# Intro to GPU Computing

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### Why use GPU computing?

General Purpose Graphical Processing Unit (GPGPU) computing is a great step towards HPC computing on consumer hardware. It works best with programs that are:

- Data parallel (can act independently on different elements)
- Throughput intensive (There are a lot of elements)

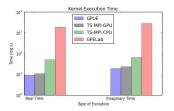


Figure: http://peterwittek.com/gpe-comparison.html

### GPU vs CPU

GPU Computing can do many things much faster than the CPU; however, there are a few drawbacks:

	CPU	GPU	
Memory	128GB	12GB	
Parallelization	afterthought OpenMP, MPI	natural CUDA, OpenCL	
Boilerplate	a little	a lot	

### Parallelization

In most GPU simulations, data is parsed into **threads**(work-item), **blocks**(work-group), and a **grid**(NDRange).

- Threads have fast shared memory within a block.
- Data parallelism within a block

$ \begin{array}{c ccccc} T_{0,0} & T_{1,0} & T_{2,0} & T_{3,0} \\ \hline T_{0,1} & T_{1,1} & T_{2,1} & T_{3,1} \\ \hline T_{0,2} & T_{1,2} & T_{2,2} & T_{3,2} \\ \hline T_{0,3} & T_{1,3} & T_{2,3} & T_{3,3} \\ \hline \end{array} $	$\mathbf{B}_{1,0}$	$\mathbf{B}_{2,0}$	$\mathbf{B}_{3,0}$
$\mathbf{B}_{0,1}$	$\mathbf{G}_{0}^{\mathrm{B}_{1,1}}$	${f B}_{2,1}$	$\mathbf{B}_{3,1}$
$\mathbf{B}_{0,2}$	$\mathbf{B}_{1,2}$	$\mathbf{B}_{2,2}$	$\mathbf{B}_{3,2}$
$\mathbf{B}_{0,3}$	$\mathbf{B}_{1,3}$	$\mathbf{B}_{2,3}$	$\mathbf{B}_{3,3}$



#### Hardware

There are two major vendors for GPU's:

AMD "Open" computing (Must use **OpenCL**)

nVidia "Industry standard" for GPU computing (can use OpenCL or CUDA).

For the most part, these follow trends you hear about in gaming: nVidia trail-blazes and AMD keeps up; however, this is not necessarily true with recent cards.

OpenCL and CUDA are comparable in performance, though CUDA has more robust libraries.

#### CUDA

CUDA (once Compute Unified Device Architecture) is the standard programming language to use for GPGPU computing and boasts speed and performance; however, it only works on nVidia cards.

In GPU computing, functions are called kernels:

```
__global__ May be called from the host or device
```

\_\_device\_\_ Must be called from the device

\_\_host\_\_ Is just a normal function

There are also a bunch of CUDA-specific functions(cudaMalloc, cudaMemcpy, cudaFree, etc...)

A quick example of vector addition can be found in the git repo under intro/CUDA

# CUDAnative.jl

This is a julia implementation of CUDA and will be developed further in the future.

- It is much easier to use than CUDA and works well with most Julia code.
- It is incomplete and hard to build
- More informations can be found here: http://juliagpu.github.io/CUDAnative.jl/stable/man/usage.html

# OpenCL

OpenCL is the Open Computing Language created by Khronos (OpenGL, Vulkan) and...

- Follows similar notation to OpenGL. In OpenGL, shaders are read in as strings, but in OpenCL, kernels are read in as strings
- Allows users to use all hardware on their computer in the same language, including CPU, GPU, FPGA, etc...
- Also allows for OpenGL interoperability for visualizations

A quick example of vector addition can be found in the git repo under intro/OpenCL

### Accessing GPU's at OIST

After logging on to Sango or Tombo, you can check which GPU's are taken with

squeue -p gpu

and can access a GPU node (interactively) with

```
srun g++ vec_add.cpp -I/apps/free/cuda/8.0.27/include
   -L/apps/free/cuda/8.0.27/lib64 -l0penCL
srun --partition=gpu --gres=gpu:1 a.out
```

Once you have access, you can check each GPU with nvidia-smi