



Microprocessor Systems

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Syllabus

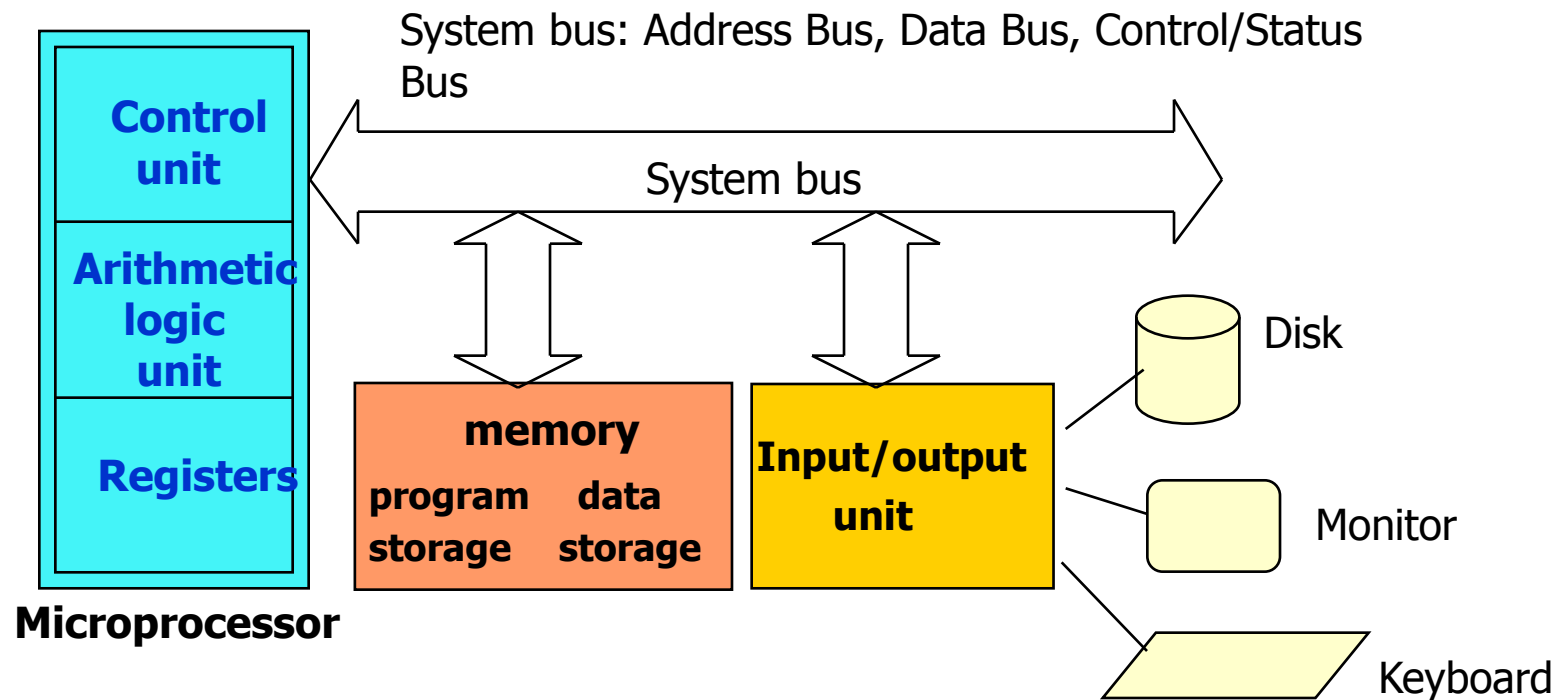
1. Introduction, Number Systems
2. Computer Overview - Memory
3. Memory Design
4. Quiz 1, CPU overview, Instruction format
5. Addressing methods
6. Instruction types
7. Instruction types - cntd
8. Midterm Exam 1
9. Parallel communication interface
10. Serial communication interface
11. Quiz 2, Subroutines, Interrupts, Stack, Coding techniques
12. Coding examples and applications
13. Midterm Exam 2
14. Development of Microprocessor Based Designs



Topics

- Serial Communication
- ACIA

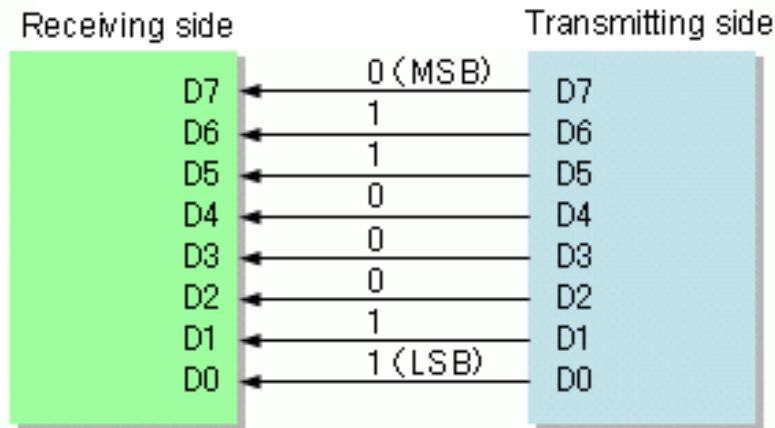
Computer Organization



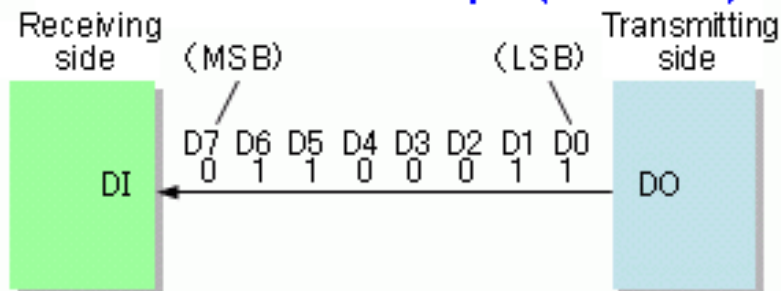
I/O Interfacing

- The I/O communication can be Parallel or Serial

Parallel interface example



Serial interface example (MSB first)



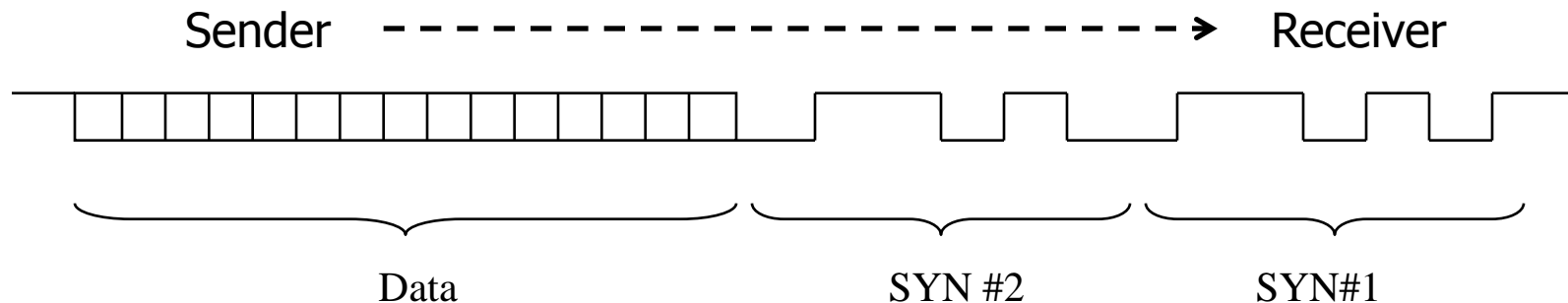


Serial Communication

- Serial communication requires one wire and bits are transferred one at a time
 - Therefore, there needs to be an agreement on how “long” each bit stays on the line.
- There are parameters that must be agreed upon between the two computer systems. One of them is the speed.
 - The rate of transmission is usually measured in bits/second or baud.
- Two different types of serial transfer
 - Synchronous serial transfer
 - Asynchronous serial transfer

Synchronous Data Transmission

- The two units share a common clock frequency
 - The transmitter and receiver can negotiate the transmission rate and lock (synchronize) their clocks.
- Usually used for high speed transmission.
- Message based.
 - The sender cannot transmit characters simply as they occur and consequently has to store them until it has built up a block - thus the system is unsuitable for applications where characters are generated at irregular intervals.
 - Synchronization occurs at the beginning of a long message.
- The SYN character is sent periodically to maintain synchronization



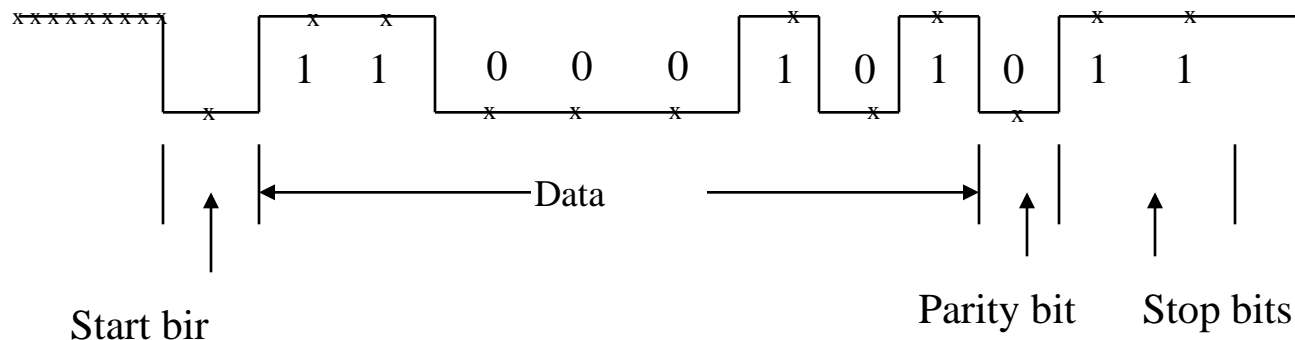


Asynchronous Serial Transfer

- Each character is transmitted as separate entity. The device must be able to recognize:
 - When transmission is occurring
 - When to read a bit of data
 - When the transmission ends
 - When the transmission is idle (no data being transmitted)
- Special bits are inserted at both ends of the character code
- Each character consists of three parts :
 - start bit : always "0", indicate the beginning of a character
 - information bits : data
 - stop bit : always "1"

Asynchronous Serial Transfer

- Asynchronous transmission rules :
 - When a character is not being sent, the line is kept in the 1-state
 - The initiation of a character transmission is detected from the start bit, which is always "0"
 - The information bits always follow the start bit
 - Then the transmitter calculates the parity bit and transmits it
 - Finally one or two stop bits are sent by returning the line to the 1-state





Asynchronous Serial Transfer

- Follows agreed upon standards:
- There is a protocol between sender and receiver specifying:
 - Data rate: The rate of transmission is usually measured in bits/second or baud
 - start bit: The transmission begins with a start bit
 - data length: the seven or eight bits representing the character are transmitted
 - stop bit: the transmission is concluded with one or two stop bits.
 - parity bit: This bit is set on (1) or off (0), depending on the serial communications parameters such as even parity bit and odd parity bit.
 - In case of even parity, the parity bit is set to 1, if the number of ones in a given set of bits (not including the parity bit) is odd, making the number of ones in the entire set of bits (including the parity bit) even.



Rate of Transmission

- For parallel transmission, all of the bits are sent at once.
- For serial transmission, the bits are sent one at a time.
 - Therefore, there needs to be agreement on how “long” each bit stays on the line.
- The rate of transmission is usually measured in bits/second or baud.
 - Baud = bits / second.
 - Seconds / bits = 1 /baud



Example

- Given a certain baud rate, how long should each bit last?
 - A Baud of 19200Bd for serial transmission:
 - Bit rate: 19200bps & Bit time is $1/19200$ sec
 - If there is 1 Start Bit, 1 Stop bit, 8 data bits in the frame =>
Data rate = $19200 / 10 = 1920$ Byte/sec.

Baud	# of stop bits	Byte / s .	Bit time (ms.)
110	2	10	9.09
150	1	15	6.67
300	1	30	3.33
1200	1	120	0.83
2400	1	240	0.42
4800	1	480	0.21
9600	1	960	0.10
19200	1	1920	0.05



Asynchronous Serial Communication

- Transmitting numeric data is straightforward
- Transmitting characters are encoded with a binary value.
 - Most well know is American Standard Code for Information Interchange (ASCII)
 - Another is UNICODE.

ASCII Table

Dec	Hex	Char	Dec	Hex	Char	Dec	Hex	Char	Dec	Hex	Char
0	00	Null	32	20	Space	64	40	@	96	60	`
1	01	Start of heading	33	21	!	65	41	A	97	61	a
2	02	Start of text	34	22	"	66	42	B	98	62	b
3	03	End of text	35	23	#	67	43	C	99	63	c
4	04	End of transmit	36	24	\$	68	44	D	100	64	d
5	05	Enquiry	37	25	%	69	45	E	101	65	e
6	06	Acknowledge	38	26	&	70	46	F	102	66	f
7	07	Audible bell	39	27	'	71	47	G	103	67	g
8	08	Backspace	40	28	(72	48	H	104	68	h
9	09	Horizontal tab	41	29)	73	49	I	105	69	i
10	0A	Line feed	42	2A	*	74	4A	J	106	6A	j
11	0B	Vertical tab	43	2B	+	75	4B	K	107	6B	k
12	0C	Form feed	44	2C	,	76	4C	L	108	6C	l
13	0D	Carriage return	45	2D	-	77	4D	M	109	6D	m
14	0E	Shift out	46	2E	.	78	4E	N	110	6E	n
15	0F	Shift in	47	2F	/	79	4F	O	111	6F	o
16	10	Data link escape	48	30	0	80	50	P	112	70	p
17	11	Device control 1	49	31	1	81	51	Q	113	71	q
18	12	Device control 2	50	32	2	82	52	R	114	72	r
19	13	Device control 3	51	33	3	83	53	S	115	73	s
20	14	Device control 4	52	34	4	84	54	T	116	74	t
21	15	Neg. acknowledge	53	35	5	85	55	U	117	75	u
22	16	Synchronous idle	54	36	6	86	56	V	118	76	v
23	17	End trans. block	55	37	7	87	57	W	119	77	w
24	18	Cancel	56	38	8	88	58	X	120	78	x
25	19	End of medium	57	39	9	89	59	Y	121	79	y
26	1A	Substitution	58	3A	:	90	5A	Z	122	7A	z
27	1B	Escape	59	3B	;	91	5B	[123	7B	{
28	1C	File separator	60	3C	<	92	5C	\	124	7C	
29	1D	Group separator	61	3D	=	93	5D]	125	7D	}
30	1E	Record separator	62	3E	>	94	5E	^	126	7E	~
31	1F	Unit separator	63	3F	?	95	5F	_	127	7F	□



Topics

- Serial Communication
- ACIA

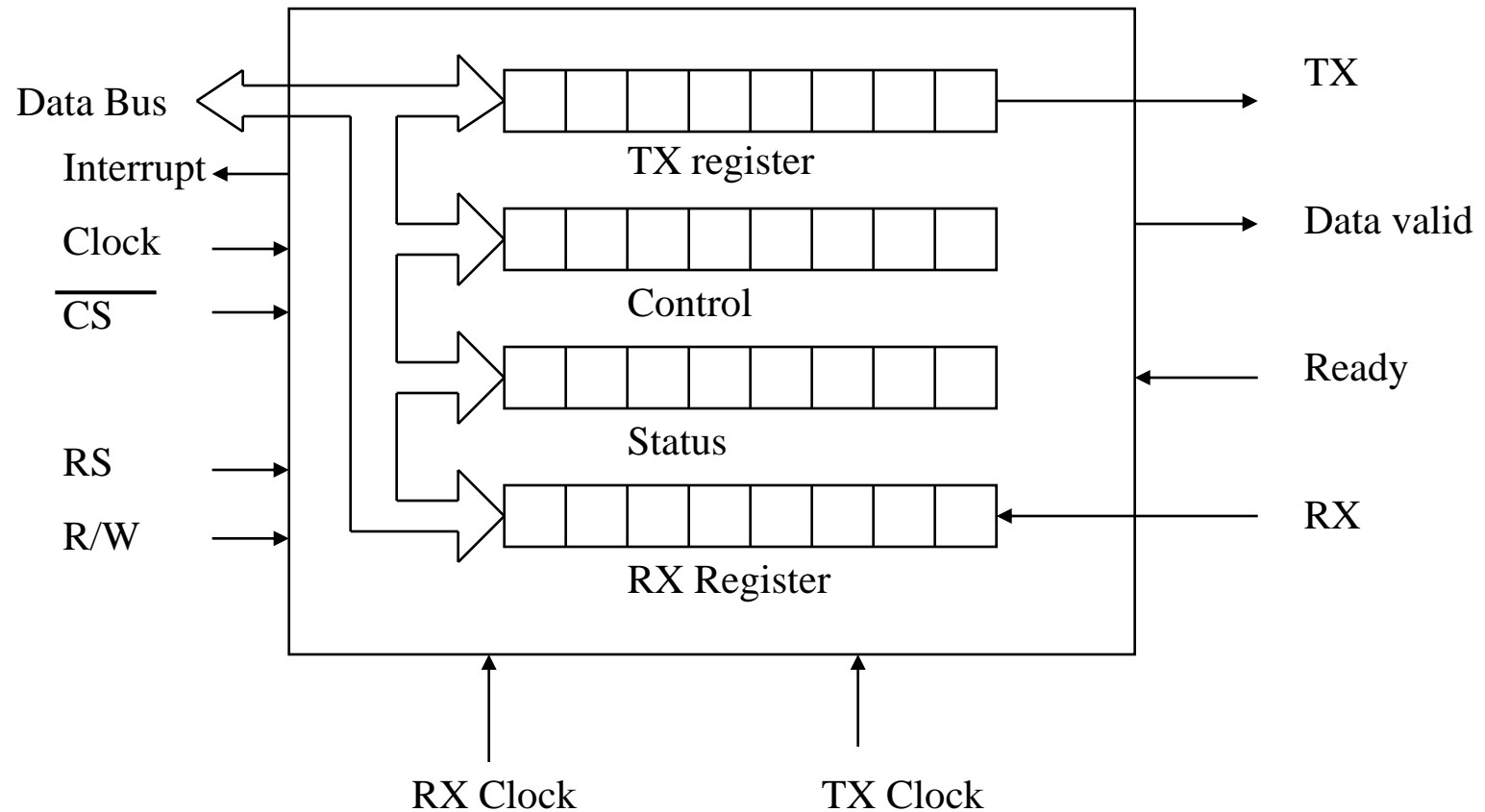


Asynchronous Communication Interface Adapter

■ 4 Basic Units:

- Transmitter (TX): Transmits to the peripheral. Parallel input-Serial output shift register. Start, stop, and parity bits are appended to the data (from the CPU data bus), and transmitted serially. Transmitter clock determines the bit rate.
- Receiver (RX): Receives from the peripheral. Serial input-parallel output shift register. Start, stop, and parity bits are removed from the transmission and transferred to CPU data bus.
- Status Register: Status flags for Received Data, Transmitted Data, Parity Check, Frame Check, Peripheral Ready.
- Control Register: Adjusted for establishing the transmission protocol and interrupt mechanisms.

ACIA



How to select each register with a single RS signal?

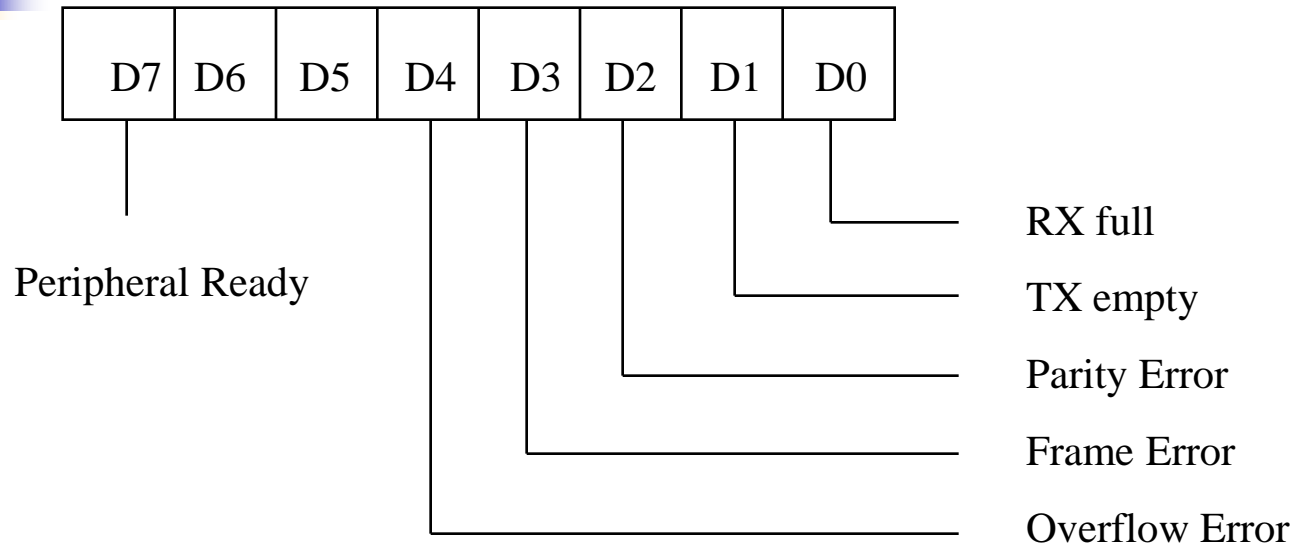
- Hint: Use another control signal, but which one?



ACIA Register Selection

RS	R/W	Register
0	0	TX
1	0	Control
0	1	RX
1	1	Status

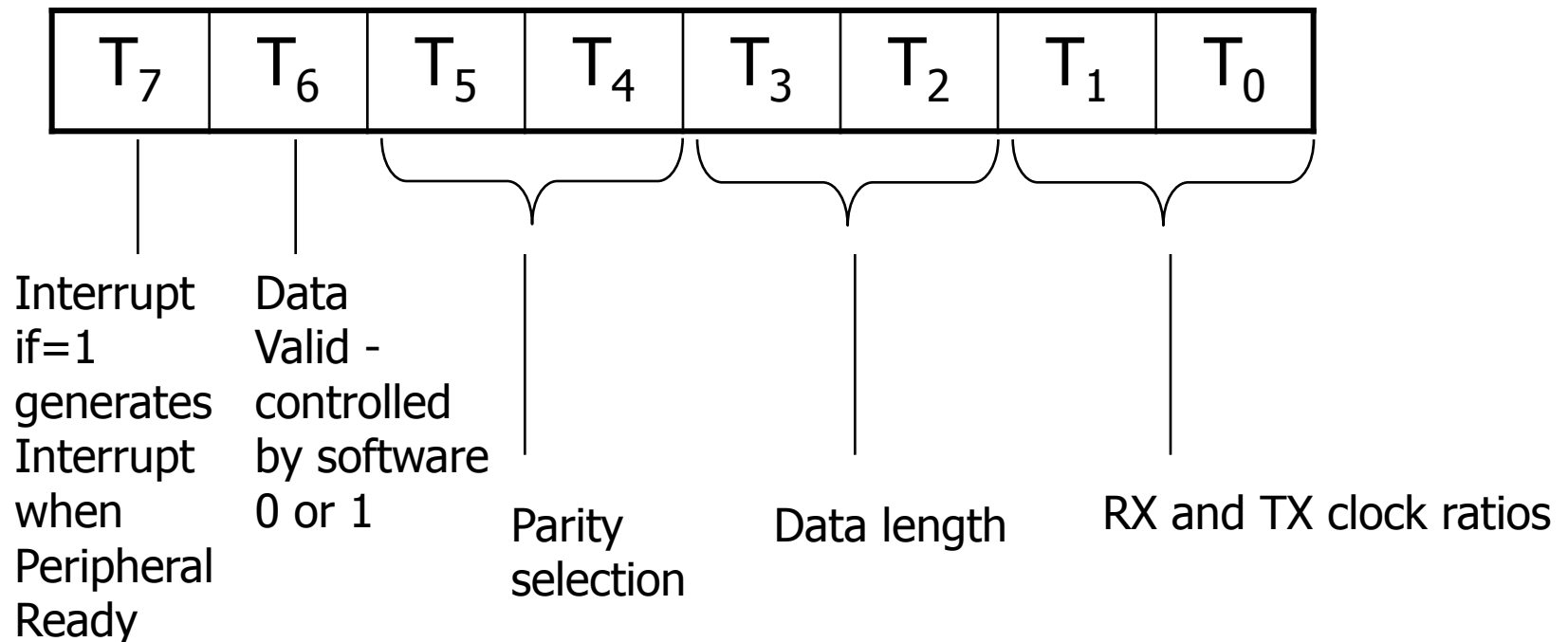
ACIA Status Register



- D0=1 Indicates new data at the RX register.
- D1=1 Indicates the data is transmitted to the peripheral.
- D2=1 Parity error.
- D3=1 Frame error: If the frame is short or long.
- D4=1 Overflow error: New data arrives before previous one is received.
- D7=1 Indicates the peripheral is ready.

ACIA – Control Register

- Determines the Data Valid output, interrupt mechanisms and communication protocol





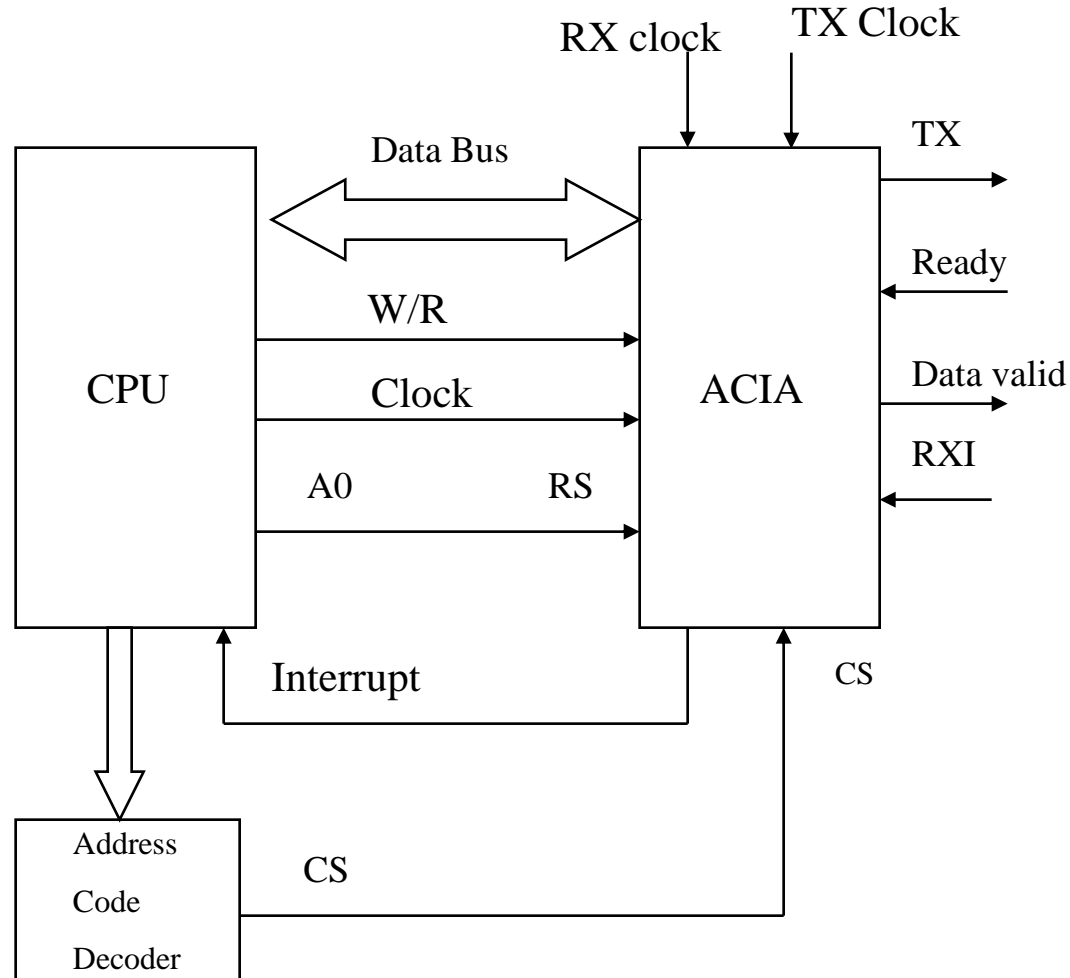
Control register

T1	T0	RX and TX clock ratios
0	0	1/1
0	1	1/2
1	0	1/4
1	1	1/8

T3	T2	Data Length and the Number of Stop Bits
0	0	7 data bit + 1 stop bit
0	1	7 data bit + 2 stop bit
1	0	8 data bit + 1 stop bit
1	1	8 data bit + 2 stop bit

T5	T4	Parity Bit Settings
0	0	No parity check
0	1	odd parity
1	0	even parity
1	1	-

ACIA – Connection to the CPU





Example-1

- A computer receives signed 8-bit numbers via EDU-ACIA. If the received number is positive or zero, it will be sent via the EDU-PIA as it is. If the received number is negative, it will be complemented and sent via the EDU-PIA.
- ACIA Conditioning:
 - Bit rate 1200 bit/s
 - Even parity $T_5=1$ $T_4=0$
 - 8 bit data+ 1 stop bit $T_3=1$ $T_2=0$
 - RX & TX CLK ratio=1/4 $T_1=1$ $T_0=0$
 - ACIA <Control> 00101010 \$2A



Example-1

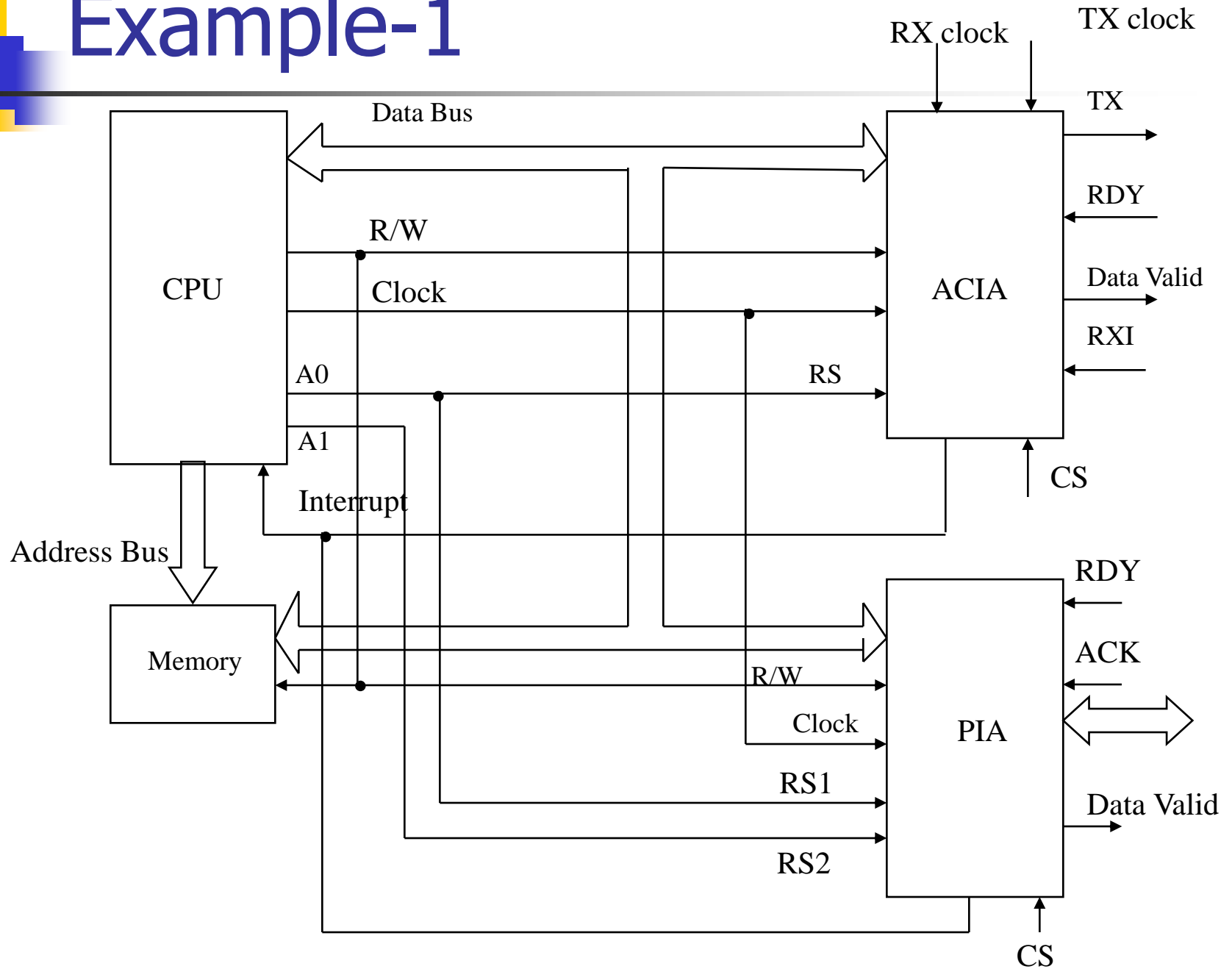
- PIA conditioning:

- Direction register: $\$FF$ (PIA port is all output)
- PIA Peripheral Ready (PIA_RDY)

Input 1- \rightarrow 0 \Rightarrow D7=1 , no interrupt generated:
D1=0 D0=0

- PIA Data Valid (PIA_DV) will be set: D5=0 D4=1
- PIA <Status/Control> 00010000 \$10

Example-1





Example-1

START	LDA SP, \$FFFF BSR CONA BSR CONP BSR READD TST A, \$80 BEQ FWD COM A	CONA	LDA B, \$2A STA B, <CONTROL> RTS
FWD	BSR CHK	CONP	LDA B, \$FF STA B, <DIRECTION> LDA B, \$10 STA B, <STATUS/CONTROL> RTS
SON	SWI		
READD	LDA B, <STATUS> AND B, \$01 BEQ « LDA A, <RX> RTS	CHK	LDA B, <STATUS/CONTROL> AND B, \$80 BEQ CHK STA A, PORT RTS



Example-2

Two computers are connected via ACIA interfaces.
Write a code to transfer the memory contents of
Computer-1 between addresses \$0000 and \$0100, to
the same memory addresses of Computer-2
The ACIAs for both computers will be conditioned as
follows:

RX/TX clk ratio: 1/8

T1=1 T0=1

8 bit data + 2 stop bits

T3=1 T2=1

Even parity

T5=1 T4=0

Control Register: 0010 1111 \Rightarrow \$2F



Example-2

TX Computer:

```
START  LDA    SP, $FFFF
        BSR    COND
        LDA    IX, $0000
BACK   BSR    INSP
        LDA    A, <IX+0>
        STA    A, <TRANSMITTER>
        INC    IX
        CMP    IX, $0101
        BNEQ   BACK
        SWI
COND   LDA    A, $2F
        STA    A, <CONTROL>
        RTS
INSP   LDA    A, <STATUS>
        AND    A, $02
        BEQ    INSP
        RTS
```

RX Computer:

```
START  LDA    SP, $FFFF
        BSR    COND
        LDA    IX, $0000
BACK   BSR    INSP
        STA    A, <IX+0>
        INC    IX
        CMP    IX, $0101
        BNEQ   BACK
        SWI
COND   LDA    A, $2F
        STA    A, <CONTROL>
        RTS
INSP   LDA    A, <STATUS>
        AND    A, $01
        BEQ    INSP
        LDA    A, <RECEIVER>
        RTS
```



Example-3

- On a display "A=" will be written, then the user enters a single digit decimal number. On the new line "B=" will be written. Then, another single digit decimal number will be written. On the next line "S=" will be written and the sum of the entered numbers will be written. The characters will be transmitted with the ASCII standard. ACIA will be conditioned as follows:

RX / TX clock frequency ratio: 1/1	T1=0	T0=0
8-bit data + 2 stop bits	T3=1	T2=1
Even Parity	T5=1	T4=0

Control Register: 0010 1100 \$2C



Example-3

```
START  LDA    SP, $FFFF
        LDA    A, $2C
        STA    A,<CONTROL>
        LDA    A, $41  */ A */
        BSR    SEND
        LDA    A, $3D  */ = */
        BSR    SEND
        BSR    RECV
        BSR    SEND
        STA    A, $0010  */ 37 */
        BSR    NEWLN

SEND    LDA    B,<STATUS>
        AND    B,$02
        BEQ    SEND
        STA    A,<TRANSMITTER>
        RTS
```

```
        LDA    A, $42  */ B */
        BSR    SEND
        LDA    A, $3D  */ = */
        BSR    SEND
        BSR    RECV
        BSR    SEND
        STA    A, $0011*/39*/
        BSR    NEWLN
        LDA    A, $53  */ S */
        BSR    SEND
        LDA    A, $3D  */ = */
        BSR    SEND
NEWLN   LDA    A, $0D
        BSR    SEND
        LDA    A, $0A
        BSR    SEND
        RTS

        RECV   LDA    B,<STATUS>
        AND    B,$01
        BEQ    RECV
        LDA    A,<RECEIVER>
        RTS
```



Example-3

```
LDA    A, <$0011>
AND    A, $0F */ 09 */
LDA    B,<$0010>
AND    B, $0F */ 07 */
ADD    A,B    */ 10 */
DAA                    */ 16 */
TAB                    */A->B */
SHR    A
SHR    A
SHR    A
SHR    A    */ 01 */
OR     A,$30 */ 31 */
BSR    SEND
TBA                    */B->A */
AND    A, $0F */ 06 */
OR     A, $30 */ 36 */
BSR    SEND
END    SWI
```

