

A Sudoku Solver

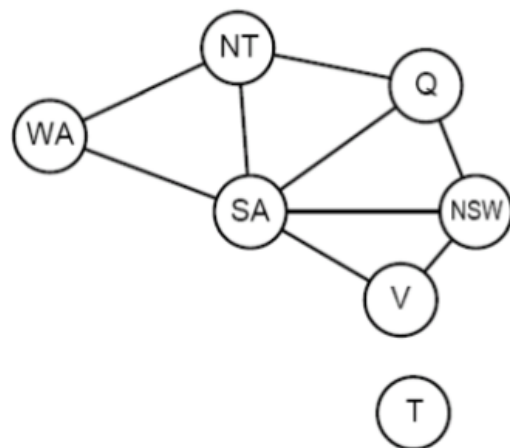
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Outline

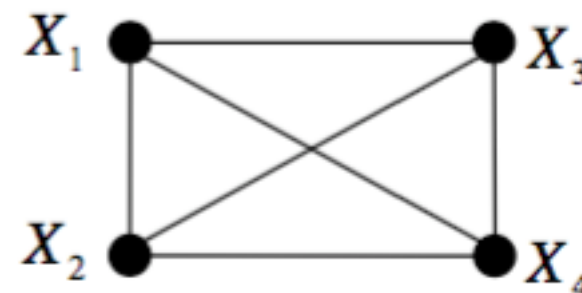
- CSP(Constrained Satisfaction Problem)
- Sudoku problem
- Existing solutions and adopted method
- Performance and future improvement

Constrained Satisfaction Problem

- **State:** defined by variable, with value from domain
- **Goal test:** a set of constraints



	1	2	3	4
X_1			Q	
X_2	Q			
X_3				Q
X_4		Q		



Sudoku

- Grid: 9×9 cells, 3×3 sub-grids
Variables: 81 cells Domain: {1,2,3,4,5,6,7,8,9}
- Each row, column, sub-grid contains a permutation of 1-9
Constraints: 27 non-equals

5	3			7				
6			1	9	5			
	9	8					6	
8				6				3
4			8		3			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9

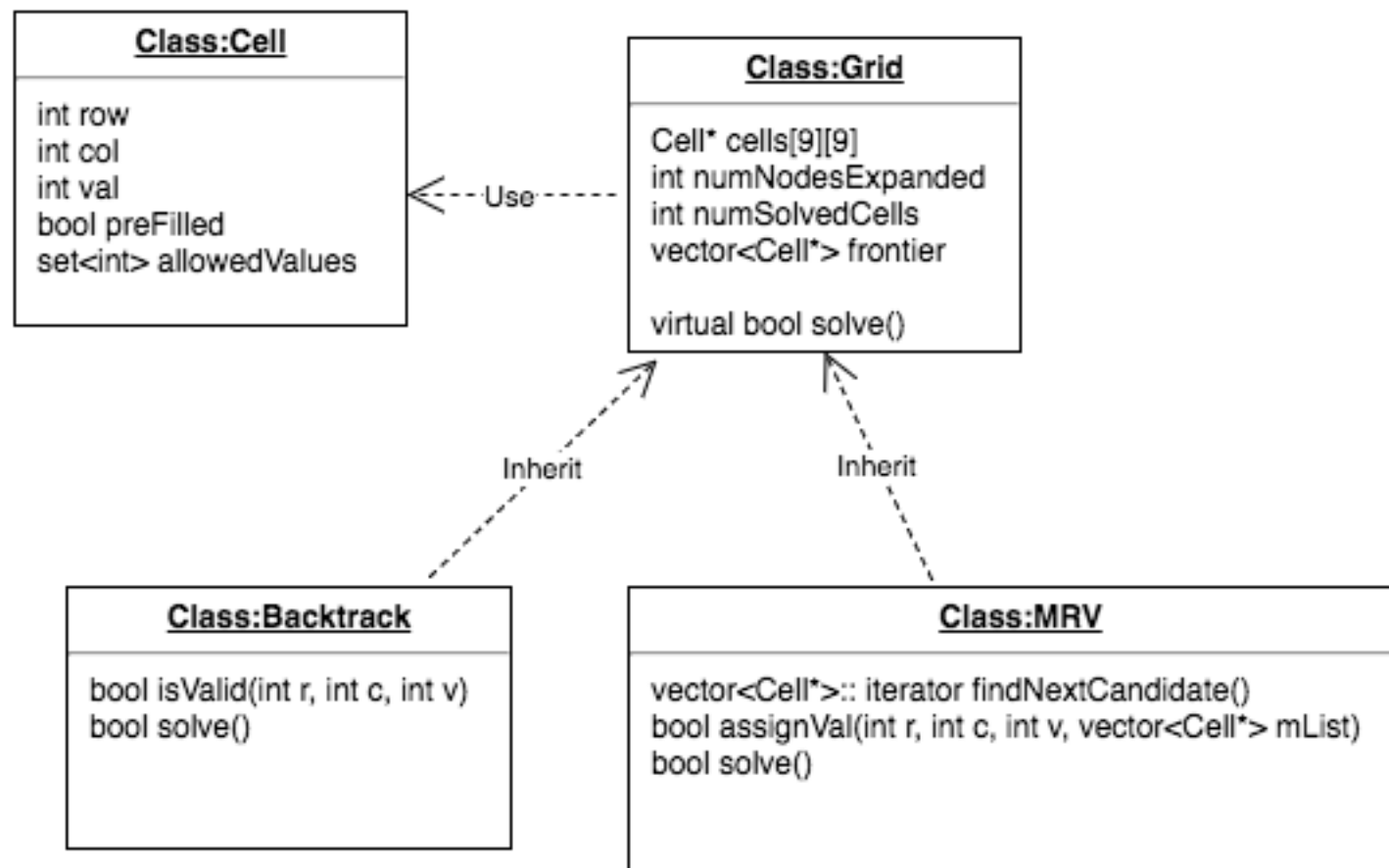
5	3	4	6	7	8	9	1	2
6	7	2	1	9	5	3	4	8
1	9	8	3	4	2	5	6	7
8	5	9	7	6	1	4	2	3
4	2	6	8	5	3	7	9	1
7	1	3	9	2	4	8	5	6
9	6	1	5	3	7	2	8	4
2	8	7	4	1	9	6	3	5
3	4	5	2	8	6	1	7	9

Existing solutions

- Base: backtrack
- Reducing search space:
 - arc/path/k consistency
- During search:
 - look ahead: variable/ value ordering
 - look-back: buckjump, constraint recording, etc


Our approach (C++)

- Naive backtrack and Forward Checking with MRV
- Classes: Cell, Grid, Backtrack, MRV
- Grid inherited by Backtrack and MRV



Naive backtrack

```
bool solveFrom(int row, int col) {  
    if (numSolvedCell == TOTAL_CELL) return true;  
  
    if (cells[row][col]->preFilled)  
        return solveFrom(col == GRID_DIM - 1 ? row + 1 : row, col == GRID_DIM - 1 ? 0 : col + 1);  
  
    for (int val = 1; val <= 9; val++)  
        if (isValid(row, col, val)) {  
            cells[row][col]->value = val;  
  
            if(solveFrom(col == GRID_DIM - 1 ? row + 1 : row, col == GRID_DIM - 1 ? 0 : col + 1))  
                return true;  
  
            cells[row][col]->value = Cell::EMPTY_VALUE;  
            numSolvedCell--;  
        }  
    return false;  
}
```



5	3	4	6	7	8	9	1	2
6	7	2	1	9	5	3	4	8
1	9	8	3	4	2	5	6	7
8	5	9	7	6	1	4	2	3
4	2	6	8	5	3	7	9	1
7	1	3	9	2	4	8	5	6
9	6	1	5	3	7	2	8	4
2	8	7	4	1	9	6	3	5
3	4	5	2	8	6	1	7	9

FCMRV

```

bool solve() {
    if (frontier.size() == 0)
        return true;

    std::vector<Cell*>::iterator curCell_itr = findNextCandidate();
    Cell* curCell = * curCell_itr;
    frontier.erase(curCell_itr);

    std::set<int> possibleValues = curCell->allowedValues;

    for (std::set<int>::iterator it = possibleValues.begin();
        it != possibleValues.end(); it++) {

        int curVal = *it;
        std::vector<Cell*> modifiedCells;

        if(!assignCell(curCell, curVal, modifiedCells))
            continue;

        if (solve())
            return true;

        for (int i = 0; i < modifiedCells.size(); i++)
            modifiedCells[i]->allowedValues.insert(curVal);
    }
    curCell->value = 0;
    frontier.push_back(curCell);
    return false;
}

```

7	1 2 6	8	9 9	4 5 6 2	4 5 6 3	3	1 4 5 6	1 5
4 6 9	3 6	4 6	2	4 5 6 8	1	4 6 7 8 9	4 5 6 7 8	5 8 9
5	1 6	1 4 6	7	3	4 6 8 9	2	1 4 6 8	1 8 9
1 8	4	1 7	5	9 7 9	3 1	2	6	
3	1 5 6	9	4	8	2 6	1	1 5	7
6 8	5 6 7 8	2	1	6 7	3 6 4	9	3 5 8	
1 2 8	9	3	6	1 2 5	2 5 8	1	1	4
1 2 4 6 8	1 2 6 8	1 4 6	3 8 9	7	2 3 4 8 9	5	1 3 6 8	1 2 3 8 9
1 2 4 6 8	1 2 6 7 8	5	3 8 9	1 2 4 9	2 3 4 8 9	1 6 7 8 9	1 3 6 7 8	1 2 3 8 9

Performance

6	4	2		1	8		5	9	8	
3		5			9		4			
-----+-----+-----										
7	2	1			4		5			
		4					2			
	9			3			7	8	4	
-----+-----+-----										
	6			5			8	7		
1		8			3			6	2	
		9		2			1			
-----+-----+-----										



9	1	2		4	6	8		5	7	3	
6	4	7		1	3	5		9	2	8	
3	8	5		7	2	9		6	4	1	
-----+-----+-----											
7	2	1		8	9	4		3	5	6	
8	3	4		6	5	7		2	1	9	
5	9	6		3	1	2		7	8	4	
-----+-----+-----											
2	6	3		5	4	1		8	9	7	
1	5	8		9	7	3		4	6	2	
4	7	9		2	8	6		1	3	5	
-----+-----+-----											

method	#nodes expanded	time
Naive backtrack	1150	500 us
FCMRV	63	250 us

Future improvement

- Use min-heap as frontier for MRV to find the next candidate
- Apply value ordering: e.g. least constraining value
- Introduce other heuristic