## Technical details for the SEIR graphical model of the Open SEIR-Graph project

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## 1 SEIR graphical model

We consider N nodes on the graph,  $\mathcal{G}$  indexed by an integer  $i \in \{1, ..., N\}$ . Each node may be in one of four states, Susceptible (0), Exposed (1), Infectious(2) or Removed(3). Denoting the state of any particular node by  $X_{i,t}$  for discrete time index,  $t \geq 0$ , then we define the four time series

$$\{S_t\}_{t\geq 0} = \sum_{i=1}^{N} \mathcal{I}\{X_{i,t} = 0\}$$
$$\{E_t\}_{t\geq 0} = \sum_{i=1}^{N} \mathcal{I}\{X_{i,t} = 1\}$$
$$\{I_t\}_{t\geq 0} = \sum_{i=1}^{N} \mathcal{I}\{X_{i,t} = 2\}$$
$$\{R_t\}_{t\geq 0} = \sum_{i=1}^{N} \mathcal{I}\{X_{i,t} = 3\}$$

Where I is the indicator function that the argument is true. Since the state is categorical, we have that at every time point  $S_t + E_t + I_t + R_t = N$ .

Starting in the intial configuration  $X_{0,0} = 2$  and  $X_{i,0} = 0$  for  $i \neq 0$ , the dynamics proceeds in the manner below, where we use  $n_{i,t}(x,\mathcal{G})$  to denote the number of neighbors of the node i, which are in a state x at time t.

At each time point T, iterate through each node i:

- If  $X_{i,T} = 0$ , simulate  $A \sim \text{Binomial}(n_{i,T}(1,\mathcal{G}), p_E)$  and  $B \sim \text{Binomial}(n_{i,T}(2,\mathcal{G}), p_I)$ , then if  $A + B \geq 1$  set  $X_{i,T+1}$  to 1.
- If  $X_{i,T} = 1$  and  $X_{i,T-\delta_I}$  then set  $X_{i,T+1}$  to 2
- If  $X_{i,T} = 2$  and  $X_{i,T-\delta_R}$  then set  $X_{i,T+1}$  to 3

This process is parameterised by  $\theta = (p_E, p_I, \delta_I, \delta_R)$ . The first may be interpreted as the probabilities of transmission, on any given day, from an exposed node to a susceptible neighbor, from an infectious node to a susceptible neighbor. The final two parameters are the incubation and recovery periods in days.

We notice that this process necessarily leads to a state where all nodes are either in state 0 or state 3. This can be used as a stopping condition in the iterative process.

## 2 Dynamic Interventions

In the SEIR model in the previous section, the Graph,  $\mathcal{G}$  was static throughout the state evolution. We define a dynamic intervention as those which add additional rules to modify  $\mathcal{G}$ . Denoting the state of the graph at a particular time point by  $\mathcal{G}_t$  then an SEIR model with a dynamic intervention modifies the first step if the iteration to

• If  $X_{i,T} = 0$ , simulate  $A \sim \text{Binomial}(n_{i,T}(1,\mathcal{G}_T), p_E)$  and  $B \sim \text{Binomial}(n_{i,T}(2,\mathcal{G}_T), p_I)$ , then if  $A + B \geq 1$  set  $X_{i,T+1}$  to 1.

Then adds an additional step at each time point, once the node iteration is complete, which obtains  $\mathcal{G}_{T+1}$  conditional on  $\mathcal{G}_T$  and the histories  $\{X_{i,t}\}$  up to time point T

## 3 Estimands

The desired estimand of interest is the expected peak proportion of infected individuals given an intial graph  $\mathcal{G}$  and dynamic intervention rule  $\mathcal{D}$ .

$$\psi(\mathcal{G}, \mathcal{D}) = E\left[\max_{t \ge 0} \{S_t\}\right] \tag{1}$$

Such an estimand can be made using the Monte Carlo estimate

$$\hat{\psi}(\mathcal{G}, \mathcal{D}) = M^{-1} \sum_{j=1}^{M} \left( \max_{t \ge 0} \{S_t\} \right)_j \tag{2}$$

where  $(\max_{t\geq 0} \{S_t\})_j$  is a set of M simulated samples.