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"They told me I couldn't, so I did"

Work Experience

Fleming College Peterborough, ON

Mechatronics Course Developer, Instructor, Applied Projects Manager & Mentor of Student Capstones

- Developing a Mechatronics course including lectures, labs, exams & projects
 - Responsible for Agile Project Managment, providing sponsors with desired expectations within scope of agreements
 - Supervising students during lab sections, evaluating their performance in Electronics & Electricity labs

Network Centric Applied Research Team

Toronto, ON

Jan. 2019 - Present

ROBOTICS RESEARCHER

ADJUNCT FACULTY

Aug. 2018 - Present

- · Developing and implementing a modified Pioneer 2DX Autonomous Mobile Robot using 2D Lidar, localization, SLAM, mapping, path planning, and obstacle avoidance
 - Comparision of Gmapping, EKF, Hector, SLAM systems, utilizing fusion sensors
 - Premapping and SLAM in Search & Rescue Field research
 - Stair mapping, glass detection, and navigation, investigation
 - Full ROS Navigation system and Gazebo simulation in indoor environment using RPLidar

SDI Marketing (TMS) Newmarket, ON

MANAGER & LEAD ADVISOR

Sep. 2015 - Nov. 2018

- · Managed and oversaw the operations of multiple stores. Developed and performed incentives, and trained District's employees & lead advisors
 - Multiple award winner for top sale performance
 - Generated a 314% growth in revenue (Over \$1M Revenue)
 - Earned a reputation for effective leadership under ambitious deadlines

McMaster University (Smart Joint Monitoring Lab)

Hamilton, ON

SCHOLAR

Jan. 2016 - Sep. 2016

- · Worked with Prof. Jamal Deen to analyze gait kinematics and gait kinetics. This led to a research on Smart Joint Methods based on adding gyroscopes, force plates, EMG, & muscle force. Further researched on Slavelberg, Former-Cordero estimate 3D ground reaction forces (GRFs), and optimal placement of accelerometers.
 - Gait analysis, accuracy and reliability of Smart Joint Methods and Optimal Sensors Placement
 - Surveyed the Bro, Intille and Gjoreski approaches based on accelerators, gyroscopes, and force sensors

Research Experience _____

Ryerson University

Toronto, ON

MASTER OF ENGINEERING AT EE DEPARTMENT

Sep. 2015 - Present

Prediction models for digit recognition, car acceptability, wine quality, & water level

Advisor: Prof. Farah Mohammadi

- Modeled and simulated with MATLAB on different real world datasets
- Created a Neural Network, SVM Prediction Model, K-means clustering for image dimensionality reduction
- · Lines, & circles detection in noisy environment with 5 pixels accuracy

Advisor: Dr. Lev Kirischian

- Blurring Process, Edge detection, and Hough transform algorithms with OpenCV
- Comparison of Hough transform; Fast and Random Hough transform; and efficient randomized algorithm

Shahid Beheshti University

Tehran, Iran

RESEARCH ASSISTANT AT ELECTRONICS LAB

Jan. 2012 - Jul. 2015

· Final Project: Designing, simulating and implementing CMOS amplifier with Beta-Multiplier Reference Advisor: Prof. Hashemipour

- High gain low noise CMOS amplifier design with a BMR utilizing positive close loop feedback, novel Cascade Currant Mirrors

Designing and implementing a ZigBee OEM Module Starter

Advisor: Prof. Jalali

- Designed, optimized, and implemented a ProBee ZE10 Starter using ARM Cortex M3
- Sigma-Delta AD Converters analysis, the highway traffic measurment analysis using GPS mobile devices

AUGUST 18, 2019 OMID KARIMPOUR · CURRICULUM VITAE

Teaching Experience

2019 **Human Robot Interaction**, Graduate Assistant Ryerson University 2019 Final Project Mentorship, Mentor Fleming College 2019 **Electricity 1**, Lab Instructor Fleming College 2012-15 Mathematical and Physics, Instructor Raadfar Academy

Academy Membership

IEEE (Institute of Electrical & Electronics Engineers)

Ryerson Student Branch

Nov. 2018 - PRESENT

MEMBER

MEMBER

- Organized a project showcase for faculties, graduates, and undergraduates
- Hosted an "Improving Communications Skills for Engineers" workshop
- · Participated and started a number of IEEE events such as Industry Night

Hardware-software co-design, DE2-Altera FPGA based, and Nios II SoPC Development

Embeded System

Sep. 2017 - Dec. 2017

- · Real-time scheduling techniques, concurrency, system on chip and hardware software codesign tools
- Real-time scheduling and investigating RTOS using uVision, RTX, and ARM Cortex M3

Reliability evaluation & build in self repair of reconfigurable

Digital System Testing

Jan. 2017 - June. 2017 Reliability analysis & comparison of hierarchical redundancy, optimal repair, coarse redundancy, Tile-based

- · Analyzed combinational and sequential circuit test generation methods. memory, delay testing, and testability design methodology

Architecture analysis and high-level synthesis of ASP of a VOP buffer

Architiectural Synthesis

CORE MEMBER

Sep. 2012 - Dec. 2016

- Analyze the fully pipelined variant of architecture to get the highest performance of ASP along with 32-bit Multi Cycle Processor design.
- · Assess the economic aspects, power consumption, and VOP area, determined by the available memory bandwidth

Education

Ryerson University Toronto, ON

M.Eng. in Electrical and Computer Engineering

Aug. 2016 - Present

Shahid Beheshti University (former National University of Iran)

Tehran, Iran

B.S. IN ELECTRICAL AND COMPUTER ENGINEERING

Sep. 2010 - Jan 2015

Skills

Programming C/C++, Python, MATLAB, VHDL, Verilog, LaTeX

Robotic Programming Tools ROS (Robot Operating System), OpenCV

Smart Phone Programming iOS (Swift)

> Web HTML, CSS, JS, php

Microcontrollers AVR, ARM, FPGA

Analog Digital Design Tools H-Spice, P-Spice

Honors & Awards

1st Place, TMS, Certified for top revenue improvement, Eastern Canada 2018 GTA, ON

2017 1st Place, TMS, Certified for top leadership, Eastern Canada GTA, ON

Ranked Top 1%, Mathematics and Physics among more than 178,000 students in Iranian nationwide 2010 Tehran, Iran

university entrance examination (Konkoor).

2008 Accepted, Iranian National Olympiad Competition in Mathematics Tehran, Iran