

# You Perturb It, You Pay For It According to $\mathcal{K}(A)$ : Norms and Error Analysis

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MTH 499-02

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- Norms: properties, types, examples

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- Theorems, results on norms
- Relative/absolute error in perturbations, conditioning number



## Definition

Let  $V$  be a vector space. A norm is a function  $\|\cdot\| : V \rightarrow \mathbb{R}^+$  that has the following properties:

- $\|x\| > 0$  if  $x \neq 0$ ,  $x \in V$
- $\|\lambda x\| = |\lambda| \|x\|$  if  $\lambda \in \mathbb{R}$ ,  $x \in V$
- $\|x + y\| \leq \|x\| + \|y\|$  for all  $x, y \in V$  (triangle inequality)

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Other comments:

- Norm can be thought of as generalization of absolute value
- Interpretation: vector length in  $\mathbb{R}^2$ ,  $\mathbb{R}^3$





Vector Norms:

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- $l_k$  norm

$$l_k = \|x\|_k = \left( \sum_{i=1}^n |x_i|^k \right)^{1/k} \quad \text{where } k \in \{1, 2, \dots\} \text{ and } x = (x_1, \dots, x_n)^T$$

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- Some common instances of the  $l_k$  norm:

$k$	$l_k$
1	$\ x\ _1 = \sum_{i=1}^n  x_i $
2	$\ x\ _2 = \left( \sum_{i=1}^n x_i^2 \right)^{1/2}$
$\infty$	$\ x\ _\infty = \max_{1 \leq i \leq n}  x_i $

- Consider vectors in  $\mathbb{R}^3$

$$x = (2, -1, 3)^T \quad y = (7, 2, 5)^T \quad z = (-3, 1, -9)^T$$

	$\ \cdot\ _1$	$\ \cdot\ _2$	$\ \cdot\ _\infty$
$x$			
$y$			
$z$			

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	$\ \cdot\ _1$	$\ \cdot\ _2$	$\ \cdot\ _\infty$
$x$	6		
$y$			
$z$			

$$\|x\|_1 = 2 + 1 + 3 = 6$$

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	$\ \cdot\ _1$	$\ \cdot\ _2$	$\ \cdot\ _\infty$
$x$	6	3.74	
$y$			
$z$			

$$\|x\|_2 = \sqrt{2^2 + 1^2 + 3^2} = 3.74$$

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$$\|x\|_\infty = 3$$

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	$\ \cdot\ _1$	$\ \cdot\ _2$	$\ \cdot\ _\infty$
$x$	6	3.74	3
$y$	14	8.83	7
$z$	13	9.54	9



## Definition

A matrix norm subordinate to a vector norm  $\|\cdot\|$  is defined as

$$\|A\| = \sup \{ \|Au\| : u \in \mathbb{R}^n, \|u\| = 1 \},$$

where  $A$  is an  $n \times n$  matrix.

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- Subordinate to vector norm  $\|\cdot\|_2$  is

$$\begin{aligned} \|A\|_2 &= \sup_{\|x\|_2=1} \{\|Ax\|_2\} \\ &= \sqrt{\rho(A^T A)}, \end{aligned}$$

where  $\rho(A^T A)$  is spectral radius of  $A^T A$ , largest eigenvalue of  $A^T A$ .

- Consider matrix  $A = \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$

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- So,  $\|A\|_2 = \sqrt{6.8541} \approx 2.618$ .



- Consider the matrix  $B = \begin{bmatrix} 3 & 2 & 4 \\ 2 & 0 & 2 \\ 4 & 2 & 3 \end{bmatrix}$

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- $\|B\|_2$  is simply the maximum absolute row sum, which is 9.



## Theorem (Subordinate Matrix Norm)

*If  $\|\cdot\|$  is any norm in  $\mathbb{R}^n$ , then the equation*

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## Other Results

- $\|Ax\| \leq \|A\|\|x\| \quad (x \in \mathbb{R}^n)$
- $\|AB\| \leq \|A\|\|B\|$
- $\|I\| = 1$



## Results

- Let  $Ax = b$  be a linear system and let  $B$  be a perturbation of  $A$  such that  $B\tilde{x} = b$ . Then the following holds:

$$\frac{\|x - \tilde{x}\|}{\|x\|} \leq \|I - BA\|$$



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$$\frac{\|x - \tilde{x}\|}{\|x\|} \leq \mathcal{K}(A) \frac{\|b - \tilde{b}\|}{\|b\|}$$

where  $\mathcal{K}(A) = \|A\| \|A^{-1}\|$  is called the condition number of  $A$

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- $\mathcal{K}(A)$  large,  $A$  ill-conditioned, else  $A$  well-conditioned
- $\mathcal{K}(A) > 0$



### Definition

We define the error  $e$  and residual  $r$  for perturbed systems as follows:

$$e = x - \tilde{x} \quad \text{and} \quad r = b - \tilde{b} = Ax - A\tilde{x} = Ae$$

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- Question: why useful?
- Answer:  $b$ ,  $r$ ,  $\mathcal{K}(A)$  known, so can estimate the relative error in  $x$

Consider