

**Итоговый проект по курсу
«Введение в модели последовательных данных»**

Predictive maintenance on pump sensor data

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Описание датасета

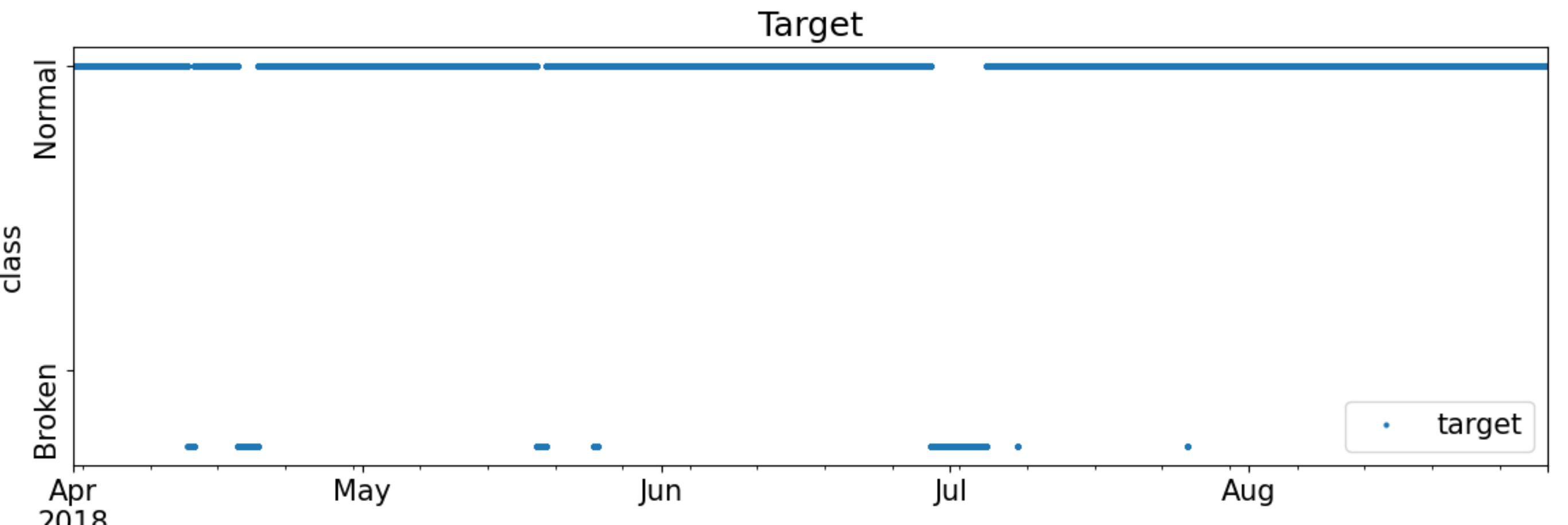
Задача профилактического обслуживания насоса
(predictive maintenance)

Датасет: https://ga-data-cases.s3.eu-central-1.amazonaws.com/pump_sensor.zip

Размерность: 220320 x 55

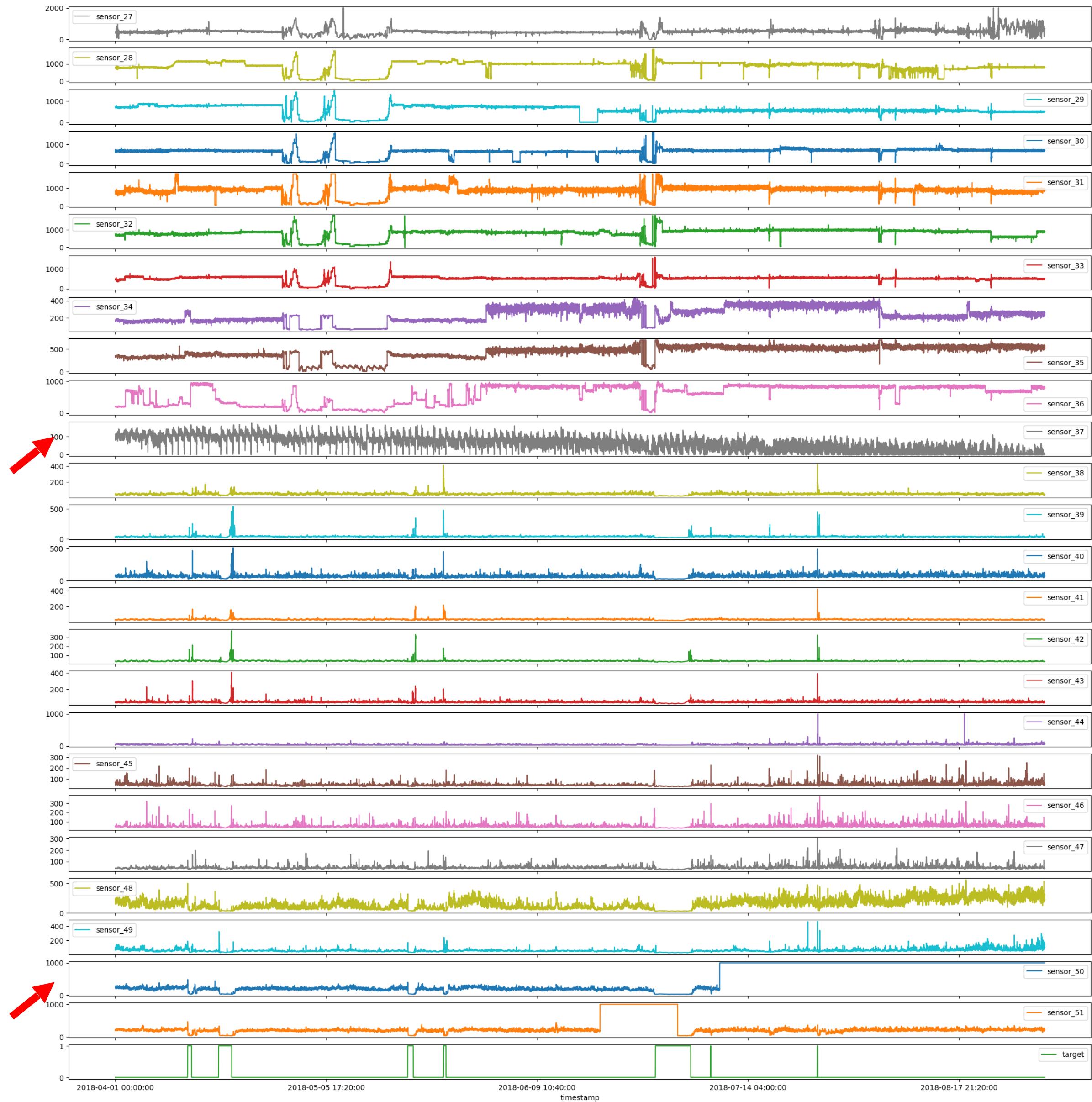
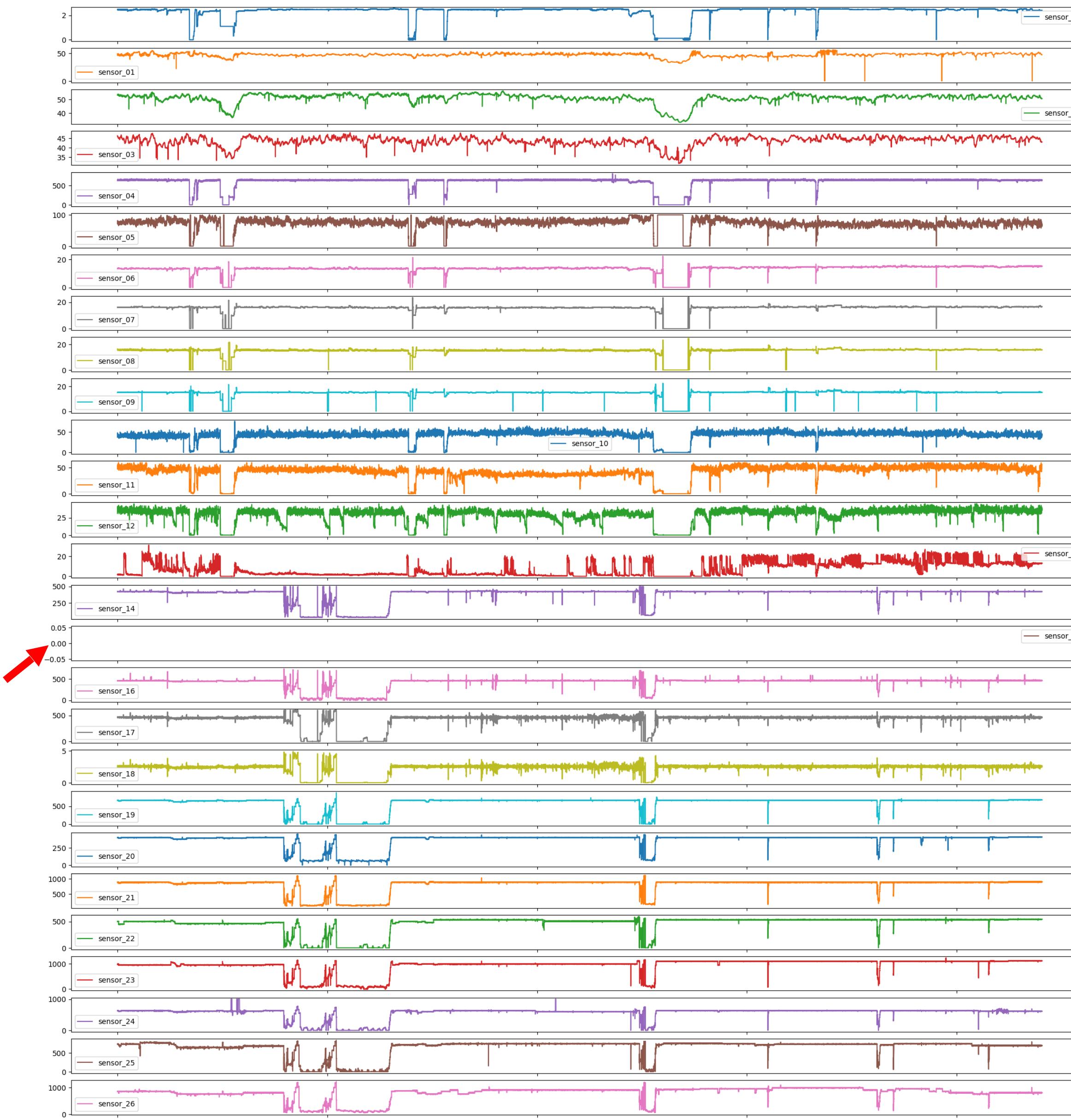
Описание целевого столбца:

NORMAL	205836
BROKEN	14477

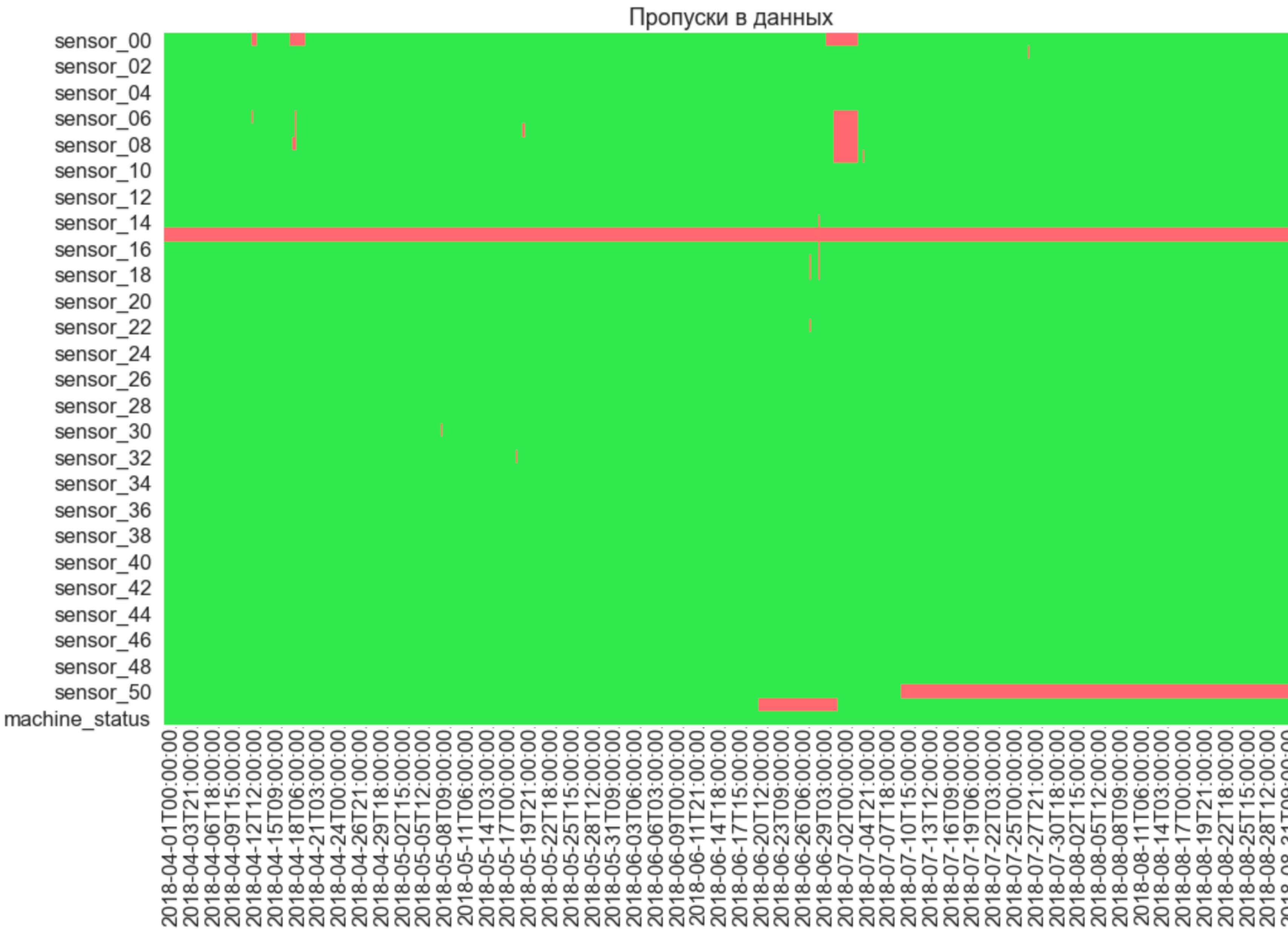


timestamp	sensor_00	sensor_01	sensor_02	sensor_03	sensor_04	sensor_05	sensor_06	sensor_07	sensor_08	sensor_09	...	sensor_44	sensor_45	sensor_46	sensor_47	sensor_48	sensor_49	sensor_50	sensor_51	machine_status
2018-04-01 00:00:00	2.465394	47.09201	53.2118	46.310760	634.3750	76.45975	13.41146	16.13136	15.56713	15.05353	...	39.641200	65.68287	50.92593	38.194440	157.9861	67.70834	243.0556	201.3889	NORMAL
2018-04-01 00:01:00	2.465394	47.09201	53.2118	46.310760	634.3750	76.45975	13.41146	16.13136	15.56713	15.05353	...	39.641200	65.68287	50.92593	38.194440	157.9861	67.70834	243.0556	201.3889	NORMAL
2018-04-01 00:02:00	2.444734	47.35243	53.2118	46.397570	638.8889	73.54598	13.32465	16.03733	15.61777	15.01013	...	39.351852	65.39352	51.21528	38.194443	155.9606	67.12963	241.3194	203.7037	NORMAL
2018-04-01 00:03:00	2.460474	47.09201	53.1684	46.397568	628.1250	76.98898	13.31742	16.24711	15.69734	15.08247	...	39.062500	64.81481	51.21528	38.194440	155.9606	66.84028	240.4514	203.1250	NORMAL
2018-04-01 00:04:00	2.445718	47.13541	53.2118	46.397568	636.4583	76.58897	13.35359	16.21094	15.69734	15.08247	...	38.773150	65.10416	51.79398	38.773150	158.2755	66.55093	242.1875	201.3889	NORMAL

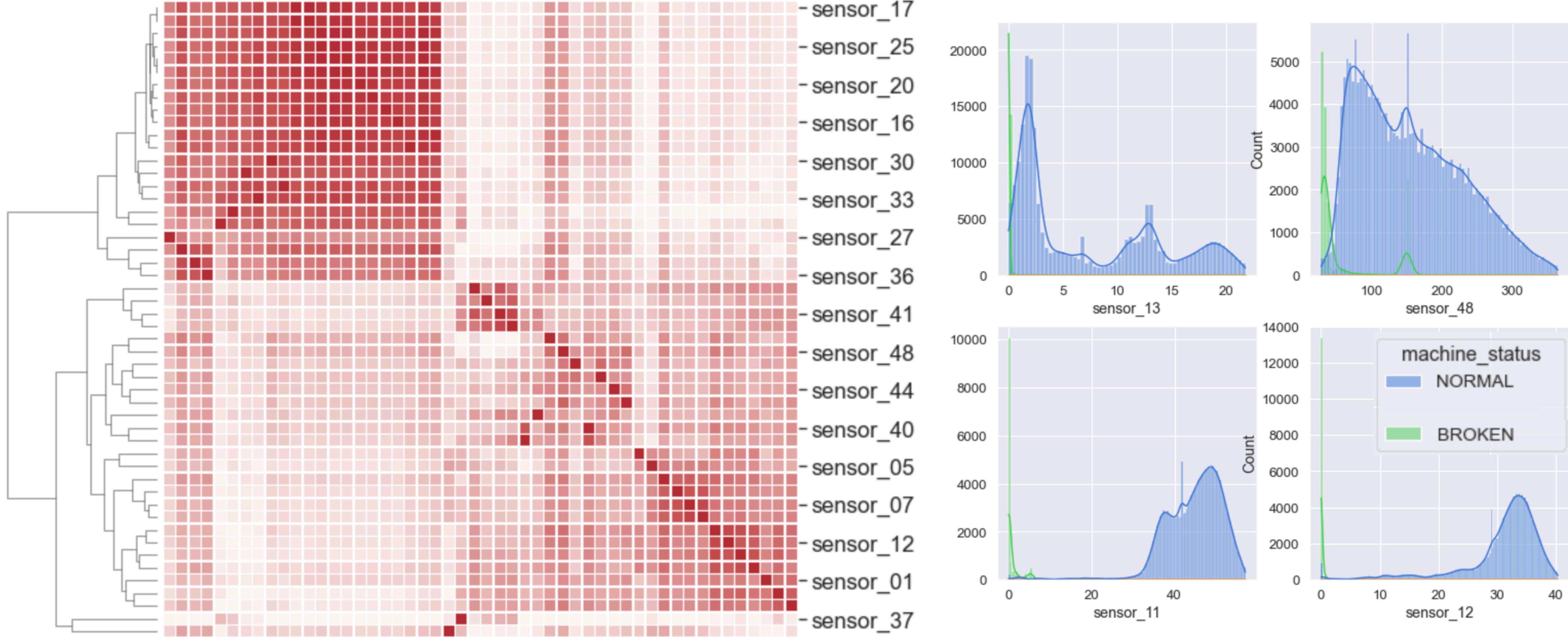
Визуализация датасета



Обработка пропусков



Корреляции, значимые признаки



Метрики

- Binary crossentropy

```
model.compile(loss='binary_crossentropy', optimizer='adam')
```

```
class_weight = {0: 1.,
                1: 15.}
```

Распределение machine_status



Подготовка данных

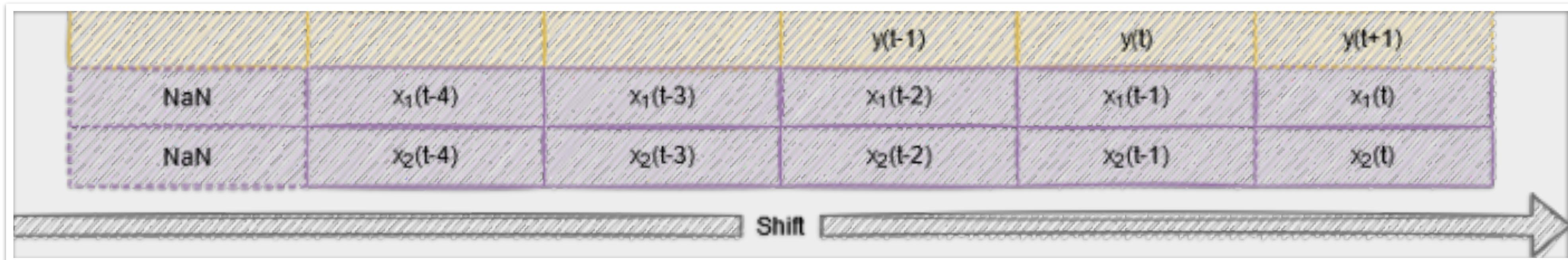
Основные шаги программы:

```
1) data = data.fillna(method="ffill")
2) data['target'] = data['machine_status'].map({'NORMAL': 0, 'BROKEN': 1, 'RECOVERING': 1})
3) data = data.drop(labels=['sensor_15', 'sensor_37', 'sensor_50', 'machine_status'], axis=1)
4) data_scaled.iloc[:, :-1] = MinMaxScaler().fit_transform(data.iloc[:, :-1])
5) data_shift.iloc[:, -1] = data_scaled.iloc[:, -1].shift(-Future)

Future = 60 — параметр сдвига (см. рис. ниже)
```

Разбиение на обучающий, валидационный и тестовый датасеты:

```
X_train = data_shift.iloc[:120000, :-1].values
y_train = data_shift.iloc[:120000, -1].values
X_valid = data_shift.iloc[140000:, :-1].values
y_valid = data_shift.iloc[140000:, -1].values
X_test = data_shift.iloc[120000:140000, :-1].values
y_test = data_shift.iloc[120000:140000, -1].values
```



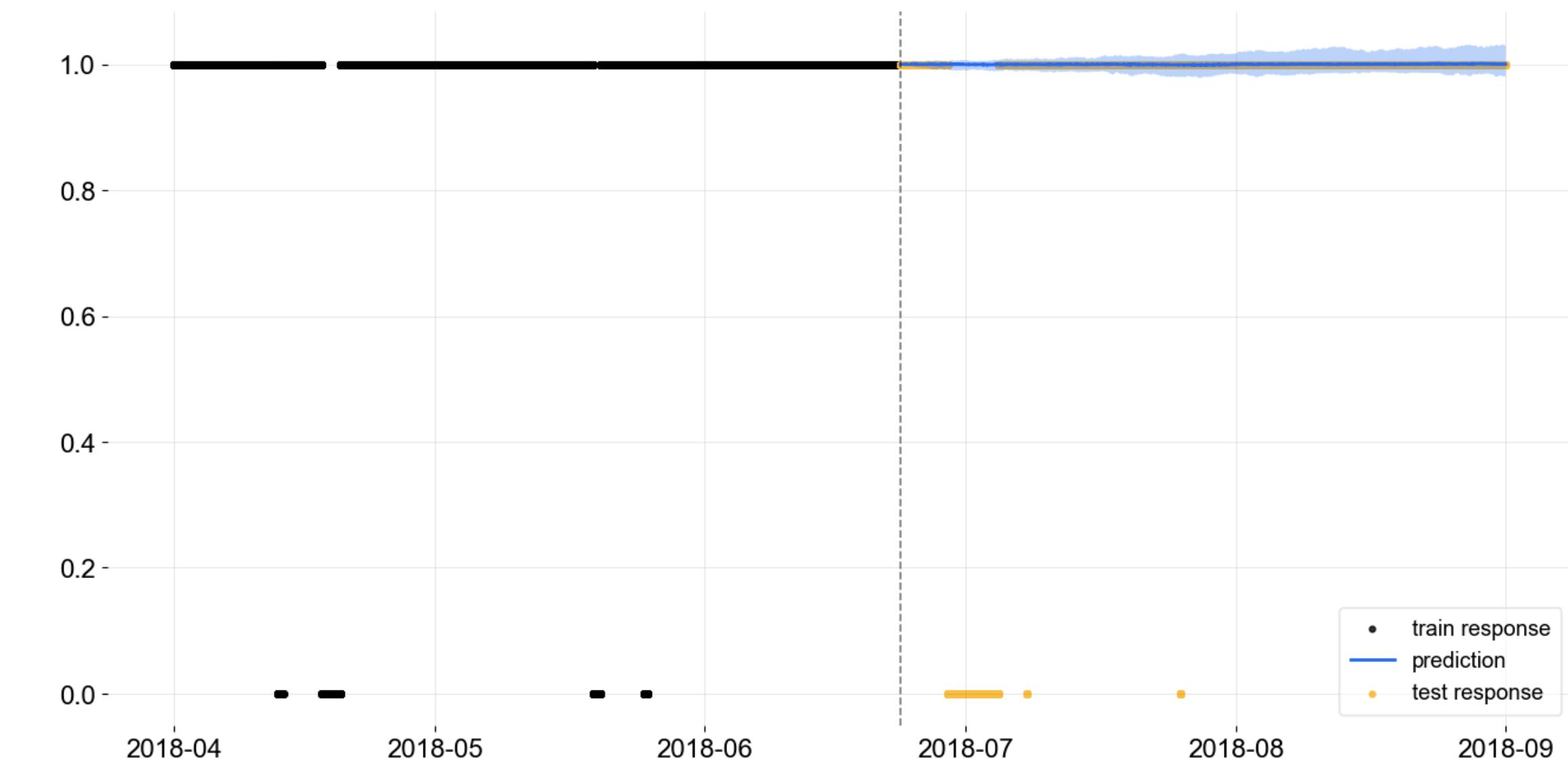
Модели

- ARIMA/Orbit
- RNN
- PCA + Transformer
- LSTM

Обучение Orbit

```
from orbit.models.dlt import DLT
# инициализируем модель
model = DLT(
    response_col='delta',
    date_col='timestamp',
    regressor_col=list(train.columns[:-1]),
    global_trend_option = 'flat',
    seed=1,
)
# обучаем модель
model.fit(df=train.reset_index())
# делаем прогноз
y_train_pred = model.predict(df=train.iloc[:, n:].reset_index())
y_test_pred = model.predict(df=test.iloc[:, n:].reset_index())
```

Test



Обучение RNN

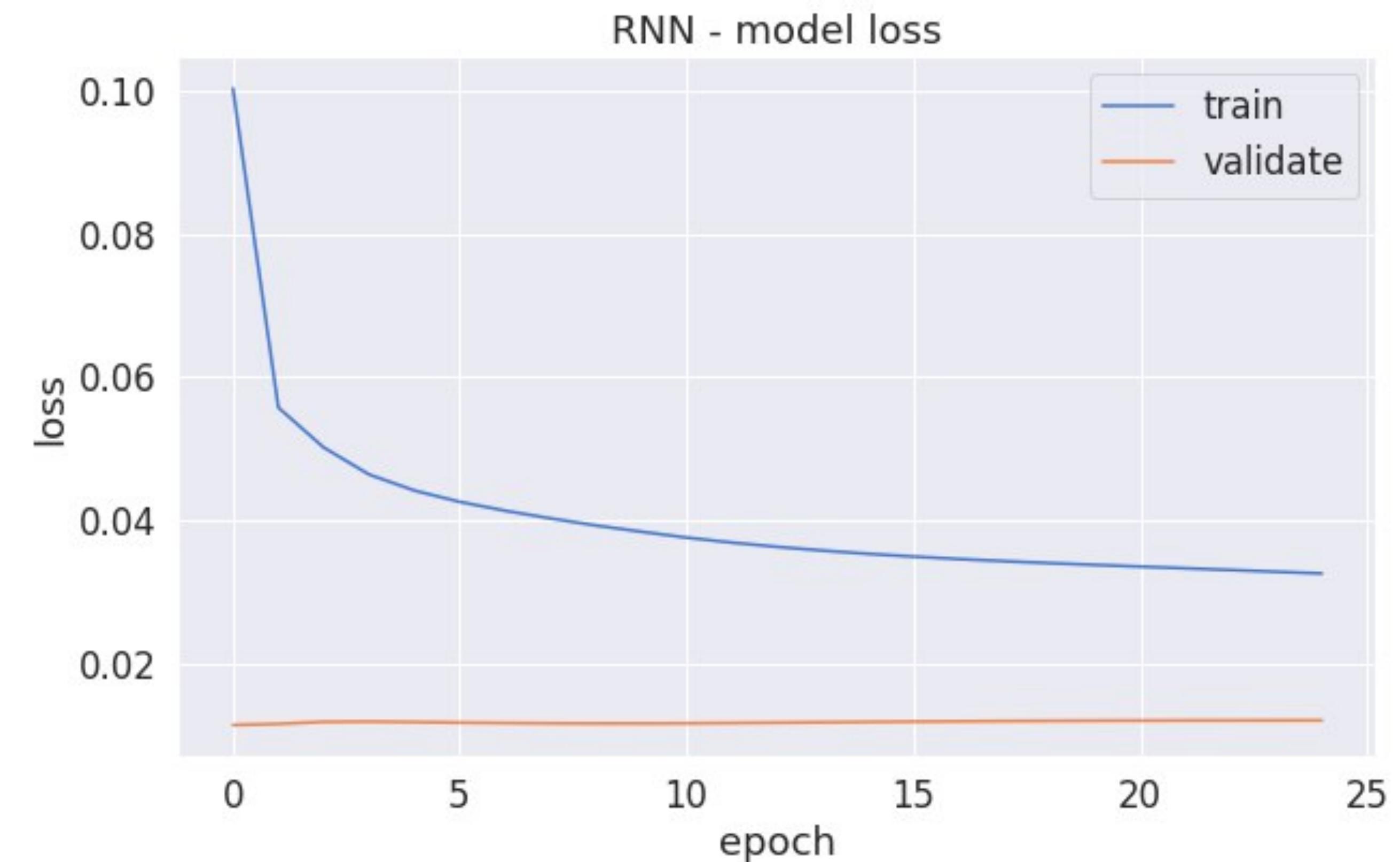
```
x = SimpleRNN(16, input_shape=(in_shape[1], in_shape[2]))(inputs)
out = Dense(1, activation='sigmoid')(x)

model = tf.keras.Model(inputs=inputs, outputs=out)

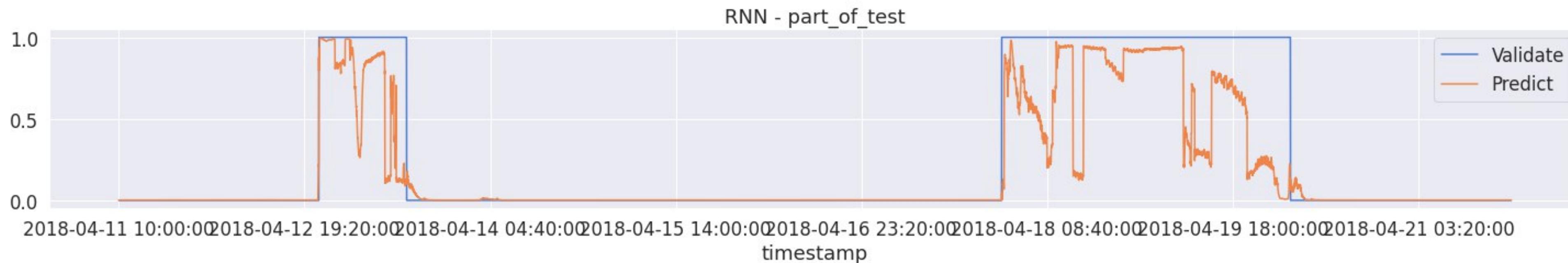
model.compile(loss='binary_crossentropy',
              optimizer='adam')
```

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[None, 1, 49]	0
simple_rnn_5 (SimpleRNN)	(None, 16)	1056
dense_6 (Dense)	(None, 1)	17

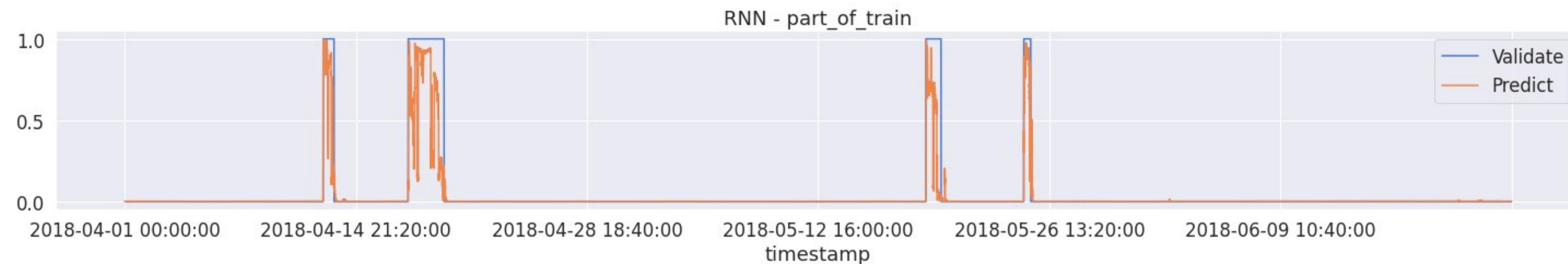
Total params: 1,073
Trainable params: 1,073
Non-trainable params: 0



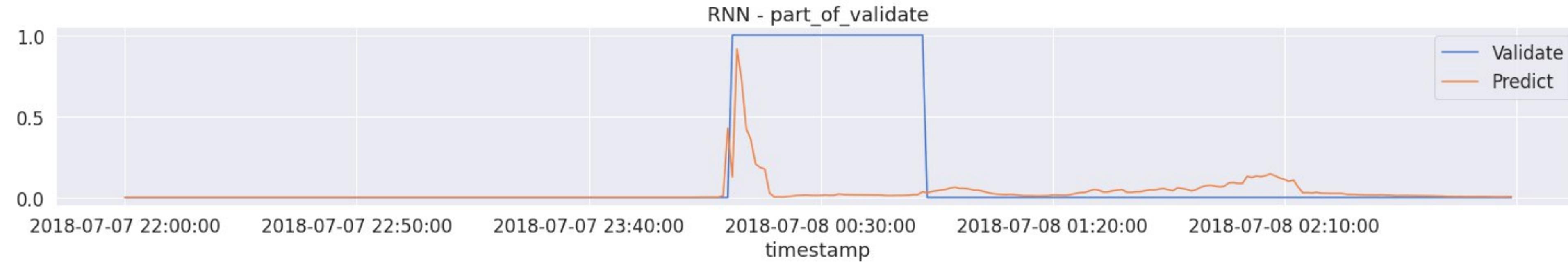
Train



Validate



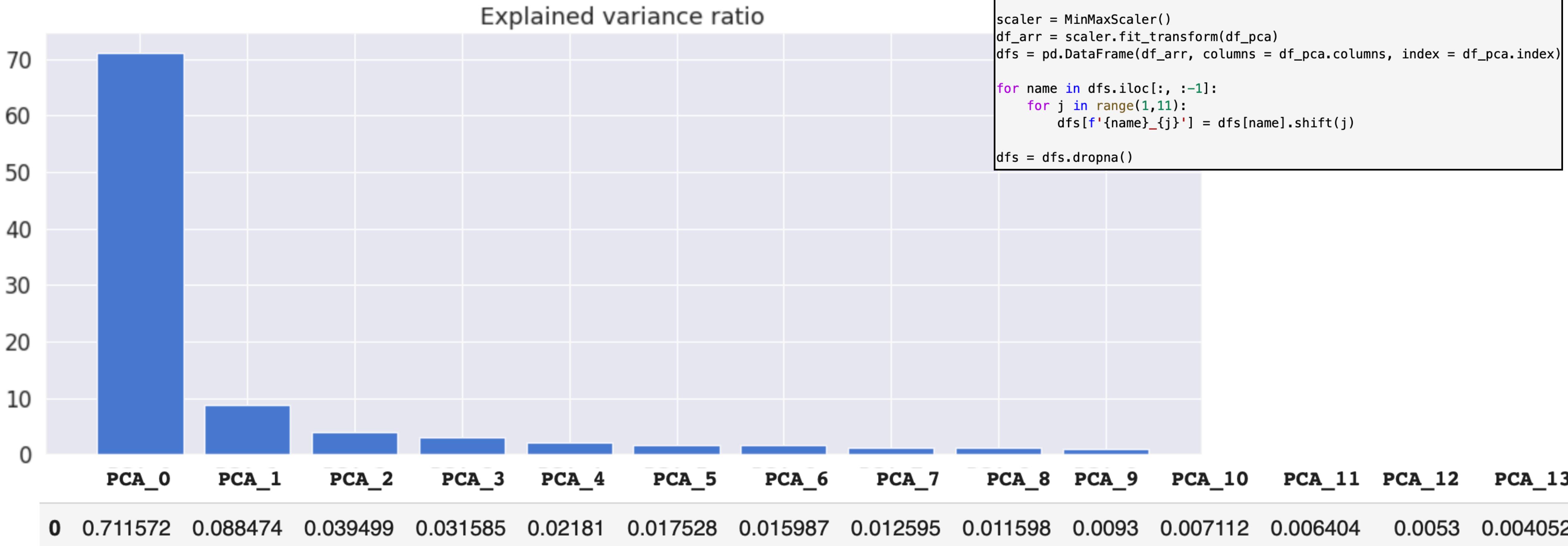
Test



Разложение PCA

```
from sklearn.decomposition import PCA
pca_transformer = PCA()
X2 = pca_transformer.fit_transform(df)

df_pca = pd.DataFrame(X2, columns = [f'PCA_{i}' for i in range(51)], index = df.index)
```



Итоговые признаки

```
df_pca = df_pca.iloc[:, :-1]
df_pca['machine_status'] = df['machine_status']

from sklearn.preprocessing import MinMaxScaler

scaler = MinMaxScaler()
df_arr = scaler.fit_transform(df_pca)
dfs = pd.DataFrame(df_arr, columns = df_pca.columns, index = df_pca.index)

for name in dfs.iloc[:, :-1]:
    for j in range(1, 11):
        dfs[f'{name}_{j}'] = dfs[name].shift(j)

dfs = dfs.dropna()
```

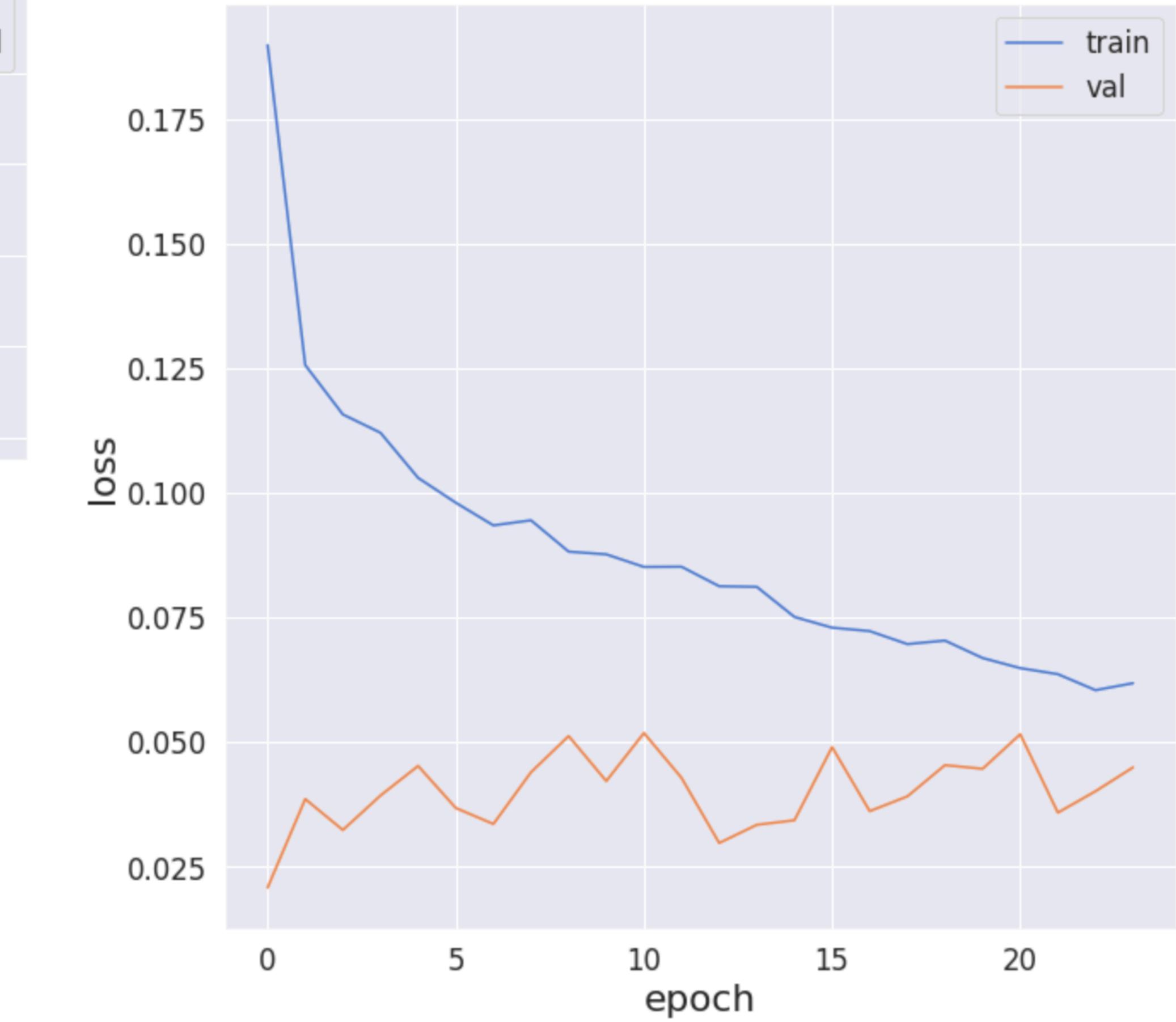
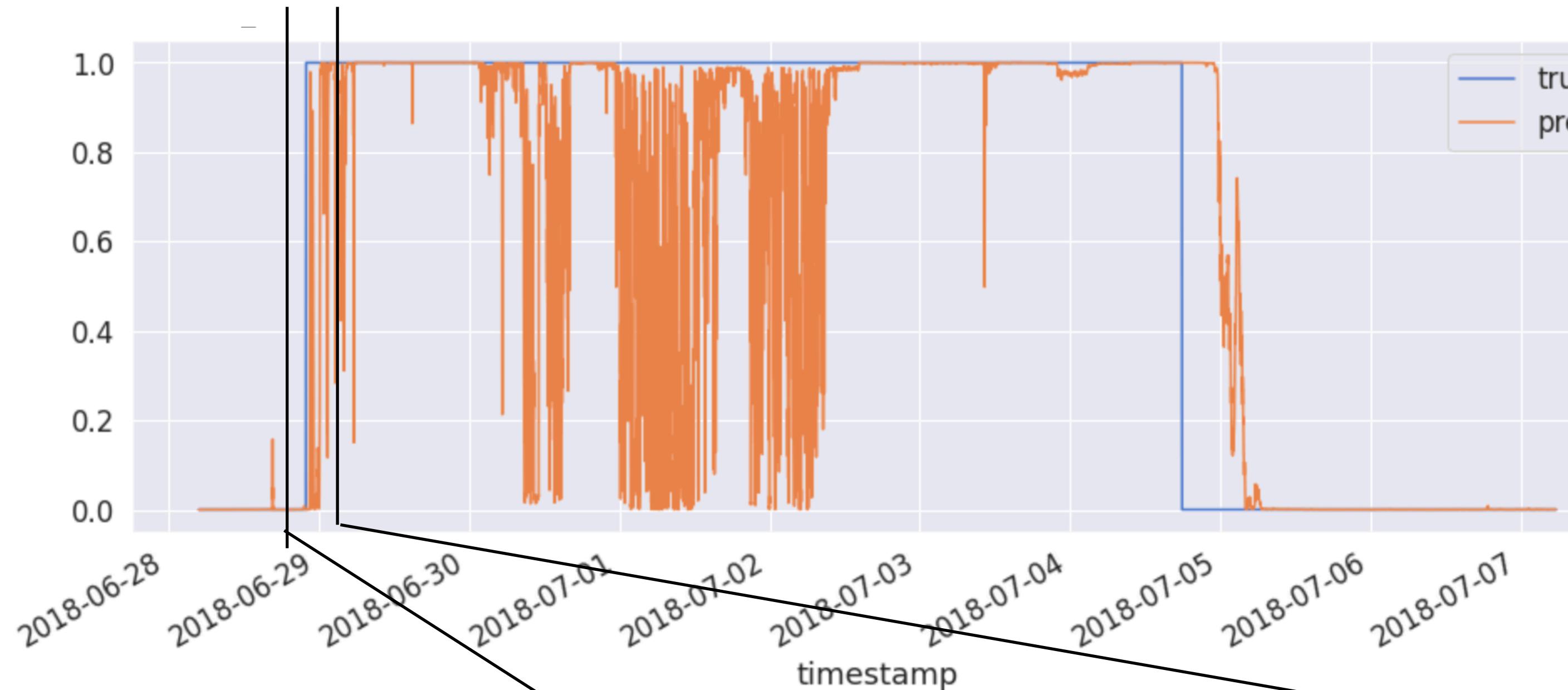
Обучение Transformer

```
model = build_model(  
    input_shape,  
    head_size=32,  
    num_heads=4,  
    ff_dim=4,  
    num_transformer_blocks=1, ←  
    mlp_units=[128],  
    mlp_dropout=0.4,  
    dropout=0.25,  
)  
  
model.compile(  
    loss="sparse_categorical_crossentropy",  
    optimizer=keras.optimizers.Adam(learning_rate=1e-3),  
    metrics=["sparse_categorical_accuracy"],  
)  
model.summary()  
  
history = model.fit(  
    x_train,  
    y_train,  
    validation_split=0.2,  
    epochs=10,  
    batch_size=256,  
    class_weight=class_weight ←  
)
```

Layer (type)	Output Shape	Param #	Connected to
input_3 (InputLayer)	[None, 110, 1]	0	[]
multi_head_attention_2 (MultiHeadAttention)	(None, 110, 1)	897	['input_3[0][0]', 'input_3[0][0]']
dropout_6 (Dropout)	(None, 110, 1)	0	['multi_head_attention_2[0][0]']
tf.__operators__.add_4 (TFOpLabda)	(None, 110, 1)	0	['dropout_6[0][0]', 'input_3[0][0]']
conv1d_4 (Conv1D)	(None, 110, 4)	8	['tf.__operators__.add_4[0][0]']
dropout_7 (Dropout)	(None, 110, 4)	0	['conv1d_4[0][0]']
conv1d_5 (Conv1D)	(None, 110, 1)	5	['dropout_7[0][0]']
layer_normalization_5 (LayerNormalization)	(None, 110, 1)	2	['conv1d_5[0][0]']
tf.__operators__.add_5 (TFOpLabda)	(None, 110, 1)	0	['layer_normalization_5[0][0]', 'tf.__operators__.add_4[0][0]']
global_average_pooling1d_2 (GlobalAveragePooling1D)	(None, 110)	0	['tf.__operators__.add_5[0][0]']
dense_4 (Dense)	(None, 64)	7104	['global_average_pooling1d_2[0][0]']
dropout_8 (Dropout)	(None, 64)	0	['dense_4[0][0]']
dense_5 (Dense)	(None, 2)	130	['dropout_8[0][0]']

Total params: 8,146

Предсказание Transformer



Обучение LSTM

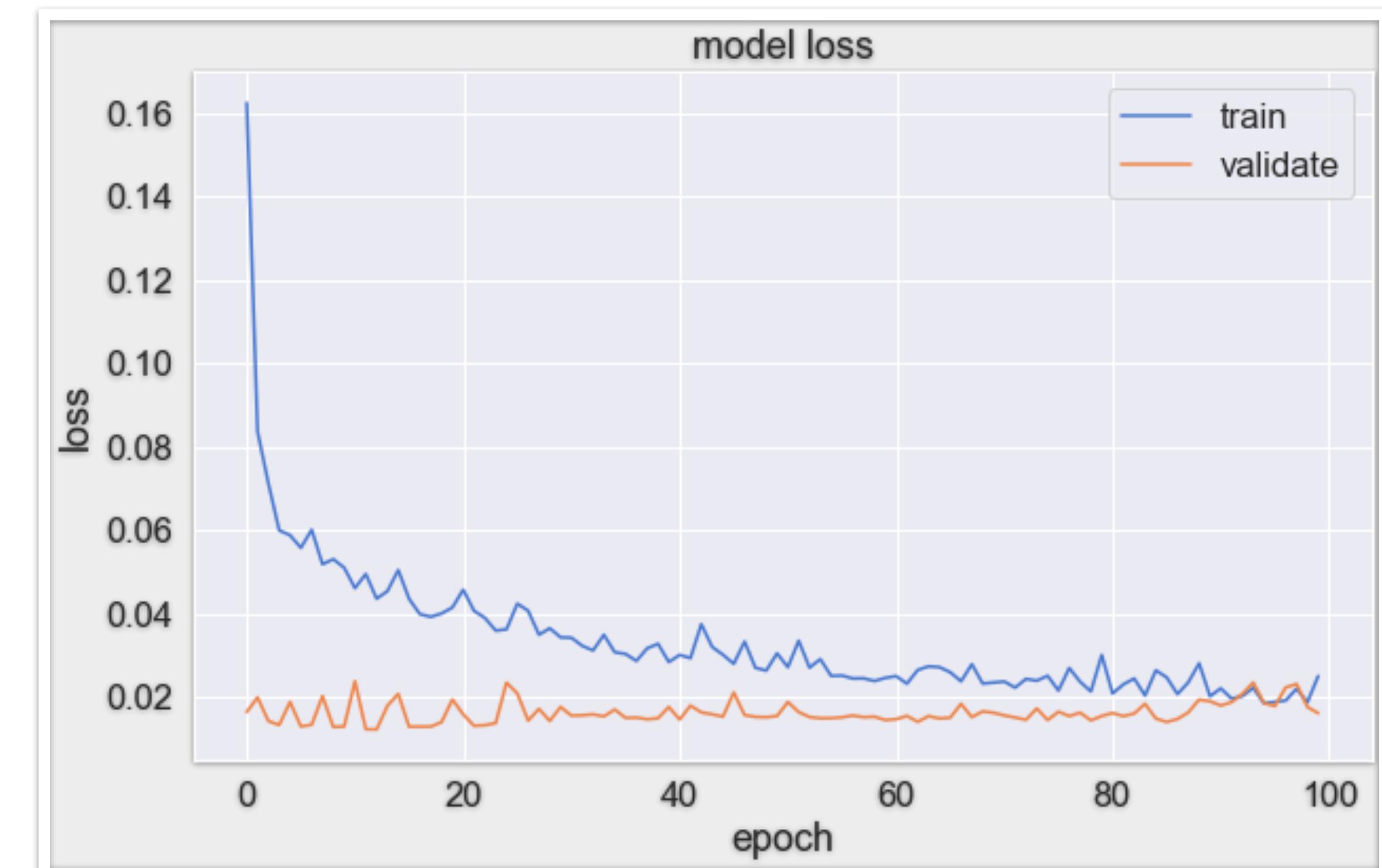
Описание модели:

```
inputs= tf.keras.Input(shape=(in_shape[1], in_shape[2]))  
x = LSTM(50, activation='relu', input_shape=(in_shape[1], in_shape[2]), return_sequences=True)(inputs)  
x = LSTM(50, activation='relu')(x)  
out = Dense(1, activation='sigmoid')(x)  
  
model = tf.keras.Model(inputs=inputs, outputs=out)  
  
model.compile(loss='binary_crossentropy', optimizer='adam')
```

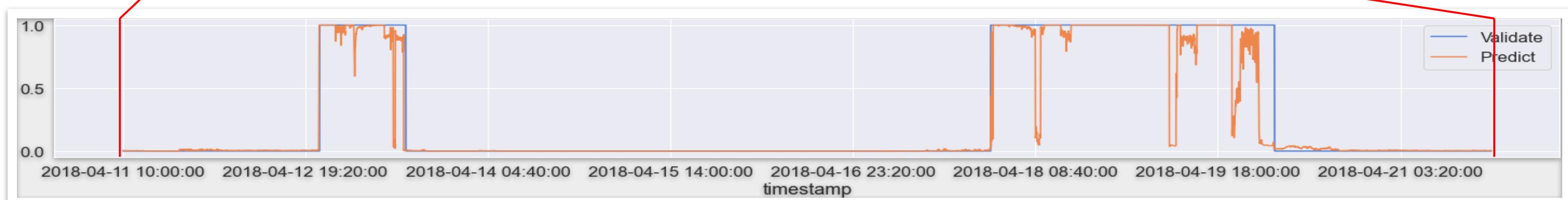
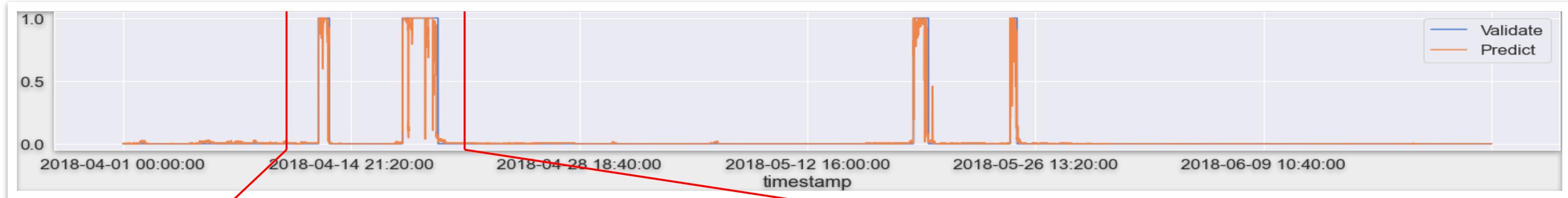
Обучение модели:

```
model.fit(X_train, y_train, epochs=100, batch_size=32, validation_data=(X_valid, y_valid), shuffle=False)
```

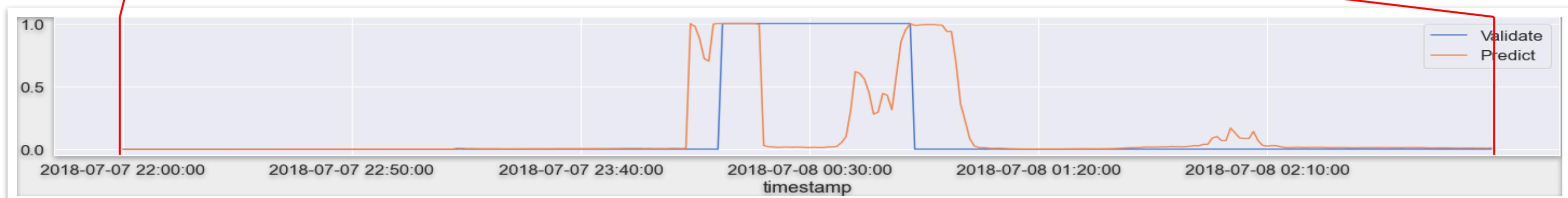
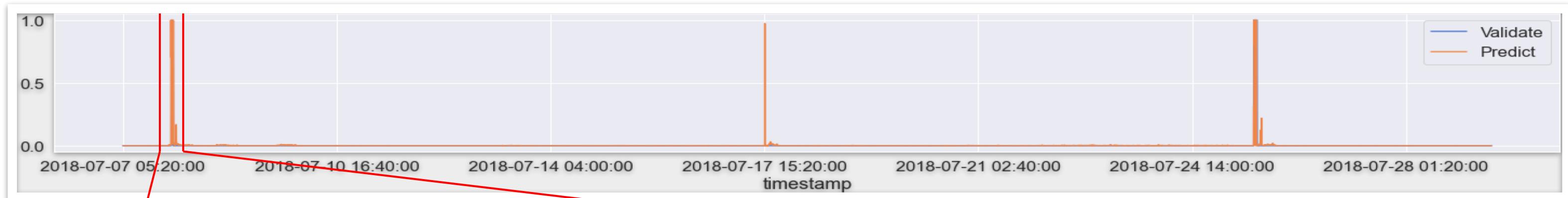
Layer (type)	Output Shape	Param #
=====		
input_1 (InputLayer)	[None, 1, 49]	0
lstm (LSTM)	(None, 1, 50)	20000
lstm_1 (LSTM)	(None, 50)	20200
dense (Dense)	(None, 1)	51
=====		
Total params:	40,251	
Trainable params:	40,251	
Non-trainable params:	0	



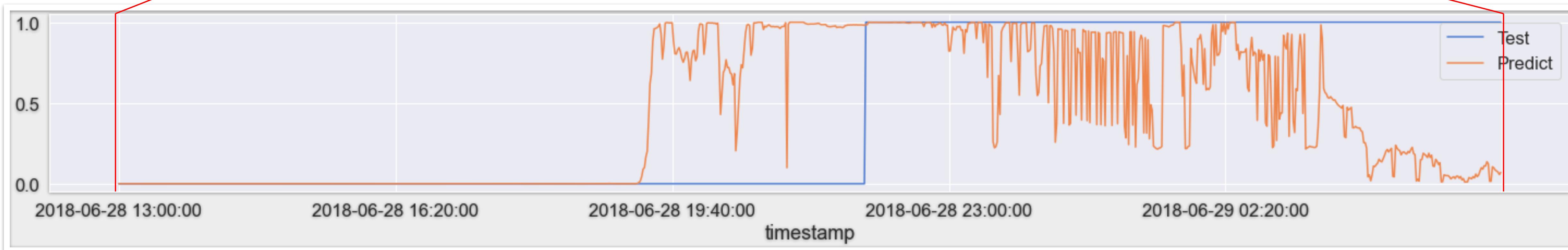
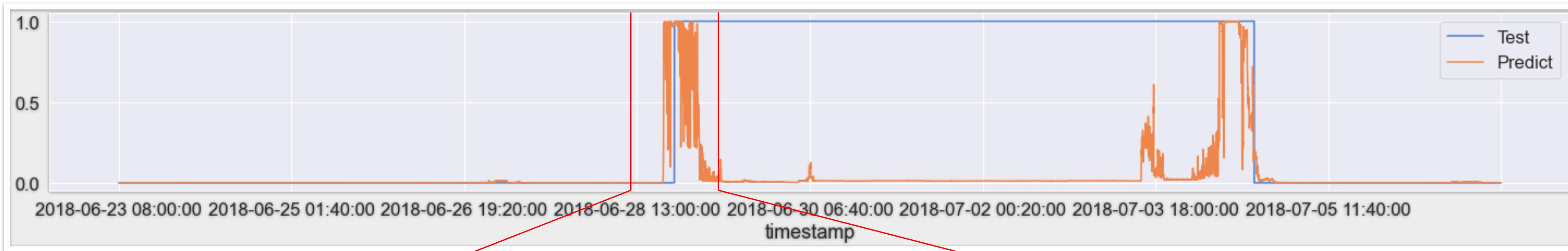
Train



Validate



Предсказание LSTM



Заключение

1. Архитектура сети LSTM показала наилучший результат
2. Сдвиг таргета позволяет предсказать поломку насоса заранее (3 часа)
3. Время обучения LSTM(100 эпох) составило 11 минут.