## Math Camp

# Module #1 Vector spaces and linear maps Part I: enacting peace

"The introduction of numbers as coordinates is an act of violence."  $_{\rm H~Wevl}$ 

$$\begin{array}{ccc}
\alpha_{1} \subset X \\
\exists x_{1} \in X \\
x_{1} \notin \alpha_{1}
\end{array}$$

#### Why vector spaces?

Economics is a multivariate affair...

- trade offs only occur when there are two or more outcomes
- linear (or vector) spaces are the simplest environment capable of handling multi-dimensional problems
- start abstract: no reference yet to bases, dimension or coordinates

## Vector spaces and direct sums

v, weV. v+weV

Definition A vector space is a <u>set V</u> that is closed <u>under</u> addition, and <u>under scalar multiplication</u> by elements of  $\mathbb{R}$ 

they are related by the distributed property:

$$\alpha \in \mathbb{R}, v, w \in V \Rightarrow \alpha(v+w) = \alpha v + \alpha w$$

• *V* contains a special element:

• More generally, could be any field.

#### Vector spaces and direct sums

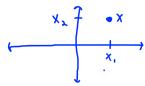
• If V and W are vector spaces then  $V \oplus W$  is the Cartesian product of V and W such that

$$\circ \ \underline{x \in V \oplus W} \text{ implies } \underline{x} = (\underline{v_x}, \underline{w_x}), \text{ with } v_x \in \underline{V}, w_x \in W$$

$$\circ \ x + y = (\underline{v_x} + \underline{w_x}, v_y + \underline{v_y}) = (\underline{v_x} + \underline{v_y}, \underline{u_x} + \underline{w_y})$$

• Q: what is  $\mathbb{R} \oplus \mathbb{R}$ ?

$$x = (x, , X_2)$$



## Spans and subsets



Definition. A <u>subspace</u> W of V is a subset of V that is, itself, a vector space.

Definition. If  $A \subset V$  then the <u>span</u> of A is the set of all finite linear combinations of elements of A:

$$\operatorname{span}(A) = \left\{ \sum_{k=1}^m \alpha_{\underline{k}} a_{\underline{k}} \text{ such that } m \in \mathbb{N}, \underline{\alpha_k \in \mathbb{R}}, \underline{a_k \in A} \right\}$$

• span(A) is the smallest subspace of V containing A.

$$A \subset V$$
 span  $(A) = \alpha \binom{a_1}{a_2} + B\binom{b_1}{b_2}$ 

$$A = \left\{ \binom{a_1}{a_2}, \binom{b_1}{b_2} \right\}$$

$$\Delta = \{\alpha_1, \alpha_2, \alpha_3\}$$
  
Linear Independence and bases  $\alpha_1, \alpha_2, \alpha_3$ 

Definition.  $\underline{A} \subset V$  is *linearly independent* if no element of A can be written as a finite linear combination of other elements of A.

More formally, A is linearly independent if whenever

$$\{a_1,...,a_n\}\subset A \text{ and } \sum_{k=1}^n\alpha_ka_k=0$$
 it follows that  $\alpha_k=0$  for  $k=1,...n$ . B:  $\{\binom{1}{0},\binom{0}{1}\}$ 

Definition. A <u>basis</u> of V is a linearly independent set  $\underline{B} \subset V$  that spans V.

Linear Independence and bases

Theorem (Fundamental theorem of linear algebra)

if  $A = \{a_1,...,a_n\} \subset V$  is a basis for V and  $B = \{b_1,...,b_m\} \subset V$  is linearly independent then  $m \leq n$ 

#### **Dimension**

If  $B \subset V$  is a basis then  $\dim V = |B|$ .

Let  $\dim V = n$ . Then

- If B ⊂ V is linearly independent then B is a basis for span(B) and dim span(B) = |B|.
- If  $B \subset V$  is linearly independent and |B| = m < n then there exists  $C \subset V$  so that  $B \cup C$  is a basis for V.
- If W is a subspace of V then  $\dim(W) \leq \dim(V)$ .

#### Linear functions

Category Theory: everything is objects and arrows

In the category of linear spaces,

- objects are vector spaces
- arrows are linear maps

**Definition.** If V and W are vector spaces then a map  $f:V\to W$  is *linear* provided

$$f(\alpha v_1 + \beta v_2) = \alpha f(v_1) + \beta f(v_2)$$

#### Linear functions

Definition. A linear map is an *isomorphism* if it is invertible.

If there is an isomorphism between the vector spaces V and W then we say that V and W are *isomorphic*, written  $V \cong W$ .

#### Linear functionals

**Definition**. A *linear functional*  $\alpha$  on V is a linear map  $\alpha: V \to \mathbb{R}$ .

- The set of linear functionals,  $V^*$ , called the *dual space*
- V\* is a vector space
- If  $\dim V < \infty$  the  $V^* \cong V$ .

#### Linear functions

Let  $f: V \to W$  be a linear map.

Definition. The *kernel (or nullspace)* of f is the collection of vectors that f sends to zero:

$$ker(f) = \{v \in V : f(v) = 0\} \subset W$$

- ker(f) is a subspace of V
- The *nullity* of *f* is the dimension of its kernel

#### Linear functions

**Definition.** The *range* of f is the image of V in W under f:

$$f(V) = \{ w \in W : \exists v \in V \text{ with } f(v) = w \} \subset W$$

- The range of *f* is a subspace of *W*
- The rank of f is the dimension of the range

#### **Linear Functions**

**Rank Nullity Theorem**: if V is finite dimensional and  $f: V \to W$  is a linear map then the rank of f plus the nullity of f equals the dimension of V

$$\dim ker(f) + \dim f(V) = \dim V$$

#### Information and nullity

Let  $f: V \to W$  b a linear map. Define the following relation on V:

$$v_1 \sim v_2 \iff f(v_1) = f(v_2) \text{ i.e. } v_1 - v_2 \in ker(f)$$

- ullet  $\sim$  is an equivalence relation
- ullet  $\sim$  measures the information lost by f

#### Linear extensions

Let V and W be vector spaces and  $B\subset V$  a basis. Let  $\phi:B\to W$  be any function. Then there exists unique linear map  $\Phi:V\to W$  such that the following diagram commutes:



Let  $B = \{b_1, \dots, b_n\}$  be a basis for V and  $\{w_1, \dots, w_n\} \subset W$ . Define a linear map  $\Phi$  from V to W by sending  $b_i$  to  $\phi(b_i) = w_i$ , and *extending linearly:* 

$$v = \sum_{k=1}^{n} \beta_k b_k \to \sum_{k=1}^{n} \beta_k \phi(b_k) = \sum_{k=1}^{n} \beta_k w_k \equiv \Phi(v).$$

#### Linear extensions

Let V and W be vector spaces and  $B \subset V$  a basis. Let  $\phi : B \to W$  be *any* function. Then there exists unique linear map  $\Phi : V \to W$  such that the following diagram commutes:



Note that the behavior of linear map is entirely characterized by its behavior on a basis

Characterization of finite dimensions vector spaces

**Theorem.**  $\dim(V) = n \implies V \cong \mathbb{R}^n$ 

## Dynamics and Decompositions

Let dim V = n and  $f : V \to V$  be linear. Given  $v_0 \in V$ , define  $v_{t+1} = f(v_t)$ .

- The *dynamic f* traces a path/orbit in the vector space *V*.
- The orbits of f partition V.
- The subspace W ⊂ V is invariant (under the action of f) provide f(W) ⊂ W.

#### Dynamics and decompositions

**Theorem (Schur Decomposition)** Let  $\dim V = n$  and  $f: V \to V$  be linear. Then there is a collection of invariant subspaces  $\{V_k\}_{k=1}^n$  such that

$$\dim(V_k) = k$$
 and  $V_k \subset V_{k+1}$ 

## Dynamics and decompositions

Definition. The scalar  $\lambda \in \mathbb{R}$  of a linear map f is an eigenvalue provided there exists  $v \in V$  such that  $f(v) = \lambda v$ 

- v is called an associated eigenvector.
- if v is an eigenvector associated to  $\lambda$  then f scales v by  $\lambda$ .
- the collection of all eigenvectors associated with an eigenvalue is called the eigenspace.

## Eigenspace decomposition (greatest thing ever!)

#### The set up:

- $\dim V = m$  and  $f: V \to V$  linear
- $V(\lambda)$  is the eigenspace associated with  $\lambda$
- Assume the eigenvalues are distinct.

Then there is an isomorphism  $\phi: V \to \bigoplus_{i=1}^m V(\lambda_i)$  such that

