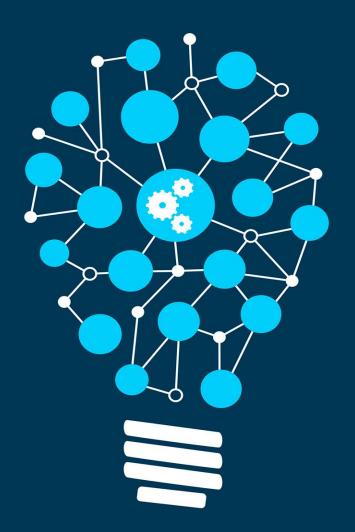


人工智能技术及应用

Artificial Intelligence and Application

Classification



Classification



- Credit Scoring
 - Input: income, savings, profession, age, past financial history
 - Output: accept or refuse
- Medical Diagnosis
 - Input: current symptoms, age, gender, past medical history
 - Output: which kind of diseases
- Handwritten character recognition

Input:



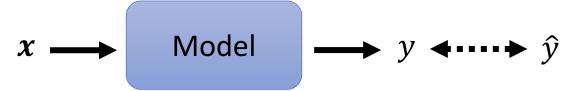
output:



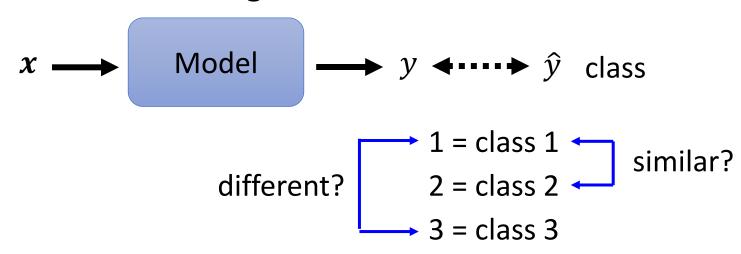
- Face recognition
 - Input: image of a face, output: person

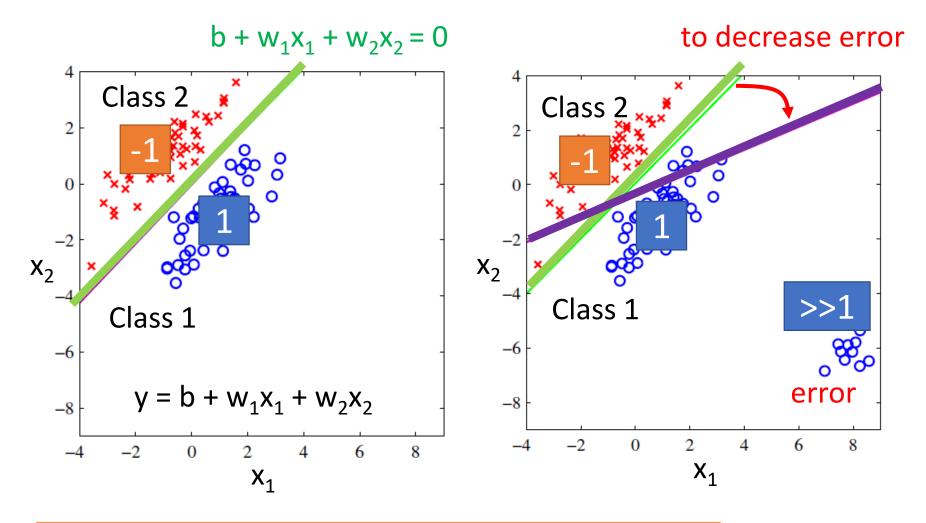
Classification as Regression?

Regression



Classification as regression?





Penalize to the examples that are "too correct" ... (Bishop, P186)

 Multiple class: Class 1 means the target is 1; Class 2 means the target is 2; Class 3 means the target is 3 problematic

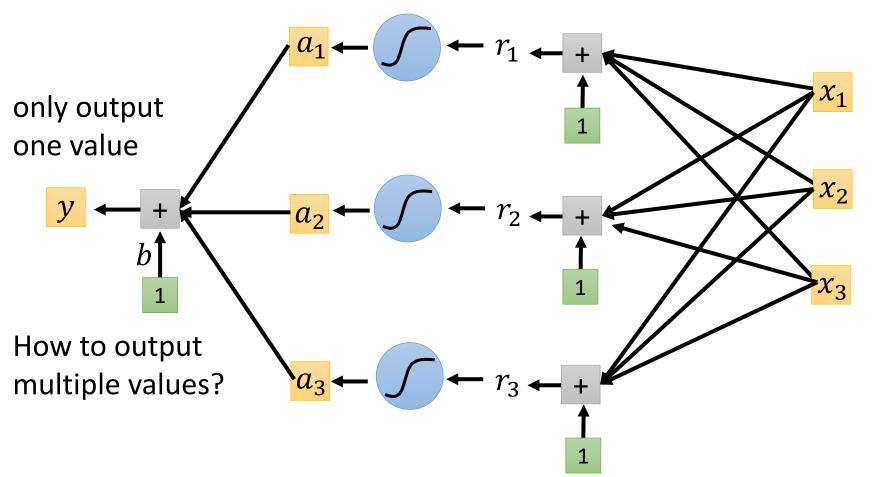
Class as one-hot vector

Class 1

Class 2

Class 3

$$\widehat{y} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$
 or $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ or $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$



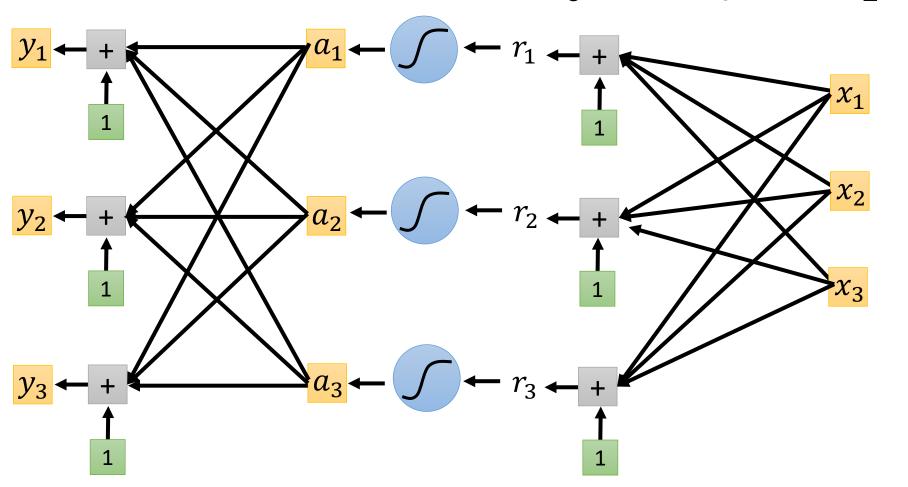
Class as one-hot vector

Class 1

Class 2

Class 3

$$\widehat{y} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$
 or $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ or $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$



Regression

feature

label

$$\hat{y} \longleftrightarrow y = b + c^T \sigma(b + W x)$$

Classification

feature

$$y = b' + W' \sigma(b + W x)$$

label $\hat{y} \leftarrow \psi' = softmax(y)$

O or 1 Make all values Can have

between 0 and 1

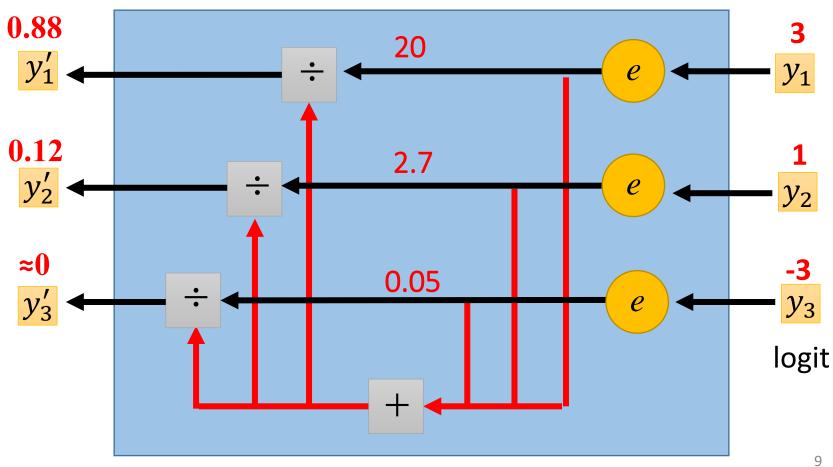
8

any value

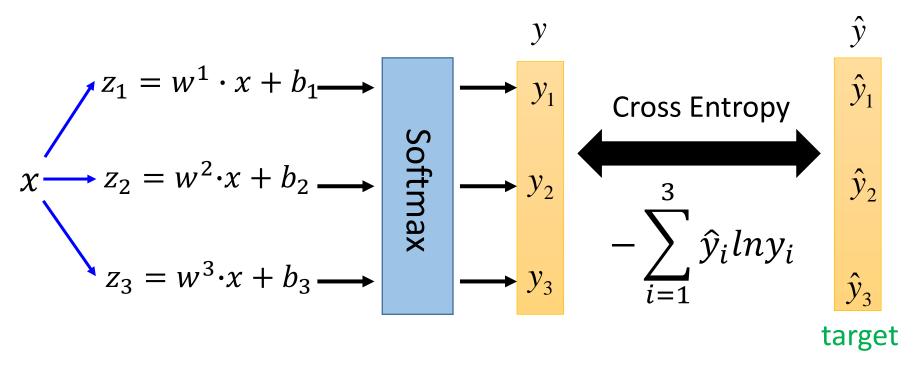
$$y_i' = \frac{exp(y_i)}{\sum_j exp(y_i)} \quad = \begin{array}{l} 1 > y_i' > 0 \\ \sum_i y_i' = 1 \end{array}$$

Softmax

How about **binary classification**? ©



Multi-class Classification (3 classes as example)



If $x \in class 1$

$$\hat{y} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

If $x \in class 2$

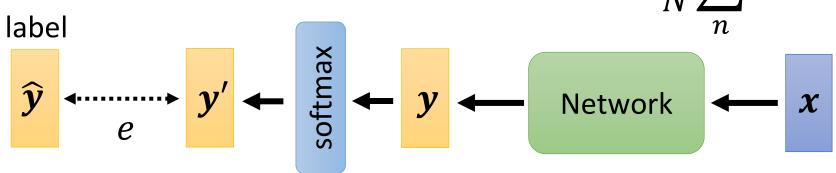
$$\hat{y} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

If $x \in class 3$

$$\hat{y} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Loss of Classification

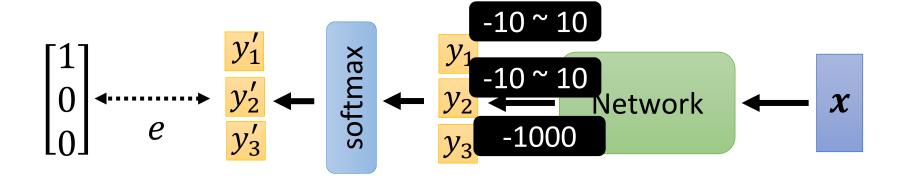
$$L = \frac{1}{N} \sum_{n} e_n$$

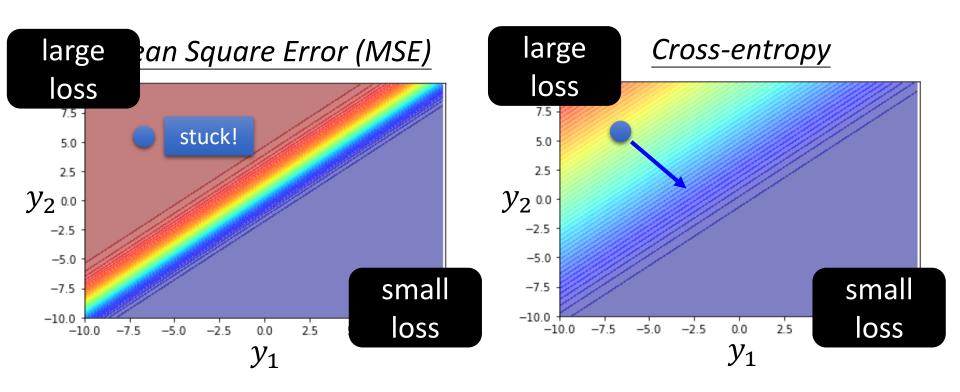


Mean Square Error (MSE)
$$e = \sum_{i} (\widehat{y}_i - y_i')^2$$

$$\frac{\textit{Cross-entropy}}{e} = -\sum_{i} \widehat{y}_{i} ln y_{i}'$$

Minimizing cross-entropy is equivalent to maximizing likelihood.



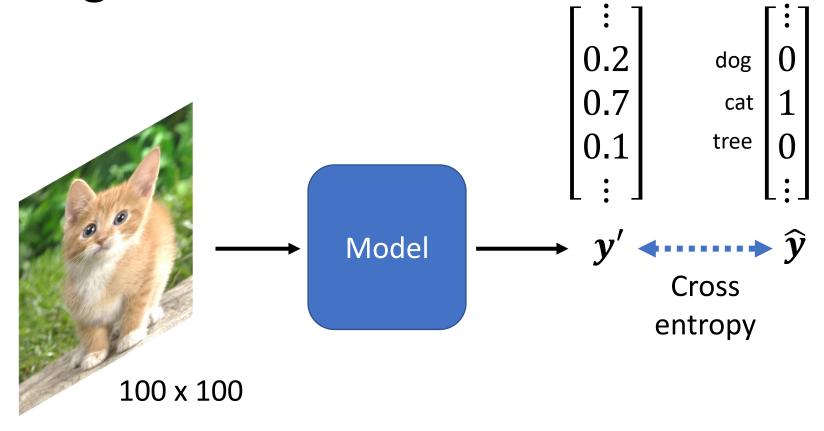


Changing the loss function can change the difficulty of optimization.

Convolutional Neural Network (CNN)

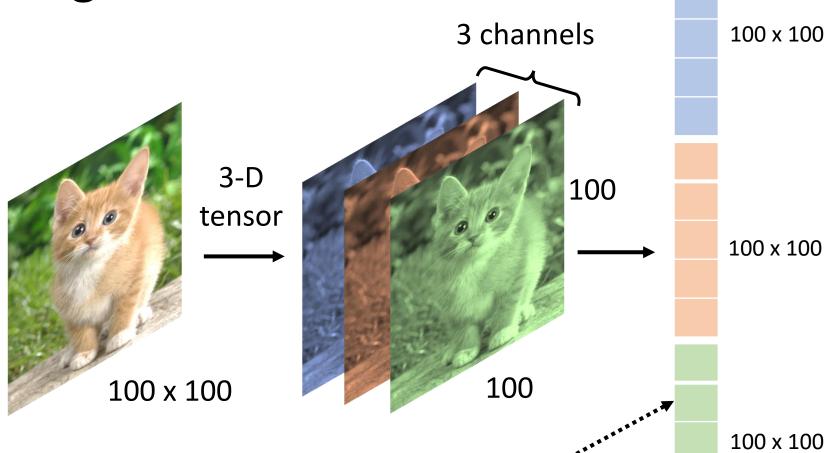


Image Classification



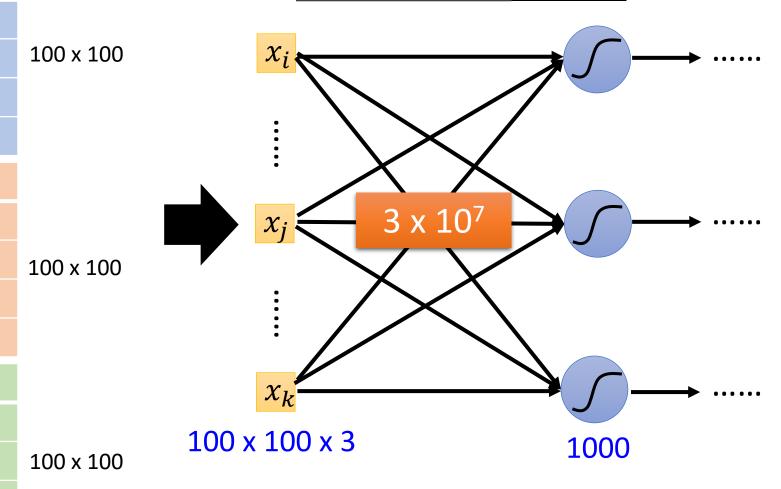
(All the images to be classified have the same size.)

Image Classification



value represents intensity

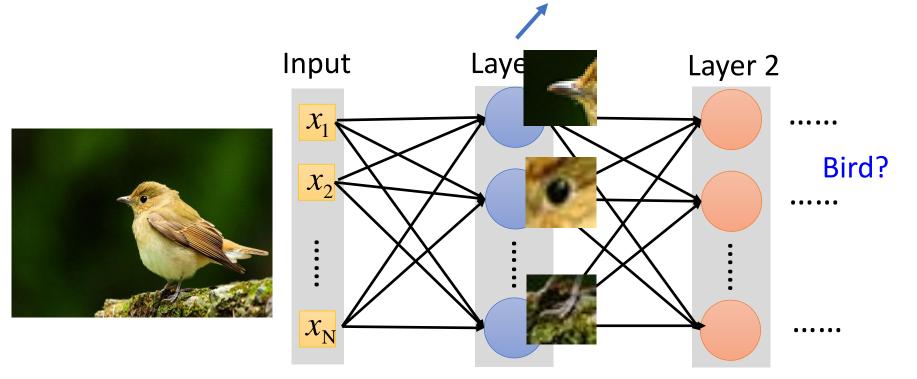
Fully Connected Network



Do we really need "fully connected" in image processing?

Observation 1

Identifying some critical patterns

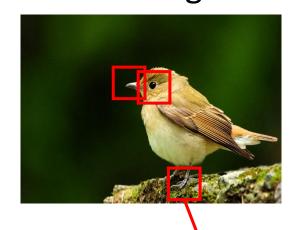


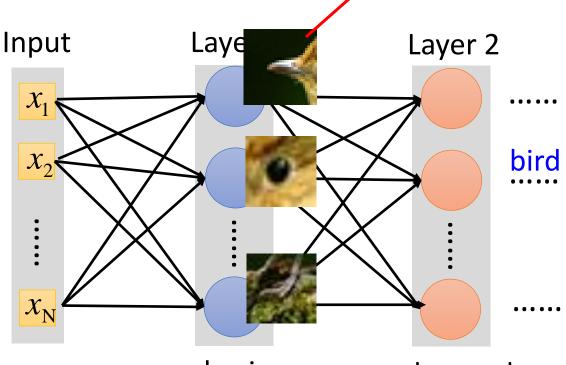
Perhaps human also identify birds in a similar way ... ©

Observation 1

A neuron does not have to see the whole image.

Need to see the whole image?



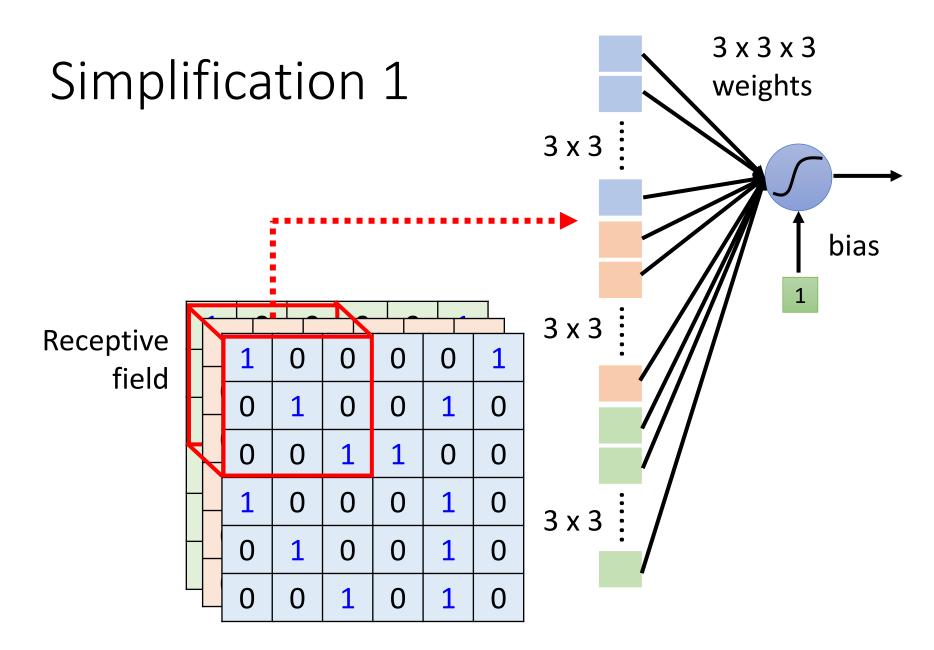


basic detector

advanced detector

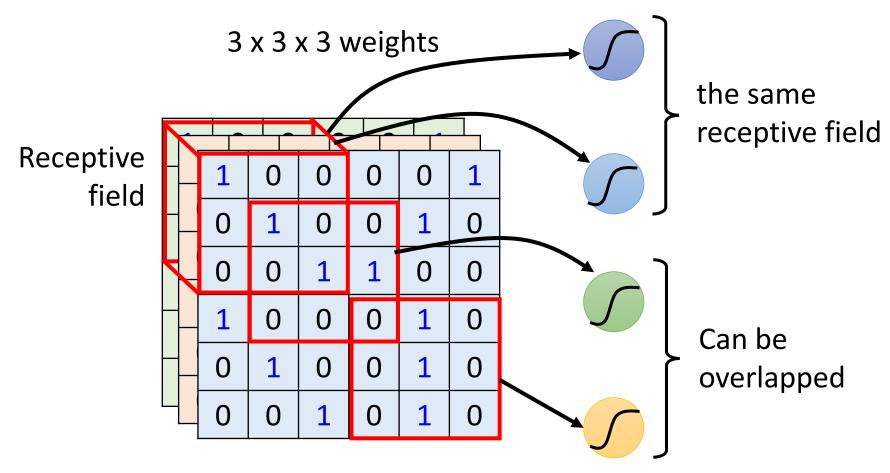
Some patterns are much smaller than the whole image.

Connecting to small region with less parameters



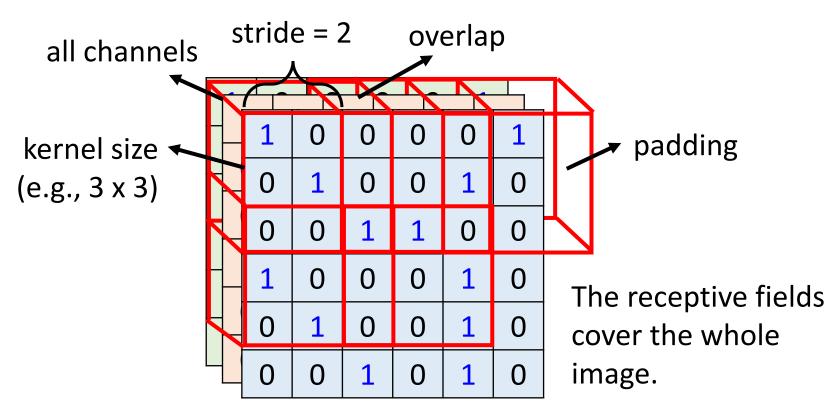
Simplification 1

- Can different neurons have different sizes of receptive field?
- Cover only some channels?
- Not square receptive field?



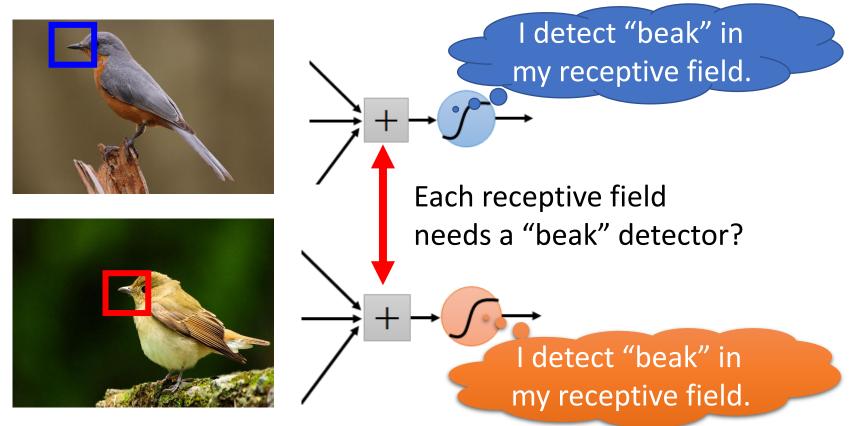
Simplification 1 – Typical Setting

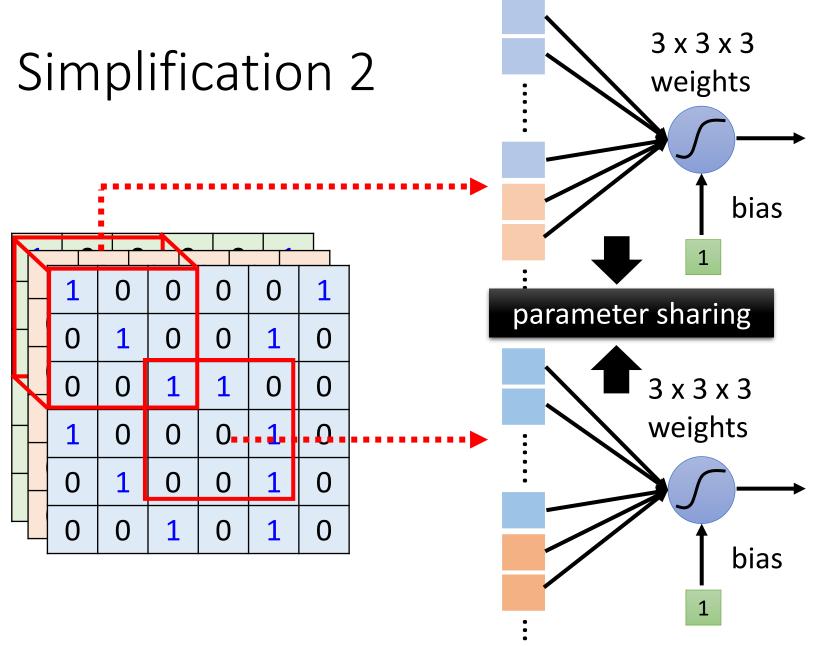
Each receptive field has a set of neurons (e.g., 64 neurons).

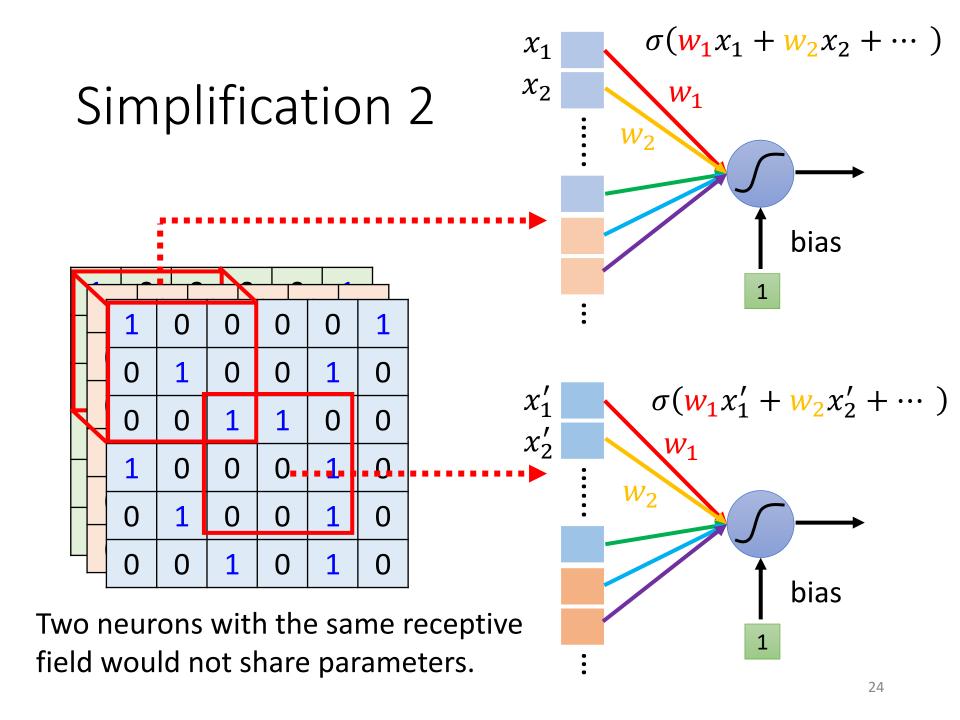


Observation 2

The same patterns appear in different regions.

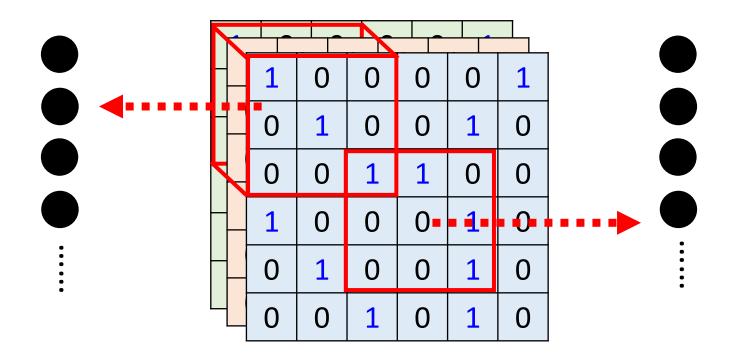






Simplification 2 – Typical Setting

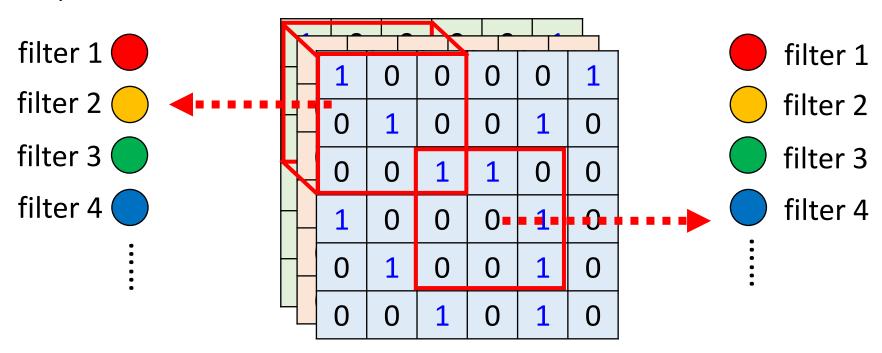
Each receptive field has a set of neurons (e.g., 64 neurons).



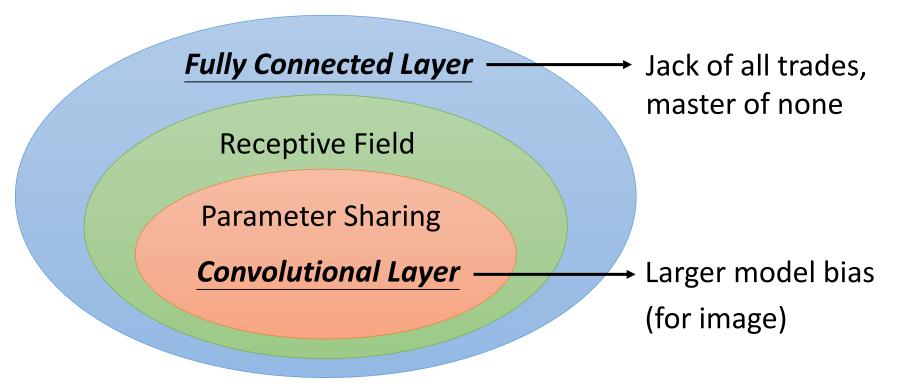
Simplification 2 – Typical Setting

Each receptive field has a set of neurons (e.g., 64 neurons).

Each receptive field has the neurons with the same set of parameters.



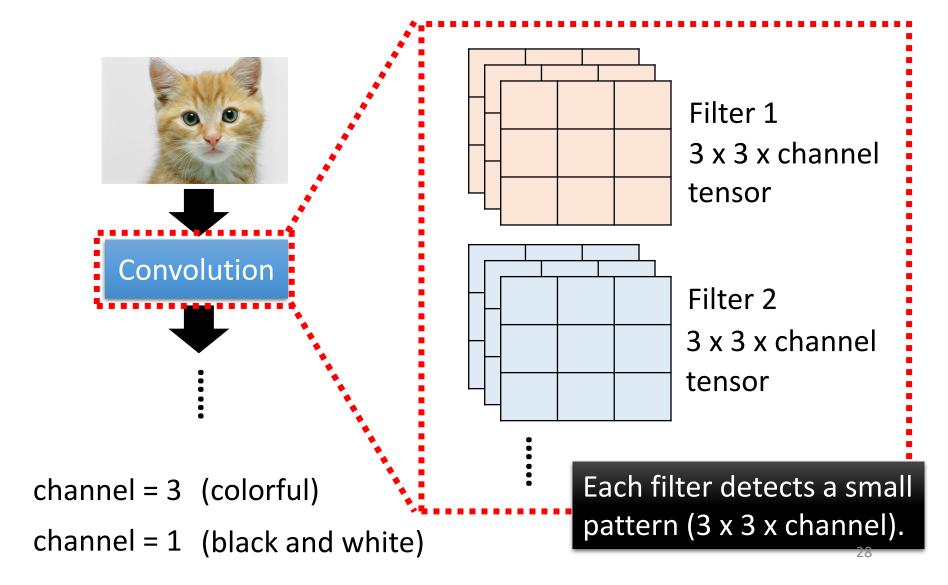
Benefit of Convolutional Layer



- Some patterns are much smaller than the whole image.
- The same patterns appear in different regions.

Another story based on *filter* ©

Convolutional Layer



CNN – Convolution

Those are the network parameters to be learned.

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1
Matrix

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2
Matrix



Each filter detects a small pattern (3 x 3).

Property 1

CNN – Convolution

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

3 (-1

6 x 6 image

CNN – Convolution

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

If stride=2

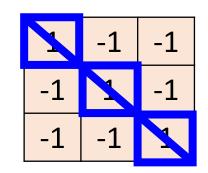
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

3 -3

6 x 6 image

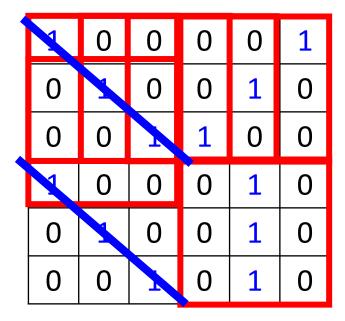
We set stride=1 below

CNN — Convolution

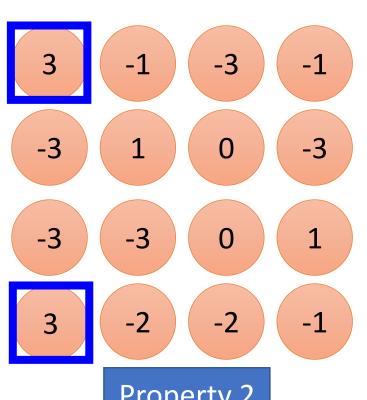


Filter 1

stride=1



6 x 6 image



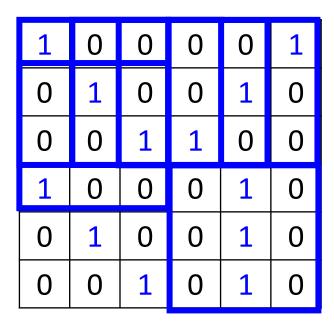
Property 2

Convolutional Layer

-1	1	-1
-1	1	-1
-1	1	-1

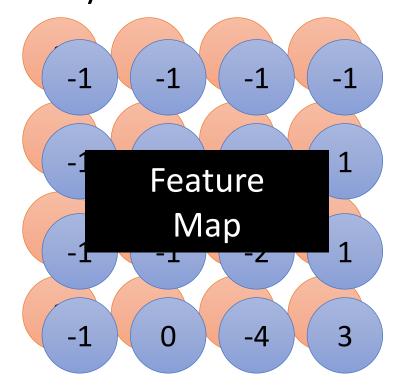
Filter 2

stride=1

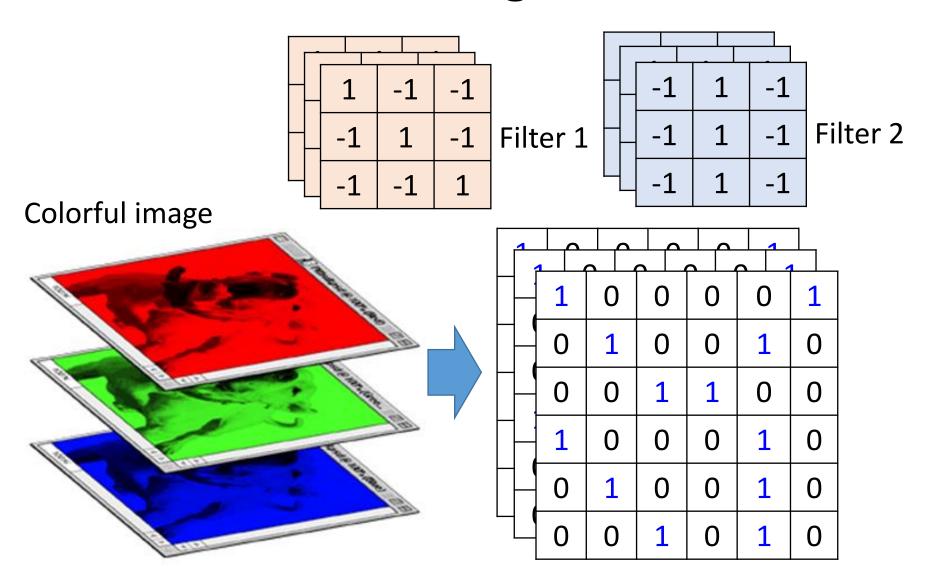


6 x 6 image

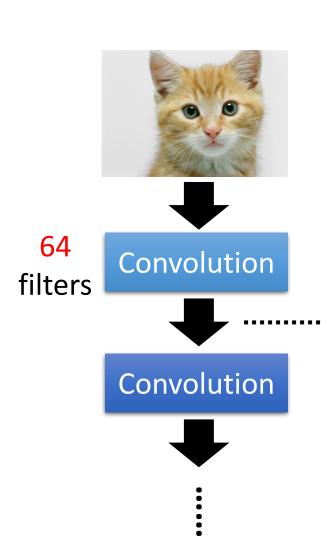
Do the same process for every filter

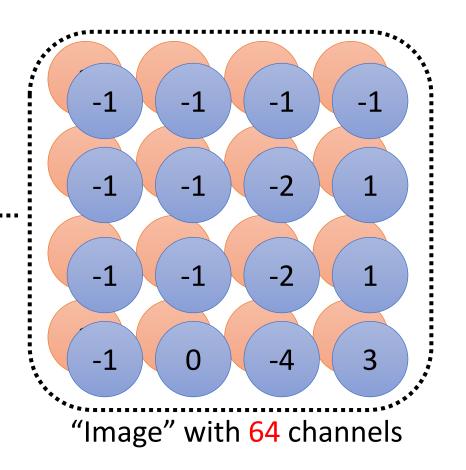


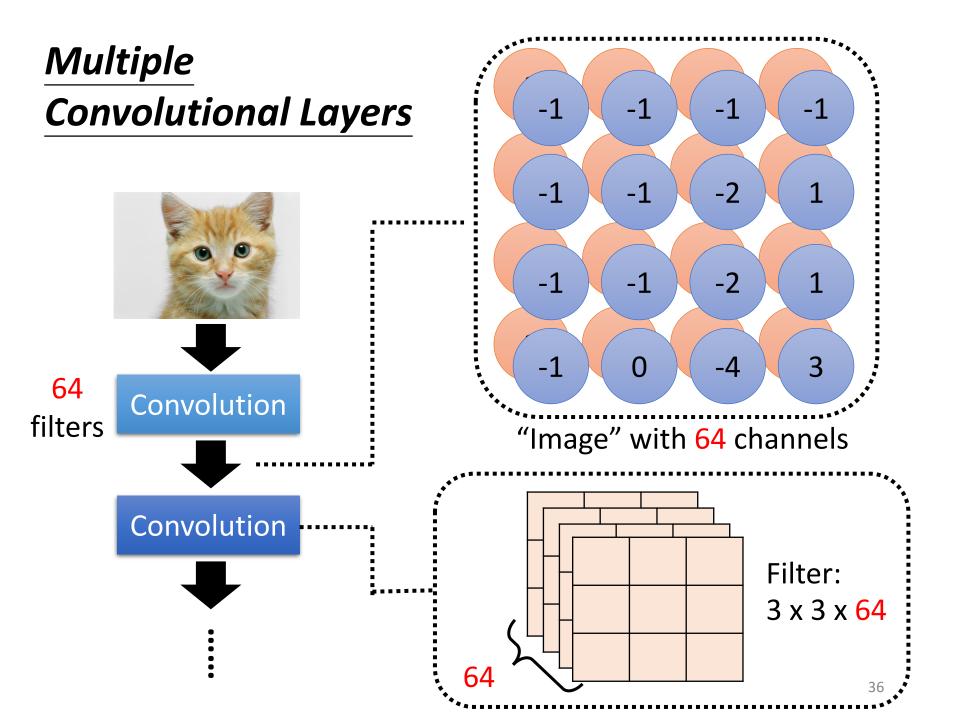
CNN – Colorful image



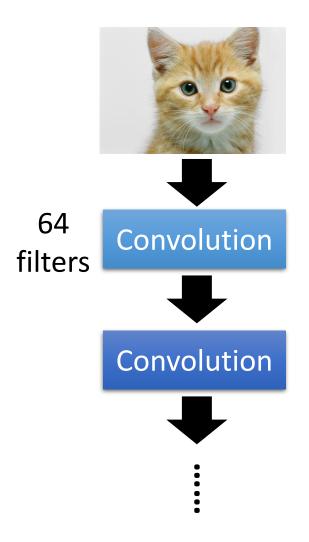
Convolutional Layer



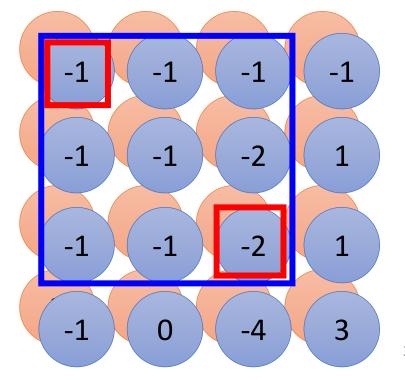




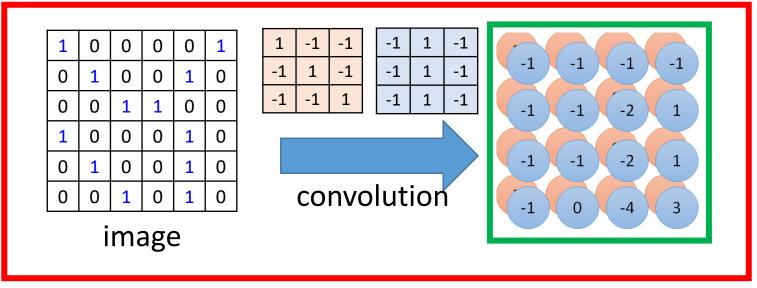
Multiple Convolutional Layers



1	0	0	0	0	1	
0	1	0	0	1	0	
0	0	1	1	0	0	
1	0	0	0	1	0	
0	1	0	0	1	0	
0	0	1	0	1	0	

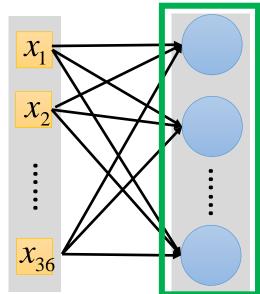


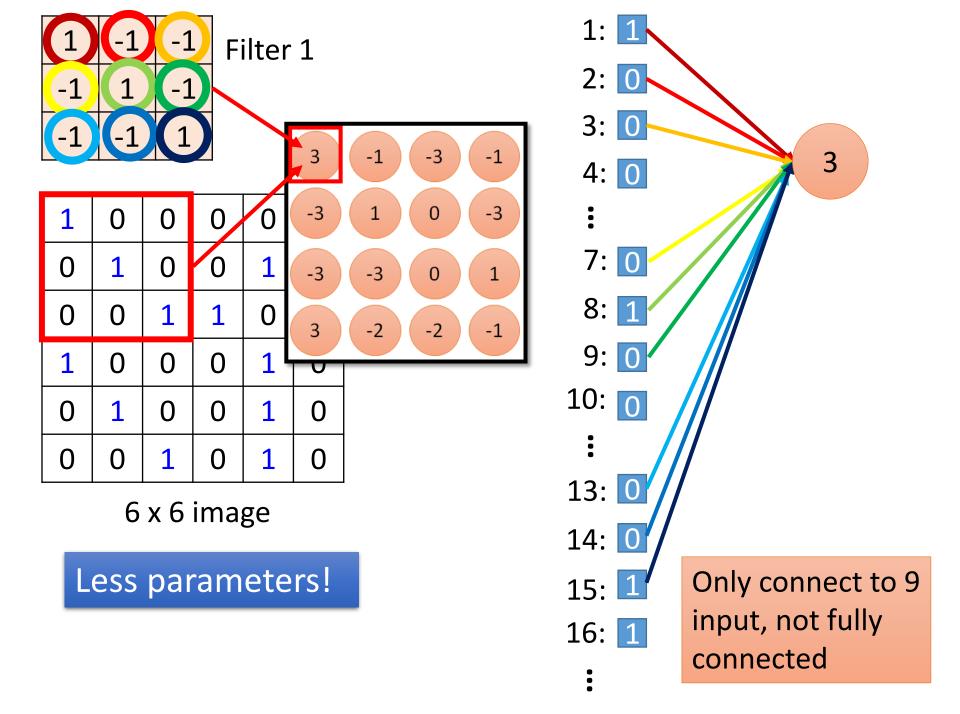
Convolution v.s. Fully Connected

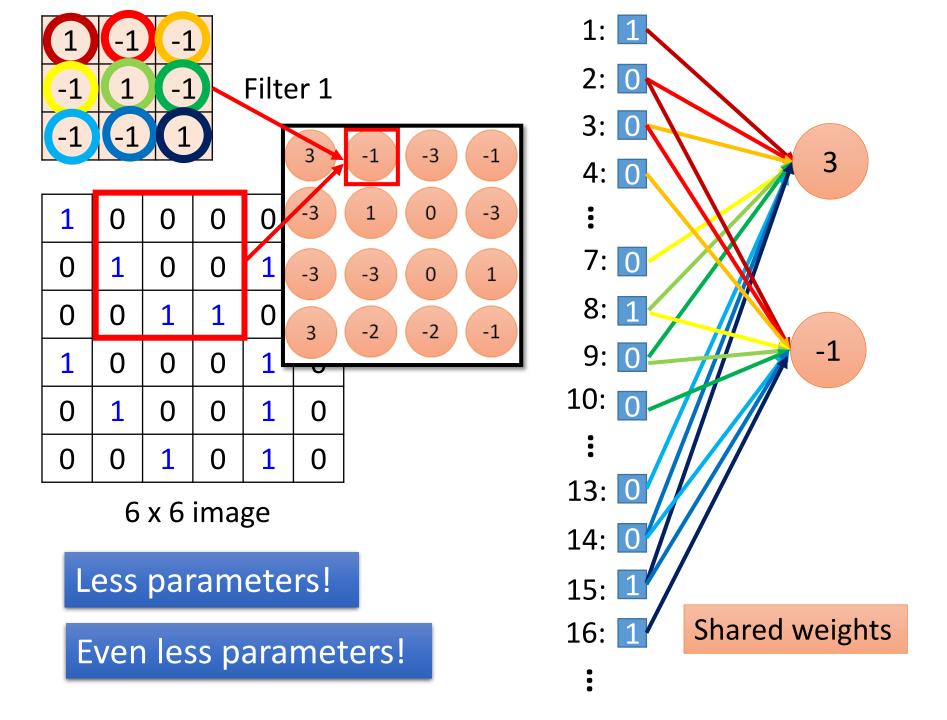


Fullyconnected

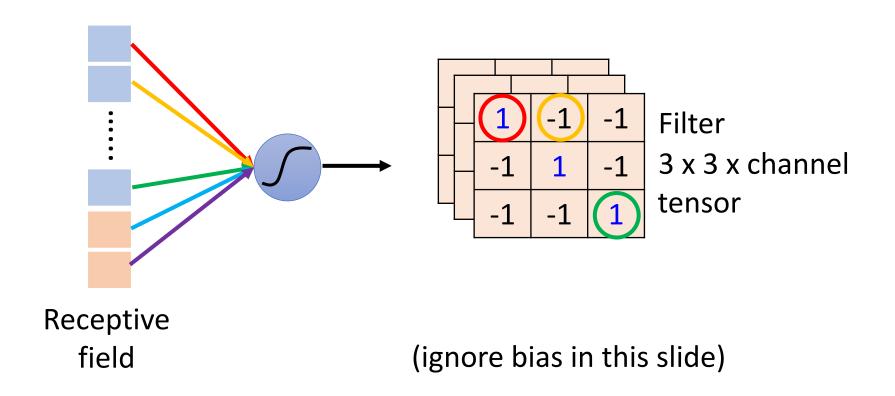
1	0	0	0	0	1	
0	1	0	0	1	0	
0	0	1	1	0	0	
1	0	0	0	1	0	
0	1	0	0	1	0	
0	0	1	0	1	0	



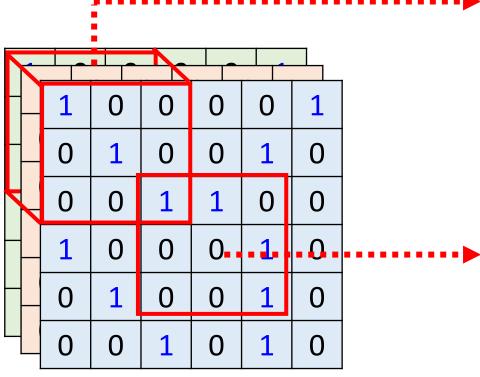




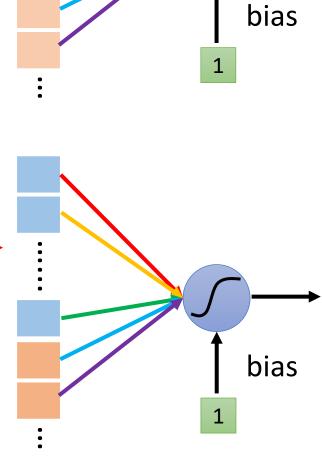
Comparison of Two Stories



The neurons with different receptive fields **share the parameters**.



Each filter convolves over the input image.



Convolutional Layer

Neuron Version Story	Filter Version Story
Each neuron only considers a receptive field.	There are a set of filters detecting small patterns.
The neurons with different receptive fields share the parameters.	Each filter convolves over the input image.

They are the same story.

Observation 3

Subsampling the pixels will not change the object

bird



We can subsample the pixels to make image smaller

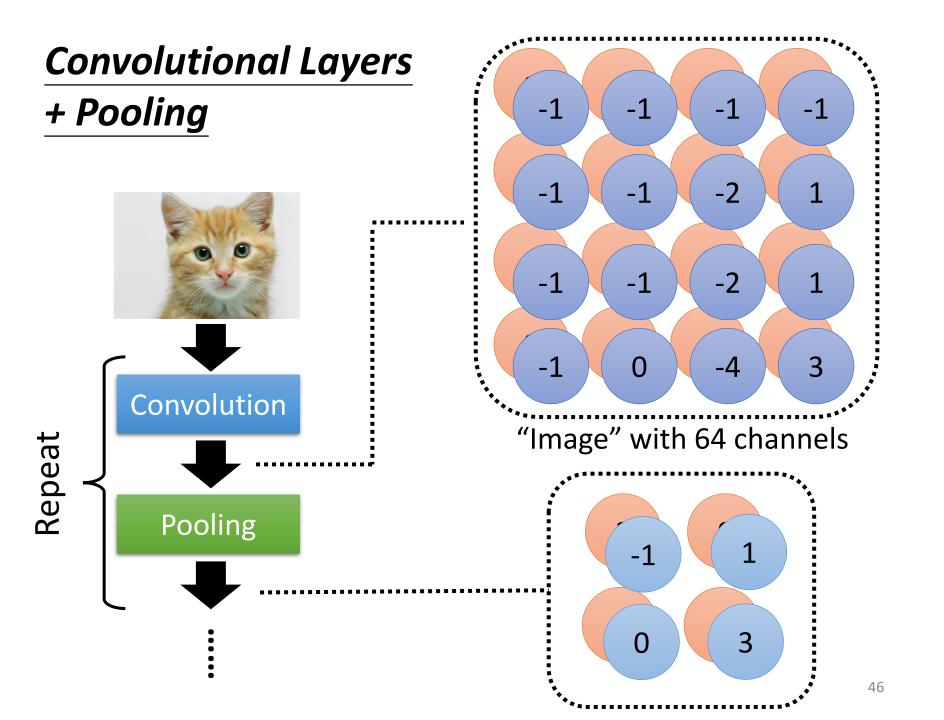


Less parameters for the network to process the image

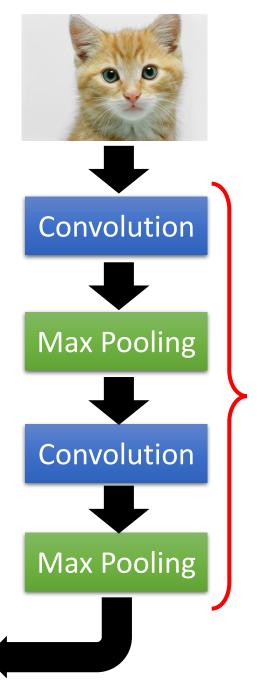
Pooling – Max Pooling

	1	-1	-1			-1	1	-1
	-1	1	-1	Filter 1		-1	1	-1
	-1	-1	1			-1	1	-1
3	-1		-3	-1	-1	-	1	-1
-3	1		0	-3	-1	-	1	-2
-3	-3		0	1	-1	-	1	-2
3	-2		-2	-1	-1)	-4

Filter 2



cat dog softmax **Fully Connected** Feedforward network Flatten



Can repeat many times

Property 1

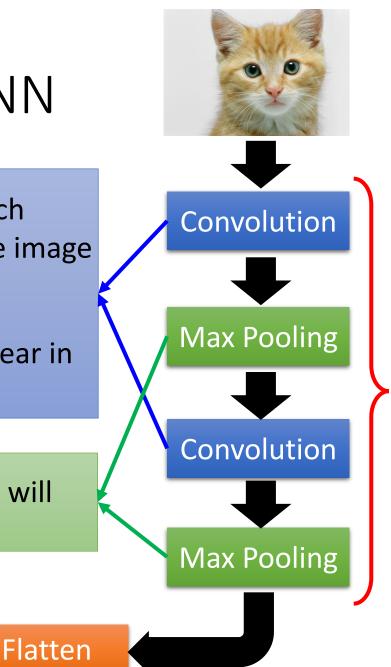
Some patterns are much smaller than the whole image

Property 2

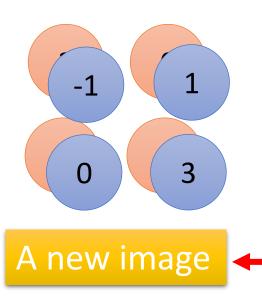
The same patterns appear in different regions.

Property 3

Subsampling the pixels will not change the object

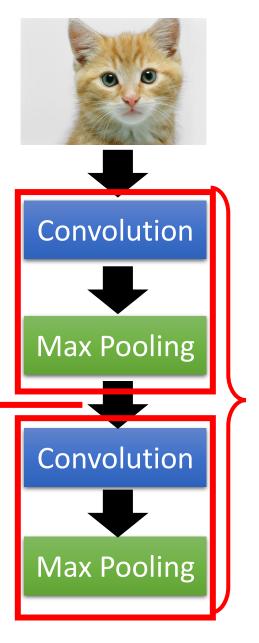


Can repeat many times



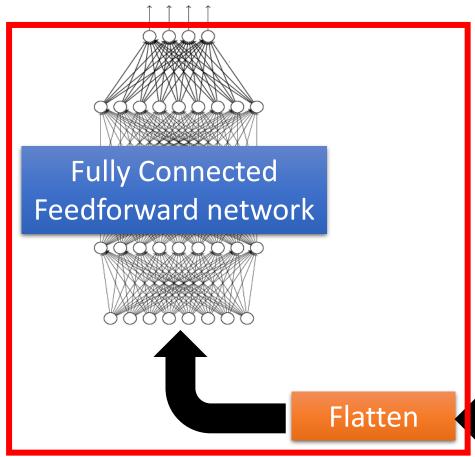
Smaller than the original image

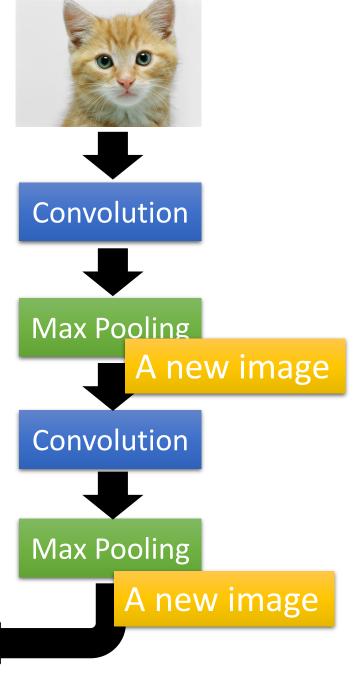
The number of the channel is the number of filters

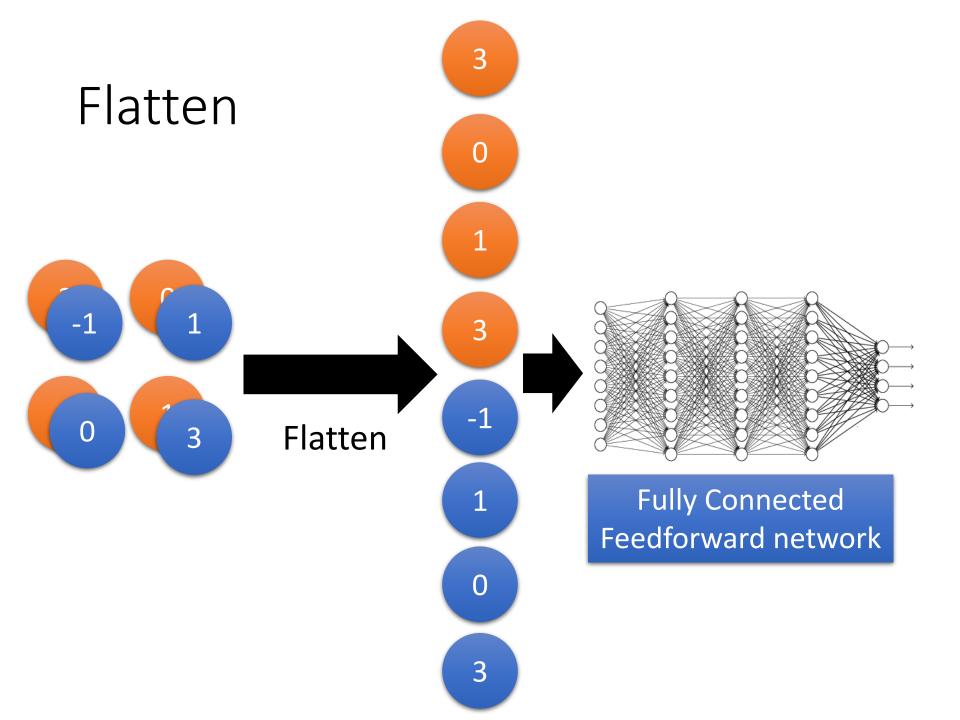


Can repeat many times

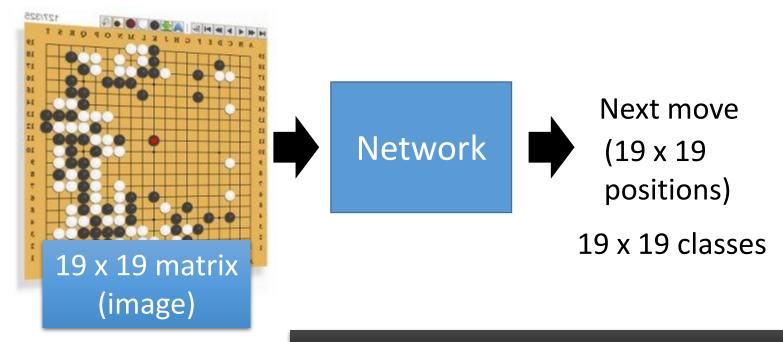
cat dog







Application: Playing Go



48 channels in Alpha Go

Black: 1

white: -1

none: 0

Fully-connected network can be used

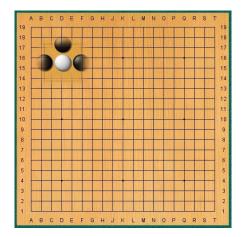
But CNN performs much better.

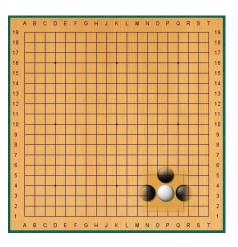
Why CNN for Go playing?

Some patterns are much smaller than the whole image

Alpha Go uses 5 x 5 for first layer

The same patterns appear in different regions.





Why CNN for Go playing?

Subsampling the pixels will not change the object



Pooling

How to explain this???

Neural network architecture. The input to the policy network is a $19 \times 19 \times 48$ image stack consisting of 48 feature planes. The first hidden layer zero pads the input into a 23 \times 23 image, then convolves k filters of kernel size 5 \times 5 with stride 1 with the input image and applies a rectifier nonlinearity. Each of the subsequent hidden layers 2 to 12 zero pads the respective previous hidden layer into a 21×21 image, then convolves k filters of kernel size 3×3 with stride 1, again followed by a rectifier nonlinearity. The final layer convolves 1 filter of kernel size 1×1 with stride 1, with a different bias for each position, and applies a softmax function. The match version of AlphaGo used k = 192 filters; Fig. 2b and Extended Data Tabl 256 and

384 filters

Alpha Go does not use Pooling

More Applications

Static, Δ , $\Delta\Delta$ Convolution layer max pooling feature maps other fully feature maps connected hidden layers Frequency bands Frames Share same weights

Speech

https://dl.acm.org/doi/10.110 9/TASLP.2014.2339736

Natural Language Processing

https://www.aclweb.org/anthology/S15-2079/

