# Multicollinearity

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#### Outline

Why Collinearity Is a Problem

Matrix-Geometric Perspective on Multicollinearity

### Multiple Linear Regression

The coefficients of the estimates:

$$\hat{\beta} = (X^{\mathsf{T}}X)^{-1}X^{\mathsf{T}}y$$

■ The variance of the estimates:

$$Var\left[\hat{\beta}\right] = \sigma^2 (X^{\mathsf{T}}X)^{-1}$$

If that matrix isn't exactly singular, but is close to being non-invertible, the variances will become huge.

# Collinearity

There are several equivalent conditions for any square matrix, say u, to be singular or non-invertible:

- The determinant det u or |u| is 0.
- At least one eigenvalue of u is 0.
- u is rank deficient, meaning that one or more of its columns (or rows) is equal to a linear combination of the other rows.

- Dealing with Collinearity by Deleting Variables
- Diagnosing Collinearity Among Pairs of Variables
- Geometric Perspective
- ■Why Multicollinearity Is Harder

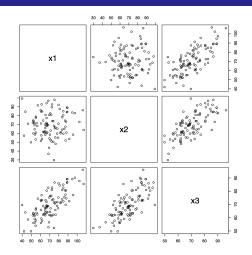


Figure: suppose  $X_1$  and  $X_2$  are independent Gaussians, of equal variance  $\sigma^2$ , and  $X_3$  is their average,  $X_3 = (X_1 + X_2)/2$ 

### Multicollinearity

Multicollinearity means that

$$c_1X_1 + c_2X_2 + \dots + c_pX_p = \sum_{i=1}^p c_iX_i = c_0$$

To simplify this, let's introduce  $p \times 1$  matrix  $a = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_p \end{bmatrix}$  ,so we can

write multicollinearity as  $a^{\mathsf{T}}X = c_0$ , for  $a \neq 0$ 

$$Var[a^{\mathsf{T}}X] = 0, \quad a \neq 0$$

$$Var[a^{\mathsf{T}}X] = Var\left[\sum_{i=1}^{p} c_{i}X_{i}\right]$$

$$= \sum_{i=1}^{p} \sum_{j=1}^{p} c_{i}c_{j}Cov[X_{i}, X_{j}]$$

$$= a^{\mathsf{T}}Var[X] a$$

■ The eigenvectors of Var [X], such that

$$Var[X] v_i = \lambda v_i$$

- The eigenvalues are all 0.
- Any vector can be re-written as a sum of eigenvectors:

$$a = \sum_{i=1}^{p} \left( a^{\mathsf{T}} v_i \right) v_i$$

- The eigenvectors can be chosen so that they all have length 1 and are orthogonal to each other.
- Var [X] can be expressed as

$$Var[X] = VDV^{\mathsf{T}}$$

$$\begin{aligned} Var[X] & = Var[X] \sum_{i=1}^{p} (a^{\mathsf{T}} v_i) v_i \\ & = \sum_{i=1}^{p} (a^{\mathsf{T}} v_i) Var[X] v_i \\ & = \sum_{i=1}^{p} (a^{\mathsf{T}} v_i) \lambda_i v_i \\ a^{\mathsf{T}} Var[X] & = \left( \sum_{i=1}^{p} (a^{\mathsf{T}} v_i) v_j \right)^{\mathsf{T}} \sum_{i=1}^{p} (a^{\mathsf{T}} v_i) \lambda_i v_i \\ & = \sum_{i=1}^{p} \sum_{j=1}^{p} (a^{\mathsf{T}} v_i) (a^{\mathsf{T}} v_i) v_j^{\mathsf{T}} v_i \\ & = \sum_{i=1}^{p} (a^{\mathsf{T}} v_i)^2 \lambda_i \end{aligned}$$

- The predictors are multi-collinear if and only if Var [X] has zero eigenvalues.
- Every multi-collinear combination of the predictors is either an eigenvector of Var [X] with zero eigenvalue, or a linear combination of such eigenvectors.