view_frames Result Recorded at time: 248.750 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_laser cpu_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec upper_base_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 248.734 (0.016 sec old) Buffer length: 4.960 sec torso_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec head_pan_link left_shoulder_link right_shoulder_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec head_tilt_link left_shoulder_forward_link right_shoulder_forward_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec neck_link right shoulder up link left_shoulder_up_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec left_upper_arm_link right_upper_arm_link head_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 4.960 sec Buffer length: 4.960 sec antenna_link left_elbow_link right_elbow_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left_lower_arm_link right_lower_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 248.734 (0.016 sec old) Most recent transform: 248.734 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec left_wrist_link right_wrist_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (248.750 sec old) Most recent transform: 0.000 (248.750 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left_hand_link right_hand_link