

Lab 4 - Curvatures

Geometry Processing (GPR)

1 Curvature from a Monge patch

When we have a point cloud or triangle mesh we compute the Hessian at a point by locally adjusting a function. This is known as a *Monge patch*.

For a given point \mathbf{p} , its normal \mathbf{n} , and its neighbors $\mathcal{P} = \{p_i\}_{1 \leq i \leq m}$, we need to fit a quadratic function:

$$w(u, v) = au^2 + buv + cv^2 + du + ev + f = \mathbf{q}^T \mathbf{s}$$

$$\mathbf{q} = (u^2 \quad uv \quad v^2 \quad u \quad v \quad 1)^T, \quad \mathbf{s} = (a \quad b \quad c \quad d \quad e \quad f)^T$$

First we need to transform the neighbors to a coordinate system $(\mathbf{u}, \mathbf{v}, \mathbf{w})$ aligned with the normal \mathbf{n} . The origin will be point \mathbf{p} itself.

$$\begin{aligned}\mathbf{w} &= -\mathbf{n} \\ \mathbf{u} &= \mathbf{O}\mathbf{x} \times \mathbf{w} \\ \mathbf{v} &= \mathbf{w} \times \mathbf{u}\end{aligned}$$

We transform all the neighbors to this system from \mathbf{p}_i to (u_i, v_i, w_i) :

$$\begin{aligned}u_i &= \langle \mathbf{u}, \mathbf{p}_i - \mathbf{p} \rangle \\ v_i &= \langle \mathbf{v}, \mathbf{p}_i - \mathbf{p} \rangle \\ w_i &= \langle \mathbf{w}, \mathbf{p}_i - \mathbf{p} \rangle\end{aligned}$$

Then we fit the function using least squares:

$$\begin{aligned}
E(\mathcal{P}, w(u, v)) &= \sum_{i=1}^m (w(u, v) - w_i)^2 = \sum_{i=1}^m (\mathbf{q}_i^T \mathbf{s} - w_i)^2 \\
&= \sum_{i=1}^m [(\mathbf{q}_i^T \mathbf{s})^2 + w_i^2 - 2w_i(\mathbf{q}_i^T \mathbf{s})] \\
&= \mathbf{s}^T \left(\sum_{i=1}^m \mathbf{q}_i \mathbf{q}_i^T \right) \mathbf{s} + \sum_{i=1}^m w_i^2 - 2\mathbf{s}^T \sum_{i=1}^m w_i \mathbf{q}_i
\end{aligned}$$

$$\begin{aligned}
\min_w E(\mathcal{P}, w) \rightarrow \nabla E(\mathcal{P}, w) = 0 \iff 2 \left(\sum_{i=1}^m \mathbf{q}_i \mathbf{q}_i^T \right) \mathbf{s} - 2 \sum_{i=1}^m w_i \mathbf{q}_i = 0 \iff \\
\left(\sum_{i=1}^m \mathbf{q}_i \mathbf{q}_i^T \right) \mathbf{s} = \sum_{i=1}^m w_i \mathbf{q}_i \iff \mathbf{A}\mathbf{s} = \mathbf{b}
\end{aligned}$$

Then the Hessian \mathbf{H}_w is simple to extract from the function $w(u, v)$:

$$\mathbf{H}_w = \begin{pmatrix} \frac{\partial^2 w}{\partial u^2} & \frac{\partial^2 w}{\partial v \partial u} \\ \frac{\partial^2 w}{\partial u \partial v} & \frac{\partial^2 w}{\partial v^2} \end{pmatrix} = \begin{pmatrix} 2a & b \\ b & 2c \end{pmatrix}$$