

Single Image Haze Removal Using Dark Channel Prior

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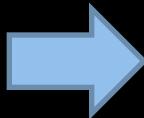
The Chinese University of Hong Kong

Hazy Images



- Low visibility
- Faint colors

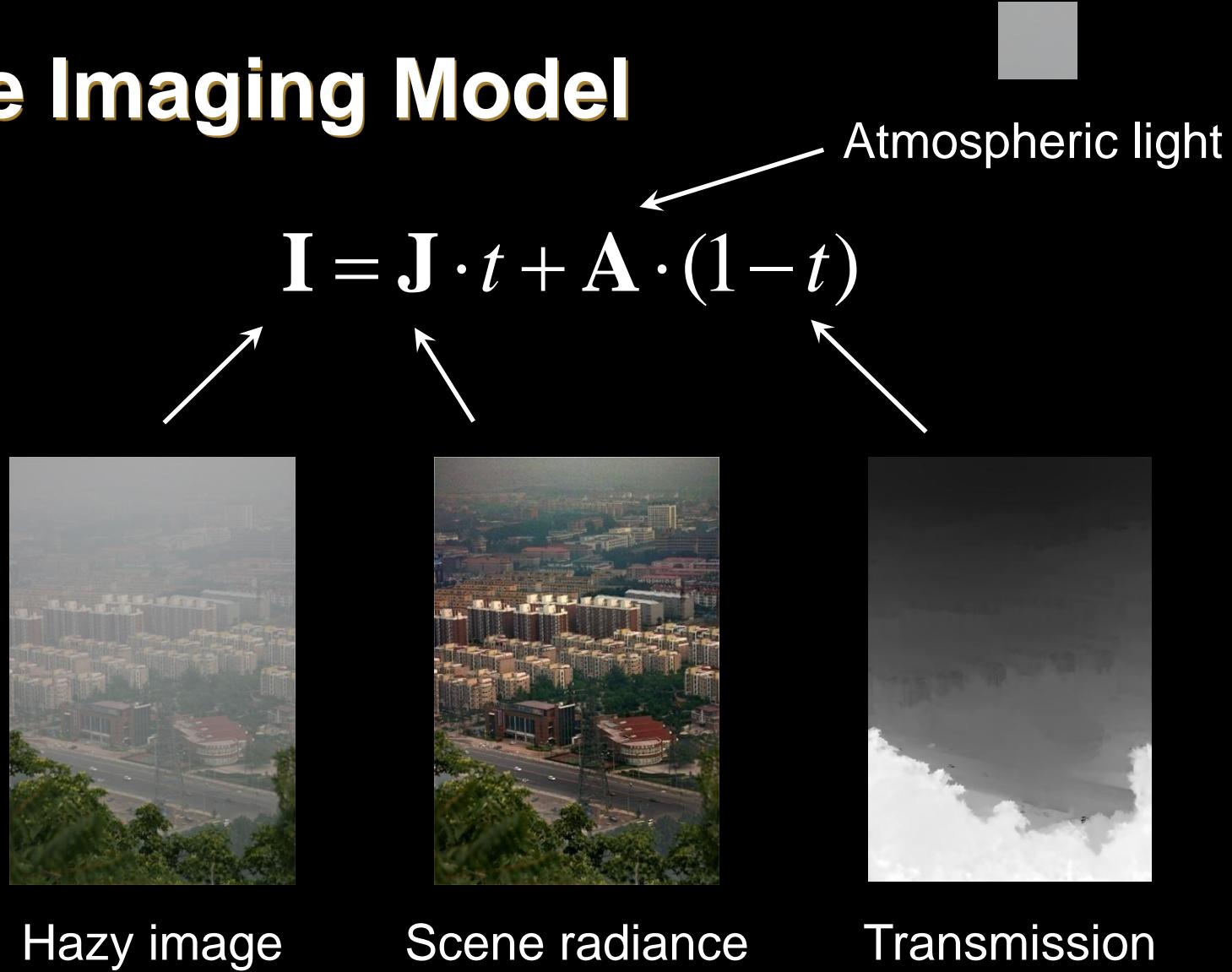
Goals of Haze Removal



depth

- Scene restoration
- Depth estimation

Haze Imaging Model



Haze Imaging Model

$$\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$$



Depth

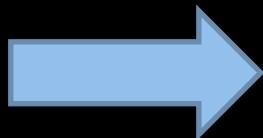
$$d = -\beta \ln t$$




Transmission

Ambiguity in Haze Removal

scene
radiance



...

input

depth

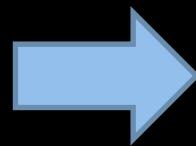


Previous Works

- Using additional information
 - Polarization filter [Shwartz et al., CVPR'06]
 - Multiple images [Narasimhan & Nayar, CVPR'00]
 - Known 3D model [Kopf et al., Siggraph Asia'08]
 - User-assistance [Narasimhan & Nayar, CPMCV'03]

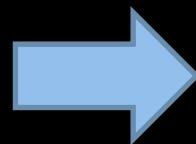
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]



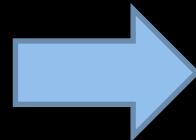
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]



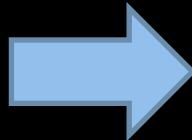
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]
 - Independent Component Analysis [Fattal, Siggraph 08]

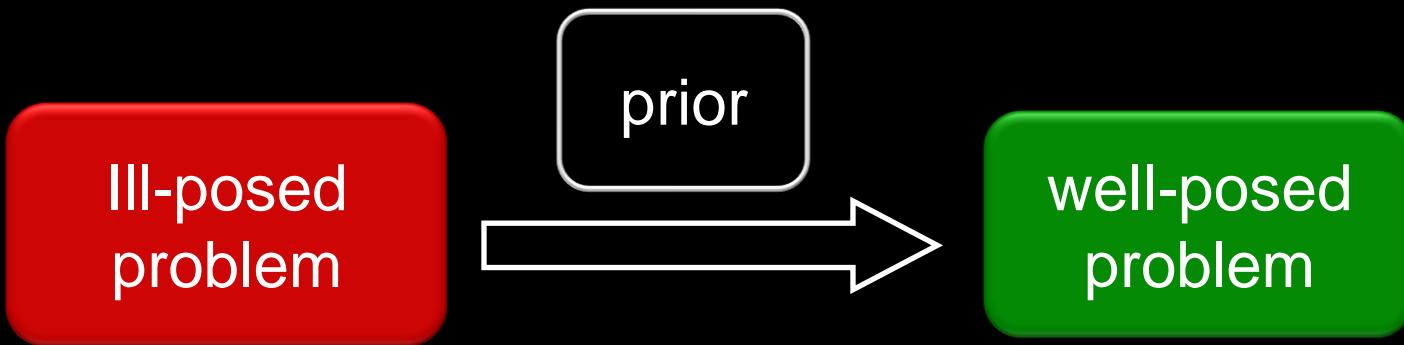


Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]
 - Independent Component Analysis [Fattal, Siggraph 08]



Priors in Computer Vision



- Smoothness prior
- Sparseness prior
- Exemplar-based prior

Dark Channel Prior

Dark Channel

- $\min(\text{rgb}, \text{local patch})$

Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$

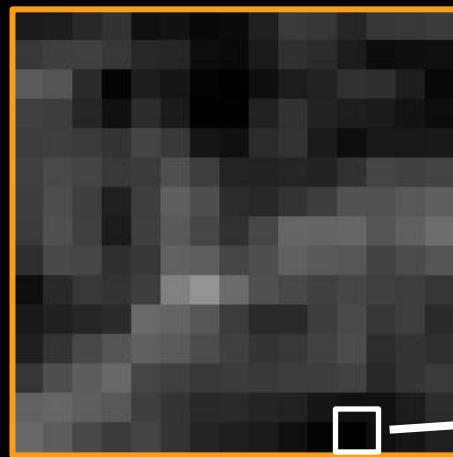


$\min(r, g, b)$

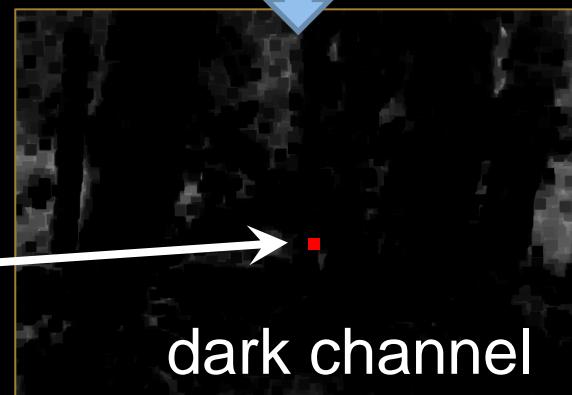
Dark Channel

- min (rgb, local patch)
 - min (r, g, b)
 - min (local patch) = min filter

15 x 15



darkest



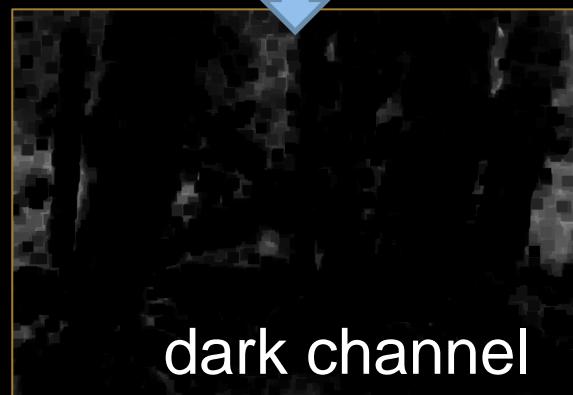
dark channel

Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$
 - $\min(\text{local patch}) = \text{min filter}$

$$J^{dark}(\mathbf{x}) = \min_{y \in \Omega(\mathbf{x})} (\min_{c \in \{r,g,b\}} J^c(y))$$

- J^c : color channel of J
- J^{dark} : dark channel of J

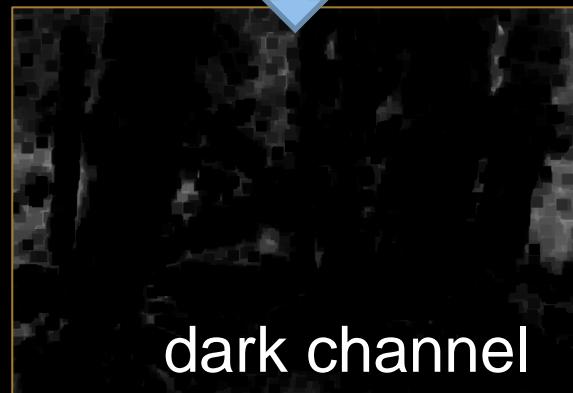


Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$
 - $\min(\text{local patch}) = \text{min filter}$

$$J^{dark} = \min_{\Omega} (\min_c J^c)$$

- J^c : color channel of J
- J^{dark} : dark channel of J



A Surprising Observation

Haze-free



A Surprising Observation

Haze-free



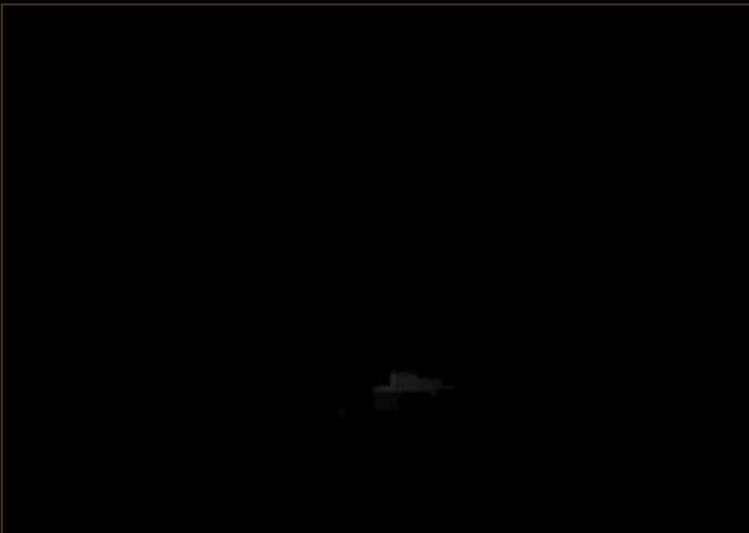
A Surprising Observation

Haze-free



A Surprising Observation

Haze-free



A Surprising Observation

Haze-free

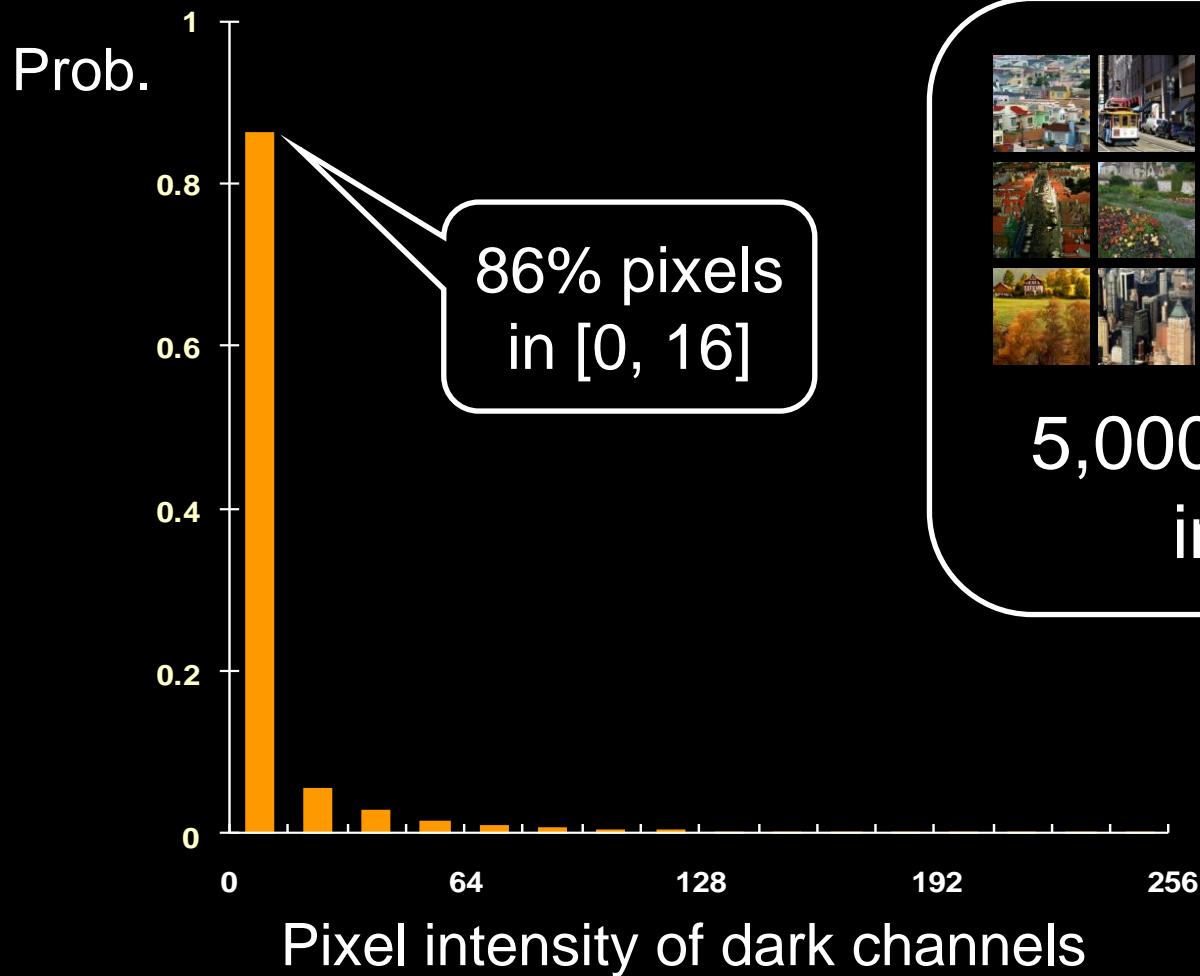


A Surprising Observation

Haze-free



A Surprising Observation



86% pixels
in [0, 16]



5,000 haze-free
images

Dark Channel Prior

- For outdoor haze-free images

$$\min_{\Omega} \left(\min_c J^c \right) \rightarrow 0$$

What makes it dark?

- Shadow



- Colorful object



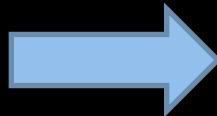
- Black object



Dark Channel of Hazy Image



hazy image



dark channel

- The dark channel is no longer dark.

Transmission Estimation

Haze imaging model $I = J \cdot t + A \cdot (1 - t)$

Normalize

$$\frac{I^c}{A^c} = \frac{J^c}{A^c} t + 1 - t$$

Compute dark channel

$$\min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right) = \left\{ \min_{\Omega} \left(\min_c \frac{J^c}{A^c} \right) \right\} t + 1 - t$$

Transmission Estimation

Dark Channel Prior

$$\min_{\Omega} (\min_c J^c) \rightarrow 0$$

Compute dark channel

$$\min_{\Omega} (\min_c \frac{I^c}{A^c}) = \left[\min_{\Omega} (\min_c \frac{J^c}{A^c}) \right] t + 1 - t \rightarrow 0$$

Transmission Estimation

Estimate transmission

$$t = 1 - \min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right)$$



Compute dark channel

$$\min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right) = \left\{ \min_{\Omega} \left(\min_c \frac{J^c}{A^c} \right) \right\} t + 1 - t$$

Transmission Estimation

Estimate transmission

$$t = 1 - \min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right)$$



input I



estimated t



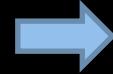
Transmission Optimization

Haze imaging model $\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$

Matting model $\mathbf{I} = \mathbf{F} \cdot \alpha + \mathbf{B} \cdot (1 - \alpha)$



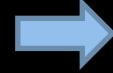
+



α



+



Refined
transmission

Transmission Optimization

$$E(t) = \lambda \|t - \tilde{t}\|^2 + t^T Lt$$

Data termSmoothness term

- **L** - matting Laplacian [Levin et al., CVPR '06]
- Constraint - soft, dense (matting - hard, sparse)

Transmission Optimization



before optimization

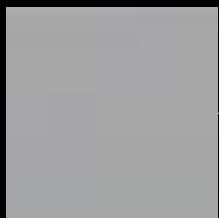
Transmission Optimization



after optimization

Atmospheric Light Estimation

A: most hazy



brightest pixel

brightest pixels



hazy image

dark channel

Scene Radiance Restoration

Atmospheric
light

$$I = J \cdot t + A \cdot (1 - t)$$



Hazy image

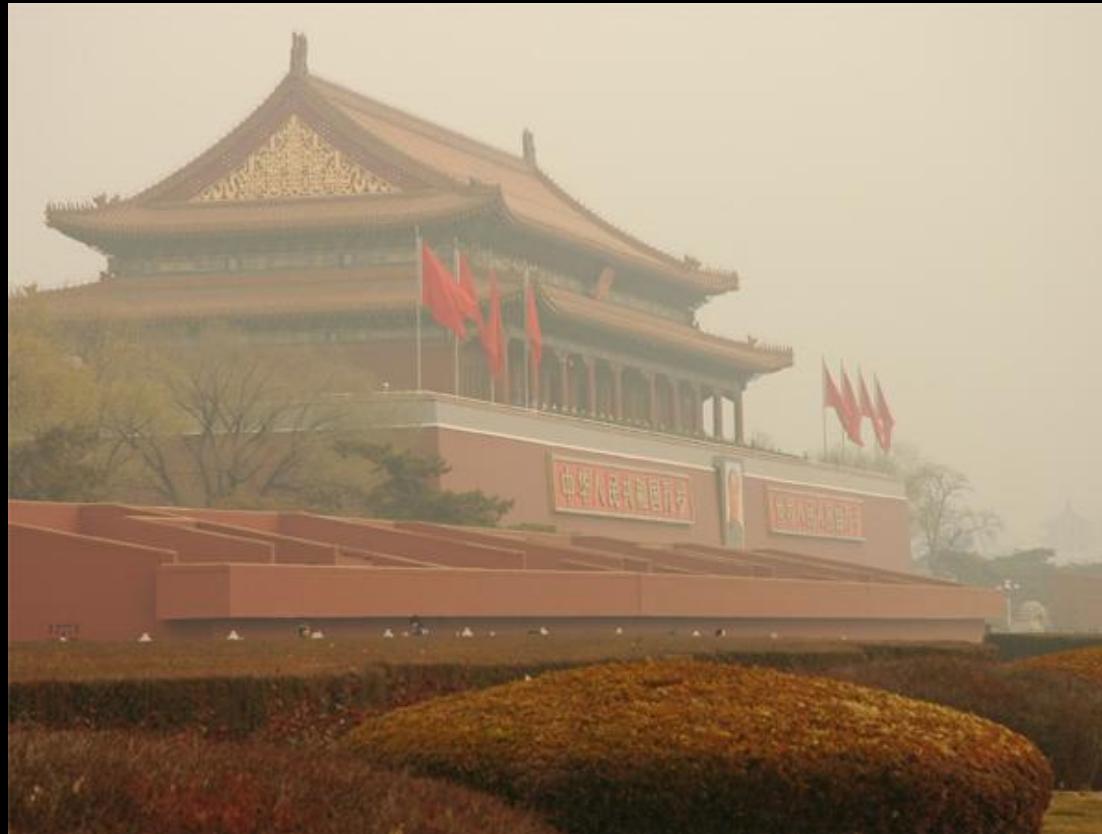


Scene radiance



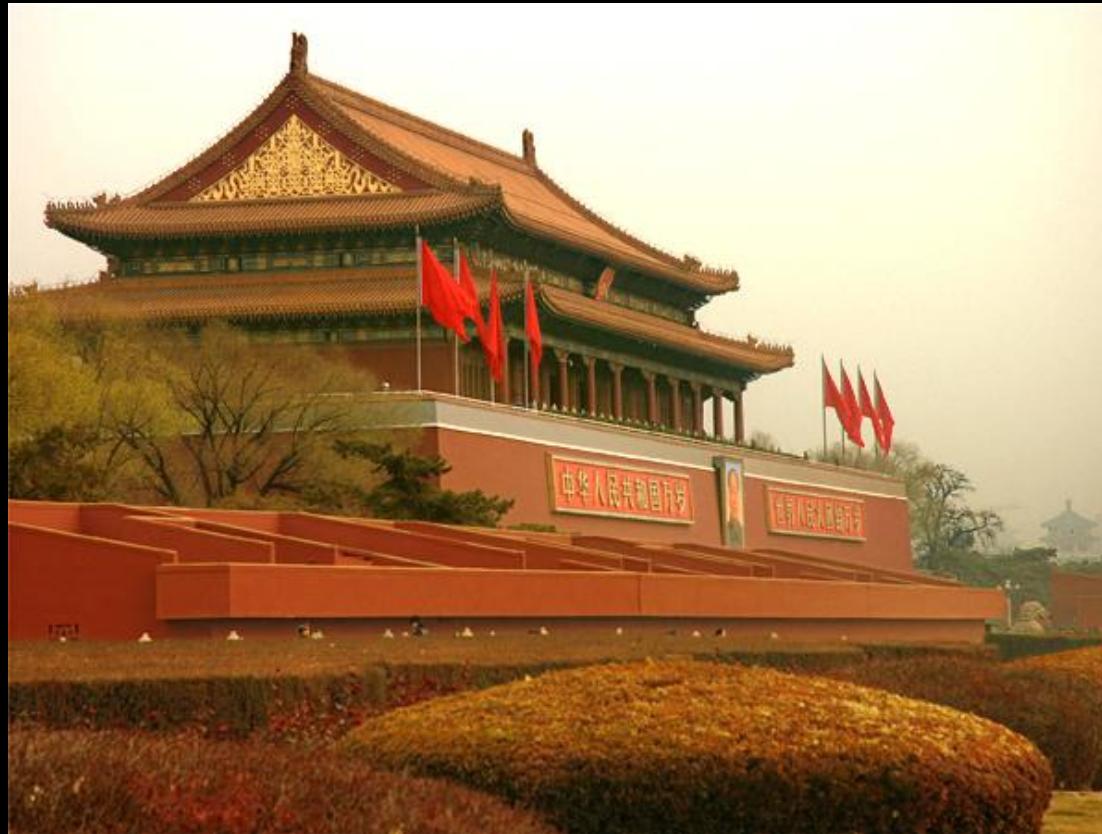
Transmission

Results



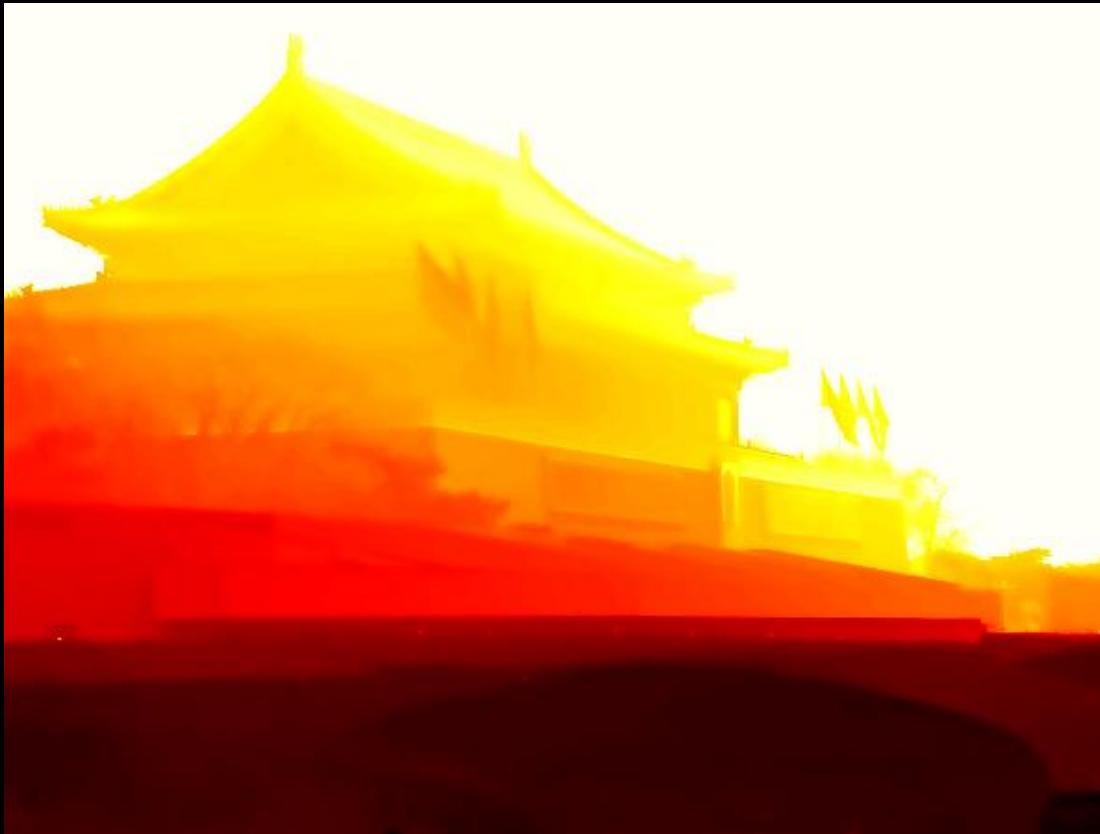
input

Results



recovered image

Results



depth

Results



input

Results



recovered image

Results



depth

Results



input

Results



recovered image

Results



depth

Comparisons



input



[Fattal Siggraph 08]

Comparisons



input



our result

Comparisons



input



[Tan, CVPR 08]

Comparisons



input



our result

Comparisons



input



[Kopf et al, Siggraph Asia 08]



our result

Results: De-focus



recovered scene radiance



input



depth

Results: De-focus



de-focus



input



depth

Results: Video

output



input



Results: Video

output



input



Limitations

- Inherently white or grayish objects



input



our result



transmission

Limitations

- Haze imaging model is invalid
 - e.g. non-constant \mathbf{A}



input



our result

Summary

- Dark channel prior
 - A natural phenomenon
 - Very simple but effective
 - Put a bad image to good use

Thank you