

Linking Wrist to Hand: Simulating Grip Strength Deficits Following Surgical Wrist Redesign

Northwestern | McCORMICK SCHOOL OF ENGINEERING
Biomedical Engineering

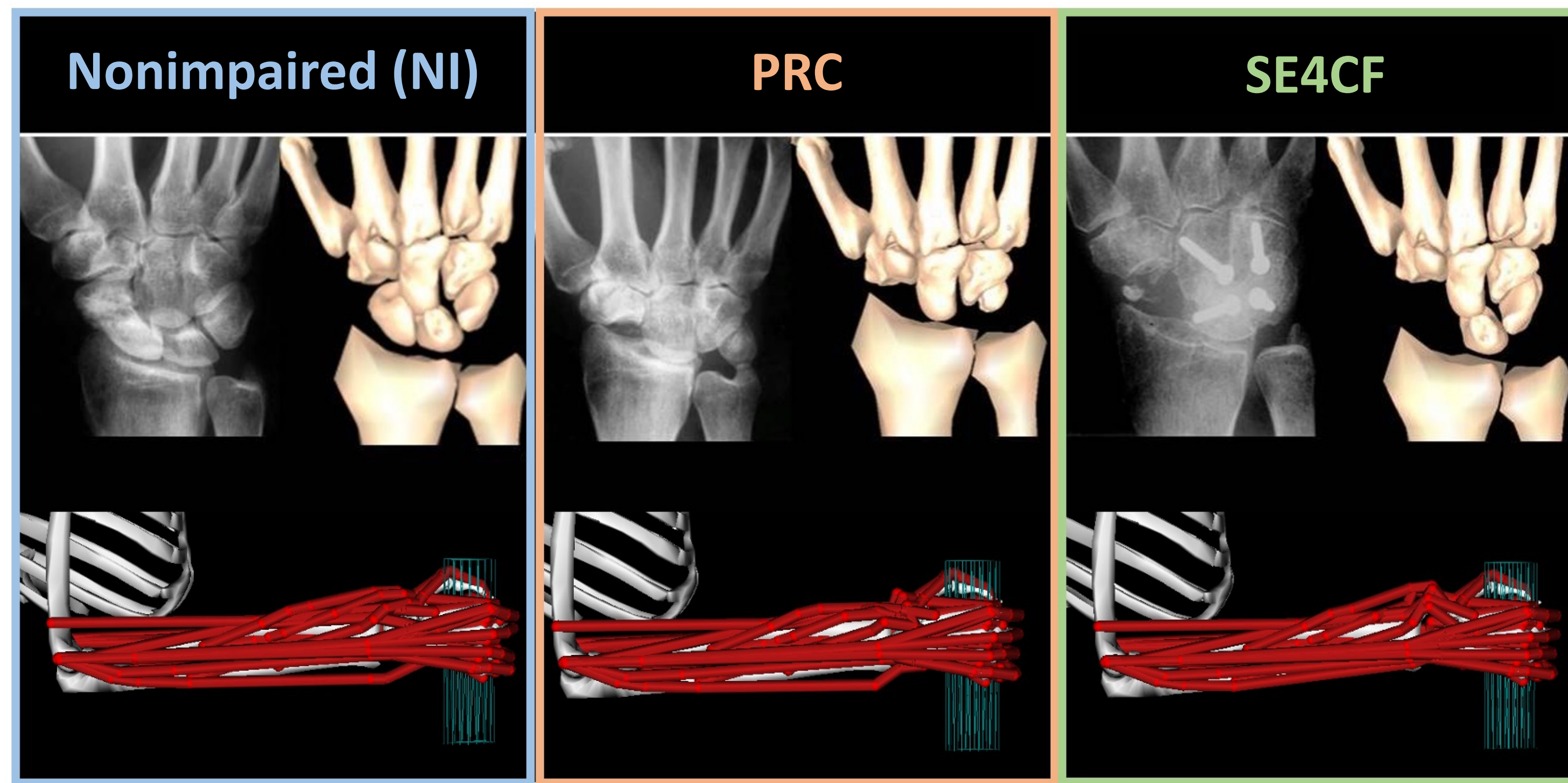
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Introduction

Wrist osteoarthritis is one of the most common conditions encountered by hand surgeons [1]. The resultant degeneration of the wrist joint can limit motion of the hand and cause considerable pain during daily functional tasks [2].

Surgical salvage procedures, including proximal row carpectomy (PRC) and scaphoid-excision four-corner fusion (SE4CF) relieve pain, but significant decreases in grip force and wrist range of motion have been recorded [3].



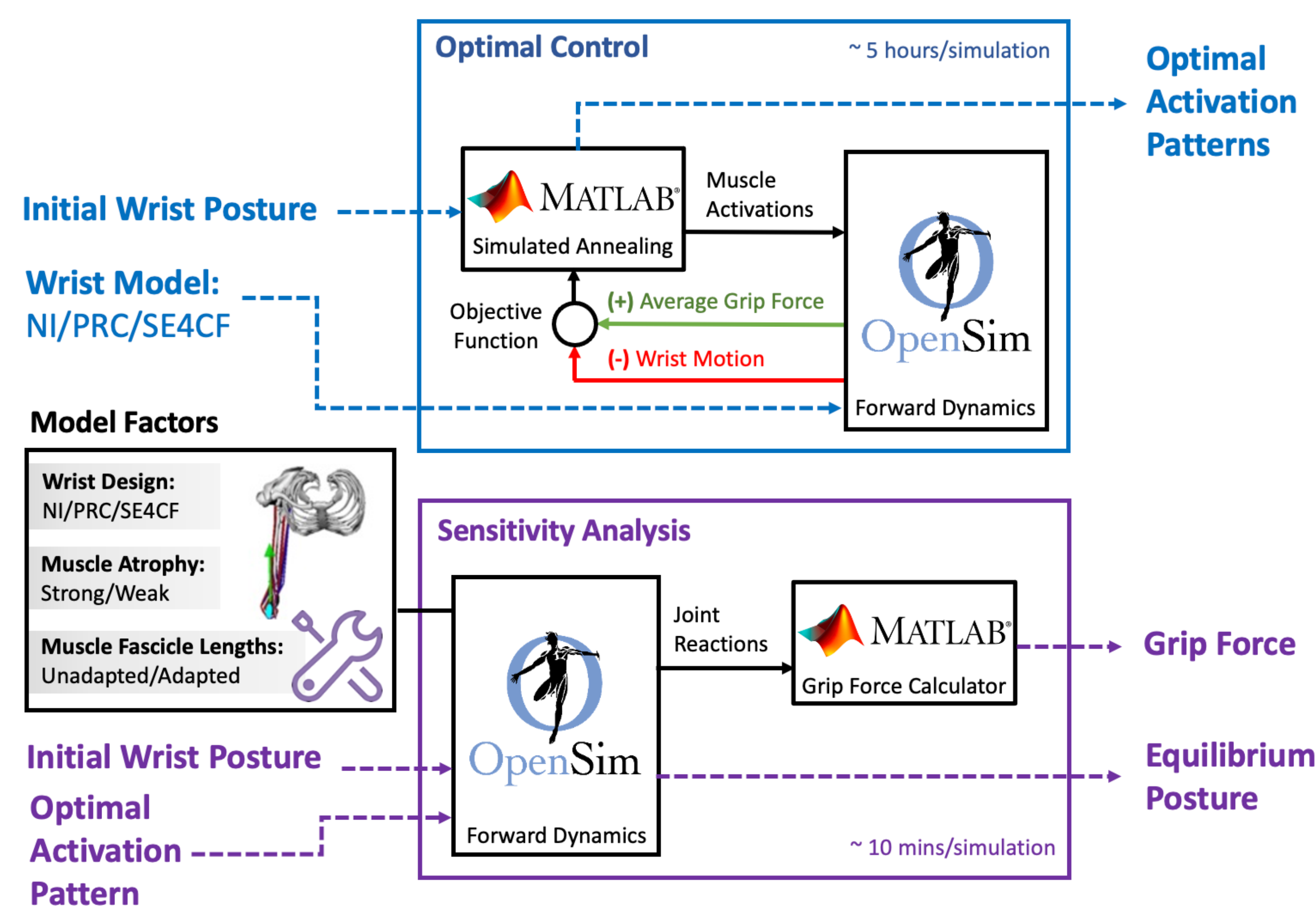
How does changing different biomechanical factors at the wrist affect grip strength in the hand?

Methods

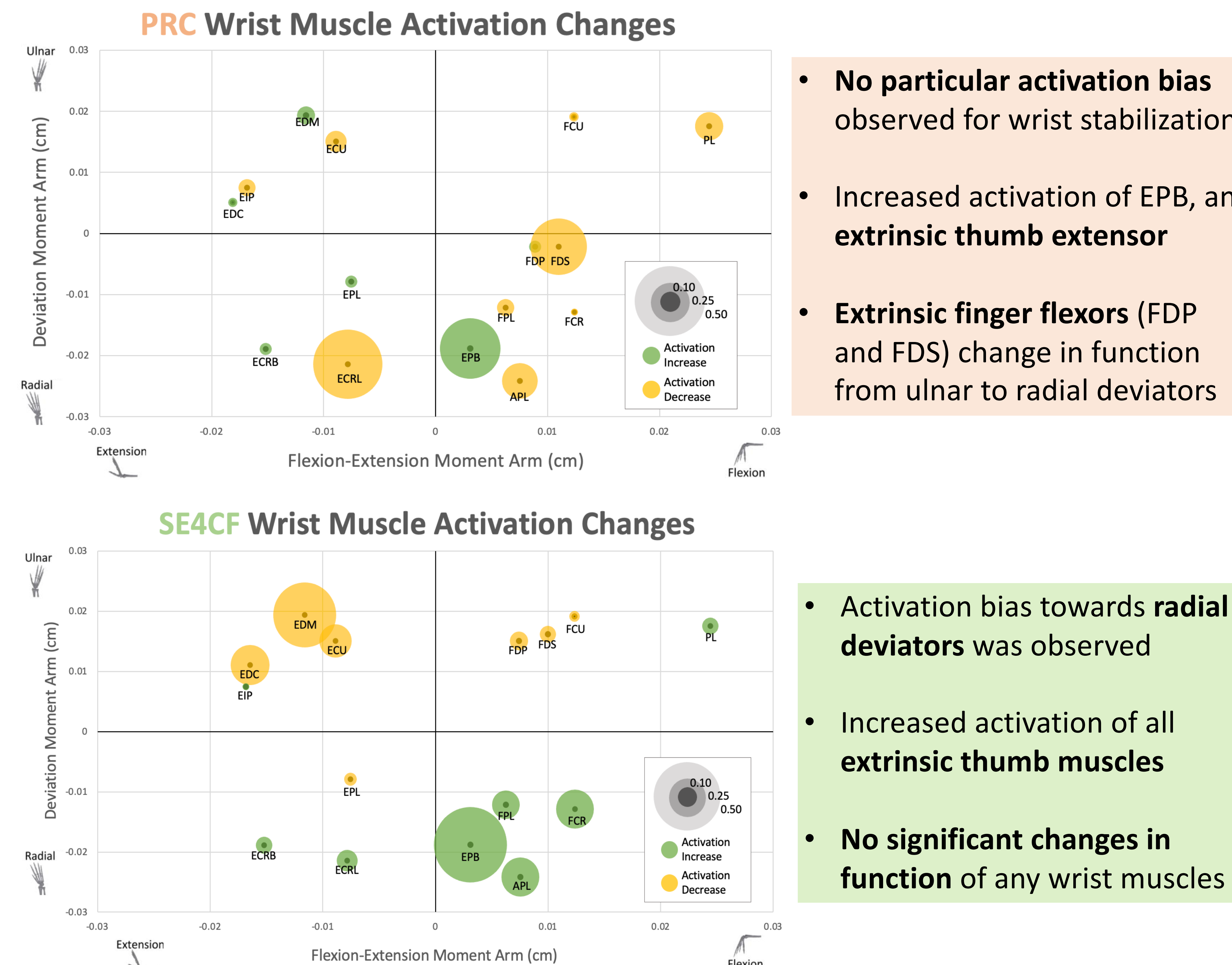
Activation patterns that produce maximum grip force in the **preferred wrist posture of nonimpaired populations** (NIOPT: 35° Ext., 7° Ulnar) were computed for each model using an optimal control framework [4,5].

A sensitivity study was conducted using a **forward dynamics approach**:

- **Muscle activations**: optimal control simulations
- **Simulated wrist redesign**: altered wrist bones, axes, moment arms [6]
- **Simulated disuse atrophy and fascicle length adaptation**: altered muscle parameters consistent with chronic osteoarthritis and surgical salvage [7]



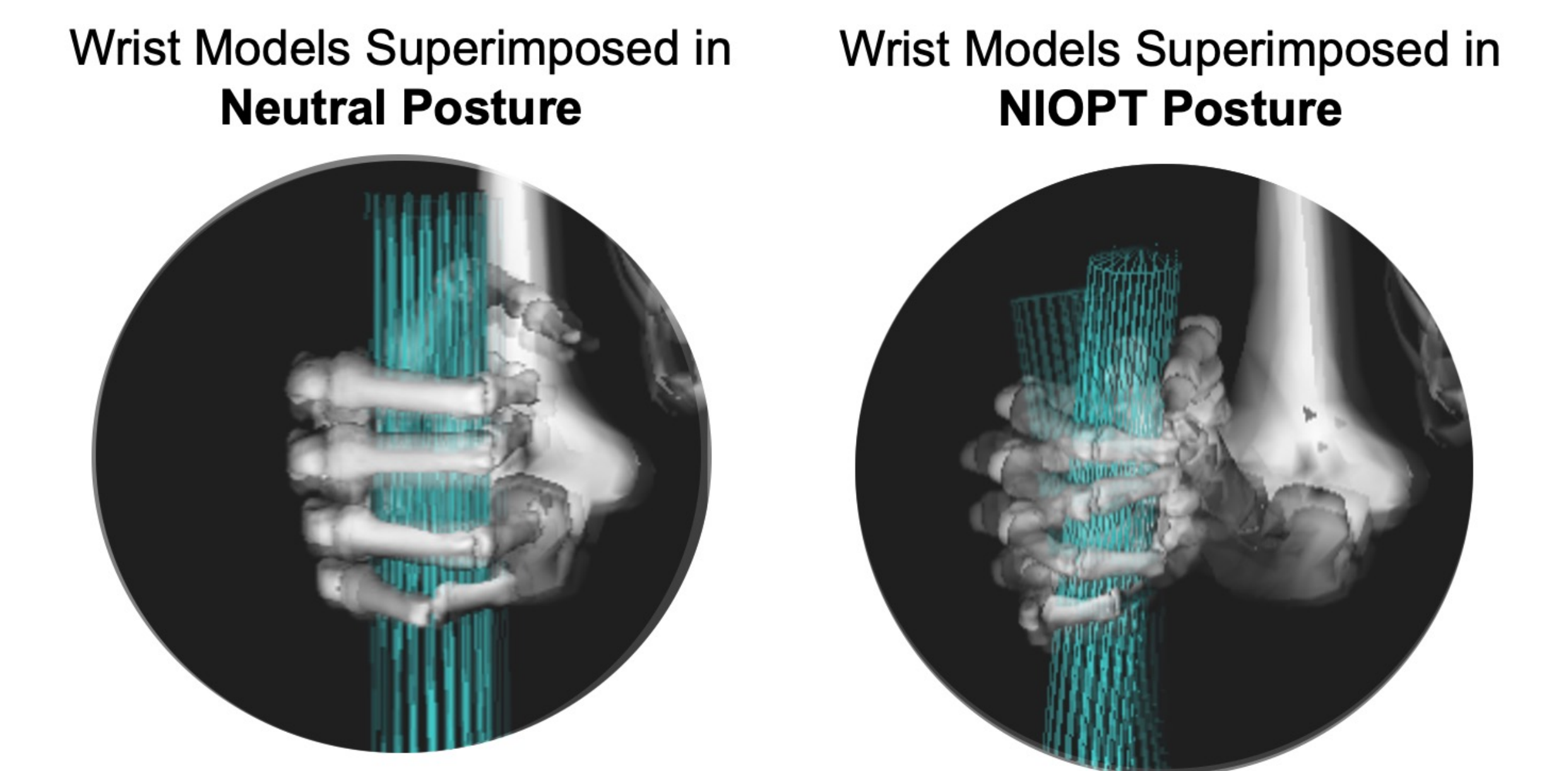
Optimal Control Patterns



Discussion

- The SE4CF wrist recruited extrinsic thumb muscles as radial flexors to stabilize the wrist. It is unclear if relying on extrinsic thumb muscle for wrist stabilization during hand function is feasible.

- Maximum grip capacity is most sensitive to wrist posture. PRC and SE4CF patients are unlikely to choose the same extended posture for maximum grip as a nonimpaired person due to range of motion loss.



- More explicit definitions of wrist posture during clinical grip measurements are needed to fully understand strength differences between clinical groups following wrist surgery.
- Maintenance of wrist position during grip is highly sensitive to the activation pattern used. New control strategies must be learned following biomechanical changes to maintain wrist stability.

Future Directions

Repeat Sensitivity Study in Neutral

- Optimize activations of surgical models in neutral to provide a direct comparison of grip force that limits range of motion effects
- Penalize extrinsic thumb muscle use to evaluate how control strategies without high thumb muscle activity affect grip force

Data Collection

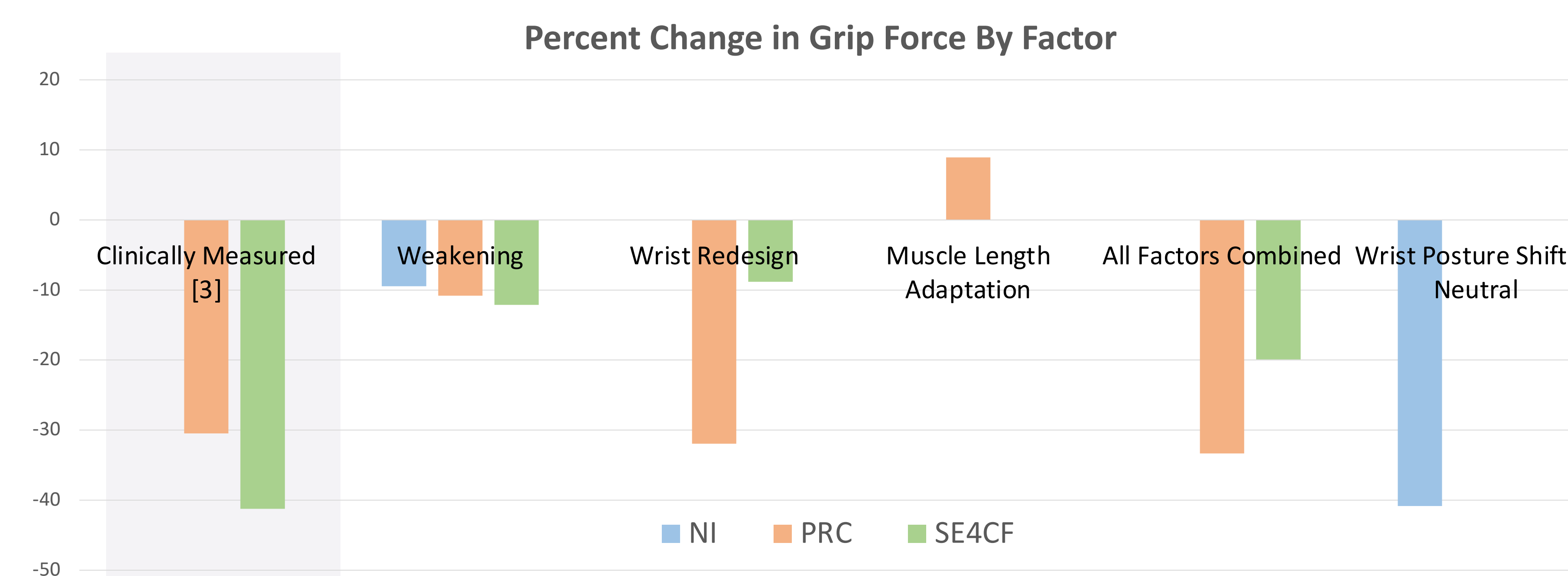
- Validate surgical optimal control through EMG data collection
- Examine adopted wrist postures during functional grip tasks
- Develop protocol for clinical maximum grip force measurements that considers wrist posture; Collect grip data across wrist range of motion

Further research will improve understanding of the biomechanical connection between the wrist and hand. Understanding the effects of individual factors within a treatment can help us pinpoint areas for improvement in the procedure or supplemental rehabilitation techniques.

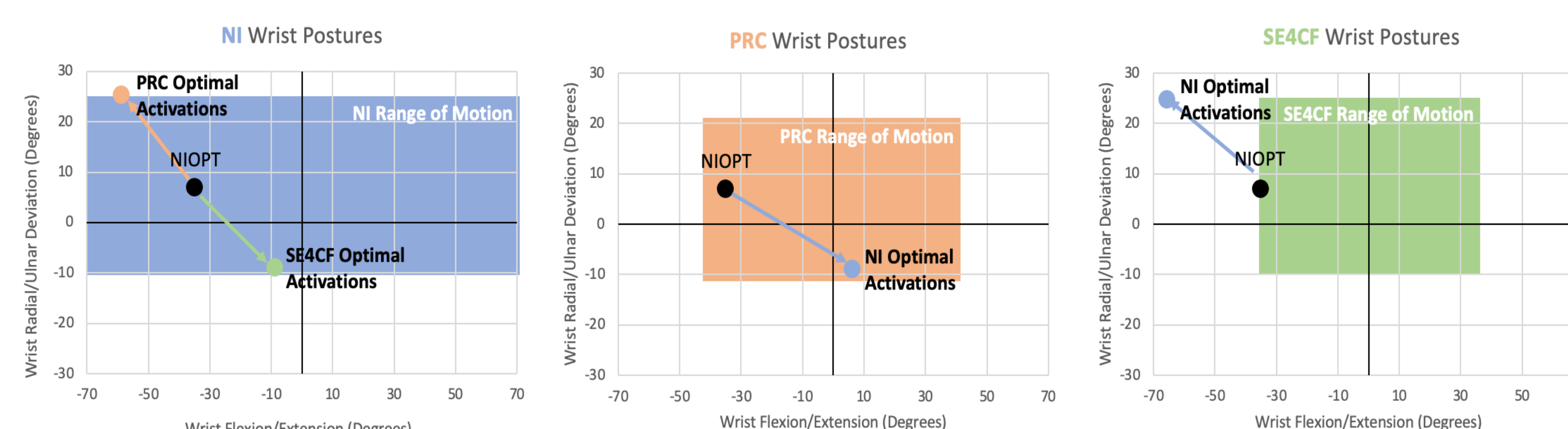
References & Acknowledgements

This work is supported by Merit Review Award #I01RX0019900 from the United States (U.S.) Department of Veterans Affairs Rehabilitation Research and Development Service. This content does not represent the views of the U. S. Department of Veterans Affairs or the United States Government. We thank Dr. Michael Bednar for his contribution to these research questions.

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- PRC grip force is most sensitive to wrist redesign; SE4CF is most sensitive to weakening
- Combining all factors reflects clinical weakness for the PRC, but not for the SE4CF



- Altering any factors without reoptimizing the activation pattern changes wrist posture