

# Math Camp

## Module #2: Vector spaces and linear maps

### Part II: enacting violence

*Remember: "The introduction of numbers as coordinates is an act of violence."*  
*still H. Weyl*

## Coordinates

Let  $V$  be a real vector space of dimension  $n$ , and let  $A = \{a_1, \dots, a_n\}$  be a basis for  $V$ .

- $v \in V \implies \exists! \{\alpha_k^v\}_{k=1}^n$  s.t.  $v = \sum_{k=1}^n \alpha_k^v a_k$
- The scalars  $\{\alpha_1^v, \dots, \alpha_n^v\}$  comprise the *coordinate representation* of  $v$  with respect to the basis  $A$

**Dirac function** : given two sets  $X$  and  $Y$ ,  $\delta : X \times Y \rightarrow \{0, 1\}$  is defined by  $\delta_{xy} = 1$  if and only if  $x = y$ .

- $X = Y = \mathbb{Z}$  is illustrative:  $\delta_{ij} = 1 \Leftrightarrow i = j$

$\mathbb{R}^n$

- $x \in \mathbb{R}^n$  implies  $x = (x_1, \dots, x_n)$  with  $x_i \in \mathbb{R}$
- Always think of  $x$  as a column
- The *canonical basis* for  $\mathbb{R}^n$  is  $\mathcal{E} = \{e_1, \dots, e_n\}$ , where  $e_j = (e_{1j}, \dots, e_{nj})$  and  $e_{ij} = \delta_{ij}$ .
- Let  $\dim V = n$  with basis  $A$ . Define  $\varphi : V \rightarrow \mathbb{R}^n$  by setting  $\varphi(a_i) = e_i$ . Talk amongst yourselves.

$\mathbb{R}^{m \times n}$

- A real  $m \times n$  matrix is a rectangular array of real numbers with  $m$  rows and  $n$  columns
- If  $A \in \mathbb{R}^{m \times n}$  then  $A = (a_{ij})$ , where  $i = 1, \dots, m$  and  $j = 1, \dots, n$ , i.e.

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}$$

- $\mathbb{R}^{m \times n}$  is a vector space with canonical basis  $\{e^{ij}\}$  where

$$(e_{kl}^{ij}) = \delta_{(i,j)(k,l)}$$

## Linear functionals

Let  $V$  be a real vector space

- A *linear functional* is a linear map from  $V$  to  $\mathbb{R}$
- The *dual space*  $V^*$  of  $V$  is the vector space of linear functionals from  $V$  to  $\mathbb{R}$
- Let  $\dim V = n$  with basis  $A = \{a_1, \dots, a_n\}$ . Define  $a_i^* : A \rightarrow \mathbb{R}$  on  $A$  by  $a_i^*(a_j) = \delta_{ij}$ , and extend linearly. Then  $A^*$  is a basis for  $V^*$ .
- The coordinate representation of  $v^* \in V^*$  with respect to  $A^*$  is  $(v^*(a_1), \dots, v^*(a_n)) \in \mathbb{R}^n$ .

## Inner products

An *inner product* on a real vector space  $V$  is a symmetric, positive definite, bilinear form, i.e. a map  $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$  such that

- $\langle v, v \rangle \geq 0$  with equality only when  $v = 0$  (positive definiteness)
- $\langle v, w \rangle = \langle w, v \rangle$  (symmetry)
- For any  $v \in V$ , the maps  $\langle v, \cdot \rangle : V \rightarrow \mathbb{R}$  and  $\langle \cdot, v \rangle : V \rightarrow \mathbb{R}$  are linear (bilinearity). Thus

$$\langle v, \alpha w_1 + \beta w_2 \rangle = \alpha \langle v, w_1 \rangle + \beta \langle v, w_2 \rangle$$

$$\langle \alpha w_1 + \beta w_2, v \rangle = \alpha \langle w_1, v \rangle + \beta \langle w_2, v \rangle$$

## Inner products and linear functionals on $\mathbb{R}^n$

For  $v, w \in \mathbb{R}^n$ , define  $\langle v, w \rangle = \sum_{i=1}^n v_i w_i$ .

- If  $v \in \mathbb{R}^n$  then  $v^* = \langle \cdot, v \rangle \in (\mathbb{R}^n)^*$ .
- If  $v^*$  in  $(\mathbb{R}^n)^*$  then there exists  $v \in \mathbb{R}^n$  such that  $v^* = \langle \cdot, v \rangle$
- $\mathbb{R}^n \cong (\mathbb{R}^n)^*$  with the isomorphism given by  $v \rightarrow \langle \cdot, v \rangle$
- The kernel of  $v^*$  is the subspace of  $\mathbb{R}^n$  *orthogonal* to  $v$ .
- Inner products impart geometry

## Row vectors are linear functionals

Let  $v \in \mathbb{R}^n$ , viewed as a column vector. Then  $v^T$  is the corresponding row vector.

$$v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \implies v^T = (v_1, \dots, v_n)$$

- $v^T w = \sum_{i=1}^n v_i w_i = v_j w_j = \langle v, w \rangle$
- $v \in \mathbb{R}^n$  implies  $v^T \in (\mathbb{R}^n)^*$



## Linear maps are columns of linear functionals

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be any function.

- $f(x) = \begin{pmatrix} f^1(x) \\ \vdots \\ f^m(x) \end{pmatrix}$  where  $f^i : \mathbb{R}^n \rightarrow \mathbb{R}$
- If  $f$  is linear then  $f^i$  is a linear functional
- If  $f$  is linear then  $f$  is a column vector of row vectors

## Matrices are linear maps

Let  $A = \{a_1, \dots, a_n\}$  and  $B = \{b_1, \dots, b_m\}$  be bases of  $V$  and  $W$  respectively. Let  $T : V \rightarrow W$  be linear.

Define the  $m \times n$  matrix  $\beta(T)$  as follows: for  $1 \leq j \leq n$ , the  $j^{\text{th}}$ -column of  $\beta(T)$  is the coordinate representation of  $T(a_j) \in \mathbb{R}^m$  against the basis  $B$ :  $T(a_j) = \sum_{i=1}^m \beta(T)_{ij} b_i$ . Then

$$\begin{aligned} T(v) &= T\left(\sum_{j=1}^n \alpha_j^v a_j\right) = \sum_{j=1}^n \alpha_j^v T(a_j) \\ &= \sum_{j=1}^n \alpha_j^v \left(\sum_{i=1}^m \beta(T)_{ij} b_i\right) = \sum_{i=1}^m \left(\sum_{j=1}^n \beta(T)_{ij} \alpha_j^v\right) b_i \end{aligned}$$

Thus the coordinate representation of  $T(v)$  against  $B$  is  $\beta(T)\alpha^v$ .

## Matrices as linear maps

Matrices are exactly linear maps represented against bases

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \varphi_A \downarrow & & \uparrow \varphi_B^{-1} \\ \mathbb{R}^n & \xrightarrow{\beta(T)\alpha^v} & \mathbb{R}^m \end{array}$$

Here  $\varphi_A$  and  $\varphi_B$  are the canonical isomorphisms and  $\beta(T)\alpha^v$  is obtained by the matrix multiplication.

In particular, matrix multiplication is composition of linear maps.

## The Transpose

**Definition.** The *transpose*  $A^T$  of an  $m \times n$  matrix  $A$  is an  $n \times m$  is given by  $a_{ij}^T = a_{ji}$ .

- If  $v \in \mathbb{R}$  is viewed as a column matrix then  $v^T$  can be viewed as a row matrix
- Under matrix multiplication, a row vector is a linear functional.
- $\langle v, w \rangle = v^T w$ .

## The Transpose

If  $S : V \rightarrow W$  then  $S^* : W^* \rightarrow V^*$  is given by  $S^*(w^*)(v) = w^*(S(v))$ .

The following diagram commutes:

$$\begin{array}{ccc} V & \xrightarrow{S} & W \\ \uparrow \phi_V & & \uparrow \phi_W \\ V^* & \xleftarrow{S^*} & W^* \end{array}$$

Fixing bases,  $\beta(S)^T = \beta(S^*)$ .

## The Determinant

The *determinant* is a map  $\det : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  that is magical:

- $\det(I_n) = 1$
- $\det(AB) = \det(A) \det(B)$
- $\det(\alpha A) = \alpha^n \det(A)$

There are two very important points worth emphasizing

- the determinant is a polynomial of degree  $n$  in its entries
- because it is a polynomial in its entries, the determinant is computable

## The Determinant

There are two ways to compute the determinant: geometrically, and using eigenvalues

Geometry.

- Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a linear function (square matrix) and let  $S \subset \mathbb{R}^n$  be the unit cube, that is,  $S = [0, 1]^n$
- Because  $T$  is linear, the image of  $S$  under  $T$  is an  $m$ -dimensional parallelepiped, where  $m$  is the rank of  $T$ .
- The determinant of  $T$  is the signed volume of this parallelepiped.
- By the RNT,  $\det(T) = 0 \Leftrightarrow \dim(\ker(T)) > 0$

## The Determinant

### Eigenvalues.

- Recall that  $\lambda \in \mathbb{R}$  is an eigenvalue of  $T$  provided there is  $v \neq 0$  such that  $T(v) = \lambda v$ , or  $(T - \lambda I_n)(v) = 0$ .
- Thus  $\dim \ker(T - \lambda I_n) > 0$ , whence  $\phi_T(\lambda) \equiv \det(T - \lambda I_n) = 0$
- $\phi_T(\lambda)$  is the *characteristic polynomial* of  $T$
- The eigenvalues of  $T$  are the roots of this polynomial, and may be complex.



## The Determinant

- $\phi_T(\lambda) \equiv \det(T - \lambda I_n)$
- Every  $n \times n$  matrix has exactly  $n$  eigenvalues corresponding to the  $n$  roots of the characteristic polynomial
- The determinant of  $T$  is equal to the product of the eigenvalues
- $\det(T) = 0$  iff zero is an eigenvalue of  $T$

## Invertibility

Given sets  $X$  and  $Y$ , let  $f : X \rightarrow Y$  be any map.

- $f$  is *injective* if  $f(x_1) = f(x_2)$  implies  $x_1 = x_2$
- $f$  is surjective provided that for any  $y \in Y$  there is an  $x \in X$  so that  $y = f(x)$
- a function that is both surjective and injective is *bijective*
- *Bijectivity is necessary and sufficient for invertibility of a linear map*
- *If  $\dim V < \infty$  then linear map from  $V$  to  $V$  is invertible if and only if its nullity is zero.*

## Invertibility

A matrix is invertible provided that the associated linear map is invertible

**Theorem 3.2** A square matrix is invertible if and only if its determinant is non-zero

Why is this theorem so important?

## Column and Row Space

Let  $M \in \mathbb{R}^{m \times n}$ , and denote by  $\{M^i\}_{i=1}^m \subset \mathbb{R}^n$  the rows of  $M$  (but “written” as column vectors), and by  $\{M_j\}_{j=1}^n \subset \mathbb{R}^m$  the columns of  $M$ .

- the **row space** of  $M$  is  $\text{span}(\{M^i\}_{i=1}^m)$
- the **column space** of  $M$  is  $\text{span}(\{M_j\}_{j=1}^n)$
- the columns of  $M$  span the range of the associated linear map
- the dimension of the column and row space are equal

## Column and Row Space

Let  $T : V \rightarrow W$  linear.

$$\begin{aligned} \dim \text{ of row space of } \beta(T) &= \dim \text{ of column space of } \beta(T)^T \\ &= \dim(T^*(W^*)) \\ &= \dim(T(V)) \\ &= \dim \text{ of column space of } \beta(T) \end{aligned}$$

## Coordinate Transforms

Let  $V$  be a vector space with bases for  $A = \{a_1, \dots, a_n\}$  and  $B = \{b_1, \dots, b_n\}$

- For  $v \in V$ ,  $\alpha^v$  and  $\beta^v$  are the coordinate representations of  $v$  against  $A$  and  $B$
- $\beta(A, B)$  is the  $n \times n$  matrix with columns as the coordinate representations of the elements of  $A$  against the basis  $B$ .
- $\beta^v = \beta(A, B)\alpha^v$

## Coordinate Transforms

Two matrices  $P$  and  $Q$  are *similar* if there is  $S$  so that  $Q = SPS^{-1}$

- Let  $V$  have bases  $A$  and  $B$  and let  $T : V \rightarrow V$  be linear.
- Let  $M(T,A)$  and  $M(T,B)$  be the matrix representations of  $T$  against  $A$  and  $B$ . Then

$$M(T,B) = \beta(A,B)M(T,A)\beta(A,B)^{-1}.$$

## Coordinate Transforms

Let  $M$  be a  $n \times n$  representing  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  against the canonical basis.

- Suppose  $M$  has  $n$  linearly independent eigenvectors  $\Xi = \{\xi_1, \dots, \xi_n\}$  and associated eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$ .
- Let  $S$  be the matrix whose columns are the  $\xi_i$
- Let  $\Lambda$  be the matrix representation of  $T$  against  $\Xi$
- $M = S\Lambda S^{-1}$ , so  $\Lambda = S^{-1}MS$ .
- $\Lambda$  is a diagonal matrix, and the diagonal elements correspond to the eigenvalues of  $M$ .



## Coordinate Transforms

The product  $S\Lambda S^{-1}$  is an **eigenvalue decomposition** of  $M$

- When an eigenvalue decomposition exists, the matrix is said to be diagonalizable, i.e. similar to a diagonal matrix
- Not all matrices are diagonalizable

**Theorem 3.3** If  $M \in \mathbb{R}^{n \times n}$  had  $n$  distinct eigenvalues then  $M$  is diagonalizable