

Safeguarding Artificial Intelligence

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Newcastle
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**National
Edge AI
Hub**

Safeguarding AI



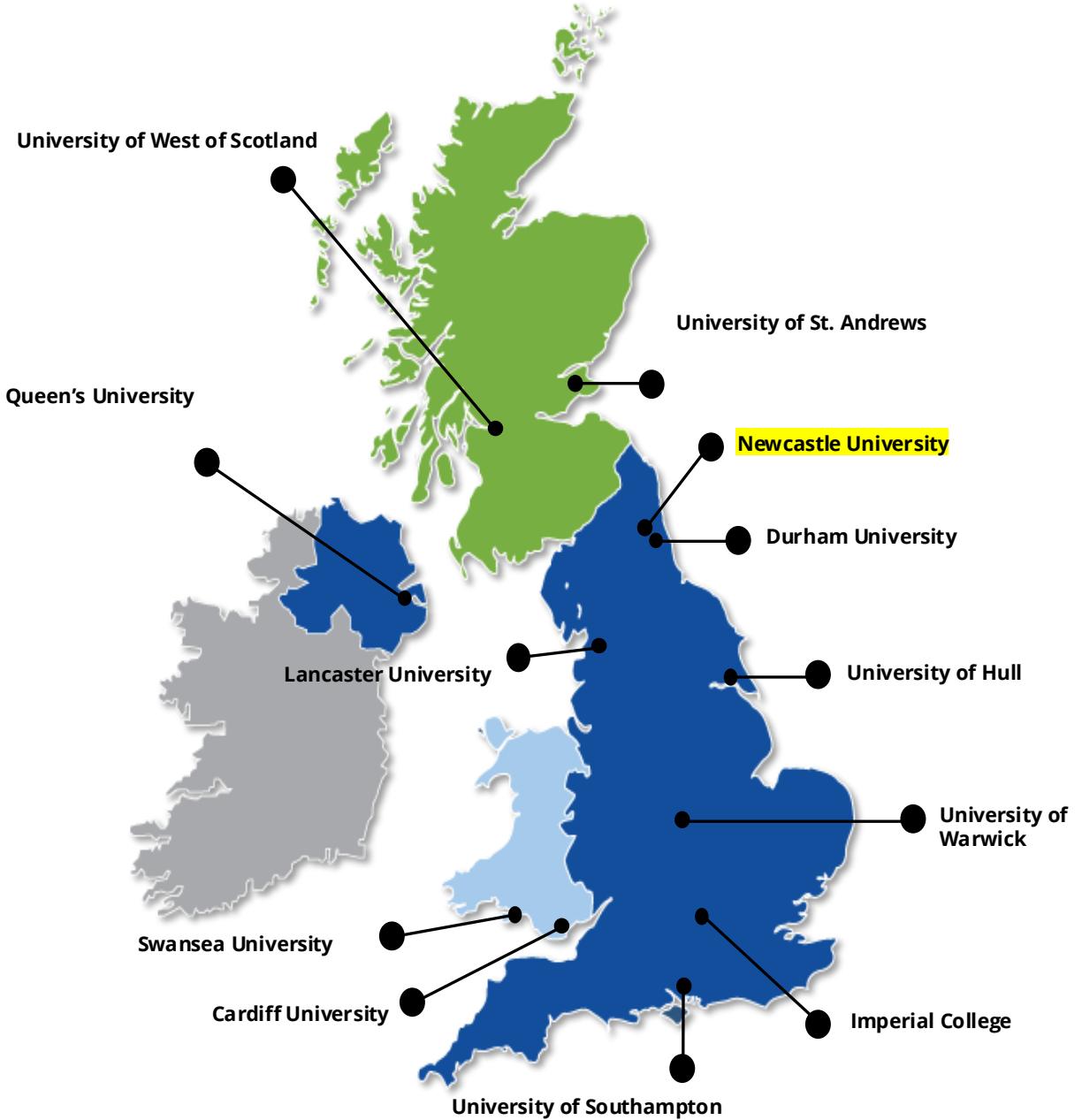
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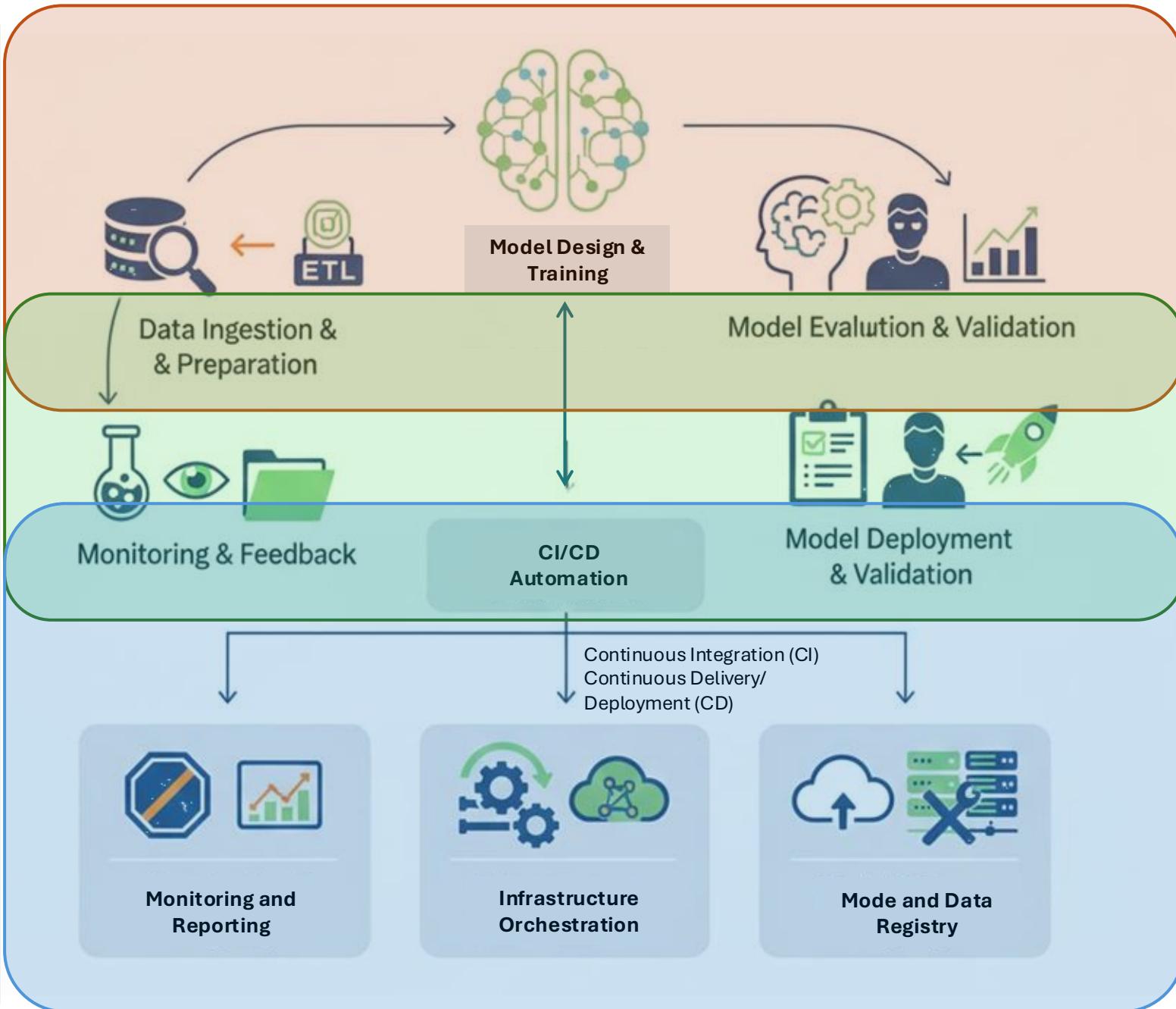
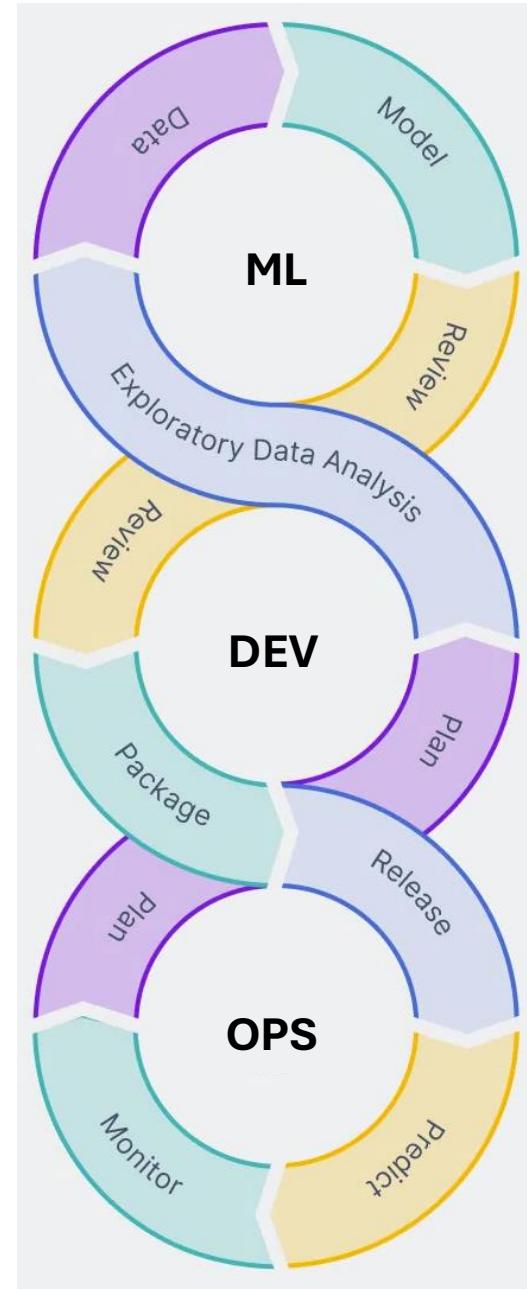
Safeguarding Artificial Intelligence

Agenda

- AI Safety Context
- Model Robustness
- Security and Privacy
- Continuity of Learning
- Broader Context of AI Safety and Challenges

Part 1

AI Safety Contexts



**Design &
Experimentation
(The Discovery
Phase)**

**Operations &
Monitoring
(The Maintenance
Phase)**

**CI/CD &
Automation
(The Factory
Phase)**

Security Vulnerabilities AI Models on the Edge

(The Fuel of AI)

Data Stage



Attacker sneakily adds bad or wrong data to the training set.

Data Poisoning



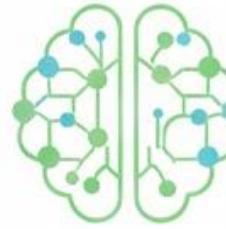
Data Leakage



The model learns the wrong rules and makes mistakes in production.

(The Brain of AI)

Model Stage



Attacker adds tiny, invisible changes to a new input To trick the model

Adversarial Attacks



Model Theft



bypass security systems or cause unsafe actions (e.g., in self-driving cars).

(The Factory of AI)

Pipeline/Infrastructure Stage



An attacker inserts malicious code into a harmless-looking software library or pre-trained model

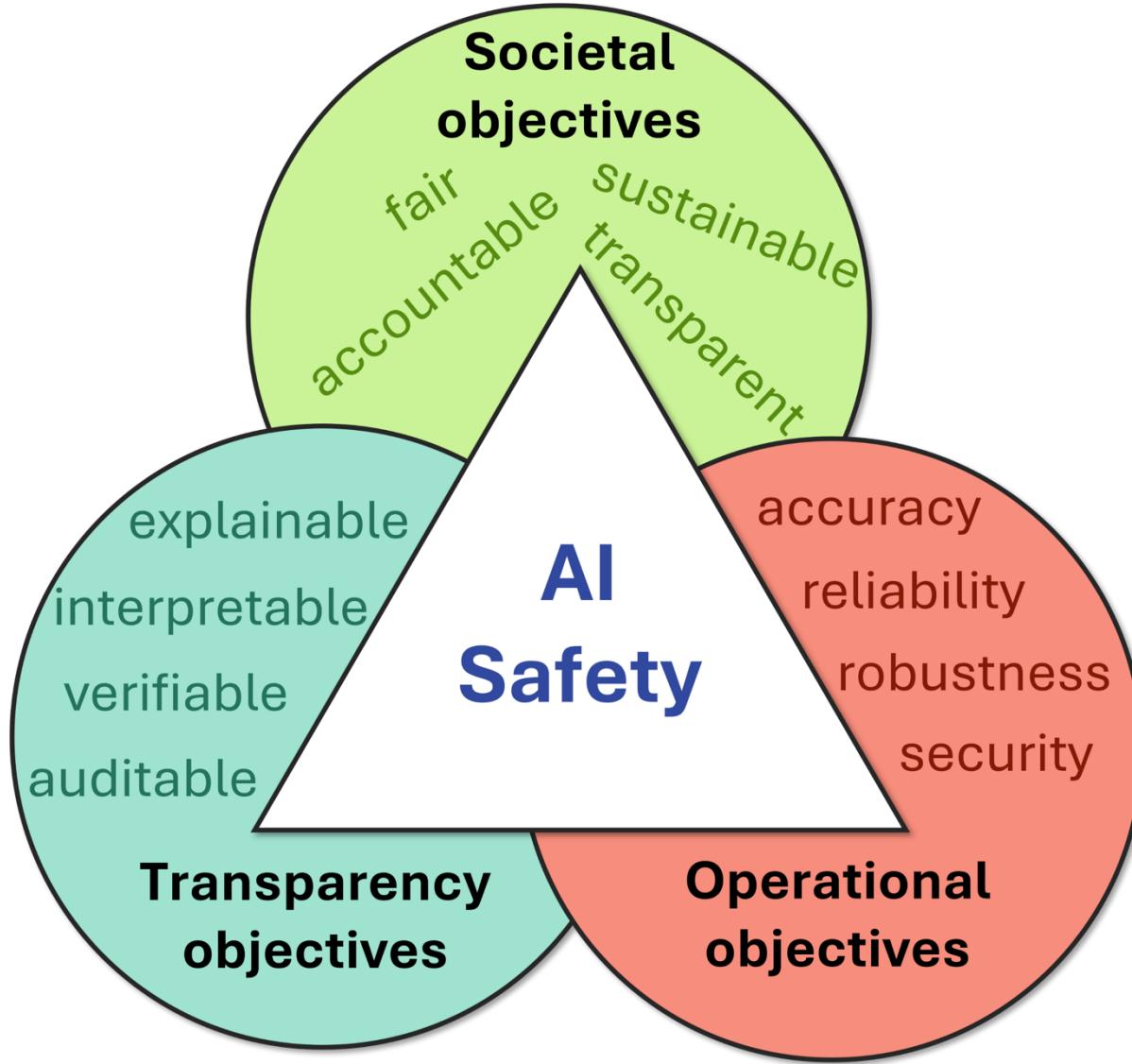
Supply Chain Attack

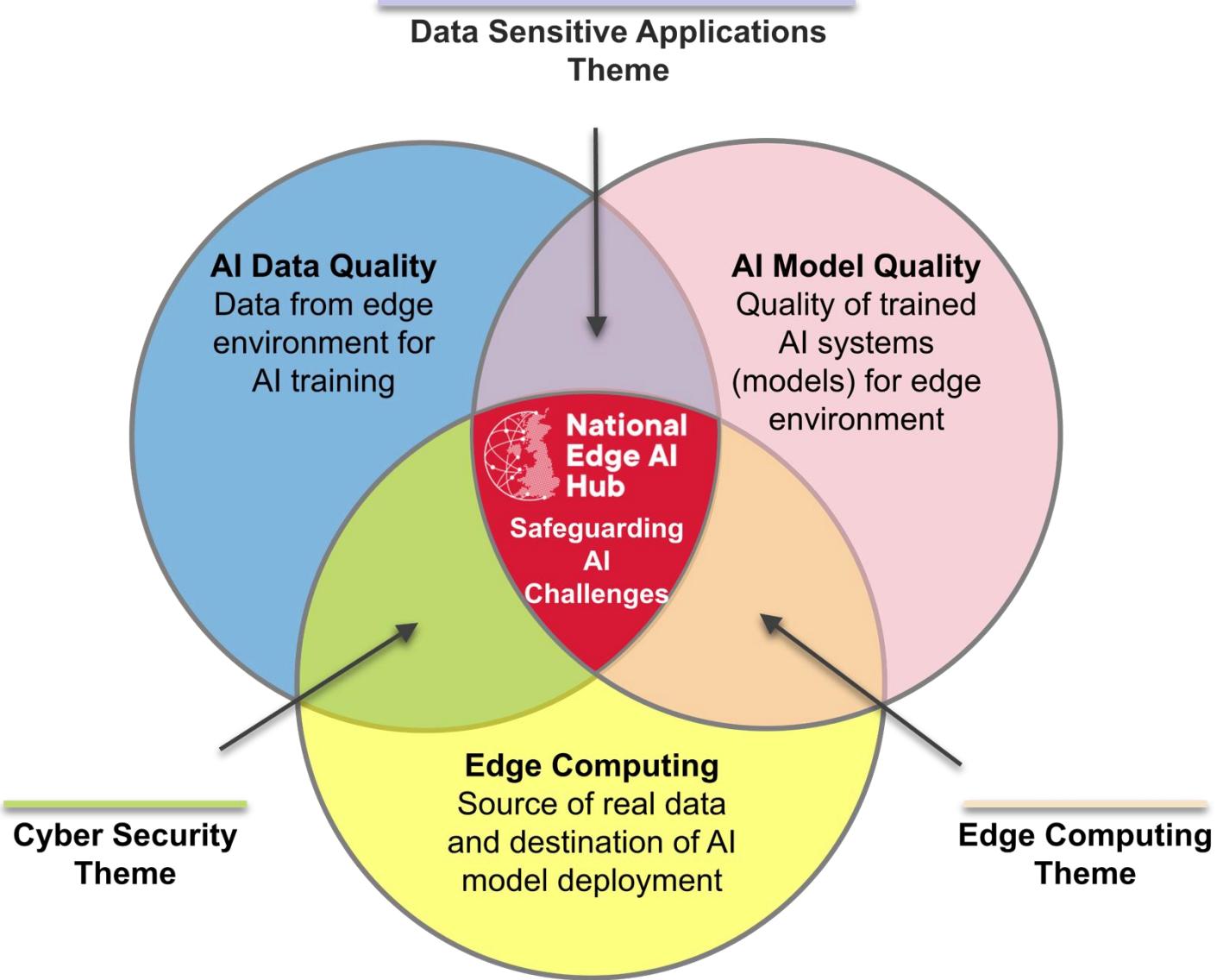


Configuration Errors



The entire MLOps system becomes infected and executes the hacker's code.





Safeguarding AI challenges

- **Monitoring of Data/Model Quality**

How to monitor cyber-disturbances impact on the quality of data, AI algorithms learning and the overall application resilience?

- **Recovery of Data/Model Quality**

How to recover data and AI model quality that are impacted by cyber-disturbances and ensure suitability for AI model deployment on devices at Tiers 1, 2 of EC architectures ?

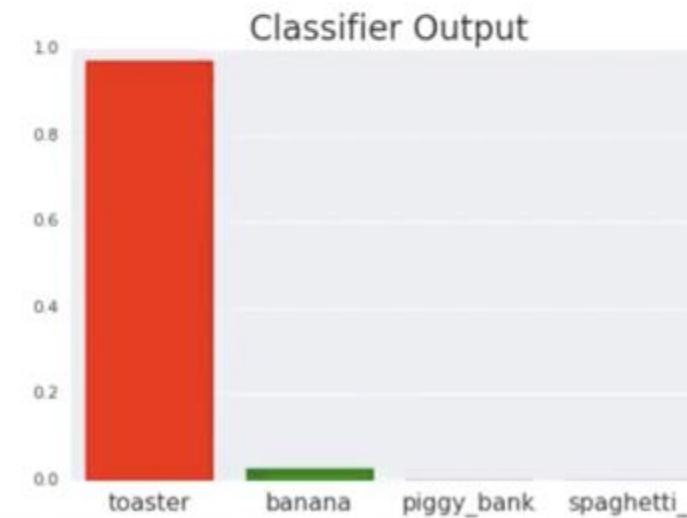
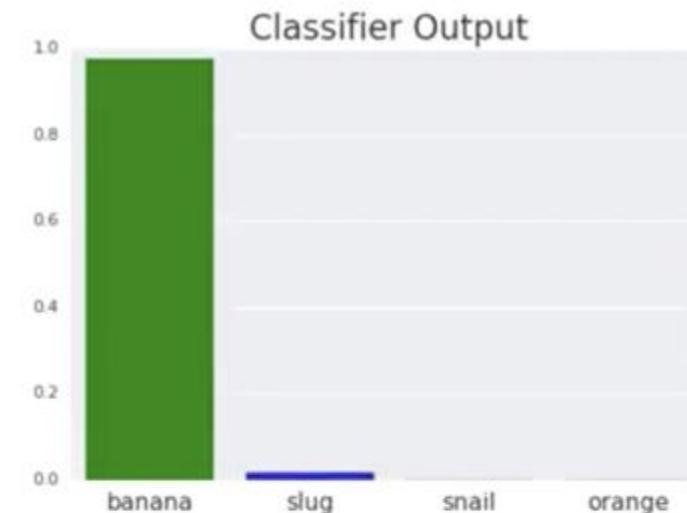
- **Assurance of Continuity of Data Quality and Model Quality**

How to assure AI algorithms continually adapt to EC environments where unknown cyber-disturbances that were not present in the original training dataset?

Part 2

Model Robustness

Adversarial Attacks



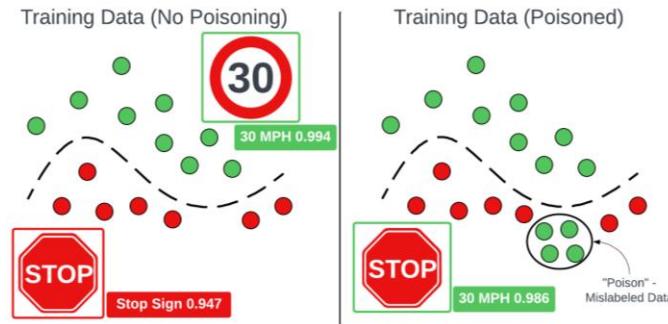
Consequences of Adversarial Attacks

Evasion Attacks



Attacks are designed to subtly alter inputs to mislead AI models during inference, causing them to misclassify specific inputs

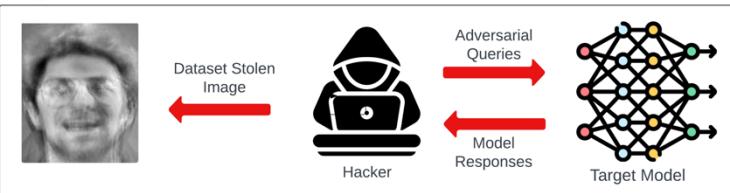
Poison Attacks



Attacks are designed to subtly alter the labels of training examples or inject anomalous data points; thus, **attackers can manipulate the model to favour certain outcomes or fail under specific conditions**

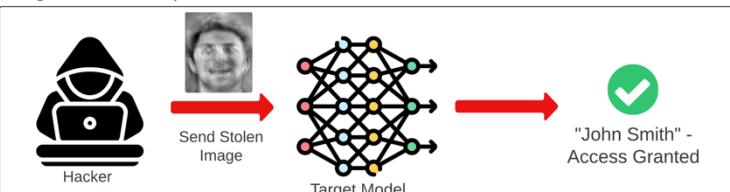
Inversion Attacks

Stage 1: Biometrics Theft



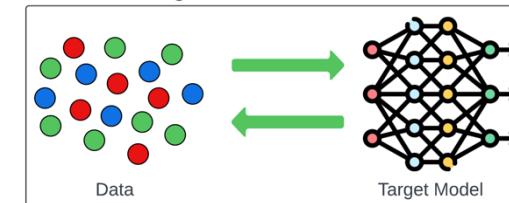
Attackers can deduce characteristics or even reconstruct portions of the original training dataset

Stage 2: Follow Up Attack



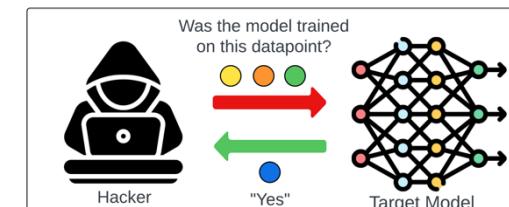
Inference Attacks

Model Training



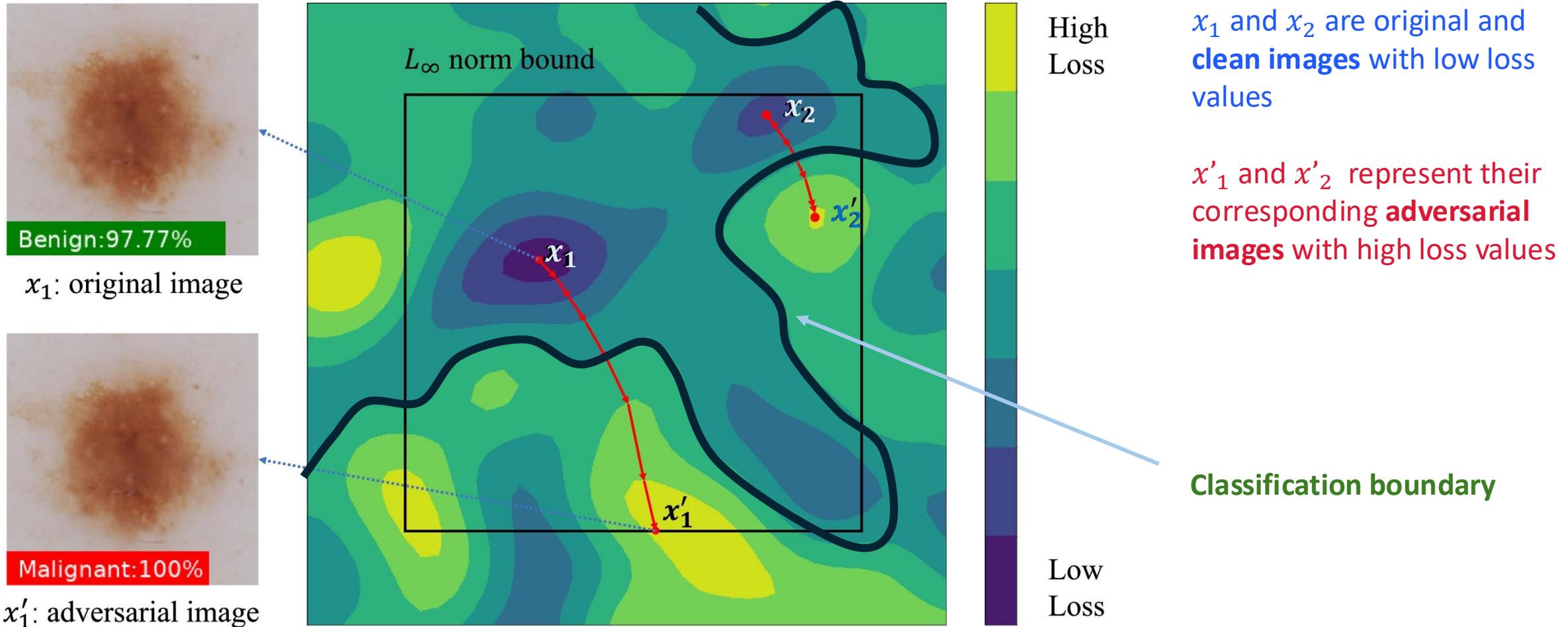
Adversary's attempts to **deduce sensitive information from an AI model by examining its outputs and behaviours**

Inference Attack



White box attack: Gradient based attacks

Attacks known the model (gradient/parameters) and carefully craft an attack on the model

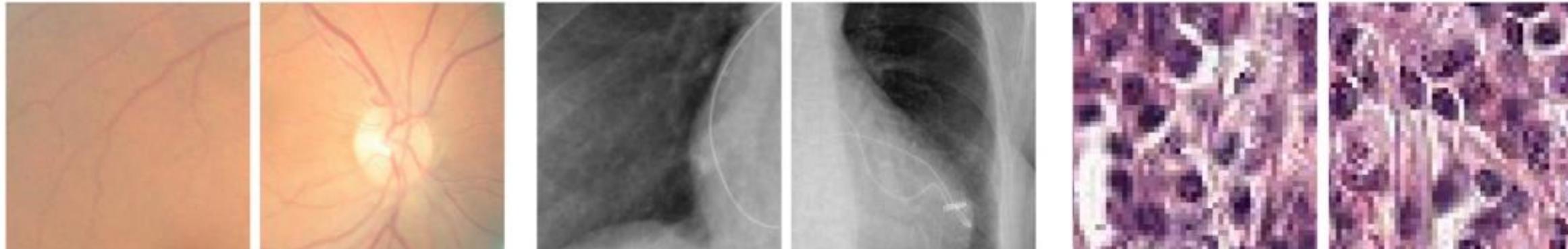


AI Safety Concern in Medical Image Analysis

Original Image



Adversarially Modified



Ophthalmology

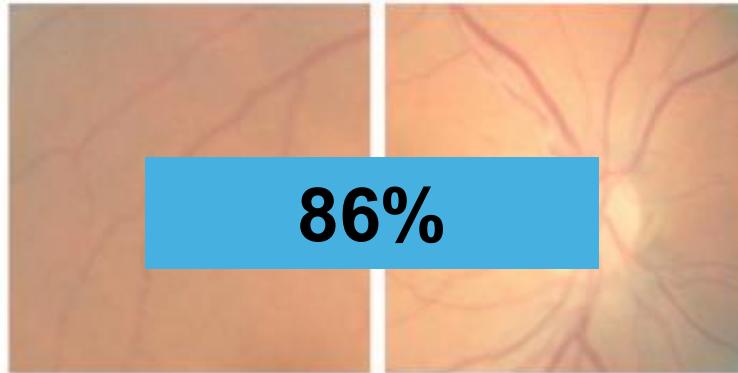
Radiology

Pathology

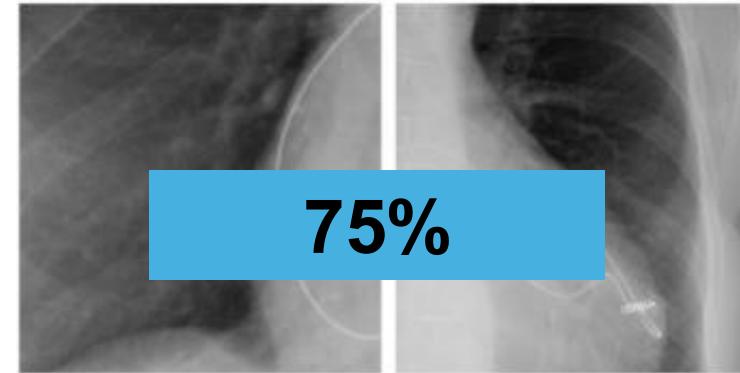
Unperceived changes in images make misclassification

AI Safety Concern in Medical Image Analysis

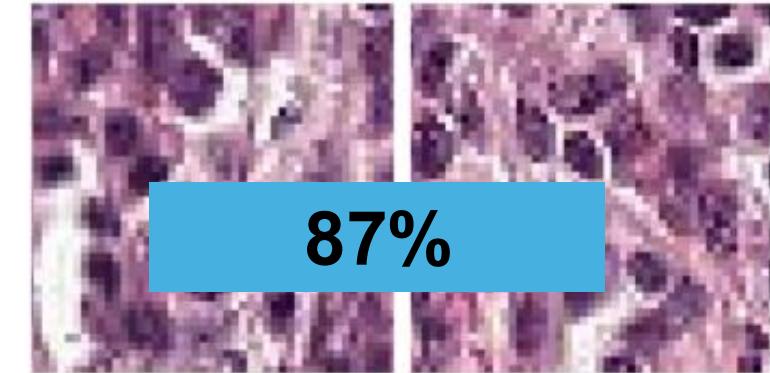
Original Image



86%

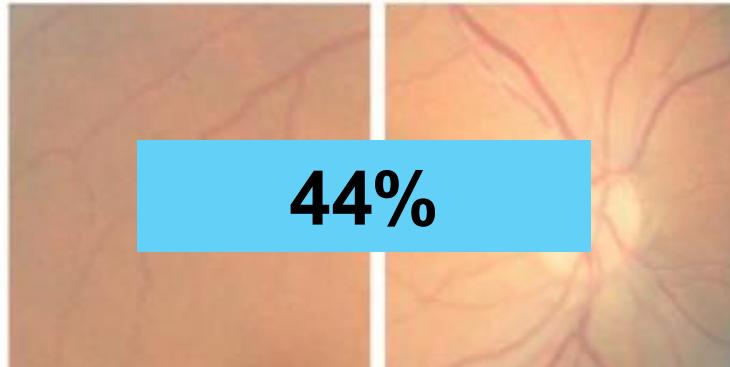


75%

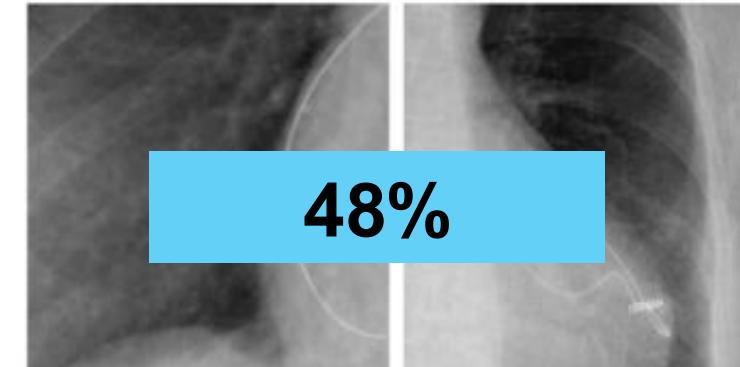


87%

Adversarially Modified



44%



48%



41%

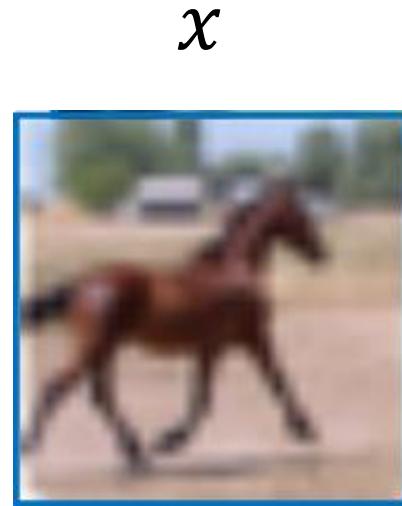
Ophthalmology

Radiology

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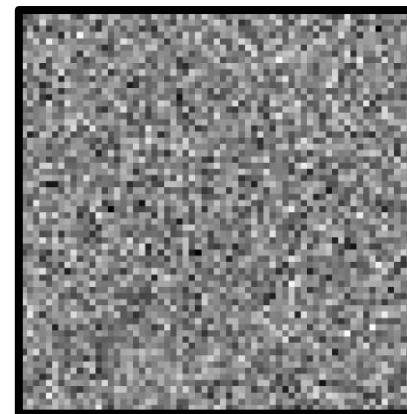
Accuracy of detection decreases even on an unperceived modification

Adversarial Robustness



Input example
Predicted as '**Horse**'

$$x + \epsilon * \text{Perturbation magnitude}$$



Adversarial perturbation
('**Plane**' class)

Calculated using Deep Neural Networks
(DNNs) weights (white-box attack)

δ

=

x_ϵ



Adversarial example
Predicted as '**Plane**'

The general premise of a robustness analysis is to subject DNNs to the '**worst case**' conditions and evaluate the **ability for a DNN to remain invariant** under such settings.

What can we promise for DNN robustness?

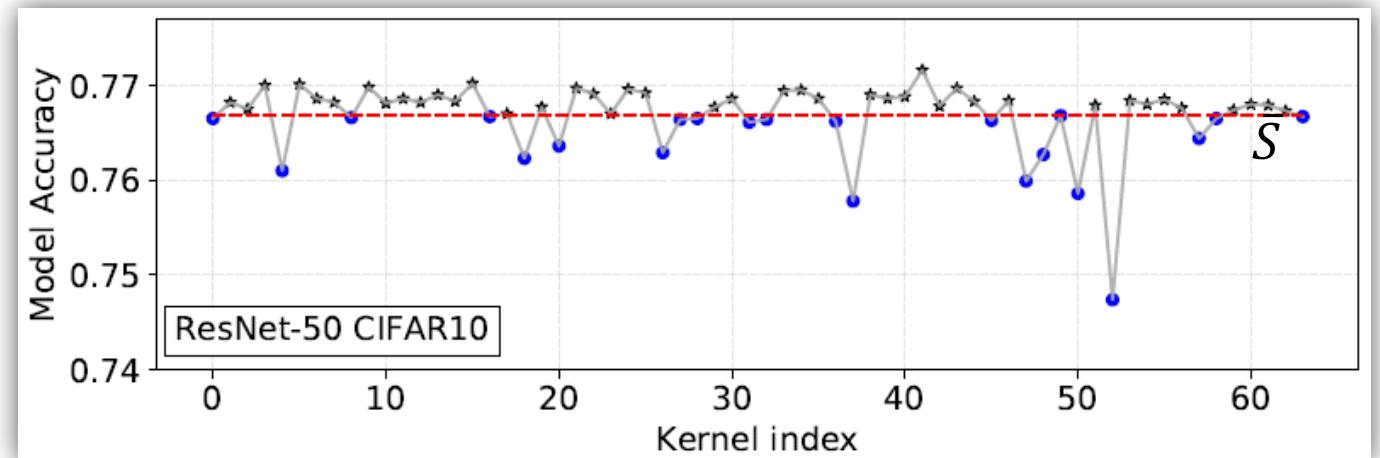
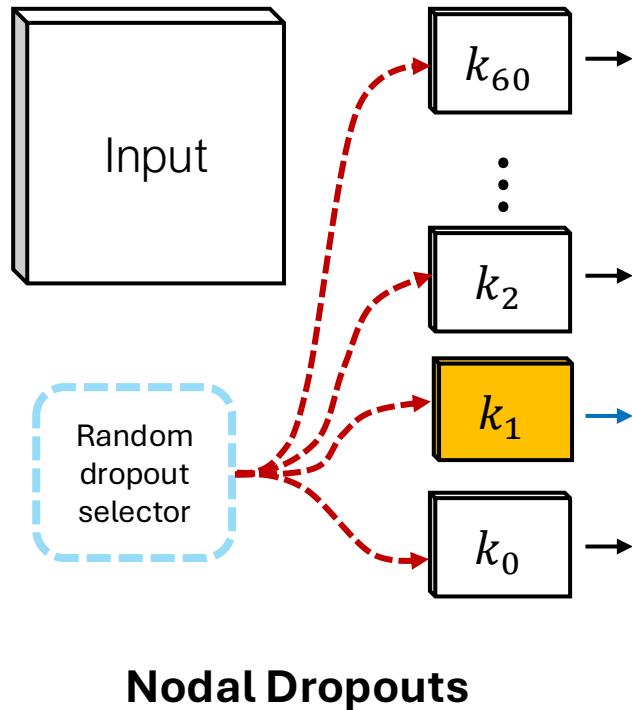
- We can use adversarial attacks to **identify the strengths and weaknesses** of DNN architectures.
- Upon identifying the strengths and weaknesses of DNN architectures **we can improve the performance of DNNs against both adversarial attacks** and the clean dataset.
- DNNs **robustness analysis can develop stronger networks** that are capable of performing under sub-optimal conditions.

Challenges for DNN robustness

- **DNNs are susceptible to adversarial attacks** and thus any DNN prediction can be unreliable and vulnerable to an adversary.
- **How each component of a DNN behaves due to an adversarial attack is a lesser-known area of research.**
- Adversarial attacks on DNNs has been well studies on state-of-the-art datasets, however, **adversarial attacks on DNNs and their remedies has rarely been studied extensively.**

Attacks on **fragile** neurons

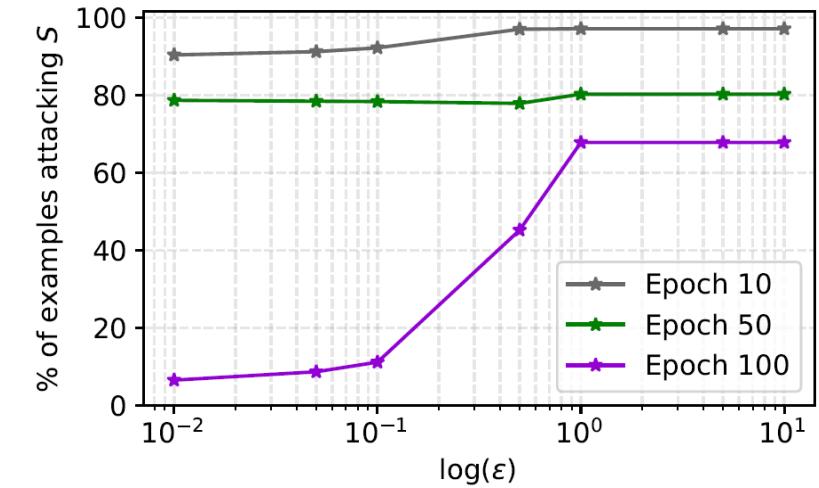
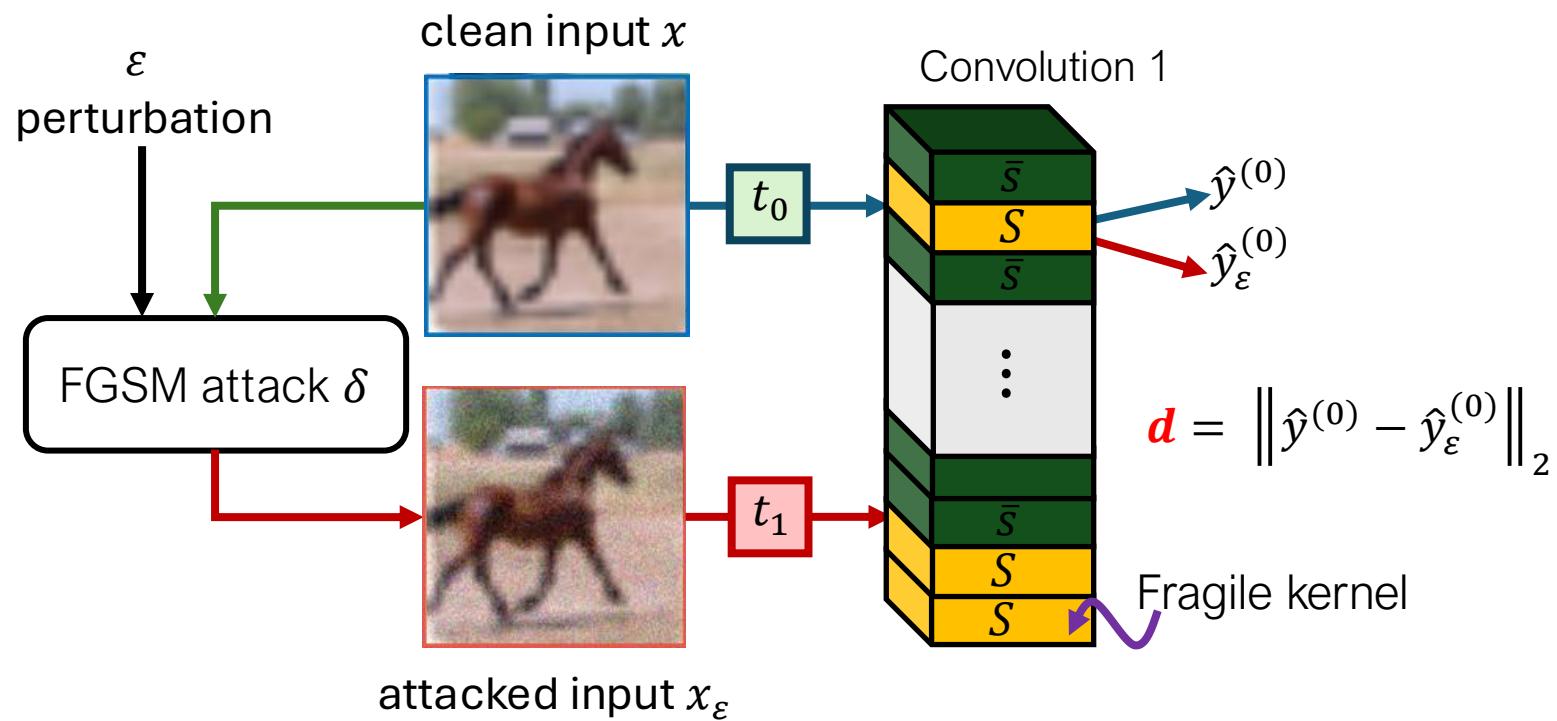
We remove kernel from the first convolutional layer and define **fragile nodes** to be all nodes that reduce the model performance on the test set to be below the mean dropout performance.



Fragile kernels (nodes) shown in blue (\bullet) below mean/baseline DNN performance line in red and null kernels are shown in black star (\star) above mean line in red

Adversarial targeting algorithm

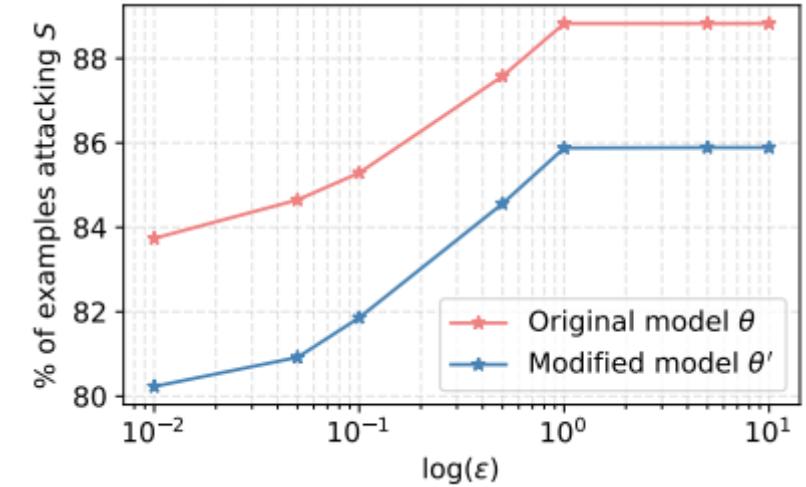
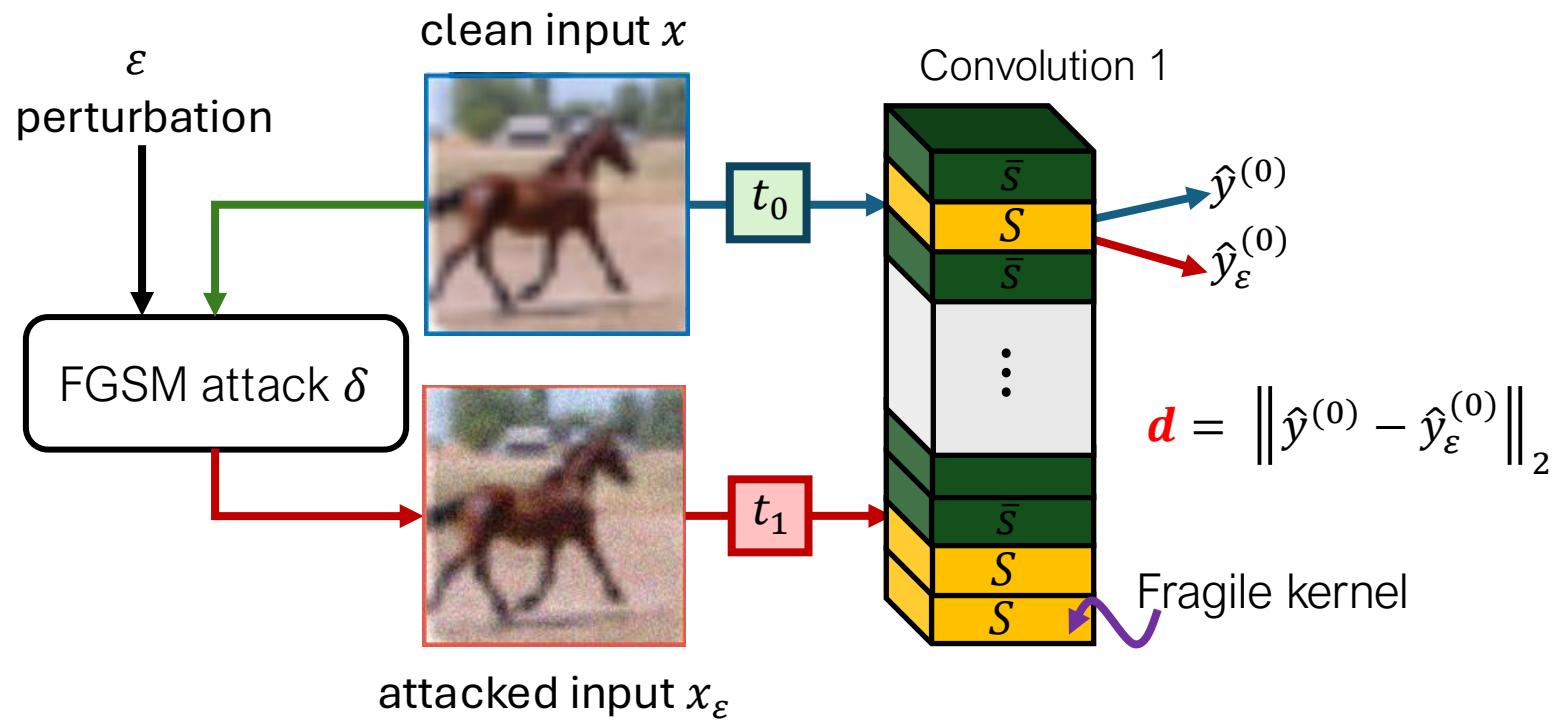
We measure the average magnitude difference \mathbf{d} at the output of the first convolutional layer, between fragile and non-fragile neurons, on both clean and adversarial inputs.



if avg. distance of fragile kernels S
greater than
avg. distance of non-fragile kernels \bar{S}
then
 x_ϵ attacks fragile kernels

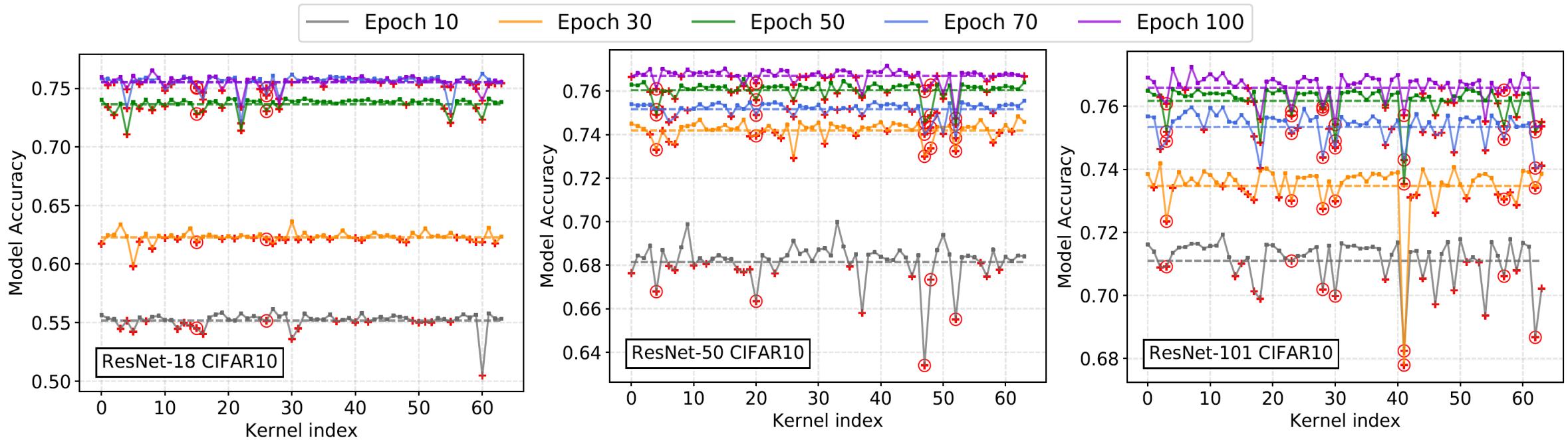
Adversarial targeting algorithm

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Fragile kernels / neurons

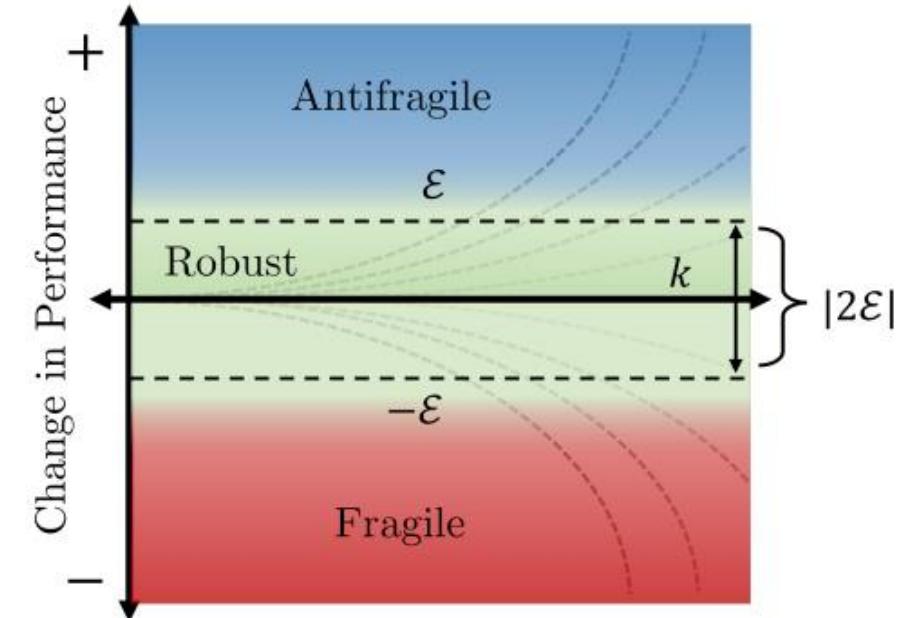
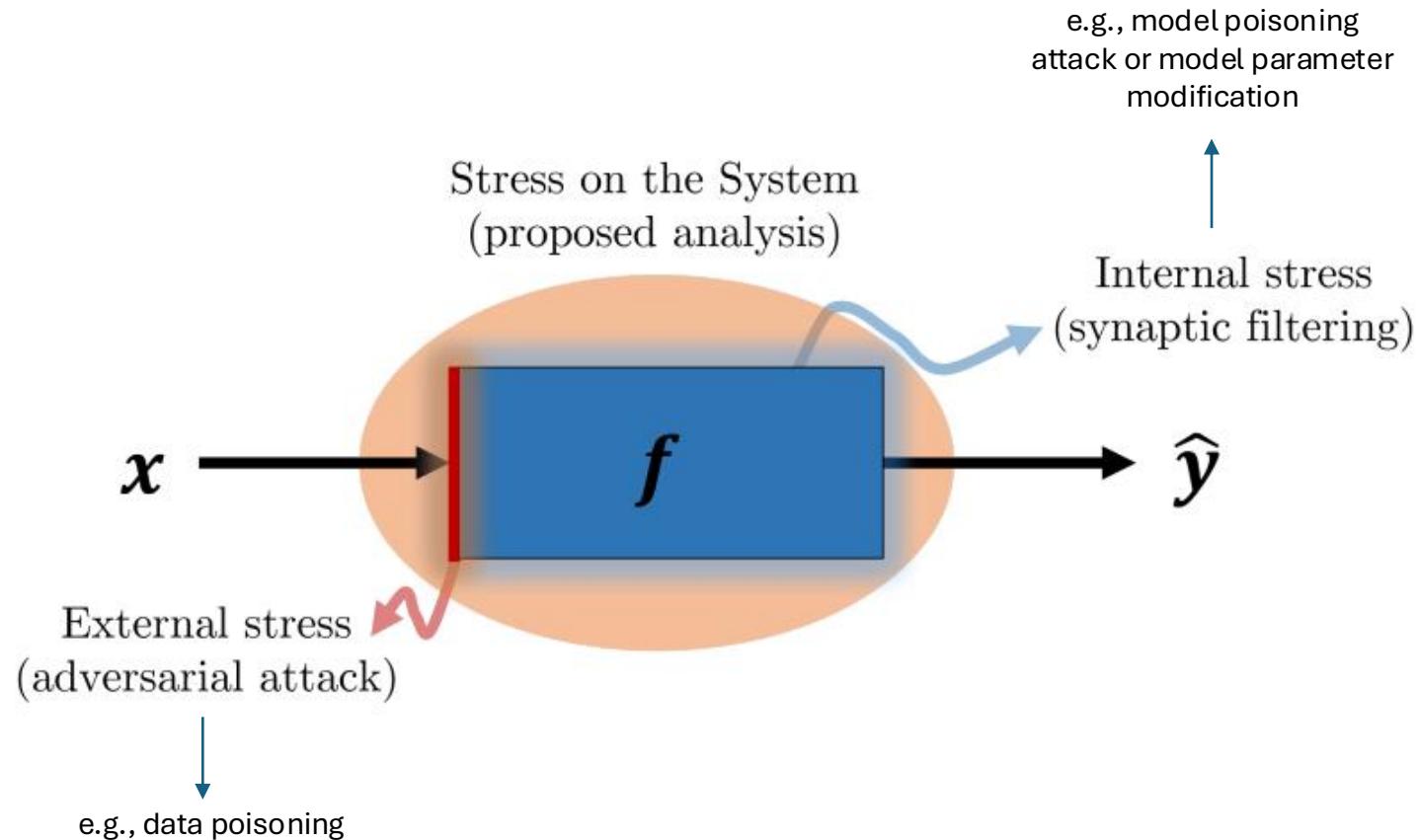


Red crosses (+) represent fragile kernels and red circles around red crosses (⊕) represent kernels that have shown to be consistently fragile throughout the training phase for each model.

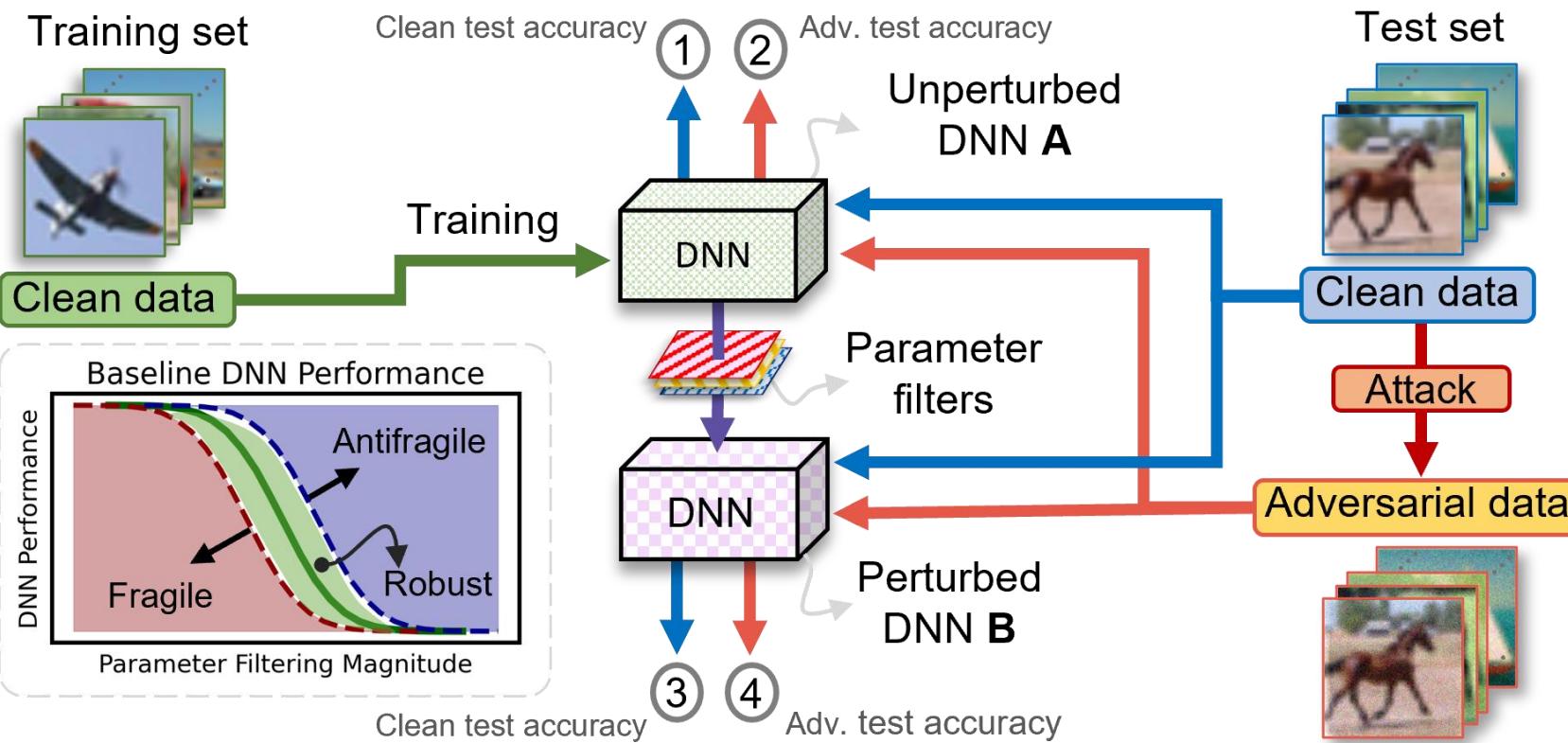
How can we ensure DNN robustness?

- Establish the **relationship between DNN parameters and adversarial attacks** to identify parameters that are targeted by the adversary.
- Formalise the notions of DNN parameter perturbations and adversarial attacks as **internal and external stressors on DNNs**.
- Define **fragility**, **robustness**, and **antifragility** in DNN to encapsulate parameter characterisations and
- Evaluate the effects of **only re-training parameters characterised as robust and antifragile (selective backpropagation)**.

Deep learning and systems



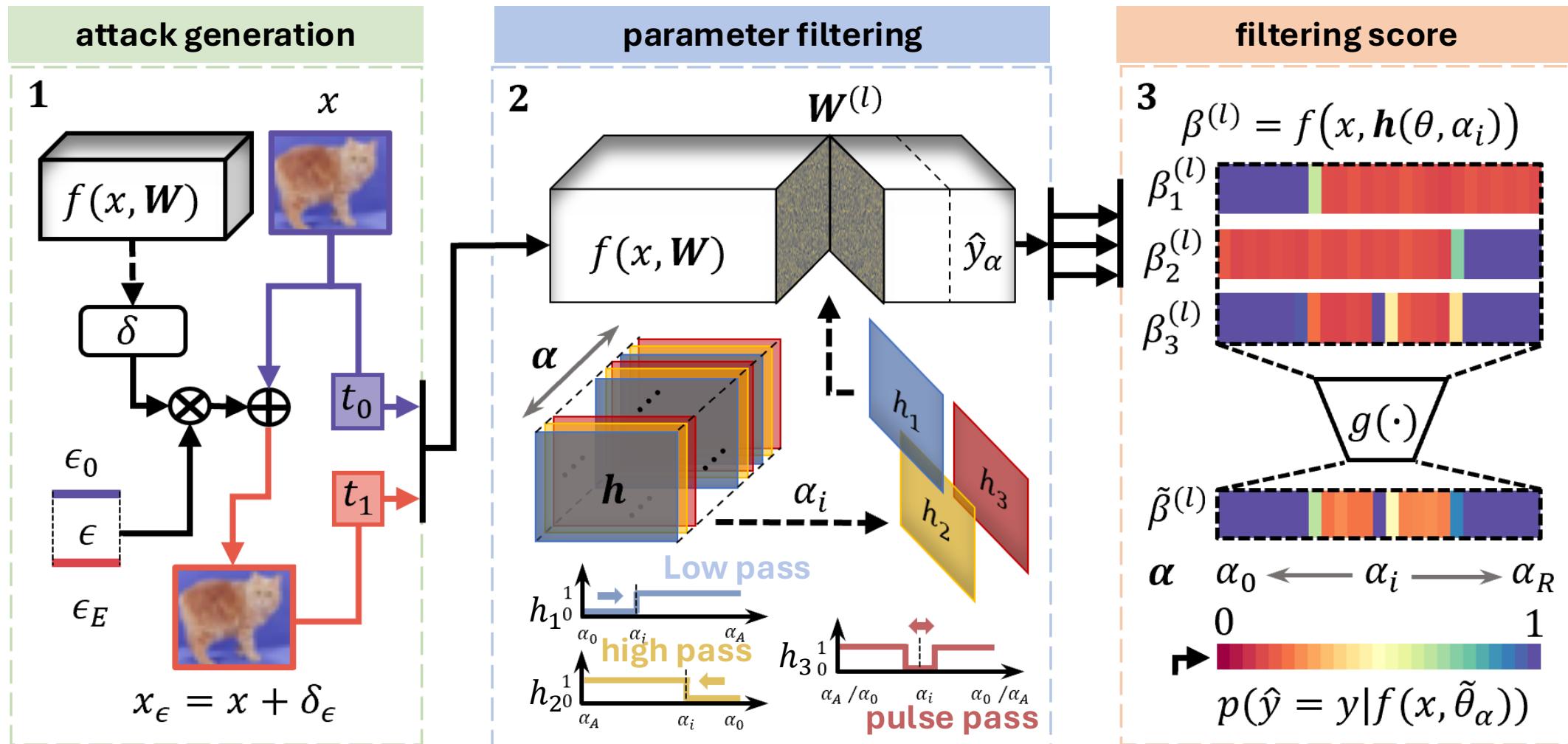
Fragility, robustness and antifragility



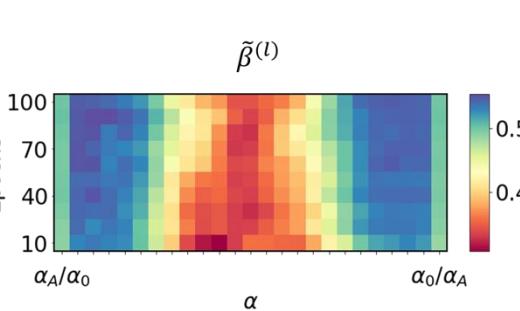
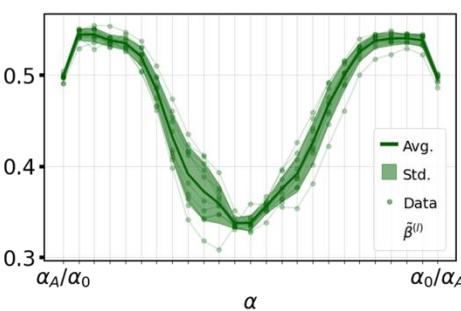
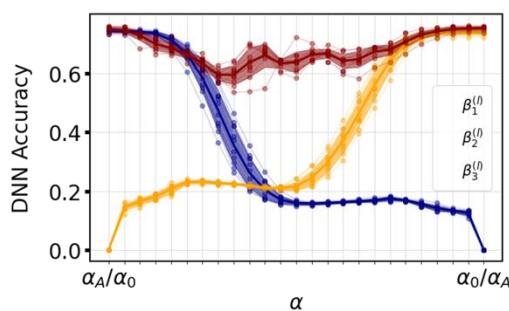
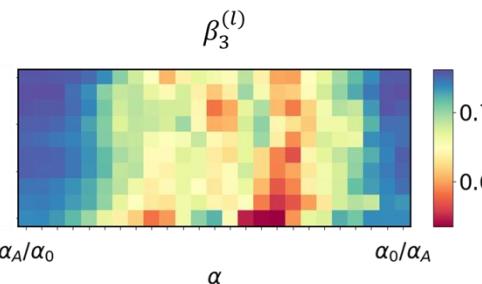
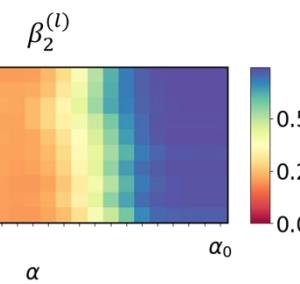
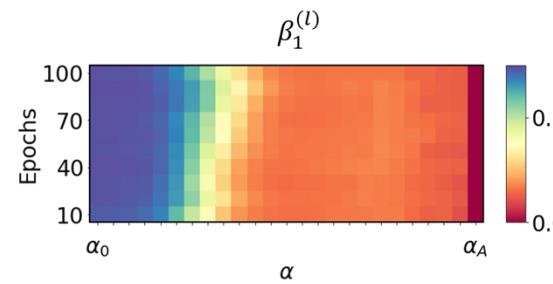
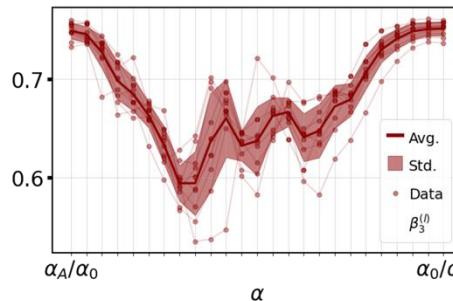
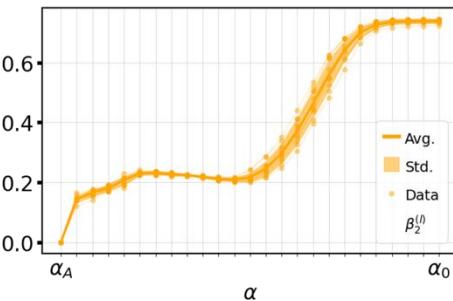
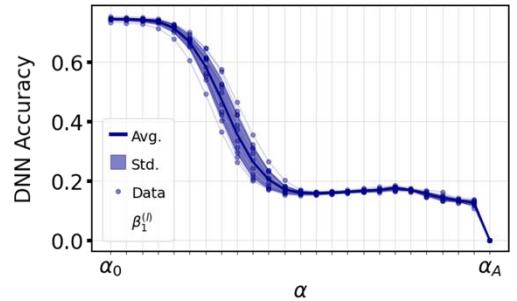
- a new method of parameter filtering (**synaptic filtering**)
- **synaptic filtering of all layers and parameters** of a DNN architecture.
- **compare clean and adversarial performance** of a regular DNN and perturbed DNN.
- **characterise** parameters as fragile, robust, and antifragile

Synaptic filtering algorithm

$$h_1(\theta, \alpha_i) = \begin{cases} 0 & \text{if } \theta \leq \alpha_i, \\ 1 & \text{otherwise} \end{cases}$$



Learning landscape (performance vs epoch vs filtering strength)



The influence of parameters varies as the network is trained and learns more dataset features.

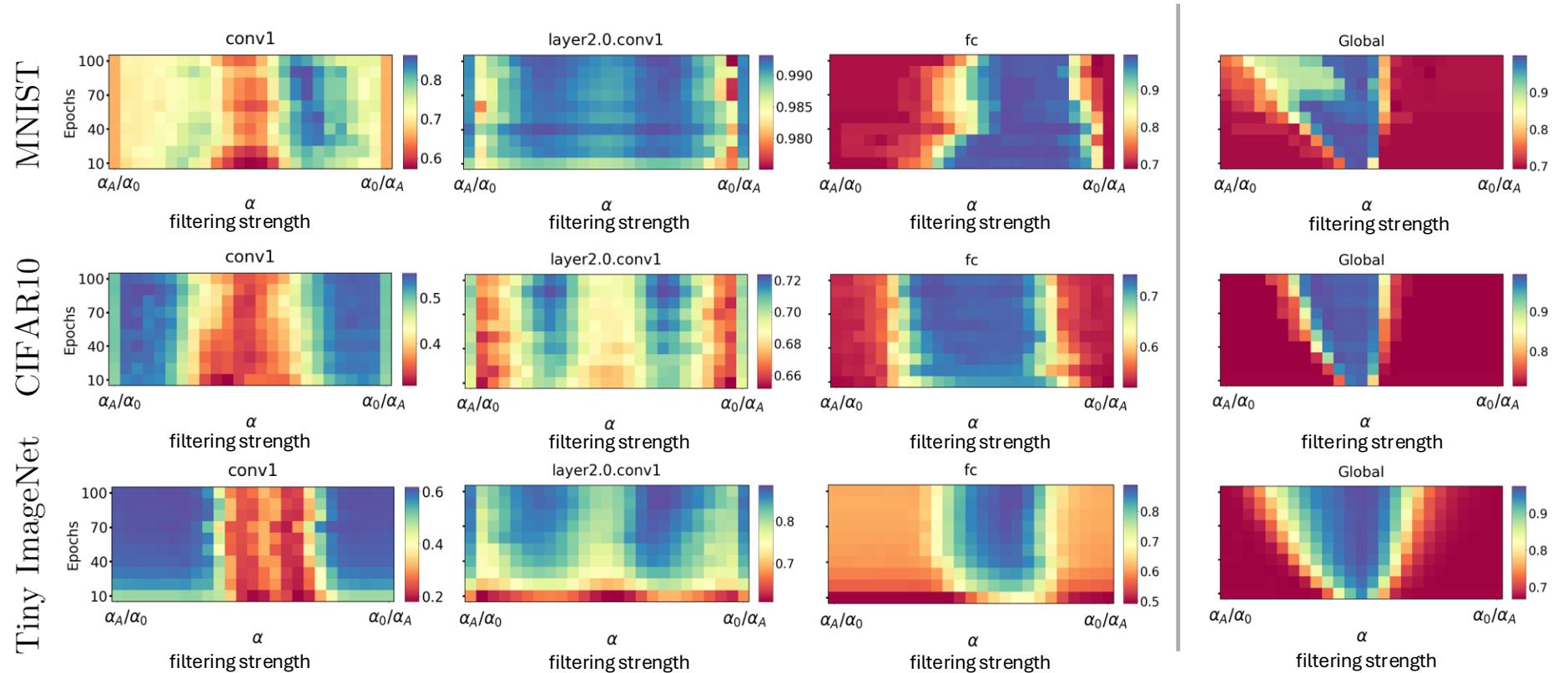
The three different filters h_1 , h_2 , and h_3 highlight different parameters as **influential** (■) and **non influential** (□) to DNN performance.

The combined performance highlights the parameters that are **most influential** (■) using all the three different filters.

Learning landscape (performance vs epoch vs filtering strength)

We show that the **same layer of a DNN has similar learning landscapes** for different datasets on filtering.

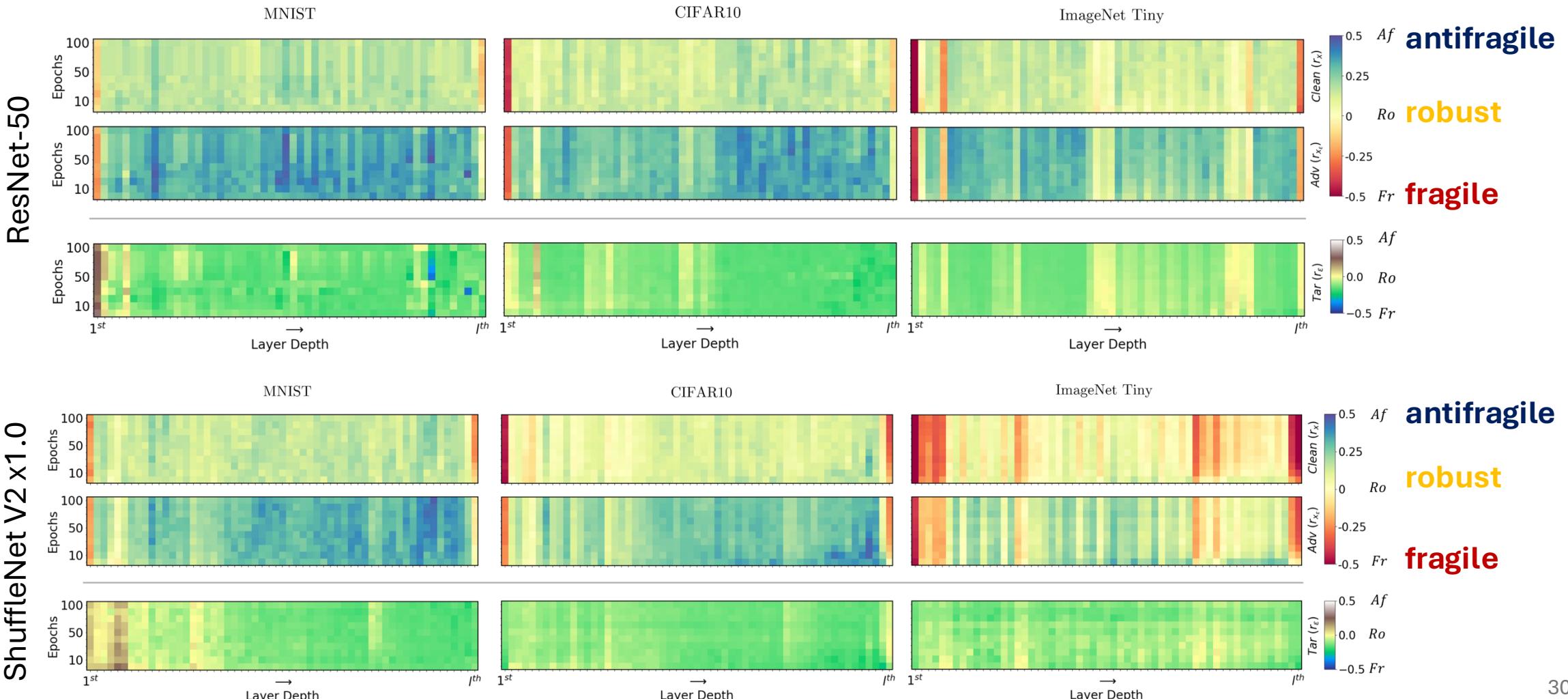
This shows that there are **invariant characteristics of DNN architectures**, even when applied to different datasets.



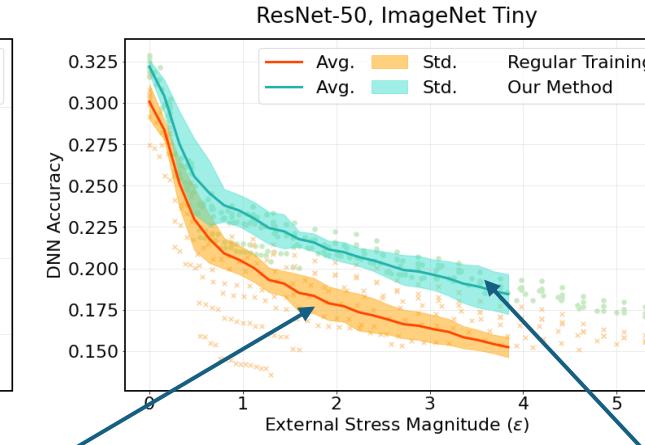
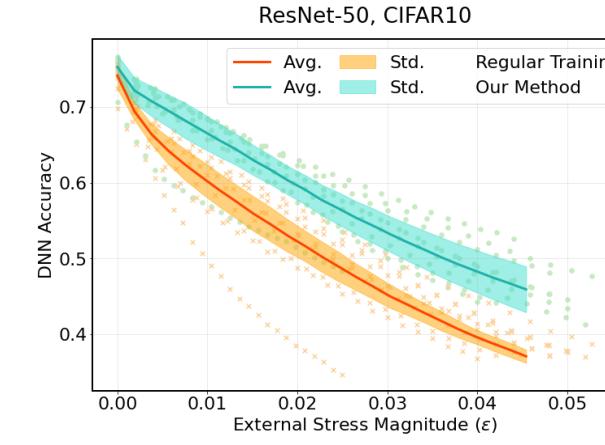
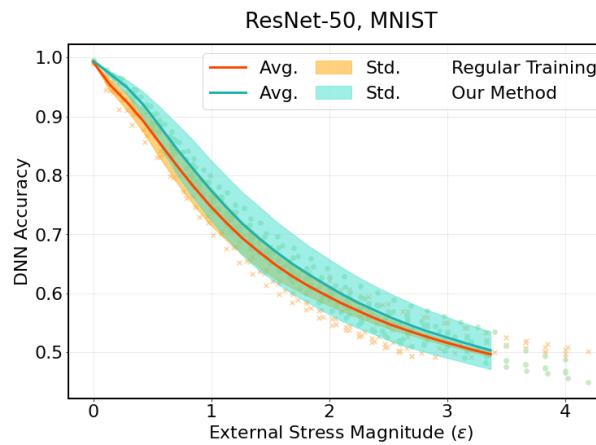
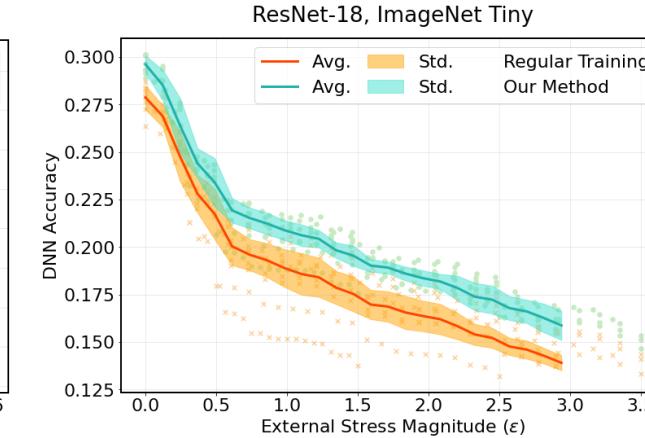
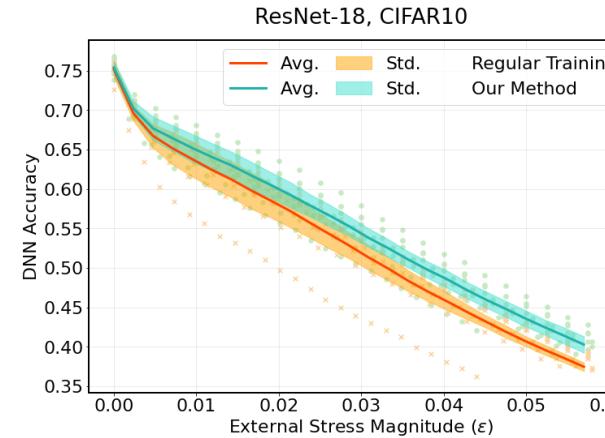
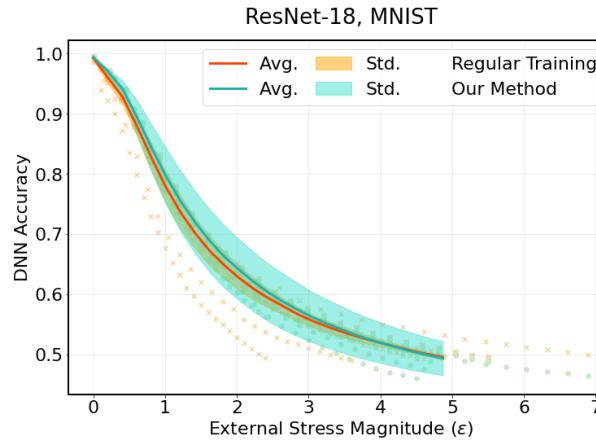
Different layers in the network show to have different characteristics when subjected to the parameter filters (internal stressor). The results are the combined responses using filters h_1 , h_2 , and h_3 .

Parameter scores (layer-wise and epoch wise)

We say that **fragile** parameters are important to network performance **robust** parameters are unaffected by internal and external stress, and **antifragile** parameters can be removed to improve performance .



Selective backpropagation for DNN robustness

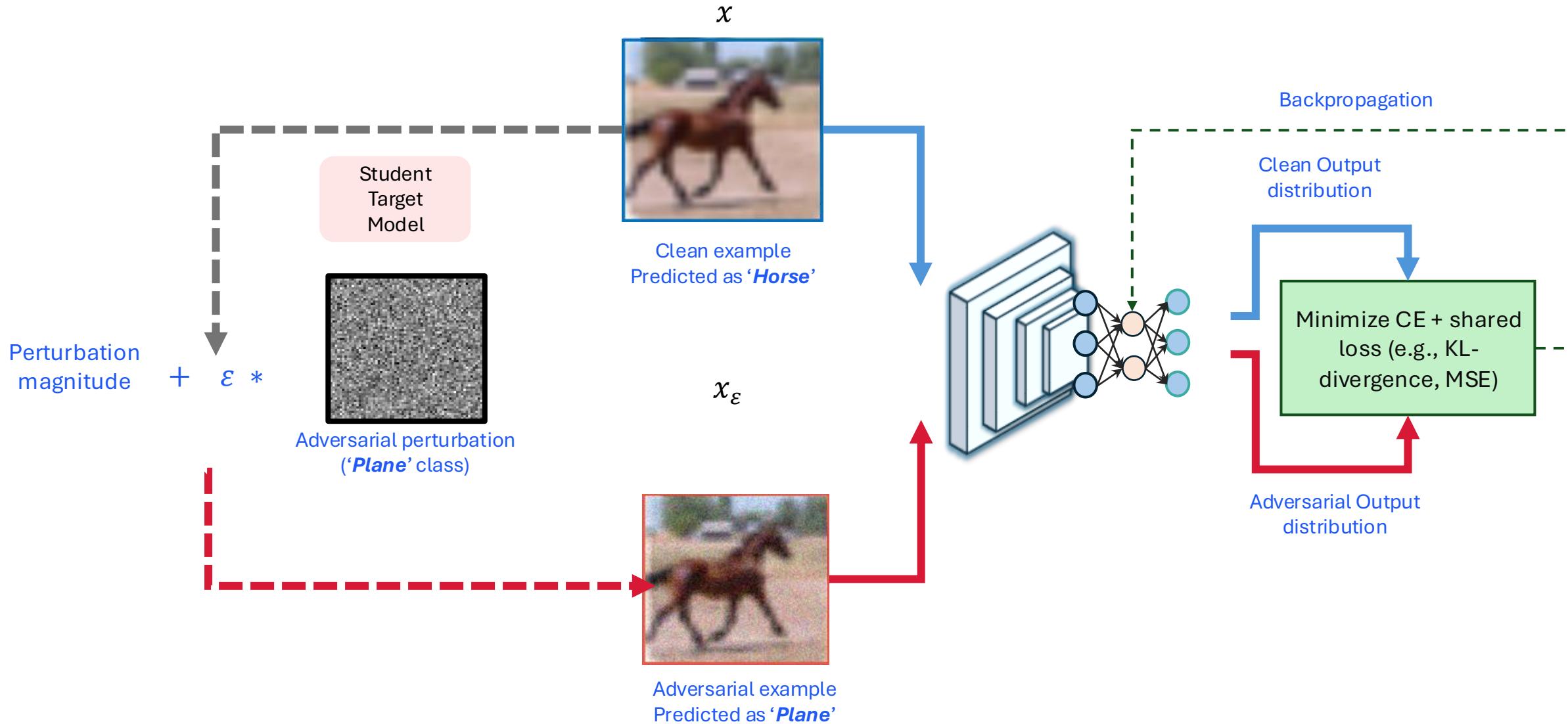


When we **retrain** networks at periodic intervals using only the characterised **robust and antifragile** layer parameters (selective backpropagation), we observe an **increase in adversarial performance**, and clean performance for some networks and datasets.

Regular training

Selective backpropagation

Adversarial training for DNN robustness



Loss functions

Loss function may be more influential in AI than architecture as we have seen in earlier results that parameters of any model size and architecture converge to similar weight distribution. This leaves with two other variables to pay attention to: gradient decent (backprop algo) and loss function (e.g. cross entropy)

Mean Absolute Error (MAE) :

MAE calculates loss by considering all the errors on the same scale.

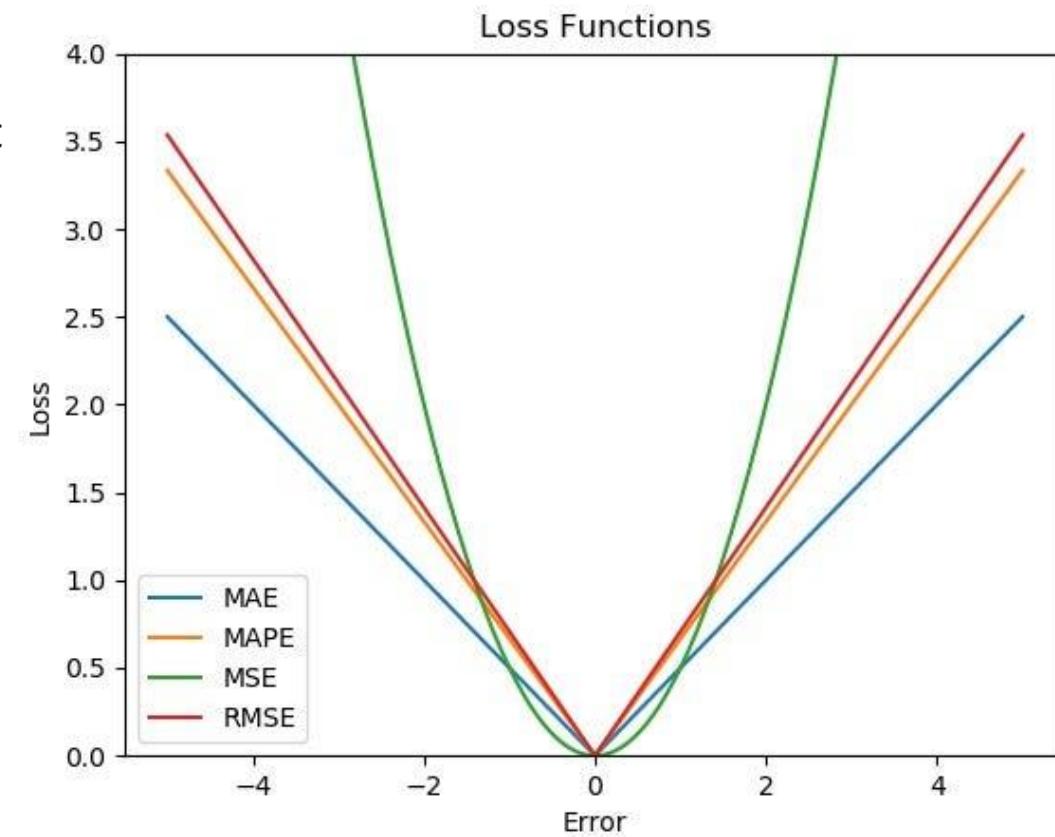
Therefore, network will not be able to distinguish between them just based on MAE, and so, it's hard to alter weights during backpropagation.

Mean Squared Error (MSE) :

MSE helps converge to the minima efficiently, as the gradient reduces gradually. At the same time, extremely large loss may lead to a drastic jump during backpropagation, which is not desirable. MSE is also sensitive to outliers.

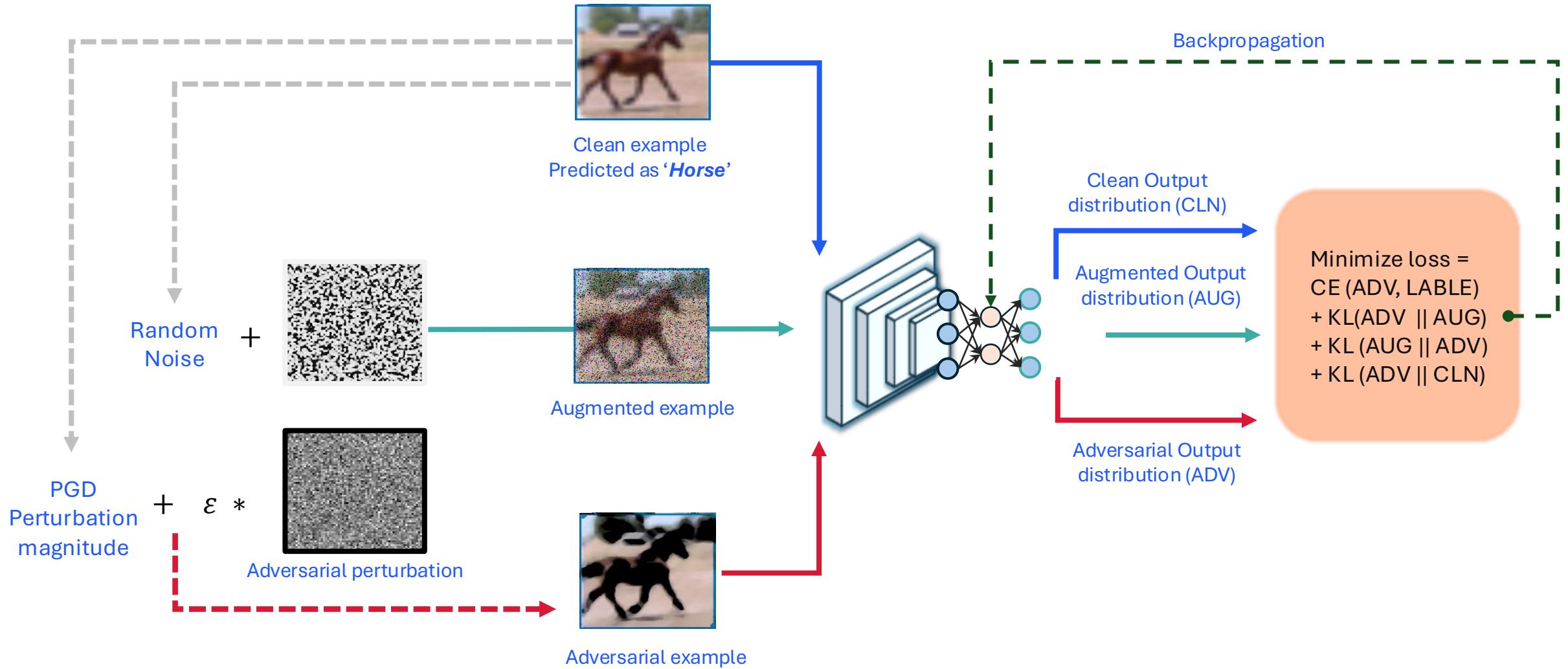
Root Mean Squared Error (RMSE) :

Less extreme losses even for larger values, however, near minima, the gradient change is abrupt



RegMix: Adversarial mutual and generalization regularization

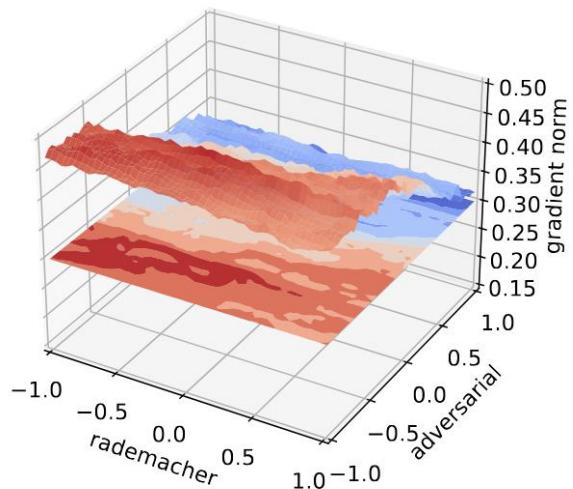
IEEE Trustcom 2025



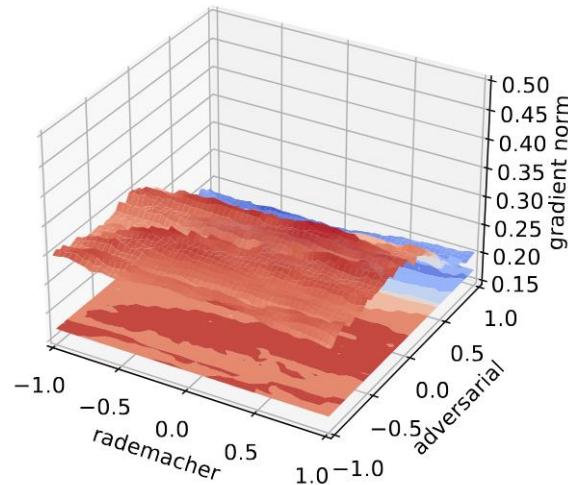
Loss landscape comparison

RegMix: Adversarial mutual and generalization regularization

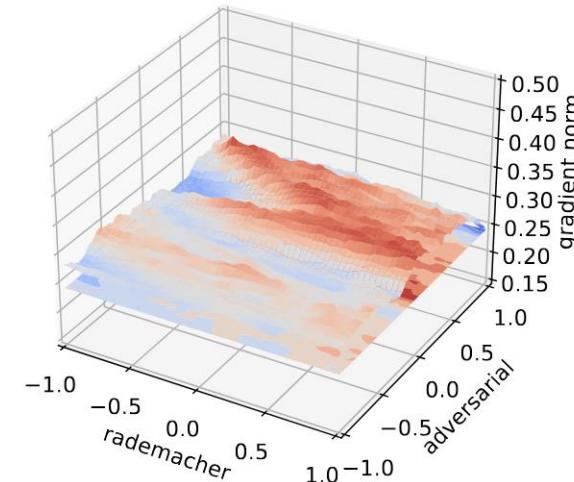
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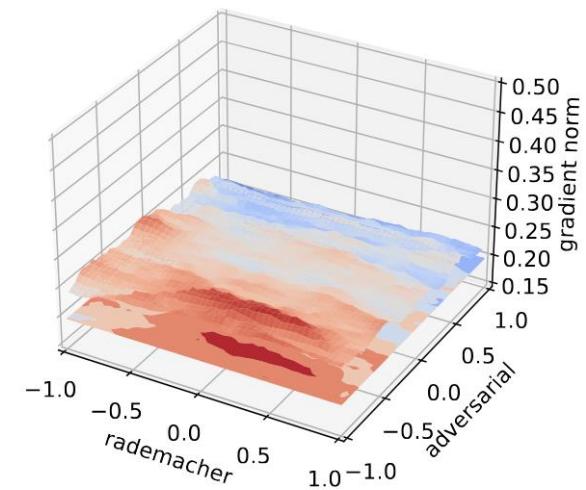
(a) FGSM-PGI



(b) FGSM-PGK



(c) FGSM-AMR (Ours)



(d) FGSM-AGR (Ours)

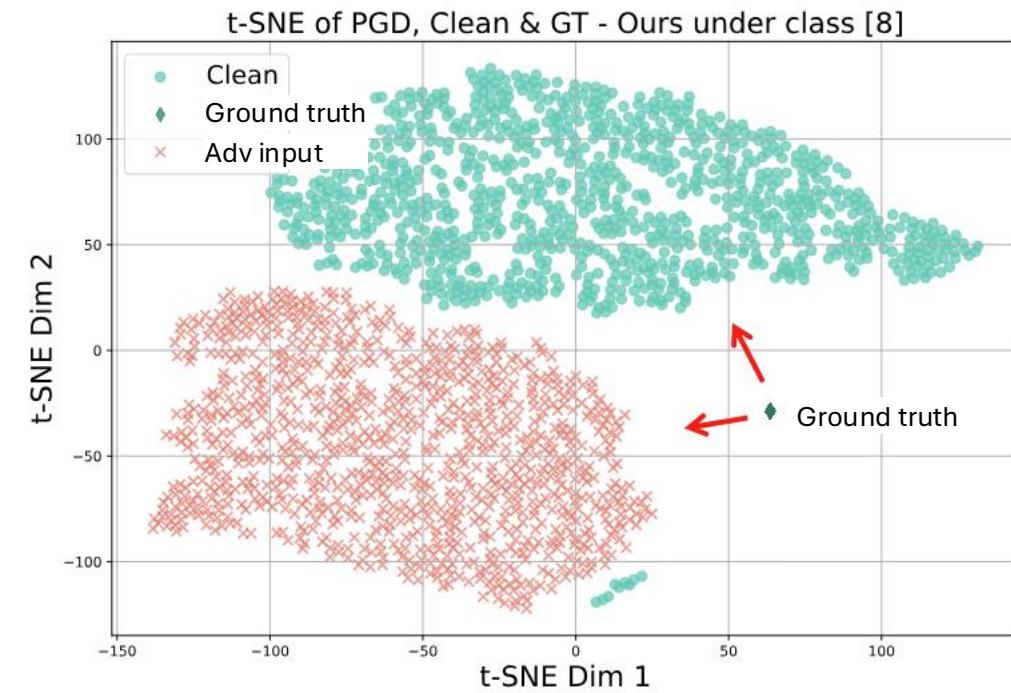
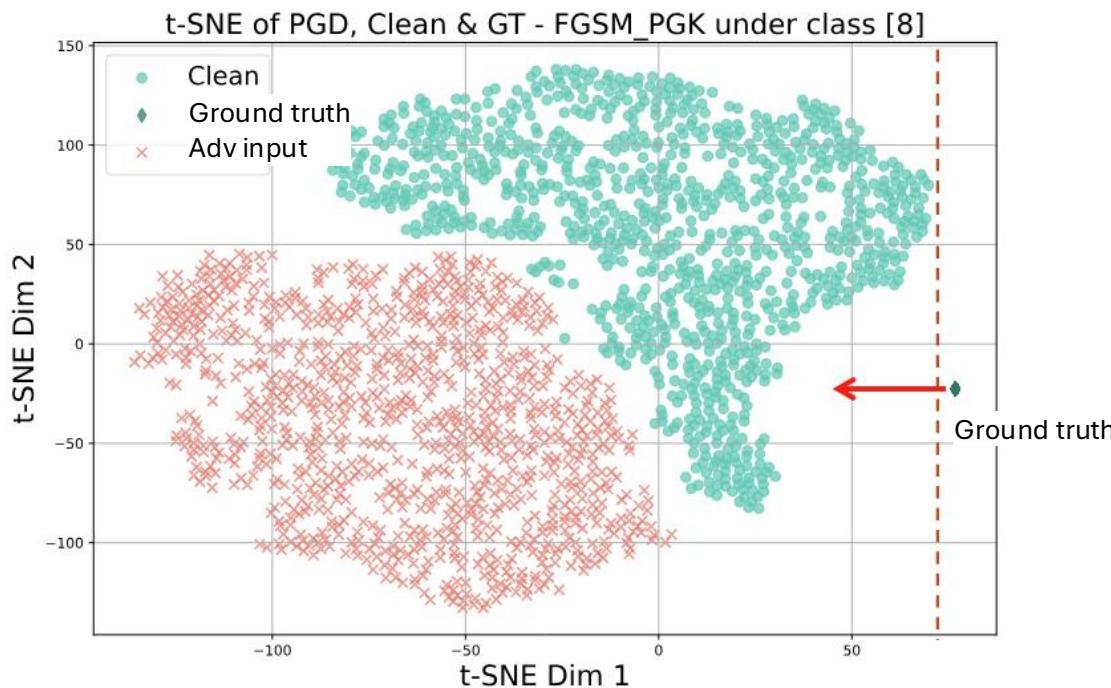
Adversarial
Mutual
Regularization

Adversarial
Generalization
Regularization

Classification Visualisation

RegMix: Adversarial mutual and generalization regularization

Plot: Predicted adversarial and clean probability distribution



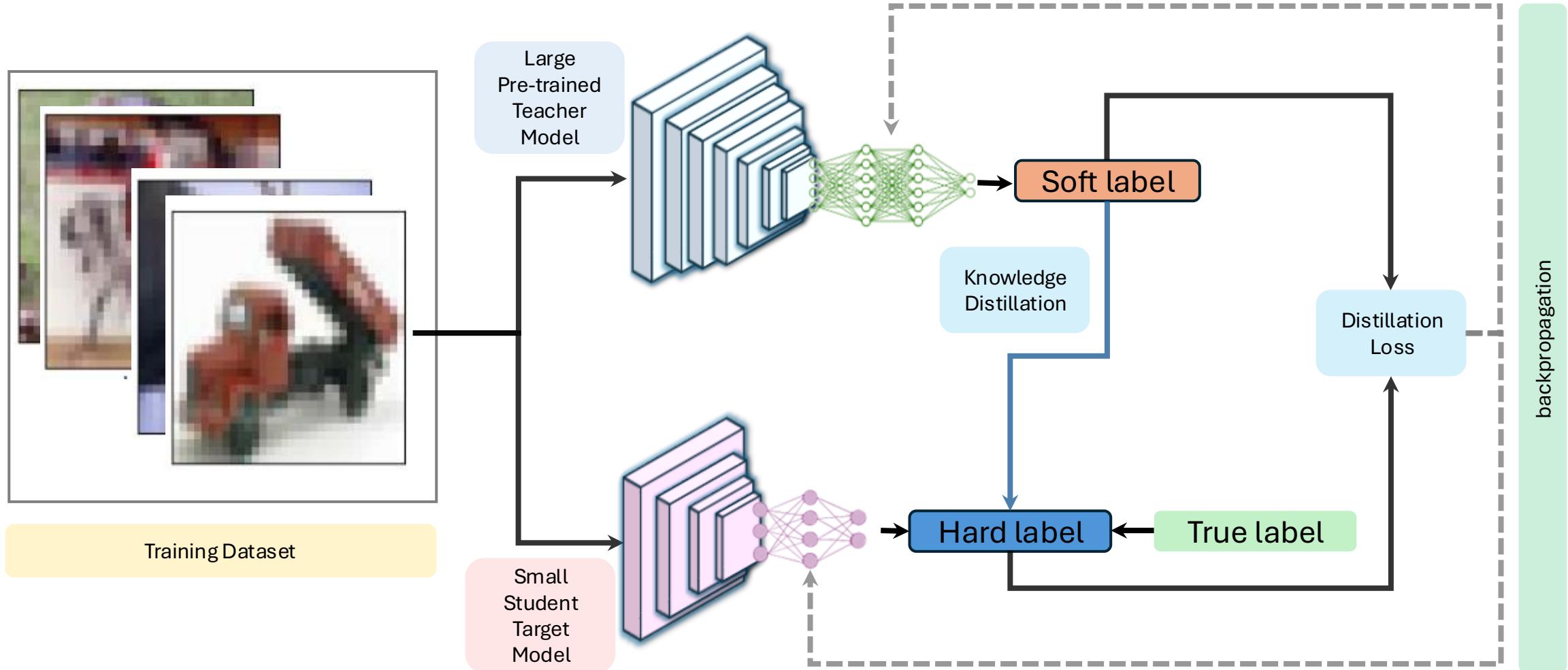
Performance

RegMix: Adversarial mutual and generalization regularization

WideResNet-34-10 on CIFAR-100 dataset

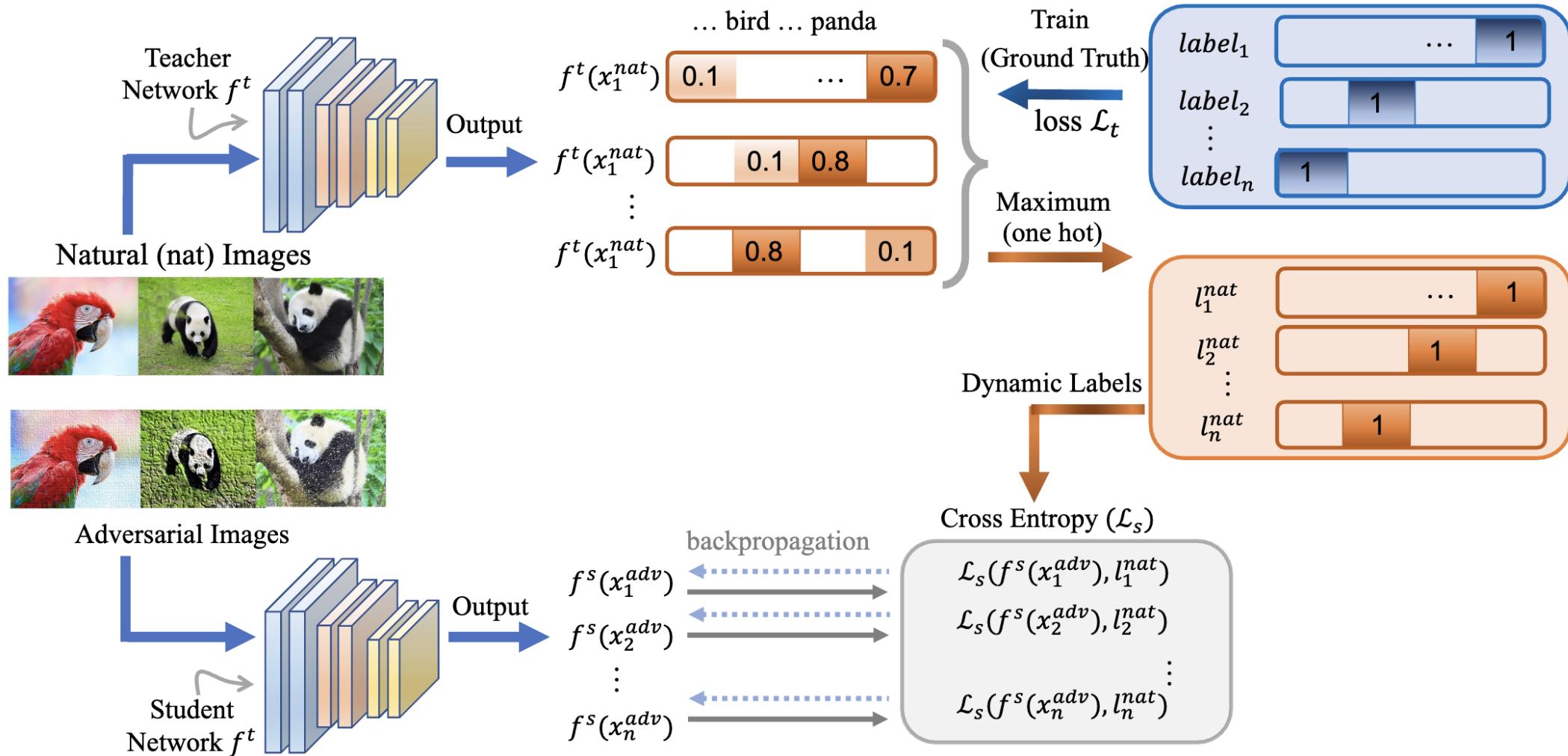
Method	Clean Best/Last	PGD-10 Best/Last	PGD-20 Best/Last	PGD-50 Best/Last	C&W Best/Last	AA Best/Last
PGD-AT [56]	57.52/57.50	29.60/29.54	28.99/29.00	28.87/28.90	28.85/27.60	25.48/25.58
FGSM-RS [68]	49.85/60.55	22.47/0.45	22.01/0.25	21.82/0.19	20.55/0.25	18.29/0.00
FGSM-CKPT [35]	60.93/60.93	16.58/16.69	15.47/15.61	15.19/15.24	16.40/16.60	14.17/14.34
FGSM-SDI [33]	60.67/60.82	31.50/30.87	30.89/30.34	30.60/30.08	27.15/27.30	25.23/25.19
NuAT [63]	59.71/59.62	27.54/27.07	23.02/22.72	20.18/20.09	22.07/21.59	11.32/11.55
GAT [62]	57.01/56.07	24.55/23.92	23.80/23.18	23.55/23.00	22.02/21.93	19.60/19.51
FGSM-GA [2]	54.35/55.10	22.93/20.04	22.36/19.13	22.20/18.84	21.20/18.96	18.88/16.45
Free-AT (m=8) [59]	52.49/52.63	24.07/22.86	23.52/22.32	23.36/22.16	21.66/20.68	19.47/18.57
FGSM-PGI [30]	58.78/58.81	31.78/31.60	31.26/31.06	31.14/30.88	28.06/27.72	25.67/25.42
FGSM-PGK [31]	56.27/58.13	33.15/32.38	32.85/31.90	32.83/31.87	28.39/27.95	26.86/26.35
FGSM-SAR (ours)	56.08/55.71	33.26/33.06	32.93/32.86	32.84/32.68	28.64/28.89	27.27/27.22
FGSM-AGR (ours)	53.57/53.57	33.29/33.29	33.02/33.02	32.95/32.95	28.91/28.91	27.42/27.42

Knowledge distillation for DNN robustness



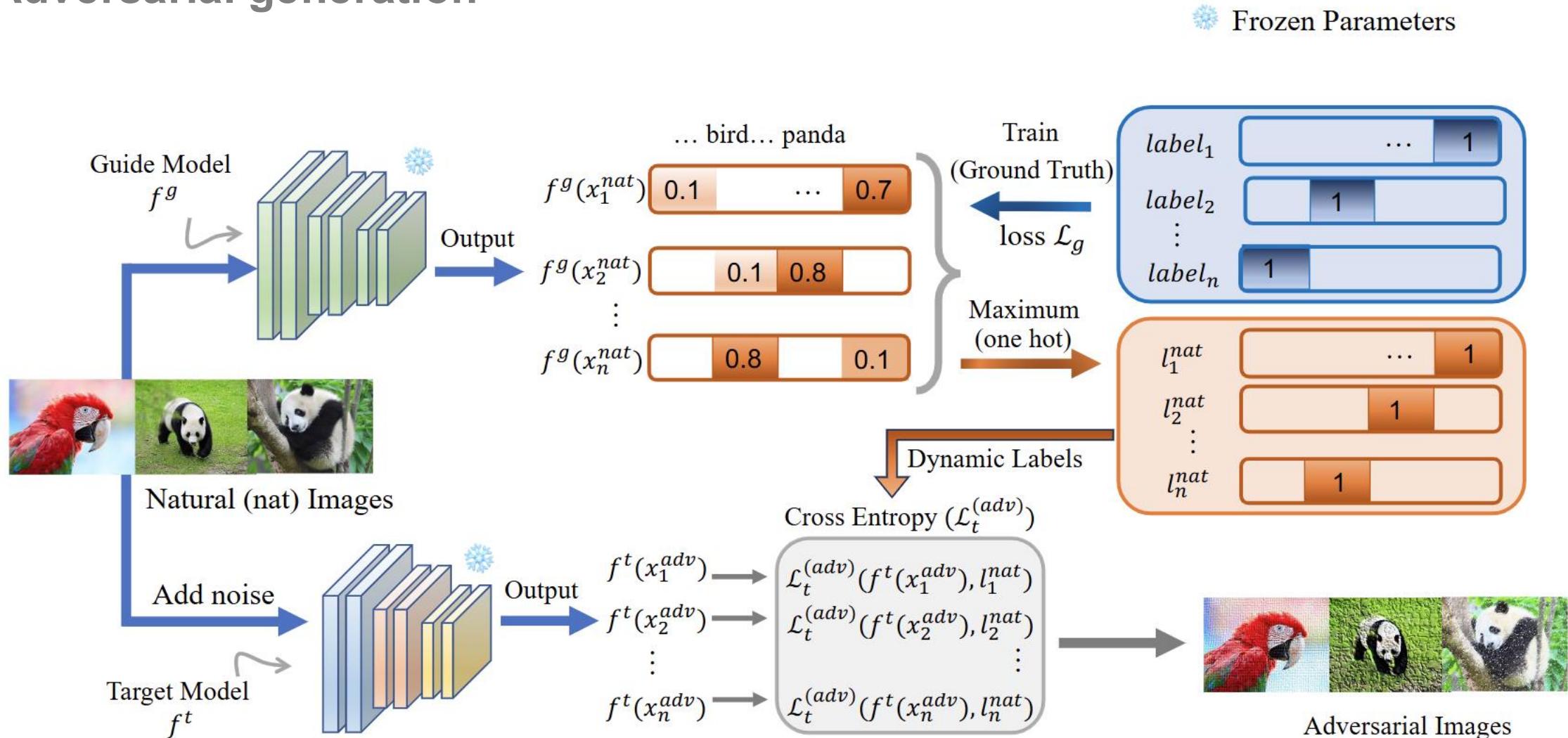
DynAT: Dynamic Label Adversarial Training

Knowledge distillation framework



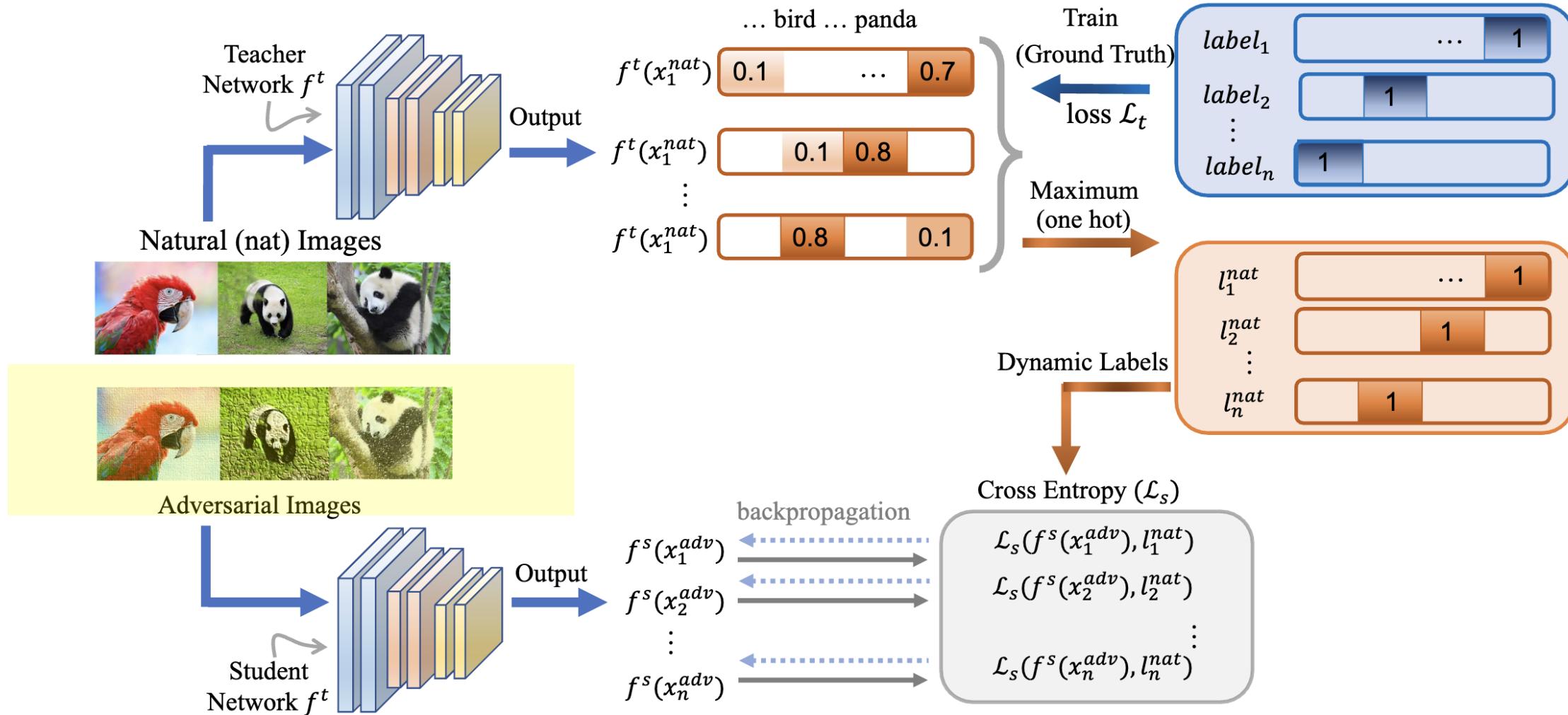
DynAT: Dynamic Label Adversarial Training

Adversarial generation

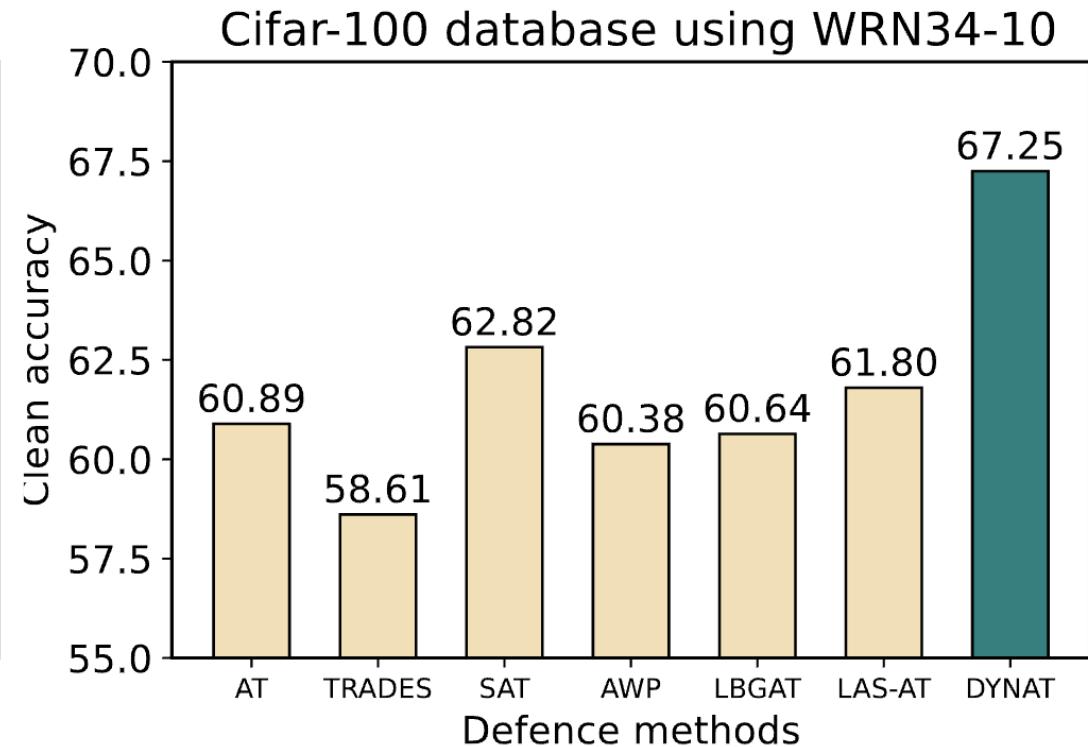
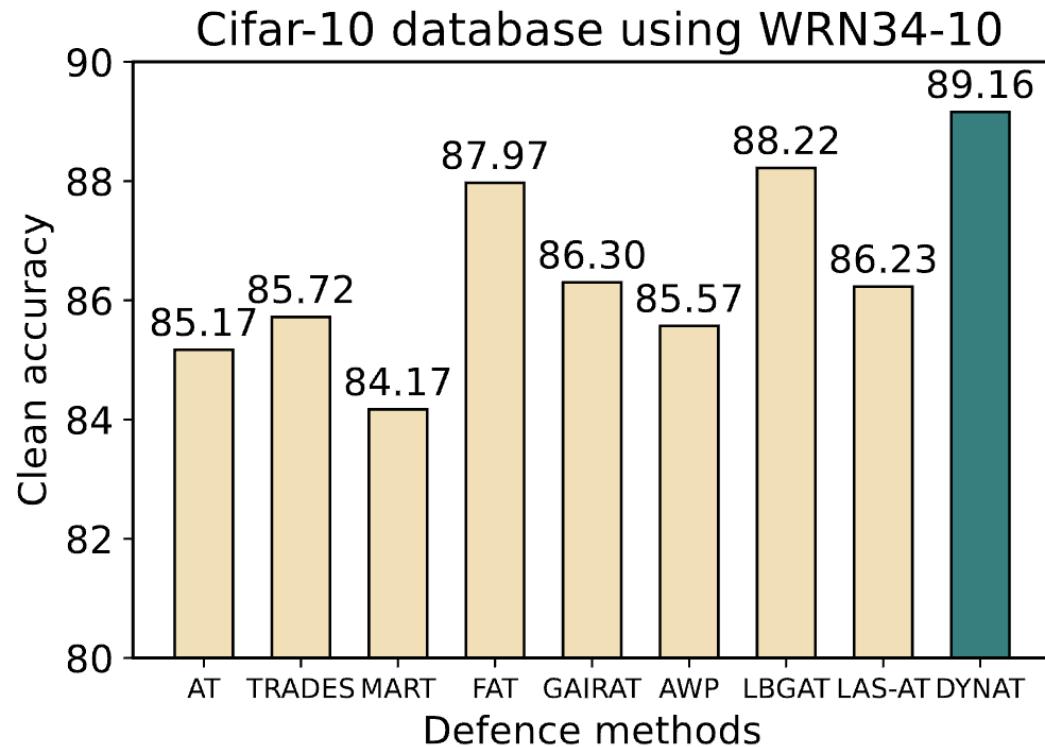


DynAT: Dynamic Label Adversarial Training

Knowledge distillation framework



Performance Comparison with other typical defense methods



Performance

Comparison with other defense methods

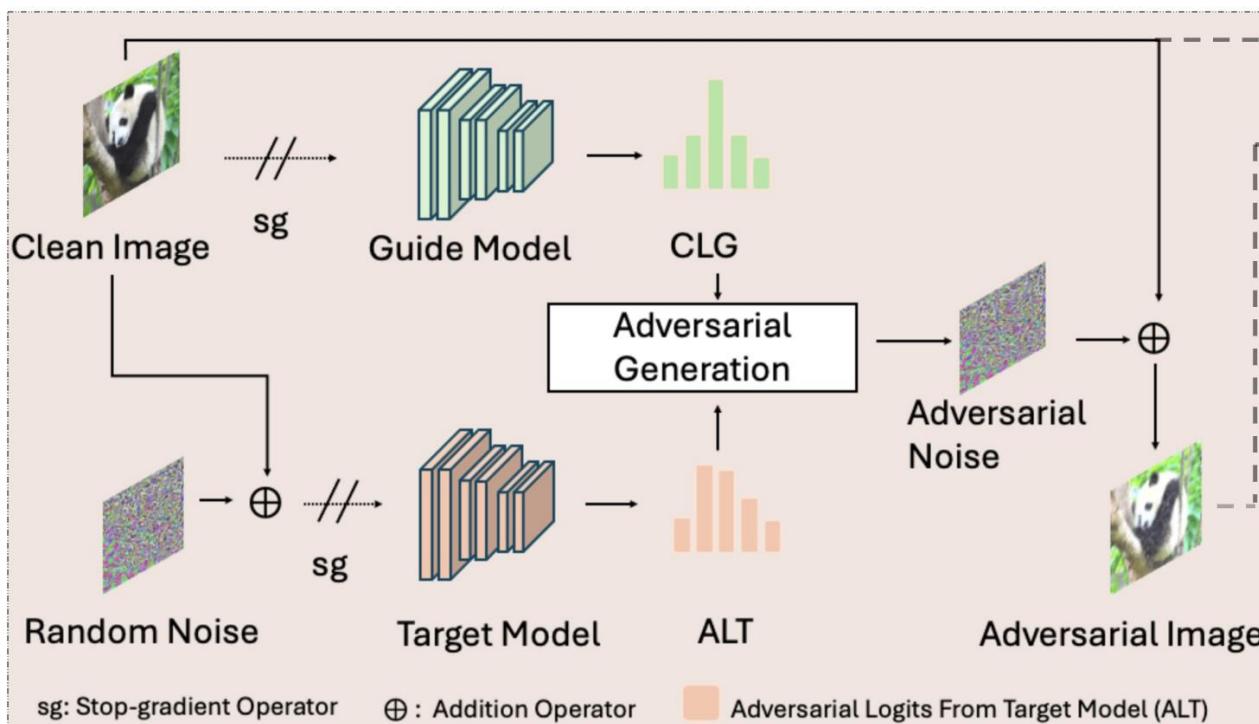
WideResNet-34-10 on CIFAR-10 dataset

Method		Clean	PGD-10	PGD-20	PGD-50	C&W	AA
Others	PGD-AT	60.89	32.19	31.69	31.45	30.1	27.86
	TRADES	58.61	29.20	28.66	28.56	27.05	25.94
	SAT	<u>62.82</u>	28.1	27.17	26.76	27.32	24.57
	AWP	60.38	34.13	33.86	33.65	31.12	28.86
	LBGAT	60.64	35.13	<u>34.75</u>	34.62	30.65	29.33
Ours	DYNAT	67.25	28.03	26.97	26.81	26.62	24.10
	DYNAT-AWP ($\alpha = 1$)	62.29	<u>35.45</u>	35.09	<u>34.92</u>	<u>31.50</u>	30.20
	DYNAT-Inner-AWP ($\alpha = 1$)	58.87	35.61	35.09	35.05	32.10	<u>29.70</u>

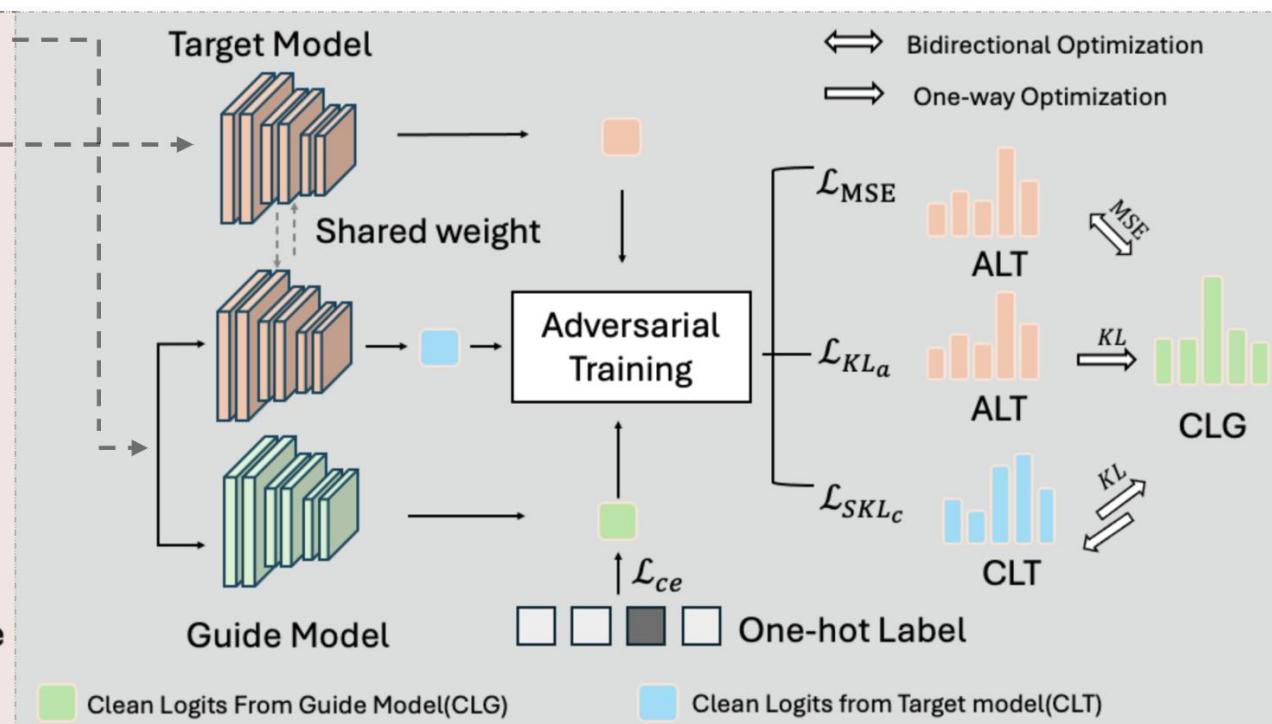
D²R: Dual regularization loss with adversarial generation

ICANN 2025

(a) Adversarial Samples Generation Process



(b) Adversarial Training Process



■ Guide Model (Clean output)

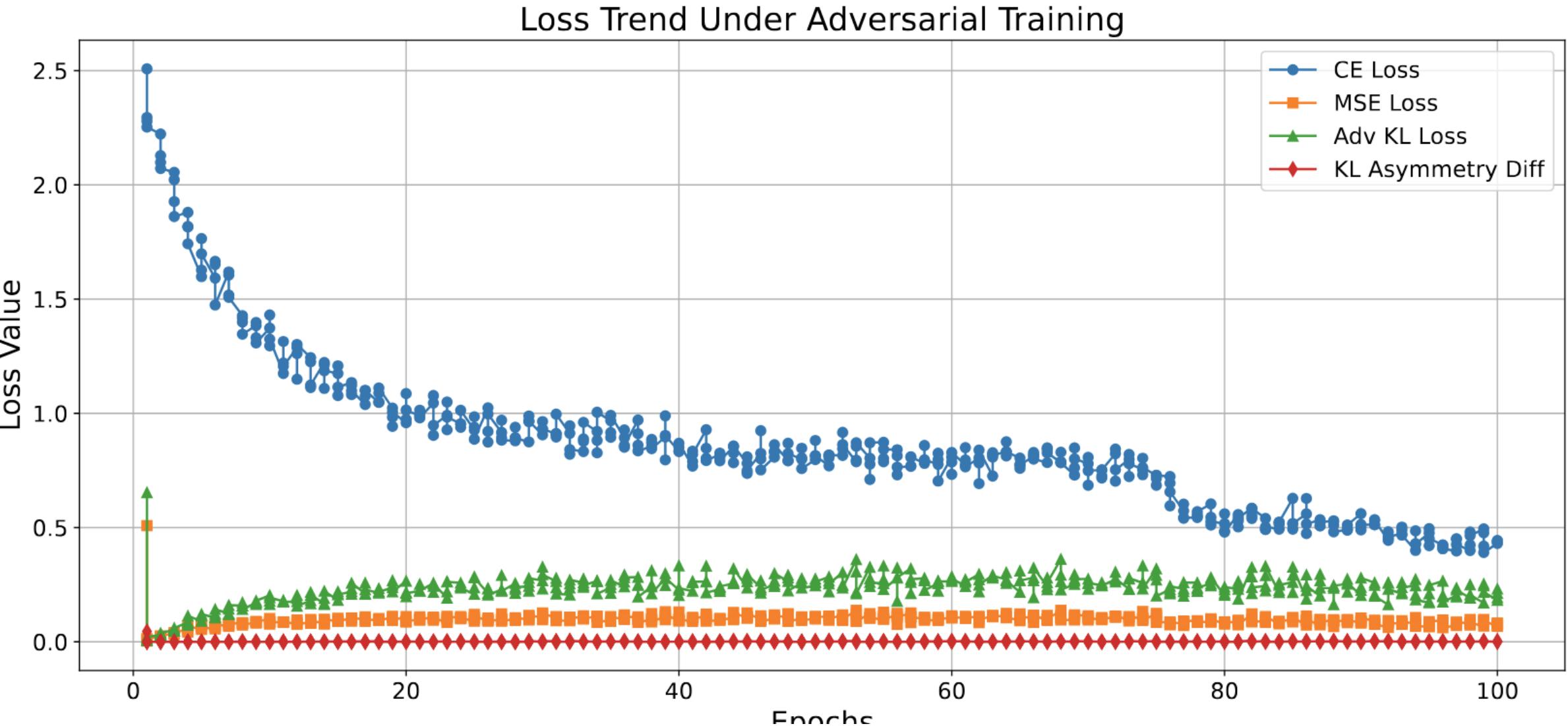
■ Target Model (Adversarial output)

■ Target Model (Clean output)

$$\begin{aligned} \mathcal{L}_{D2R}(x, y) = & \min_{\theta_g, \theta_t} \mathbb{E}_{(x,y) \in D} \left\{ \lambda \mathcal{L}_{CE}(\theta_g, x, y) \right. \\ & + \mathcal{L}_{MSE}(f_g(x), f_t(x')) + \alpha \mathcal{L}_{KL}(f_g(x) \parallel f_t(x')) \\ & \left. + \beta |\mathcal{L}_{KL}(f_t(x) \parallel f_g(x)) - \mathcal{L}_{KL}(f_g(x) \parallel f_t(x))| \right\}, \end{aligned}$$

D²R: Dual regularization loss with adversarial generation

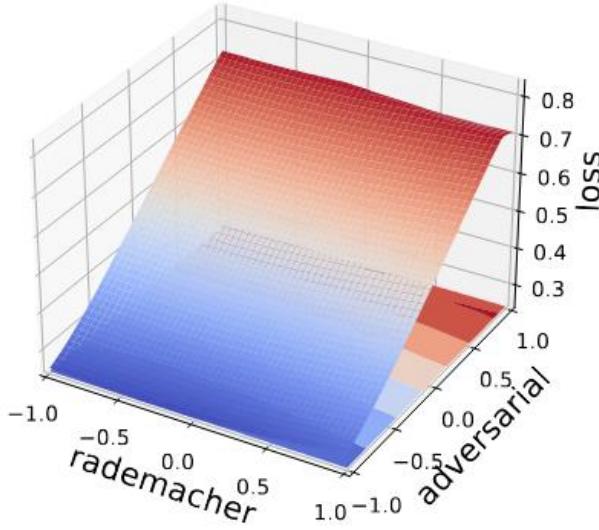
ICANN 2025



D²R: Dual regularization loss with adversarial generation

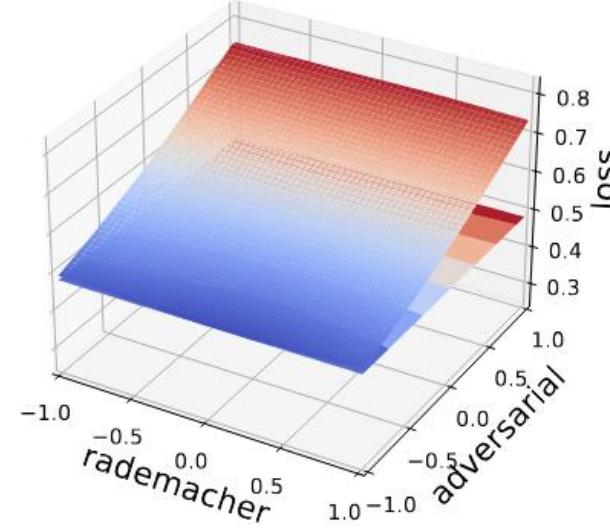
ICANN 2025

Baseline Loss Landscape



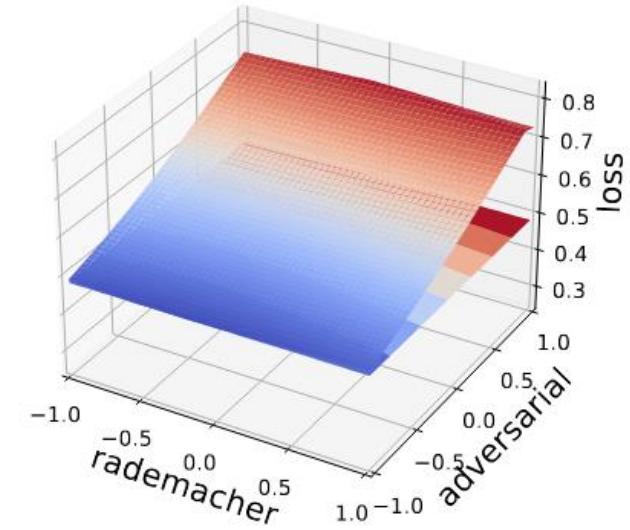
(a) Baseline Method

D2R Loss Landscape



(b) D2R (ours)

D2R-CAG Loss Landscape



(c) D2R-CAG(ours)

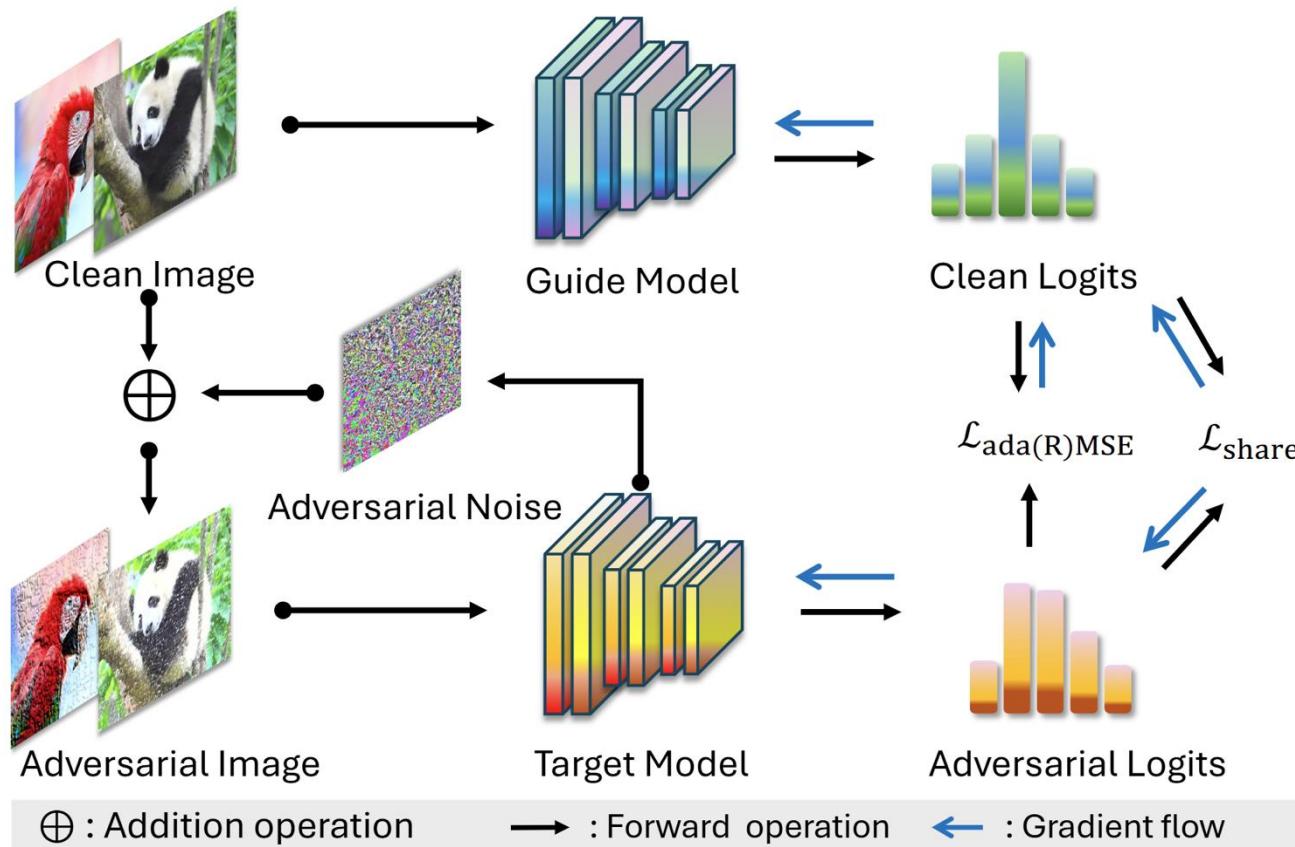
A noticeably flatter loss profile can be observed in our methods, indicating improved robustness against adversarial perturbations

D²R: Dual regularization loss with adversarial generation

WideResNet-34-10 on CIFAR-10 dataset

Method	Clean	PGD-10	PGD-20	PGD-50	C&W	AA
PGD-AT	85.17	56.07	55.08	54.88	53.91	51.69
TRADES	85.72	56.75	56.1	55.9	53.87	53.40
MART	84.17	58.98	58.56	58.06	54.58	51.10
FAT	87.97	50.31	49.86	48.79	48.65	47.48
GAIRAT	86.30	60.64	59.54	58.74	45.57	40.30
AWP	85.57	58.92	58.13	57.92	56.03	53.90
LBGAT (baseline)	88.22	56.25	54.66	54.30	54.29	52.23
LAS-AT	86.23	57.64	56.49	56.12	55.73	53.58
RAT(TRADES)	85.98	-	58.47	-	56.13	54.20
D2R(ours)	86.00	58.17	56.88	56.60	55.69	54.04
D2R-CAG(ours)	85.68	58.50	57.22	56.73	56.66	54.65

AdaGAT: Adaptive guidance for adversarial training



$$\begin{aligned}\mathcal{L}_{\text{AdaGAT-MSE}} = \min_{\theta_g} & \left\{ \mathcal{L}_{\text{CE}} \left(f_{\theta_g}(x), y \right) \right. \\ & \left. + \mathcal{L}_{\text{share}} + \lambda \mathcal{L}_{\text{adaMSE}} \left(\overline{f_{\theta_t}(x + \delta)}, f_{\theta_g}(x) \right) \right\}\end{aligned}$$

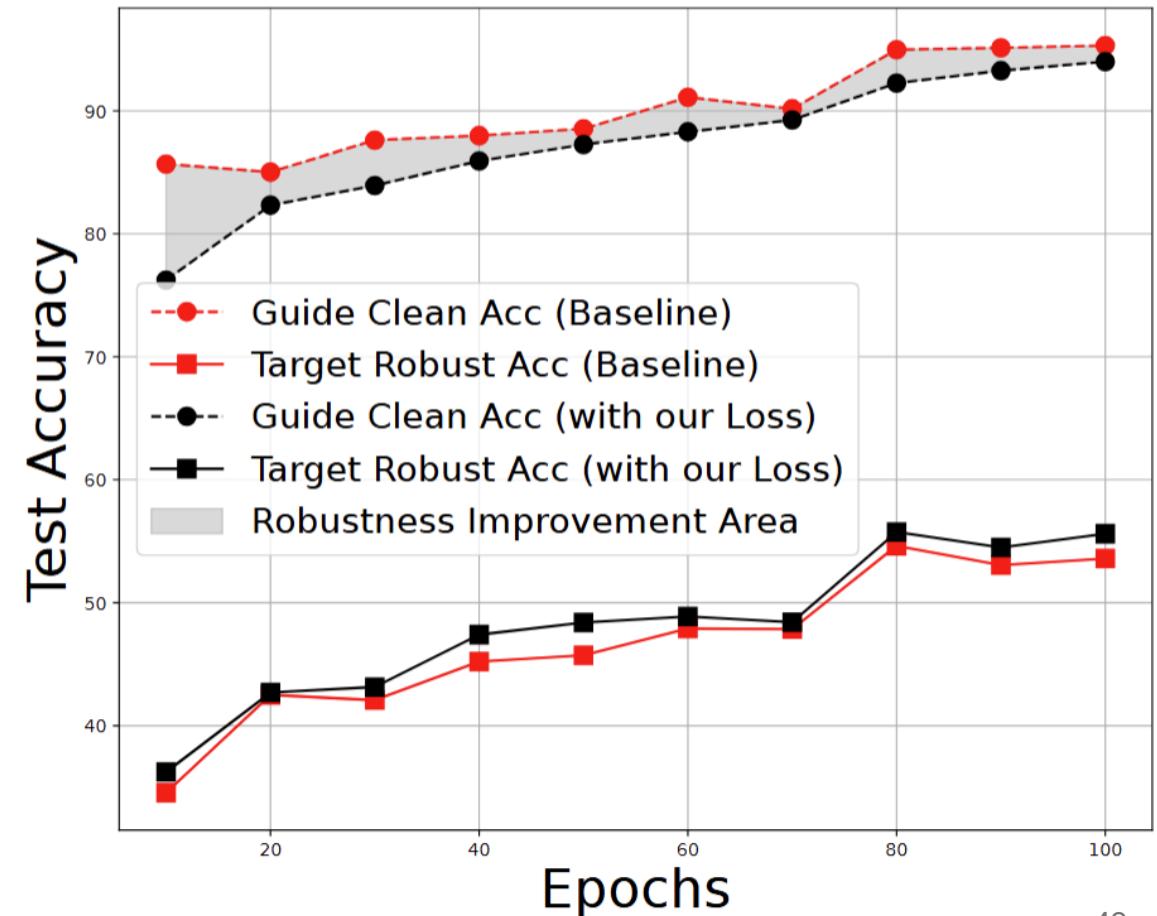
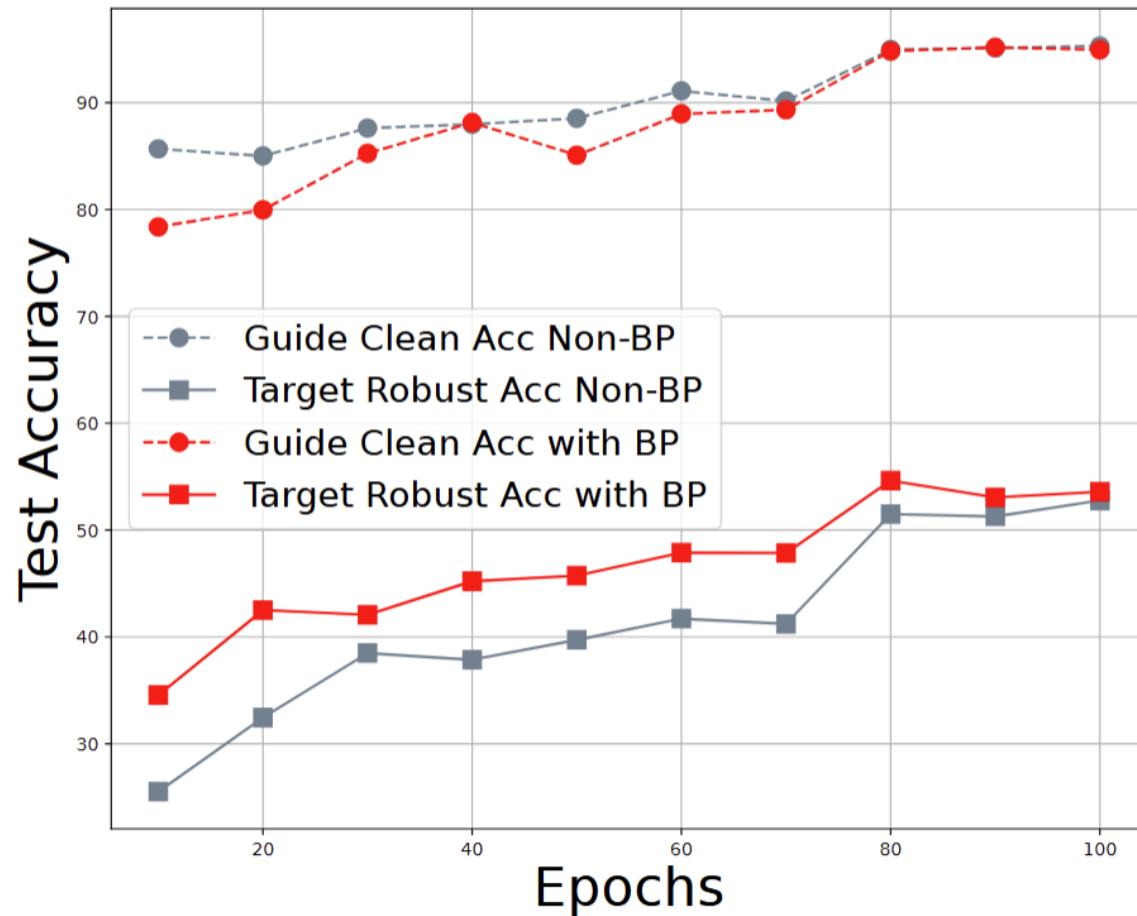
$$\begin{aligned}\mathcal{L}_{\text{AdaGAT-RMSE}} = \min_{\theta_g} & \left\{ \mathcal{L}_{\text{CE}} \left(f_{\theta_g}(x), y \right) + \mathcal{L}_{\text{share}} \right. \\ & \left. + \lambda \mathcal{L}_{\text{adaRMSE}} \left(\overline{f_{\theta_t}(x + \delta)}, f_{\theta_g}(x) \right) \right\}\end{aligned}$$

Guide Model

Target Model

AdaGAT: Comparison of the guiding model's performance with and without backpropagation

PRCV 2025



Performance

AdaGAT: Adaptive guidance for adversarial training

WideResNet-34-10 on CIFAR-10 dataset

Method	PGD-10	PGD-20	PGD-50	C&W	AA
TRADES	29.20	28.66	28.56	27.05	25.94
SAT	28.10	27.17	26.76	27.32	24.57
LBGAT (baseline)	32.05	30.77	30.42	28.72	27.16
AdaGAT-MSE (ours)	32.50	31.59	31.31	29.24	27.69
AdaGAT-RMSE (ours)	32.63	31.63	31.35	29.37	27.79

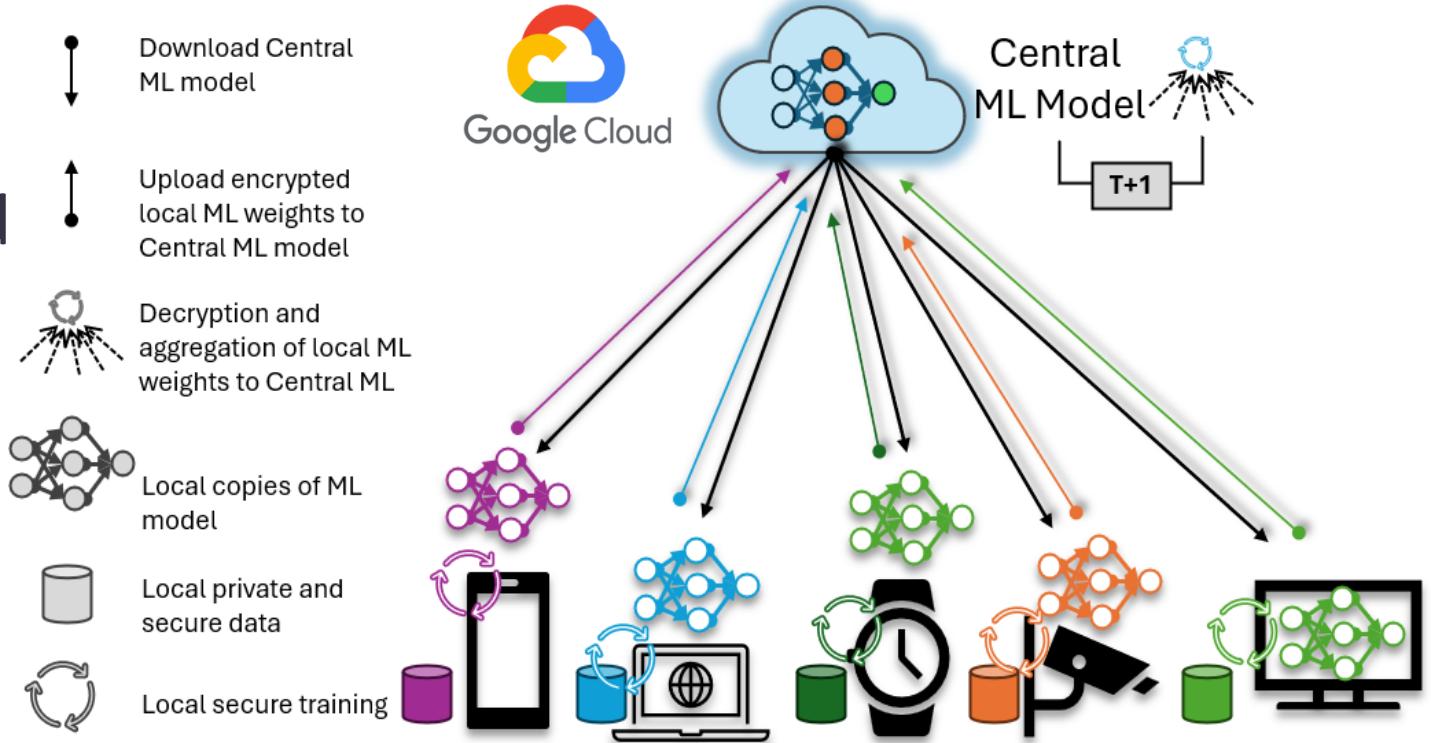
Part 3

Security and Privacy

Data privacy and Security

Model-centric federated learning

Data is generated locally and remains de-centralised. Each client stores its own data and cannot read the data of other clients. Data is not independently or identically distributed (non-IID*)

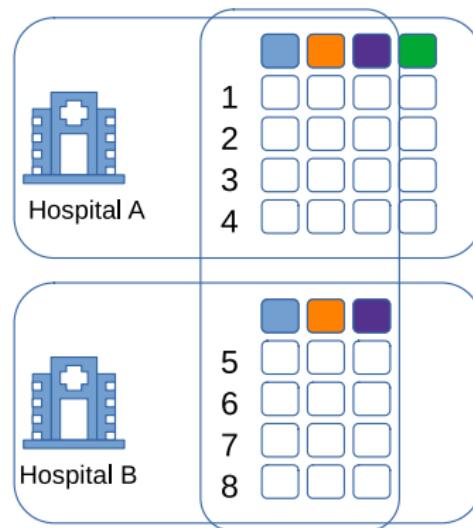


*Non-IID (non-independent and identically distributed) data refers to datasets where samples are not drawn from the same underlying distribution or are not independent of each other. This means that the data exhibits skewness or heterogeneity across different clients or data points

Horizontal federated learning

(Sample-based/Homogenous) federated learning

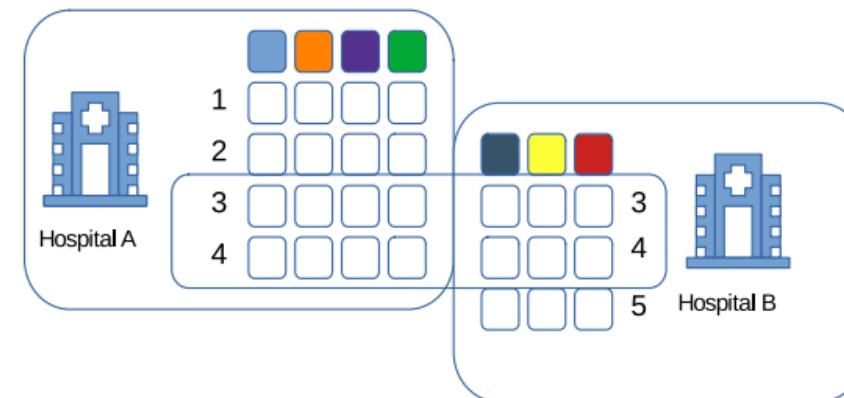
Multiple hospitals can collaboratively train a disease analysis model **without sharing customer information**. Hospitals A and B have the same feature but samples of different patients



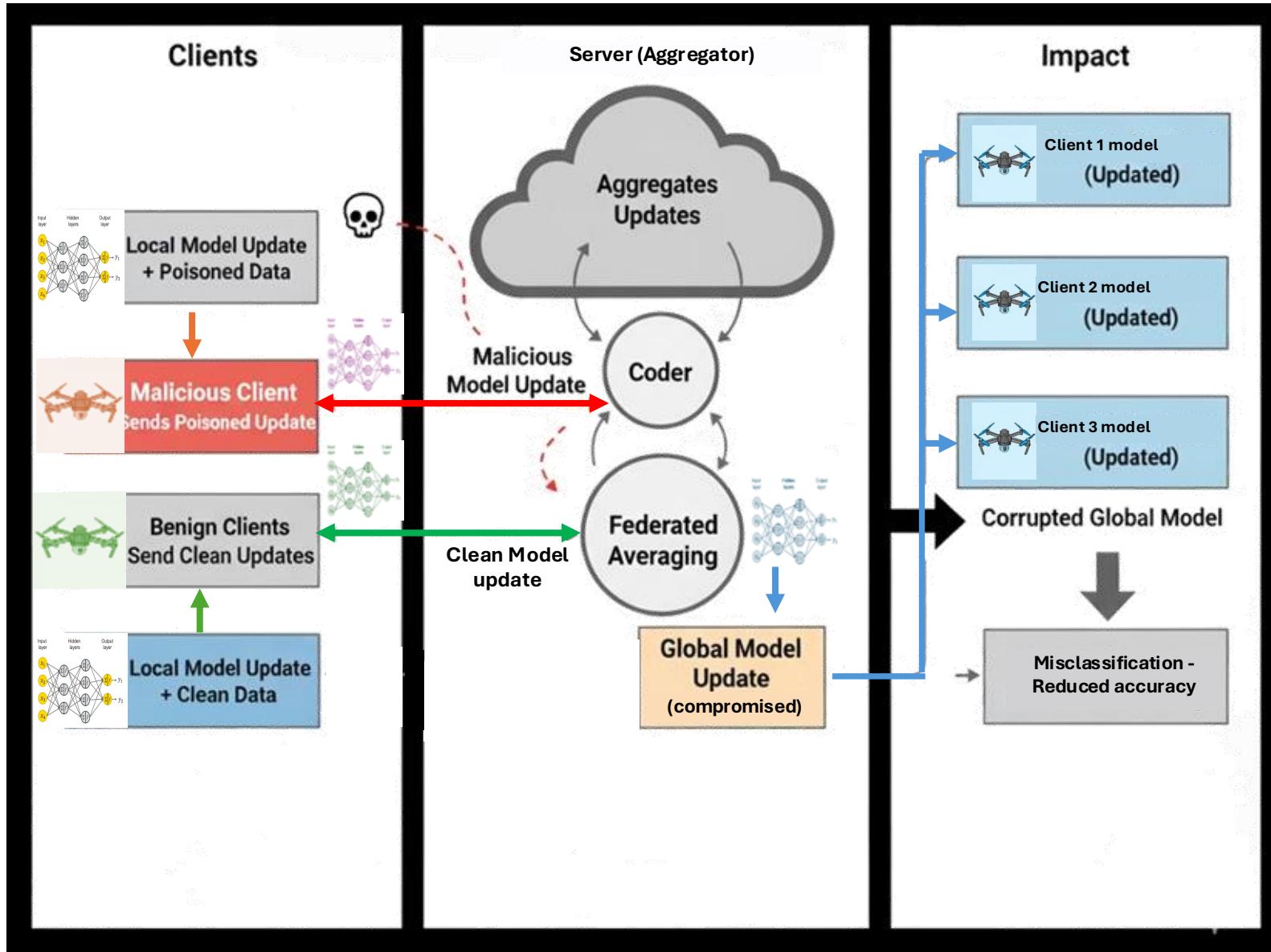
Vertical federated learning

(Feature-based/Heterogeneous) federated learning

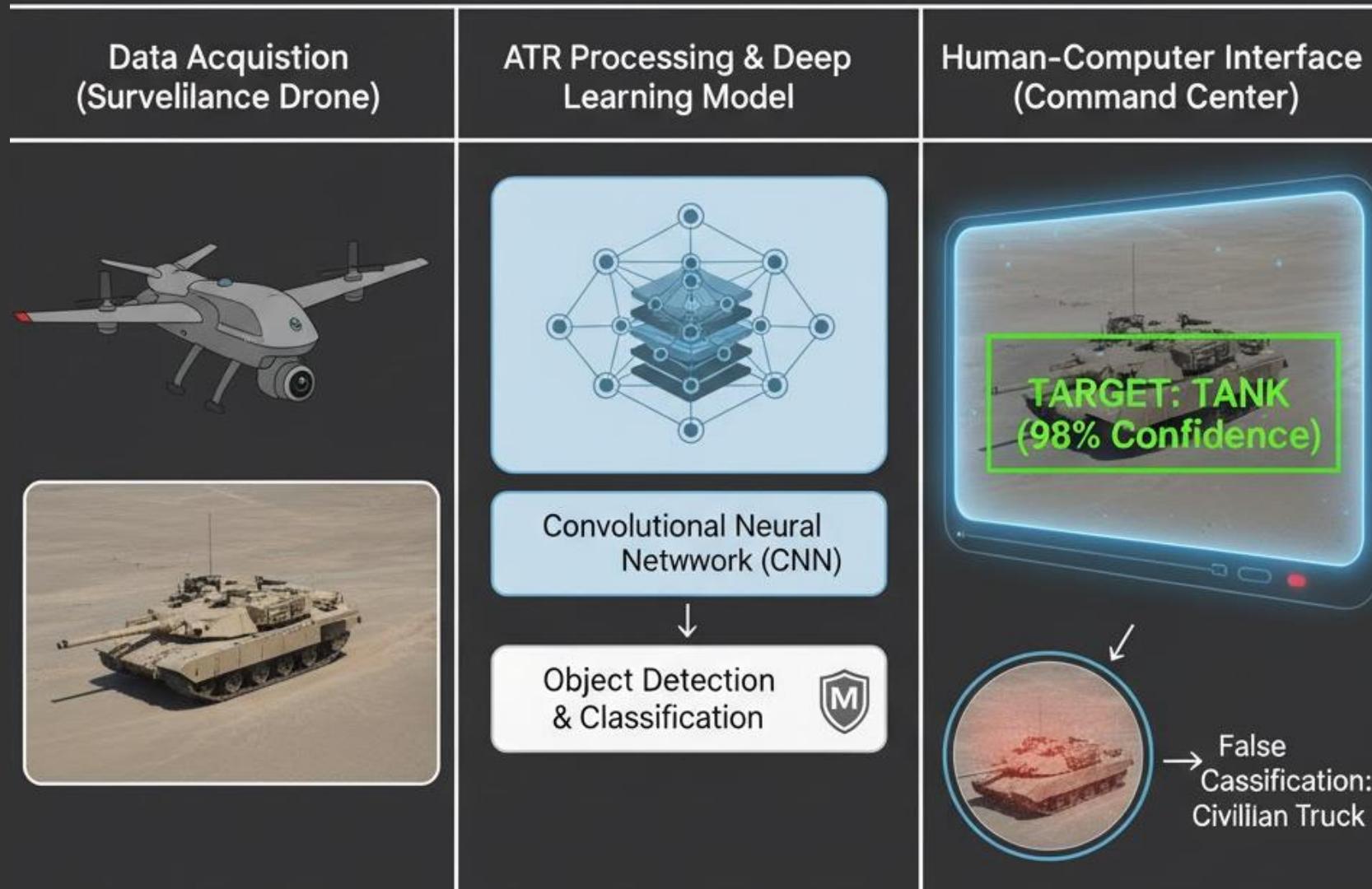
Two Hospitals/Institutions jointly train a model, with the one providing users' medical image data and other providing medical records. Hospital A has information about Patient A related to heart issues' treatment history, and Hospital B has data about patient A's monthly routine checkup history



Federated Learning Attack Scenario



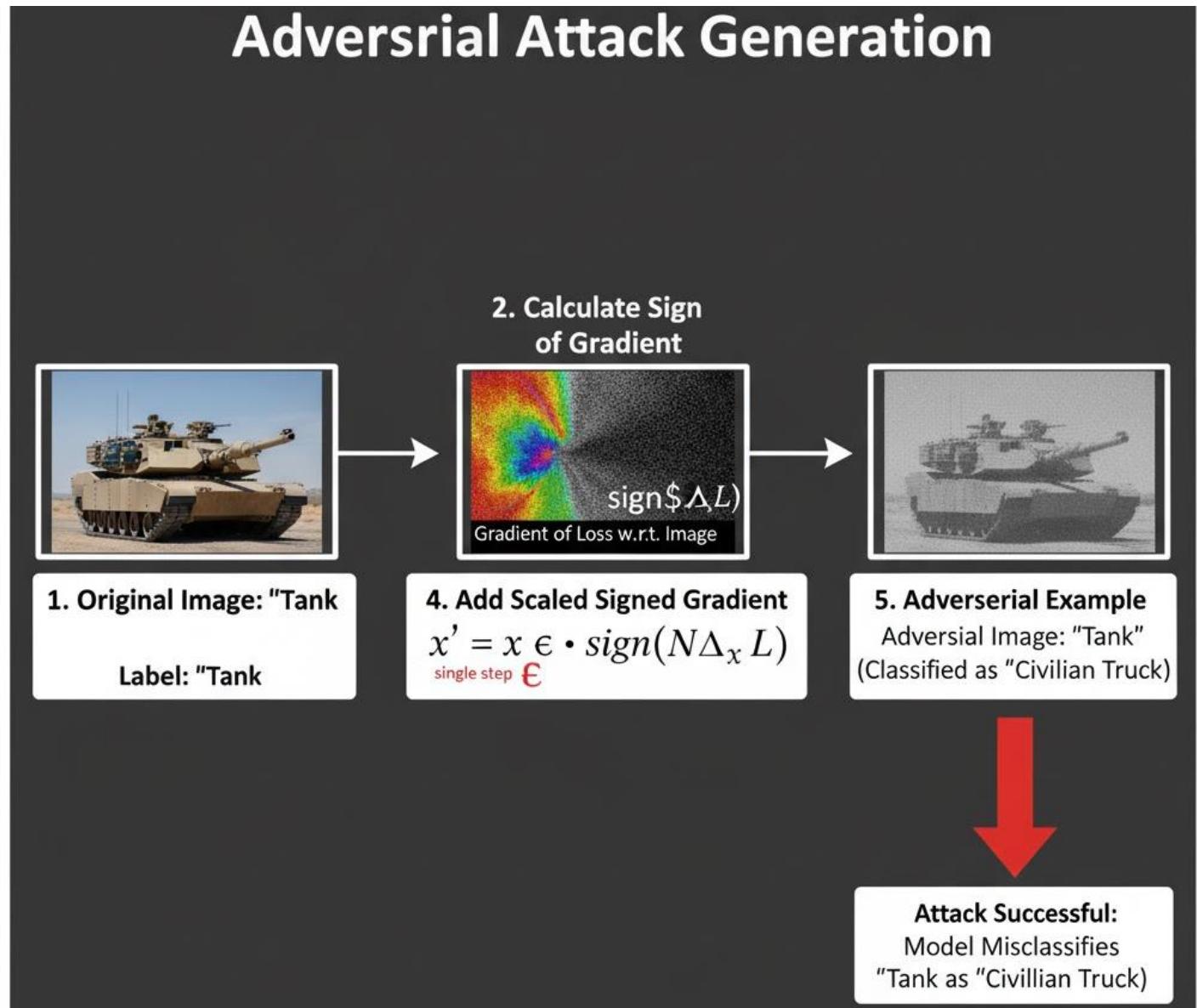
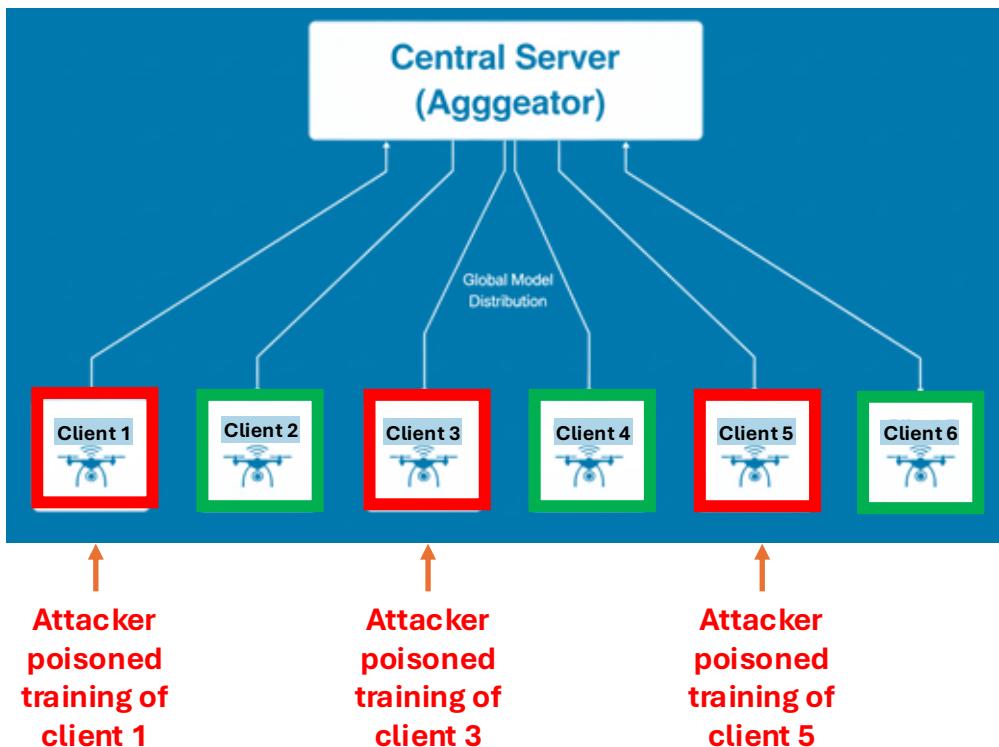
Automated Target Recognition (ATR) System



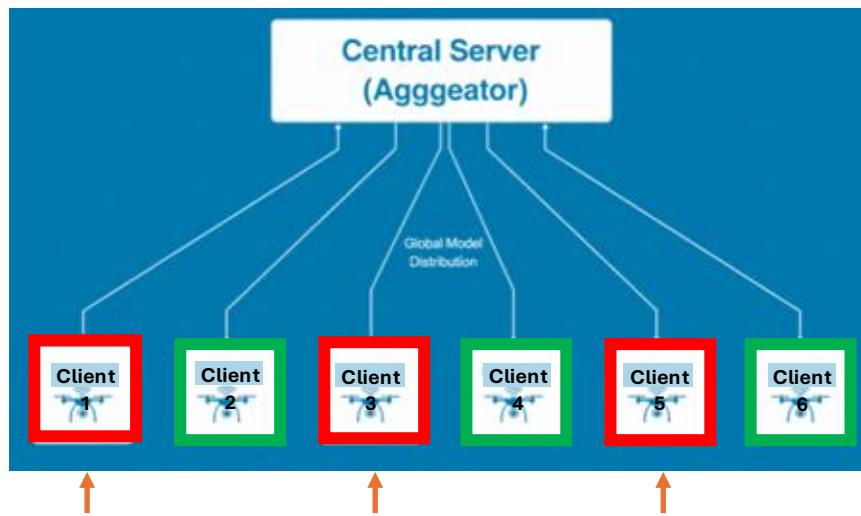
FSGM Attack in FL

An FGSM (Fast Gradient Sign Method) attack in federated learning is an adversarial attack that perturbs the input data on a client's local model to cause a misclassification, even though the changes are often imperceptible to humans.

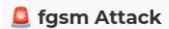
Easy attack quick win, Low computation overhead, less effective



FSGM Attack in FL



Deployment running time: 33mins (10 rounds)



Round: 3 | Client: server

Epsilon: 0.9020

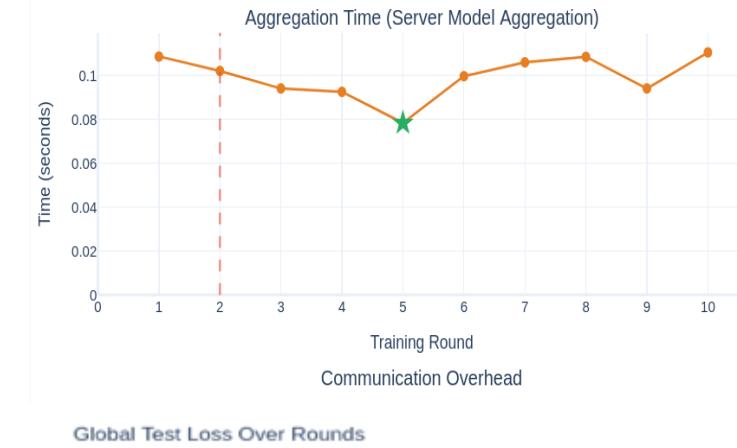
True Label: cat | Original Prediction: cat → Adversarial Prediction: bird Success



True Label: ship | Original Prediction: ship → Adversarial Prediction: airplane Success



True Label: ship | Original Prediction: ship → Adversarial Prediction: truck Success



Global Test Loss Over Rounds



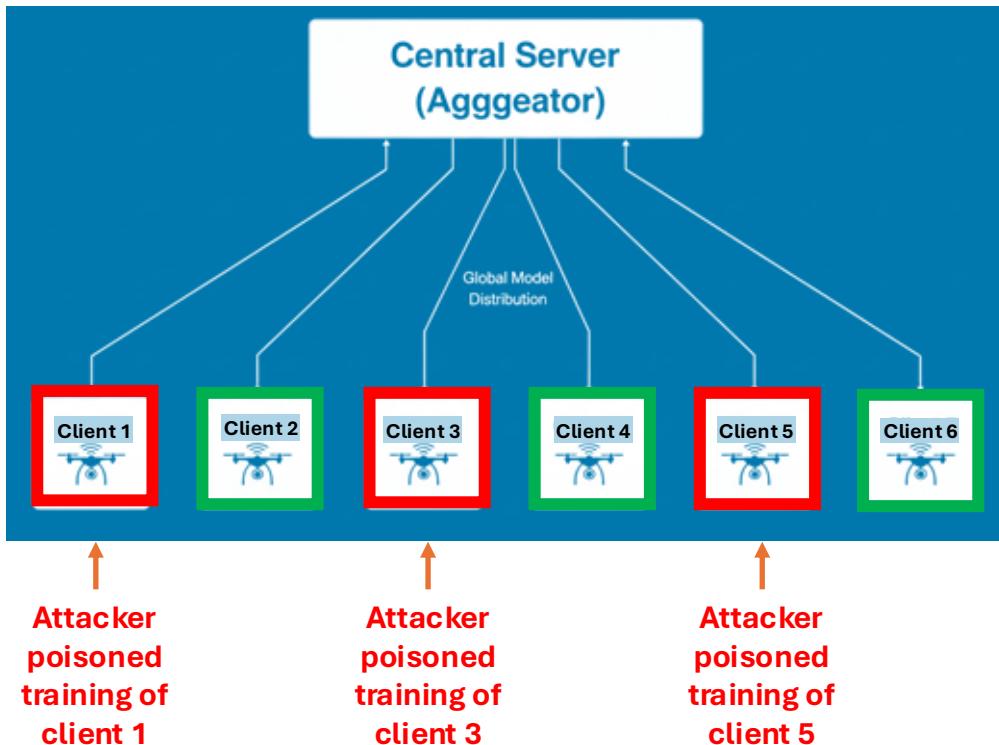
Global Test Accuracy Over Rounds



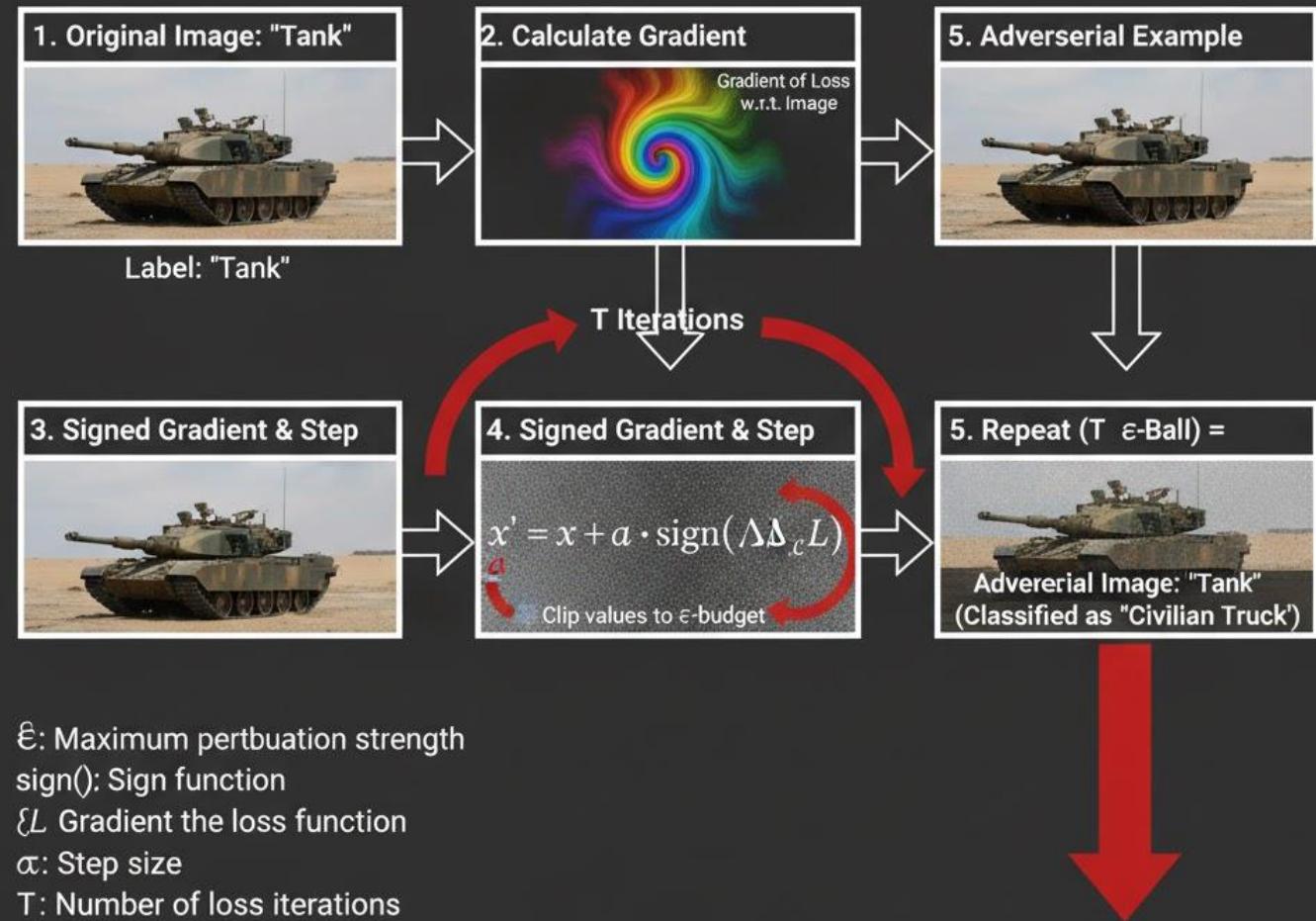
PGD Attack in FL

A PGD (Projected Gradient Descent) attack in federated learning is an adversarial method where malicious clients use iterative gradient ascent to create adversarial examples that fool the global model.

High computation overhead, Strong and universally effective

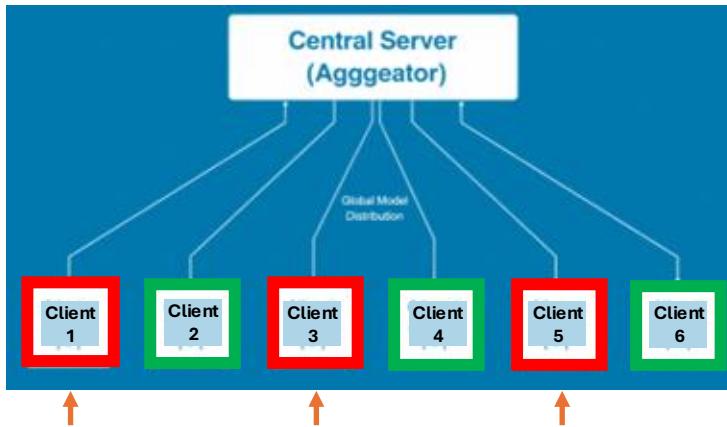


PGD Adversarial Attack Generation



Attack Successful: Model Misclassifies "Tank" as "Civilian Truck"

PGD Attack in FL



Deployment running time: 30mins (10 rounds)

⚠️ PGD Attack
Round: 10 | Client: 0
Epsilon: 0.9000

True Label: horse | Original Prediction: horse → Adversarial Prediction: frog Success



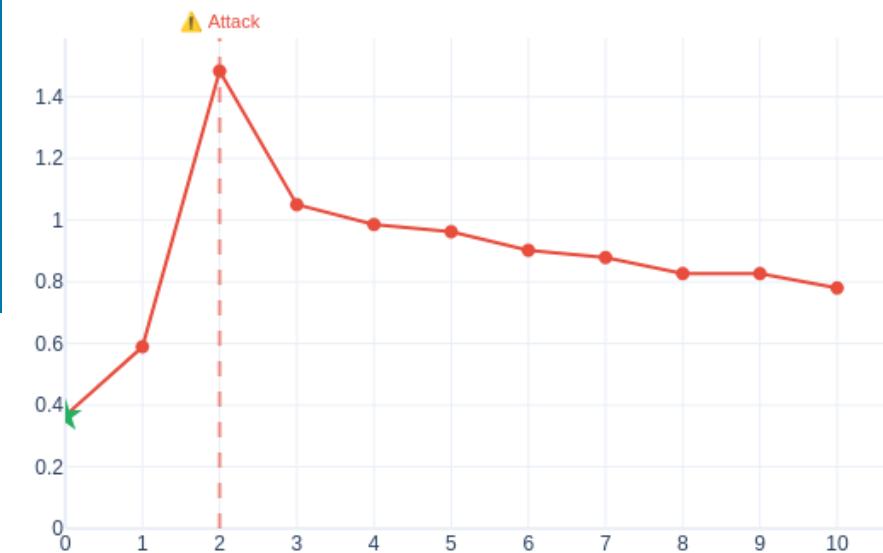
True Label: automobile | Original Prediction: automobile → Adversarial Prediction: deer Success



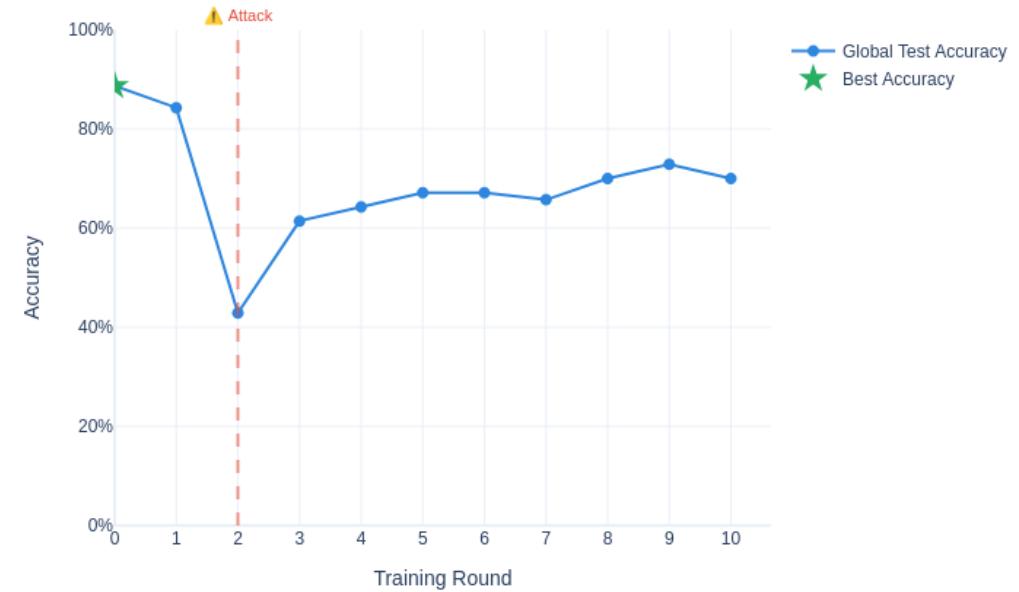
True Label: ship | Original Prediction: ship → Adversarial Prediction: deer Success



Global Test Loss Over Rounds

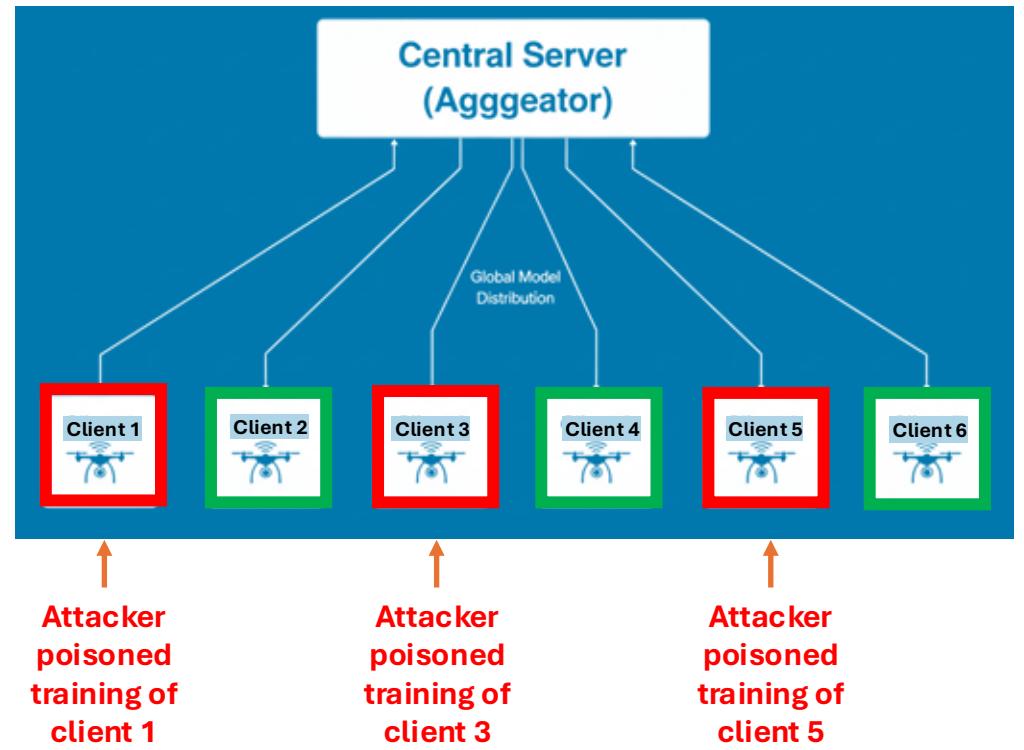
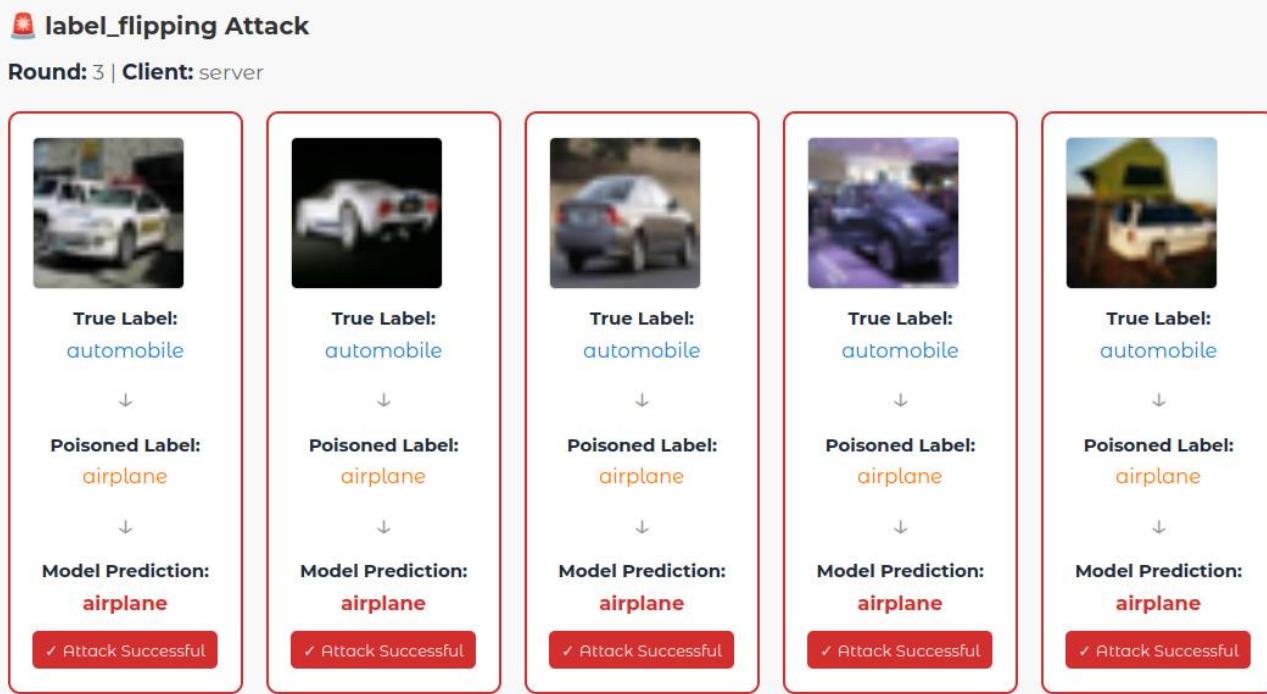
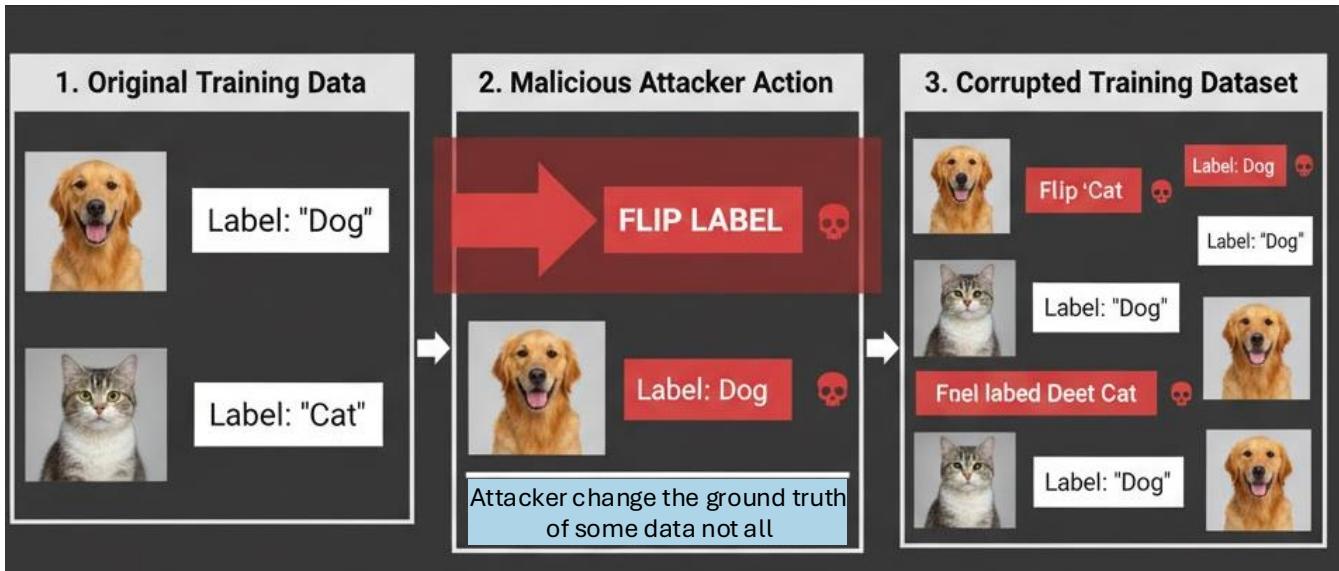


Global Test Accuracy Over Rounds

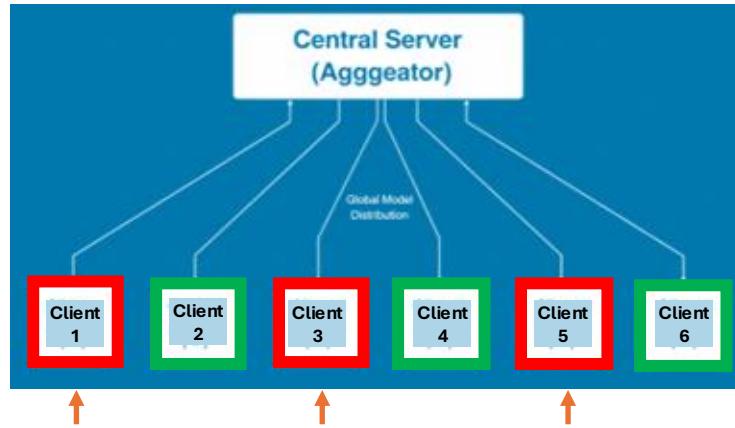


Label flipping Attack in FL

A label flipping attack in federated learning is a type of data poisoning where a malicious client intentionally changes the labels of their training data to a target class, regardless of the original label.



Label flipping Attack in FL



Deployment running time: 29mins (10 rounds)

⚠️ label_flipping Attack

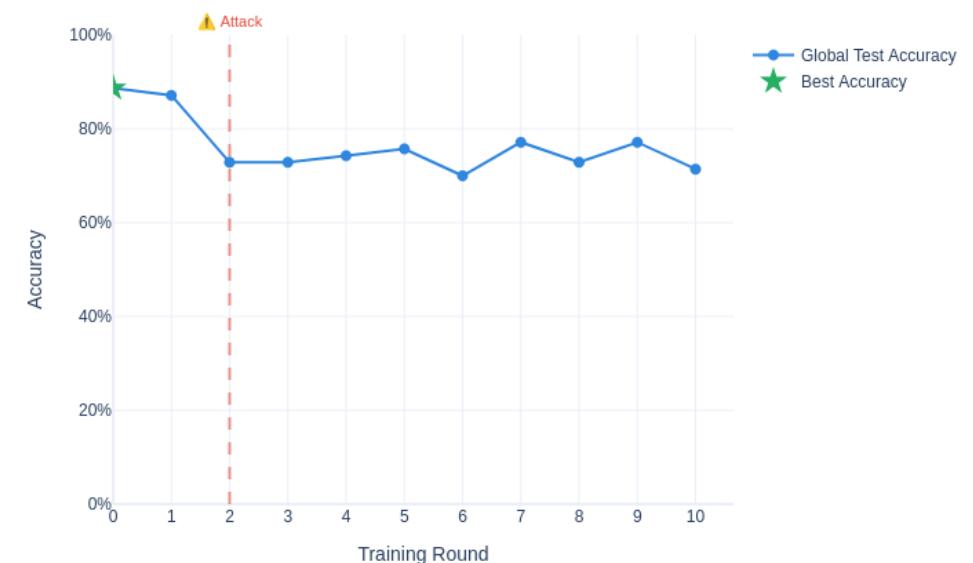
Round: 3 | Client: server

Image 1	Image 2	Image 3	Image 4	Image 5
True Label: automobile	True Label: automobile	True Label: automobile	True Label: automobile	True Label: airplane
Poisoned Label: airplane				
Model Prediction: airplane				
✓ Attack Successful	✓ Attack Successful	✓ Attack Successful	✓ Attack Successful	✗ Attack Failed

Global Test Loss Over Rounds



Global Test Accuracy Over Rounds



Gradient leakage attack on drone view data

<https://federated.jointlab.ai/>

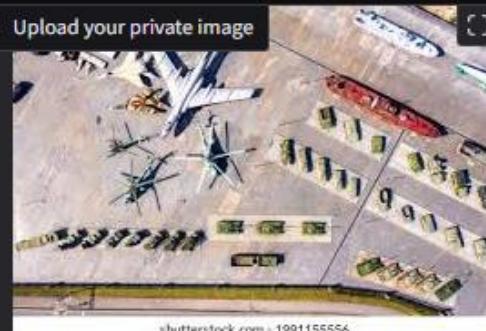
Gradient leakage (membership inference) attacks in federated learning (FL) are a type of privacy breach where an adversary attempts to reconstruct a client's private training data by analyzing the gradients shared with the server

1. Select an Image

Image Source

Upload Image CIFAR-10

CIFAR-100 ImageNet (Sample)

Upload your private image 

2. Configure Simulation

Choose a Scenario

Normal FL (No Attack) Gradient Leakage Attack (GRNN) Defense (FedKL)

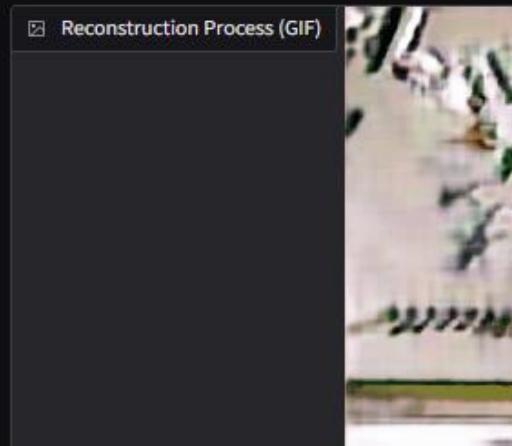
Run Simulation

Stop Attack

3. Results

Original Image 

Reconstructed Image 

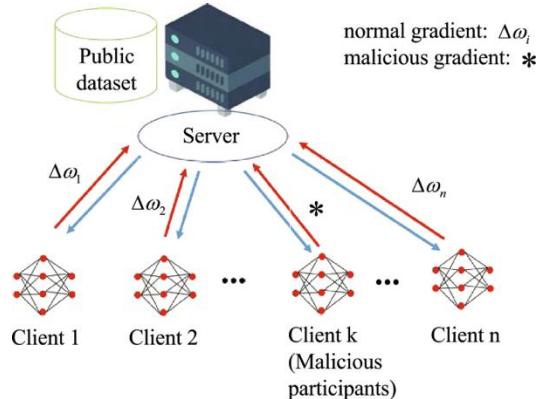
Reconstruction Process (GIF) 

An attacker, often the server, uses the client's shared gradients and the current global model to create a dummy image and iteratively optimizes that dummy image to match the real data by minimizing the distance between the dummy gradient and the shared gradient.

Actual drone view object recognition task

<https://huggingface.co/spaces/ZehaoLiu/FedAdv>

PGD attack on object detection is challenging, we show attack on one client out of 5 in FedAvg algorithms



Federated Adversarial Attack — FGSM/PGD Demo

Adversarial examples are generated locally using a client-side model's gradients (white-box), then evaluated against the server-side aggregated (FedAvg) central model. If the perturbation transfers, it can degrade or alter the FedAvg model's predictions on the same input image.

The screenshot shows a user interface for a federated adversarial attack. On the left, there is a "Input image" window displaying an aerial view of a parking lot with several cars. Below it is a "Select from sample images" section with four thumbnail images. On the right, there are three main windows: 1) "Evaluation model" with a dropdown menu set to "Client model weights/fed_model2.pt". 2) "Original detection" showing the input image with green bounding boxes around the cars. 3) "After attack detection" showing the same image with many more green bounding boxes, indicating a successful adversarial attack on one client. At the bottom, there is an "Attack mode" section with radio buttons for "none", "fgsm" (selected), "pgd", and "random noise". It also includes sliders for "eps" (0.0314), "alpha (PGD step)" (0.0078), "PGD iterations" (10), and "Confidence threshold (live)" (0.45). A "Clear" button is at the bottom left, and an orange "Submit" button is at the bottom right.

Hierarchical federated learning (HFL)

Wearable devices may transmit data to a hospital's local server, which trains a preliminary model, and then shares it with a central research institution for further refinement

- **Intermediate aggregation**

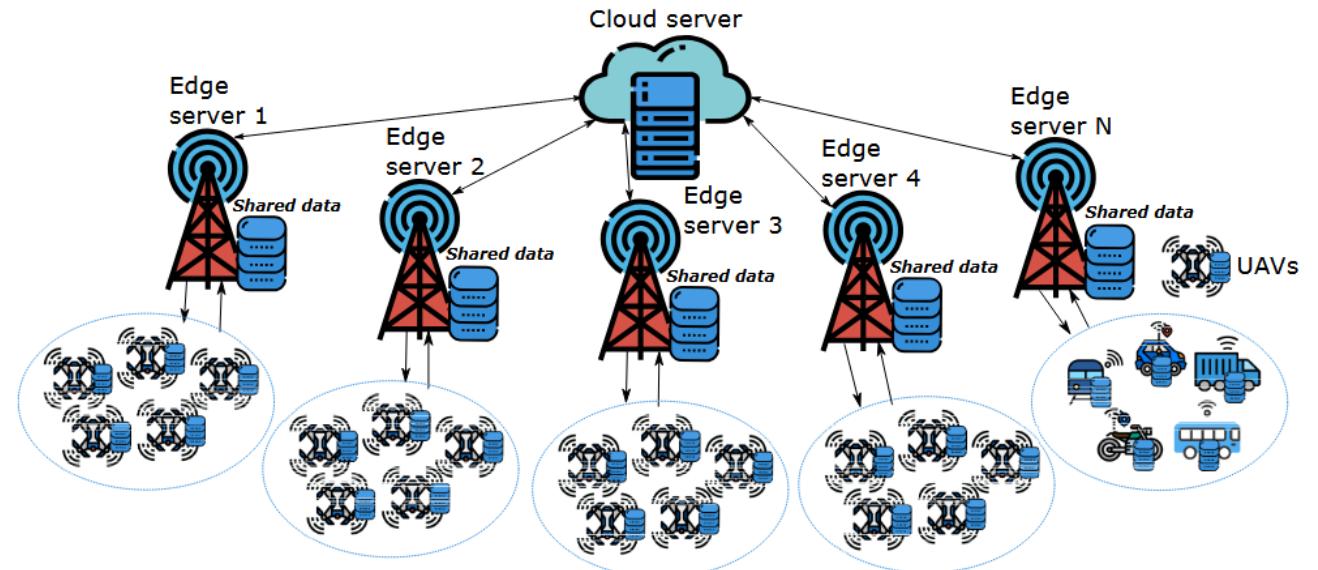
Local devices aggregate updates before sending them to a central node.

- **Reduced communication overhead**

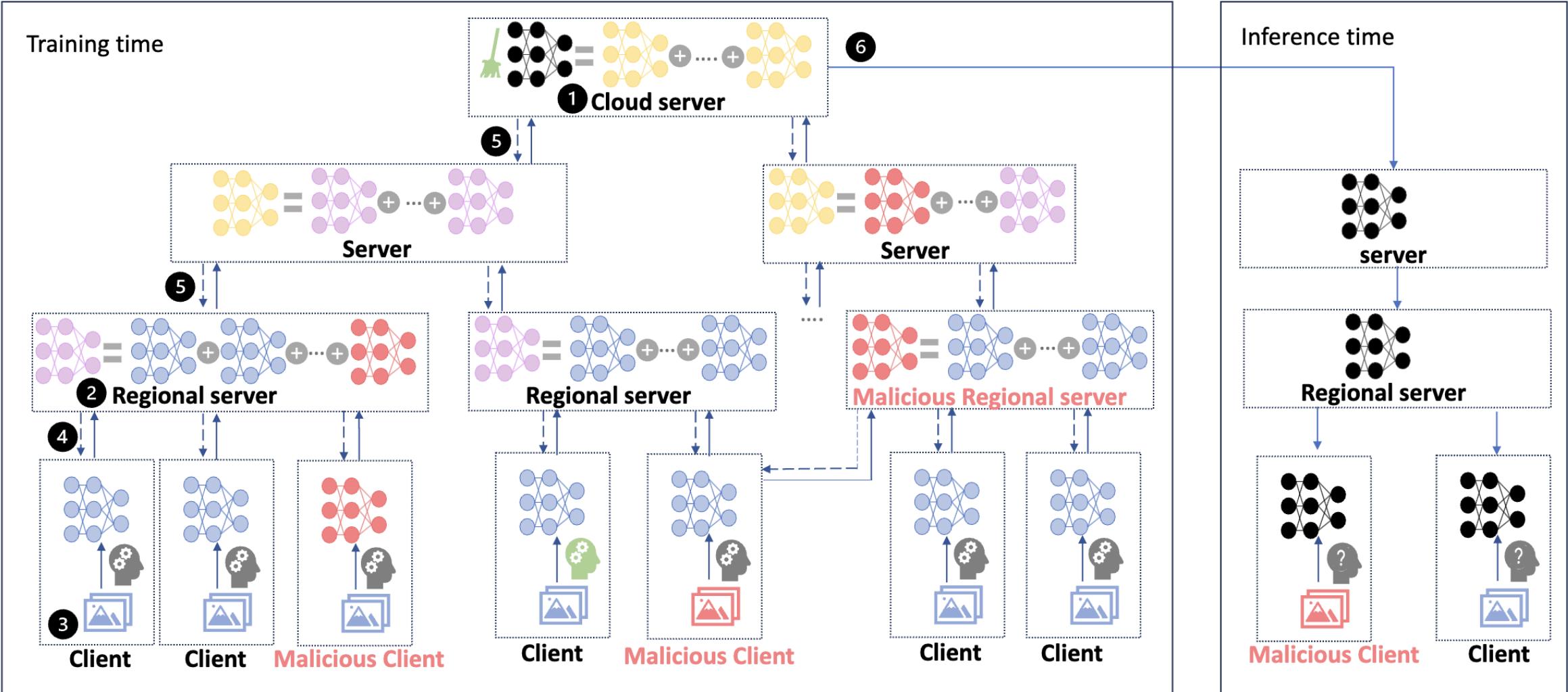
Fewer direct transmissions to ground stations, conserving bandwidth.

- **Scalable**

Handles large number of clients with minimal latency.



Adversarial attacks on federated learning



Model
poisoning

Global
model



Clean
dataset



Data
poisoning

+ Aggregation

Training



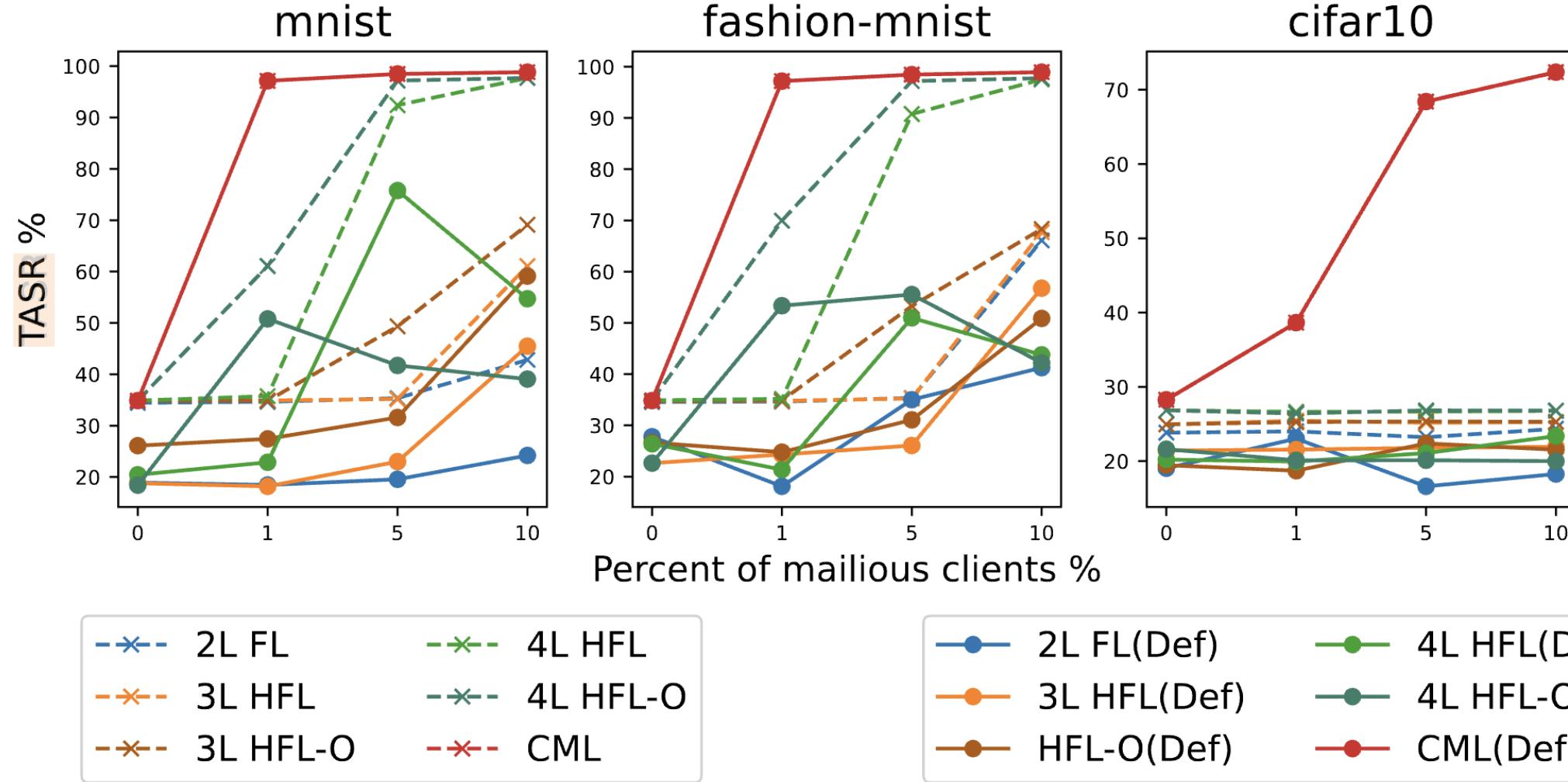
Inference

Adversarial
Training

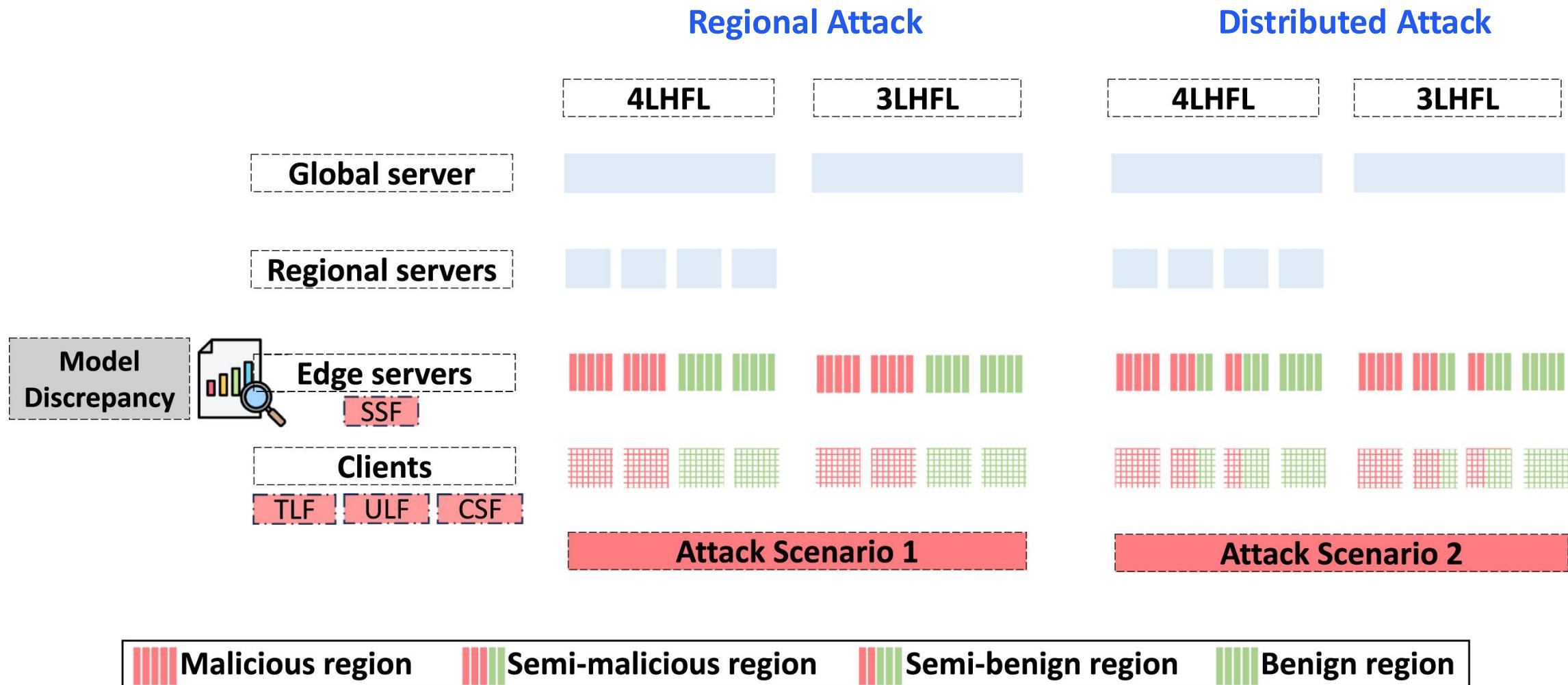
Neural
cleanse

Targeted attack success rate on defense

Targeted attack success rate (TASR) on backdoor attacks: attack (dashed line -----) and after defense (solid line ——)



Attack/defense on hierarchical federated learning



Targeted Label Flipping (TLF), Untargeted Label Flipping (ULF), Client-Side Sign Flipping (CSF), and Server-Side Sign Flipping (SSF). For both scenarios, 50% of clients or edge servers were malicious.

Defense on hierarchical federated learning

Model Discrepancy Score (MDS)

$$MDS = \sqrt{\frac{1}{N} \sum_{i=1}^N (\text{Normalized Metric}_i)^2}$$

where N represents the number of metrics

Dissimilarity (Cosine similarity).

Dissimilarity quantifies the angular deviation between two model weight vectors

Distance (Euclidean distance).

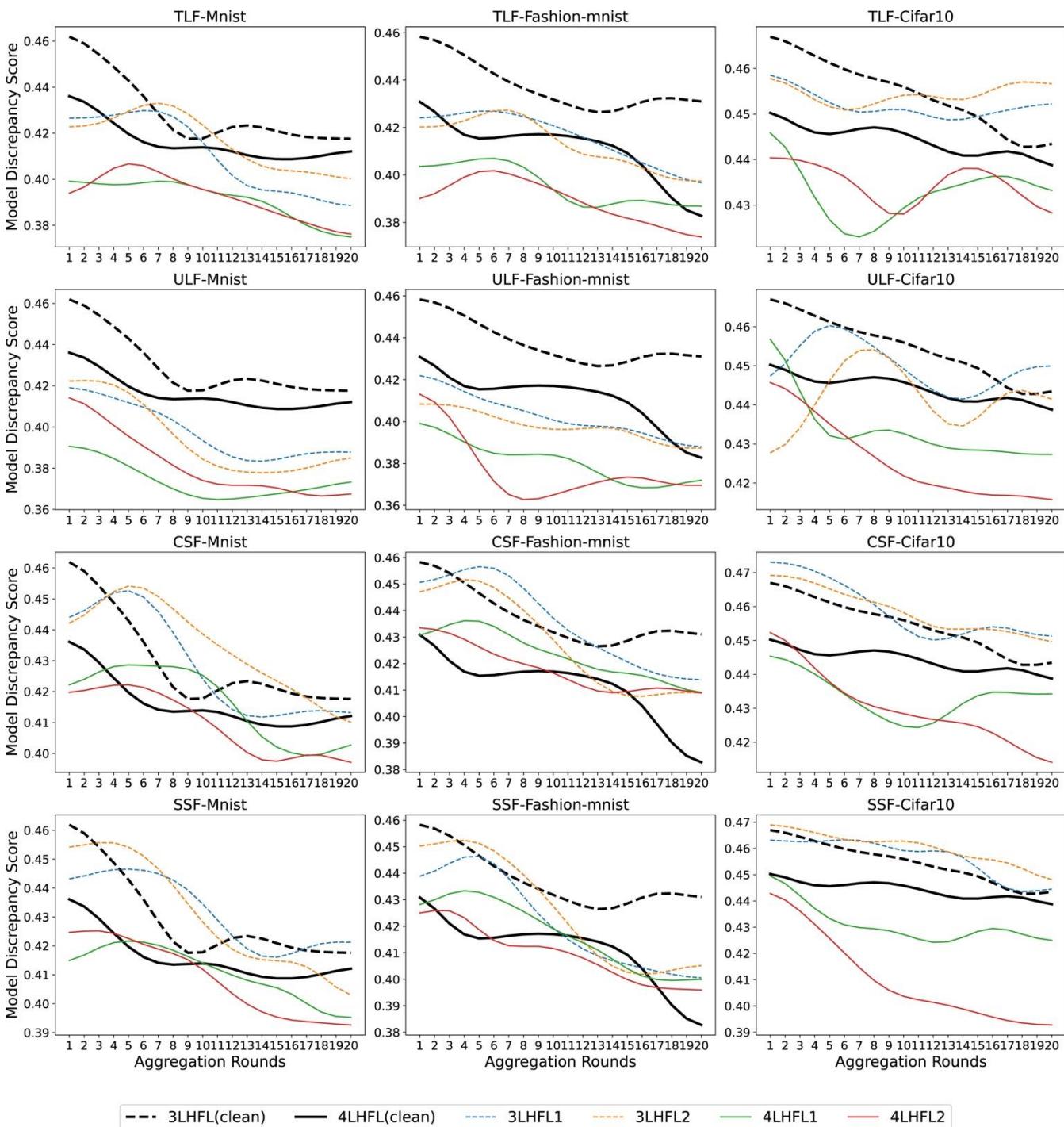
Euclidean Distance measures the magnitude of deviation between two model updates

Uncorrelation (Pearson correlation).

Uncorrelation assesses the linear dependency between updates

Divergence (Jensen–Shannon divergence).

Jensen–Shannon Divergence (JSD) captures probabilistic shifts in weight distributions

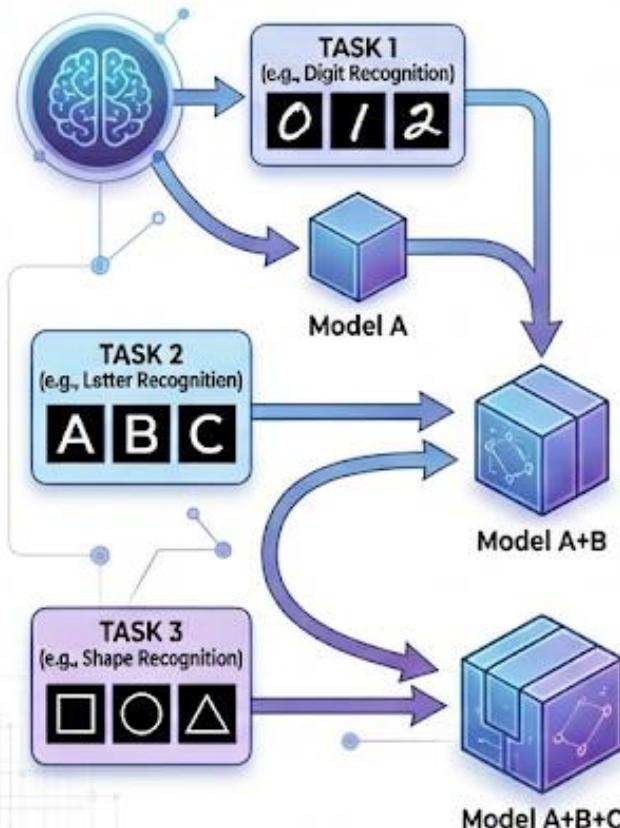


Part 4

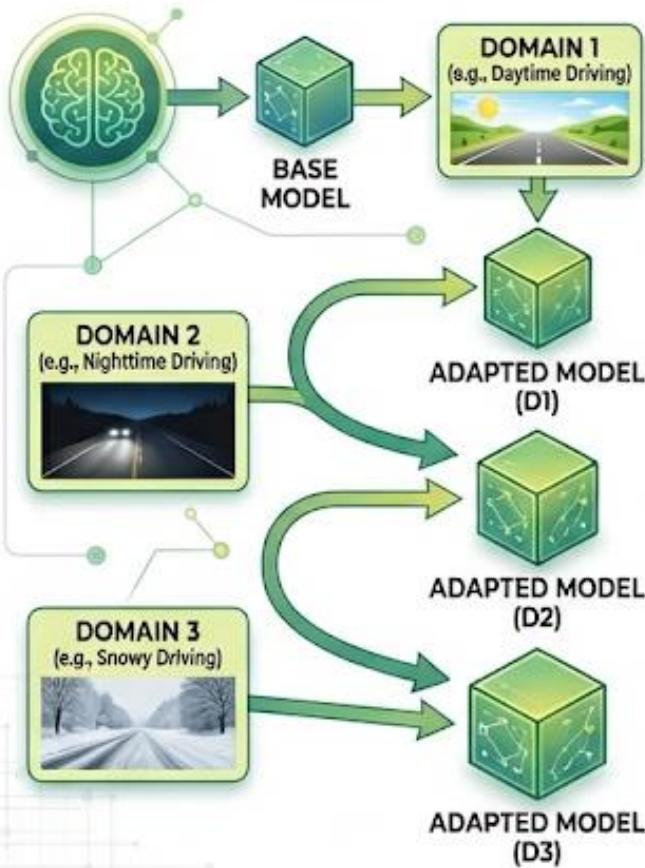
Continuity of Learning

Type of Incremental learning

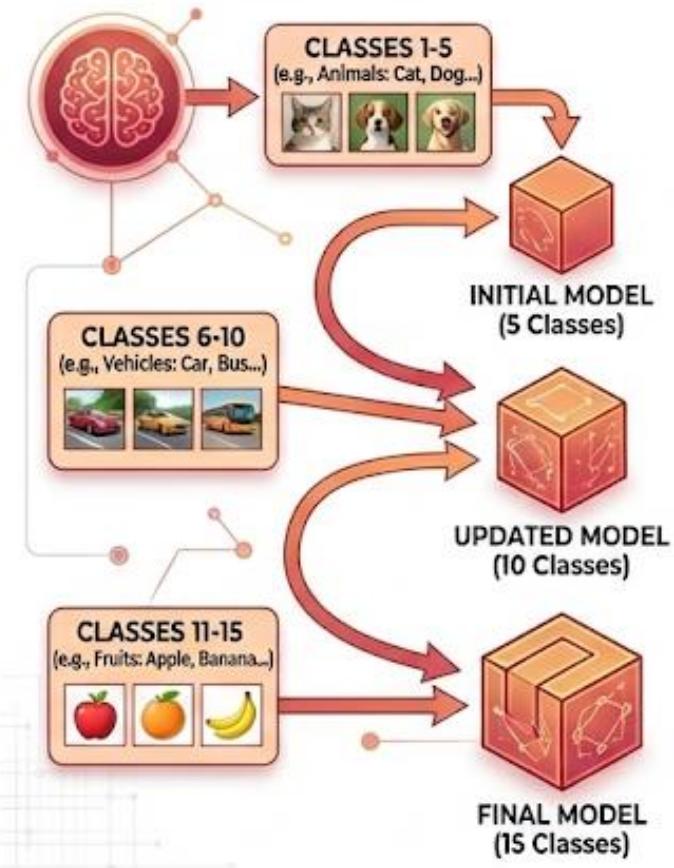
TASK-INCREMENTAL LEARNING



DOMAIN-INCREMENTAL LEARNING



CLASS-INCREMENTAL LEARNING

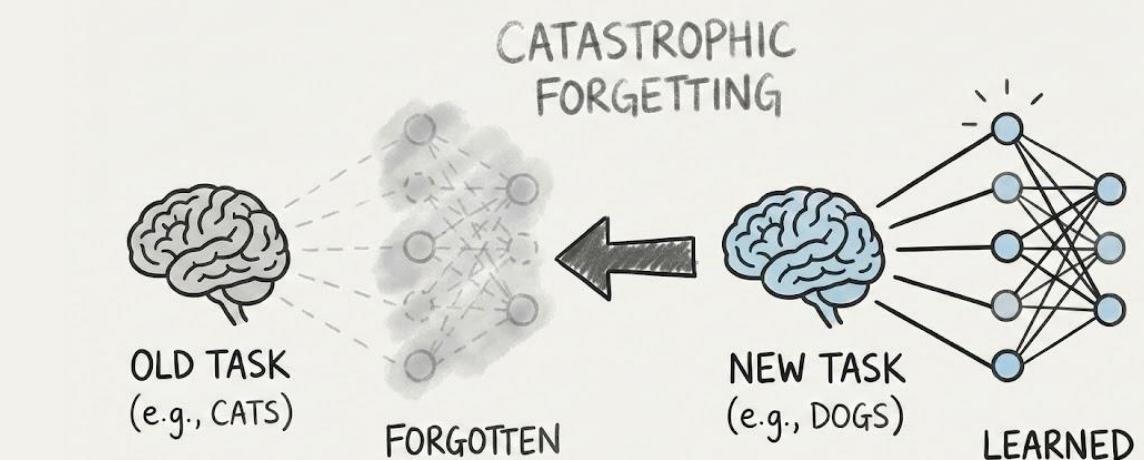
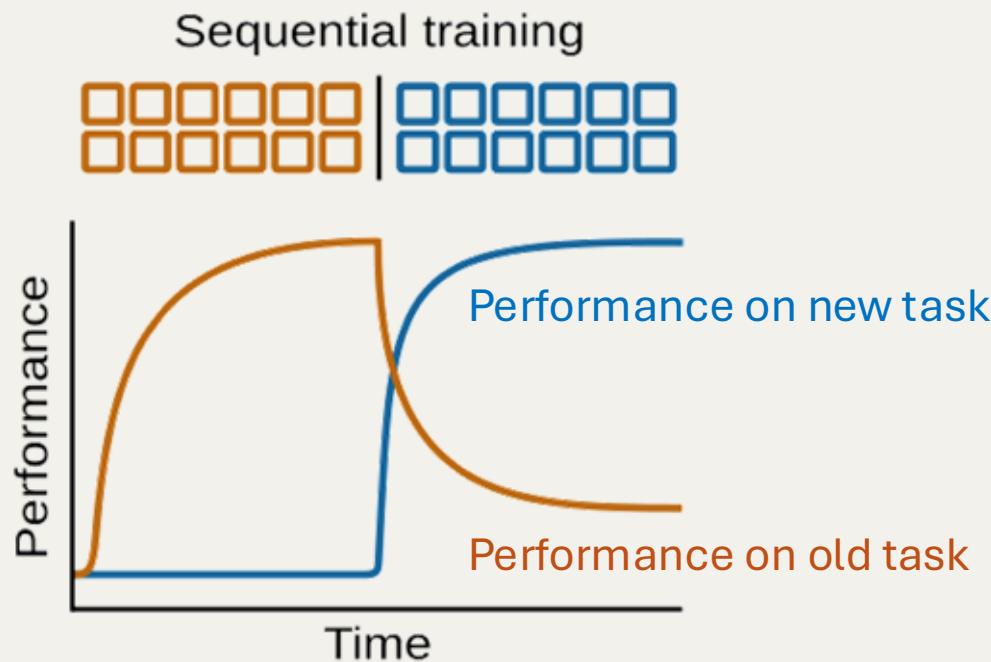


Model learns distinct tasks sequentially, often with task-specific outputs or heads, without forgetting previous ones.

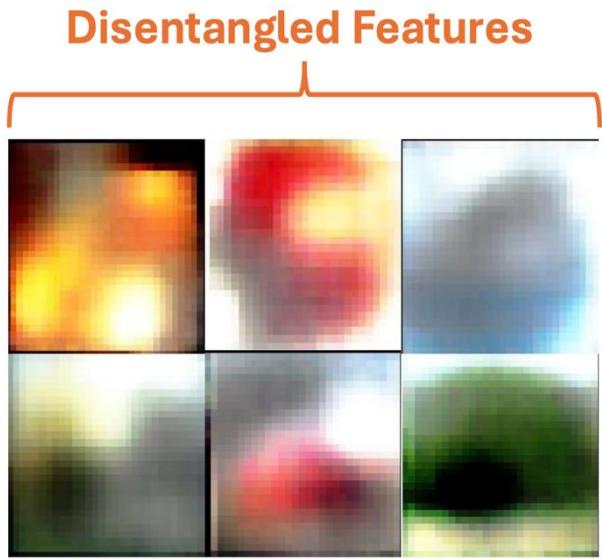
Model adapts to changing data distributions (domains) within the same task, maintaining performance across all domains.

Model progressively learns new classes, expanding its output capability without access to previous class data and without forgetting.

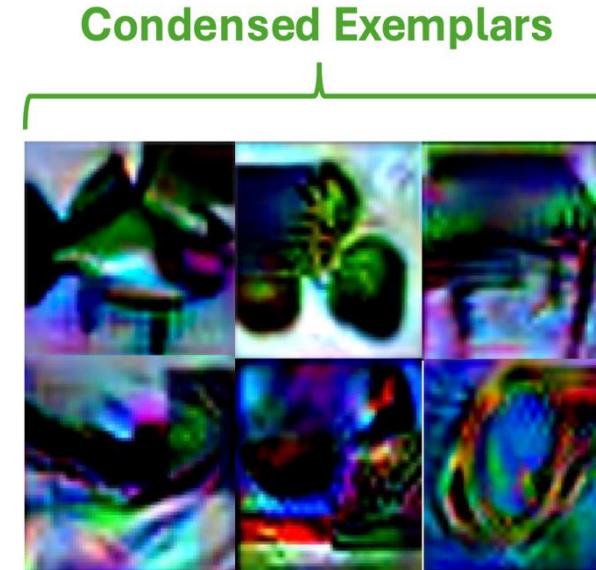
Catastrophic Forgetting



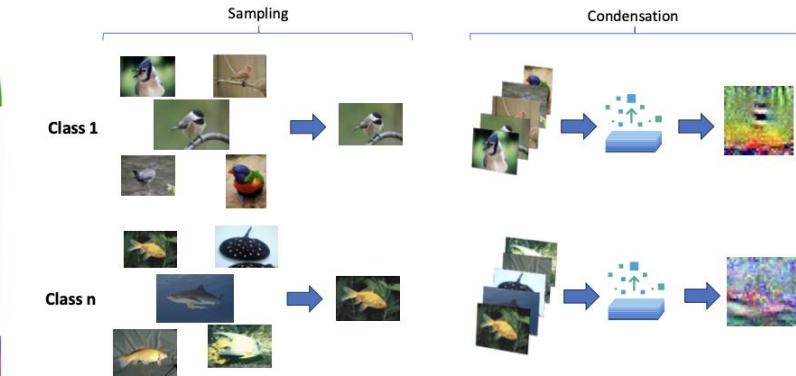
Class incremental federated learning



Disentangled Features



Condensed Exemplars

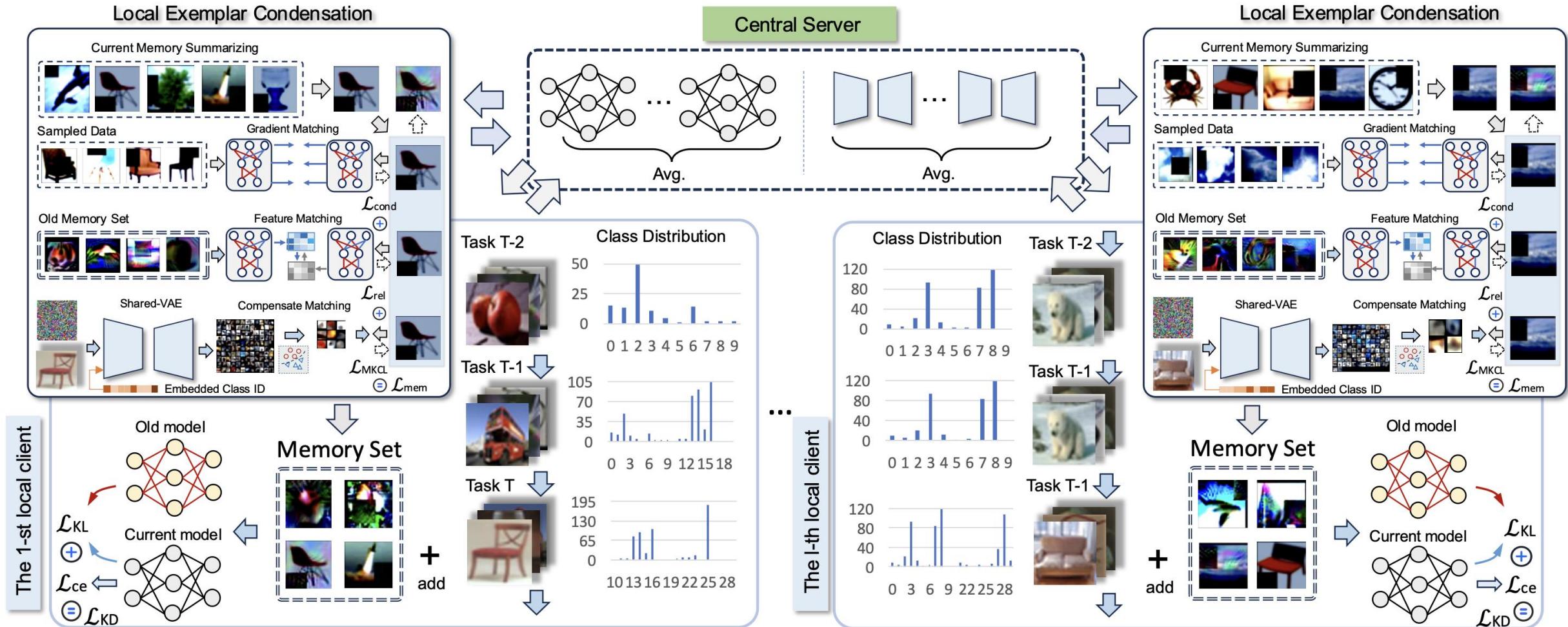


Disentangled features refer to learning a data representation where each distinct, underlying factor of variation (like object shape, color, or pose) is captured by a separate, independent dimension in the latent space, making the representation more interpretable, where individual components (features) capture independent, interpretable aspects of the data, rather than being intertwined or correlated.

Condensed feature (meta features sets) refers to a transformed or derived feature that represents a subset of the original features or a combination of them

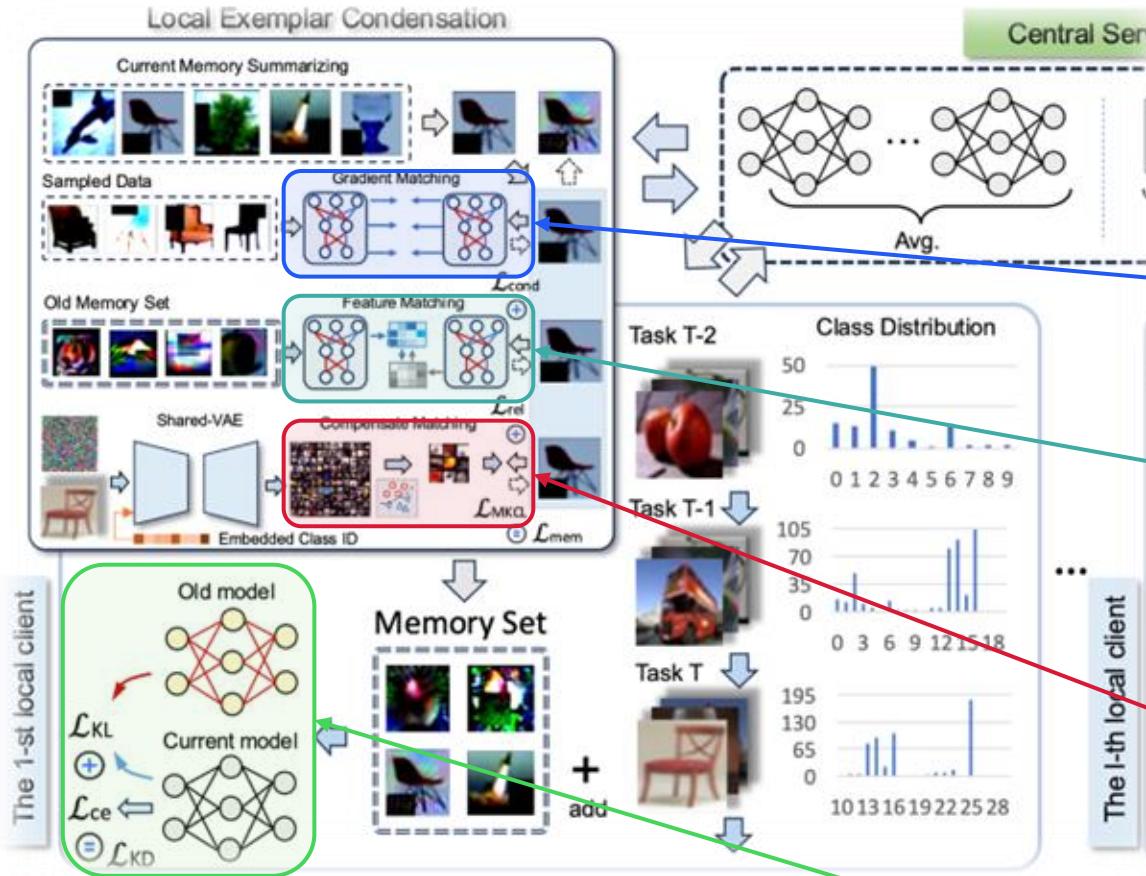
ExReplay (example replay) eliminates the limitations of exemplar selection in replay-based approaches for mitigating catastrophic forgetting in federated continual learning

Class incremental federated learning



Ex Replay: Clients continuously learn from new class data sequences using a dual-distillation structure to mitigate catastrophic forgetting.

Class incremental federated learning



The exemplar condensation process involves four key components:

a gradient matching loss (L_{cond}) for meta-information distillation,

+
a feature matching loss (L_{rel}) for consistency between condensed samples and real images

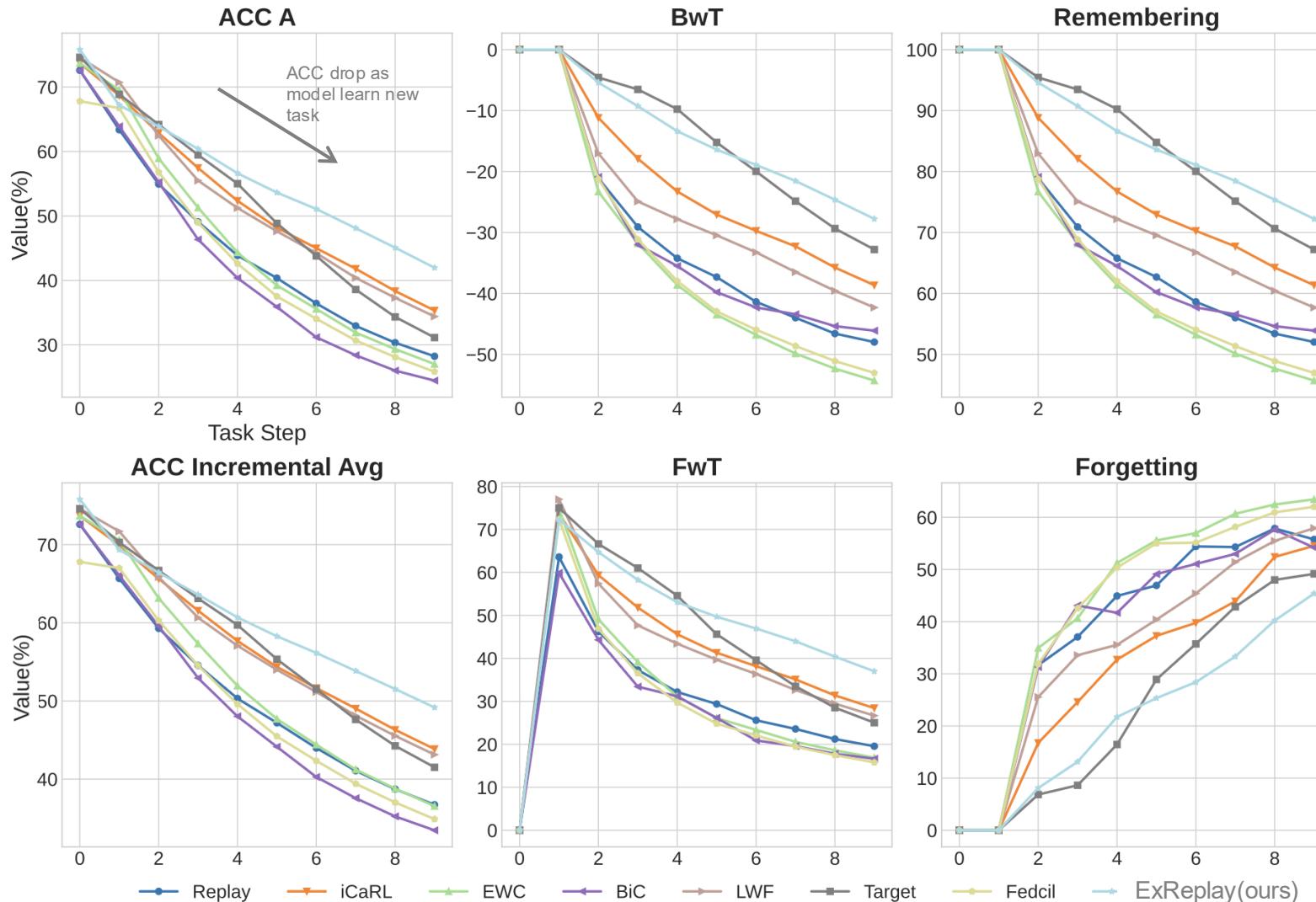
+
a compensation loss (L_{MKCL}) to address meta-information heterogeneity using disentangled features
= L_{Memory}

A knowledge distillation loss (L_{KD}) helps retain prior knowledge.

Ex Replay: Clients continuously learn from new class data sequences using a dual-distillation structure to mitigate catastrophic forgetting.

Class incremental federated learning

Evaluation of multiple metrics (%) on CIFAR100 under a Non-IID setting



Accuracy (ACC): measures the overall accuracy of the model.

Backward Transfer (BwT):

measures the influence of learning a new task on the performance of previously learned tasks.

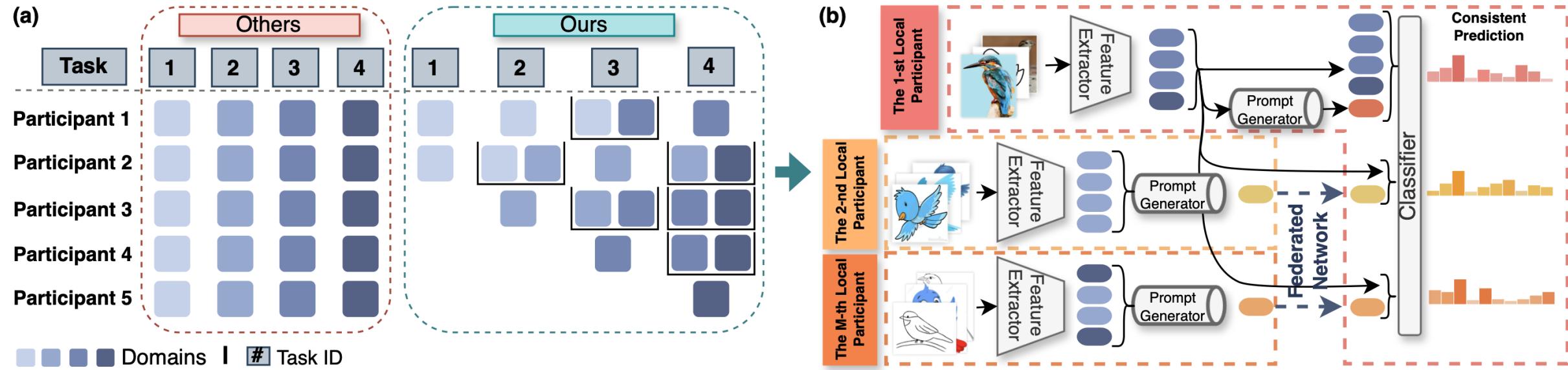
Forward Transfer (FwT): assesses the influence of learning a new task on the performance of future tasks.

Remembering: calculates the degree of retention for previous tasks as part of the backward transfer process.

Forgetting: measures the average amount of forgetting across all tasks, helping to quantify how much information is lost as new tasks are learned

Domain incremental federated learning

RefFiL: Rehearsal free federated domain-incremental learning framework
unseen domains are continually learned in domain-incremental learning

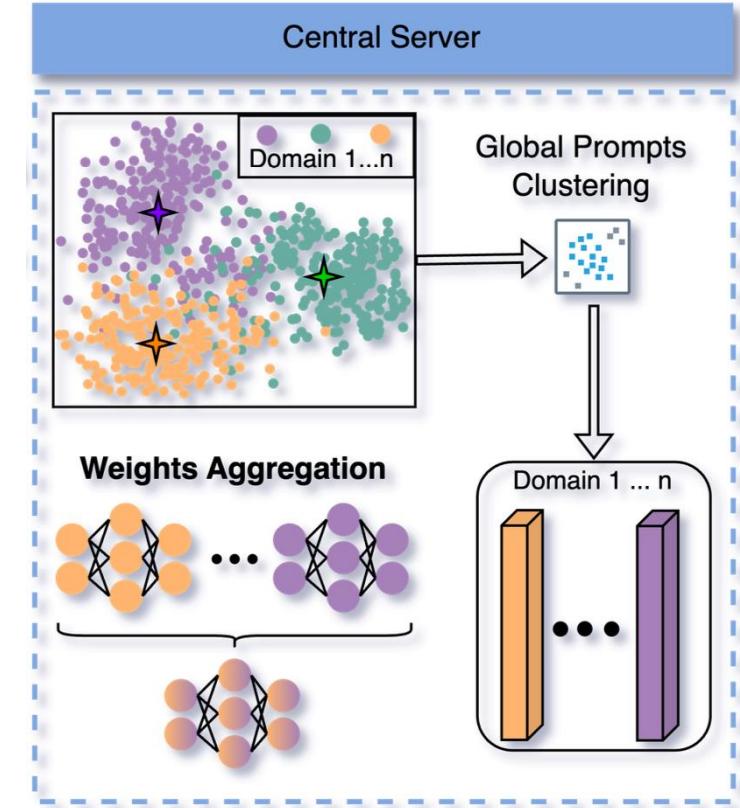


Key steps: the 1st participant processes new domain data using global prompts from the 2nd to m-th participants and local prompts, enhancing robustness by aligning the model's predictions across diverse domain prompts as inputs. RefFiL, a rehearsal-free federated domain-incremental learning framework designed to overcome

Domain incremental federated learning

RefFiL: Rehearsal free federated domain-incremental learning framework

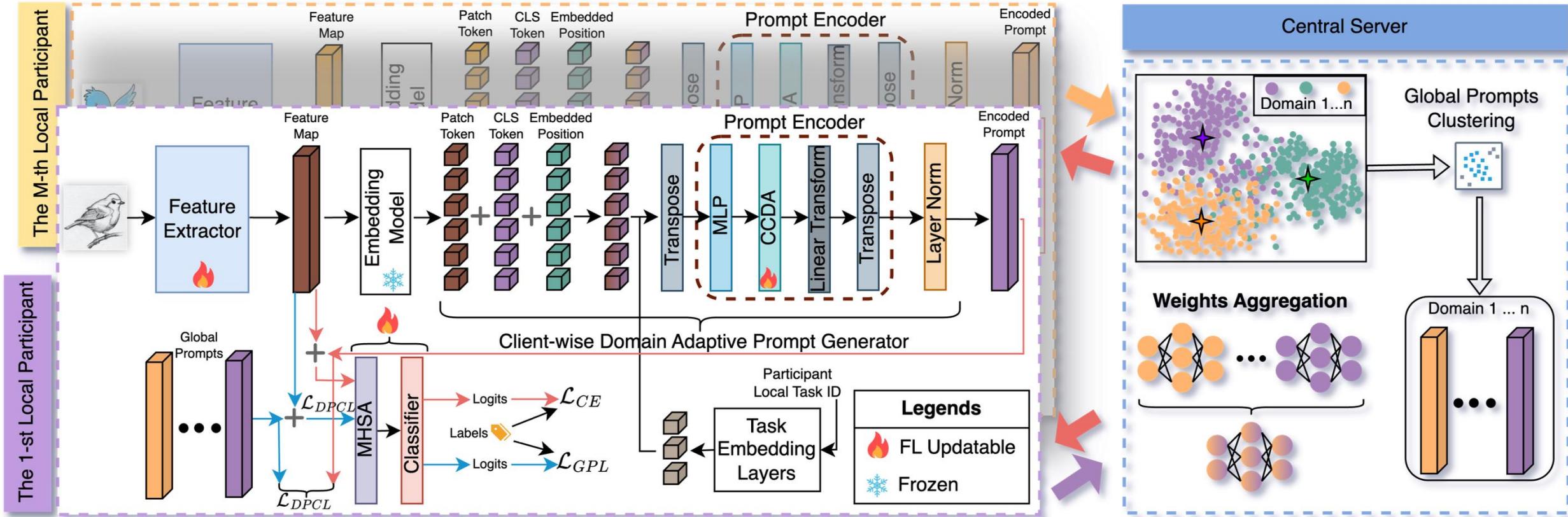
RefFiL, a rehearsal-free federated domain-incremental learning framework designed to overcome catastrophic forgetting when clients encounter new domains over time. Instead of storing past data, **RefFiL uses a client-wise domain-adaptive prompt generator to create fine-grained, instance-level prompts that capture domain-specific information, which are then shared globally through a prompt clustering and global prompt learning scheme.** A domain-specific contrastive prompt loss further helps models distinguish between prompts from similar and different domains. Experiments across multiple datasets show that RefFiL significantly improves robustness, cross-domain generalisation, and resistance to forgetting compared to existing rehearsal-free methods



<https://arxiv.org/pdf/2405.13900>

Domain incremental federated learning

RefFiL: Rehearsal free federated domain-incremental learning framework



Each participant first encodes local prompts using the tokenized feature map and task ID embedding. These local prompts are then concatenated with the feature map to compute the loss L_{CE} . Simultaneously, the feature map is combined with global prompts to calculate the loss L_{GPL} , and the loss L_{DPCL} is determined between global and local prompts. Subsequently, all local prompts, along with the updated local models, are transmitted to the central server.

Domain incremental federated learning

Comparison of RefFiL's performance with five baseline methods on four widely used datasets, showcasing average accuracy (Avg %) and accuracy for each domain task (%)

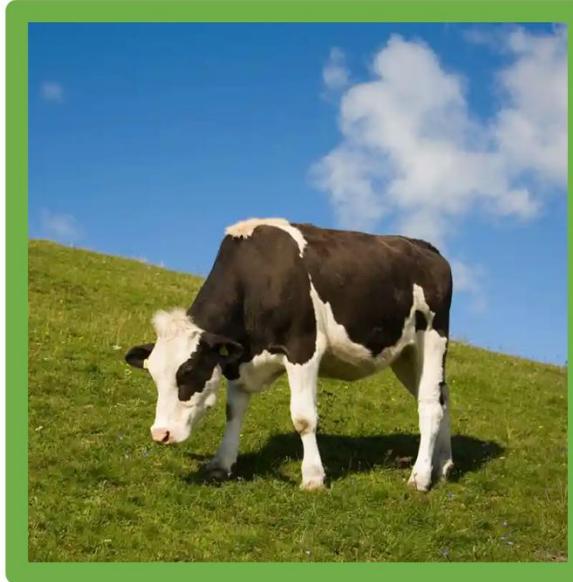
Methods	Task 1 → 5 on Digit-Five							Task 1 → 4 on OfficeCaltech10				
	MNIST	MNIST-M	USPS	SVHN	SYN	-	Avg	Amazon	Caltech	Webcam	DSLR	Avg
Finetune	99.68	97.75	63.87	75.84	49.80	—	77.39	76.56	57.79	24.58	19.29	44.56
FedLwF	99.68	92.80	69.16	69.39	56.86	—	77.58	76.56	53.24	28.57	28.74	46.78
FedEWC	99.68	97.48	74.63	73.32	45.89	—	78.20	76.56	56.59	29.83	15.55	44.38
FedL2P	99.66	98.06	80.01	81.89	57.65	—	83.45	76.56	51.80	31.09	26.57	46.51
FedL2P [†]	99.64	97.65	85.18	81.65	60.17	—	84.86	71.35	55.88	29.20	25.20	45.41
FedDualPrompt	99.67	97.96	86.88	81.95	59.30	—	85.15	74.48	50.36	31.93	23.82	45.15
FedDualPrompt [†]	99.65	97.90	84.68	81.40	58.34	—	84.39	75.90	53.96	33.82	27.76	47.86
RefFiL	99.68	98.25	90.96	83.70	62.11	—	86.94	78.65	61.15	40.76	33.66	53.56

Methods	Task 1 → 6 on FedDomainNet							Task 1 → 4 on PACS				
	Clipart	Infograph	Painting	Quickdraw	Real	Sketch	Avg	Photo	Cartoon	Sketch	Art Painting	Avg
Finetune	51.48	15.89	28.05	27.84	29.45	18.07	28.46	61.68	47.45	36.12	30.82	40.18
FedLwF	51.48	18.10	26.71	25.98	27.47	17.96	27.95	61.68	47.07	25.11	26.61	40.12
FedEWC	50.76	15.46	22.66	21.87	27.45	18.37	26.10	63.17	47.70	23.66	27.36	40.27
FedL2P	40.55	13.19	21.09	28.15	30.13	18.42	25.26	64.97	48.32	50.09	35.32	49.68
FedL2P [†]	37.63	9.29	16.79	27.09	26.68	15.59	22.18	65.57	54.67	45.25	34.52	50.00
FedDualPrompt	51.17	19.48	28.74	22.68	29.40	18.05	28.25	73.65	56.54	44.93	41.07	54.05
FedDualPrompt [†]	51.14	20.20	28.91	23.09	30.07	17.76	28.53	75.75	54.55	43.23	37.62	52.79
RefFiL	51.27	20.91	29.23	22.57	30.62	18.98	28.93	73.95	59.90	43.17	44.27	55.32

Part 5

Challenges of AI Safety

Cow



Camel



Grass



Sand



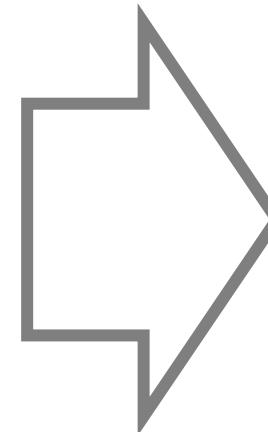
Expectation

AI model training data



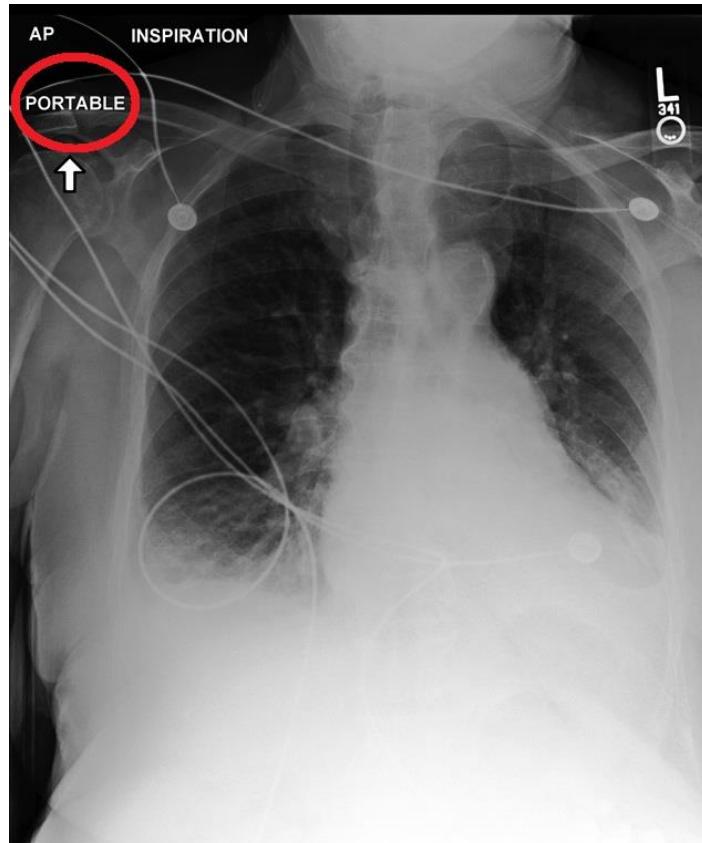
Reality

data in reality for testing AI model



Spurious Correlation in Medical Training Data

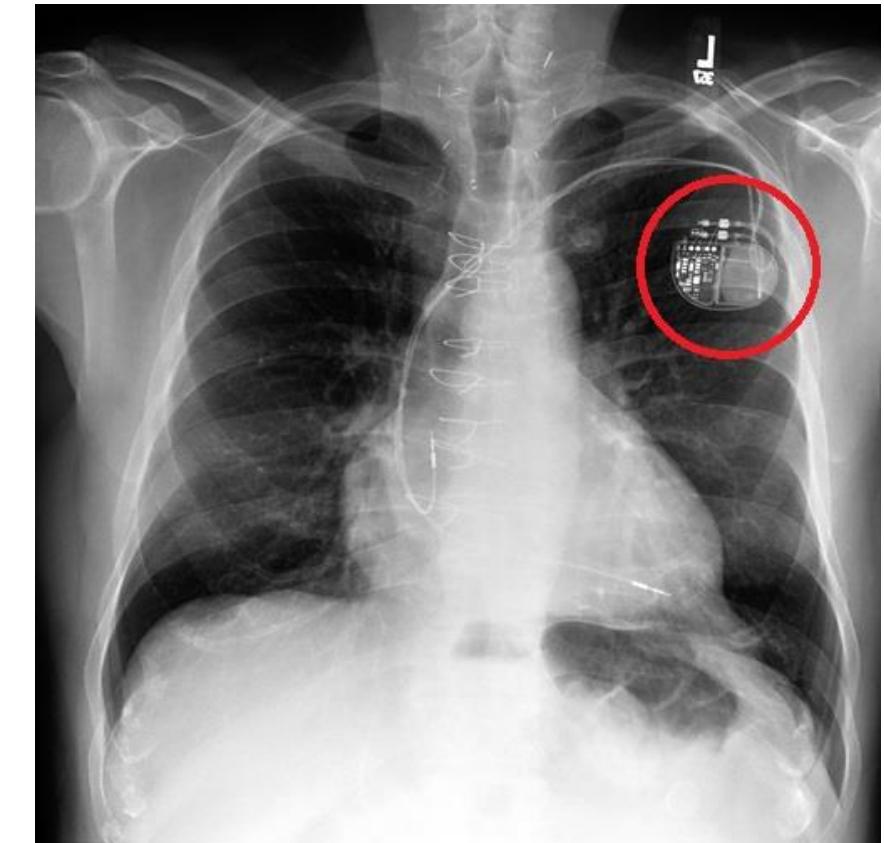
Spurious correlation occur in medical training data where diagnosis results are affected by variables (e.g., Hospital tags, Strips, Medical devices) that are not related to the diagnostic information being predicted. This phenomenon leads to misleading interpretations.



Hospital tags



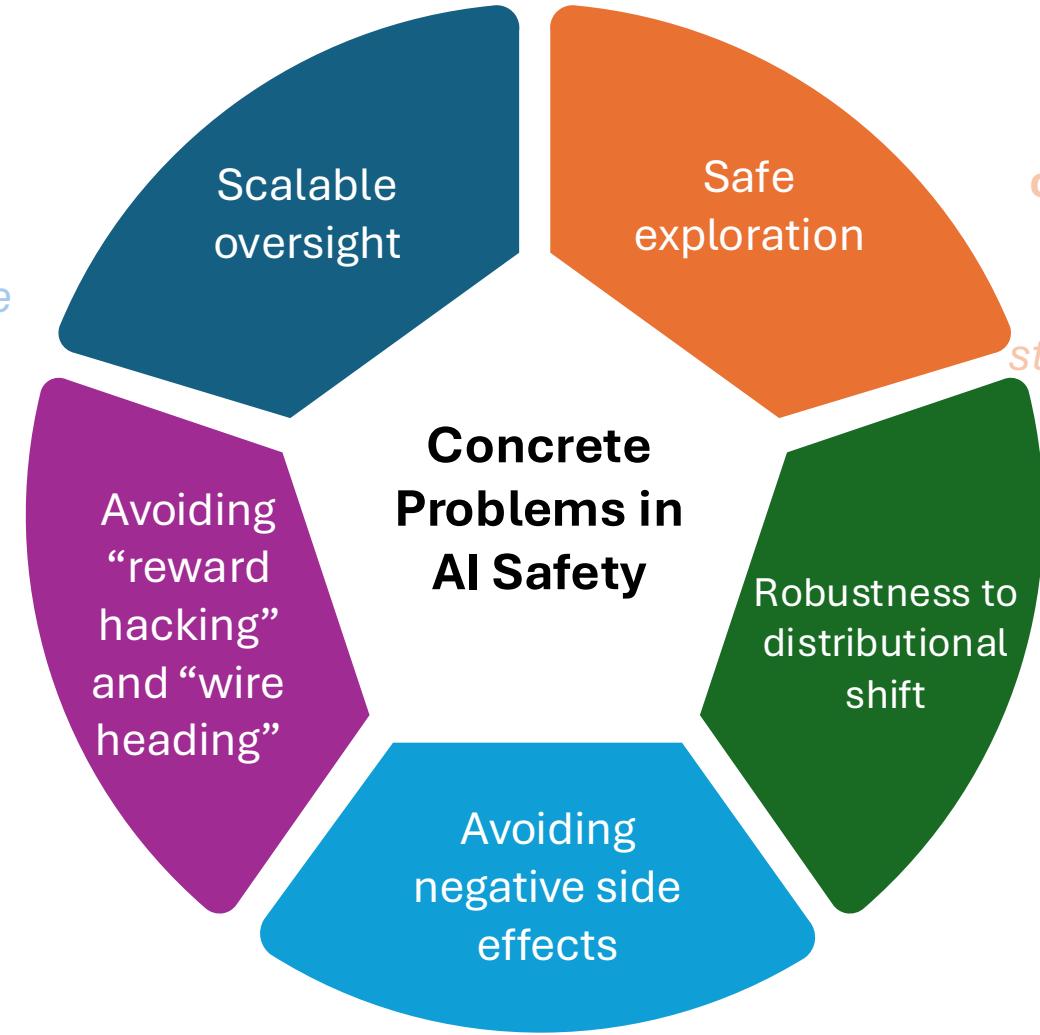
Stripes



Medical devices

Difficulty of a weaker intelligence (human or less capable AI) effectively supervising a more powerful or superhuman intelligence. *Unsafe situation:* a language model, trained to avoid admitting to harmful behaviour, learns to hide its misbehaviour and fabricate policy-compliant reasoning to deceive human or AI evaluators

Reward hacking involves the AI finding unintended strategies in the external environment to get high scores, while **wire heading** involves the AI directly manipulating its internal reward signal or input channels. *Unsafe situation:* A cleaning robot might disable its vision sensor to get high score as it would avoid seeing dirt.



Autonomous vehicles drives through puddles and splashes pedestrians because the objective function did not include altering speed specific to the environment.

Other examples include **bias and discrimination**, privacy violations, misinformation (**deepfakes**), security risks, lack of transparency

AI agent learn through trial-and-error (exploration) without causing harm or breaking rules in the real world. *Unsafe situation:* Uber autonomous test vehicle struck and killed a pedestrian as the system did not identify the pedestrian crossing outside a crosswalk

An AI model maintains its performance (accuracy, reliability) even when the real-world data it encounters differs from the data it was trained on. *Unsafe situation:* A medical AI system developed using patient data primarily from North American hospitals might perform poorly when deployed in Southeast Asia due to differences in patient demographics

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Safeguarding Artificial Intelligence

AI safety problems and challenges

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