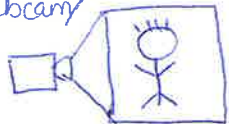


$4 \times 4 = 16$ man weeks accountable

- Pure ~~open~~ CV mode

- Data base on poses

webcam



Kinect

DB

matching Y/N

Step 1

HOI

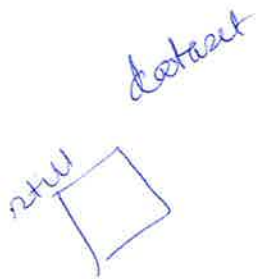
MS-1

↓

Step 2

- Skeleton/feature compare and feedback to correct [HACK] feature/lookup

MS-02



Webot (32 bit interface)

Step 1

- Transfer / Hard code DB poses to Webot

MS-1

Step 2

- Transfer motor angles to standard skeleton

MS-02

OpenCV Step 2

Webot Step 2

HOI

2 weeks

establish feedback loop.