

BLG 335E – Analysis of Algorithms I Fall 2013, Recitation 6 25.12.2013

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Outline



- Augmenting Data Structures
- Amortised Analysis

Question 1



• [Course Book Exercises 14.3-6]

Show how to maintain a dynamic set Q of numbers that supports the operation MIN-GAP, which gives the magnitude of the difference of the two closest numbers in Q. For example, if $Q = \{1, 5, 9, 15, 18, 22\}$, then MIN-GAP(Q) returns 18 - 15 = 3, since 15 and 18 are the two closest numbers in Q. Make the operations INSERT, DELETE, SEARCH, and MIN-GAP as efficient as possible, and analyze their running times.



- Underlying data structure?
- A red-black tree in which the numbers in the set are stored simply as the keys of the nodes.
- SEARCH is then just the ordinary TREE-SEARCH for binary search trees, which runs in $O(\lg n)$ time on red-black trees.



- The red-black tree is augmented by the following fields in each node *x*:
- 1. min-gap[x] contains the minimum gap in the subtree rooted at x. It has the magnitude of the difference of the two closest numbers in the subtree rooted at x. If x is a leaf (its children are all nil[T]), let min- $gap[x] = \infty$.
- 2. *min-val*[*x*] contains the minimum value (key) in the subtree rooted at *x*.
- 3. max-val[x] contains the maximum value (key) in the subtree rooted at x.



- Maintaining the information:
- The three fields added to the tree can each be computed from information in the node and its children.
- Therefore, they can be maintained during insertion and deletion without affecting the $O(\lg n)$ running time:



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\begin{aligned} & \textit{min-val}[x] = \begin{cases} & \textit{min-val}[left[x]] & \text{if there's a left subtree }, \\ & \textit{key}[x] & \text{otherwise }, \end{cases} \\ & \textit{max-val}[x] = \begin{cases} & \textit{max-val}[right[x]] & \text{if there's a right subtree }, \\ & \textit{key}[x] & \text{otherwise }, \end{cases} \\ & \textit{min-gap}[left[x]] & (\infty \text{ if no left subtree}) , \\ & \textit{min-gap}[right[x]] & (\infty \text{ if no right subtree}) , \\ & \textit{key}[x] - \textit{max-val}[left[x]] & (\infty \text{ if no left subtree}) , \\ & \textit{min-val}[right[x]] - \textit{key}[x] & (\infty \text{ if no right subtree}) . \end{cases} \end{aligned}
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- Why to define min-val and max-val?
- In order to make it possible to compute *min-gap* from information at the node and its children.



- What about MIN_GAP?
- MIN-GAP simply returns the *min-gap* stored at the tree root.
- Thus, its running time is O(1).



- How to get the closest numbers? (This is not asked in the question)
- Starting from the root, look for where the minimum gap (the one stored at the root) came from.
- At each node x, simulate the computation of min-gap[x] to figure out where min-gap[x] came from.
- If it came from a subtree's *min-gap* field, continue the search in that subtree.
- If it came from a computation with *x*'s key, then *x* and that other number are the closest numbers.
- Complexity? O(lg n)

Question 2



- [Course Book Exercises 17.1-3 & 17.2-2] A sequence of *n* operations is performed on a data structure. The *ith* operation costs *i* if *i* is an exact power of 2, and 1 otherwise.
- Determine the amortized cost per operation:
 - a. Using the aggregate analysis.
 - b. Using the accounting method.

Asırlardır Cağdas



Cost

Operation

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a. Total cost:

$$\sum_{i=1}^{n} c_i \le n + \sum_{j=0}^{\lg n} 2^j = n + (2n-1)$$

$$< 3n$$

• Amortized cost per operation is O(1).



- b. Charge each operation 3, then:
 - If *i* is not an exact power of 2, pay 1, and store 2 as credit.
 - If i is an exact power of 2, pay i, using stored
 credit.
 Operation Cost Actual cost Credit remaining
 - Amortized cost is 3n
 - Actual cost is less
 than 3n (from a.)
 - Credit never runs out (is never negative)

- Amortized cost per operation is O(1)

2	3	2	3
3	3	1	5
4	3	4	4
5	3	1	6
6	3	1	8
7	3	1	10
8	3	8	5
9	3	1	7
10	3	1	9
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