

Probabilistic Functional Programming

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Modeling Probability

How do we model stochastic and probabilistic processes in programming languages?

The Boy-Girl Paradox

1. Mr. Jones has two children. The older child is a girl. What is the probability that both children are girls?
2. Mr. Smith has two children. At least one of them is a boy. What is the probability that both children are boys?

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Part of the difficulty in the question is that it's ambiguous: can we use programming languages to lend some precision?

Using normal features built in to the language.

```
from random import randrange, choice

class Child:
    def __init__(self):
        self.gender = choice(['boy', 'girl'])
        self.age = randrange(18)
```



```
from operator import attrgetter

def mr_jones():
    child_1 = Child()
    child_2 = Child()
    eldest = max(child_1, child_2,
                  key=attrgetter('age'))
    assert eldest.gender == 'girl'
    return [child_1, child_2]
```

```
def mr_smith():  
    child_1 = Child()  
    child_2 = Child()  
    assert child_1.gender == 'boy' or \  
           child_2.gender == 'boy'  
    return [child_1, child_2]
```

Unclear semantics

What contracts are guaranteed by probabilistic functions?

What does it mean *exactly* for a function to be probabilistic?

Why isn't the following¹ “random”?

```
int getRandomNumber()  
{  
    return 4; // chosen by fair dice roll.  
              // guaranteed to be random.  
}
```

¹Randall Munroe. *Xkcd: Random Number*. en. Title text: RFC 1149.5 specifies 4 as the standard IEEE-vetted random number. Feb. 2007. URL: <https://xkcd.com/221/> (visited on 07/06/2018).

What about this?

```
children_1 = [Child(), Child()]  
children_2 = [Child()] * 2
```

How can we describe the difference between `children_1` and `children_2`?

Underpowered

There are many more things we may want to do with probability distributions.

What about expectations?

```
def expect(predicate, process, iterations=100):  
    success, tot = 0, 0  
    for _ in range(iterations):  
        try:  
            success += predicate(process())  
            tot += 1  
        except AssertionError:  
            pass  
    return success / tot
```

The Ad-Hoc Solution

```
p_1 = expect(  
    lambda children: all(child.gender == 'girl'  
                           for child in children),  
    mr_jones)  
p_2 = expect(  
    lambda children: all(child.gender == 'boy'  
                           for child in children),  
    mr_smith)
```

$$p_1 \approx \frac{1}{2}$$
$$p_2 \approx \frac{1}{3}$$

Monadic Modeling

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- Why should we implement it? What is it useful for?
- How should we implement it? How can it be made efficient?
- Can we glean any insights on the nature of probabilistic computations from the language? Are there any interesting symmetries?

The Erwig And Kollmansberger Approach

First approach²:

```
newtype Dist a = Dist { runDist :: [(a, ℝ)] }
```

A distribution is a list of possible events, each tagged with a probability.

²Martin Erwig and Steve Kollmansberger. “Functional Pearls: Probabilistic Functional Programming in Haskell”. In: *Journal of Functional Programming* 16.1 (2006), pp. 21–34. ISSN: 1469-7653, 0956-7968. DOI: 10.1017/S0956796805005721. URL: <http://web.engr.oregonstate.edu/~erwig/papers/abstracts.html%5C#JFP06a> (visited on 09/29/2016).

We could (for example) encode a die as:

die :: *Dist Integer*

die = *Dist* [(1, $\frac{1}{6}$), (2, $\frac{1}{6}$), (3, $\frac{1}{6}$), (4, $\frac{1}{6}$), (5, $\frac{1}{6}$), (6, $\frac{1}{6}$)]

This lets us encode (in the types) the difference between:

children_1 :: [*Dist Child*]

children_2 :: *Dist* [*Child*]

As we will use this as a DSL, we need to define the language features we used above:

```
def mr_smith():  
    child_1 = Child()  
    child_2 = Child()  
    assert child_1.gender == 'boy' or \  
           child_2.gender == 'boy'  
    return [child_1, child_2]
```


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```

1. = (assignment)
2. assert
3. return

Assignment i

Assignment expressions can be translated into lambda expressions:

$$\begin{aligned} & \text{let } x = e_1 \text{ in } e_2 \\ \equiv \\ & (\lambda x. e_2) e_1 \end{aligned}$$

In the context of a probabilistic language, e_1 and e_2 are distributions. So what we need to define is application: this is encapsulated by the “monadic bind”:

$$(\gg) :: \text{Dist } a \rightarrow (a \rightarrow \text{Dist } b) \rightarrow \text{Dist } b$$

Assignment ii

For a distribution, what's happening inside the λ is e_1 given x . Therefore, the resulting probability is the product of the outer and inner probabilities.

$$xs \ggg f = \text{Dist} \left[\begin{array}{l} (y, xp \times yp) \\ | (x, xp) \leftarrow \text{runDist } xs \\ , (y, yp) \leftarrow \text{runDist } (f \ x) \end{array} \right]$$

Assertion

Assertion is a kind of conditioning: given a statement about an event, it either occurs or it doesn't.

```
guard :: Bool → Dist ()  
guard True  = Dist [((), 1)]  
guard False = Dist []
```

Return is the “unit” value for a distribution; the certain event, the unconditional distribution.

return :: *a* → *Dist a*

return *x* = *Dist* [(*x*, 1)]

Putting it all Together

$mrSmith :: Dist [Child]$

$mrSmith = do$

$child1 \leftarrow child$

$child2 \leftarrow child$

$guard (gender\ child1 \equiv Boy \vee gender\ child2 \equiv Boy)$

$return [child1, child2]$

$expect :: (a \rightarrow \mathbb{R}) \rightarrow Dist\ a \rightarrow \mathbb{R}$

$expect\ p\ xs = \frac{\sum [p\ x \times xp | (x, xp) \leftarrow runDist\ xs]}{\sum [xp | (-, xp) \leftarrow runDist\ xs]}$

$probOf :: (a \rightarrow Bool) \rightarrow Dist\ a \rightarrow \mathbb{R}$

$probOf\ p = expect\ (\lambda x \rightarrow \text{if } p\ x \text{ then } 1 \text{ else } 0)$

$\text{probOf } (\text{all } ((\equiv) \text{ Girl} \circ \text{gender})) \text{ mrJones} \equiv \frac{1}{2}$
 $\text{probOf } (\text{all } ((\equiv) \text{ Boy} \circ \text{gender})) \text{ mrSmith} \equiv \frac{1}{3}$

Once the semantics are described, different interpreters are easy to swap in.

Monty Hall i

```
data Decision = Decision { stick  :: Bool  
                           , switch :: Bool }
```

```
montyHall :: Dist Decision
```

```
montyHall = do
```

```
    car      ← uniform [1..3]
```

```
    choice1 ← uniform [1..3]
```

```
    let left  = [door | door ← [1..3], door ≠ choice1]
```

```
    let open  = head [door | door ← left, door ≠ car]
```

```
    let choice2 = head [door | door ← left, door ≠ open]
```

```
    return (Decision { stick  = car ≡ choice1  
                      , switch = car ≡ choice2 })
```

While we can interpret it in the normal way to solve the problem:

$$\begin{aligned} \textit{probOf stick montyHall} &\equiv \frac{1}{3} \\ \textit{probOf switch montyHall} &\equiv \frac{2}{3} \end{aligned}$$

Monty Hall iii

We could alternatively draw a diagram of the process.

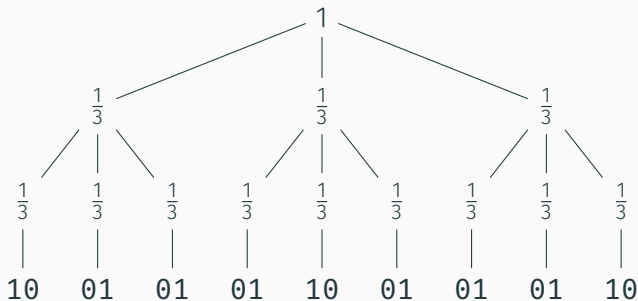


Figure 1: AST from Monty Hall problem. **1** is a win, **0** is a loss. The first column is what happens on a stick, the second is what happens on a loss.

Theoretical Foundations

Stochastic Lambda Calculus

It is possible³ to give measure-theoretic meanings to the operations described above.

$$\mathcal{M} \llbracket \text{return } x \rrbracket (A) = \begin{cases} 1, & \text{if } x \in A \\ 0, & \text{otherwise} \end{cases} \quad (1)$$

$$\mathcal{M} \llbracket d \ggg k \rrbracket (A) = \int_X \mathcal{M} \llbracket k(x) \rrbracket (A) d\mathcal{M} \llbracket d \rrbracket (x) \quad (2)$$

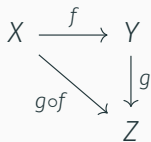
³Norman Ramsey and Avi Pfeffer. “Stochastic Lambda Calculus and Monads of Probability Distributions”. In: *29th ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages*. Vol. 37. ACM, 2002, pp. 154–165. URL: <http://www.cs.tufts.edu/~nr/cs257/archive/norman-ramsey/pmonad.pdf> (visited on 09/29/2016).

Giry⁴ gave a categorical interpretation of probability theory.

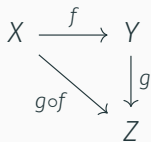
⁴Michèle Giry. “A Categorical Approach to Probability Theory”. In: *Categorical Aspects of Topology and Analysis*. Ed. by A. Dold, B. Eckmann, and B. Banaschewski. Vol. 915. Berlin, Heidelberg: Springer Berlin Heidelberg, 1982, pp. 68–85. ISBN: 978-3-540-11211-2 978-3-540-39041-1. DOI: [10.1007/BFb0092872](https://doi.org/10.1007/BFb0092872). URL: <http://link.springer.com/10.1007/BFb0092872> (visited on 03/03/2017).

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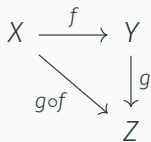


Categories, Quickly



Objects $\text{Ob}(\mathbf{C}) = \{X, Y, Z\}$

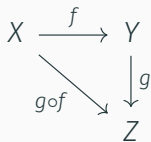
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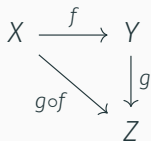


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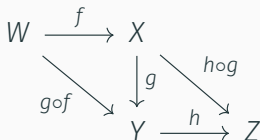


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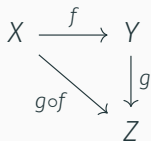


$$(h \circ g) \circ f = h \circ (g \circ f) \quad (3)$$

$$A \curvearrowright id_A$$

$$\forall A. A \in \text{Ob}(\mathbf{C}) \exists id_A : \text{hom}_{\mathbf{C}}(A, A) \quad (4)$$

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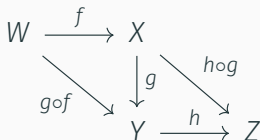


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Example

Set is the category of sets, where objects are sets, and arrows are functions.

Functors

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$$\begin{array}{ccc} \mathbf{F}X & \xrightarrow{\mathbf{F}f} & \mathbf{F}Y \\ \uparrow & & \uparrow \\ X & \xrightarrow{f} & Y \end{array}$$

Functors which embed categories into themselves are called Endofunctors.

Monads

In the category of Endofunctors, **Endo**, a Monad is a triple of:

1. An Endofunctor m ,
2. A natural transformation:

$$\eta : A \rightarrow m(A) \tag{5}$$

This is an operation which embeds an object.

3. Another natural transformation:

$$\mu : m^2(A) \rightarrow m(A) \tag{6}$$

This collapses two layers of the functor.

The Category of Measurable Spaces

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In code (we restrict to measurable functions):

```
newtype Measure a = Measure ((a → ℝ) → ℝ)
```

We now get η and μ :

$integrate :: Measure\ a \rightarrow (a \rightarrow \mathbb{R}) \rightarrow \mathbb{R}$

$integrate\ (Measure\ m)\ f = m\ f$

$return :: a \rightarrow Measure\ a$

$return\ x = Measure\ (\lambda measure \rightarrow measure\ x)$

$(\gg=) :: Measure\ a \rightarrow (a \rightarrow Measure\ b) \rightarrow Measure\ b$

$xs \gg= f = Measure\ (\lambda measure \rightarrow integrate\ xs$
 $\quad (\lambda x \rightarrow integrate\ (f\ x)$
 $\quad (\lambda y \rightarrow measure\ y)))$

Other Applications

It has been shown⁵ that the semantics of the probability monad suitable encapsulate *differential privacy*.

⁵Jason Reed and Benjamin C. Pierce. “Distance Makes the Types Grow Stronger: A Calculus for Differential Privacy”. In: *ACM Sigplan Notices*. Vol. 45. ACM, 2010, pp. 157–168. URL: <http://dl.acm.org/citation.cfm?id=1863568> (visited on 03/01/2017).

LINQ⁶ is an API which provides a monadic syntax for performing queries (sql, etc.)

PINQ⁷ extends this to provide *differentially private* queries.

⁶Don Box and Anders Hejlsberg. *LINQ: .NET Language Integrated Query*. en. Feb. 2007. URL:

<https://msdn.microsoft.com/en-us/library/bb308959.aspx> (visited on 07/09/2018).

⁷Frank McSherry. “Privacy Integrated Queries”. In: *Communications of the ACM* (Sept. 2010). URL: <https://www.microsoft.com/en-us/research/publication/privacy-integrated-queries-2/>.

Conclusion
