# Omid Hosseini Jafari

# Curriculum Vitae

### Personal Information

⊠ Email omid.hosseini\_jafari@iwr.uni-heidelberg.de

hj.omid@gmail.com

Homepage https://ohosseini.github.io

### Education

2015-Present Ph.D. candidate, Heidelberg University, Heidelberg, Germany.

Scene Understanding

2011–2014 Masters of Science, RWTH-Aachen University, Aachen, Germany.

Media Informatics

Thesis Title - "Improving depth based people detection for mobile robotics"

2005–2009 Bachelor of Science Azad University - South Tehran Branch, Tehran, Iran.

Software Engineering

Thesis Title – "Face recognition using appearance based methods"

### Research Interests

Computer Vision, Machine Learning, Deep Learning, Scene Understanding

### Publications

ACCV 2018 Deep Object Co-Segmentation

Omid Hosseini Jafari\*, Weihao Li\*, Carsten Rother (\* equal contribution)

ACCV 2018 iPose: Instance-Aware 6D Pose Estimation of Partly Occluded Objects

Omid Hosseini Jafari\*, S.K. Mustikovela\*, K. Pertsch, E. Brachmann, C. Rother (\* equal contribution)

ICCV 2017 Bounding Boxes, Segmentations and Object Coordinates: How Important is Recognition for 3D Scene Flow Estimation in Autonomous Driving Scenarios?

Omid Hosseini Jafari\*, A. Behl\*, S. K. Mustikovela\*, H. Abu Alhaija, C. Rother, A. Geiger (\* equal contribution)

International Conference on Computer Vision (ICCV), Oct. 2017

VMV 2017 Semantic-Aware Image Smoothing

Weihao Li, Omid Hosseini Jafari, Carsten Rother

International Symposium on Vision, Modeling and Visualization (VMV), Sep. 2017

ICRA 2017 Analyzing Modular CNN Architectures for Joint Depth Prediction and Semantic

Segmentation

Omid Hosseini Jafari, Oliver Groth, Alexander Kirillov, Michael Y. Yang, Carsten Rother IEEE International Conference on Robotics and Automation (ICRA), June 2017

ICRA 2016 Real-Time RGB-D based Template Matching Pedestrian Detection

Omid Hosseini Jafari, Michael Y. Yang

IEEE International Conference on Robotics and Automation (ICRA), June 2016

# ICRA 2014 Real-Time RGB-D based People Detection and Tracking for Mobile Robots and Head-Worn Cameras

Omid Hosseini Jafari, Dennis Mitzel, Bastian Laibe

IEEE International Conference on Robotics and Automation (ICRA), June 2014

### Skills

Programming Languages C/C++, Python, C#, Basic(Commodore64, GWBasic, QBasic, Visual Basic), Pascal, Java

Tools Pytorch, Tensorflow, CAFFE, MATALB, CodeVision, AVR, PSpice

Operating Systems Linux/Unix, Windows, MS-DOS

Graphics Design 3D Studio, 3DS max, blender, ZBrush, Maya

### Research Experiences

2016 - 2018 Research Supervision and Teaching Preparation, TU Dresden and Heidelberg University

Master thesis supervision Computer Vision Lecture

July 2016 ICVSS 2016 Summer School

June 2013 CVPR 2013 Demo

Mentors: Dr. Dennis Mitzel, Prof. Bastian Leibe

Online People Detector and Tracker

Apr. 2013 - Aug. 2013 Lab Project, Fraunhofer IAIS, Bonn, Germany

Mentor: Dr. Rolf Bardeli

Video processing and augmented reality.

Oct. 2012 - Apr. 2013 Lab Project, Human Language Technology and Pattern Recognition Group

Mentor: Prof. Hermann Ney Automatic Speech Recognition

Mar. 2012 - Oct. 2014 Student Research Asistant, Computer Vision Lab at RWTH Aachen University, Germany

Advisor: Prof. Bastian Leibe

Multiple pedestrian detection and tracking.

2006 - 2009 ACM ICPC

as Participant and Mentor

2006 - 2009 **Teaching Assistant**, Azad University, Tehran, Iran

Fundamentals of Programming (C++)

Data Structure

introduction to algorithms

Logical Circuits

### References

Ph.D. Advisor Dr. Prof. Carsten Rother, Visual Learning Lab, Heidelberg University, Germany.

⊠ carsten.rother@iwr.uni-heidelberg.de

Research Mentor Prof. Dr. Andreas Geiger, Max Plunk Institute and University of Tübingen, Germany.

⊠ andreas.geiger@tue.mpg.de

M.Sc. Advisor Prof. Dr. Bastian Leibe, Visual Computing Institute, RWTH Aachen University, Germany.

☑ leibe@vision.rwth-aachen.de

## **Hobbies**

Playing musical instruments (Piano, Guitar, Tanbur), Cycling, Badminton, Tennis, Hiking, Paragliding