



CAL POLY

CALIFORNIA POLYTECHNIC UNIVERSITY  
SAN LUIS OBISPO

MASTERS THESIS

# Artificial Neural Network-Based Robotics

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# Chapter 1

## L<sup>A</sup>T<sub>E</sub>X Usage

### 1.1 Figures and Ref

This is where I introduce stuff. See Figure 1.1.



Figure 1.1: Pad thai

## 1.2 Math

$$f(x) = x^2 \tag{1.1}$$

This is an equation that we don't want to number:

$$f(x) = x^2$$

Here's an in-line equation:  $f(x) = x^2$ .

Here's an aligned equation: Aligns at the &.

$$1 + 2 = 3$$

$$1 = 3 - 2$$

$$f(x) = x^2$$

$$g(x) = \frac{1}{x}$$

$$F(x) = \int_b^a \frac{1}{3} x^3$$

$$\frac{1}{\sqrt{x}}$$

$$\begin{bmatrix} a & \lambda \\ c & d \end{bmatrix}$$

## 1.3 Citations

Random citation [1] embeddeed in text.

Random citation [2] embeddeed in text.

Random citation [1] embeddeed in text. [3] [4]

## 1.4 Accents

Première ẋ

## 1.5 Dashes

The space is 3-dimensional.

Read pages 3–4.

I saw them—there were 3 men alive

The temperature dropped to −3 degrees.

## 1.6 Lists

- First Level
    - Second Level
      - \* Third Level
        - Fourth Level
1. First level item
  2. First level item
    - (a) Second level item
    - (b) Second level item
      - i. Third level item
      - ii. Third level item
        - A. Fourth level item
        - B. Fourth level item

## 1.7 Groups

will produce a paragraph that is four (this is an easy mistake to make).

## 1.8 Code highlighting

---

```
class MyClass(Yourclass):
def __init__(self, my, yours):
bla = '5 1 2 3 4'
print bla
```

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