CSC 21100: Fundamentals of Computer Systems x86 Assembly

Instructor: Zheng Peng
Assistant Professor
Computer Science Department
City College of New York

This lecture slides contain materials from

- · Assembly tutorial by Professor Ray Toal, Electrical Engineering & Computer Science, Loyola Marymount University
- University of Virginia, Computer Science, CS216: Program and Data Representation, Spring 2006, by Professor David Evans
- The x86 PC Assembly Language, Design and Interfacing, by Muhammad Ali Mazidi, Janice Gillespie Mazidi and Danny Causey
- NASM Assembly Language Tutorials asmtutor.com

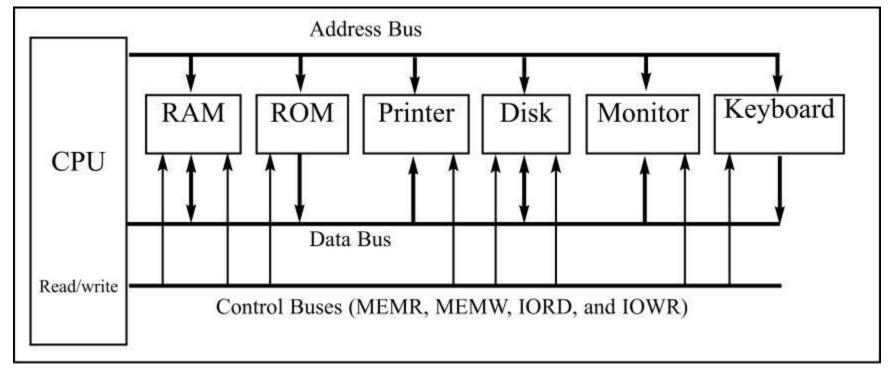
x86 Architecture Overview

- x86 is a family of instruction set architectures (ISA) based on the Intel 8086 CPU and its Intel 8088 variant.
- The architecture has been implemented in processors from Intel, Cyrix, AMD, VIA and many other companies.
- Currently, the majority of personal computers and laptops sold are based on the x86 architecture.
- x86 also dominates compute-intensive workstation and cloud computing segments.

Processor Modes

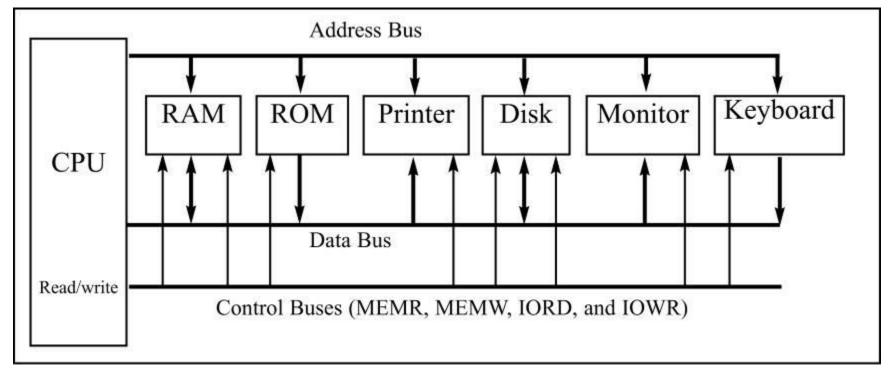
- A processor implementing the x86 architecture can execute in:
 - Real Mode: A highly restricted operating mode in which only the first 1 MB of physical memory is directly accessible.
 - Protected Mode: The normal mode of operation.
 This mode expands addressable physical memory to 16 MB and addressable virtual memory to 1 GB, and provides protected memory.
 - Other Modes: Not discussed in this class.

Inside a Computer (1)



- CPU: "central processing unit" (also called a processor)
 - CPU function is to execute (process) information stored in memory.
 - I/O devices, such as keyboard & monitor provide a means of communicating with the CPU.
 - The CPU is connected to memory and I/O through a group of wires called a bus.

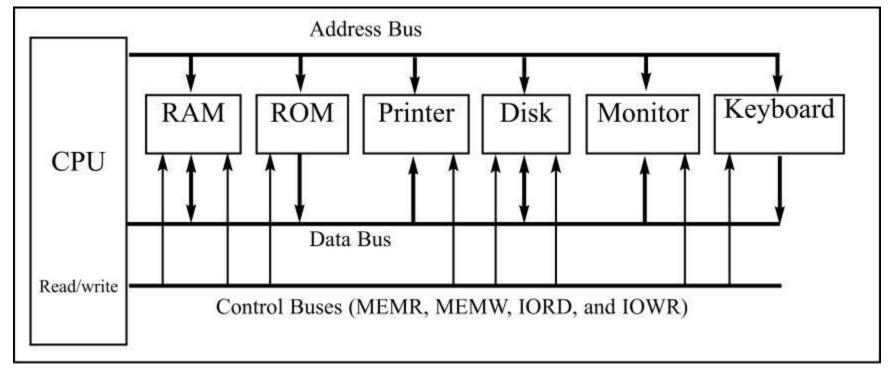
Inside a Computer (2)



Bus:

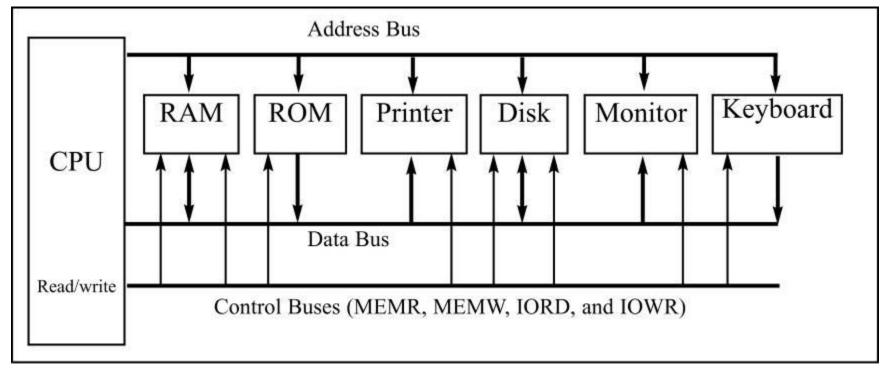
- Data bus: it carries information in/out of a CPU
- Address bus: it is used to identify devices and memory connected to the CPU
- Control bus: it provides device control signals.

Inside a Computer (3)



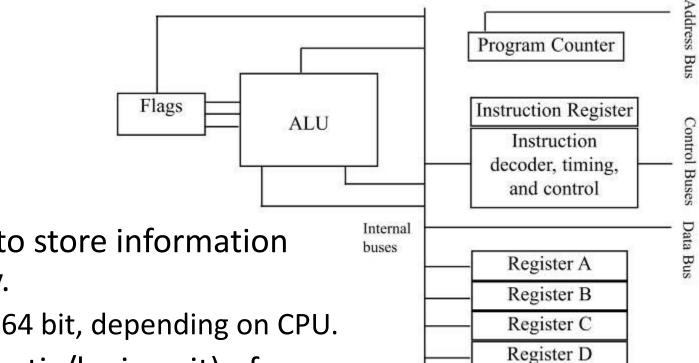
- RAM: "random access memory" (sometimes called read/write memory)
 - Used for temporary storage of programs while running.
 - Data is lost when the computer is turned off.
 - RAM is sometimes called volatile memory.

Inside a Computer (4)



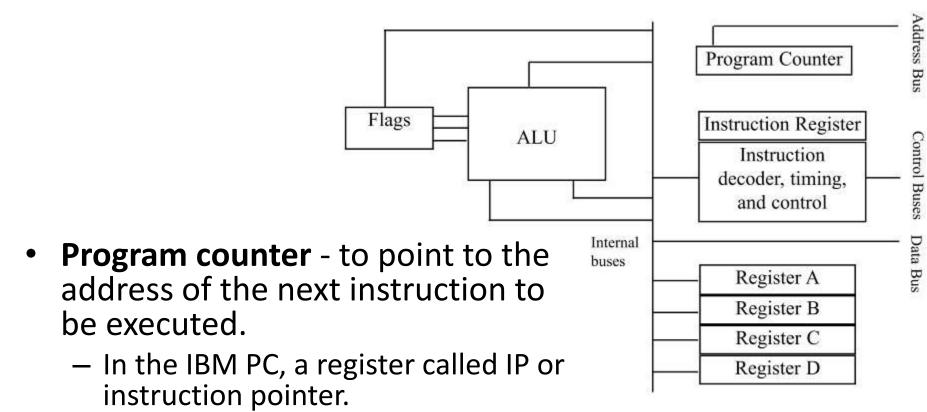
- ROM: "read-only memory"
 - Contains programs and information essential to the operation of the computer.
 - Information in ROM is permanent, cannot be changed by the user, and is not lost when the power is turned off.
 - ROM is called nonvolatile memory.

Inside a CPU (1)



- **Registers** to store information temporarily.
 - 8, 16, 32, 64 bit, depending on CPU.
- ALU (arithmetic/logic unit) for arithmetic functions such as add, subtract, multiply, and divide.
 - Also logic functions such as AND, OR, and NOT.

Inside a CPU (2)



 Instruction decoder - to interpret the instruction fetched into the CPU.

CPU at Work (1)

- A step-by-step analysis of CPU processes to add three numbers, with steps & code shown.
 - Assume a CPU has registers A, B, C, and D.
 - An 8-bit data bus and a 16-bit address bus.
 - The CPU can access memory addresses 0000 to FFFFH.
 - A total of 10000H locations.

Action	Code	Data
Move value 21H into register A	вон	21H
Add value 42H to register A	04H	42H
Add value 12H to register A	04H	12H

CPU at Work (2)

 If the program to perform the actions listed above is stored in memory locations starting at 1400H, the following would represent the contents for each memory address location...

Memory ad	dress	Contents	of n	nemory	ado	dress			
1400		(B0) code	for	moving	g a	value	to	register	A
1401		(21) value	to	be mov	ved				
1402		(04) code	for	adding	g a	value	to	register	Α
1403		(42) value	e to	be add	ded				
1404		(04) code	for	adding	g a	value	to	register	A
1405		(12) value	to	be add	ded				
1406		(F4) code	for	halt					

CPU at Work (3)

- The CPU puts the address 1400H on the address bus and sends it out.
 - Memory finds the location while the CPU activates the READ signal, indicating it wants the byte at 1400H.
 - The content (B0) is put on the data bus & brought to the CPU.

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04) code for adding a value to register A
1403	(42) value to be added
1404	(04) code for adding a value to register A
1405	(12) value to be added
1406	(F4) code for halt

CPU at Work (4)

- The CPU decodes the instruction B0 with the help of its instruction decoder dictionary.
 - Bring the byte of the next memory location into CPU Register A.

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04)code for adding a value to register A
1403	(42) value to be added
1404	(04) code for adding a value to register A
1405	(12) value to be added
1406	(F4) code for halt

CPU at Work (5)

- From memory location 1401H, the CPU fetches code 21H directly to Register A.
 - After completing the instruction, the program counter points to the address of the next instruction - 1402H.
 - Address 1402H is sent out on the address bus, to fetch the next instruction.

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04)code for adding a value to register A
1403	(42) value to be added
1404	(04) code for adding a value to register A
1405	(12) value to be added
1406	(F4) code for halt

CPU at Work (6)

- From 1402H, the CPU fetches code 04H.
 - After decoding, the CPU knows it must add the byte at the next address (1403) to the contents of register A.
 - After it brings the value (42H) into the CPU, it provides the contents of Register A, along with this value to the ALU to perform the addition.
 - Program counter becomes 1404, the next instruction address.

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04)code for adding a value to register A
1403	(42)value to be added
1404	(04)code for adding a value to register A
1405	(12) value to be added
1406	(F4) code for halt

CPU at Work (7)

- Address 1404H is put on the address bus and the code is fetched, decoded, and executed.
 - Again adding a value to Register A.
 - The program counter is updated to 1406H

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04)code for adding a value to register A
1403	(42) value to be added
1404	(04)code for adding a value to register A
1405	(12) value to be added
1406	(F4) code for halt

CPU at Work (8)

- The contents of address 1406 (HALT code) are fetched in and executed.
 - The HALT instruction tells the CPU to stop incrementing the program counter and asking for the next instruction.
 - Without HALT, the CPU would continue updating the program counter and fetching instructions.

Memory address	Contents of memory address
1400	(B0)code for moving a value to register A
1401	(21) value to be moved
1402	(04) code for adding a value to register A
1403	(42) value to be added
1404	(04) code for adding a value to register A
1405	(12) value to be added
1406	(F4)code for halt

x86 Segments

- A typical Assembly language program consists of at least three segments:
 - A code segment which contains the assembly language instructions that perform the tasks that the program was designed to accomplish.
 - A data segment used to store information (data) to be processed by the instructions in the code segment.
 There may be many data segments.
 - A stack segment used by the CPU to store information temporarily.
 - An <u>optional</u> extra segment a spare segment that may be used for specifying a location in memory.

x86 Segment Registers

All x86 segment registers are 16 bits in size,

irrespective of the CPU:

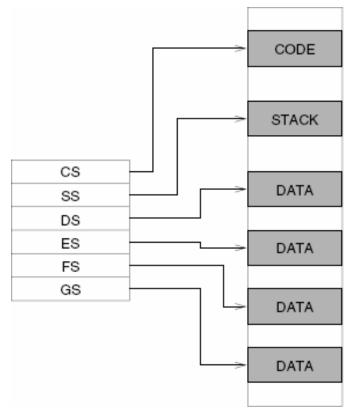
– CS: code segment register

DS: data segment register

SS: stack segment register

ES: extra segment register

– FS and GS: clones of ES



Addressing Memory

- A memory reference has four parts and is often written as [SELECTOR: BASE + INDEX * SCALE + OFFSET]. Example: [FS:ECX+ESI*8+93221]
 - The selector is one of the six segment registers;
 - The base is one of the eight general purpose registers;
 - The index is any of the general purpose registers except ESP;
 - The scale is 0, 1, 2, 4, or 8;
 - The offset is any 32-bit number.
- The minimal reference consists of only a base register or only an offset; a scale can only appear if there is an index present.
- Sometimes the memory reference is written like this:

```
selector
offset(base, index, scale)
```

x86 Data Types

Type name	Number of bits	Bit indices
Byte	8	70
Word	16	150
Doubleword	32	320
Quadword	64	630
Doublequadword	128	1270

Endianness

- The sequential order used to store a word in computer memory
 - Big Endian: Most-significant byte at least address of a word
 - Little Endian: Least-significant byte at least address
- As an example, suppose we have a <u>hexadecimal</u> number 0x12345678.

Address	00	01	10	11
Big Endian	12	34	56	78
Little Endian	78	56	34	12

• The x86 is little endian, meaning the least significant bytes come first in memory

First Assembly Program

- "Hello World!"
 - Assembly version

```
Writes "Hello, World" to the console using only system calls.
     To assemble and run:
          nasm -f elf hello.asm & ld -m elf i386 hello.o -o hello
7
8
9
10
11 _start:
12
13
14
15
16 exit:
17
18
19
20
21 message:
22
              global
                         start
              section
                          .text
                         eax, 4
                                                     ; system call number for write
              mov
                                                     ; file handle 1 is stdout
                         ebx, 1
              mov
                         ecx, message
                                                     ; address of string to output
              mov
                         edx, 13
                                                     ; number of bytes
              mov
              int 80h
                                                     ; request an interrupt on libc using INT 80h
                                                     ; syscam call number for exit
              mov
                          eax, 1
                          ebx, 0
                                                     ; return 0 status on exit - 'No Errors'
              mov
              int 80h
                                                     ; request an interrupt on libc using INT 80h
              section
                          .data
                          "Hello, World", OAh
                                                      ; note the newline at the end
```

First Assembly Program

 Most programs consist of directives followed by one or more sections.

```
Writes "Hello, World" to the console using only system calls.
     To assemble and run:
                                     Directives
         nasm -f elf hello.asm & ld -m elf i386 hello.o -o hello
8 9 10 11 12 13 14 15 16 17 18 19 20
              global
                          start
              section
                         .text
    start:
                                                    ; system call number for write
                         eax, 4
              mov
                                                    ; file handle 1 is stdout
                         ebx, 1
              mov
                         ecx, message
                                                     address of string to output
              mov
                         edx, 13
                                                    ; number of bytes
              mov
              int 80h
                                                    ; request an interrupt on libc using INT 80h
   exit:
                                                    ; syscam call number for exit
                         eax, 1
              mov
                         ebx, 0
                                                    ; return 0 status on exit - 'No Errors'
              mov
              int 80h
                                                     request an interrupt on libc using INT 80h
                                                     Sections
              section
                         .data
                         "Hello, World", OAh
                                                     ; note the newline at the end
   nessage:
```

First Assembly Program

 Lines can have an optional label. Most lines have an instruction followed by zero or more operands.

```
Writes "Hello, World" to the console using only system calls.
     To assemble and run:
          nasm -f elf hello.asm & ld -m elf i386 hello.o -o hello
8
9
10
11
12
13
14
15
16
17
18
19
20
21
              global
                           start
               section
                          .text
    start:
                          eax, 4
                                                     ; system call number for write
              mov
                          ebx, 1
                                                     ; file handle 1 is stdout
               \mathbf{v}
                                                     ; address of string to output
                          ecx, message
               NOW
                          edx, 13
                                                     ; number of bytes
               \mathbf{v}
               int 80h
                                                     ; request an interrupt on libc using INT 80h
   exit:
                                                     ; syscam call number for exit
                          eax, 1
              mov
                          ebx, 0
                                                     ; return 0 status on exit - 'No Errors'
              mov
              int 80h
                                                     ; request an interrupt on libc using INT 80h
              section
                          .data
                          "Hello, World", OAh
                                                      ; note the newline at the end
```

Assemble and Run

```
zheng@Hudson:~/Assembly$
zheng@Hudson:~/Assembly$ nasm -f elf hello.asm
zheng@Hudson:~/Assembly$ ls hello.o
hello.o
zheng@Hudson:~/Assembly$ ld -m elf_i386 hello.o -o hello
zheng@Hudson:~/Assembly$ ls hello
hello
zheng@Hudson:~/Assembly$ ./hello
hello
zheng@Hudson:~/Assembly$ ./hello
Hello, World
zheng@Hudson:~/Assembly$
```

Your First Few Instructions

There are hundreds of instructions. You can't learn them all at once. Just start with these:

mov x, y	$x \leftarrow y$
and x, y	$x \leftarrow x$ and y
or <i>x, y</i>	$x \leftarrow x \text{ or } y$
xor x, y	$x \leftarrow x \text{ xor } y$
add x, y	$x \leftarrow x + y$
sub x, y	$x \leftarrow x - y$
inc x	$x \leftarrow x + 1$
dec x	$x \leftarrow x - 1$
int 80h	Request an interrupt on libc using INT 80h
db	A <u>pseudo-instruction</u> that declares bytes that will be in memory when the program runs

Complete list of instructions can be found here:

https://software.intel.com/en-us/articles/intel-sdm

System Call Table

- System call: a special type of function call, in which a computer program requests a service from the kernel of the operating system it is executed on.
- The following table lists some of the system calls for the Linux kernel. It could also be thought of as an API for the interface between user space and kernel space.

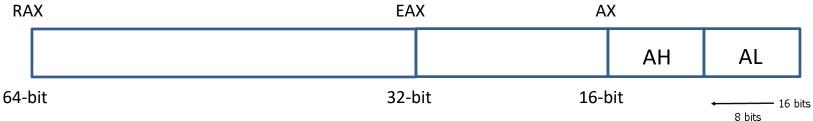
#	Name	Register			
		EAX	EBX	ECX	EDX
1	sys_exit	0x01	-	-	-
3	sys_read	0x03	unsigned int fd	char *buf	size_t count
4	sys_write	0x04	unsigned int fd	const char *buf	size_t count
5	sys_open	0x05	const char *name	int flags	int mode
6	sys_close	0x06	unsigned int fd	-	-

Complete list of Linux system calls can be found here:

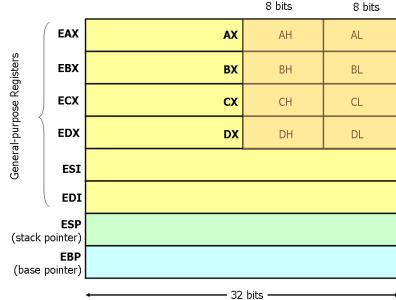
http://shell-storm.org/shellcode/files/syscalls.html

The Three Kinds of Operands (1)

- Register Operands
 - General-purpose registers in x86 processors can be accessed as either 32-bit, 16-bit or 8-bit registers



- Different purposes
- A register is used for the accumulator.
- B register is a base addressing register.
- C register is a counter in loop operations.
- D register points to data in I/O operations
- ESI/EDI are index registers



The Three Kinds of Operands (2)

- Memory Operands
 - These are the basic forms of addressing:
 - [number]
 - [reg]
 - [reg + reg*scale]
 - [reg + number]
 - [reg + reg*scale + number]
 - The number is called the displacement; the plain register is called the base; the register with the scale is called the index.
 - Example

```
[750] ; displacement only
[ebp] ; base register only
[ecx + esi*4] ; base + index * scale
[ebp + edx] ; scale is 1
[ebx - 8] ; displacement is -8
[eax + edi*8 + 500] ; all four components
[ebx + counter] ; uses the address of the variable 'counter' as the displacement
```

The Three Kinds of Operands (3)

- Immediate Operands
 - These can be written in many ways. Here are some examples from the official docs.

```
200
             ; decimal
0200
             ; still decimal - the leading 0 does not make it octal
             ; explicitly decimal - d suffix
0200d
0d200
             ; also decimal - 0d prefex
0c8h
             ; hex - h suffix, but leading 0 is required because c8h looks like a var
            ; hex - the classic 0x prefix
0xc8
0hc8
             ; hex - for some reason NASM likes Oh
310g
             ; octal - g suffix
0q310
             ; octal - Og prefix
11001000b
            ; binary - b suffix
             ; binary - Ob prefix, and by the way, underscores are allowed
0b1100 1000
```

Instructions formats

Most of the basic instructions have only the following forms:

add reg, reg
add reg, mem
add reg, imm
add mem, reg
add mem, imm

Defining Data and Reserving Space

 To reserve space in memory, you can use the following pseudo instructions

```
db
      0x55
                          ; just the byte 0x55
db
      0x55,0x56,0x57
                          ; three bytes in succession
db 'a', 0x55
                          ; character constants are OK
db
      'hello',13,10,'$'
                          ; so are string constants
      0x1234
dw
                          ; 0x34 0x12
      'a'
                          ; 0x61 0x00 (it's just a number)
dw
      'ab'
                          ; 0x61 0x62 (character constant)
dw
dw
      'abc'
                          ; 0x61 0x62 0x63 0x00 (string)
     0x12345678
                          ; 0x78 0x56 0x34 0x12
dd
dd
     1.234567e20
                          ; floating-point constant
      0x123456789abcdef0 ; eight byte constant
dq
                          ; double-precision float
dq
     1.234567e20
                          ; extended-precision float
dt
      1.234567e20
```

Conditional Instructions (1)

- After an arithmetic or logic instruction, or the compare instruction, cmp, the processor sets or clears bits in its eflags*. The most interesting flags are:
 - s (sign)
 - z (zero)
 - c (carry)
 - o (overflow)
- So after doing, say, an addition instruction, we can perform a jump, move, or set, based on the new flag settings. For example:

jz label	Jump to label L if the result of the operation was zero				
cmovno x, y	$x \leftarrow y$ if the last operation did <i>not</i> overflow				
setc x	$x \leftarrow 1$ if the last operation had a carry, but $x \leftarrow 0$ otherwise (x must be a byte-size register or memory location)				

^{*}https://en.wikibooks.org/wiki/X86_Assembly/X86_Architecture#EFLAGS_Register

Conditional Instructions (2)

- The conditional instructions have three base forms:
 - j for conditional jump
 - cmov for conditional move
 - set for conditional set
- The suffix of the instruction can be one of many forms:

S	ns	Z	nz	С	nc	0	no	р	np
ре	ро	е	ne	I	nl	le	nle	g	ng
ge	nge	а	na	ae	nae	b	nb	be	nbe

Detailed example can be found here:

https://en.wikibooks.org/wiki/X86 Assembly/Control Flow

Understanding Function Calling

Steps

- Pass arguments through stack
- Transfer control to the function
- Perform function operations
- Place result in register for caller
- Return to place of call

Function Call Instructions

Instructions:

push x	Decrement esp by the size of the operand, then store x in [esp]
pop <i>x</i>	Move [esp] into x , then increment esp by the size of the operand
call <i>label</i>	Push the address of the next instruction, then jump to the label
ret	Pop into the instruction pointer

- Any register that your function needs to use should have it's current value put on the stack for safe keeping using the **PUSH** instruction.
- Then after the function has finished it's logic, these registers can have their original values restored using the POP instruction.
- When you CALL a subroutine, the address you called it from in your program is pushed onto the stack.
- This address is then popped off the stack by **RET** and the program jumps back to that place in your code.

Calling Convention (1)

- The calling convention is a protocol about how to call and return from functions.
- Calling convention is based heavily on the use of the hardware-supported stack.
 - It is based on the push, pop, call, and ret instructions
- Arguments are passed to the functions by using the stack. Function return value is stored in the EAX register.
- Both function caller and callee need to follow the calling convention

Calling Convention (2)

Caller rules:

- To call a function, use the call instruction.
- Before the function call,
 - Save EAX, ECX, EDX if the caller relies on the values in them.
 - Push function arguments onto the stack in inverted order
- After the function call, the caller
 - Find the return value in the EAX register.
 - Remove the arguments from stack.
 - Restore the contents of caller-saved registers by popping them off of the stack.

Calling Convention (3)

- Caller rules (example)
 - To call a function: myfunc (arg1, arg2, arg3)

```
section .text
3
   start:
5
           push eax
                                     ; save eax on stack
6
                                     ; save ecx and edx on stack if needed
7
           push arg3
                                     ; push last argument first
8
           push arg2
                                     ; push the second argument
           push arg1
                                     ; push first argument last
10
           call myfunc
                                     ; call the function
           add esp, 12
                                    ;remove arguments
           mov [result], eax
                                     ; the result of myfunc is now in eax
                                     restore edx and ecx if previously saved;
           pop eax
                                     ;restore eax
15 ;
           section .bss
17 result: resb 4
                                     ; reserve 4 bytes to store the result
18
```

Calling Convention (4)

Callee rules

- At the beginning of the function
 - Push the value of EBP onto the stack, and then copy the value of ESP into EBP.
 - Next, allocate local variables by making space on the stack.
 - Next, save the values of the callee-saved registers (EBX, EDI, and ESI) that will be used by the function.
- At the end of the function
 - Leave the return value in EAX.
 - Restore the old values of any callee-saved registers that were modified.
 - Deallocate local variables.
 - Restore the caller's base pointer value by popping EBP off the stack.
 - Return to the caller by executing a RET instruction

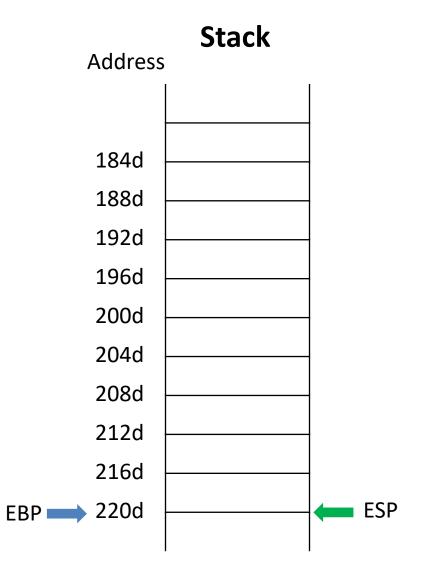
Calling Convention (5)

Callee rules (example)

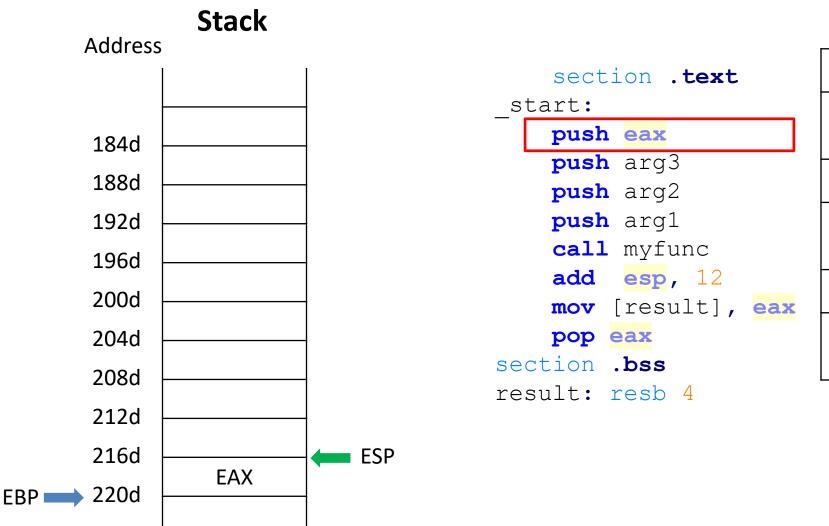
```
myfunc:
  ; Subroutine Proloque
         push ebp
                  ; Save the old base pointer value.
         mov ebp, esp ; Set the new base pointer value.
 6
         sub esp, 4 ; Make room for one 4-byte local variable.
 7
8
         ; (no need to save EBX, EBP, or ESP)
  ; Subroutine Body
12
13
14
15
16
17
18
         mov eax, [ebp+8] ; Move value of parameter 1 into EAX
         mov esi, [ebp+12]; Move value of parameter 2 into ESI
         mov edi, [ebp+16]; Move value of parameter 3 into EDI
         mov [ebp-4], edi ; Move EDI into the local variable
         add [ebp-4], esi ; Add ESI into the local variable
         add eax, [ebp-4]; Add the contents of the local variable
                       ; into EAX (final result)
```

Calling Convention (5)

Callee rules (example)



```
EAX
    section .text
start:
                          12345678h
    push eax
    push arg3
                             ESI
    push arg2
    push arg1
                          13571357h
    call myfunc
    add esp, 12
                            EDI
    mov [result], eax
    pop eax
                          24682468h
section .bss
result: resb 4
```



EAX

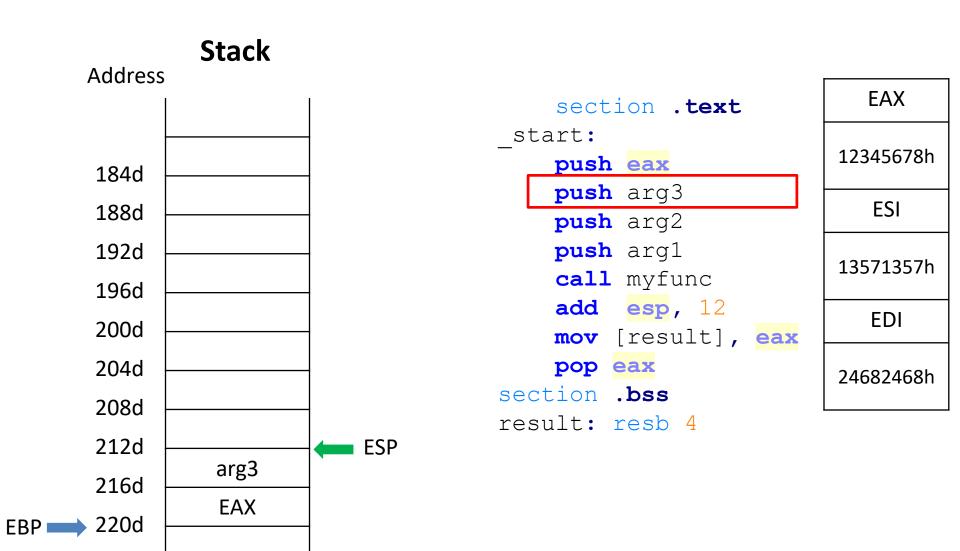
12345678h

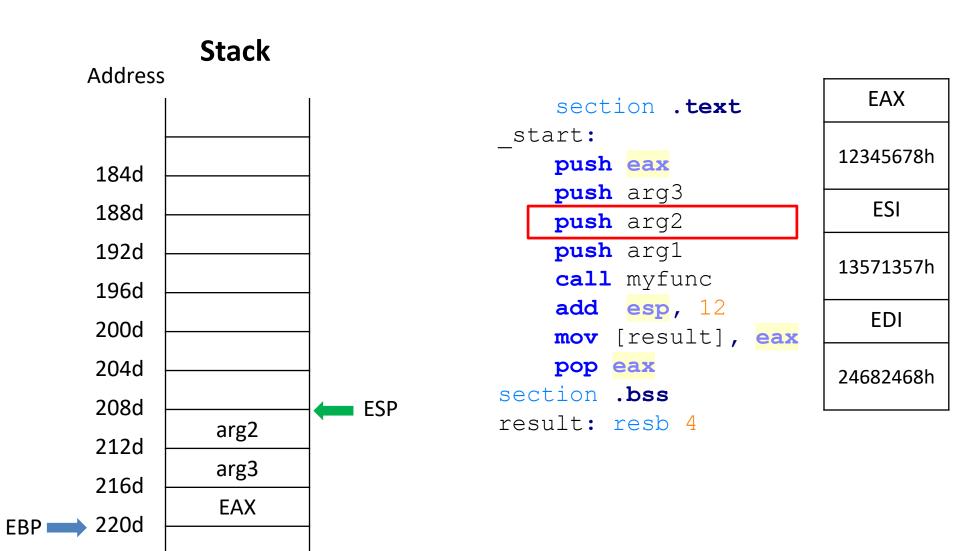
ESI

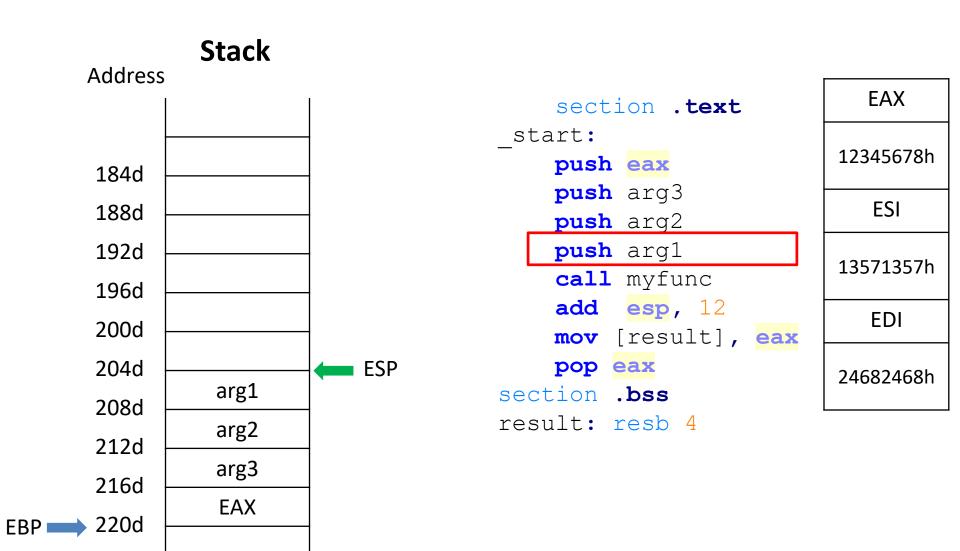
13571357h

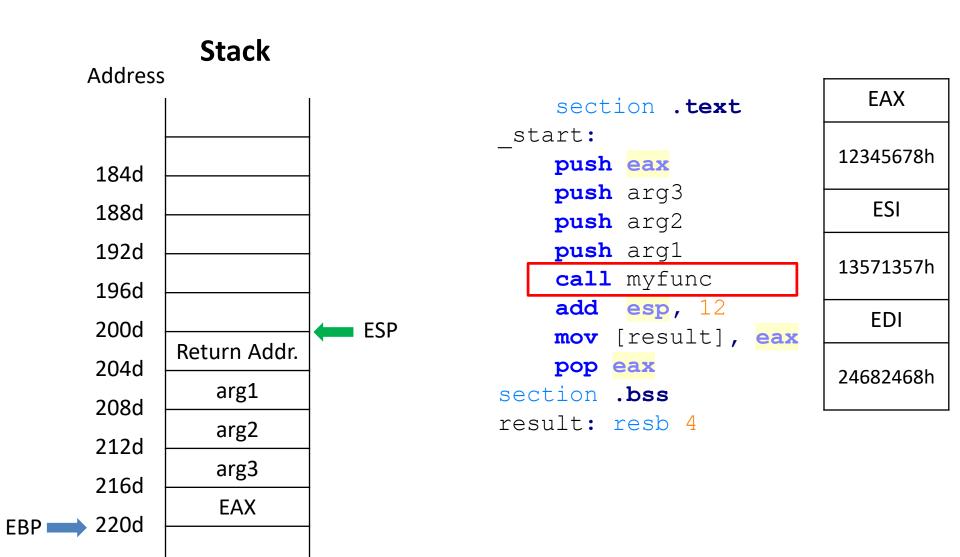
EDI

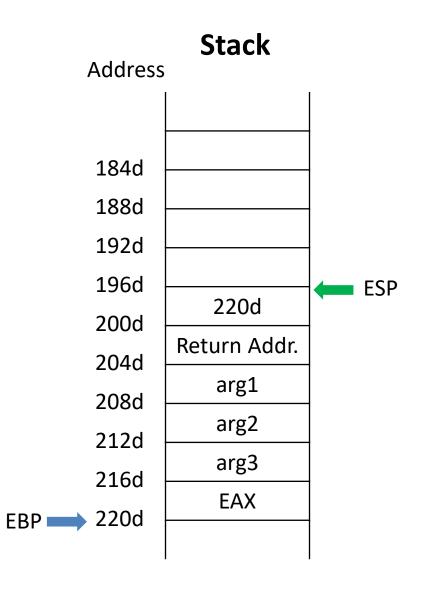
24682468h



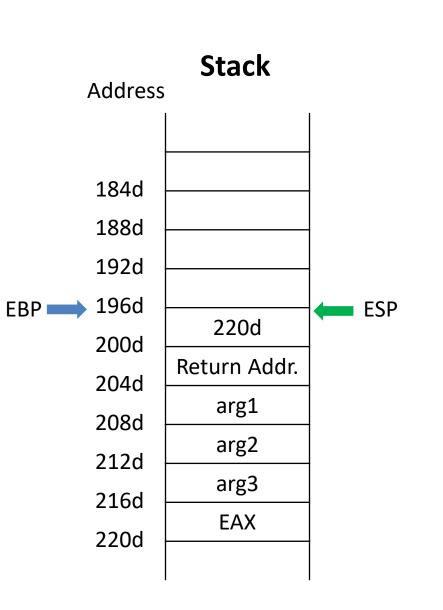




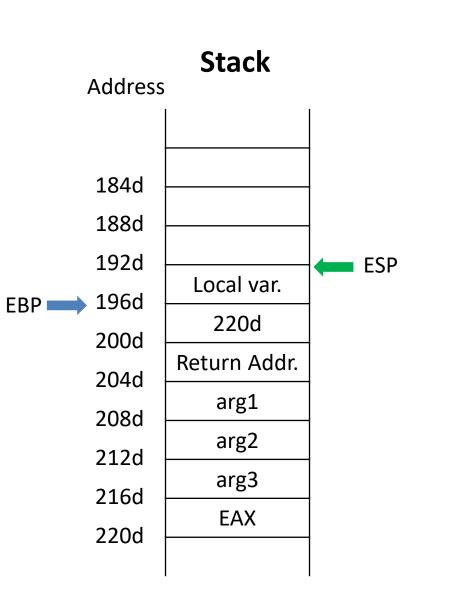




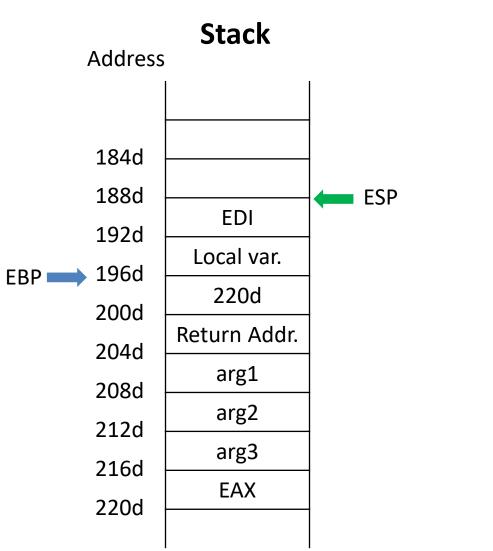
```
myfunc:
; Subroutine Prologue
    push ebp
                            EAX
    mov ebp, esp
    sub esp, 4
                         12345678h
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```



```
myfunc:
; Subroutine Prologue
    push ebp
                            EAX
    mov ebp, esp
    sub
         esp, 4
                         12345678h
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```

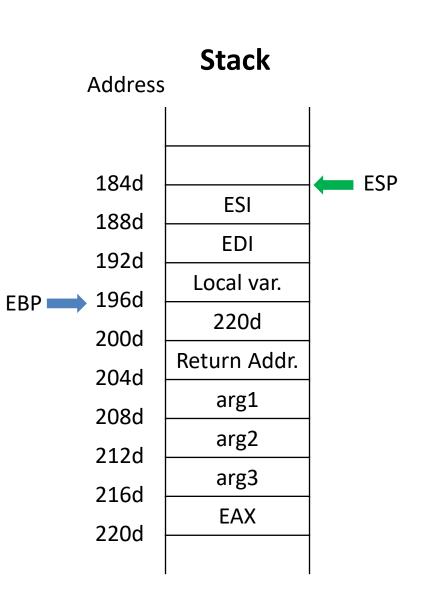


```
myfunc:
; Subroutine Prologue
    push ebp
                            EAX
    mov ebp, esp
    sub esp, 4
                         12345678h
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```



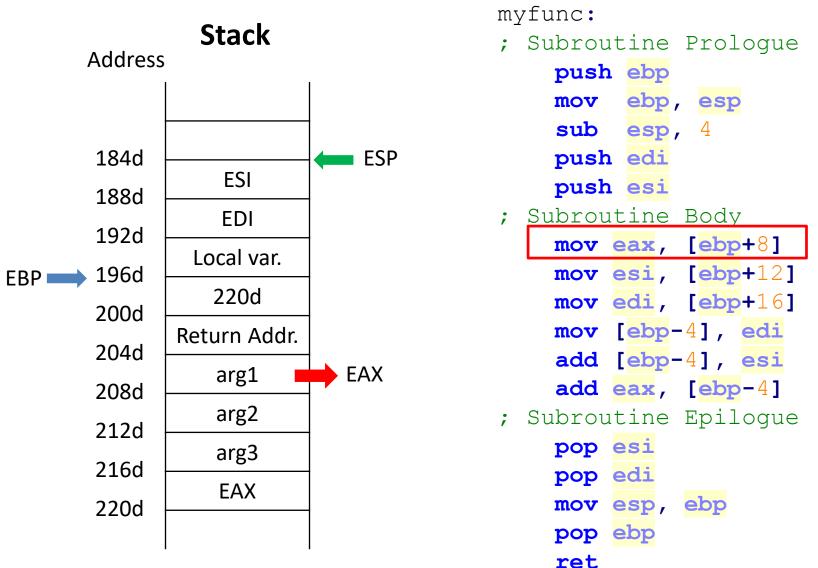
```
myfunc:
; Subroutine Prologue
    push ebp
                           EAX
    mov ebp, esp
    sub esp, 4
                         12345678h
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
```

pop ebp

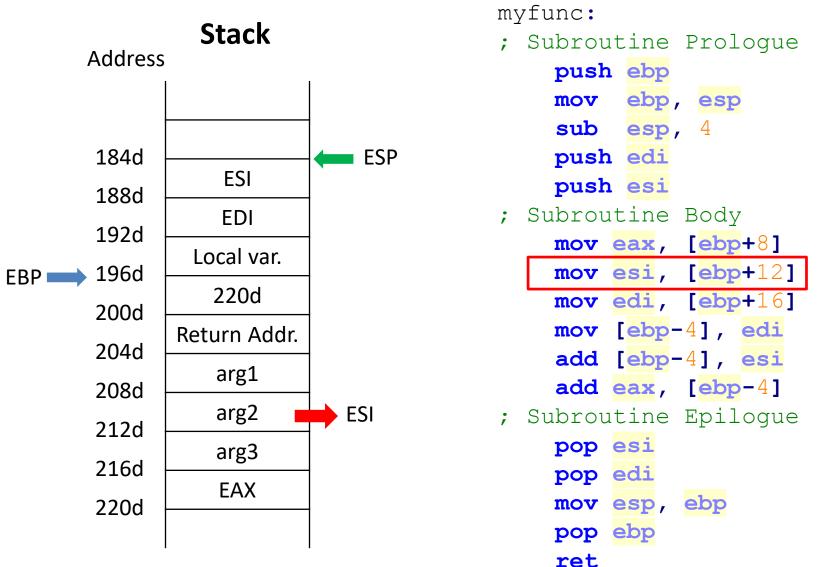


```
myfunc:
; Subroutine Prologue
    push ebp
                           EAX
    mov ebp, esp
    sub esp, 4
                         12345678h
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
```

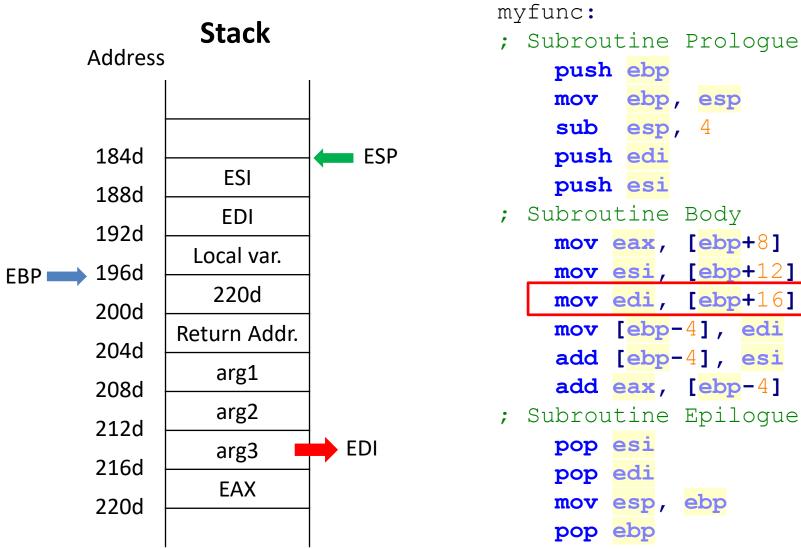
pop ebp



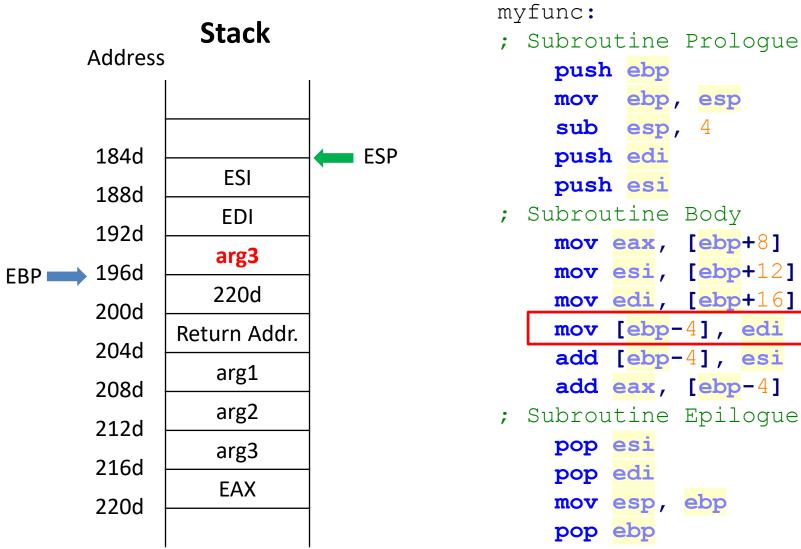
EAX arg1 ESI 13571357h EDI 24682468h



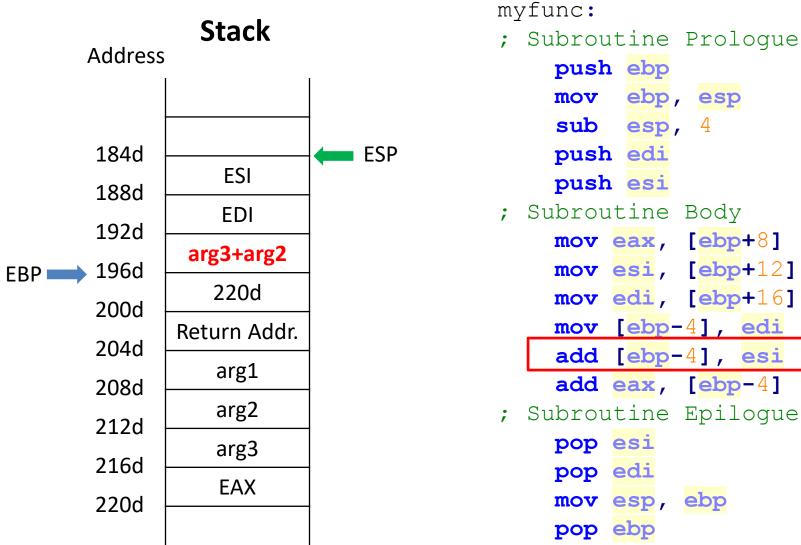
EAX arg1 ESI arg2 EDI 24682468h



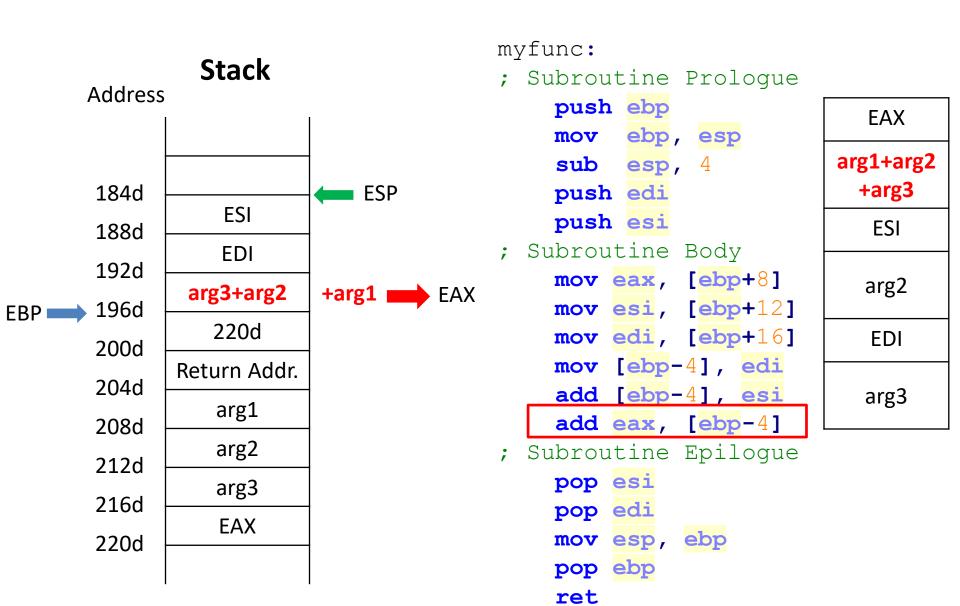
```
; Subroutine Prologue
                           EAX
    mov ebp, esp
                           arg1
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                           arg2
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                           arg3
    add eax, [ebp-4]
```

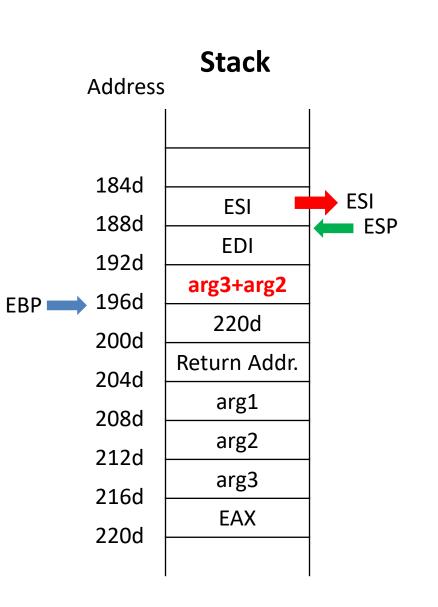


```
; Subroutine Prologue
    push ebp
                           EAX
    mov ebp, esp
    sub esp, 4
                           arg1
    push edi
    push esi
                           ESI
; Subroutine Body
    mov eax, [ebp+8]
                           arg2
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                           EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                           arg3
    add eax, [ebp-4]
```

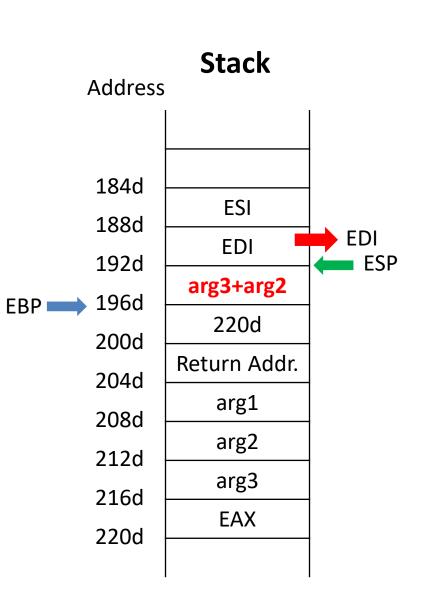


```
EAX
                        arg1
                         ESI
                        arg2
mov esi, [ebp+12]
mov edi, [ebp+16]
                         EDI
mov [ebp-4], edi
add [ebp-4], esi
                        arg3
```



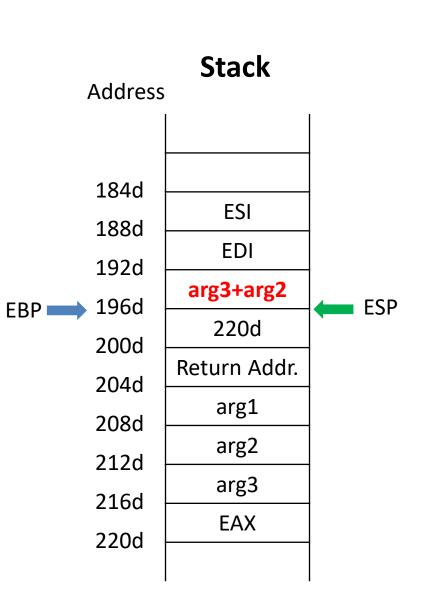


```
myfunc:
; Subroutine Prologue
    push ebp
                           EAX
    mov ebp, esp
                         arg1+arg2
    sub esp, 4
                           +arg3
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                           arg3
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```

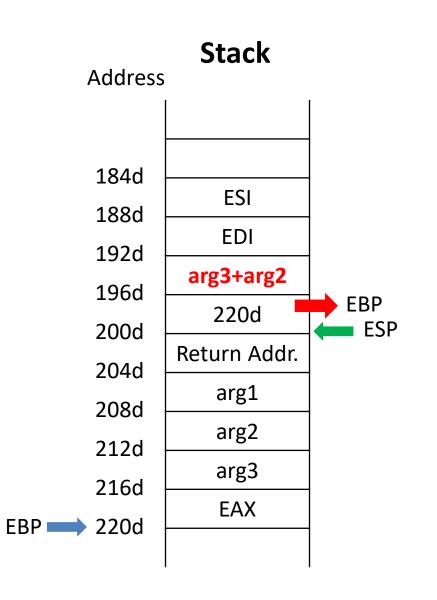


```
myfunc:
; Subroutine Prologue
    push ebp
                            EAX
    mov ebp, esp
                         arg1+arg2
    sub esp, 4
                           +arg3
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
```

pop ebp



```
myfunc:
; Subroutine Prologue
    push ebp
                            EAX
    mov ebp, esp
                         arg1+arg2
    sub esp, 4
                           +arg3
    push edi
    push esi
                            ESI
; Subroutine Body
    mov eax, [ebp+8]
                         13571357h
    mov esi, [ebp+12]
    mov edi, [ebp+16]
                            EDI
    mov [ebp-4], edi
    add [ebp-4], esi
                         24682468h
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```



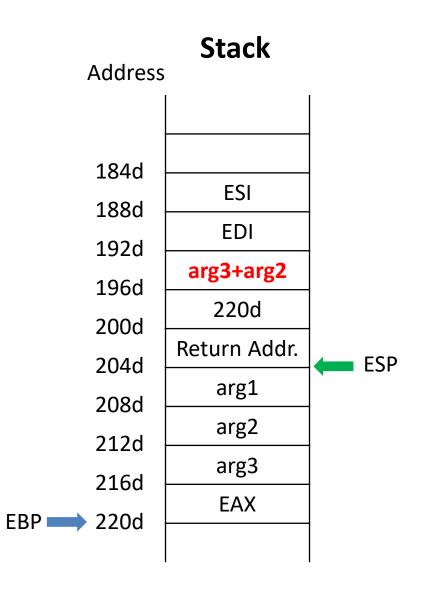
```
myfunc:
; Subroutine Prologue
    push ebp
    mov ebp, esp
    sub esp, 4
    push edi
    push esi
; Subroutine Body
    mov eax, [ebp+8]
    mov esi, [ebp+12]
    mov edi, [ebp+16]
    mov [ebp-4], edi
    add [ebp-4], esi
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
```

```
EAX

arg1+arg2
+arg3
ESI

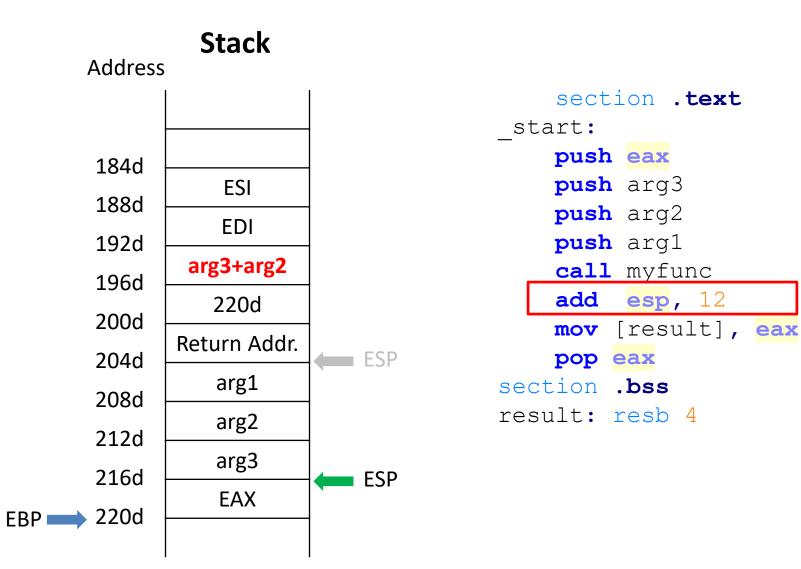
13571357h
EDI

24682468h
```

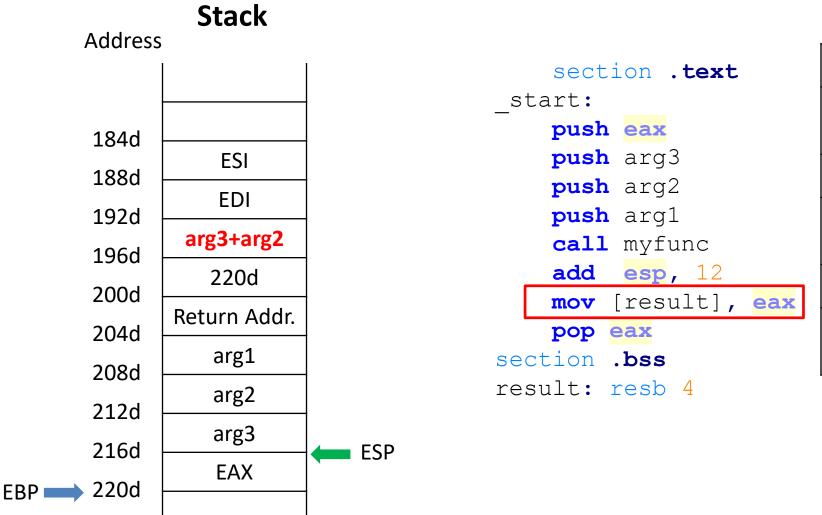


```
myfunc:
; Subroutine Prologue
    push ebp
    mov ebp, esp
    sub esp, 4
    push edi
    push esi
; Subroutine Body
    mov eax, [ebp+8]
    mov esi, [ebp+12]
    mov edi, [ebp+16]
    mov [ebp-4], edi
    add [ebp-4], esi
    add eax, [ebp-4]
; Subroutine Epilogue
    pop esi
    pop edi
    mov esp, ebp
    pop ebp
    ret
```

```
EAX
arg1+arg2
+arg3
ESI
13571357h
EDI
24682468h
```



EAX
arg1+arg2
+arg3
ESI
13571357h
EDI
24682468h



EAX

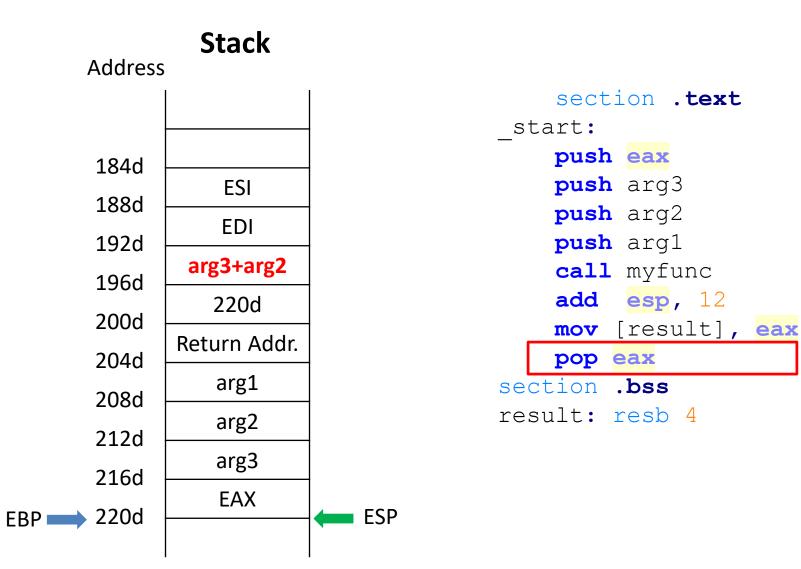
arg1+arg2
+arg3

ESI

13571357h

EDI

24682468h



EAX

12345678h

ESI

13571357h

EDI

24682468h