

# CS-583: Deep Learning AutoEncoder

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# Autoencoder

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## **Motivation:**

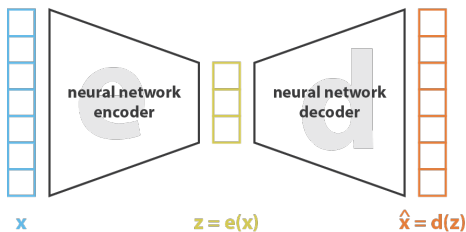
- Deep neural networks require lot of data
- Sometimes not very much labeled data, but plenty of unlabeled data (text, images, videos)
- Humans rarely get direct supervision; can learn from raw sensory information?

# Autoencoder

## Analogy:

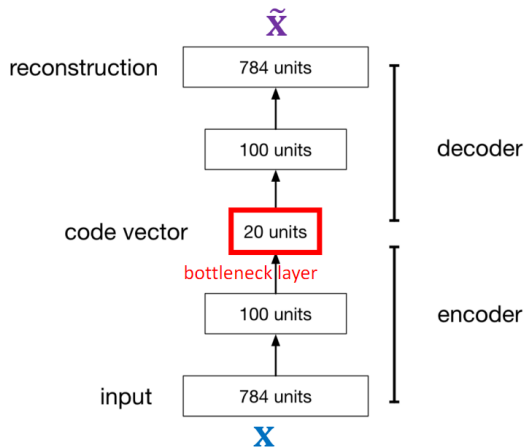
A A A A B B B B B  $\Rightarrow$  4 A's, 5 B's  $\Rightarrow$  A A A A B B B B B

**Key idea:** If we can compress a data point and still reconstruct it, then we have learned something generally useful



$$\text{loss} = \|x - \hat{x}\|^2 = \|x - d(z)\|^2 = \|x - d(e(x))\|^2$$

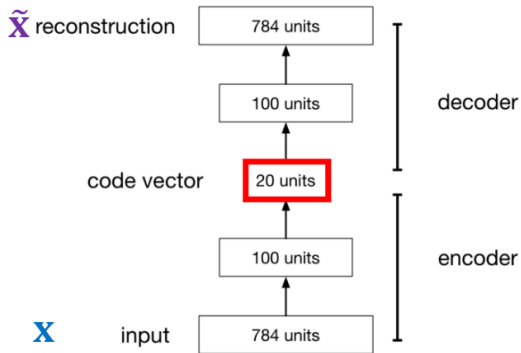
# Autoencoder



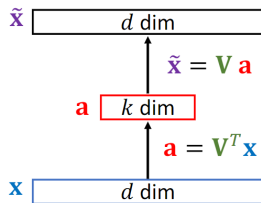
- An autoencoder is a neural net taking an input  $x$  and reconstruct  $x$
- For dim reduction, we need a bottleneck layer whose output shape is much smaller than the input
- Loss function:  $\sum_{j=1}^x |x_j - \tilde{x}_j|_2^2$

# Autoencoder

Autoencoder is nonlinear  
 $\tilde{x} = \text{decoder}(\text{encoder}(x))$



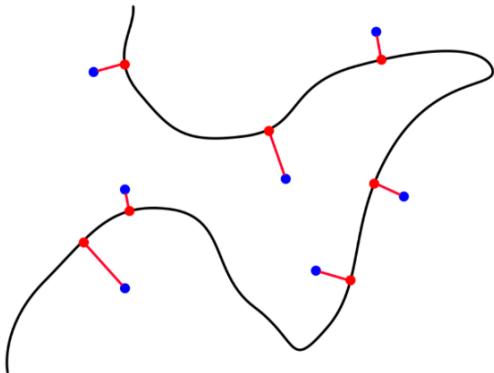
PCA is linear  
 $\tilde{x} = VV^T x$



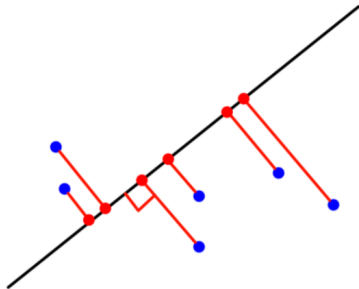
# Autoencoder

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Autoencoder projects data onto nonlinear manifold



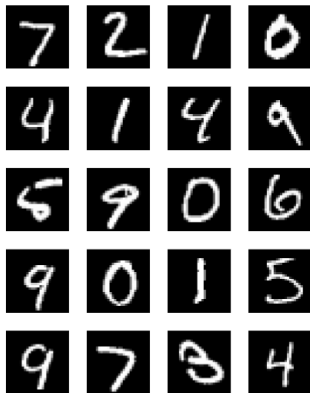
PCA projects data onto a subspace



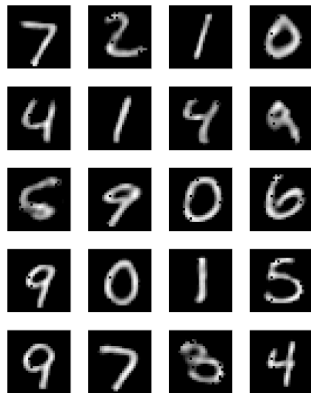
# Autoencoder

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Input

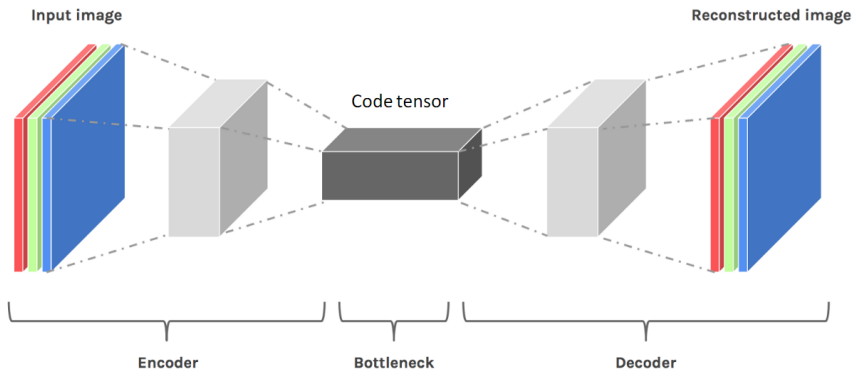


Reconstructed



# Convolutional Autoencoder

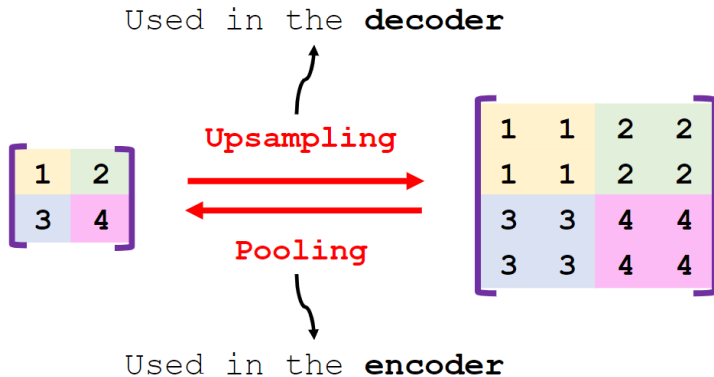
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# Convolutional Autoencoder

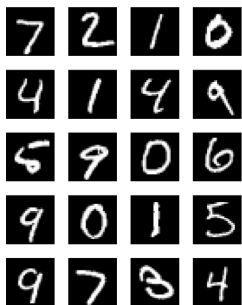
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# Convolutional Autoencoder

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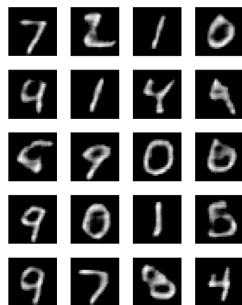
Original Input



Dense Autoencoder

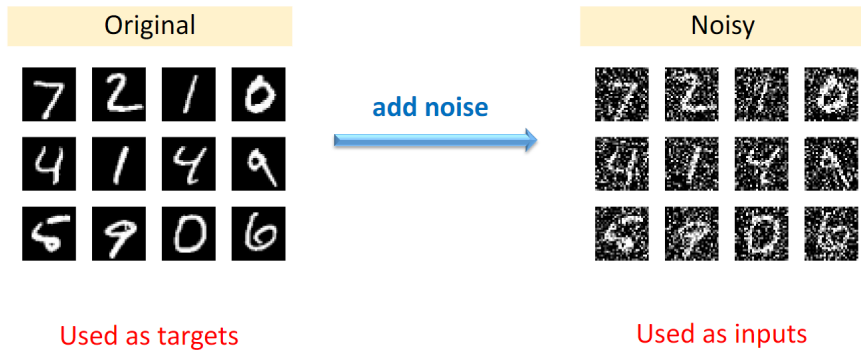


Conv Autoencoder



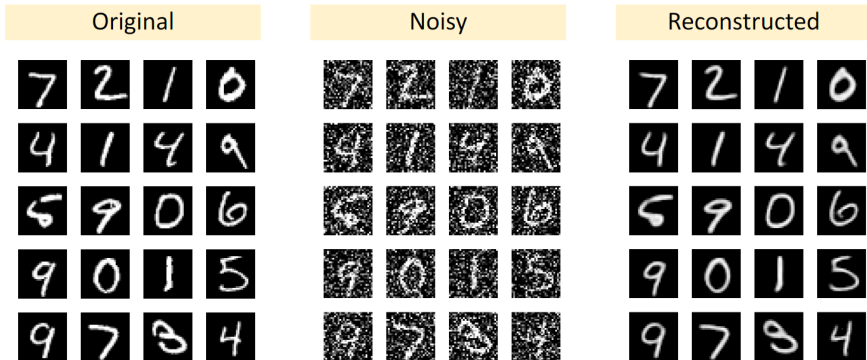
# Denoising Autoencoder

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# Denoising Autoencoder

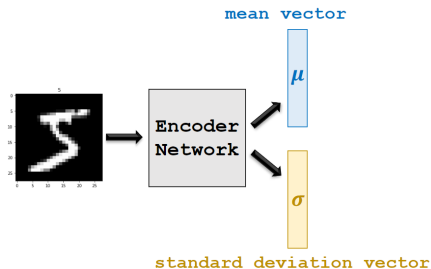
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# Variational Autoencoder

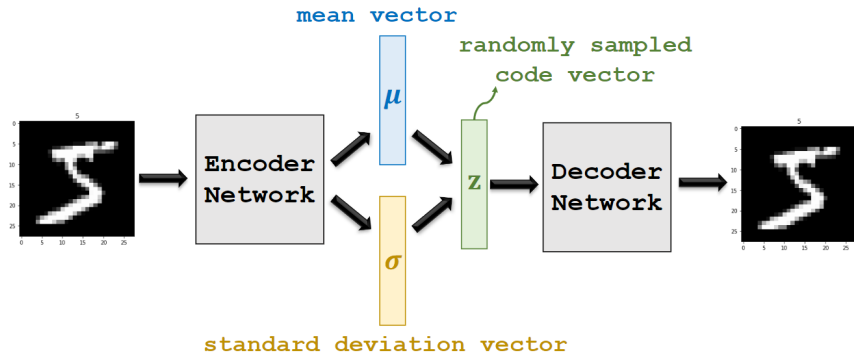
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Instead of a single vector output by the encoder, VAE outputs a distribution

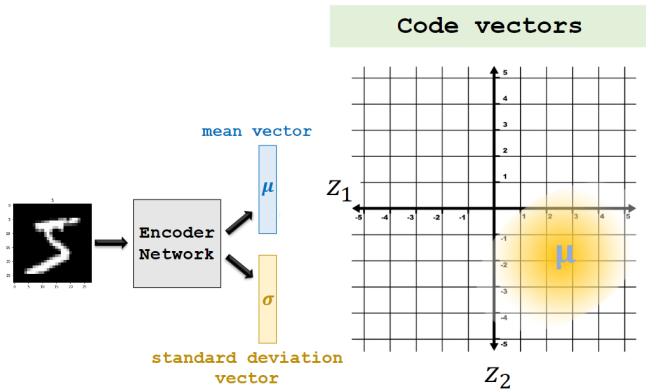


# Variational Autoencoder

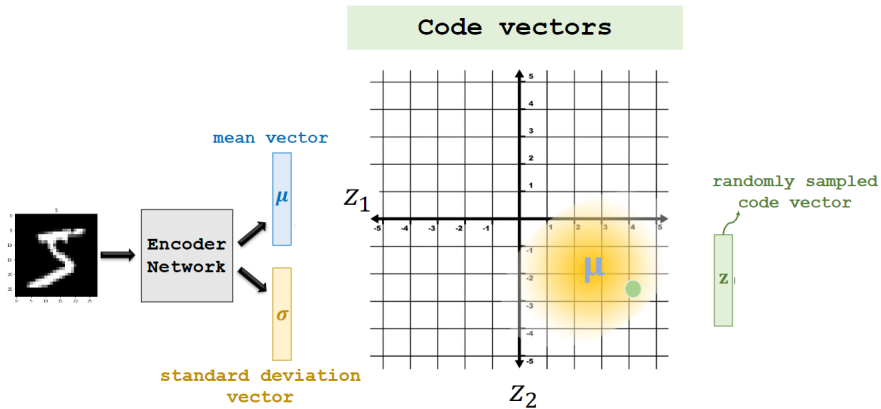
Sample a code vector from the distribution and reconstruct the original



# Variational Autoencoder

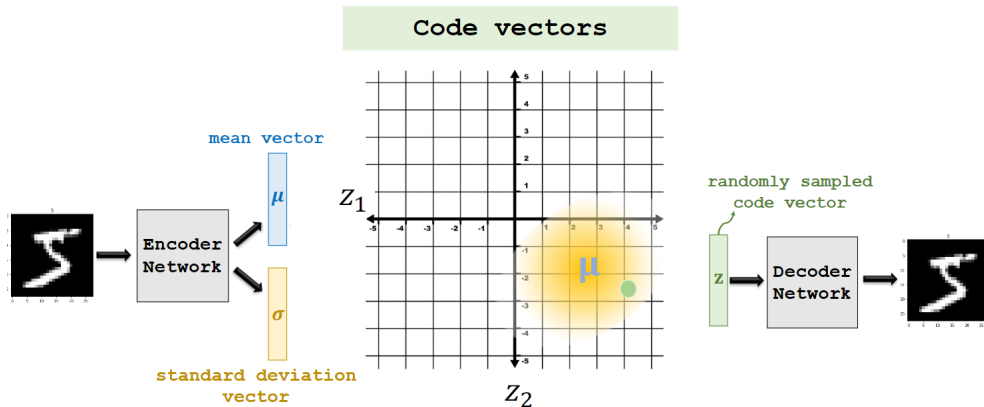


# Variational Autoencoder



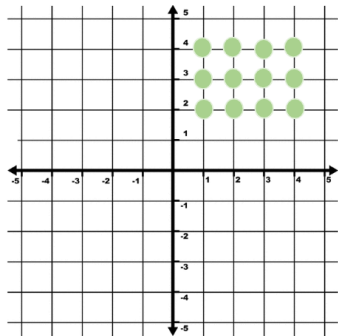


# Variational Autoencoder



# Variational Autoencoder

## Code vectors



- Get a set of code vectors from the grid:

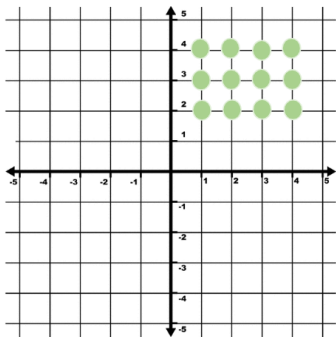
$$z_1, z_2, z_3, z_4, z_5, \dots$$

For every code vector  $z_i$ , map it to an image using the decoder:

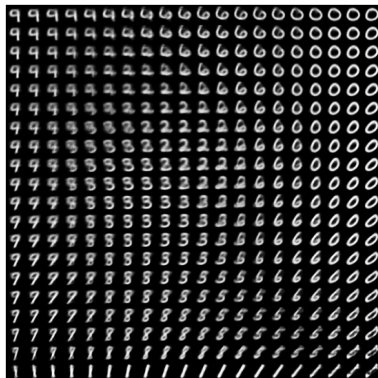
$$image_i = decoder(z_i)$$

# Variational Autoencoder

Code vector



Images



# Variational Autoencoder

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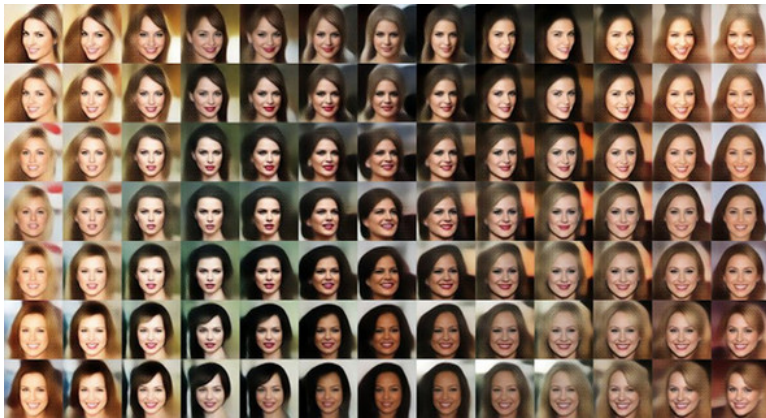
- Function  $f$  is continuous if a small change in  $z$  (input) results in a small change in  $f(z)$  function value)
- The decoder network is trained to be (almost) continuous
- If the code vectors  $z$  and  $z'$  are similar, then the images

$$\text{Decoder}(z) \quad \text{and} \quad \text{Decoder}(z')$$

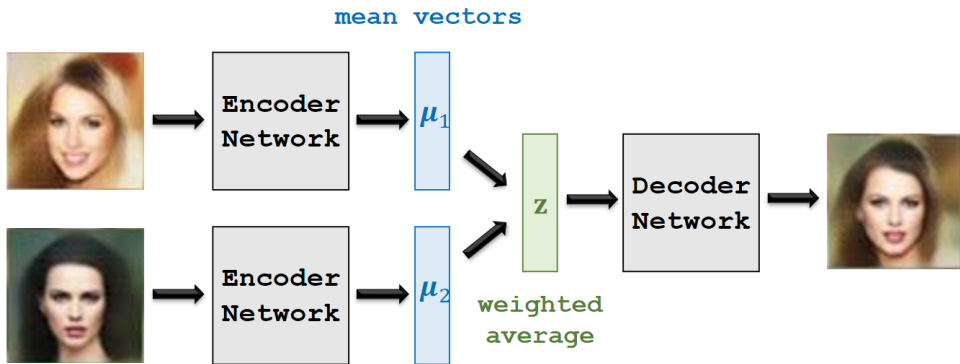
are similar as well

# Variational Autoencoder

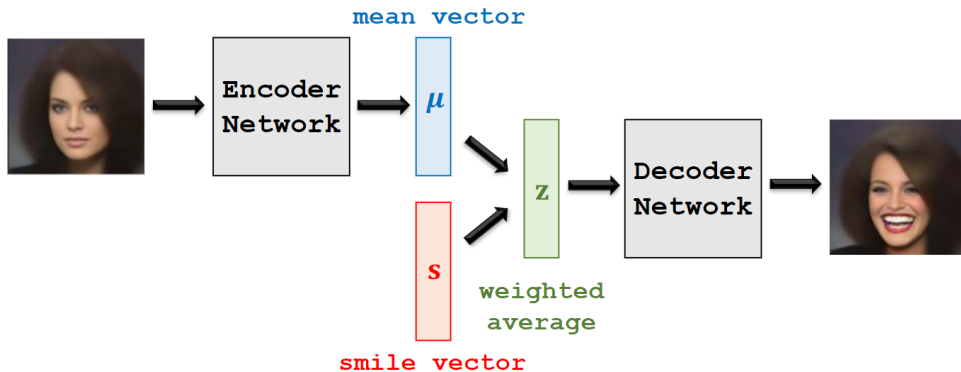
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# Variational Autoencoder



# Variational Autoencoder



# Variational Autoencoder

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$\mu$

$\mu + s$

$\mu + 2s$

$\mu + 3s$

$\mu + 4s$



$\mu$

$\mu - s$

$\mu - 2s$

$\mu - 3s$

$\mu - 4s$





# Summary

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- Autoencoder: generalizations of (linear) PCA
  - Autoencoder = Encoder + Decoder
  - Original/noisy images  $\rightarrow$  original images
  - Application: Dimensionality reduction or Denoising
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- VAE = AE + probability tricks
  - The decoder network behaves like a continuous function
  - Application: Edit images (average faces/add smile etc.)

# References

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Stuart Russell and Xiaodong Song (2021)

CS 188 — Introduction to Artificial Intelligence

*University of California, Berkeley*



Chelsea Finn and Nima Anari (2021)

CS221 — Artificial Intelligence: Principles and Techniques

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**The End**