sigma^2} (y_i - x_i^T \beta)^2 \right) \\ &= -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log(\sigma^2) + \frac{1}{2\sigma^2} SSE_n(\beta)\end{aligned}$$

- ▶ β enters only through $SSE_n(\beta)$ thus $\hat{\beta}_{mle} = \hat{\beta}_{ols}$
- ▶ $\hat{\sigma}_{mle}^2$ - maximize $\log L(\hat{\beta}_{mle}, \sigma^2)$

★ FOC

$$\frac{\partial}{\partial \sigma^2} \log L(\hat{\beta}_{mle}, \hat{\sigma}^2) = -\frac{n}{2} \frac{1}{\hat{\sigma}^2} + \frac{SSE_n(\hat{\beta}_{mle})}{2(\hat{\sigma}^2)^2} = 0$$

★ $\hat{\sigma}_{mle}^2 = \frac{1}{n} \sum \hat{u}_i^2$

Normal (Gaussian) Regression Model 2

- the sample value of the log-likelihood

$$\log L\left(\hat{\beta}_{mle}, \hat{\sigma}_{mle}^2\right) = -\frac{n}{2}(\log(2\pi) + 1) - \frac{n}{2} \log\left(\hat{\sigma}_{mle}^2\right)$$

- ▶ this value, or the negative of this value, is reported as a measure of fit
- no surprise that $\hat{\beta}_{mle} = \hat{\beta}_{ols}$ - most loss functions have an ML equivalent
- Carl Friedrich Gauss (1777-1855) mathematician
 - ▶ proposed normal regression model, derived the OLSE as the MLE
 - ▶ claims to have discovered this in 1795 at the age of eighteen
 - ▶ not published until 1809
 - ▶ interest in the result reinforced by Laplace's simultaneous discovery of the CLT, which provided justification for viewing random disturbances as approximately normal

Proof of Projection Matrix Property 2

$$\begin{aligned} \text{tr}(P) &= \text{tr}\left(X\left(X^T X\right)^{-1} X^T\right) \\ &= \text{tr}\left(\left(X^T X\right)^{-1} X^T X\right) \\ &= \text{tr}\left(I_k\right) \\ &= k \end{aligned}$$

Return to Leverage

Derivation of Matrix Components

$$\hat{Q}_{xx} = \begin{bmatrix} \hat{Q}_{11} & \hat{Q}_{12} \\ \hat{Q}_{21} & \hat{Q}_{22} \end{bmatrix} = \begin{bmatrix} n^{-1} X_1^T X_1 & n^{-1} X_1^T X_2 \\ n^{-1} X_2^T X_1 & n^{-1} X_2^T X_2 \end{bmatrix}$$

$$\hat{Q}_{xy} = \begin{bmatrix} \hat{Q}_{1y} \\ \hat{Q}_{2y} \end{bmatrix} = \begin{bmatrix} n^{-1} X_1^T y \\ n^{-1} X_2^T y \end{bmatrix}$$

- partitioned matrix inversion formula yields

$$\hat{Q}_{xx}^{-1} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{Q}^{11} & \hat{Q}^{12} \\ \hat{Q}^{21} & \hat{Q}^{22} \end{bmatrix} = \begin{bmatrix} \hat{Q}_{11.2}^{-1} & -\hat{Q}_{11.2}^{-1} \hat{Q}_{12} \hat{Q}_{22}^{-1} \\ -\hat{Q}_{22.1}^{-1} \hat{Q}_{21} \hat{Q}_{11}^{-1} & \hat{Q}_{22.1}^{-1} \end{bmatrix}$$

$$\begin{aligned} \hat{\beta}_1 &= \hat{Q}_{11.2}^{-1} \left(\frac{1}{n} X_1^T y - \frac{1}{n} X_1^T X_2 \left(\frac{1}{n} X_2^T X_2 \right)^{-1} \frac{1}{n} X_2^T y \right) \\ &= \hat{Q}_{11.2}^{-1} \left(\frac{1}{n} X_1^T M_2 y \right) \end{aligned}$$

Derivation Continued

$$\widehat{Q}_{11 \cdot 2} = \widehat{Q}_{11} - \widehat{Q}_{12} \widehat{Q}_{22}^{-1} \widehat{Q}_{21}$$

$$\widehat{Q}_{22 \cdot 1} = \widehat{Q}_{22} - \widehat{Q}_{21} \widehat{Q}_{11}^{-1} \widehat{Q}_{12}$$

$$\begin{aligned}\widehat{Q}_{11 \cdot 2} &= \widehat{Q}_{11} - \widehat{Q}_{12} \widehat{Q}_{22}^{-1} \widehat{Q}_{21} \\ &= \frac{1}{n} X_1^T X_1 - \frac{1}{n} X_1^T X_2 \left(\frac{1}{n} X_2^T X_2 \right)^{-1} \frac{1}{n} X_2^T X_1 \\ &= \frac{1}{n} X_1^T M_2 X_1\end{aligned}$$

• therefore

$$\begin{aligned}\widehat{\beta}_1 &= \widehat{Q}_{11 \cdot 2}^{-1} \left(\frac{1}{n} X_1^T M_2 y \right) \\ &= \left(X_1^T M_2 X_1 \right)^{-1} X_1^T M_2 y\end{aligned}$$

Return to Regression Components