# Process Synchronization (4)

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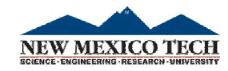


#### **In-Class Work 3**

- ☐ The following figure shows the sequence of semaphore operations at the beginning and at the end of the tasks A, B.
- Determine for each of the 4 cases a, b, c and d, whether or in which sequence the tasks are executed, using the initializations of the semaphore variables given in Table 1.
- □ wait() is an atomic operation that waits for semaphore to become positive, then decrements it by 1, i.e. if the semaphore is 0, wait() is blocked.
- □ signal() is an atomic operation that increments the semaphore by 1, waking up a waiting wait() if any.
- ☐ SA, SB are the two semaphores corresponding to Tasks A and B.

#### **In-Class Work 3**

Task A Task B wait(SA) wait(SB) wait(SA) wait(SB) signal(SB) signal(SA) **END END** Table 1 a b c d SA 2 1 0 2 SB 0 1 2 1



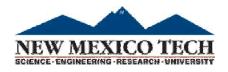
#### Answer

a: task A

b: No task will be executed

c: task B

d: task A, task B



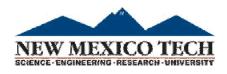
# Classical Problems of Synchronization

- ☐ Classical problems used to test newlyproposed synchronization schemes
  - ☐ Bounded-Buffer Problem
  - ☐ Readers and Writers Problem
  - ☐ Dining-Philosophers Problem



#### **Bounded-Buffer Problem**

- $\square$  *n* buffers, each can hold one item
- □Semaphore mutex initialized to the value 1
- □Semaphore **full** initialized to the value o
- □Semaphore **empty** initialized to the value n



### **Bounded Buffer Problem** (Cont.)

The structure of the producer process

```
do {
   /* produce an item in next_produced */
   wait (empty);
   wait (mutex);
   /* add next produced to the buffer */
   signal(mutex);
   signal(full);
} while (true);
```

### **Bounded Buffer Problem** (Cont.)

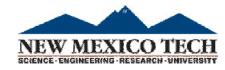
The structure of the consumer process

```
Do {
   wait(full);
   wait (mutex);
 /* remove an item from buffer to next_consumed */
   signal(mutex);
   signal(empty);
     /* consume the item in next consumed */
  } while (true);
```

#### **Readers-Writers Problem**

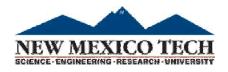
☐ A data set is shared among a number of concurrent processes ☐ Readers – only read the data set; they do *not* perform any updates □ Writers – can both read and write ☐ Problem – allow multiple readers to read at the same time □ Only one single writer can access the shared data at the same time ☐ Several variations of how readers and writers are considered – all involve some form of priorities ☐ Shared Data □ Data set ☐ Semaphore rw\_mutex initialized to 1 ☐ Semaphore mutex initialized to 1

☐ Integer read\_count initialized to 0



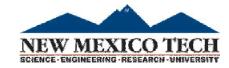
### Readers-Writers Problem Variations

- ☐ *First* variation no reader kept waiting unless writer has permission to use shared object
- □ **Second** variation once writer is ready, it performs the write ASAP
- ☐ Both may have starvation leading to even more variations



### Readers-Writers Problem (Cont.)

The structure of a writer process



## Readers-Writers Problem (Cont.)

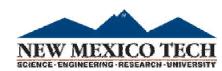
The structure of a reader process

```
do {
   wait(mutex);
   if (read_count == 1) /* First reader in */
      wait(rw_mutex); /* Lock out writers */
   signal(mutex);
       /* reading is performed */
   wait(mutex);
   read count--; /* Protected by mutex */
   if (read_count == 0) /* Last out */
          signal(rw_mutex); /* Let in writers */
   signal(mutex);
} while (true);
```

### Dining-Philosophers Problem



- ☐ Philosophers spend their lives alternating thinking and eating
- □ Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
  - ☐ Need both to eat, then release both when done
- ☐ In the case of 5 philosophers
  - ☐ Shared data
    - ☐ Bowl of rice (data set)
    - ☐ Semaphore chopstick [5] initialized to 1



### Dining-Philosophers Problem Algorithm

 $\Box$  The structure of Philosopher *i*: do { wait (chopstick[i]); wait (chopstick[(i + 1) % 5]); // eat signal (chopstick[i] ); signal (chopstick[(i + 1) % 5]); // think } while (TRUE);

☐ What is the problem with this algorithm?

