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### 5.2 Diagonalizability

**Theorem 5.5.** Let T be a linear operator on a vector space V, and let  $\lambda_1$ ,  $\lambda_2, \ldots, \lambda_k$  be distinct eigenvalues of T. If  $v_1, v_2, \ldots, v_k$  are eigenvectors of T such that  $\lambda_i$  corresponds to  $v_i$   $(1 \le i \le k)$ , then  $\{v_1, v_2, \ldots, v_k\}$  is linearly independent.

Proof.

**Corollary.** Let T be a linear operator on an n-dimensional vector space V. If T has n distinct eigenvalues, then T is diagonalizable.

**Definition.** A polynomial f(t) in P(F) splits over F if there are scalars c,  $a_1, a_2, \ldots, a_n$  (not necessarily distinct) in F such that

$$f(t) = c(t - a_1)(t - a_2) \cdots (t - a_n).$$

**Definition.** Let  $\lambda$  be an eigenvalue of a linear operator or matrix with characteristic polynomial f(t). The (algebraic) multiplicity of  $\lambda$  is the largest positive integer k for which  $(t - \lambda)^k$  is a factor of f(t).

**Definition.** Let T be a linear operator on a vector space V, and let  $\lambda$  be an eigenvalue of T. Define  $\mathsf{E}_{\lambda} = \{x \in \mathsf{V} : \mathsf{T}(x) = \lambda x\} = \mathsf{N}(\mathsf{T} - \lambda \mathsf{I}_{\mathsf{V}})$  The Set  $\mathsf{E}_{\lambda}$  is called the **eigenspace** of T corresponding to the eigenvalue  $\lambda$ . Analogously, we define the **eigenspace** of a square matrix A to be the eigenspace of  $\mathsf{L}_A$ .

**Theorem 5.6.** The characteristic polynomial of any diagonalizable linear operator splits.

**Theorem 5.7.** Let T be a linear operator on a finite-dimensional vector space V, and let  $\lambda$  be an eigenvalue of T having multiplicity m. Then  $1 \le \dim(\mathsf{E}_{\lambda}) \le m$ .

**Lemma.** Let T be a linear operator, and let  $\lambda_1, \lambda_2, \ldots, \lambda_k$  be distinct eigenvalues of T. For each  $i = 1, 2, \ldots, k$ , let  $v_i \in \mathsf{E}_{\lambda_i}$ , the eigenspace corresponding to  $\lambda_i$ . If

$$v_1 + v_2 + \dots + v_k = 0,$$

then  $v_i = \theta$  for all i.

**Theorem 5.8.** Let T be a linear operator on a vector space V, and let  $\lambda_1, \lambda_2, \ldots, \lambda_k$  be distinct eigenvalues of T. For each  $i=1, 2, \ldots, k$ , let  $S_i$  be a finite linearly independent subset of the eigenspace  $\mathsf{E}_{\lambda_i}$ . Then  $S=S_1\cup S_2\cup\cdots\cup S_k$  is a linearly independent subset of V.

**Theorem 5.9.** Let T be a linear operator on a finite-dimensional vector space V such that the characteristic polynomial of T splits. Let  $\lambda_1, \lambda_2, \ldots, \lambda_k$  be the distinct eigenvalues of T. Then

- (a) T is diagonalizable if and only if the multiplicity of  $\lambda_i$  is equal to  $\dim(\mathsf{E}_{\lambda_i})$  for all i.
- (b) if T is diagonalizable and  $\beta_i$  is an ordered basis for  $\mathsf{E}_{\lambda_i}$  for each i, then  $\beta = \beta_1 \cup \beta_2 \cup \cdots \cup \beta_k$  is an ordered basis for V consisting of eigenvectors of T.
- (c) State and prove results analogous to (a) and (b) for matrices.

Corollary. Let T be a linear operator on an n-dimensional vector space V. Then T is diagonalizable if and only if both of the following conditions hold.

- 1. The characteristic polynomial of T splits.
- 2. For each eigenvalue  $\lambda$  of T, the multiplicity of  $\lambda$  equals  $n \text{rank}(\mathsf{T} \lambda \mathsf{I})$ .

### Direct sums

**Definition.** Let  $W_1, W_2, ..., W_k$  be subspaces of a vector space V. We define the **sum** of these subspaces to be the set

$$\{v_1 + v_2 + \dots + v_k : v_i \in W_i \text{ for } 1 \le i \le k\},\$$

which we denote by  $W_1 + W_2 + \cdots + W_k$  or  $\sum_{i=1}^k W_i$ .

**Definition.** Let  $W_1, W_2, \ldots, W_k$  be subspaces of a vector space V. We call V the **direct sum** of the subspaces  $W_1, W_2, \ldots, W_k$  and write  $V = W_1 \oplus W_2 \oplus \cdots \oplus W_k$ , If

$$V = \sum_{i=1}^k W_i$$

and

$$W_j \cap \sum_{i \neq j} W_i = \{0\}$$
 for each  $j \ (1 \le j \le k)$ .

**Theorem 5.10.** Let  $W_1, W_2, ..., W_k$  be subspaces of a finite-dimensional vector space V. The following conditions are equivalent.

- (a)  $V = W_1 \oplus W_2 \oplus \cdots \oplus W_k$
- (b)  $V = \sum_{i=1}^{k} W_i$  and, for any vectors  $v_1, v_2, ..., v_k$  such that  $v_i \in W_i$   $(1 \le i \le k)$ , if  $v_1 + v_2 + \cdots + v_k = 0$ , then  $v_i = 0$  for all i.
- (c) Each vector  $v \in V$  can be uniquely written as  $v = v_1 + v_2 + \cdots + v_k$ , where  $v_i \in W_i$ .
- (d) If  $\gamma_i$  is an ordered basis for  $W_i$   $(1 \le i \le k)$ , then  $\gamma_1 \cup \gamma_2 \cup \cdots \cup \gamma_k$  is an ordered basis for V.
- (e) For each  $i=1,\,2,\,\ldots,\,k$ , there exists an ordered basis  $\gamma_i$  for  $\mathsf{W}_i$  such that  $\gamma_1\cup\gamma_2\cup\cdots\cup\gamma_k$  is an ordered basis for  $\mathsf{V}$ .

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Proof. Continued...

**Theorem 5.11.** A linear operator T on a finite-dimensional vector space V is diagonalizable if and only if V is the direct sum of the eigenspaces of T.

## 5.6 Invariant subspaces and the Cayley–Hamilton Theorem

**Definition.** Let T be a linear operator on a vector space V. A subspace W of V is called a T-invariant subspace of V if  $T(W) \subseteq W$ , that is, if  $T(v) \in W$  for all  $v \in W$ .

**Theorem 5.21.** Let T be a linear operator on a finite-dimensional vector space V, and let W be a T-invariant subspace of V. Then the characteristic polynomial of  $T_W$  divides the characteristic polynomial of T.

**Theorem 5.22.** Let T be a linear operator on a finite-dimensional vector space V, and let W denote the T-cyclic subspace of V generated by a nonzero vector  $v \in V$ . Let  $k = \dim(W)$ . Then

- (a)  $\{v, \mathsf{T}(v), \mathsf{T}^2(v), \dots, \mathsf{T}^{k-1}(v)\}$  is a basis for  $\mathsf{W}$ .
- (b) If  $a_0v + a_1\mathsf{T}(v) + \cdots + a_{k-1}\mathsf{T}^{k-1}(v) + \mathsf{T}^k(v) = 0$ , then the characteristic polynomial of  $\mathsf{T}_\mathsf{W}$  is  $f(t) = (-1)^k(a_0 + a_1t + \cdots + a_{k-1}t^{k-1} + t^k)$ .

#### The Cayley-Hamilton Theorem

**Theorem 5.23** (Cayley-Hamilton). Let T be a linear operator on a finite-dimensional vector space V, and let f(t) be the characteristic polynomial of T. Then  $f(T) = T_0$ , the zero transformation. That is, T "satisfies" its characteristic equation.

Proof.

Corollary (Cayley-Hamilton Theorem for Matrices). Let A be an  $n \times n$  matrix, and let f(t) be the characteristic polynomial of A. Then f(A) = O, the  $n \times n$  zero matrix.

**Theorem 5.24.** Let T be a linear operator on a finite-dimensional vector space V, and suppose that  $V = W_1 \oplus W_2 \oplus \cdots \oplus W_k$ , where  $W_i$  is a T-invariant subspace of V for each i  $(1 \le i \le k)$ . Suppose that  $f_i(t)$  is the characteristic polynomial of  $T_{W_i}$   $(1 \le i \le k)$ . Then  $f_1(t) \cdot f_2(t) \cdot \cdots \cdot f_k(t)$  is the characteristic polynomial of T.

**Definition.** Let  $B_1 \in \mathsf{M}_{m \times m}(F)$ , and let  $B_2 \in \mathsf{M}_{n \times n}(F)$ . We define the **direct sum** of  $B_1$  and  $B_2$ , denoted  $B_1 \oplus B_2$ , as the  $(m+n) \times (m+n)$  matrix A such that

$$A_{ij} = \begin{cases} (B_1)_{ij} & \text{for } 1 \le i, \ j \le m \\ (B_2)_{(i-m), \ (j-m)} & \text{for } m+1 \le i, \ j \le n+m \\ 0 & \text{otherwise} \end{cases}$$

If  $B_1, B_2, \ldots, B_k$  are square matrices with entries from F, then we define the **direct sum** of  $B_1, B_2, \ldots, B_k$  recursively by

$$B_1 \oplus B_2 \oplus \cdots \oplus B_k = (B_1 \oplus B_2 \oplus \cdots \oplus B_{k-1}) \oplus B_k.$$

If  $A = B_1 \oplus B_2 \oplus \cdots \oplus B_k$ , then we often write

$$A = \begin{pmatrix} B_1 & O & \cdots & O \\ O & B_2 & \cdots & O \\ \vdots & \vdots & & \vdots \\ O & O & \cdots & B_k \end{pmatrix}.$$

**Theorem 5.25.** Let T be a linear operator on a finite-dimensional vector space V, and let W<sub>1</sub>, W<sub>2</sub>, ..., W<sub>k</sub> be T-invariant subspaces of V such that  $V = W_1 \oplus W_2 \oplus \cdots \oplus W_k$ . For each i, let  $\beta_i$  be an ordered basis for W<sub>i</sub>, and let  $\beta = \beta_1 \cup \beta_2 \cup \cdots \cup \beta_k$ . Let  $A = [T]_{\beta}$  and  $B_i = [T_{W_i}]_{\beta_i}$  for  $i = 1, 2, \ldots, k$ . Then  $A = B_1 \oplus B_2 \oplus \cdots \oplus B_k$ .