Hiyeon Kim, 118654
Lars Meyer, 114719

Exercise 1.6

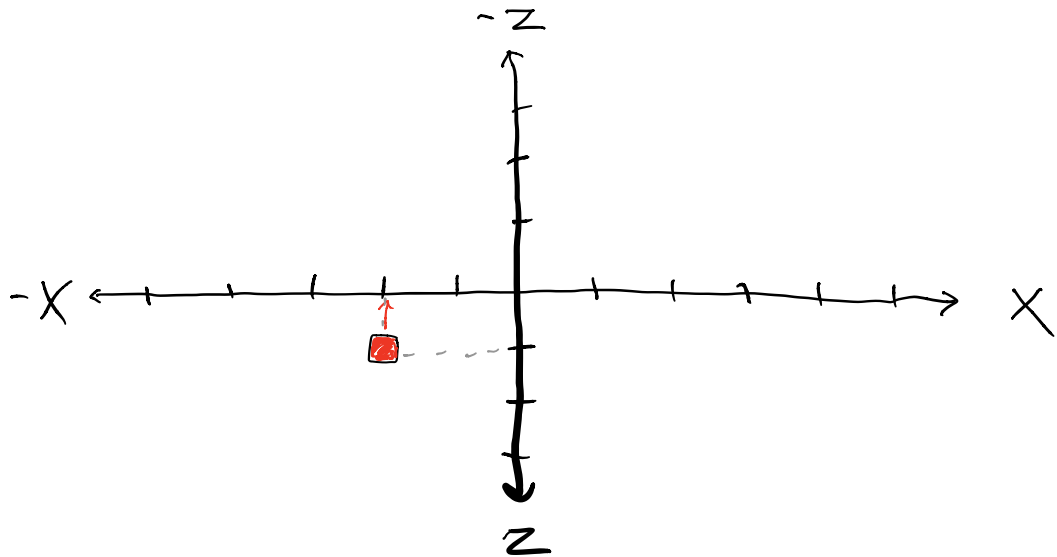▷ rot(90, y) · trans(5.0, 0.0, -2.0)

5

-X

-2

z
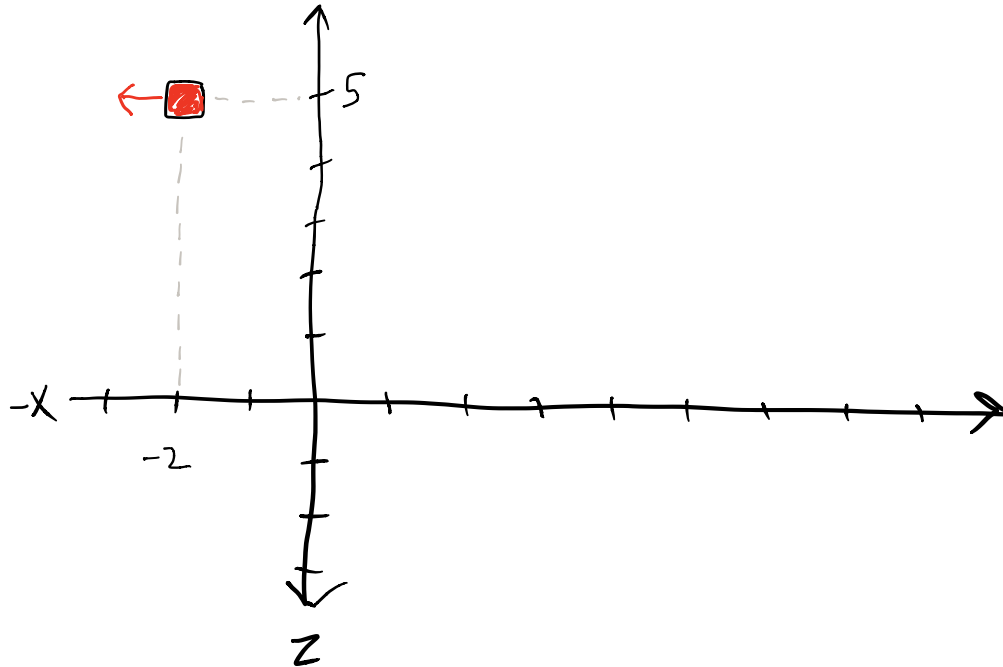
▷ trans(-4.0, 0.0, 2.0) · scale(0.5)

~z

-X

X

z
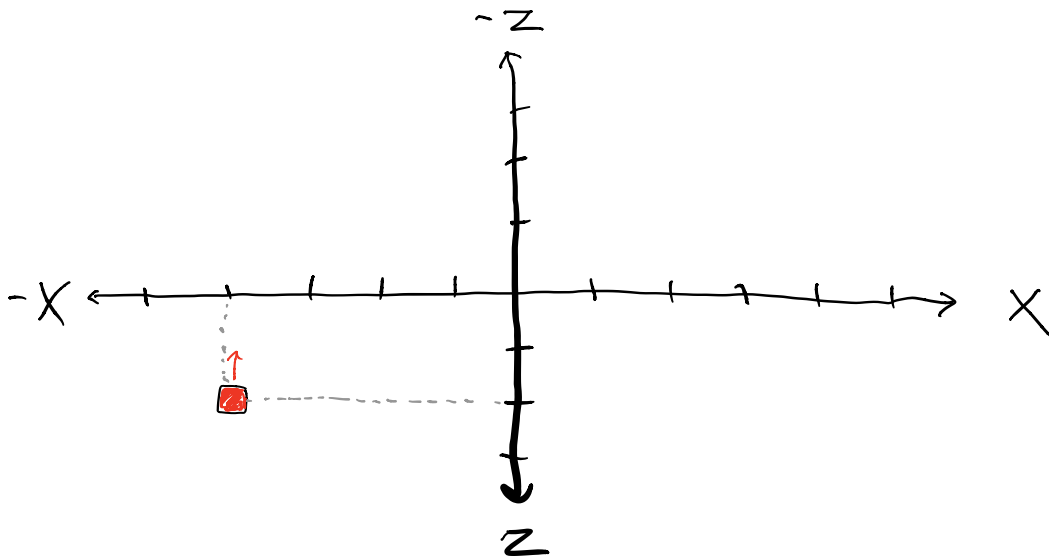
▷ scale (0.5) · trans (−4.0, 0.0, 2.0)

▷ trans (−2.0, 0.0, 4.0) · scale (0.5) · rot (180, y)