

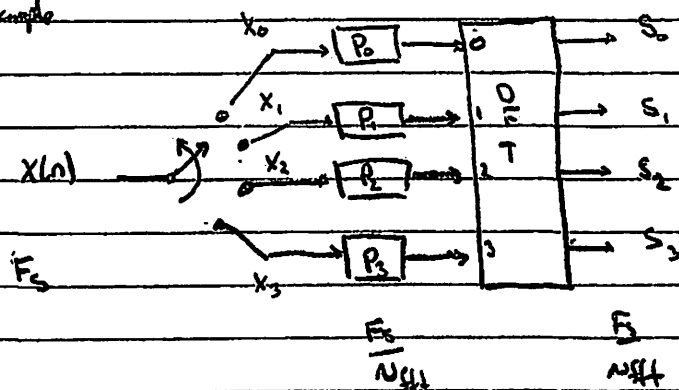
Polyphase Filter \rightarrow Tmux

$$\boxed{\text{Polyphase Filter} \rightarrow \text{MFFT}} = \text{Tmux}$$

when

$$F_{\text{out}} = \frac{F_s}{N_{\text{FFT}}}, \text{ polyphase filter is most efficient}$$

example

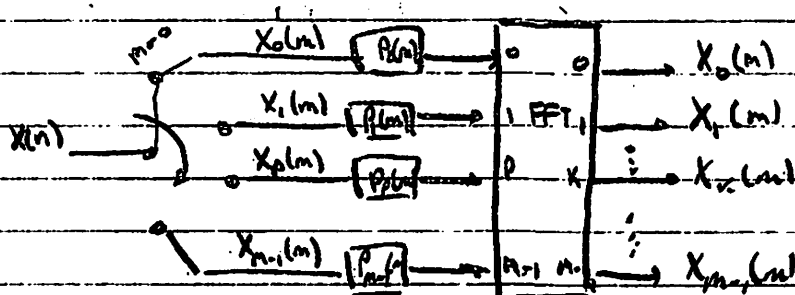


P is a lowpass filter split into parallel paths using polyphase filtering concepts. $h(n)$ is filter impulse response.

$$\text{output filter centers are at } f_k = k \frac{F_s}{N_{\text{fft}}}$$

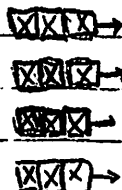
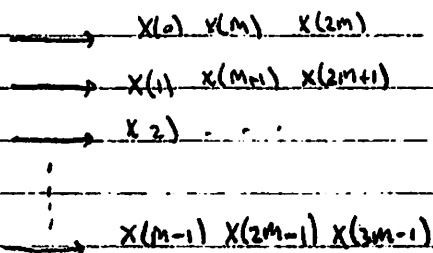
If input blocks are overlapped then output is oversampled, at a rate $\frac{F_s}{D}$, where $D = (1 - \text{overlap}) N_{\text{fft}}$.

Polyphase Filterbank w/ FFT modulator

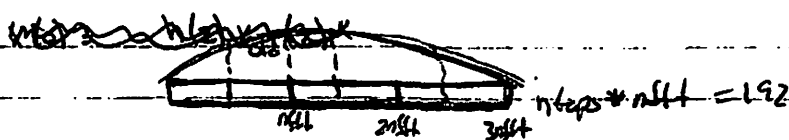


$$X_k(n) = \sum_{p=-\infty}^{M-1} x(n - pM) e^{-j2\pi k p / M}$$

Data Input Structure



3-Tap



$$\begin{aligned}
 \bar{y}(k) &= \sum_{l=0}^{L-1} h(l) p(k-l) & L = \text{Length of filter} \\
 &= \sum_{l=0}^{L-1} h(l) x(k-l) e^{-j2\pi f_0(k-l)T} \\
 &= \sum_{l=0}^{L-1} h(l) x(k-l) e^{-j2\pi f_0 kT} e^{+j2\pi f_0 lT} \\
 &= e^{-j2\pi f_0 kT} \sum_{l=0}^{L-1} h(l) x(k-l) e^{j2\pi f_0 lT}
 \end{aligned}$$

Decimate by $M \Rightarrow k = rM$

$$y(r) = e^{-j2\pi f_0 rMT} \sum_{l=0}^{L-1} h(l) x(rM-l) e^{j2\pi f_0 lT}$$

- 1- Assume $f_s \equiv N \cdot \Delta f$ and $f_0 \equiv n \cdot \Delta f$
- 2- Assume $L \equiv Q \cdot N$
- 3- Assume $M \equiv N$ or $M \equiv N/2$

So, using 1-

$$y(r) = e^{-j2\pi n \Delta f rMT} \sum_{l=0}^{L-1} h(l) x(rM-l) e^{j2\pi n \Delta f lT}$$

$$y(r) = e^{-j2\pi n \frac{rM}{N}} \sum_{l=0}^{L-1} h(l) x(rM-l) e^{+j2\pi n \frac{l}{N}}$$

$$f_s = \frac{1}{T}$$

$$T = \frac{1}{N \Delta f}$$

using 2- $l \equiv qN + p$ $0 \leq q \leq Q-1$; $0 \leq p \leq N-1$

$$y(r) = e^{-j2\pi n \frac{rM}{N}} \sum_{q=0}^{Q-1} \sum_{p=0}^{N-1} h(qN+p) x(rM-qN-p) e^{j2\pi n \frac{(qN+p)}{N}}$$

$$y(r) = e^{-j2\pi n \frac{rM}{N}} \sum_{q=0}^{Q-1} \sum_{p=0}^{N-1} h(qN+p) x(rM-qN-p) e^{j2\pi n \frac{qN}{N}} e^{j2\pi n \frac{p}{N}}$$

$$y(r) = e^{-j2\pi n \frac{rM}{N}} \sum_{p=0}^{N-1} e^{j2\pi n \frac{p}{N}} \left[\sum_{q=0}^{Q-1} h(qN+p) x(rM-qN-p) \right]$$

$= v(r, p)$

$$y(r) = e^{-j2\pi \frac{nrM}{N}} \sum_{p=0}^{N-1} e^{j2\pi \frac{np}{N}} v(r, p)$$

using 3 - $M = \frac{N}{K}$, $K = 1, 2, \text{ or } 4$

$$e^{-j2\pi \frac{nrM}{N}} = e^{-j2\pi \frac{nr}{K}} = \left[e^{-j\frac{2\pi}{K}} \right]^{nr} = \left[-j^{\frac{4}{K}} \right]^{nr}$$

So,

$$y(r) = \left[-j^{\frac{4}{K}} \right]^{nr} \sum_{p=0}^{N-1} e^{j2\pi \frac{np}{N}} v(r, p)$$

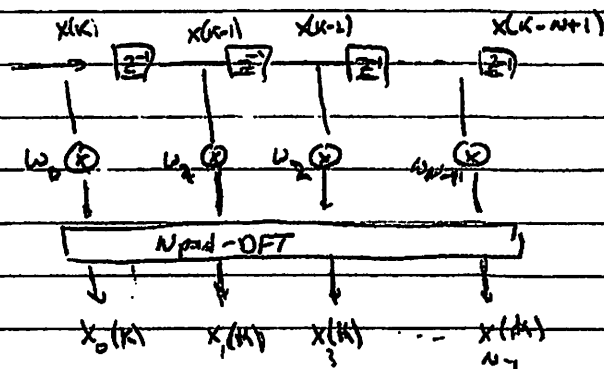
If $K=1$ then

$$y(r) = \sum_{p=0}^{N-1} e^{j2\pi \frac{np}{N}} v(r, p)$$

*Note: The computation of $v(r, p)$ is often called "Polyphase filtering".

What if we want multiple channels?

DFT Filterbank Approach - Another way of looking at it.



$$x_m(k) = \sum_{p=0}^{N-1} x(k-p) \omega(p) e^{j2\pi \frac{mp}{N}}$$

$$\text{Let } \bar{\omega}_m(p) = \omega(p) e^{j2\pi \frac{mp}{N}}$$

$$\Rightarrow x_m(k) = \sum_{p=0}^{N-1} x(k-p) \bar{\omega}_m(p)$$

This is output of a FIR filter with $x(k)$ as the input & $\bar{\omega}_m(p)$ as the impulse response.

$$x_m(k) = x(p) * \omega_m(p)$$

also,

$$W_m(\omega) = \sum_{p=0}^{N-1} \bar{\omega}_m(p) e^{-j\omega p T}$$

Transfer Function of Filter

If $\omega(p) = 1$ then,

$$W_m(\omega) = \sum_{p=0}^{N-1} e^{j2\pi \frac{mp}{N}} e^{-j\omega p T} = e^{-j\pi \frac{m}{N}} e^{-j\frac{(N-1)\omega T}{2}} \cdot \frac{\sin \frac{N\omega T}{2}}{\sin \left(\frac{\pi}{N} - \frac{\omega T}{2} \right)}$$

other bins (m) have the same response. -

• Decimation Demo 13.2.m 0.042Hz

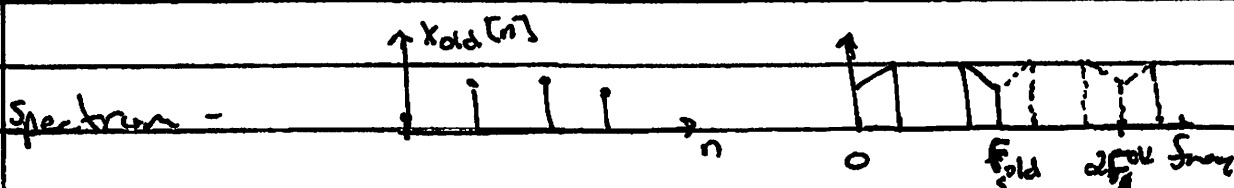
• Interpolation



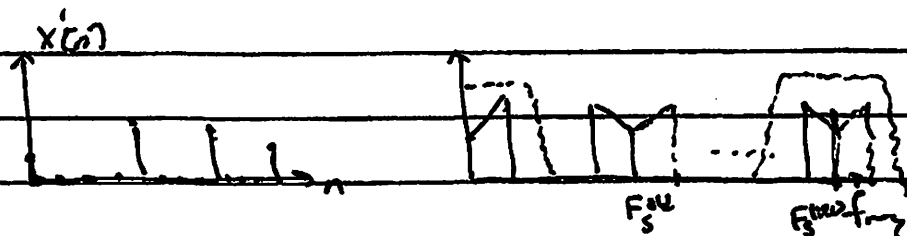
$$x_{old}[n] = x[0], x[1], x[2], x[3]$$

from

$$x'_{new}[n] = x_{old}[0] \circ \circ \circ x_{old}[1] \circ \circ \circ x_{old}[2] \circ \circ \circ$$



$M=4$



Demo 13.1.m
13.3.m

- low pass filter $x'[n]$ to attenuate spectral images;
- This filter is called "Interpolation filter".

Note - Accuracy of interpolation process depends on stopband attenuation of low pass interpolation filter.

Note - Inherent amplitude loss factor of M . To achieve unity gain between $x_{old}[n]$ and $x_{new}[n]$ the filter must have gain of M .

- Combining decimation and interpolation

Q: How do we change sample rate by any rational fraction ~~constant~~ M/D ?

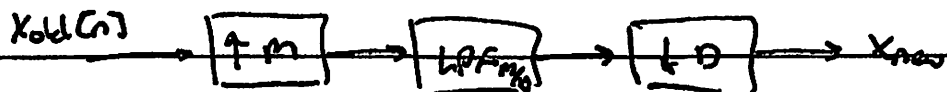
A: $x_{old}[n] \rightarrow \boxed{\uparrow M} \rightarrow \boxed{LPF_M} \rightarrow \boxed{LPF_D} \rightarrow \boxed{\downarrow D} \rightarrow x_{new}[n]$

Example

Change sample rate ~~to~~ by 7.125.

$$\Rightarrow M=57, D=8 \quad \frac{M}{D} = \frac{57}{8} = 7.125$$

We can combine LPF_M & LPF_D .



↑
called "multirate" filter.

This is again a job of lowpass filter design!

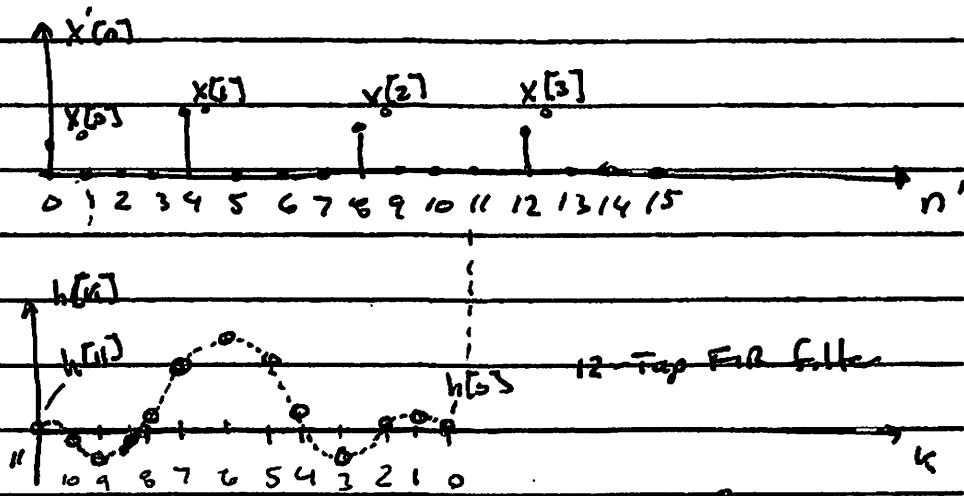
This process is very inefficient.

Example $\frac{M}{D} = \frac{4}{3} \Rightarrow$ stuff 3 zeros then LP-filter.

$\frac{3}{4}$ of multiples will be ~~zeros~~ zeros.

Next, discard $\frac{2}{3}$ of filter outputs... very ~~not~~ inefficient!

• Polyphase Filters



$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

- 12 mults for each output $x_{\text{new}}[n]$
- 9 mults are always zero

With $M=4$, there are 4 different sets of coeff used to compute $x_{\text{new}}[n]$

$$x_{\text{new}}[0] = h[3]x_0[2] + h[7]x_0[1] + h[11]x_0[0]$$

$$x_{\text{new}}[1] = h[5]x_0[3] + h[4]x_0[2] + h[8]x_0[1]$$

$$x_{\text{new}}[2] = h[1]x_0[3] + h[5]x_0[2] + h[9]x_0[1]$$

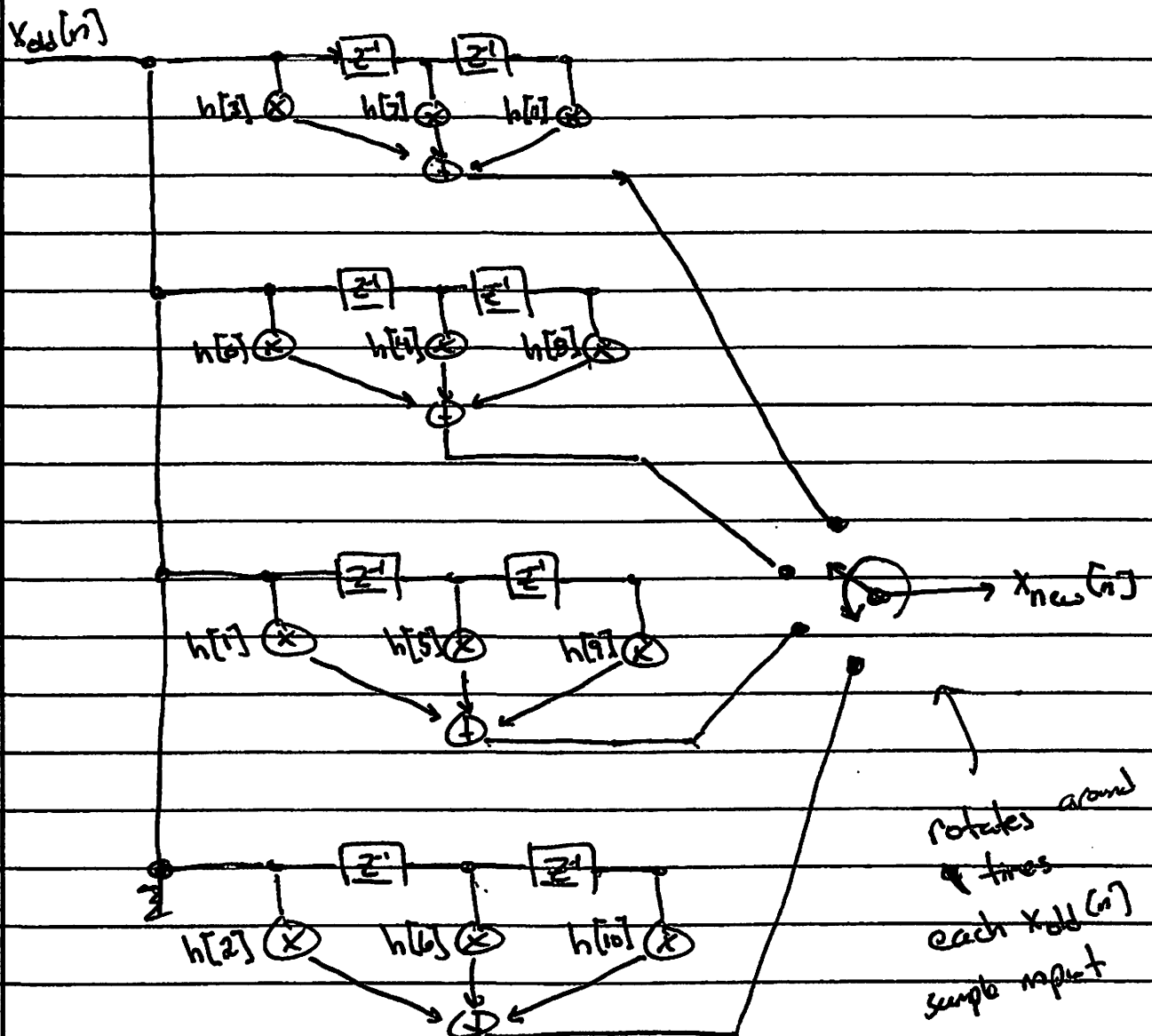
$$x_{\text{new}}[3] = h[2]x_0[3] + h[6]x_0[2] + h[10]x_0[1]$$

$$x_{\text{new}}[4] = h[3]x_0[3] + h[7]x_0[2] + h[11]x_0[1]$$

⋮

We can implement this with a bank of 4 sub-filters

↓ see next page



$$\begin{aligned}
 H(z) = & h[0] + h[4]z^{-1} + h[8]z^{-2} \\
 & + [h[1] + h[5]z^{-1} + h[9]z^{-2}]z^{-1} \\
 & + [h[2] + h[6]z^{-1} + h[10]z^{-2}]z^{-2} \\
 & + [h[3] + h[7]z^{-1} + h[11]z^{-2}]z^{-3}
 \end{aligned}$$

Note - $z^{-1} = z_c^{-4}$ & $z^{-2} = z_c^{-8}$

$$\begin{aligned}
 \Rightarrow H(z) = & h[0] + h[4]z_c^{-4} + h[8]z_c^{-8} \\
 & + h[1]z_c^{-1} + h[5]z_c^{-5} + h[9]z_c^{-9} \\
 & + h[2]z_c^{-2} + h[6]z_c^{-6} + h[10]z_c^{-10} \\
 & + h[3]z_c^{-3} + h[7]z_c^{-7} + h[11]z_c^{-11}
 \end{aligned}$$

$$H(z) = \sum_{k=0}^{11} h[k]z_c^{-k}$$

12-Tap FIR filter.

What about decimation?

