AVL Trees

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Abstract

This is a verified implementation of AVL trees in Agda, taking ideas primarily from Conor McBride's paper "How to Keep Your Neighbours in Order" [2] and the Agda standard library [1].

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1 Introduction

First, some imports.

```
{-# OPTIONS --without-K #-}

open import Relation.Binary
open import Relation.Binary.PropositionalEquality
open import Level using (Lift; lift; _□_; lower)
open import Data.Nat as N using (N; suc; zero; pred)
open import Data.Product
open import Data.Unit
open import Data.Maybe
open import Function
open import Data.Bool
open import Data.Empty
```

Next, we declare a module: the entirety of the following code is parameterized over the key type, and a strict total order on that key.

2 Bounded

The basic idea of the verified implementation is to store in each leaf a proof that the upper and lower bounds of the trees to its left and right are ordered appropriately.

Accordingly, the tree type itself will have to have the upper and lower bounds in its indices. But what are the upper and lower bounds of a tree with no neighbours? To describe this case, we add lower and upper bounds to our key type.

```
module Bounded where infix 5 [_]

data [•]: Set k where [][]: [•]
[_]: (k: Key) \rightarrow [\bullet]
```

This type itself admits an ordering relation.

```
infix 4 _{[<]}_{\_}
[<] : [\bullet] \rightarrow [\bullet] \rightarrow \operatorname{Set} r
```

Finally, we can describe a value as being "in bounds" like so.

```
infix 4 _<_<_
<_< <_: [\bullet] \rightarrow Key \rightarrow [\bullet] \rightarrow Set \ r
l < x < u = l [<] [x] \times [x] [<] u
```

3 Balance

To describe the balance of the tree, we use the following type:

The tree can be either left- or right-heavy (by one), or even. The indices of the type are phrased as a proof:

$$max(x,y) = z (1)$$

The height of a tree is the maximum height of its two subtrees, plus one. Storing a proof of the maximum in this way will prove useful later.

We will also need some combinators for balance:

```
\begin{array}{l} \div: \ \forall \ \{x\ y\ z\} \to \langle \ x \sqcup y \ \rangle \equiv z \to \langle \ z \sqcup x \ \rangle \equiv z \\ \div \ \swarrow = \div \\ \div \ \div = \div \\ \div \ \searrow = \checkmark \\ \\ \div: \ \forall \ \{x\ y\ z\} \to \langle \ x \sqcup y \ \rangle \equiv z \to \langle \ y \sqcup z \ \rangle \equiv z \\ \div \ \swarrow = \times \\ \div \ \swarrow = \div \\ \div \ \swarrow = \div \\ \div \ \searrow = \div \end{array}
```

4 The Tree Type

The type itself is indexed by the lower and upper bounds, some value to store with the keys, and a height. In using the balance type defined earlier, we ensure that the children of a node cannot differ in height by more than 1. The bounds proofs also ensure that the tree must be ordered correctly.

```
data Tree \{v\}
(V: Key \rightarrow \mathsf{Set}\ v)
(l\ u: [\bullet]): \mathbb{N} \rightarrow
\mathsf{Set}\ (k \sqcup v \sqcup r) \ \mathsf{where}
\mathsf{leaf}\ : (l < u: l [<]\ u) \rightarrow \mathsf{Tree}\ V\ l\ u\ 0
\mathsf{node}: \ \forall\ \{h\ lh\ rh\}
(k: Key)
(v: V\ k)
(bl: \langle\ lh\ \sqcup\ rh\ \rangle \equiv h)
(lk: \mathsf{Tree}\ V\ l\ [\ k\ ]\ lh)
(ku: \mathsf{Tree}\ V\ l\ k\ ]\ u\ rh) \rightarrow
\mathsf{Tree}\ V\ l\ u\ (\mathsf{suc}\ h)
```

5 Rotations

AVL trees are rebalanced by rotations: if, after an insert or deletion, the balance invariant has been violated, one of these rotations is performed as correction.

Before we implement the rotations, we need a type to describe a tree whose height may have changed:

5.1 Right Rotation

When the left subtree becomes too heavy, we rotate the tree to the right.

```
 \begin{aligned} \operatorname{rot}^r &: \forall \; \{\mathit{lb} \; \mathit{ub} \; \mathit{rh} \; v\} \; \{\mathit{V} : \mathit{Key} \to \mathsf{Set} \; v\} \\ &\to (\mathit{k} : \; \mathit{Key}) \\ &\to \mathit{V} \; \mathit{k} \\ &\to \mathsf{Tree} \; \mathit{V} \; \mathit{lb} \; [\; \mathit{k} \; ] \; (\mathsf{suc} \; (\mathsf{suc} \; \mathit{rh})) \\ &\to \mathsf{Tree} \; \mathit{V} \; [\; \mathit{k} \; ] \; \mathit{ub} \; \mathit{rh} \\ &\to \mathsf{Inserted} \; \mathit{V} \; \mathit{lb} \; \mathit{ub} \; (\mathsf{suc} \; (\mathsf{suc} \; \mathit{rh})) \end{aligned}
```

This rotation comes in two varieties: single and double. Single rotation can be seen in figure 1.

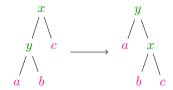


Figure 1: Single right-rotation

And double rotation in figure 2.

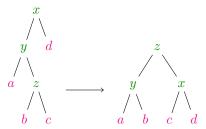


Figure 2: Double right-rotation

```
 \begin{array}{l} \operatorname{rot}^r \; x \; xv \; (\operatorname{node} \; y \; yv \; \smallsetminus \; a \; (\operatorname{node} \; z \; zv \; bl \; b \; c)) \; \; d = \\ 0 + \; (\operatorname{node} \; z \; zv \; \vdash \; (\operatorname{node} \; y \; yv \; (\  \, \vdash \; bl) \; a \; b) \; (\operatorname{node} \; x \; xv \; (\  \, \vdash \; bl) \; c \; d)) \end{array}
```

5.2 Left Rotation

Left-rotation is essentially the inverse of right.

```
 \begin{array}{l} \operatorname{rot}^l : \ \forall \ \{\mathit{lb} \ \mathit{ub} \ \mathit{lh} \ \mathit{v}\} \ \{\mathit{V} : \mathit{Key} \to \mathsf{Set} \ \mathit{v}\} \\ & \to (\mathit{k} : \ \mathit{Key}) \\ & \to \mathit{V} \ \mathit{k} \\ & \to \mathsf{Tree} \ \mathit{V} \ \mathit{lb} \ [\ \mathit{k}\ ] \ \mathit{lh} \\ & \to \mathsf{Tree} \ \mathit{V} \ [\ \mathit{k}\ ] \ \mathit{ub} \ (\mathsf{suc} \ (\mathsf{suc} \ \mathit{lh})) \\ & \to \mathsf{Inserted} \ \mathit{V} \ \mathit{lb} \ \mathit{ub} \ (\mathsf{suc} \ (\mathsf{suc} \ \mathit{lh})) \end{array}
```

Single (seen in figure 3).

```
        \text{rot}^l \ x \ xv \ c \ (\text{node} \ y \ yv \times b \ a) = \\
        0 + \ (\text{node} \ y \ yv + \ (\text{node} \ x \ xv + c \ b) \ a)
```

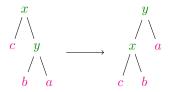


Figure 3: Single left-rotation

```
        \text{rot}^l \ x \ xv \ c \ (\text{node} \ y \ yv - b \ a) = \\
        1 + \ (\text{node} \ y \ yv \ \rightthreetimes \ (\text{node} \ x \ xv \ \smallsetminus \ c \ b) \ a)
```

and double (figure 4):

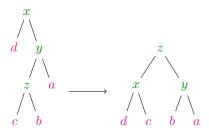


Figure 4: Double left-rotation

```
 \begin{array}{l} \operatorname{rot}^l \; x \; xv \; d \; (\operatorname{node} \; y \; yv \; \times \; (\operatorname{node} \; z \; zv \; bl \; c \; b) \; a) = \\ 0 + \; (\operatorname{node} \; z \; zv \; + \; (\operatorname{node} \; x \; xv \; ( \dots \; bl) \; d \; c) \; (\operatorname{node} \; y \; yv \; ( \dots \; bl) \; b \; a)) \end{array}
```

6 Insertion

After the rotations, insertion is relatively easy. We allow the caller to supply a combining function.

```
insert : \forall \{l \ u \ h \ v\} \ \{V : Key \rightarrow \mathsf{Set} \ v\} \ (k : Key)
\rightarrow V \ k
\rightarrow (V \ k \rightarrow V \ k \rightarrow V \ k)
\rightarrow \mathsf{Tree} \ V \ l \ u \ h
\rightarrow l < k < u
\rightarrow \mathsf{Inserted} \ V \ l \ u \ h
insert v \ vc \ f \ (\mathsf{leaf} \ l < u) \ (l \ , \ u) = 1 + \ (\mathsf{node} \ v \ vc \ \neg \ (\mathsf{leaf} \ l) \ (\mathsf{leaf} \ u))
insert v \ vc \ f \ (\mathsf{node} \ k \ kc \ bl \ tl \ tr) \ prf \ \mathsf{with} \ \mathsf{compare} \ v \ k
insert v \ vc \ f \ (\mathsf{node} \ k \ kc \ bl \ tl \ tr) \ (l \ , \ )
\mid \mathsf{tri} < a \ \_ \ \mathsf{with} \ \mathsf{insert} \ v \ vc \ f \ tl \ (l \ , \ a)
\dots \ \mid 0 + tl \ = 0 + \ (\mathsf{node} \ k \ kc \ bl \ tl \ tr)
\dots \ \mid 1 + tl \ \mathsf{with} \ bl
\dots \ \mid x \ = \mathsf{rot}^r \ k \ kc \ tl \ tr
```

```
 \begin{array}{l} \ldots \mid \neg = 1 + \text{ (node } k \, kc \, \times \, tl' \, tr) \\ \ldots \mid \times = 0 + \text{ (node } k \, kc \, - \, tl' \, tr) \\ \text{insert } v \, vc \, f \, (\text{node } k \, kc \, bl \, tl \, tr) \\ \mid \text{tri} \approx \_ \, \text{refl} \, \_ = 0 + \, (\text{node } k \, (f \, vc \, kc) \, bl \, tl \, tr) \\ \text{insert } v \, vc \, f \, (\text{node } k \, kc \, bl \, tl \, tr) \, (\_ \, , \, u) \\ \mid \text{tri} > \_ \, \_ \, c \, \text{with insert } v \, vc \, f \, tr \, (c \, , \, u) \\ \ldots \mid 0 + \, tr' = 0 + \, (\text{node } k \, kc \, bl \, tl \, tr') \\ \ldots \mid 1 + \, tr' \, \text{with } \, bl \\ \ldots \mid \times = 0 + \, (\text{node } k \, kc \, - \, tl \, tr') \\ \ldots \mid \neg = 1 + \, (\text{node } k \, kc \, \times \, tl \, tr') \\ \ldots \mid \times = \operatorname{rot}^l \, k \, kc \, tl \, tr' \\ \end{array}
```

7 Lookup

Lookup is also very simple. No invariants are needed here.

```
\begin{array}{c} \mathsf{lookup} : (k:\mathit{Key}) \\ \to \forall \; \{l\; u\; s\; v\} \; \{V:\mathit{Key} \to \mathsf{Set}\; v\} \\ \to \mathsf{Tree}\; V\; l\; u\; s \\ \to \mathsf{Maybe}\; (V\; k) \\ \mathsf{lookup}\; k\; (\mathsf{leaf}\; l{<}u) = \mathsf{nothing} \\ \mathsf{lookup}\; k\; (\mathsf{node}\; v\; vc \; \_\; tl\; tr) \; \mathsf{with}\; \mathsf{compare}\; k\; v \\ \dots \; |\; \mathsf{tri}{<}\; \_\; \_ = \mathsf{lookup}\; k\; tl \\ \dots \; |\; \mathsf{tri}{\approx}\; \_\; \mathsf{refl}\; \_ = \mathsf{just}\; vc \\ \dots \; |\; \mathsf{tri}{>}\; \_\; \_ = \mathsf{lookup}\; k\; tr \\ \end{array}
```

8 Deletion

Deletion is by far the most complex operation out of the three provided here. For deletion from a normal BST, you go to the node where the desired value is, perform an "uncons" operation on the right subtree, and use that to rebuild and rebalance the tree.

8.1 Uncons

First then, we need to define "uncons". We'll use a custom type as the return type from our uncons function, which stores the minimum element from the tree, and the rest of the tree:

```
data Deleted \{v\} (V: Key \rightarrow \mathsf{Set}\ v) (lb\ ub: [ullet]): \mathbb{N} \rightarrow \mathsf{Set}\ (k \sqcup v \sqcup r) where \_{-0}: \forall\ \{n\} \rightarrow \mathsf{Tree}\ V\ lb\ ub\ n \rightarrow \mathsf{Deleted}\ V\ lb\ ub\ n = \_{-1}: \forall\ \{n\} \rightarrow \mathsf{Tree}\ V\ lb\ ub\ n \rightarrow \mathsf{Deleted}\ V\ lb\ ub\ (\mathsf{suc}\ n) deleted : \forall\ \{v\ lb\ ub\ n\}\ \{V: Key \rightarrow \mathsf{Set}\ v\} \rightarrow \mathsf{Inserted}\ V\ lb\ ub\ n \rightarrow \mathsf{Deleted}\ V\ lb\ ub\ (\mathsf{suc}\ n) deleted (0+snd)=snd-1 deleted (1+snd)=snd-0 deleted (\mathsf{Fin.suc}\ (\mathsf{
```

```
record Cons \{v\} (V: Key \rightarrow \mathsf{Set}\ v) (lb\ ub: [ullet]) (h: \mathbb{N}): \mathsf{Set}\ (k \sqcup v \sqcup r) where constructor cons field head: Key val: V \mapsto \mathsf{Nead} V \mapsto \mathsf{Nead}
```

You'll notice it also stores a proof that the extracted element preserves the lower bound.

The uncons function itself is written in a continuation-passing style.

```
uncons : \forall \{lb \ ub \ h \ lh \ rh \ v\} \{V : Key \rightarrow \mathsf{Set} \ v\}
             \rightarrow (k: Key)
             \rightarrow V k
             \to \left\langle \ lh \mathrel{\sqcup} rh \right. \big\rangle \! \equiv h
             \rightarrow Tree V lb [k] lh
             \rightarrow Tree V [k] ub rh
             \rightarrow Cons V lb ub (h)
uncons k \ v \ bl \ tl \ tr = go \ k \ v \ bl \ tl \ tr id
   where
   go: \forall \{lb \ ub \ h \ lh \ rh \ v \ ub' \ h'\} \{V : Key \rightarrow \mathsf{Set} \ v\}
         \rightarrow (k: Key)
         \rightarrow V k
         \rightarrow \langle lh \sqcup rh \rangle \equiv h
         \rightarrow Tree V lb [k] lh
         \rightarrow Tree V[k] ub rh
         \rightarrow (\forall \{lb'\} \rightarrow
                    Inserted V [lb'] ub (h) \rightarrow
                    Inserted V [lb'] ub'(h')
         \rightarrow Cons V lb ub' (h')
   go k \ v - (\text{leaf } l < u) \ tr \ c = \text{cons } k \ v \ l < u \ (c \ (0+tr))
   go k \ v - (\text{node } k_l \ v_l \ bl_l \ tl_l \ tr_l) \ tr \ c = \text{go } k_l \ v_l \ bl_l \ tl_l \ tr_l
      \lambda \{ (0+tl') \rightarrow c (1+ \text{ node } k \ v \times tl' \ tr) \}
          ; (1+tl') \rightarrow c (1+ \text{ node } k \ v - tl' \ tr) \}
   go k v \searrow (leaf l < u) tr c = cons <math>k v l < u (c (0 + tr))
   go k \ v \times (\text{node } k_l \ v_l \ bl_l \ tl_l \ tr_l) \ tr \ c = \text{go} \ k_l \ v_l \ bl_l \ tl_l \ tr_l
      \lambda \{ (0+tl') \rightarrow c (rot^l \ k \ v \ tl' \ tr) \}
         (1+tl') \rightarrow c (1+ \text{node } k \ v \times tl' \ tr) 
   go k \ v \times (\text{node } k_l \ v_l \ bl_l \ tl_l \ tr_l) \ tr \ c = \text{go} \ k_l \ v_l \ bl_l \ tl_l \ tr_l
      \lambda \{ (0+tl') \rightarrow c (0+ \text{ node } k \ v + tl' \ tr) \}
          ; (1+tt') \rightarrow c (1+ \text{ node } k \ v \times tt' \ tr)
```

8.2 Widening

To join the two subtrees together after a deletion operation, we need to weaken (or ext) the bounds of the left tree. This is an $\mathcal{O}(\log n)$ operation. For the exting, we'll need some properties on orderings:

Finally, the ext function itself simply walks down the right branch of the tree until it hits a leaf.

```
ext : \forall {lb\ ub\ ub'\ h\ v} {V: Key \rightarrow \mathsf{Set}\ v}
\to ub\ [<]\ ub'
\to \mathsf{Tree}\ V\ lb\ ub\ h
\to \mathsf{Tree}\ V\ lb\ ub'\ h
ext {lb} ub < ub'\ (\mathsf{leaf}\ l < u) = \mathsf{leaf}\ ([<]\mathsf{-trans}\ lb\ l < u\ ub < ub')
ext ub < ub'\ (\mathsf{node}\ k\ v\ bl\ tl\ tr) = \mathsf{node}\ k\ v\ bl\ tl\ (\mathsf{ext}\ ub < ub'\ tr)
```

8.3 Full Deletion

The deletion function is by no means simple, but it does maintain the correct complexity bounds.

```
\begin{split} & \text{join}: \ \forall \ \{lb \ ub \ lh \ rh \ h \ v \ k\} \ \{V \colon Key \to \mathsf{Set} \ v\} \\ & \to \mathsf{Tree} \ V \ [k \ ] \ ub \ rh \\ & \to \langle \ lh \sqcup rh \ \rangle \equiv h \\ & \to \mathsf{Tree} \ V \ lb \ [k \ ] \ lh \\ & \to \mathsf{Deleted} \ V \ lb \ ub \ (\mathsf{suc} \ h) \\ & \text{join} \ (\mathsf{leaf} \ k < ub) \ \not\sim \ tl = \mathsf{ext} \ k < ub \ tl - 1 \\ & \text{join} \ \{lb\} \ (\mathsf{leaf} \ k < ub) \ - \ (\mathsf{leaf} \ lb < k) = \mathsf{leaf} \ ([<]\mathsf{-trans} \ lb \ lb < k \ k < ub) \ - 1 \\ & \text{join} \ (\mathsf{node} \ k_r \ v_r \ b_r \ tl_r \ tr_r) \ b \ tl \ \mathsf{with} \ \mathsf{uncons} \ k_r \ v_r \ b_r \ tl_r \ tr_r \\ & \dots \ | \ \mathsf{cons} \ k' \ v' \ l < u \ (1+tr') = \mathsf{node} \ k' \ v' \ b \ (\mathsf{ext} \ l < u \ tl) \ tr' \ - 0 \\ & \dots \ | \ \checkmark \ = \mathsf{deleted} \ (\mathsf{rot}^r \ k' \ v' \ (\mathsf{ext} \ l < u \ tl) \ tr') \\ & \dots \ | \ \div \ = \mathsf{node} \ k' \ v' \ \checkmark \ (\mathsf{ext} \ l < u \ tl) \ tr' \ - 0 \\ \end{split}
```

```
... | \rangle = \text{node } k' \ v' + (\text{ext } l < u \ tl) \ tr' -1
delete : \forall \{lb \ ub \ h \ v\} \{V : Key \rightarrow \mathsf{Set} \ v\}
           \rightarrow (k : Key)
           \rightarrow Tree V lb ub h
           \rightarrow Deleted V lb ub h
\mathsf{delete}\ x\ (\mathsf{leaf}\ l{<}u) = \mathsf{leaf}\ l{<}u\ {-}0
delete x (node y yv b l r) with compare x y
delete x (node x yv b l r) | tri\approx \neg a refl \neg c = \text{join } r b l
delete x (node y \ yv \ b \ l \ r) | tri< a \ \neg b \ \neg c with delete x \ l
... \mid l' - 0 = \text{node } y \ yv \ b \ l' \ r - 0
... \mid l' - 1 \text{ with } b
... | \times | = \text{node } y \ yv + l' \ r - 1
... | \cdot - = \text{node } y \ yv \times l' \ r - 0
... | \times | = \text{deleted (rot}^l \ y \ yv \ l' \ r)
delete x (node y \ yv \ b \ l \ r) | tri> \neg a \ \neg b \ c \ with delete \ x \ r
... | r' - 0 = \text{node } y \ yv \ b \ l \ r' - 0
\dots \mid r' - 1 \text{ with } b
... | \times = \text{deleted } (\text{rot}^r \ y \ yv \ l \ r')
... | \cdot = \text{node } y \ yv \times l \ r' - 0
... | \rangle = \text{node } y \ yv + l \ r' - 1
```

9 Alteration

```
-- alter : \forall {lb ub h v} {V : Key \rightarrow Set v}
-- \rightarrow (k : Key)
-- → (Maybe (V k) → Maybe (V k))
-- → Tree V lb ub h
-- \rightarrow 1b < k < ub
-- \rightarrow Altered V lb ub h
-- alter x f (leaf 1<u) (1 , u) with f nothing
-- alter x f (leaf l<u) (l , u) | just yv = \uparrow (node x yv - (leaf l) (leaf u))
-- alter x f (leaf l<u) (l , u) | nothing = \langle leaf l<u \rangle
-- alter x f (node y yv bl tl tr) (l , u) with compare x y
-- alter x f (node .x xv bl tl tr) (1 , u) | tri≈ ¬a refl ¬c with f (just xv)
-- alter x f (node .x xv bl tl tr) (l , u) | tri≈ ¬a refl ¬c | just yv = ⟨ node x yv bl tl
-- alter x f (node .x xv bl tl tr) (1 , u) | tri≈ ¬a refl ¬c | nothing = fromDeleted (join
-- alter x f (node y yv bl tl tr) (l , u) | tri< a \negb \negc with alter x f tl (l , a)
-- alter x f (node y yv bl tl tr) (l , u) | tri< a \negb \negc | \uparrow tl' with bl
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a \negb \negc | \uparrow tl' | \checkmark = fromInserted\uparrow (rot^r
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a ¬b ¬c | ↑ tl' | - = ↑ (node y yv × tl'
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a \negb \negc | \uparrow tl' | \land = \langle node y yv \neg tl' tr
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a \negb \negc | \langle tl' \rangle = \langle node y yv bl tl' tr \rangle
-- alter x f (node y yv bl tl tr) (l , u) | tri< a \negb \negc | \downarrow tl' with bl
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a \negb \negc | \downarrow tl' | \times = \downarrow (node y yv \rightarrow tl'
```

```
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a ¬b ¬c | ↓ tl' | ¬ = ⟨ node y yv \ tl' tr
-- alter x f (node y yv bl tl tr) (1 , u) | tri< a ¬b ¬c | ↓ tl' | \times = fromInserted↓ (rot'
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c with alter x f tr (c , u)
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↑ tr' with bl
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↑ tr' | \times = ⟨ node y yv \times tl tr
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↑ tr' | \times = ↑ (node y yv \times tl tr
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↑ tr' | \times = fromInserted↑ (rot'
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↑ tr' \times = ⟨ node y yv bl tl tr' ⟩
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' with bl
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' | \times = fromInserted↓ (rot'
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' | \times = fromInserted↓ (rot'
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' | \times = (node y yv \times tl tr)
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' | \times = (node y yv \times tl tr)
-- alter x f (node y yv bl tl tr) (1 , u) | tri> ¬a ¬b c | ↓ tr' | \times = (node y yv \times tl tr)
```

10 Packaging

Users don't need to be exposed to the indices on the full tree type: here, we package it in thee forms.

10.1 Dependent Map

```
module DependantMap where
  data Map \{v\} (V: Key \rightarrow Set \ v): Set (k \sqcup v \sqcup r) where
     tree : \forall \{h\}
              \rightarrow Bounded. Tree V Bounded. Bounded. Bounded.

ightarrow Map V
  insertWith: \forall \{v\} \{V : Key \rightarrow Set v\} (k : Key)
                   \rightarrow V k
                   \rightarrow (V k \rightarrow V k \rightarrow V k)
                   \rightarrow Map V
                   \rightarrow Map V
  insertWith k \ v \ f (tree tr) = tree (proj<sub>2</sub> (Bounded.insert k \ v \ f \ tr (lift tt , lift tt)))
  insert : \forall \{v\}
                   \{V: Key \rightarrow \mathsf{Set}\ v\}
                   (k: Key) \rightarrow
                   V k \rightarrow
                   Map V \rightarrow
                   \mathsf{Map}\ V
  insert k v = \text{insertWith } k v \text{ const}
  lookup: (k: Key)
              \rightarrow \forall \{v\} \{V : Key \rightarrow \mathsf{Set}\ v\}
              \rightarrow Map V
              \rightarrow Maybe (V k)
```

```
\begin{array}{l} \mathsf{lookup}\ k\ (\mathsf{tree}\ tr) = \mathsf{Bounded.lookup}\ k\ tr \\ \\ \mathsf{delete}\ :\ (k:\ Key) \\ \qquad \to \ \forall\ \{v\}\ \{V:\ Key \to \mathsf{Set}\ v\} \\ \qquad \to \ \mathsf{Map}\ V \\ \qquad \to \ \mathsf{Map}\ V \\ \\ \mathsf{delete}\ k\ (\mathsf{tree}\ tr)\ \mathsf{with}\ \mathsf{Bounded.delete}\ k\ tr \\ \\ \ldots\ |\ tr'\ \mathsf{Bounded.-0} = \mathsf{tree}\ tr' \\ \\ \ldots\ |\ tr'\ \mathsf{Bounded.-1} = \mathsf{tree}\ tr' \end{array}
```

10.2 Non-Dependent (Simple) Map

```
module Map where
   data Map \{v\} (V: Set v): Set (k \sqcup v \sqcup r) where
     tree : \forall \{h\}
             \rightarrow Bounded.Tree (const V) Bounded. Bounded.

ightarrow Map V
  insertWith: \forall \{v\} \{V : Set v\} (k : Key)
                   \rightarrow (V \rightarrow V \rightarrow V)
                   \rightarrow Map V
                   \rightarrow Map V
  insertWith k \ v \ f (tree tr) = tree (proj<sub>2</sub> (Bounded.insert k \ v \ f \ tr (lift tt , lift tt)))
   empty: \forall \{v\} \{V : \mathsf{Set}\ v\} \to \mathsf{Map}\ V
   empty = tree (Bounded.leaf (lift tt))
   \mathsf{insert} \,:\, \forall \ \{v\} \ \{V \colon \mathsf{Set} \ v\} \ (k \colon \mathit{Key}) \,\to\, V \to \, \mathsf{Map} \ V \to \, \mathsf{Map} \ V
  insert k v = \text{insertWith } k v \text{ const}
  \mathsf{lookup}: \ (k: \mathit{Key}) \to \forall \ \{v\} \ \{\mathit{V}: \mathsf{Set} \ \mathit{v}\} \to \mathsf{Map} \ \mathit{V} \to \mathsf{Maybe} \ \mathit{V}
   lookup k (tree tr) = Bounded.lookup k tr
   \mathsf{delete} : (k : Key) \to \forall \{v\} \{V : \mathsf{Set}\ v\} \to \mathsf{Map}\ V \to \mathsf{Map}\ V
   delete k (tree tr) with Bounded.delete k tr
   ... | tr' Bounded.-0 = tree tr'
   ... | tr' Bounded.-1 = tree tr'
```

10.3 Set

Note that we can't call the type itself "Set", as that's a reserved word in Agda.

```
\begin{array}{l} \rightarrow \langle \mathsf{Set} \rangle \\ \\ \mathsf{insert} : Key \rightarrow \langle \mathsf{Set} \rangle \rightarrow \langle \mathsf{Set} \rangle \\ \\ \mathsf{insert} \ k \ (\mathsf{tree} \ tr) = \mathsf{tree} \ (\mathsf{proj}_2 \ (\mathsf{Bounded.insert} \ k \ \mathsf{tt} \ \mathsf{const} \ tr \ (\mathsf{lift} \ \mathsf{tt} \ , \ \mathsf{lift} \ \mathsf{tt}))) \\ \\ \mathsf{member} : Key \rightarrow \langle \mathsf{Set} \rangle \rightarrow \mathsf{Bool} \\ \\ \mathsf{member} \ k \ (\mathsf{tree} \ tr) = \mathsf{is-just} \ (\mathsf{Bounded.lookup} \ k \ tr) \\ \\ \mathsf{delete} : (k : Key) \rightarrow \langle \mathsf{Set} \rangle \rightarrow \langle \mathsf{Set} \rangle \\ \\ \mathsf{delete} \ k \ (\mathsf{tree} \ tr) \ \mathsf{with} \ \mathsf{Bounded.delete} \ k \ tr \\ \\ \ldots \mid tr' \ \mathsf{Bounded}. -0 = \mathsf{tree} \ tr' \\ \\ \ldots \mid tr' \ \mathsf{Bounded}. -1 = \mathsf{tree} \ tr' \\ \\ \end{array}
```

References

- [1] N. A. Danielsson, "The Agda standard library." [Online]. Available: https://agda.github.io/agda-stdlib/README.html
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