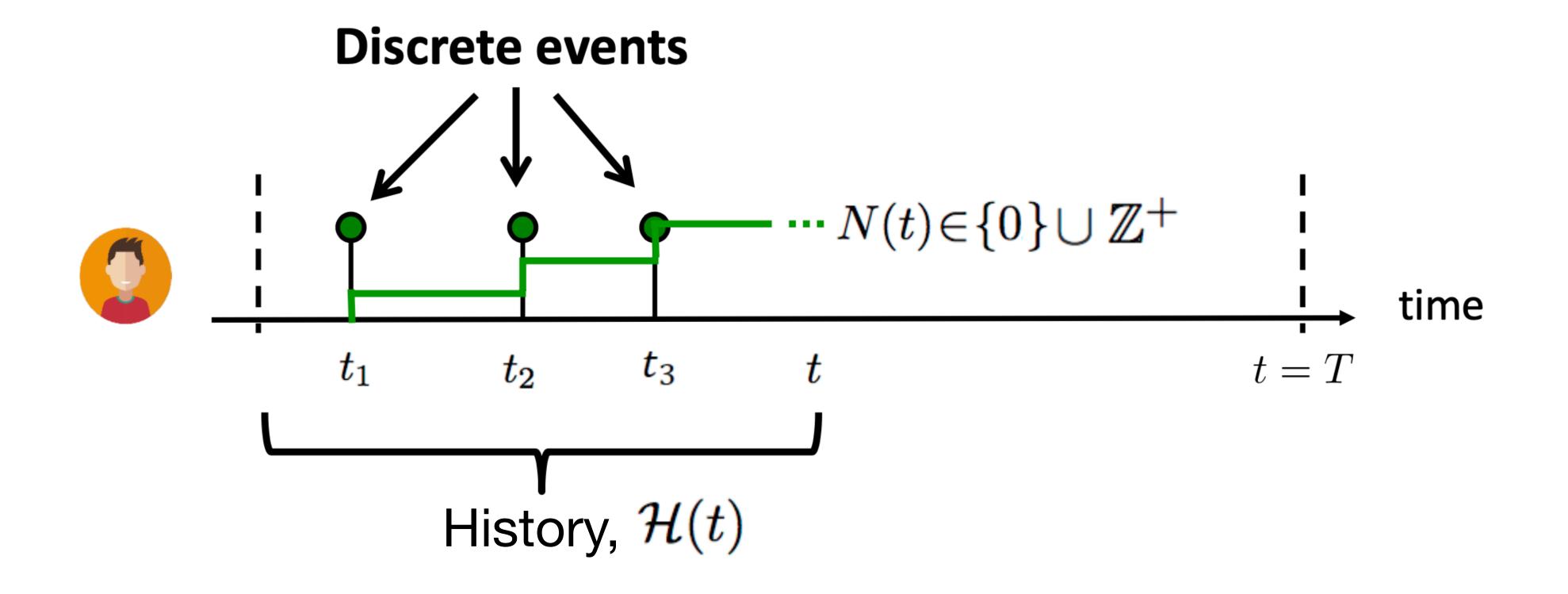
## Hawke's neural process

# Temporal Point Processes: Recap

## Temporal point processes

• **Temporal point process** — a random process whose realization consists of discrete events localized in time  $\mathcal{H} = \{t_i\}$ 



# Skoltech

### Building blocks to represent different dynamic processes

#### Poisson processes:

$$\lambda^*(t) = \lambda$$

Inhomogeneous Poisson processes:

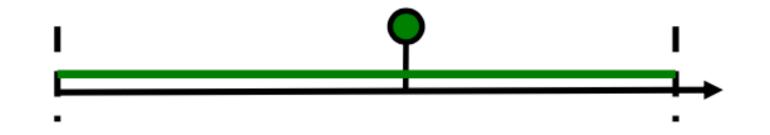
$$\lambda^*(t) = g(t)$$

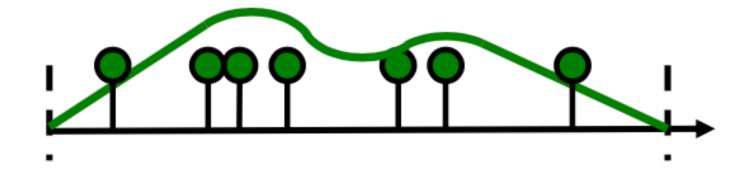
Terminating point processes:

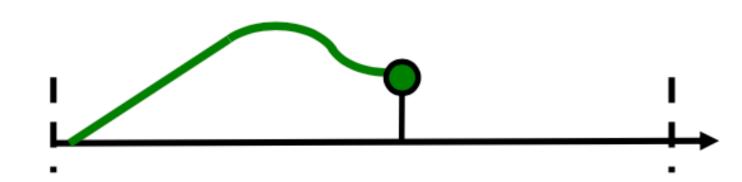
$$\lambda^*(t) = g^*(t)(1 - N(t))$$

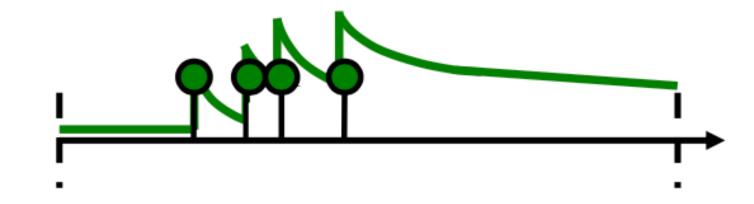
Self-exciting point processes:

$$\lambda^*(t) = \mu + \alpha \sum_{t_i \in \mathcal{H}(t)} \kappa_{\omega}(t - t_i)$$



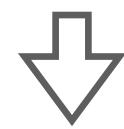






## Vanilla Hawkes process drawbacks

- Past events can temporarily raise the probability of future events
- Real world application: the flexibility of vanilla Hawkes process is very limited to approximate many sections of the problems



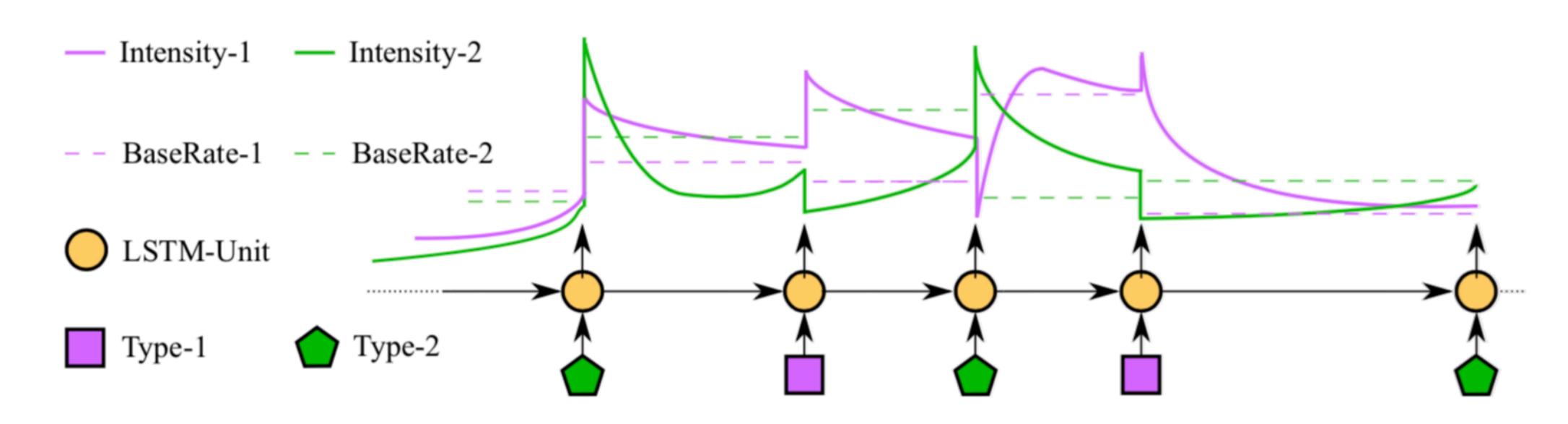
 Need a better model with least assumptions to approximate the conditional intensity function

Solution: Neural Hawkes process

## Neural Hawkes process

## Neural Hawkes process advantages

- History effect does not need to be additive
- Allows for complex memory effects (such as delays)



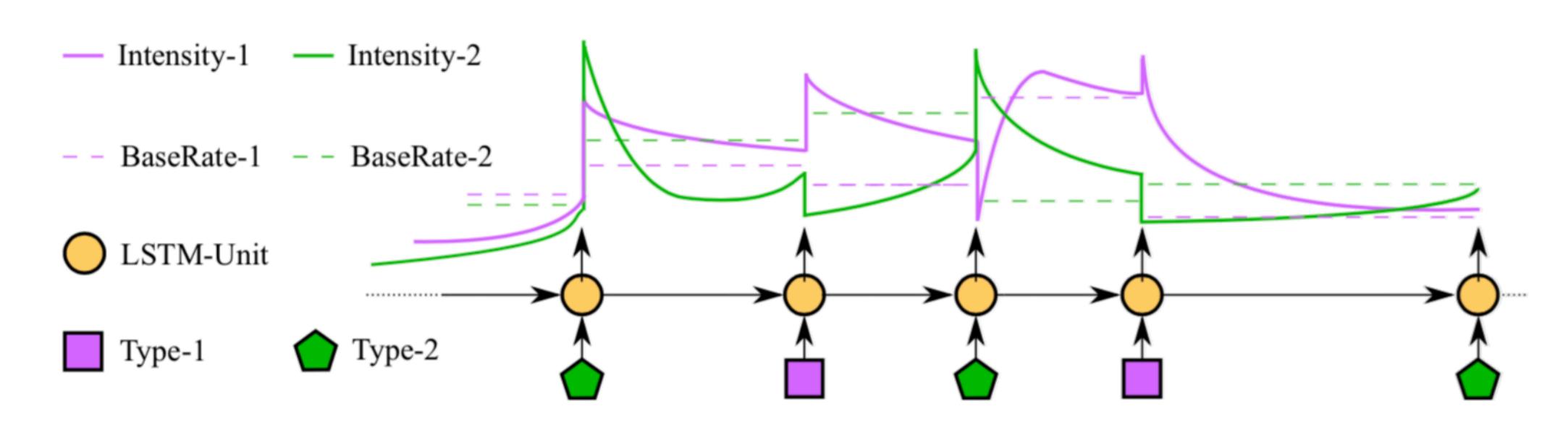
Source: Mei & Eisner, NIPS 2017

## Neural Hawkes process: RNNs

- Memory via the continuous-time LSTM
- Excitation & inhibition via activation function

$$\mathbf{h}(t) = \text{RNN}(\mathcal{H}(t))$$

$$\lambda_u(t) = f_u(\mathbf{w}_u^\top \mathbf{h}(t))$$



Source: Mei & Eisner, NIPS 2017

# Skoltech

### Event stream data

- Financial transactions
- Medical notes







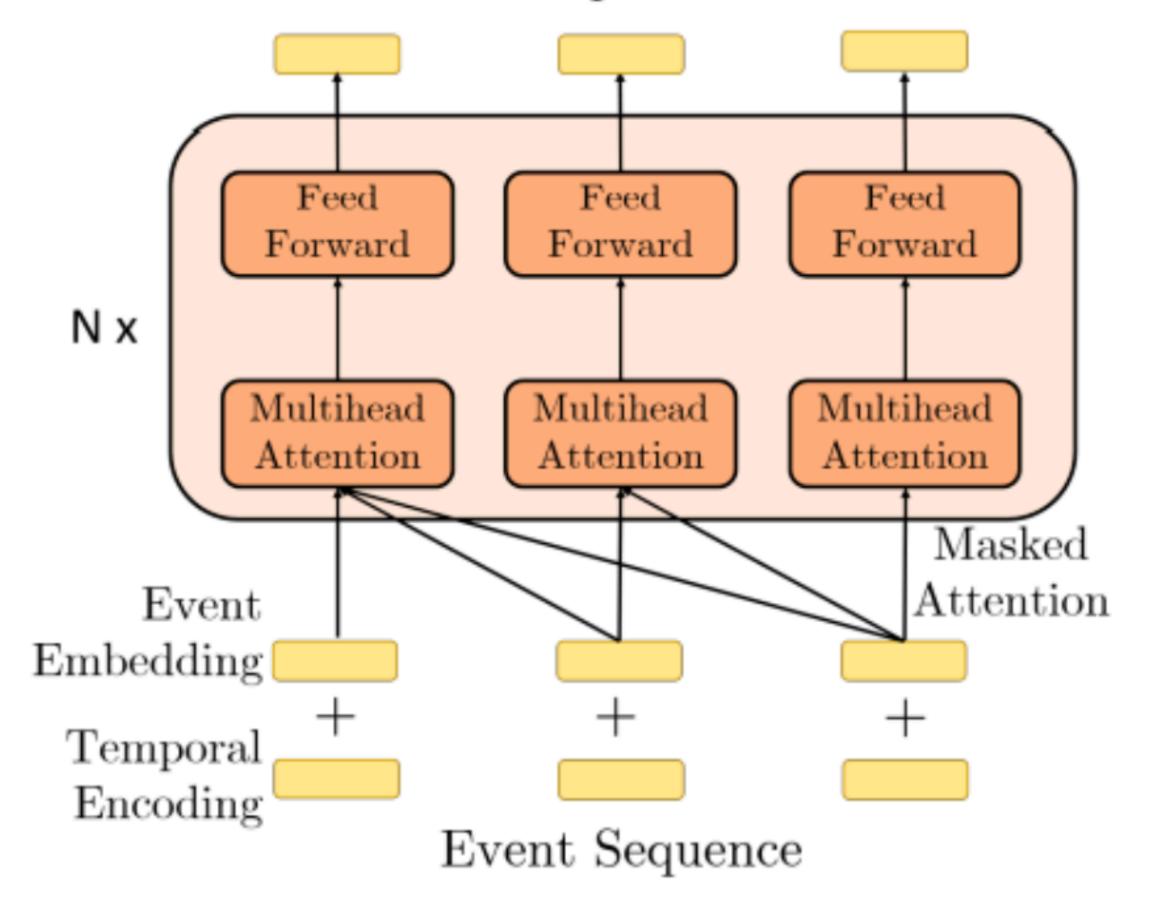
#### Long-term dependencies issues

- Financial transactions: policy issues
- Medical notes: chronic diseases



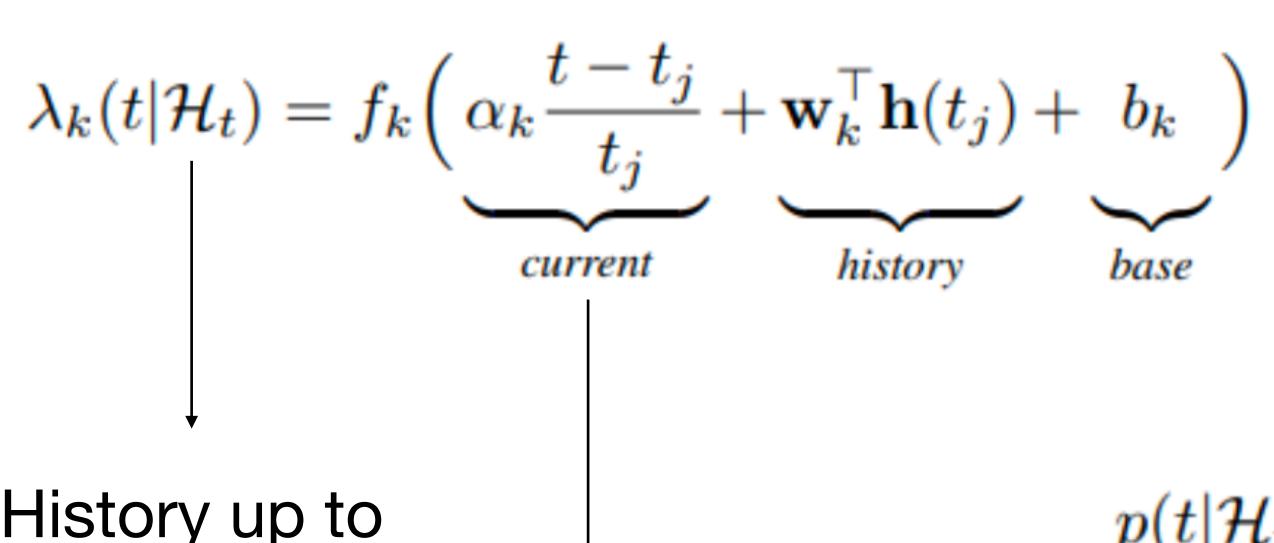
## Neural Hawkes process: Transformers

#### Hidden Representations



Source: Zuo, Simiao, et al. "Transformer Hawkes process." ICML. 2020

## Neural Hawkes process: Transformers



History up to time *t* 

Interpolation between two observed time stamps

$$p(t|\mathcal{H}_t) = \lambda(t|\mathcal{H}_t) \exp\left(-\int_{t_j}^t \lambda(\tau|\mathcal{H}_\tau)d\tau\right),\,$$

$$\widehat{t}_{j+1} = \int_{t_j}^{\infty} t \cdot p(t|\mathcal{H}_t) dt,$$

$$\widehat{k}_{j+1} = \underset{k}{\operatorname{argmax}} \frac{\lambda_k(t_{j+1}|\mathcal{H}_{j+1})}{\lambda(t_{j+1}|\mathcal{H}_{j+1})}.$$

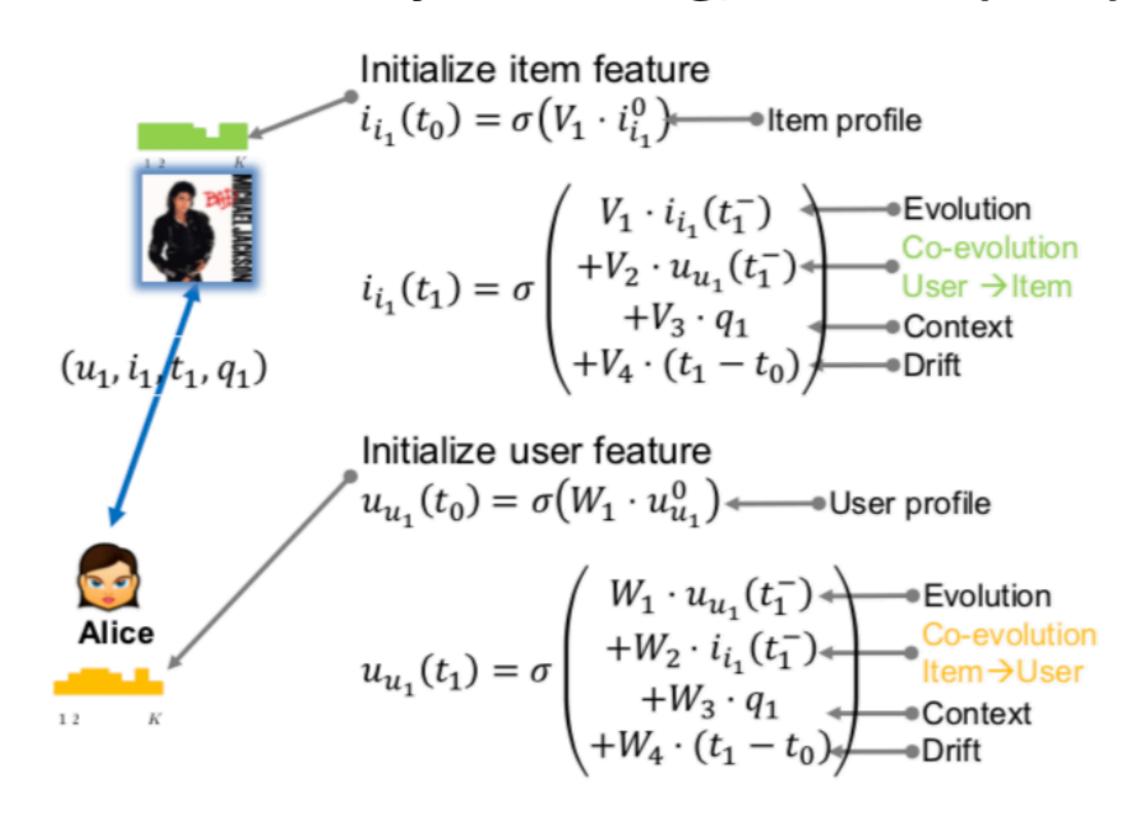
## Applications

### Predictive Models

#### Know-Evolve, Trivedi et al. (2017)

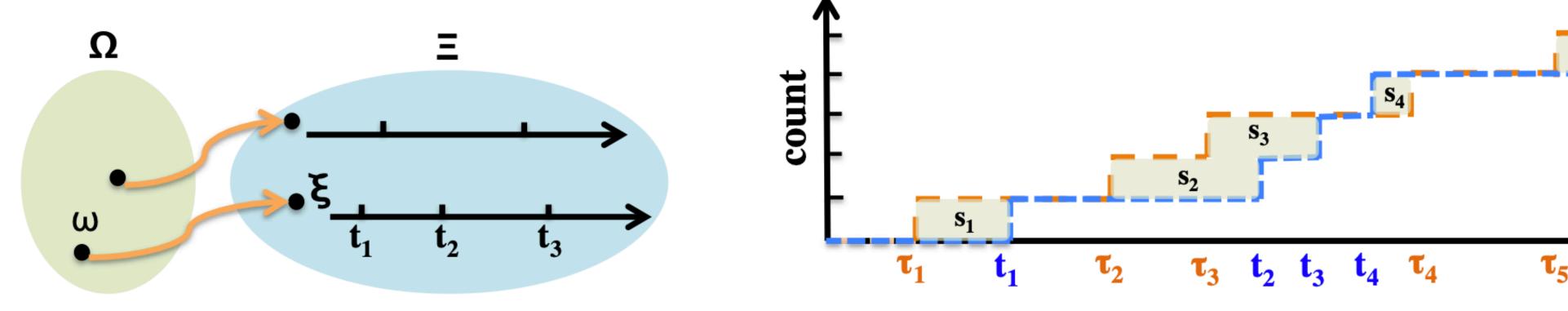


#### Coevolutionary Embedding, Dai et al. (2017)



## **Generative Models**

- Key idea: Intensity- and likelihood-free models
- a) The outcome of the random experiment  $\omega$  is mapped to a point in space of count measures  $\xi$ ;
- b) Distance between two sequences  $\xi = \{t1,t2,...\}$  and  $\rho = \{\tau1,\tau2,...\}$



a) Point process probability space

pace b)  $\|\cdot\|_{\star}$  distance between sequences

Source: Shuai Xiao et al. Wasserstein Learning of Deep Generative Point Process Models

## Conclusion

- A type of sequential data observed in many applied problems:
  - Client's actions
  - Abnormal Events
  - Diseasespread
- Various models for intensity include LSTMs, Transformers