İSTANBUL TEKNİK ÜNİVERSİTESİ BİLGİSAYAR VE BİLİŞİM FAKÜLTESİ

FPGA ÜZERİNDE BİR İŞLEMCİ TASARIMI

Bitirme Ödevi Ara Rapor

Tuğrul Yatağan 040100117

Bölüm : Bilgisayar Mühendisliği Anabilim Dalı : Bilgisayar Bilimleri

Danışman: Prof. Dr. Ahmet Coşkun Sönmez

Şubat 2015

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Özgünlük Bildirisi

- 1. Bu çalışmada, başka kaynaklardan yapılan tüm alıntıların, ilgili kaynaklar referans gösterilerek açıkça belirtildiğini,
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İstanbul, 16.02.2015

Tuğrul Yatağan

İmza"

FPGA ÜZERİNDE BİR İŞLEMCİ TASARIMI (ÖZET)

FPGA'lerin dinamik sayısal tasarım yeteneğinden faydalanılarak bütün işlemci mimarileri ve organizasyonları FPGA'ler üzerinde denenebilir. Bu farklı işlemci mimari tasarımlarının avantaj ve dezavantajlarının kıyaslanabilmesini sağlar. Ayrıca FPGA'ler yeni işlemci mimarisi tasarımlarının kolaylıkla geliştirilebilmesini ve üretimden önce test edilebilmesini sağlar. Bu projede özel tasarım mimari ve komut setine sahip bir RISC işlemci tasarlanıp, uygulamaya konulacaktır. Bu yeni mimari tasarımı için piyasada bulunan RISC işlemci mimarilerinden ilham alınmıştır. İşlemci tasarımı ve işlemcilerin çalışma mekanizmasının derinlemesine öğrenilmesi bu bitirme projesinin asıl amacıdır. Proje bitiminde komut işleyebilen tüm fonksiyonları yerinde FPGA üzerinde çalışabilen bir sanal (yazılımsal) işlemci tasarlanmıs olacaktır.

Bu projedeki sanal işlemci Verilog donanım tanımlama dilinde (HDL), Altera FPGA üzerinde geliştirilecektir. Tasarım olarak THUMB ve MIPS mimarilerinden esinlenilmiştir bu yüzden RISC mimarisi kullanılmıştır. İşlemci Harvard mimari yapısında tasarlanmıştır yani ayrı veri ve komut belleğine sahiptir. Ayrıca sabit uzunlukta Yükle/Kaydet (Load/Store) komut seti mimarisine sahiptir yani yalnızca Yükle ve Kaydet komutları veri belleğine erişebilir. Bu daha basit bir iş hattı tasarımının yapılmasına ve tek çevrimde komut işlenmesine olanak sağlamaktadır. İş hattı mimarisi için klasik RISC iş hattı mimarisi seçilmiştir yani işlemci 5 aşamalı iş hattına sahiptir. [4] İşlemci 16 Bit genişliğinde CPU, ALU, yazmaç ve veri yolu mimarisine sahiptir. Veri ve komut belleği için adres yolu genişliği 12 bittir. Bu yüzden en fazla adreslenebilir veri ve komut belleği boyutu 4K kelime uzunluğunda yani 8KB boyutundadır. Bu kısıtlamanın sebebi FPGA içerisindeki en fazla kullanılabilir dâhili bellek boyutunun kısıtlı olmasındandır.

Şimdiye kadar, tüm donanımsal ve yazılımsal kaynaklar temin edilip proje uygunluğu için test edilmiştir. Ayrıca tüm teorik ve mimari tasarım tamamlanmıştır. Proje geliştirme ve uygulama aşamasındadır.

A PROCESSOR DESIGN ON FPGA

(SUMMARY)

Using advantage of field programmable gate arrays (FPGA) dynamic digital design capability, every processor architecture and organization can be simulated on it. This gives a chance of compare different processor architecture design's advantages and disadvantages. Also new architecture designs can be tested on FPGA's before production. In this project a RISC processor will be implemented with a newly designed architecture and instruction set. Commercial processor architectures were examined and mixture of their design inspired the new architecture. Learning, design & working mechanism of a processor is main aim of this project. Final result of this project is a soft processor which will be able to execute instruction like fully functional normal microprocessor.

In this project a soft processor is designed and will be implemented on Altera FPGA in Verilog hardware description language. Mixture of THUMB and MIPS architectures were used to inspire new architecture so RISC architecture was chosen as main architecture. The processor is in Harvard architecture so it has separate instruction and data memory. Also it has fixed length Load/Store instruction set architecture which means only load and store instructions access to data memory. This leads to single cycle instruction execution capability with easier pipeline design. The classic RISC pipeline architecture is used for pipeline design so processor's pipeline has 5 stages. [4] The processor has 16 Bit CPU, ALU, register and data bus architecture. Address bus for data and instruction memory is 12 bit so maximum addressable instruction and data memory is 4K word and it is equal to 8KB. This restriction is due to the FPGA's usable internal memory size.

So far, all the hardware and software resources were obtained and tested, all theoretical research and architectural design were done.

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1. INTRODUCTION

In this project a RISC processor will be implemented with a newly designed architecture and instruction set on FPGA. Final result of this project is a soft processor which will be able to execute instruction like normal microprocessor. Project started October 2014 and will finished May 2015. Detailed project plan is described in chapter 2.

Mixture of THUMB and MIPS architectures were used to inspire new architecture so RISC architecture was chosen as main architecture. The processor is in Harvard architecture so it has separate instruction and data memory. The classic RISC pipeline architecture is used for pipeline design so processor's pipeline has 5 stages. [4] The processor has 16 Bit CPU, ALU, register and data bus architecture. Address bus for data and instruction memory is 12 bit. Detailed architectural design is described in chapter 3.1. Also processor has fixed length Load/Store instruction set architecture which means only load and store instructions access to data memory. Detailed instruction set design is described in chapter 3.1.2.

In this project the soft processor is designed and will be implemented on Altera FPGA in Verilog hardware description language. Detailed hardware and software resources are described in chapter 3.2.

So far, all the hardware and software resources were obtained and tested, all theoretical research and architectural design were done. All the work performed and left jobs to perform are described in chapter 4.

There are mainly three books to be a reference in this area. Also some online books and lecture notes are used for project's research. All sources which are used for research are referenced in chapter 5 according to APA style and cited in the text as square brackets ([#]).

2. PROJECT DECRIPTION AND PLAN

2.1. Project Description

Project consists of three main phases. Research, design and implementation. So far, research and design stages are done. All hardware and software resources are ready and tested for implementation stage.

2.2. Project Plan

It is planed that the project will be finished in May 2015. This graduation project has these major steps:

- Organization design
- Architectural design
- Instructions set design
- Choosing and understanding how to use FPGA kit
- Understanding how to program FPGA in Verilog
- ALU implementation
- Register interaction and BUS implementation
- Organization and pipeline implementation
- RAM and ROM access on FPGA
- Executing instructions in RAM
- Writing assembler for new instruction set

Schedule of these steps are shown in Figure 1.

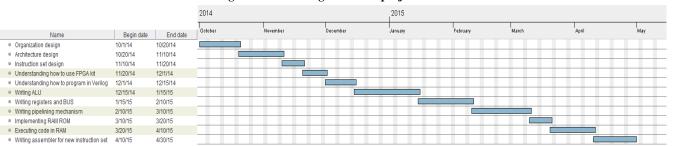


Figure 1: Gantt Diagram of the project schedule

3. STUDIES AND RESULTS

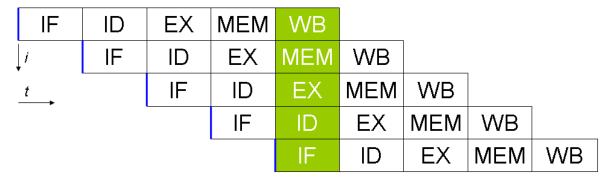
3.1. Architecture

Mixture of THUMB and MIPS architectures were used to inspire new architecture so RISC architecture was chosen as frame architecture. The processor is in Harvard architecture so it has separate instruction and data memory. Also it has fixed length Load/Store instruction set architecture which means only load and store instructions access to data memory. This leads to single cycle instruction execution capability with easier pipeline design. The classic RISC pipeline architecture is used for pipeline design so processor's pipeline has 5 stages. [4]

Classic RISC architecture pipeline has 5 stages. [4] Which are;

- Instruction fetch
- Instruction decode
- Execute (ALU)
- Memory access
- Write back

Figure 2: 5 stage classic RISC pipeline timing diagram [5]



The processor has 16 Bit CPU, ALU, register and data bus architecture. Address bus for data and instruction memory is 12 bit so maximum addressable instruction and data memory is 4K word and it is equal to 8KB

3.1.1. Organization

Slightly modified MIPS architecture is used for organizational design. Organization of major blocks with 5 stage pipeline is shown in Figure 3. [5]

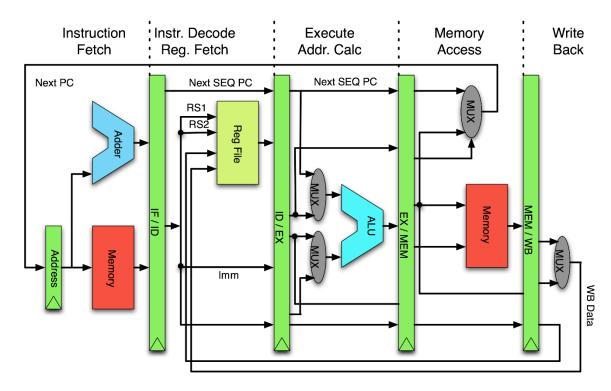


Figure 3: Classic 5 stage RISC pipeline organization [5]

There are 8 general purpose 16 bit registers in register file. Also there are 16 bit instruction and condition code register, 12 bit program counter and address register. All general purpose register accessible and they can transfer data between them. PC can only be modifiable via branch instructions, its content is not accessible. IR is not accessible. CCR's some condition bits can be changed via some instructions and they can be usable via only branch instructions.

Registers

Abbreviation	Equivalent	Bit
R0	General purpose register O	16
R1	General purpose register 1	16
R2	General purpose register 2	16
R3	General purpose register 3	16
R4	General purpose register 4	16
R5	General purpose register 5	16
R6	General purpose register 6	16
R7	General purpose register 7	16
IR	Instruction register	16
PC	Program counter	12
AR	Address register	12
CCR	Condition code register	16

Condition code register

_	15	14			 	 6		 			
Ī				Ī		IRQ	I	N	Z	С	٧

Bit	Assignment									
N	Negative/Less than									
Z	Zero									
С	Carry/Borrow									
V	Overflow									
I	IRQ Disable									
IRQ	IRQ Status									

3.1.2.Instruction Set

All instructions are 16 Bit fixed length instruction. There are 10 type of instruction. Load/Store instruction set so only load and store instructions can access to data memory.

Instruction Types

- 1. Shift Instructions
- 2. Add/Subtract Register Instructions
- 3. Add/Subtract Register Immediate Instructions
- 4. Move/Compare/Add/Subtract Immediate Instructions
- 5. ALU Instructions
- 6. Load/Store with Register Offset Instructions
- 7. Load/Store with Immediate Offset Instructions
- 8. Conditional Branch Instructions
- 9. Unconditional Branch Instruction
- 10. Inherent Instructions

Instruction Set format

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	0	0	0	0	0	Ор			off4			RS		Rd		
2	0	0	1	Ор		Off3				Rn Rs				Rd		
3	0	1	0	Ор		Off6 Rs						Rd				
4	0	1	1	0	р	Rd Off8										
5	1	0	0		0	р			Rn			RS		Rd		
6	1	0	1	Ор		off3			Ro Rb						Rd	
7	1	1	0	Ор			of	f6				Rb			Rd	
8	1	1	1	0		Cond Off8										
9	0	0	0	1	off12											
10	1	1	1	1	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ		Ор	

Operand Table

Abbreviation	Equivalent	Bit
Rd	Destination Register	3
Rs	Source Register	3
Rb	Base Register	3
Ro	Offset Register	3
off#	Immediate Offset	#
Ор	Operation	X
Cond	Condition	Х

3.1.2.1. Shift Instructions

Immediate shift operation instructions with two register operands. Logical left, logical right, arithmetic right, circular right shift operations are implemented.

				11				 5	4	3	2	1	0
0	0	0	0	0	р	of	f4		Rs			Rd	

Ор	Assembler	Action	Updates
00	LSL Rd, Rs, #Off4	Logic shift left by #Off4	NZC
01	LSR Rd, Rs, #Off4	Logic shift right by #Off4	NZC
10	ASR Rd, Rs, #Off4	Arithmetic shift right by #Off4	NZC
11	CSR Rd, Rs, #Off4	Circular shift right by #Off4	N Z C

Example Instruction:

LSR R2, R5, #10

3.1.2.2. Add/Subtract Instructions

Add and subtract operations with three register operands and immediate positive 3 bit offset.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	1	Ор	(off3			Rn			Rs			Rd	

Op	Assembler	Action	Updates		
0	ADD Rd, Rs, #Off3	Rd := Rs + Rn + #Off3	NZCV		
1	SUB Rd, Rs, #Off3	Rd := Rs - Rn + #Off3	NZCV		

Example Instructions:

3.1.2.3. Add/Subtract Register Immediate Instructions

Add and subtract operations with two register operands and immediate positive 6 bit offset.

15				10	9	8	7	6	5	4	3	2	1	0
0	1	0	Ор		0f	f6				Rs			Rd	

Op	Assembler	Action	Updates		
0	ADD Rd, Rs, #Off3	Rd := Rs + #Off6	NZCV		
1	SUB Rd, Rs, #Off3	Rd := Rs - #Off6	NZCV		

Example Instruction:

ADD R1, R4, #60

3.1.2.4. Move/Compare/Add/Subtract Immediate Instructions

Move, compare, add and subtract operations with one register operands and immediate positive 8 bit offset. Compare operations only updates condition code register, no write back stage.

1.	5	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0)	1	1	0	р		Rd					of	f8			

Op	Assembler	Action	Updates
00	MOV Rd, #Off8	Rd := #Off8	N Z
01	CMP Rd, #Off8	Rd - #Off8	NZCV
10	ADD Rd, #Off8	Rd := Rd + #Off8	NZCV
11	SUB Rd, #Off8	Rd := Rd + #Off8	NZCV

Example Instructions:

MOV R1, #130

CMP R2, #25

ADD R5, #40

SUB R3, #200

3.1.2.5. ALU Instructions

These instructions performs ALU operations like logical, shift and compare instructions with two or three register operands. Bitwise logical operations, add with carry and subtract with borrow operations, shift operations are implemented with three register operands. Complement and negations operations, compare and test operations are implemented with two register operands. Operation table for ALU instructions is incomplete, it can be extend.

					10	9	8	7	6	5	4	3	2	1	0
ĺ	1	0	0	0	р			Rn	<u> </u>		Rs			Rd	

Ор	Assembler	Action	Updates
0000	AND Rd, Rs, Rn	Rd := Rs AND Rn	N Z
0001	OR Rd, Rs, Rn	Rd := Rs OR Rn	ΝZ
0010	XOR Rd, Rs, Rn	Rd := Rs XOR Rn	N Z
0011	LSL Rd, Rs, Rn	Rd := Rs << Rn	NZC
0100	LSR Rd, Rs, Rn	Rd := Rs >> Rn	NZC
0101	ASR Rd, Rs, Rn	Rd := Rs ASR Rn	NZC
0110	CSR Rd, Rs, Rn	Rd := Rs CSR Rn	NZC
0111	ADC Rd, Rs, Rn	Rd := Rs + Rn with Carry	NZCV
1000	SBC Rd, Rs, Rn	Rd := Rs - Rn with Carry	NZCV
1001	NEG Rd, Rs	Rd := −Rs	ΝZ
1010	NOT Rd, Rs	Rd := NOT Rs	N Z
1011	CMP Rd, Rs	Rd – Rs	NZCV
1100	TST Rd, Rs	Rd AND Rs	NZCV
1101			
1110			
1111			

Example Instructions:

XOR R2, R5, R3

CSR R1, R3, R4

ADC R4, R2, R6

NOT R5, R6

CMP R3, R5

3.1.2.6. Load/Store with Register Offset Instructions

These instructions transfer 16 bit word between registers and memory. Memory address operands are base register, offset register and 3 bit immediate offset.

				10							
1	0	1	Ор	off3		Ro		Rb	_	Rd	

Ор	Assembler	Action
0	LD Rd, [Rb, Ro, #Off3]	Rd := MEM[Rb + Ro + #Off3]
1	STR Rd, [Rb, Ro, #Off3]	MEM[Rb + Ro + #Off3] := Rd

Example Instructions:

LD R5, [R1, R2, #4]

LD R3, [R5, R2] // offset is #0

STR R1, [R5, R3, #5]

3.1.2.7. Load/Store with Immediate Offset Instructions

These instructions transfer 16 bit word between registers and memory. Memory address operands are base register and 6 bit immediate offset.

15					_	_	7	6	5	4	3	2	1	0
1	1	0	Ор	-	of	f6	<u>-</u>	=		Rb	=		Rd	

Op	Assembler	Action
0	LD Rd, [Rb, #Off6]	Rd := MEM[Rb + #Off6]
1	STR Rd, [Rb, #Off6]	MEM[Rb + #Off6] := Rd

Example Instructions:

LD R3, [R5, #10]

STR R1, [R5, #26]

STR R1, [R3] // offset is #0

3.1.2.8. Conditional Branch Instructions

These instructions perform a conditional branch depending on the state of the condition code N Z C V bits with 8 bit offset from PC register. [2]

				10		8	7	6	5	4	3	2	1	0
1	1	1	0	Cor	nd			=	-	of	f8	<u> </u>	-	

Cond	Assembler	Condition Logic	Condition
0000	BEQ #Off8	z = 1	equal
0001	BNE #Off8	z = 0	not equal
0010	BCS #Off8	C = 1	unsigned higher or same
0011	BCC #Off8	C = 0	unsigned lower
0100	BMI #Off8	N = 1	negative
0101	BPL #Off8	N = 0	positive or zero
0110	BVS #Off8	V = 1	overflow
0111	BVC #Off8	V = 0	no overflow
1000	BHI #Off8	Z' * C	unsigned higher
1001	BLS #Off8	Z + C'	unsigned lower or same
1010	BGE #Off8	(N * V) + (N' * V')	signed greater than or equal
1011	BLT #Off8	N XOR V	signed less than
1100	BGT #Off8	(N * Z' * V) + (N' * Z' * V')	signed greater than
1101	BLE #Off8	Z + (N XOR V)	signed less than or equal
1110			
1111			

Example Instructions:

BEQ #50 // BEQ Label
BGT #25 // BGT Label

3.1.2.9. Unconditional Branch Instruction

This instruction performs an unconditional branch with 12 bit offset from PC register.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	1						off	F12					

Assembler	Action
BAL #Off12	PC := PC + #0ff6

Example Instruction:

BAL Label // Label may be #5324 offset

3.1.2.10. Inherent Instructions

These instructions are implied (inherent) instructions which means they have not any operand. Operation table for inherent instructions is incomplete, it can be extend.

Ор	Assembler	Action	Updates
000	NOP	No operation	
001	ION	Interrupts on	I
010	IOF	Interrupts off	I
011	RTI	Return from interrupt	
100	CLRC	Clear N Z C V bits	NZCV
101			
110			
111			

Example Instructions:

NOP

ION

3.2. Implementation

Physical implementation will be done on Altera DE0-Nano FPGA education board. Altera Quartus 13.0sp1 development environment is used for development. Altera Modelsim simulation software and Logisim digital design tool are used for simulate the design.

3.2.1.FPGA

Altera DE0-Nano development and education board has Altera Cyclone® IV EP4CE22F17C6N FPGA which has:

- 22,320 Logic elements (LEs)
- 594 Embedded memory (Kbits)
- 153 Maximum FPGA I/O pins, some pins hardwired to LEDs and switches.

These features are more than enough for implementation of the processor.

Altera EPCS16 32-MB Configuration 8 Green LEDs 40-Pin GPIO Header Device SDRAM 2 Push Buttons **USB Type** Mini-AB Port Altera Cyclone IV EP4CE22F17C6N 26-Pin Header 2-Kb I2C **EEPROM** 4 DIP Switches A/D Converter 40-Pin GPIO Header 50-MHz Clock Digital 2-Pin External Accelerometer Oscillator Power Header

Figure 4: Altera DE0-Nano development and education board [1]

Altera DE0-Nano development board enables to test new designs on FPGA via USB port, also its memory content can be assign before run and its memory content can be monitored during run time.

3.2.2. Simulation

Altera Modelsim simulation software and Logisim digital design tool are used for simulate the design before FPGA run.

3.2.2.1. Modelsim

Altera FPGA's default simulation software. It has gate level and logic level simulation capabilities. Detailed timing simulation can be done. It gives actual results as like FPGA run.

3.2.2.2. Logisim

Logisim is an educational tool for designing and simulating digital logic circuits. It can be used to design and simulate entire CPUs. It can give detailed look to processor before the FPGA implementation.

4. TO DO LIST

Jobs to do for project until end of May 2015 can be list as:

- Understanding how to program in Verilog on Altera FPGA effectively
- ALU implementation with Logisim and Verilog
- Register interaction and BUS implementation with Logisim and Verilog
- Organization and pipeline implementation with Logisim and Verilog
- RAM and ROM access on FPGA with Verilog
- Executing instructions in RAM
- Testing and correcting instruction execution
- Writing assembler for new instruction set with Python
- Testing whole system with assembler
- Getting results and making experiments on processor

5. REFERENCES

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