# 18-661 Introduction to Machine Learning

SVM - II

Spring 2025

ECE - Carnegie Mellon University

#### **Announcements**

- Homework 2 is due this Friday, February 21 at 11:59pm ET.
- Midterm exam is on Wednesday, February 26 in lecture.
  - Format: In-person, paper-based exam
  - Closed-book, but you can use a letter- or A4-sized double-sided, handwritten cheat sheet.
  - No calculators allowed.
  - Topics: MLE/MAP, linear regression, overfitting and bias-variance tradeoff, naive Bayes, logistic regression, multi-class classification, SVM (max margin and hinge loss formulations), and nearest neighbors.

#### **Outline**

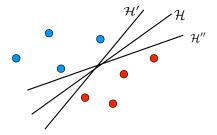
- 1. Review of Max Margin SVM Formulation
- 2. SVM: Hinge Loss Formulation
- 3. SVM: Example
- 4. A Dual View of SVMs (the short version)
- 5. Kernel SVM

Review of Max Margin SVM

**Formulation** 

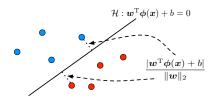
#### Intuition: Where to Put the Decision Boundary?

- Consider a separable training dataset (e.g., with two features)
- There are an infinite number of decision boundaries  $\mathcal{H}: \mathbf{w}^{\top} \mathbf{x} + b = 0!$



Which one should we pick?

## **Optimizing the Margin**



How should we pick (w, b) based on its margin? We want a decision boundary that is as far away from all training points as possible, so we to *maximize* the margin!

$$\max_{\boldsymbol{w},b} \left( \min_{n} \frac{y_n[\boldsymbol{w}^{\top} \boldsymbol{x}_n + b]}{\|\boldsymbol{w}\|_2} \right) = \max_{\boldsymbol{w},b} \left( \frac{1}{\|\boldsymbol{w}\|_2} \min_{n} y_n[\boldsymbol{w}^{\top} \boldsymbol{x}_n + b] \right)$$

Only involves points near the boundary (more on this later).

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### **Rescaled Margin**

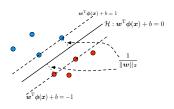
We can further constrain the problem by scaling (w, b) such that

$$\min_{n} y_n[\boldsymbol{w}^{\top} \boldsymbol{x}_n + b] = 1.$$

Note that there always exists a scaling for which this is true. We've fixed the numerator in the  $MARGIN(\boldsymbol{w}, b)$  equation, and we have:

$$MARGIN(\boldsymbol{w}, b) = \frac{\min_{n} y_{n}[\boldsymbol{w}^{\top}\boldsymbol{x}_{n} + b]}{\|\boldsymbol{w}\|_{2}} = \frac{1}{\|\boldsymbol{w}\|_{2}}$$

Hence the points closest to the decision boundary are at distance  $\frac{1}{\|\mathbf{w}\|_2}$ .



## SVM: Max-margin Formulation for Separable Data

We thus want to solve:

$$\max_{\mathbf{w},b} \underbrace{\frac{1}{\|\mathbf{w}\|_2}}_{\text{margin}} \quad \text{such that} \quad \underbrace{\min_{n} y_n[\mathbf{w}^\top \mathbf{x}_n + b] = 1}_{\text{scaling of } \mathbf{w}, b}$$

which is equivalent to

$$\max_{\boldsymbol{w},b} \frac{1}{\|\boldsymbol{w}\|_2} \quad \text{such that} \quad y_n[\boldsymbol{w}^\top \boldsymbol{x}_n + b] \geq 1, \quad \forall \quad n$$

This is further equivalent to

$$\begin{aligned} & \min_{\boldsymbol{w},b} & & \frac{1}{2} \| \boldsymbol{w} \|_2^2 \\ & \text{s.t.} & & y_n [\boldsymbol{w}^\top \boldsymbol{x}_n + b] \geq 1, & \forall & n \end{aligned}$$

Given our geometric intuition, SVM is called a **max margin** (or large margin) classifier. The constraints are called **large margin constraints**.

#### SVM for Non-separable Data

#### Constraints in separable setting

$$y_n[\mathbf{w}^{\top}\mathbf{x}_n + b] \ge 1, \quad \forall \quad n$$

#### Constraints in non-separable setting

Can we modify our constraints to account for non-separability? Specifically, we introduce slack variables  $\xi_n \geq 0$ :

$$y_n[\mathbf{w}^{\top}\mathbf{x}_n + b] \ge 1 - \xi_n, \ \forall \ n$$

- For "hard" training points, we can increase  $\xi_n$  until the above inequalities are met.
- What does it mean when  $\xi_n$  is very large? We have violated the original constraints "by a lot."

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### **Soft-margin SVM Formulation**

We do not want  $\xi_n$  to grow too large, and we can control their size by incorporating them into our optimization problem:

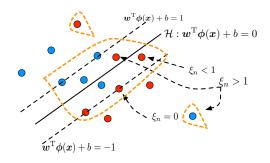
$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad \frac{1}{2} \|\boldsymbol{w}\|_{2}^{2} + C \sum_{n} \xi_{n}$$
s.t.  $y_{n} [\boldsymbol{w}^{\top} \boldsymbol{x}_{n} + b] \ge 1 - \xi_{n}, \quad \forall \quad n$ 

$$\xi_{n} \ge 0, \quad \forall \quad n$$

What is the role of C?

- User-defined hyperparameter
- Trades off between the two terms in our objective
- Same idea as the regularization term in ridge regression

## **Support Vectors: Revisit**



Support vectors satisfy  $y_n[\mathbf{w}^{\top}\mathbf{x}_n + b] = 1 - \xi_n$ :

- $\xi_n = 0$ :  $y_n[\mathbf{w}^{\top} \mathbf{x}_n + b] = 1$ , the point is on the correct side with distance  $\frac{1}{\|\mathbf{w}\|}$ .
- $0 < \xi_n \le 1$ :  $y_n[\mathbf{w}^\top \mathbf{x}_n + b] \in [0, 1)$  on the correct side, but with distance less than  $\frac{1}{\|\mathbf{w}\|}$ .
- $\xi_n > 1$ :  $y_n[\mathbf{w}^{\top}\mathbf{x}_n + b] < 0$ , on the wrong side of the boundary.

**SVM: Hinge Loss Formulation** 

## SVM vs. Logistic Regression

#### **SVM** soft-margin formulation

$$\begin{aligned} \min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad & \frac{1}{2} \|\boldsymbol{w}\|_2^2 + C \sum_n \xi_n \\ \text{s.t.} \quad & y_n [\boldsymbol{w}^\top \boldsymbol{x}_n + b] \geq 1 - \xi_n, \ \forall \ n \\ & \xi_n \geq 0, \ \forall \ n \end{aligned}$$

#### Logistic regression formulation

$$\min_{\mathbf{w}} - \sum_{n} \{ y_n \log \sigma(\mathbf{w}^{\top} \mathbf{x}_n) \\
+ (1 - y_n) \log[1 - \sigma(\mathbf{w}^{\top} \mathbf{x}_n)] \} \\
+ \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2}$$

- Logistic regression defines a loss for each data point and minimizes the total loss plus a regularization term.
- This is convenient for assessing the "goodness" of the model on each data point.
- Can we write SVMs in this form as well? The Hinge Loss formulation!

## **Derive the Hinge Loss Formulation**

Here's the soft-margin formulation again:

$$\min_{\mathbf{w},b,\xi} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{n} \xi_{n} \text{ s.t. } y_{n} [\mathbf{w}^{\top} \mathbf{x}_{n} + b] \geq 1 - \xi_{n}, \ \xi_{n} \geq 0, \ \forall \ n$$

Now since  $y_n[\mathbf{w}^{\top}\mathbf{x}_n + b] \ge 1 - \xi_n \iff \xi_n \ge 1 - y_n[\mathbf{w}^{\top}\mathbf{x}_n + b]$ :

$$\min_{\mathbf{w},b,\xi} C \sum_{n} \xi_{n} + \frac{1}{2} \|\mathbf{w}\|_{2}^{2} \text{ s.t. } \xi_{n} \geq \max(0, 1 - y_{n}[\mathbf{w}^{\top} \mathbf{x}_{n} + b]), \ \forall \ n$$

Now since the  $\xi_n$  should always be as small as possible, we obtain:

$$\min_{\mathbf{w},b} C \sum_{n} \max(0, 1 - y_n[\mathbf{w}^{\top} \mathbf{x}_n + b]) + \frac{1}{2} \|\mathbf{w}\|_2^2$$

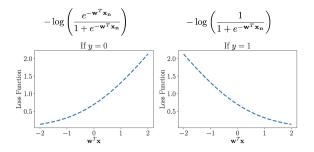
Divide by C and set  $\lambda = \frac{1}{C}$ , we get the Hinge Loss formulation:

$$\min_{\boldsymbol{w},b} \sum_{n} \underbrace{\max(0, 1 - y_n[\boldsymbol{w}^{\top} \boldsymbol{x}_n + b])}_{\text{Hinge Loss for } \boldsymbol{x}_n, \boldsymbol{y}_n} + \frac{\lambda}{2} \|\boldsymbol{w}\|_2^2$$

## Cross-Entropy Loss vs. Hinge Loss

Given training data  $(x_n, y_n)$ , the cross entropy loss was

$$-\{y_n \log \sigma(\mathbf{w}^{\top} \mathbf{x}_n) + (1 - y_n) \log[1 - \sigma(\mathbf{w}^{\top} \mathbf{x}_n)]\}$$

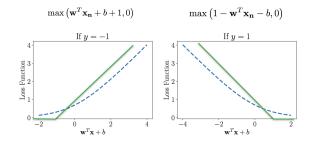


What does the Hinge Loss Function look like?

## Cross-Entropy Loss vs. Hinge Loss

Given training data  $(x_n, y_n)$ , the Hinge loss is

$$\max(0, 1 - y_n[\boldsymbol{w}^{\top}\boldsymbol{x}_n + b])$$



- Loss grows linearly as we move away from the boundary.
- No penalty if a point is more than 1 unit from the boundary.
- Makes the search for the boundary easier (as we will see later).

## **Hinge Loss SVM Formulation**

#### Minimizing the total hinge loss on all the training data

$$\min_{\boldsymbol{w},b} \sum_{n} \underbrace{\max(0,1-y_n[\boldsymbol{w}^{\top}\boldsymbol{x}_n+b])}_{\text{hinge loss for sample } n} + \underbrace{\frac{\lambda}{2} \|\boldsymbol{w}\|_2^2}_{\text{regularizer}}$$

Analogous to regularized least squares or logistic regression, as we balance between two terms (the loss and the regularizer).

- Can solve using gradient descent to get the optimal  $\mathbf{w}$  and b
- Gradient of the first term will be either 0,  $\mathbf{x}_n$  or  $-\mathbf{x}_n$  depending on  $y_n$  and  $\mathbf{w}^{\top}\mathbf{x}_n + b$ .
- Much easier to compute than in logistic regression, where we need to compute the sigmoid function  $\sigma(\mathbf{w}^{\top}\mathbf{x}_n + b)$  in each iteration.

#### Three SVM Formulations

#### Hard-margin (for separable data)

$$\min_{\boldsymbol{w},b,\xi} \frac{1}{2} \|\boldsymbol{w}\|_2^2 \text{ s.t. } y_n[\boldsymbol{w}^\top \boldsymbol{x}_n + b] \ge 1, \ \xi_n \ge 0, \ \forall \ n$$

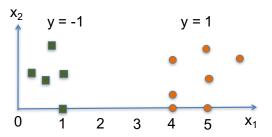
#### Soft-margin (add slack variables)

$$\min_{\mathbf{w},b,\xi} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{n} \xi_{n} \text{ s.t. } y_{n} [\mathbf{w}^{\top} \mathbf{x}_{n} + b] \ge 1 - \xi_{n}, \ \xi_{n} \ge 0, \ \forall \ n$$

Hinge loss (define a loss function for each data point) 
$$\min_{{\boldsymbol w},b} \ \sum_n \max(0,1-y_n[{\boldsymbol w}^\top{\boldsymbol x}_n+b]) + \frac{\lambda}{2} \|{\boldsymbol w}\|_2^2$$

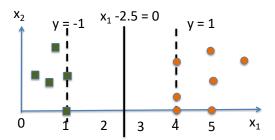
# SVM: Example

## **Example of SVM**



What will be the decision boundary learnt by solving the SVM optimization problem?

## Example of SVM



Margin = 1.5; the decision boundary has  $\mathbf{w} = [1, 0]^{\mathsf{T}}$ , and b = -2.5.

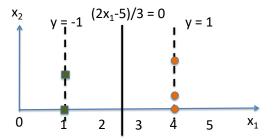
Is this the right scaling of  $\mathbf{w}$  and b? We need  $\min_n y_n(\mathbf{w}^\top \mathbf{x}_n + b) = 1...$ 

The correct parameter should be  $\mathbf{w} = [2/3, 0]^{\top}$ , and b = -5/3.

For example, for  $\mathbf{x}_n = [1, 0]^\top$ , we have

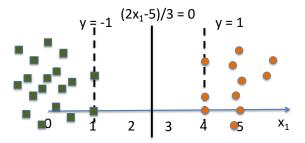
$$y_n(\mathbf{w}^{\top}\mathbf{x}_n + b) = (-1)[2/3 - 5/3] = 1.$$

## **Example of SVM: Support Vectors**



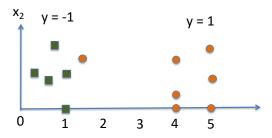
The solution to our optimization problem will be the **same** to the *reduced* dataset containing all the support vectors.

## **Example of SVM: Support Vectors**



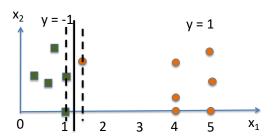
There can be many more data than the number of support vectors (so we can train on a smaller dataset).

#### **Example of SVM: Resilience to Outliers**



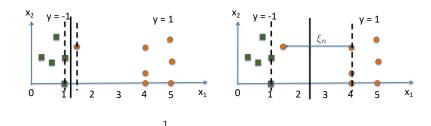
• Still linearly separable, but one of the orange dots is an "outlier".

## **Example of SVM: Resilience to Outliers**



- Naively applying the hard-margin SVM will result in a classifier with small margin.
- So, better to use the soft-margin (or equivalently, hinge loss) formulation.

## **Example of SVM: Resilience to Outliers**



$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad \frac{1}{2} \|\boldsymbol{w}\|_{2}^{2} + C \sum_{n} \xi_{n}$$
s.t.  $y_{n} [\boldsymbol{w}^{\top} \boldsymbol{x}_{n} + b] \ge 1 - \xi_{n}, \quad \forall \quad n$ 

$$\xi_{n} \ge 0, \quad \forall \quad n$$

We allow the outlier to violate the constraint by  $\xi_n$  which we penalize.

- Small  $C \Rightarrow$  more constraint violation, less sensitivity to outliers; but also (potentially) worse accuracy as more points are misclassified.
- $C = +\infty$  corresponds to hard margin SVM.

### Advantages of SVM

#### So far, shown SVM:

- 1. Maximizes distance of training data from the boundary.
- 2. Only requires a subset of the training points.
- 3. Is less sensitive to outliers.
- 4. Scales better with high-dimensional data.
- 5. Generalizes well to many nonlinear models.

We will need to use duality to show the last two properties.

#### **Outline**

- 1. Review of Max Margin SVM Formulation
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A Dual View of SVMs (the short

version)

### What Is Duality?

Duality is a way of transforming a constrained optimization problem.

It tells us sometimes-useful information about the problem structure, and can sometimes make the problem easier to solve.

- Under strong duality condition (details are beyond the scope...),
   primal and dual problems are equivalent.
- Further, due to complementary slackness, dual variables tell us whether constraints are met with = or <</li>
- The strong duality condition is not always true for all optimization problems, but is true for the soft-margin SVM problem.

Instead of solving the max margin (primal) formulation, we solve its dual problem which will have certain advantages we will see.

#### **Derivation of the Dual**

Here is a skeleton of how to derive the dual problem.

#### Recipe

- Formulate the generalized Lagrangian function (we'll define this on the next slide) that incorporates the constraints and introduces dual variables
- 2. Minimize the Lagrangian function over the primal variables
- Plug in the primal variables from the previous step into the Lagrangian to get the dual function
- 4. Maximize the dual function with respect to dual variables
- 5. Recover the solution (for the primal variables) from the dual variables

## **Deriving the Dual for SVM**

#### **Primal SVM**

$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad \frac{1}{2} \|\boldsymbol{w}\|_{2}^{2} + C \sum_{n} \xi_{n}$$
s.t.  $y_{n} [\boldsymbol{w}^{\top} \boldsymbol{x}_{n} + b] \ge 1 - \xi_{n}, \quad \forall \quad n$ 

$$\xi_{n} \ge 0, \quad \forall \quad n$$

The constraints are equivalent to the following canonical forms:

$$-\xi_n \leq 0$$
 and  $1 - y_n[\boldsymbol{w}^{\top} \boldsymbol{x}_n + b] - \xi_n \leq 0$ 

#### Lagrangian

$$L(\boldsymbol{w}, b, \{\xi_n\}, \{\alpha_n\}, \{\lambda_n\}) = C \sum_n \xi_n + \frac{1}{2} \|\boldsymbol{w}\|_2^2 - \sum_n \lambda_n \xi_n + \sum_n \alpha_n \{1 - y_n [\boldsymbol{w}^\top \boldsymbol{x}_n + b] - \xi_n\}$$

under the constraints that  $\alpha_n \geq 0$  and  $\lambda_n \geq 0$ .

## Deriving the Dual of SVM

#### Lagrangian

$$L(\mathbf{w}, b, \{\xi_n\}, \{\alpha_n\}, \{\lambda_n\}) = C \sum_{n} \xi_n + \frac{1}{2} ||\mathbf{w}||_2^2 - \sum_{n} \lambda_n \xi_n + \sum_{n} \alpha_n \{1 - y_n [\mathbf{w}^{\top} \mathbf{x}_n + b] - \xi_n\}$$

under the constraints that  $\alpha_n \geq 0$  and  $\lambda_n \geq 0$ .

- Primal variables:  $\mathbf{w}$ ,  $\{\xi_n\}$ , b; dual variables  $\{\lambda_n\}$ ,  $\{\alpha_n\}$
- Minimize the Lagrangian function over the primal variables by setting  $\frac{\partial L}{\partial \mathbf{w}} = 0$ ,  $\frac{\partial L}{\partial b} = 0$ , and  $\frac{\partial L}{\partial \xi_n} = 0$ .
- Substitute primal variables from the above into the Lagrangian to get the dual function.
- Maximize the dual function with respect to dual variables
- After some further math and simplifications, we have...

#### **Dual Formulation of SVM**

#### Dual is also a convex quadratic program

$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} \mathbf{x}_{m}^{\top} \mathbf{x}_{n}$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

- There are N dual variables  $\alpha_n$ , one for each data point
- Independent of the size d of x: SVM scales better for high-dimensional features.
- May seem like a lot of optimization variables when N is large, but many of the  $\alpha_n$ 's become zero.  $\alpha_n$  is non-zero only if the  $n^{th}$  point is a support vector

## Why Do Many $\alpha_n$ 's Become Zero?

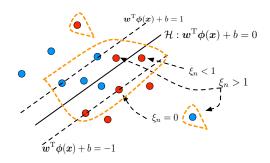
$$\begin{aligned} \max_{\alpha} \quad & \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} \mathbf{x}_{m}^{\top} \mathbf{x}_{n} \\ \text{s.t.} \quad & 0 \leq \alpha_{n} \leq C, \quad \forall \ n \\ & \sum_{n} \alpha_{n} y_{n} = 0 \end{aligned}$$

By complementary slackness:

$$\alpha_n \{1 - \xi_n - y_n [\mathbf{w}^\top \mathbf{x}_n + b]\} = 0 \quad \forall n$$

- This tells us that  $\alpha_n > 0$  only when  $1 \xi_n = y_n[\mathbf{w}^\top \mathbf{x}_n + b]$ , i.e.  $(x_n, y_n)$  is a support vector. So most of the  $\alpha_n$  is zero, and the only non-zero  $\alpha_n$  are for the support vectors.
- Further,  $\alpha_n < C$  only when  $\xi_n = 0$ . (The derivation of this is beyond the scope of today's lecture)

## Visualizing the Support Vectors



- $\alpha_n = 0$ : non-support vector.
- $0 < \alpha_n < C$ : support vector with  $\xi_n = 0$ , i.e.  $y_n[\mathbf{w}^\top \mathbf{x}_n + b] = 1$ , distance to boundary  $\frac{1}{\|\mathbf{w}\|}$ .
- $\alpha_n = C$ : support vector with  $\xi_n > 0$ , hence  $y_n[\mathbf{w}^{\top} \mathbf{x}_n + b] < 1$ .

## How to Get w and b?

#### Lagrangian

$$L(\boldsymbol{w}, b, \{\xi_n\}, \{\alpha_n\}, \{\lambda_n\}) = C \sum_n \xi_n + \frac{1}{2} \|\boldsymbol{w}\|_2^2 - \sum_n \lambda_n \xi_n$$
$$+ \sum_n \alpha_n \{1 - y_n [\boldsymbol{w}^\top \boldsymbol{x}_n + b] - \xi_n\}$$

#### Recovering w

$$\frac{\partial L}{\partial \mathbf{w}} = 0 \to \mathbf{w} = \sum_{n} \alpha_{n} y_{n} \mathbf{x}_{n}$$

Only depends on support vectors, i.e., points with  $\alpha_n > 0!$ 

## Recovering b

Find a sample  $(x_n, y_n)$  such that  $0 < \alpha_n < C$ . Using  $y_n \in \{-1, 1\}$ ,

$$y_n[\mathbf{w}^{\top} \mathbf{x}_n + b] = 1$$

$$b = y_n - \mathbf{w}^{\top} \mathbf{x}_n$$

$$b = y_n - \sum_m \alpha_m y_m \mathbf{x}_m^{\top} \mathbf{x}_n$$

## **Summary of Dual Formulation**

## Primal Max-Margin Formulation

$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad \frac{1}{2} \|\boldsymbol{w}\|_{2}^{2} + C \sum_{n} \xi_{n}$$
s.t.  $y_{n} [\boldsymbol{w}^{\top} \boldsymbol{x}_{n} + b] \ge 1 - \xi_{n}, \quad \forall \quad n$ 

$$\xi_{n} \ge 0, \quad \forall \quad n$$

#### **Dual Formulation**

$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} \mathbf{x}_{m}^{\top} \mathbf{x}_{n}$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

- In dual formulation, the # of variables is independent of dimension.
- Most of the dual variables are 0, and the non-zero ones are the support vectors.
- Can easily recover the primal solution w, b from dual solution.

# **Advantages of SVM**

#### We have shown SVM:

- 1. Maximizes distance of training data from the boundary
- 2. Only requires a subset of the training points.
- 3. Is less sensitive to outliers.
- 4. Scales better with high-dimensional data.
- 5. Generalizes well to many nonlinear models.

# Kernel SVM

## Non-linear Basis Functions in SVM

- What if the true decision boundary is not linear?
- Similar to linear regression, we can transform the feature vector x using non-linear basis functions. For example,

$$\phi(\mathbf{x}) = \left[egin{array}{c} 1 \ x_1 \ x_2 \ x_1 x_2 \ x_1^2 \ x_2^2 \end{array}
ight]$$

ullet Replace old x by  $\phi(old x)$  in both the primal and dual SVM formulations

## Primal and Dual SVM Formulations: Kernel Versions

Primal

$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \quad \frac{1}{2} \|\boldsymbol{w}\|_{2}^{2} + C \sum_{n} \xi_{n}$$
s.t.  $y_{n} [\boldsymbol{w}^{\top} \phi(\boldsymbol{x}_{n}) + b] \ge 1 - \xi_{n}, \quad \forall \quad n$ 

$$\xi_{n} \ge 0, \quad \forall \quad n$$

Dual

$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} \phi(\mathbf{x}_{m})^{\top} \phi(\mathbf{x}_{n})$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

IMPORTANT POINT: In the dual problem, we only need  $\phi(x_m)^{\top}\phi(x_n)$ .

## **Dual Kernel SVM**

We replace the inner products  $\phi(x_m)^{\top}\phi(x_n)$  with a kernel function

$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} k(\boldsymbol{x}_{m}, \boldsymbol{x}_{n})$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

#### What is a kernel function?

- $k(\mathbf{x}_m, \mathbf{x}_n)$  is a scalar-valued function that measures the similarity of  $\mathbf{x}_m$  and  $\mathbf{x}_n$ .
- $k(\mathbf{x}_m, \mathbf{x}_n)$  is a valid kernel function if it is symmetric and positive-definite. This ensures that there exists a  $\phi(\mathbf{x})$  (even if we don't know what it is) such that  $k(\mathbf{x}_m, \mathbf{x}_n) = \phi(\mathbf{x}_m)^\top \phi(\mathbf{x}_n)$ .

# **Examples of Popular Kernel Functions**

Here are some example kernel functions and the corresponding features.

• Dot product:

$$k(\mathbf{x}_m, \mathbf{x}_n) = \mathbf{x}_m^{\top} \mathbf{x}_n$$
, corresponding  $\phi(\mathbf{x}) = \mathbf{x}$ 

• Dot product with positive-definite matrix **Q**:

$$k(\mathbf{x}_m, \mathbf{x}_n) = \mathbf{x}_m^{\top} \mathbf{Q} \mathbf{x}_n$$
, corresponding  $\phi(\mathbf{x}) = \mathbf{Q}^{1/2} \mathbf{x}$ 

• Polynomial kernels (corresponding  $\phi(\mathbf{x})$  complicated):

$$k(\mathbf{x}_m, \mathbf{x}_n) = (1 + \mathbf{x}_m^{\mathsf{T}} \mathbf{x}_n)^d, \quad d \in \mathbb{Z}^+$$

• Radial basis kernel (corresponding  $\phi(\mathbf{x})$  complicated):

$$k(\mathbf{x}_m,\mathbf{x}_n) = \exp\left(-\gamma \left\|\mathbf{x}_m - \mathbf{x}_n\right\|^2\right) \text{ for some } \gamma > 0$$
 and many more.

#### The Kernel Trick

In dual SVM, we can use any of the kernel functions discussed in the previous slide.

$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} k(\mathbf{x}_{m}, \mathbf{x}_{n})$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

Each choice of kernel function will correspond to doing SVM using the transformed data  $\phi(\mathbf{x})$ , but we do not need to know what exactly is  $\phi(\mathbf{x})$ .

This is allows us using more complicated  $\phi(\mathbf{x})$  (like the  $\phi(\mathbf{x})$  associated with radial basis function) to boost performance - without knowing what  $\phi(\mathbf{x})$  is! This is known as "kernal trick".

#### **Test Prediction**

#### **Learning** w and b:

$$\mathbf{w} = \sum_{n} \alpha_{n} y_{n} \phi(\mathbf{x}_{n}),$$

$$b = y_{n} - \mathbf{w}^{\top} \phi(\mathbf{x}_{n}) = y_{n} - \sum_{m} \alpha_{m} y_{m} k(\mathbf{x}_{m}, \mathbf{x}_{n})$$

But for test prediction on a new point  $\mathbf{x}$ , do we need the form of  $\phi(\mathbf{x})$  in order to find the sign of  $\mathbf{w}^{\top}\phi(\mathbf{x}) + b$ ? Fortunately, no!

#### **Test Prediction:**

$$h(\mathbf{x}) = \operatorname{SIGN}(\sum_{n} y_{n} \alpha_{n} k(\mathbf{x}_{n}, \mathbf{x}) + b)$$

At test time it suffices to know the kernel function! So we really do not need to know  $\phi$ .

# Summary of Kernel SVM

Given a dataset  $\{(\mathbf{x}_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

Select a kernel. In general, you can just use one of the popular kernel functions (polynomial kernel or radial kernel).

## **Training**

$$\begin{aligned} \max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} k(\mathbf{x}_{m}, \mathbf{x}_{m}) \\ \text{s.t.} \quad 0 \leq \alpha_{n} \leq C, \quad \forall \ n \\ \sum_{n} \alpha_{n} y_{n} = 0 \end{aligned}$$

#### Prediction

$$h(\mathbf{x}) = \text{SIGN}(\sum_{n} y_{n} \alpha_{n} k(\mathbf{x}_{n}, \mathbf{x}) + b)$$

Given a dataset  $\{(\mathbf{x}_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

What if the data is not linearly separable?

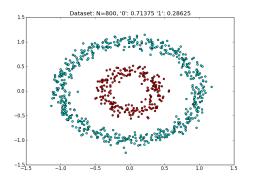
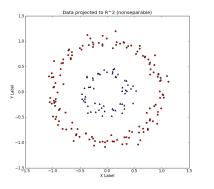


Image Source: https:

Given a dataset  $\{(x_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

Use feature  $\phi(x) = [x_1, x_2, x_1^2 + x_2^2]$  to transform the data in a 3D space



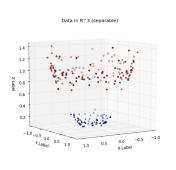


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Given a dataset  $\{(x_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

Then find the decision boundary. How? Solve the dual problem!

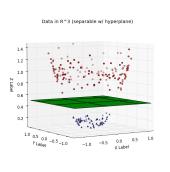
$$\max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} \phi(\mathbf{x}_{m})^{\top} \phi(\mathbf{x}_{n})$$
s.t.  $0 \le \alpha_{n} \le C$ ,  $\forall n$ 

$$\sum_{n} \alpha_{n} y_{n} = 0$$

Then find **w** and *b*. Predict  $y = \text{sign}(\mathbf{w}^T \phi(\mathbf{x}) + b)$ .

Given a dataset  $\{(\mathbf{x}_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

## Here is the resulting decision boundary



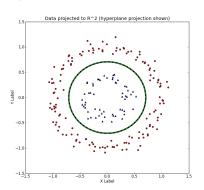


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In the previous example, we manually defined a  $\phi(\mathbf{x})$ .

As mentioned in the "kernel trick" slides, in general you don't need to concretely define  $\phi(\mathbf{x})$ . We could select a kernel function  $k(\mathbf{x}_m, \mathbf{x}_n)$  and solve the following dual SVM.

$$\begin{aligned} \max_{\alpha} \sum_{n} \alpha_{n} - \frac{1}{2} \sum_{m,n} y_{m} y_{n} \alpha_{m} \alpha_{n} k(\mathbf{x}_{m}, \mathbf{x}_{n}) \\ \text{s.t.} \quad 0 \leq \alpha_{n} \leq C, \quad \forall \ n \\ \sum_{n} \alpha_{n} y_{n} = 0 \end{aligned}$$

Test Prediction also only uses kernel:

$$h(\mathbf{x}) = \text{SIGN}(\sum_{n} y_n \alpha_n k(\mathbf{x}_n, \mathbf{x}) + b)$$

Given a dataset  $\{(\mathbf{x}_n, y_n) \text{ for } n = 1, 2, ..., N\}$ , how do you classify it using kernel SVM ?

#### Effect of the choice of kernel: Radial Basis Kernel

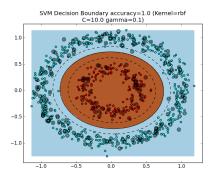


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## Advantages of SVM

Now we have shown all of the below.

- 1. Maximizes distance of training data from the boundary
- 2. Only requires a subset of the training points.
- 3. Is less sensitive to outliers.
- 4. Scales better with high-dimensional data.
- 5. Generalizes well to many nonlinear models.