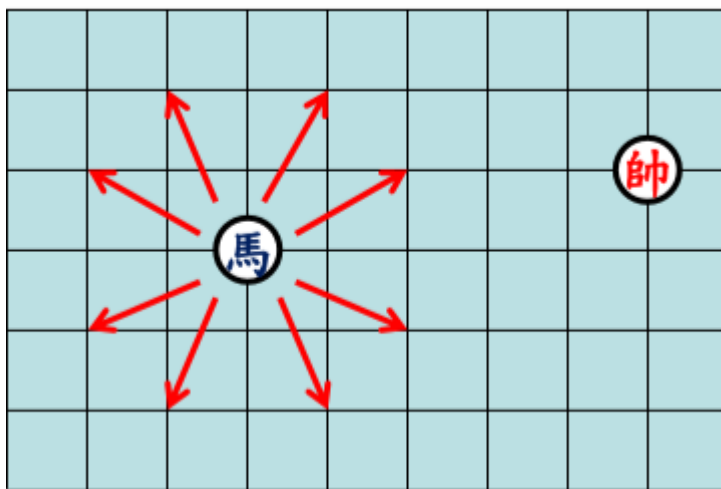


## 目標:

This programming exercise concerns the move of a "knight" in a 8x8 chessboard. A knight's moves are limited to  $(+1,+2)$  or  $(+2, +1)$  from its current position. Here you need to write a program that finds the optimal (minimum number of steps) path between two given locations on the chessboard.

其實就是象棋中馬的走法，判斷要動幾步才能到達目標地點。



馬一共有 8 個方向可以走(在不超出邊界的情況下)

## 例子:

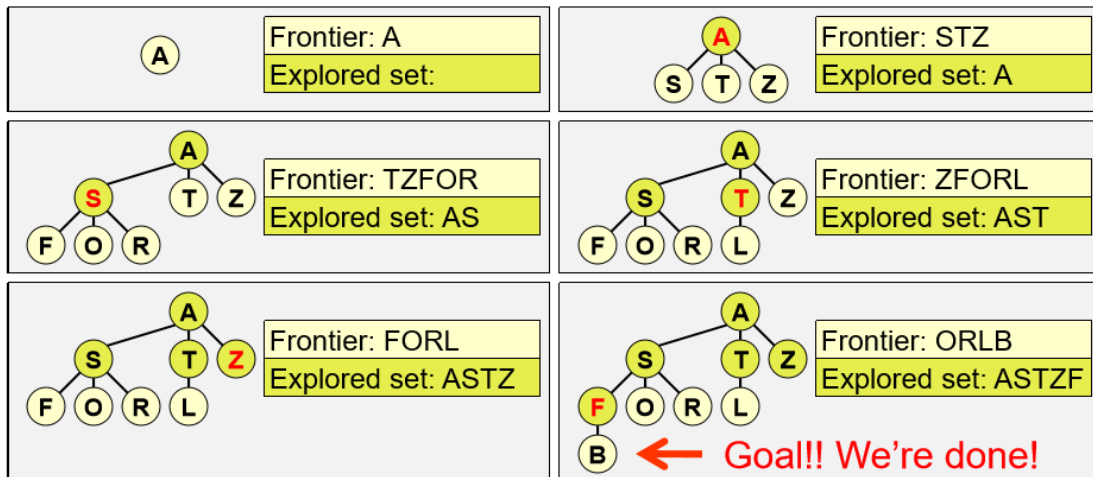
from A to B (0,0)到 (2,2) 最佳路徑 : (0,0)(2,1)(0,2)(1,0)(2,2)

使用上課學到的 BFS DFS A\* IDA\* 方法來達到效果。

# Breadth-First Search (BFS)

- Strategy: Expand shallowest unexpanded node.
- Frontier: FIFO queue
- Goal test at node generation

This example is based on graph-search of the Romania map:



概念：由淺入深 一層找完再找下一層

因為是一層一層找，所以一定會找到一個最佳解。

使用 Queue 的方式來找解，一次放一層的 queue 把 8 個方向的值做檢查，如果沒有超出棋盤範圍也沒有走到過，就 push 進 queue 裡面然後把一開始的起點 pop 掉用 while 迴圈一直找直到得到一組解為止，得到的解一定是路徑最短，但不是唯一解。可以改變 8 個方向依序的順序就可以得到不同的解。

```
Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : 1
Enter start point (form :_ _) : 0 0
Enter goal point (form :_ _) : 2 2

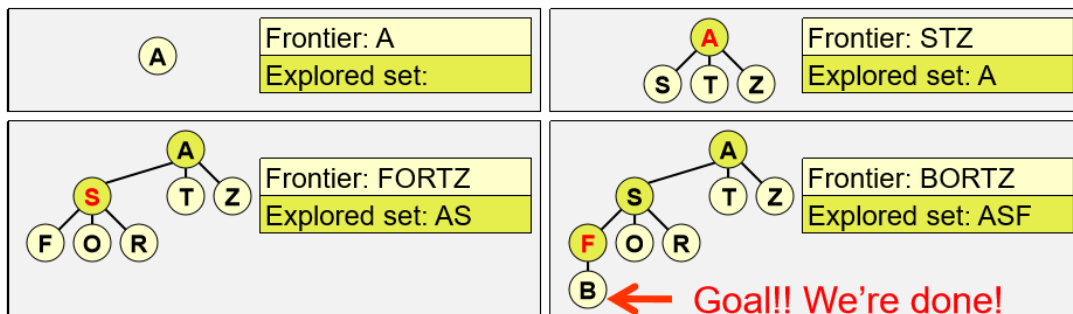
Steps:4
( 2,2 )
( 4,3 )
( 2,4 )
( 1,2 )
( 0,0 )

Process returned 0 (0x0)   execution time : 4.007 s
Press any key to continue.
```

# Depth-First Search (DFS)

- Strategy: Expand the deepest (most recent) unexpanded node.
- Frontier: FILO (stack)
- Goal test at node generation
- DFS can be implemented recursively, and therefore can be used in online search.

This example is based on graph-search of the Romania map:



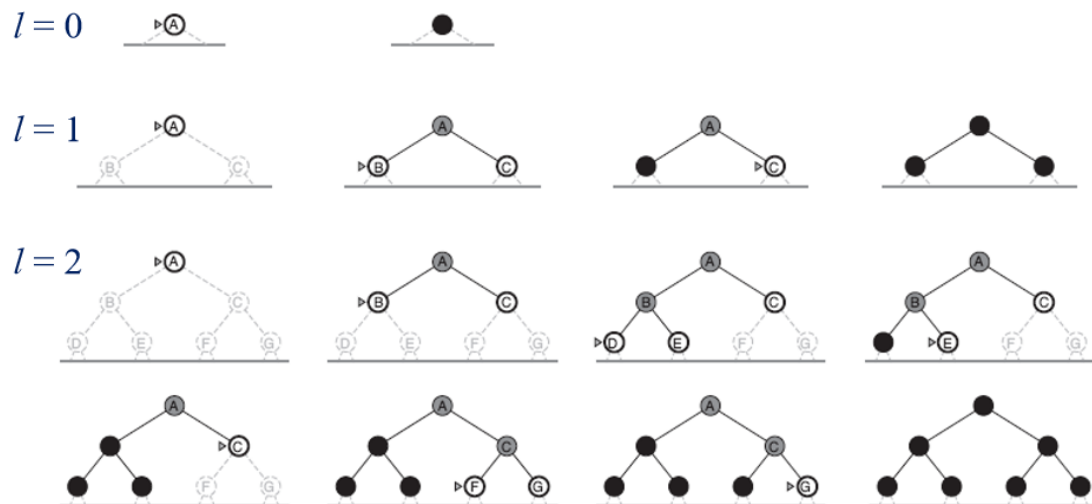
概念：一條支線找到底，沒有發現解再繼續找下一條支線。

利用 BFS 得到的觀念，但是函式是用遞迴的方式來找，這樣就可以一直跑到底，看看有沒有正確解答，如果找不到就會回到上一層在換 8 個方向中還沒試過的方向繼續找，就可以實現 DFS 先往下面找的方法。如果問題有解 DFS 找得到解，但不一定是最佳解，因為他是先往深處找，有可能其他條支線有比較淺的解答，但他不會先看。

```
Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : 2
Enter start point (form :_ _) : 0 0
Enter goal point (form :_ _) : 2 2
Steps : 52

Process returned 0 (0x0)   execution time : 4.412 s
Press any key to continue.
```

## Iterative deepening search (IDS)



概念：利用一層一層的 DFS 概念來達到 BFS 的效果，可以想成受限

制的 DFS，每搜尋完一層後，再將深度限制加大，再繼續做下去。

逐步放寬限制深度，每次重新跑，跑到限制深度還沒找到解就放寬

限制深度再重跑一次直到得解

找的方式就跟 BFS 大同小異。

```
Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : 3
Enter start point (form :_ _) : 0 0
Enter goal point (form :_ _) : 2 2

Steps:4
( 2,2 )
( 4,3 )
( 2,4 )
( 1,2 )
( 0,0 )

Process returned 0 (0x0)   execution time : 3.806 s
Press any key to continue.
```

## A\* search

A\*搜尋演算法 (A\* search algorithm) 是一種在圖形平面上，有多個節點的路徑，求出最低通過成本的演算法。常用於遊戲中的NPC的移動計算，或網路遊戲的BOT的移動計算上。

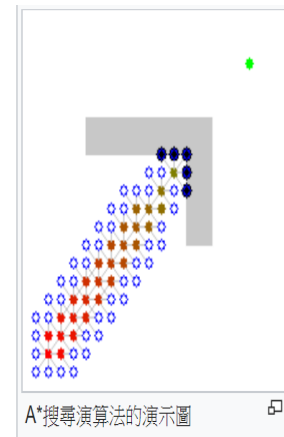
該演算法綜合了最良優先搜尋和Dijkstra演算法的優點：在進行啟發式搜尋提高演算法效率的同時，可以保證找到一條最佳路徑（基於評估函式）。

在此演算法中，如果以 $g(n)$ 表示從起點到任意頂點 $n$ 的實際距離， $h(n)$ 表示任意頂點 $n$ 到目標頂點的估算距離（根據所採用的評估函式的不同而變化），那麼A\*演算法的估算函式為：

$$f(n) = g(n) + h(n)$$

這個公式遵循以下特性：

- 如果 $g(n)$ 為0，即只計算任意頂點 $n$ 到目標的評估函式 $h(n)$ ，而不計算起點到頂點 $n$ 的距離，則演算法轉化為使用貪心策略的最良優先搜尋，速度最快，但可能得不出最佳解；
- 如果 $h(n)$ 不大於頂點 $n$ 到目標頂點的實際距離，則一定可以求出最佳解，而且 $h(n)$ 越小，需要計算的節點越多，演算法效率越低，常見的評估函式有——歐幾里得距離、曼哈頓距離、切比雪夫距離；
- 如果 $h(n)$ 為0，即只需求出起點到任意頂點 $n$ 的最短路徑 $g(n)$ ，而不計算任何評估函式 $h(n)$ ，則轉化為單源最短路徑問題，即Dijkstra演算法，此時需要計算最多的頂點；



概念：起始到目標的距離可以拆成 起始點到任一點的距離+此任一點到終點的距離。也就是  $f(n) = g(n) + h(n)$

### 可以利用這個方法來簡化問題

Heuristic function: A simple heuristic function to use is  $\text{floor}((|dx| + |dy|)/3)$ , where  $(dx, dy)$  is the vector from the current location to the goal, and  $\text{floor}(v)$  is the largest integer equal to or less than  $v$ .

利用給的 Heuristic function 下去把 8 個方向的值先求出一個值，再從小到大去執行對應的方向，再利用 BFS 方式迴圈，有點像 greedy algorithm 的方式來求解，最後不一定會得到最佳解，但會比 DFS 接近很多。

```
Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : 4
Enter start point (form :_ _) : 0 0
Enter goal point (form :_ _) : 2 2

Steps:6
( 2,2 )
( 4,3 )
( 5,5 )
( 3,6 )
( 2,4 )
( 1,2 )
( 0,0 )

Process returned 0 (0x0)   execution time : 5.250 s
Press any key to continue.
```

## Iterative deepening A\* (IDA\*)

概念：是對狀態空間的搜尋策略。它重複地執行一個有深度限制的

深度優先搜尋，每次執行結束後，它增加深度并迭代，直到找到目

標狀態。可以理解成疊加的 A\*

```
Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : 5
Enter start point (form :_ _) : 0 0
Enter goal point (form :_ _) : 2 2

Steps:4
( 2,2 )
( 4,3 )
( 2,4 )
( 1,2 )
( 0,0 )

Process returned 0 (0x0)   execution time : 3.907 s
Press any key to continue.
```

觀察：

BFS 可以準確得到最佳解，A\*是估計一個可能能求到最佳解的值再下去找，雖然不一定是最佳但也很接近了，DFS 就是一條路窮舉，如果全部展開也可以找到最佳解，但如果是先找到就停就很難找到最佳解了，如果數據很大就很沒效率。

心得：

這次的作業我學到了 queue 這個函式，也複習很多之前的工具，讓我更了解上課的內容，以及可以用來做那些運用，各個方法的優缺點。

問題：

不過我還是有點不太懂 Iterative deepening 的意義，感覺就是換一個想法做一樣的事，不過我感覺還是 BFS 最直觀也最好用

未來的想法：

感覺很多問題都可以用類似的想法，做樹狀圖用這些方法來解決問

題，我再想可不可以用 A\*來實作一個當作投資建議的參考值。

```
#include <iostream>
```

```
#include <iostream>
#include <queue>
#include <math.h>
#include <algorithm>
using namespace std;
```

//節點的結構

```
struct node {
    int cur,x,y,step;
    node *pre;
};
void BFS(int s,int s1,int g,int g1,int step){
```

    //先做一 NODE 把起始點存入

```
    node *start=new node;
    start->x=s;
    start->y=s1;
    start->step=0;
```

    //TABLE 用來檢查下一個準備要做的點有沒有走過，走過代表有

人更早就走過了，沒必要再做一次

```
    vector<node> table;
```

    //用來存還剩下要做的 NODE

```
    queue<node> memory;
    memory.push(*start);
    while(memory.front().x!=g || memory.front().y!=g1){
        int x1,y1;
        node *parent = new node;
        *parent=memory.front();
        table.push_back(memory.front());
        memory.pop();
```

```
        /*-----方向 1-----*/
```

```
node *next = new node;
next->x=parent->x+1;
next->y=parent->y+2;
next->pre=parent;
next->step=parent->step+1;
```

```
int check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
```

```
/*-----方向 2-----*/
```

```
next->x=parent->x+1;
next->y=parent->y-2;
next->pre=parent;
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
```



```

        check=1;
    }

    /*-----方向 3-----*/

    next->x=parent->x+2;
    next->y=parent->y+1;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }

    /*-----方向 4-----*/

    next->x=parent->x+2;
    next->y=parent->y-1;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
}

```

```

/*-----方向 5-----*/

next->x=parent->x-1;
next->y=parent->y+2;
next->pre=parent;
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}

/*-----方向 6-----*/

next->x=parent->x-1;
next->y=parent->y-2;
next->pre=parent;
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}

/*-----方向 7-----*/

```

```

next->x=parent->x-2;
next->y=parent->y+1;
next->pre=parent;
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}

/*-----方向 8-----*/

next->x=parent->x-2;
next->y=parent->y-1;
next->pre=parent;
check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
    check=1;
}
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}

}
node result;
result=memory.front();

```

```

        cout << endl << "Steps:" << memory.front().step << endl;
        while(result.pre){
            cout << "( " << result.x << ", " << result.y << " )" << endl;
            result = *result.pre;
        }
        cout << "( " << result.x << ", " << result.y << " )" << endl;
    }
    int ans = 0;
    vector<node> path;
    int DFS(int s, int s1, int g, int g1, int step){
        if(ans == 1){
            return 0;
        }
        node *start = new node;
        start->x = s;
        start->y = s1;
        start->step = step;

        path.push_back(*start);

        node *next = new node;
        next->x = start->x + 1;
        next->y = start->y + 2;
        next->pre = start;
        next->step = step + 1;
    }

```

//下面的 if 判斷有沒有解和超出邊界，else if 判斷是不是到了

else 進入下一層

```

    if(next->x > 8 || next->x < 0 || next->y > 8 || next->y < 0 || ans == 1){
    }
    else if(next->x == g && next->y == g1){
        ans = 1;
        cout << "Steps : " << next->step << endl;
    }
    else{

```

```

int check=0;
for(int i=0;i<path.size();i++){
    if(next->x==path[i].x && next->y==path[i].y){
        check=1;
        break;
    }
}
if(check==0){
    DFS(next->x,next->y,g,g1,next->step);
}
}

```

```

next->x=start->x+1;
next->y=start->y-2;
next->pre=start;
next->step=step+1;

```

```

if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
}
else if(next->x==g && next->y==g1){
    ans=1;
    cout << "Steps : "<<next->step <<endl;
}
else{
    int check=0;
    //cout << 2 <<endl;
    for(int i=0;i<path.size();i++){
        if(next->x==path[i].x && next->y==path[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        DFS(next->x,next->y,g,g1,next->step);
    }
}
}

```

```

next->x=start->x+2;
next->y=start->y+1;
next->pre=start;
next->step=step+1;

if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
}
else if(next->x==g && next->y==g1){
    ans=1;
    cout << "Steps : "<<next->step <<endl;
}
else{
    int check=0;
    //cout << 3 <<endl;
    for(int i=0;i<path.size();i++){
        if(next->x==path[i].x && next->y==path[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        DFS(next->x,next->y,g,g1,next->step);
    }
}

```

```

next->x=start->x+2;
next->y=start->y-1;
next->pre=start;
next->step=step+1;

if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
}
else if(next->x==g && next->y==g1){
    ans=1;
    cout << "Steps : "<<next->step <<endl;
}
else{
    int check=0;

```

```

        //cout << 4 << endl;
        for(int i=0;i<path.size();i++){
            if(next->x==path[i].x && next->y==path[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            DFS(next->x,next->y,g,g1,next->step);
        }
    }

    next->x=start->x-1;
    next->y=start->y+2;
    next->pre=start;
    next->step=step+1;

    if(next->x > 8 || next->x < 0 || next->y > 8 || next->y < 0 || ans==1){
    }
    else if(next->x==g && next->y==g1){
        ans=1;
        cout << "Steps : "<<next->step << endl;
    }
    else{
        int check=0;
        //cout << 5 << endl;
        for(int i=0;i<path.size();i++){
            if(next->x==path[i].x && next->y==path[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            DFS(next->x,next->y,g,g1,next->step);
        }
    }
}

next->x=start->x-1;

```

```
next->y=start->y-2;
next->pre=start;
next->step=step+1;
```

```
if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
}
else if(next->x==g && next->y==g1){
    ans=1;
    cout << "Steps : "<<next->step <<endl;
}
else{
    int check=0;
    //cout << 6 <<endl;
    for(int i=0;i<path.size();i++){
        if(next->x==path[i].x && next->y==path[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        DFS(next->x,next->y,g,g1,next->step);
    }
}
```

```
next->x=start->x-2;
next->y=start->y+1;
next->pre=start;
next->step=step+1;
```

```
if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
}
else if(next->x==g && next->y==g1){
    ans=1;
    cout << "Steps : "<<next->step <<endl;
}
else{
    int check=0;
    //cout << 7 <<endl;
```



```

        for(int i=0;i<path.size();i++){
            if(next->x==path[i].x && next->y==path[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            DFS(next->x,next->y,g,g1,next->step);
        }
    }

    next->x=start->x-2;
    next->y=start->y-2;
    next->pre=start;
    next->step=step+1;

    if(next->x >8 || next->x<0 || next->y >8 || next->y <0 || ans==1){
    }
    else if(next->x==g && next->y==g1){
        ans=1;
        cout << "Steps : "<<next->step <<endl;
    }
    else{
        int check=0;
        //cout << 8 <<endl;
        for(int i=0;i<path.size();i++){
            if(next->x==path[i].x && next->y==path[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            DFS(next->x,next->y,g,g1,next->step);
        }
    }
    return 0;
}

```

```

int IDS_ans=0;
vector<node> IDS_path;
int IDS(int s,int s1,int g,int g1,int step,int level){
    node *start=new node;
    start->x=s;
    start->y=s1;
    start->step=0;

    vector<node> table;

    queue<node> memory;
    memory.push(*start);
    while(memory.front().x!=g || memory.front().y!=g1){
        int x1,y1;
        node *parent = new node;
        *parent=memory.front();
        table.push_back(memory.front());
        memory.pop();
        node *next = new node;
        next->x=parent->x+1;
        next->y=parent->y+2;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
            check=1;
        }
        if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0){

```

```

        memory.push(*next);
    }
    next->x=parent->x+1;
    next->y=parent->y-2;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x+2;
    next->y=parent->y+1;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x+2;
    next->y=parent->y-1;
    next->pre=parent;
    for(int i=0;i<table.size();i++){

```

```

        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x-1;
    next->y=parent->y+2;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x-1;
    next->y=parent->y-2;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){

```

```

        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x-2;
    next->y=parent->y+1;
    next->pre=parent;
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    next->x=parent->x-2;
    next->y=parent->y-1;
    next->pre=parent;
    check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y <0){
        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }

```

```

    }
    node result;
    result=memory.front();
    cout <<endl<<"Steps:"<< memory.front().step << endl;
    while(result.pre){
        cout << "( " << result.x << ", " << result.y<<" )" <<endl;
        result=*result.pre;
    }
    cout << "( " << result.x << ", " << result.y<<" )" <<endl;

}

```

```

int A(int s,int s1,int g,int g1,int step){
    node *start=new node;
    start->x=s;
    start->y=s1;
    start->step=0;

    vector<node> table;

    queue<node> memory;
    memory.push(*start);
    while(memory.front().x!=g || memory.front().y!=g1){
        node *parent = new node;
        *parent=memory.front();
        table.push_back(memory.front());
        memory.pop();

        int x1[8],y1[8];
        float heuristic_number[8];
        x1[0]=memory.front().x+1;
        x1[1]=memory.front().x+1;
        x1[2]=memory.front().x+2;
        x1[3]=memory.front().x+2;
        x1[4]=memory.front().x-1;
        x1[5]=memory.front().x-1;
        x1[6]=memory.front().x-2;
    }
}

```

```

x1[7]=memory.front().x-2;
y1[0]=memory.front().y+2;
y1[1]=memory.front().y-2;
y1[2]=memory.front().y+1;
y1[3]=memory.front().y-1;
y1[4]=memory.front().y+2;
y1[5]=memory.front().y-2;
y1[6]=memory.front().y+1;
y1[7]=memory.front().y-1;
for(int i=0;i<8;i++){
    heuristic_number[i]=(abs(g-x1[i])+abs(g1-y1[i]))/3;
}
sort(heuristic_number,heuristic_number+8);
node *next = new node;
for(int i=0;i<8;i++){
    if((abs(g-x1[0])+abs(g1-y1[0]))/3==heuristic_number[i]){
        next->x=parent->x+1;
        next->y=parent->y+2;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            memory.push(*next);
        }
    }
    else if((abs(g-x1[1])+abs(g1-
y1[1]))/3==heuristic_number[i]){

```

```

next->x=parent->x+1;
next->y=parent->y-2;
next->pre=parent;
next->step=parent->step+1;

int check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

    check=1;
}
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
}
else if((abs(g-x1[2])+abs(g1-
y1[2]))/3==heuristic_number[i]){
    next->x=parent->x+2;
    next->y=parent->y+1;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
}

```



```

        if(check==0){
            memory.push(*next);
        }
    }
    else if((abs(g-x1[3])+abs(g1-
y1[3]))/3==heuristic_number[i]){
        next->x=parent->x+2;
        next->y=parent->y-1;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            memory.push(*next);
        }
    }
    else if((abs(g-x1[4])+abs(g1-
y1[4]))/3==heuristic_number[i]){
        next->x=parent->x-1;
        next->y=parent->y+2;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
    }

```

```

        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            memory.push(*next);
        }
    }
    else if((abs(g-x1[5])+abs(g1-
y1[5]))/3==heuristic_number[i]){
        next->x=parent->x-1;
        next->y=parent->y-2;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0){
            memory.push(*next);
        }
    }
    else if((abs(g-x1[6])+abs(g1-
y1[6]))/3==heuristic_number[i]){
        next->x=parent->x-2;
        next->y=parent->y+1;
        next->pre=parent;
        next->step=parent->step+1;

```

```

int check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

    check=1;
}
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0){
    memory.push(*next);
}
}
else if((abs(g-x1[7])+abs(g1-
y1[7]))/3==heuristic_number[i]){
    next->x=parent->x-2;
    next->y=parent->y-1;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0){
        memory.push(*next);
    }
}
}

```

```

    }
}
node result;
result=memory.front();
cout <<endl<<"Steps:"<< memory.front().step << endl;
while(result.pre){
    cout << "( " << result.x << ", " << result.y<<" )" <<endl;
    result=*result.pre;
}
cout << "( " << result.x << ", " << result.y<<" )" <<endl;
}

```

```

int solution=0;
int IDA(int s,int s1,int g,int g1,int step,int level){
    node *start=new node;
    start->x=s;
    start->y=s1;
    start->step=0;
    cout << "level : " <<level <<endl;
    vector<node> table;
    cout << "times" <<endl;
    queue<node> memory;
    memory.push(*start);
    while(memory.front().x!=g || memory.front().y!=g1){
        if(memory.front().step>level){
            memory.pop();
        }
        node *parent = new node;
        *parent=memory.front();
        table.push_back(memory.front());
        memory.pop();
        cout << "run" <<endl;
        int increase=0;
        int x1[8],y1[8];
        float heuristic_number[8];
        x1[0]=memory.front().x+1;
        x1[1]=memory.front().x+1;
        x1[2]=memory.front().x+2;

```

```

x1[3]=memory.front().x+2;
x1[4]=memory.front().x-1;
x1[5]=memory.front().x-1;
x1[6]=memory.front().x-2;
x1[7]=memory.front().x-2;
y1[0]=memory.front().y+2;
y1[1]=memory.front().y-2;
y1[2]=memory.front().y+1;
y1[3]=memory.front().y-1;
y1[4]=memory.front().y+2;
y1[5]=memory.front().y-2;
y1[6]=memory.front().y+1;
y1[7]=memory.front().y-1;
for(int i=0;i<8;i++){
    heuristic_number[i]=(abs(g-x1[i])+abs(g1-y1[i]))/3;
}
sort(heuristic_number,heuristic_number+8);
node *next = new node;
for(int i=0;i<8;i++){
    if((abs(g-x1[0])+abs(g1-y1[0]))/3==heuristic_number[i]){
        next->x=parent->x+1;
        next->y=parent->y+2;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0&&next->step<=level){
            memory.push(*next);

```

```

        increase++;
    }
}
else if((abs(g-x1[1])+abs(g1-
y1[1]))/3==heuristic_number[i]){
    next->x=parent->x+1;
    next->y=parent->y-2;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0&&next->step<=level){
        memory.push(*next);
        increase++;
    }
}
else if((abs(g-x1[2])+abs(g1-
y1[2]))/3==heuristic_number[i]){
    next->x=parent->x+2;
    next->y=parent->y+1;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }

```

```

        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0&&next->step<=level){
            increase++;
            memory.push(*next);
        }
    }
    else if((abs(g-x1[3])+abs(g1-
y1[3]))/3==heuristic_number[i]){
        next->x=parent->x+2;
        next->y=parent->y-1;
        next->pre=parent;
        next->step=parent->step+1;

        int check=0;
        if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

            check=1;
        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0&&next->step<=level){
            increase++;
            memory.push(*next);
        }
    }
    else if((abs(g-x1[4])+abs(g1-
y1[4]))/3==heuristic_number[i]){
        next->x=parent->x-1;
        next->y=parent->y+2;

```

```

next->pre=parent;
next->step=parent->step+1;

int check=0;
if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

    check=1;
}
for(int i=0;i<table.size();i++){
    if(next->x==table[i].x && next->y==table[i].y){
        check=1;
        break;
    }
}
if(check==0&&next->step<=level){
    increase++;
    memory.push(*next);
}
}
else if((abs(g-x1[5])+abs(g1-
y1[5]))/3==heuristic_number[i]){
    next->x=parent->x-1;
    next->y=parent->y-2;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0&&next->step<=level){

```



```

        increase++;
        memory.push(*next);
    }
}
else if((abs(g-x1[6])+abs(g1-
y1[6]))/3==heuristic_number[i]){
    next->x=parent->x-2;
    next->y=parent->y+1;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;
    }
    for(int i=0;i<table.size();i++){
        if(next->x==table[i].x && next->y==table[i].y){
            check=1;
            break;
        }
    }
    if(check==0&&next->step<=level){
        increase++;
        memory.push(*next);
    }
}
else if((abs(g-x1[7])+abs(g1-
y1[7]))/3==heuristic_number[i]){
    next->x=parent->x-2;
    next->y=parent->y-1;
    next->pre=parent;
    next->step=parent->step+1;

    int check=0;
    if(next->x >8 || next->x<0 || next->y >8 || next->y
<0){

        check=1;

```

```

        }
        for(int i=0;i<table.size();i++){
            if(next->x==table[i].x && next->y==table[i].y){
                check=1;
                break;
            }
        }
        if(check==0&&next->step<=level){
            increase++;
            memory.push(*next);
        }
    }

    }
    if(increase==0){
        cout<<"break"<<endl;
        break;
    }
}

if(memory.front().x==g && memory.front().y==g1){
    node result;
    result=memory.front();
    cout <<endl<<"Steps:"<< memory.front().step << endl;
    while(result.pre){
        cout << "( " << result.x << ", " << result.y<<" )" <<endl;
        result=*result.pre;
    }
    solution=1;
    cout << "( " << result.x << ", " << result.y<<" )" <<endl;
}
else{
    return 0;
}
}

int main(){
    int type;
    cout << "Enter algorithm (1.BFS 2.DFS 3.IDS 4.A* 5.IDA*) : ";
    cin >> type;

```

```

int start[2],goal[2];
cout << "Enter start point (form :_ _) : ";
cin >> start[0] >> start[1];
cout << "Enter goal point (form :_ _) : ";
cin >> goal[0] >> goal[1];
//cout <<start[0] << start[1] << goal[0] << goal[1];
int i=0;
switch(type){
    case 1:
        BFS(start[0],start[1],goal[0],goal[1],0);
        break;
    case 2:
        DFS(start[0],start[1],goal[0],goal[1],0);
        break;
    case 3:
        IDS(start[0],start[1],goal[0],goal[1],0,0);
        break;
    case 4:
        A(start[0],start[1],goal[0],goal[1],0);
        break;
    case 5:
        IDA(start[0],start[1],goal[0],goal[1],0,0);
        while(solution==0){
            i++;
            IDA(start[0],start[1],goal[0],goal[1],0,i);
        }
        break;
    default:
        break;
}
return 0;
}

```