

# Sesam User Course



JScript in GeniE command input  
Parametric modelling

Revised: 1 July 2009

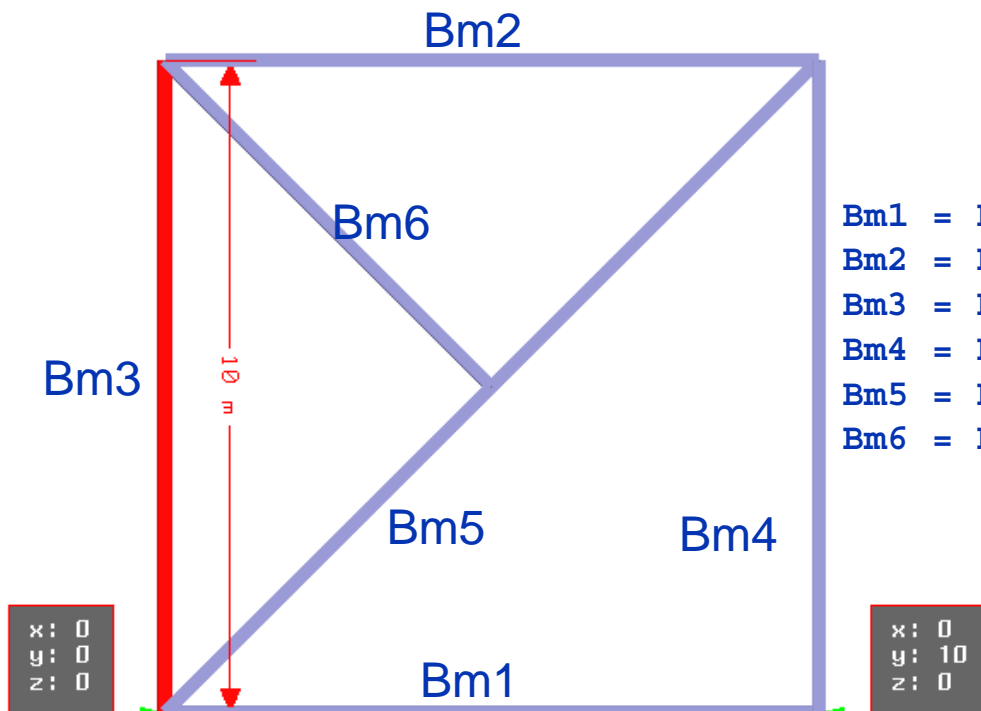
- Applications of JScript in GeniE
  - Examples on parametric models in GeniE
  - A practical example - workshop
  - GeniE & JScript – what you need to know
  - Documentation of GeniE JScript
  - For the advanced user
    - Basic JScript
    - Variables and Data Types
    - GeniE Data Types
    - Understanding the structure of GeniE commands
    - Basic JScript within GeniE commands
    - Objects
    - Accessing the objects in a model
  - Controlling Program Flow
    - if ... else
    - do ... while
    - for ...
    - for ... in
  - Functions
  - User defined functions
  - JScript objects – the Math object
  - Working with Office documents from GeniE
  - User defined JScript objects
  - Parametric modelling
  - Generating Pictures and Reports
  - Load Intensity by Jscript
  - Limitations
- 
- Some of the content require that you have access to the file “Frame.js”

# Applications of JScript in GeniE

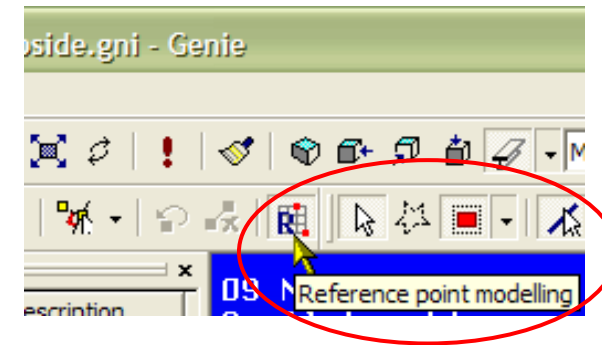
- Develop custom engineering applications
  - Script that controls GeniE and other programs
- Perform standard operations
  - Setting up a new workspace
  - Set code check parameters
  - Reporting
- Create models
  - Well organized model
  - Steady progress
  - Robust against changes
  - Parametric modeling
- Extensive model updates
  - Efficient
  - Quality control
- Distributed loads
  - Load intensity as JScript

# Parametric models in GeniE

- Can be combination of variables and reference point modelling



```
Bm1 = Beam(Point(0m,0m,0m),Point(0m,10m,0m));  
Bm2 = Bm1.copyTranslate(Vector3d(0m,0m,10m));  
Bm3 = Beam(Bm1.end1,Bm2.end1);  
Bm4 = Beam(Bm1.end2,Bm2.end2);  
Bm5 = Beam(Bm3.end1,Bm4.end2);  
Bm6 = Beam(Bm3.end2,Bm5.project(Bm3.end2));
```

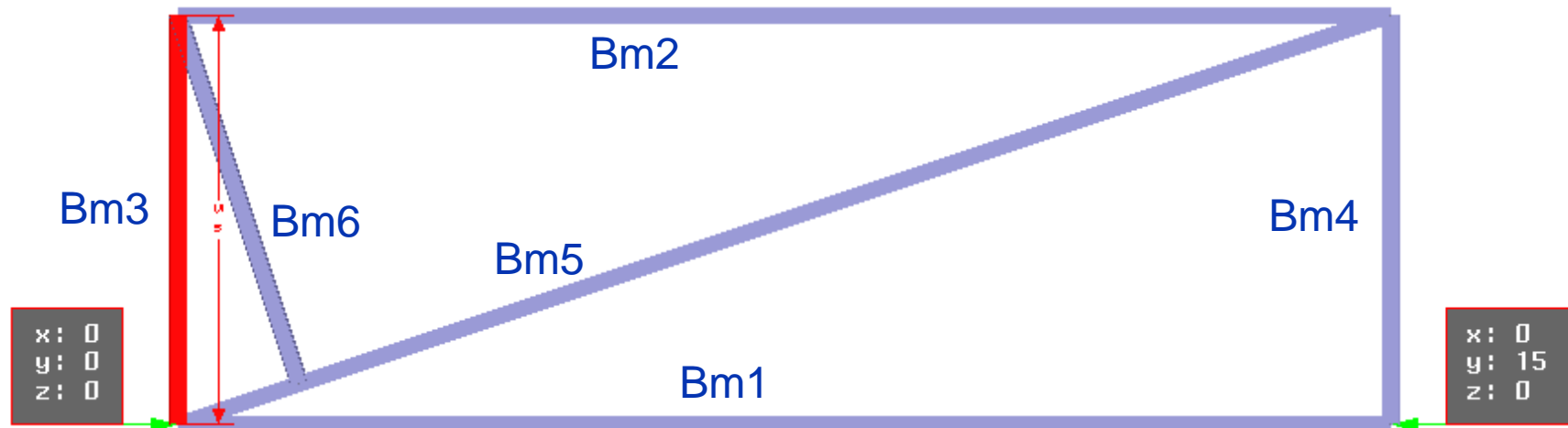


The journal file refers to beam ends rather than explicit coordinate values

## ■ Modify input parameters and re-run journal file

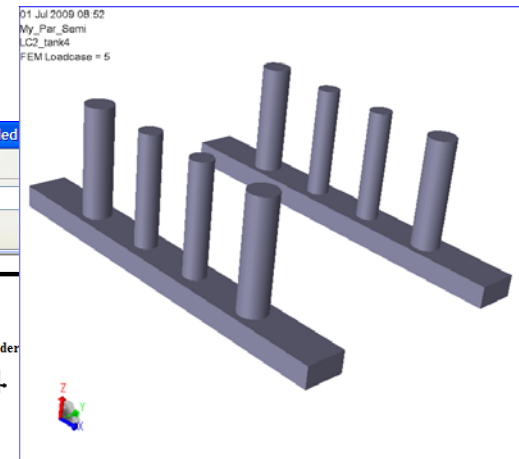
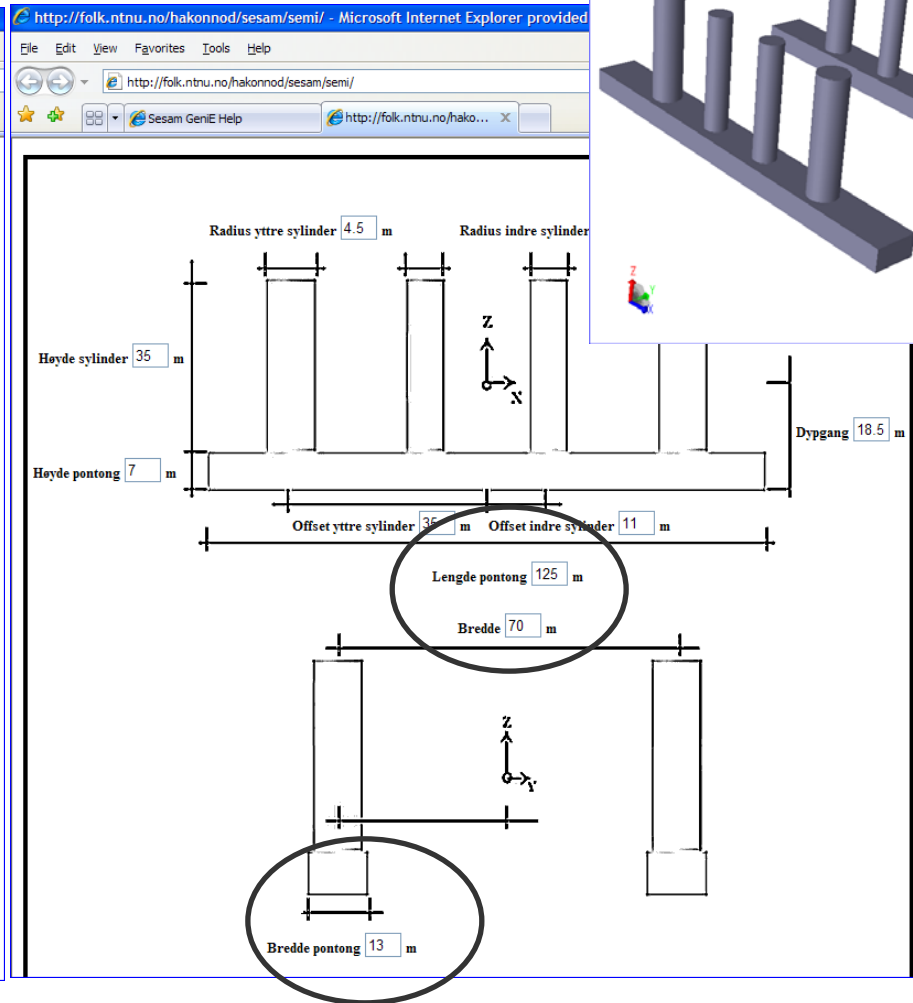
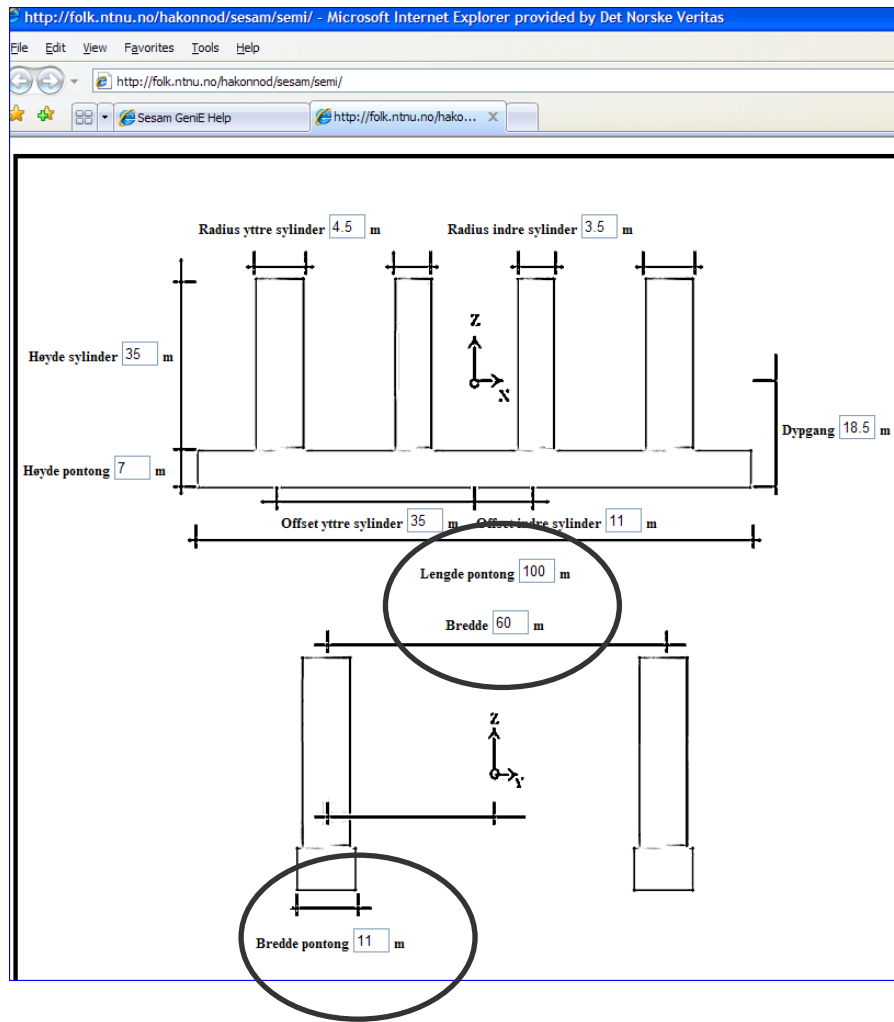
- New length of Bm1: 15 m
- New copy vector: 5 m

```
Bm1 = Beam(Point(0m,0m,0m),Point(0m,15m,0m));  
Bm2 = Bm1.copyTranslate(Vector3d(0m,0m,5m));  
Bm3 = Beam(Bm1.end1,Bm2.end1);  
Bm4 = Beam(Bm1.end2,Bm2.end2);  
Bm5 = Beam(Bm3.end1,Bm4.end2);  
Bm6 = Beam(Bm3.end2,Bm5.project(Bm3.end2));
```

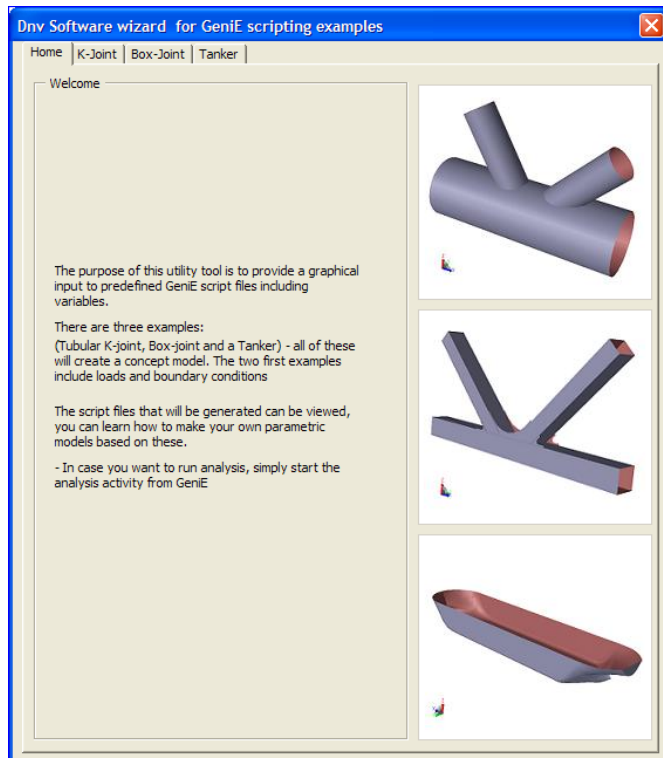


- New model automatically created
- Much more advanced models may be created
- GeniE comes with wizards using this feature
- 'Clean' js-file (File > Export > Genie journal file) loses reference point

## ■ Example on student use at a university



## ■ Parametric models available from Excel VBA



Software wizard for GenIE scripting examples

me K-Joint Box-Joint Tanker

Project name:

Save js-file

Open GenIE

Find js-file

Predefined values

Clear values

**Chord**

Chord radius:  m

Chord thickness:  mm

Chord length:  m

**Brace**

Brace 1 radius:  m

Brace 1 angle:  deg

Brace 2 radius:  m

Brace 2 angle:  deg

Brace 1 length:  m

Brace 1 gap:  m

Brace 2 length:  m

Brace 2 gap:  m

Brace 1 thickness:  mm

Brace 2 thickness:  mm

**K-joint**

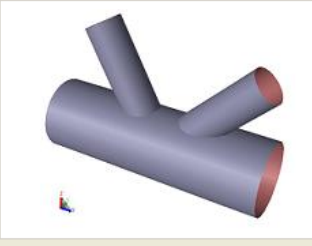
Origin: (x, y, z)

**Mesh**

Coarse mesh density:  m

Brace 1 mesh density:  m

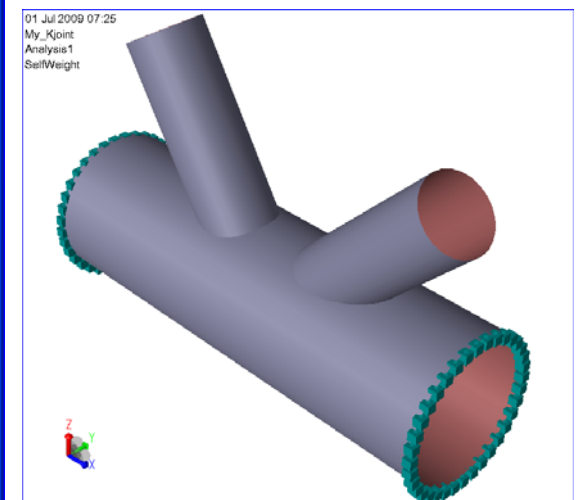
Brace 2 mesh density:  m



My\_Kjoint.js - Notepad

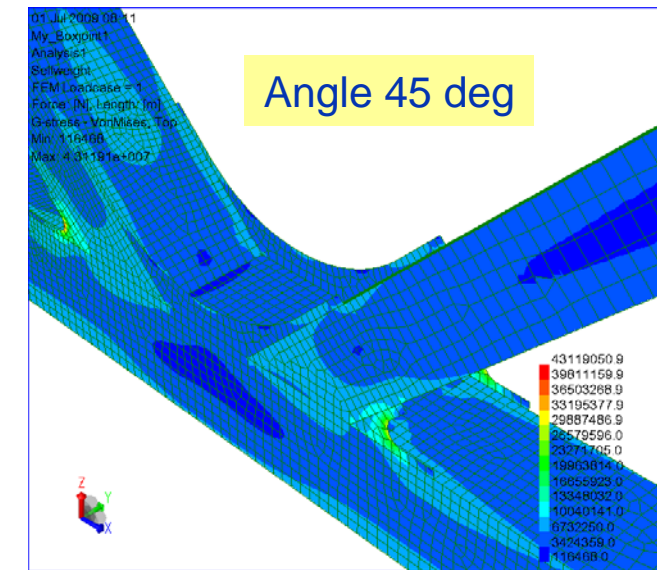
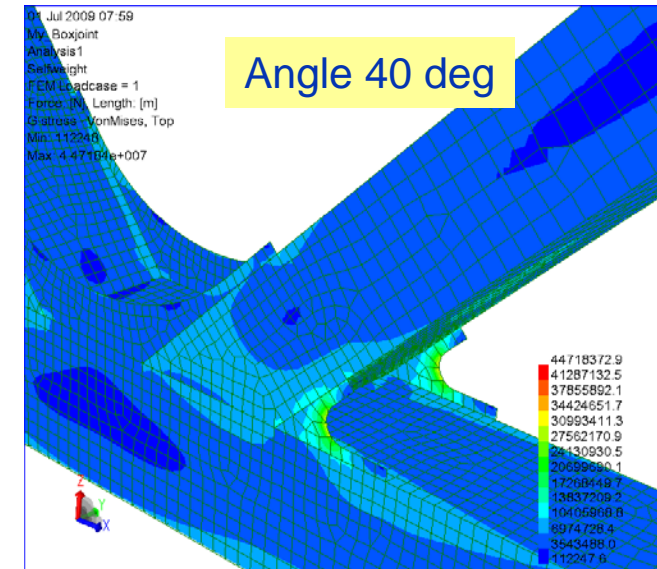
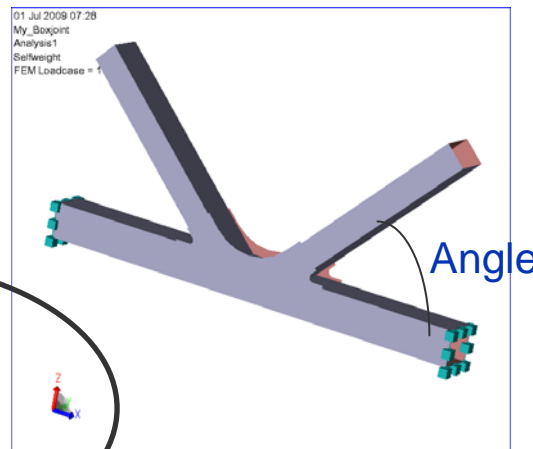
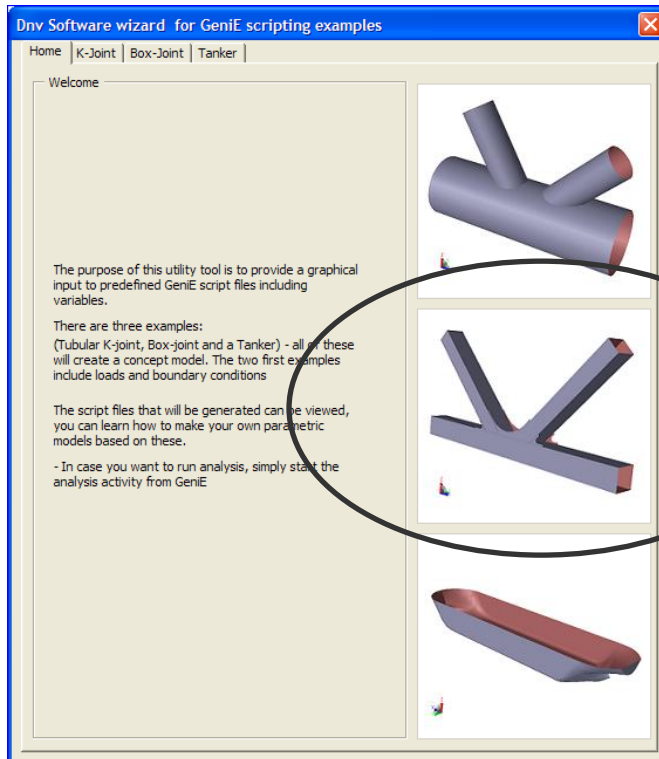
```
File Edit Format View Help

// Define variables
RadChord=4.0m;
RadBrace1=2.0m;
RadBrace2=2.0m;
Alpha=45deg;
Beta=30deg;
ChordLength = 25m;
Origin = Point(5 m, 5 m, 0 m);
Brace1Length=14m;
Brace2Length=14m;
Brace1Gap=1.0m;
Brace2Gap=0.5m;
Brace1Origin=Point(5m+Brace1Gap, 5m, 0m);
Brace2Origin=Point(5m-Brace2Gap, 5m, 0m);
LocalLength=0.7;
Chord_th = Thickness(25mm);
Brace1_th = Thickness(20mm);
Brace2_th = Thickness(15mm);
Md_coarse = MeshDensity(0.75m);
Md_Brace1 = MeshDensity(0.25m);
Md_Brace2 = MeshDensity(0.25m);
Md_coarse.growthRate = 1.05;
Md_Brace1.growthRate = 1.05;
Md_Brace2.growthRate = 1.05;
s355 = Material(355E6, 7.85E3, 2.1E11, 0.3, 1.2E-5, 0.03);
s355.setDefault();
```



# Custom Engineering Application

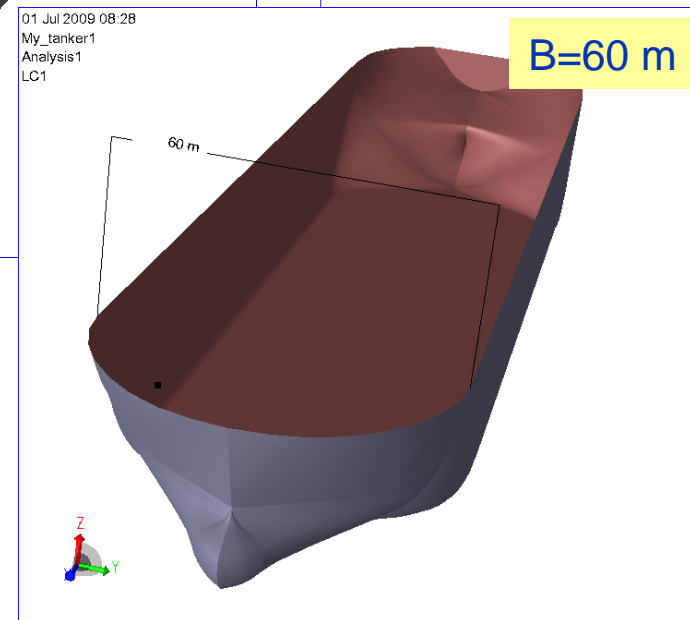
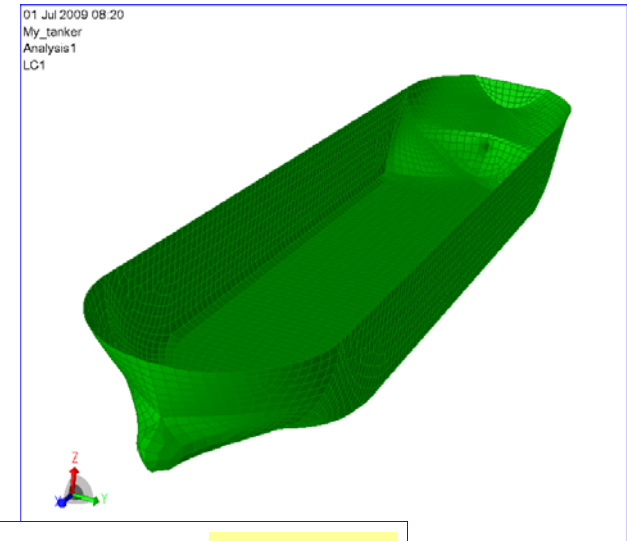
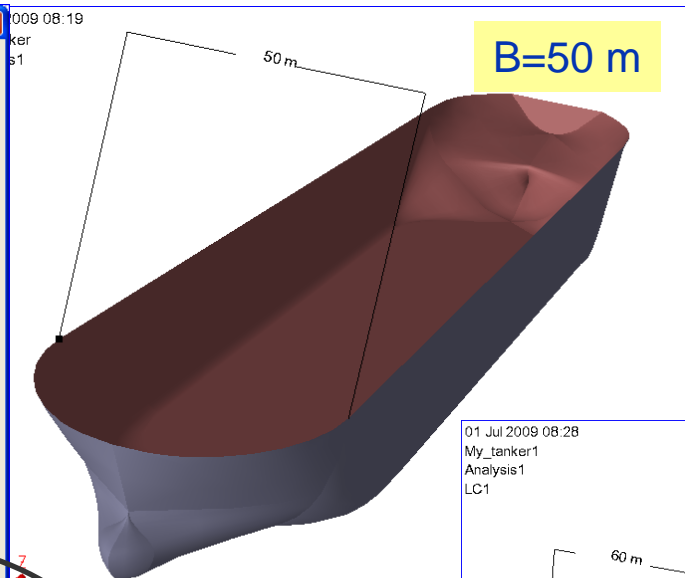
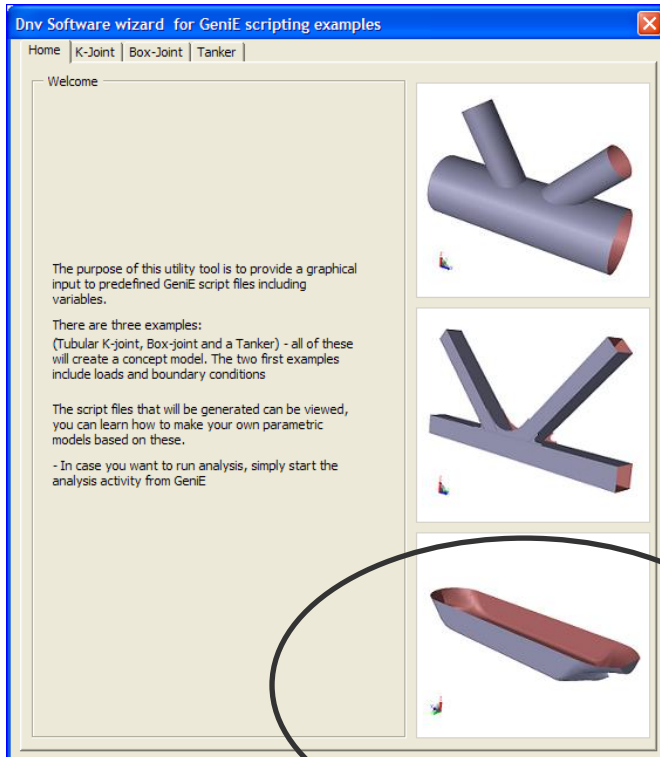
## ■ Parametric models available from Excel VBA





# Custom Engineering Application

## ■ Parametric models available from Excel VBA

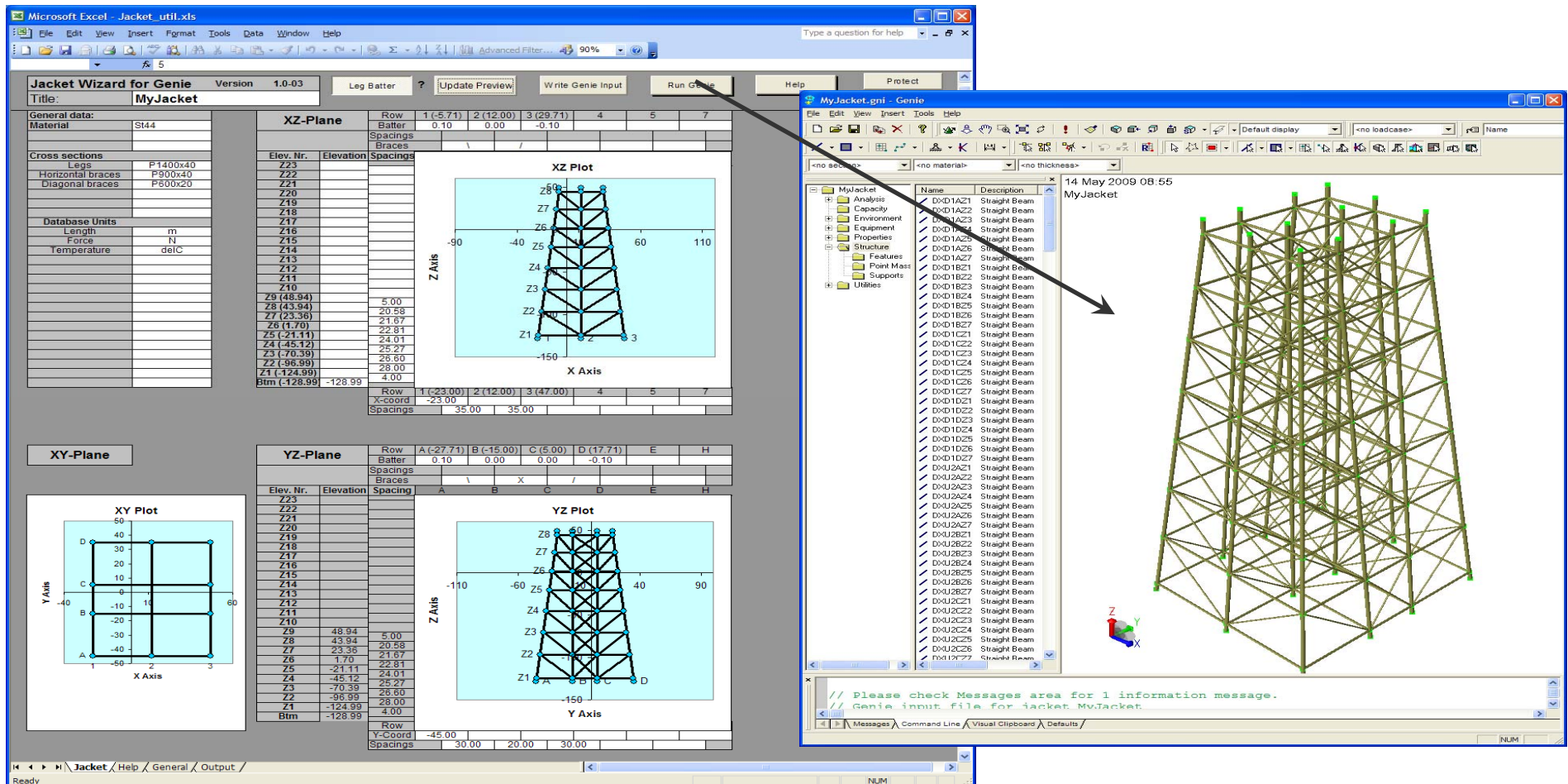


# Custom Engineering Application

MANAGING RISK

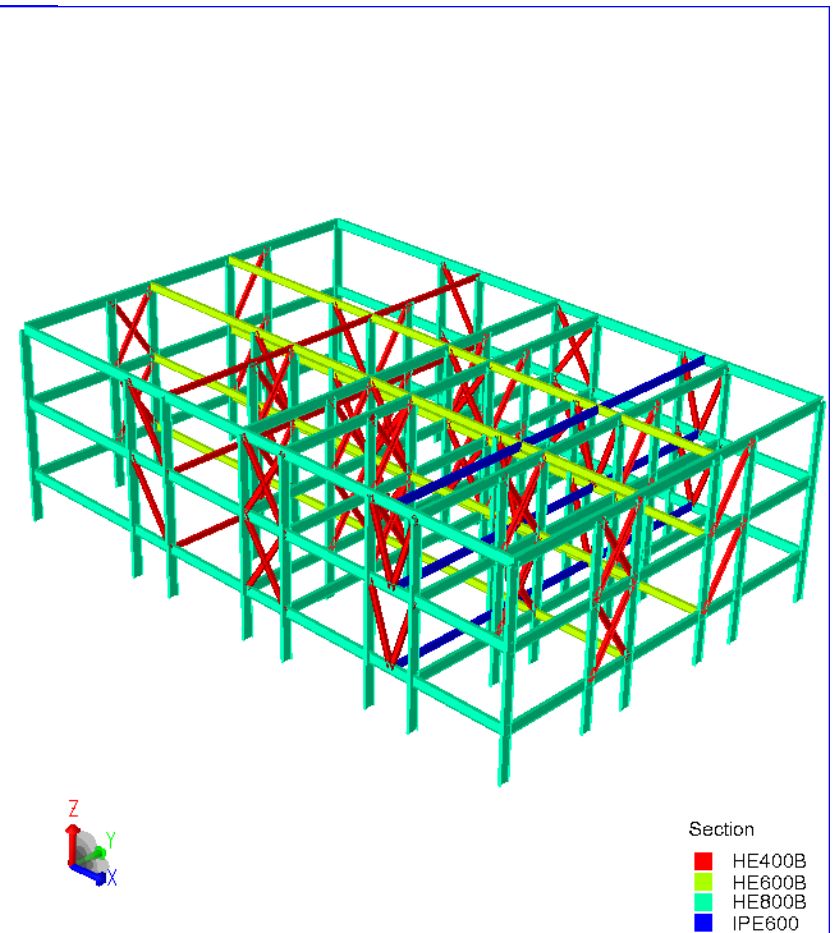
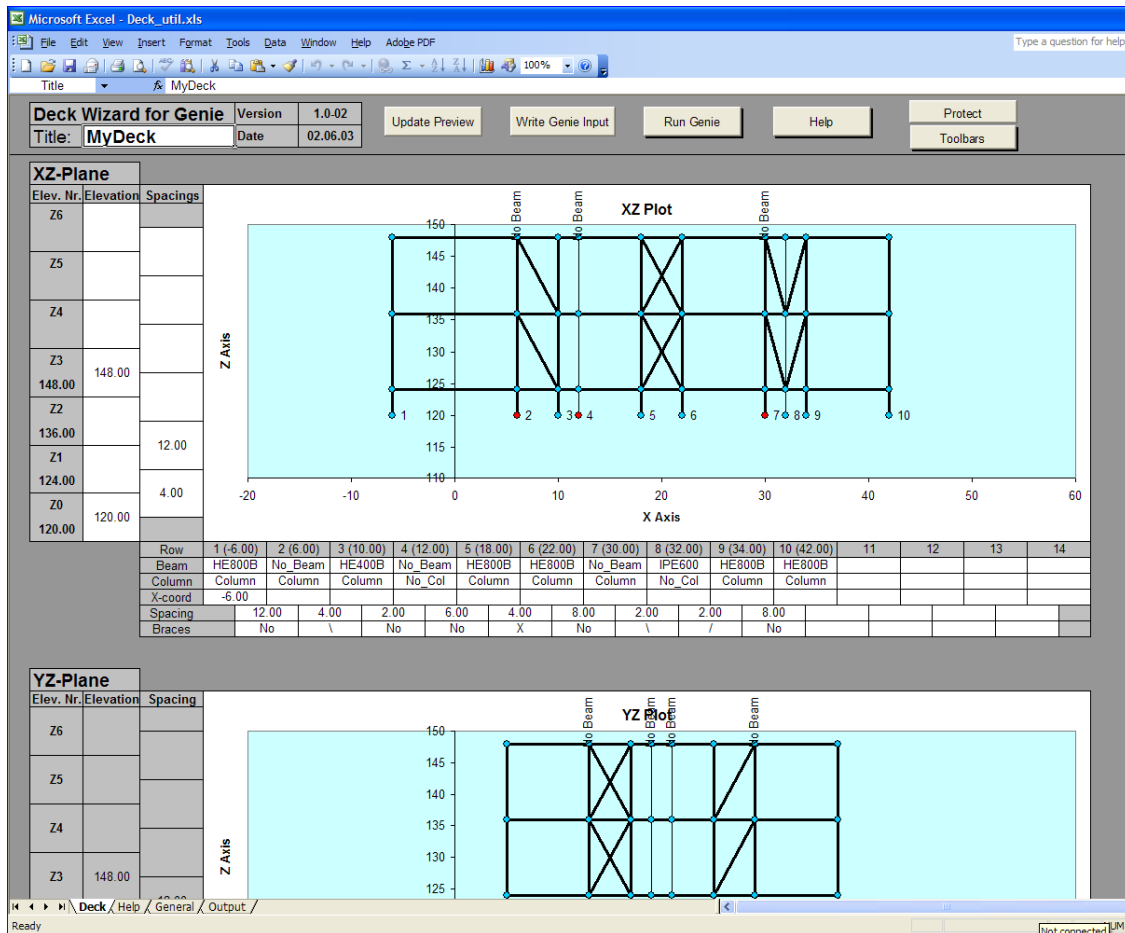


- Parametric models as part of the GeniE installation – jacket
  - Help -> Help Topics > Wizard templates

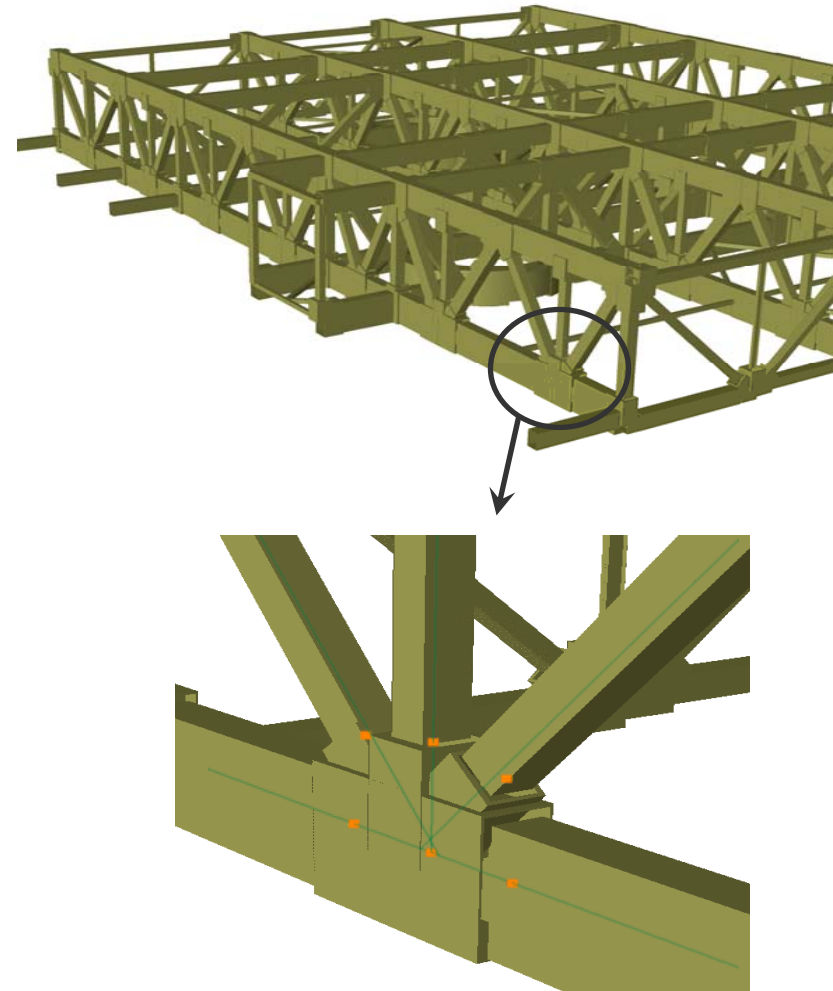


# Custom Engineering Application

- Parametric models as part of the GeniE installation – topside
  - Help -> Help Topics > Wizard templates



- Example: Extensive model update
  - Apply reinforcement and offset for gusset plates at all beam ends
  
- Make a function to
  - divide each beam into segments
  - set segment cross sections
  - set beam end offsets
  
- Call the function for each beam using tabulated data from drawings
  
- Faster, easier to check, more fun than manually editing hundreds of beams



# Using a function to update the beam ends

```
// First list the beams to be updated
// in an array
var Bea = new Array();
Bea[1] = Dx1A1;
Bea[2] = Dx1C1;
Bea[3] = Dx1E1;
Bea[4] = Dx1G1;
// and many more
//
// Define eccentricities and
// offsets for these beams
//
```

```
End1_X_center = 0.15 m;      =>
End2_X_center = 0.16 m;
End1_Offset = 1.837 m;
End2_Offset = 2.102 m;
Main_Section = D39;
End1_Section = Node_Diagonal_X;
End2_Section = Node_Diagonal_X;
```

```
// Then call a user function to do the update
//
DiagonalProp (Bea,End1_Offset,End2_Offset,
Main_Section,End1_X_center,End2_X_center,End
1_Section,End2_Section);
//
```

These data were listed in tables on the drawings

# DiagonalProp – function to update beams

```
function DiagonalProp (Bea,End1_Offset,End2_Offset,Main_Section,
    End1_X_center,End2_X_center, End1_Section,End2_Section)  {
    var NumBeam = Bea.length;
    for (i = 1; i < NumBeam ; i++) {
        Bea[i].section = Main_Section;
        //
        // Eccentricities modelled by EndOffset
        //
        if ( End1_X_center != 0. m )
            { Bea[i].setEndOffset(1,
                Vector3d(End1_X_center, 0 m,0 m));
            }
        if ( End2_X_center != 0. m )
            { Bea[i].setEndOffset(2,
                Vector3d(End2_X_center, 0 m,0 m));
            }
    }
    // Continue on next page...
```

# DiagonalProp – function continued...

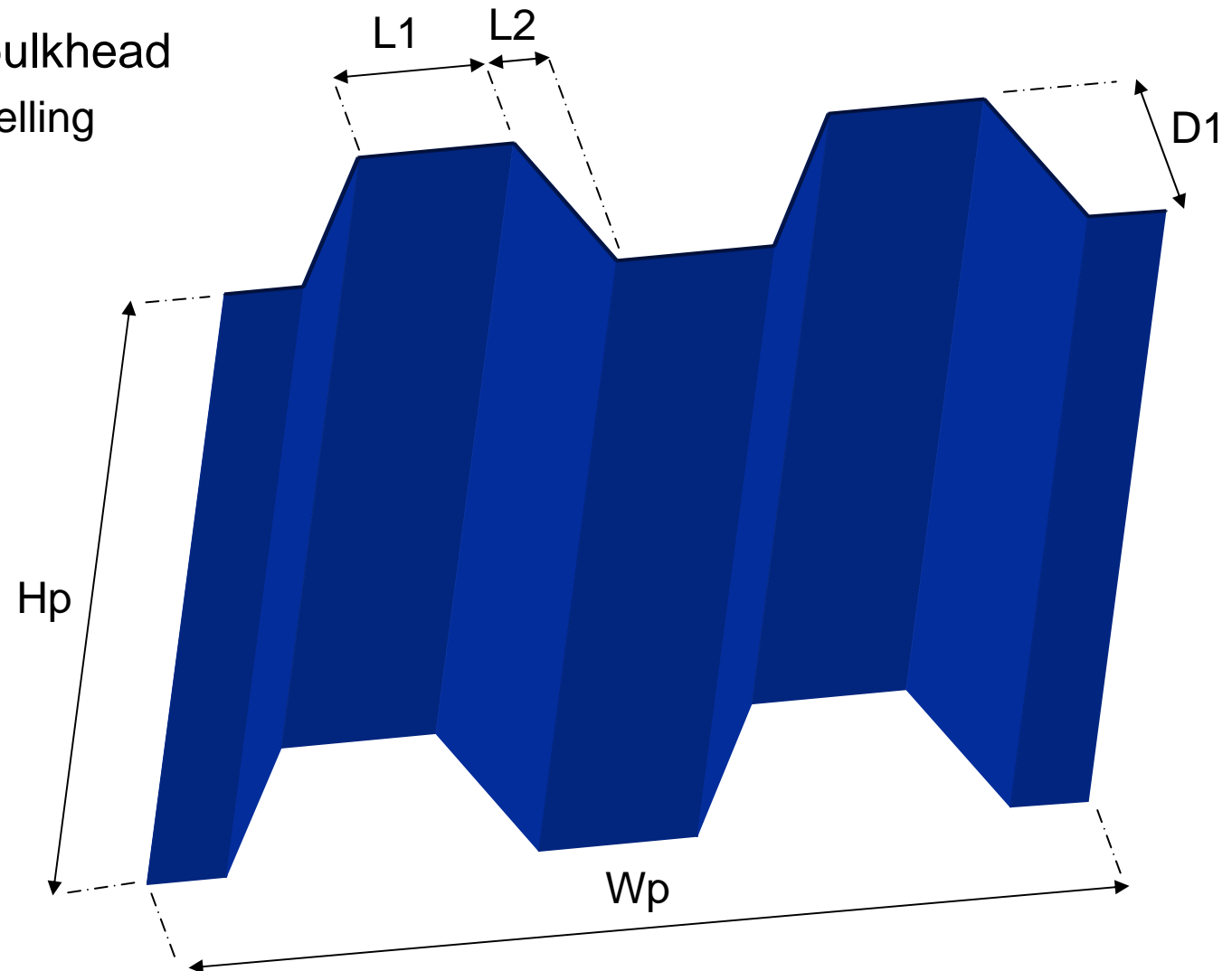
```
// Set End1 Offset and/or End2 offset
// The beam is divided at relative position  $L_{\text{segment}} / L_{\text{beam}}$ 
if ( End1_Offset != 0. m) {
    Bea[i].divideSegmentAt (1,(End1_Offset / Bea[i].length()));
    Bea[i].SetSegmentSection(1, End1_Section);
    if ( End2_Offset != 0. m) {
        Bea[i].divideSegmentAt
        (2,((Bea[i].getSegmentLength(2)-End2_Offset)/Bea[i].getSegmentLength(2)));
        Bea[i].SetSegmentSection(3, End2_Section);
    }
}
.... and similar for End2...
```



# Parametric modelling - example

## ■ Making a corrugated bulkhead

- Reference point modelling and variables
- Pure scripting





# Parametric Modelling by Reference Point



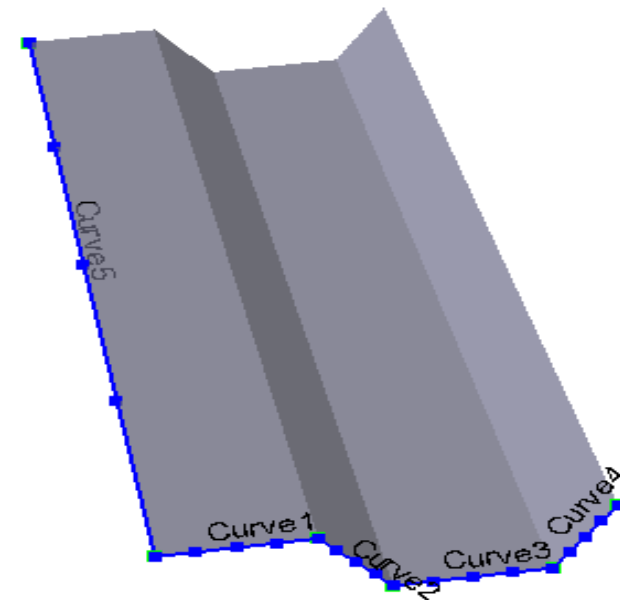
MANAGING RISK



- Reference point modelling will journal
  - relative to other structure - `Point1 = Curve1.curvePoint(1);`
  - not actual coordinates - `Point2 = Point(1 m,0.4 m,0 m);`
- Reference point modelling can be used to make parametric models

// Read the measurements from a journal file  
or define yourself

`Hp = 6.23 m; // Height of plate`  
`Wp = 12.32 m; // Width of plate`  
`L1 = 700 mm; // Length of sub panel`  
`L2 = 300 mm; // Length of corrugation`  
`D1 = 400 mm; // Depth of corrugation`

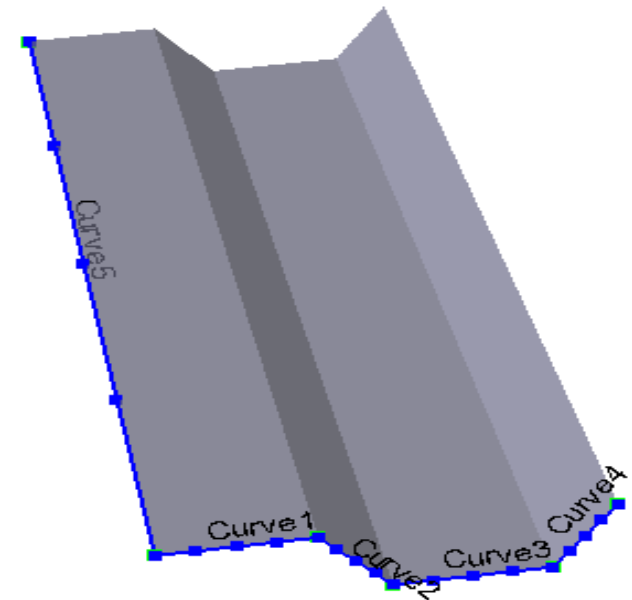


# Parametric Modelling by Reference Point

// Then model interactively using reference point modelling



```
Point1 = Point(0,0,0);
Point2 = Point1.copyTranslate(Vector3d(L1,0,0));
Point3 = Point2.copyTranslate(Vector3d(L2,D1,0));
Point4 = Point3.copyTranslate(Vector3d(L1,0,0));
Point5 = Point4.copyTranslate(Vector3d(L2,-D1,0));
Curve1 = GuideLine(Point1, Point2, 3);
Curve2 = GuideLine(Point2, Point3, 3);
Curve3 = GuideLine(Point3, Point4, 3);
Curve4 = GuideLine(Point4, Point5, 3);
Point6 = Point1.copyTranslate(Vector3d(0,0,Hp));
Curve5 = GuideLine(Point1, Point6, 3);
Pl1 = SweepCurve(Curve1, Curve5);
Pl2 = SweepCurve(Curve2, Curve5);
Pl3 = SweepCurve(Curve3, Curve5);
```



- Start with a section defining input parameter values:

$H_p = 6.23 \text{ m};$  // Height of plate

$W_p = 12.32 \text{ m};$  // Width of plate

$L_1 = 700 \text{ mm};$  // Length of sub panel

$L_2 = 300 \text{ mm};$  // Length of corrugation

$D_1 = 400 \text{ mm};$  // Depth of corrugation

- Then use the parameter names in GeniE commands to create your model

```
var i = 0; // Counter for sub panels
var j = 0; // Counter for corrugations = 4 sub panels
var Curves = new Array(); // Guide curves at the base of the plate
// Create sub panels
do {
  var StartP = (L1+L2)*2*j;    // Start point for the next corrugation
  if ( PartNr == 1) { Curves[i] = GuideLine(Point(StartP,0,0), Point((StartP+L1),0,0), 3);
    rename(Curves[i], "Line_"+i);
    LengthPlate = LengthPlate + L1;
    PartNr = 2;}
}
```

- To update the model you only need to enter new parameter values

## ■ Basic JScript

- Operators, data types, control flow, functions and objects

## ■ Basic GeniE commands

- GeniE objects, their functions and properties
- The commands you get when you work interactively

## ■ GeniE utility commands

- `ds1=DynamicSet(LimitInPlane(ZPlane3d(0)));`
- `for(var sect in ModelObjects)`
- `if(a.supportsType(typeSection))`

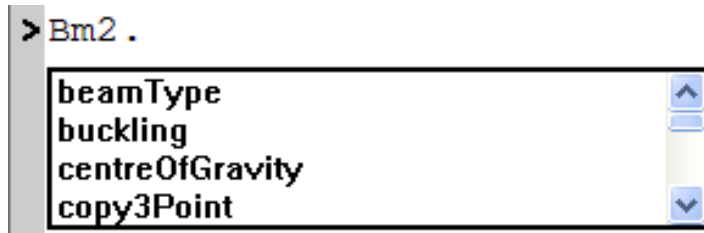
## ■ Practical applications

- Creating objects
- Setting and getting object properties
- Addressing subsets of your model
- Addressing objects by their name
- Creating your own functions

- JScript – Microsoft Developers network
  - [http://msdn.microsoft.com/en-us/library/hbxc2t98\(VS.85\).aspx](http://msdn.microsoft.com/en-us/library/hbxc2t98(VS.85).aspx)
- GeniE Help – Volume 6 and JScript Commands
  - Overview
    - The GeniE commands
    - Example:
      - Beam (three methods to create a beam)
  - Class Hierarchy
    - The GeniE objects and properties
    - Example:
      - NamedObject
        - Transformable
        - BasicConcept
          - BasicBeam
          - StraighBeam

# Documentation of GeniE JScript

- Run GeniE from GUI – look at the journal
- Use the Command window – tab completion



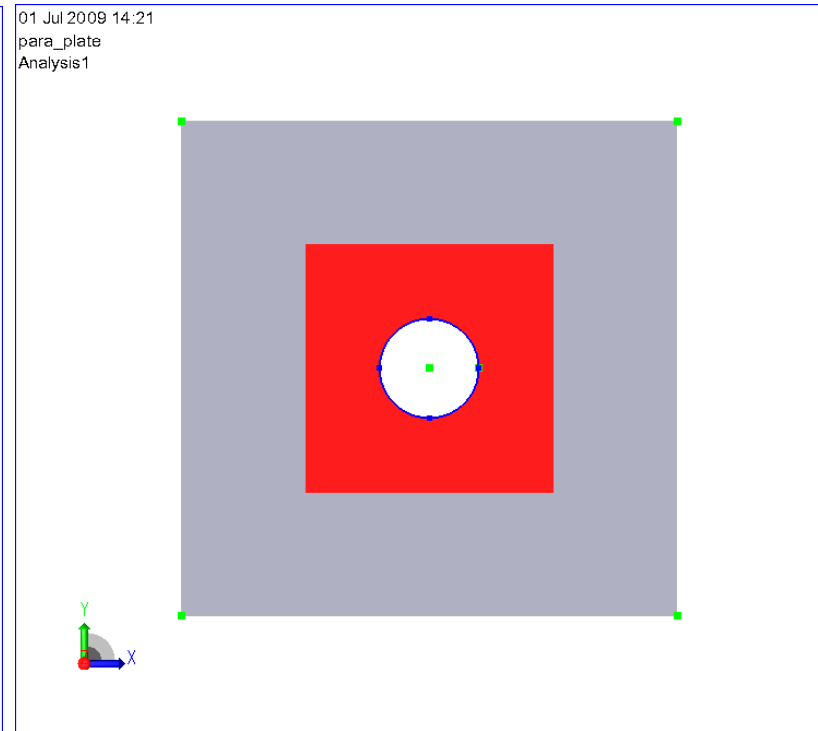
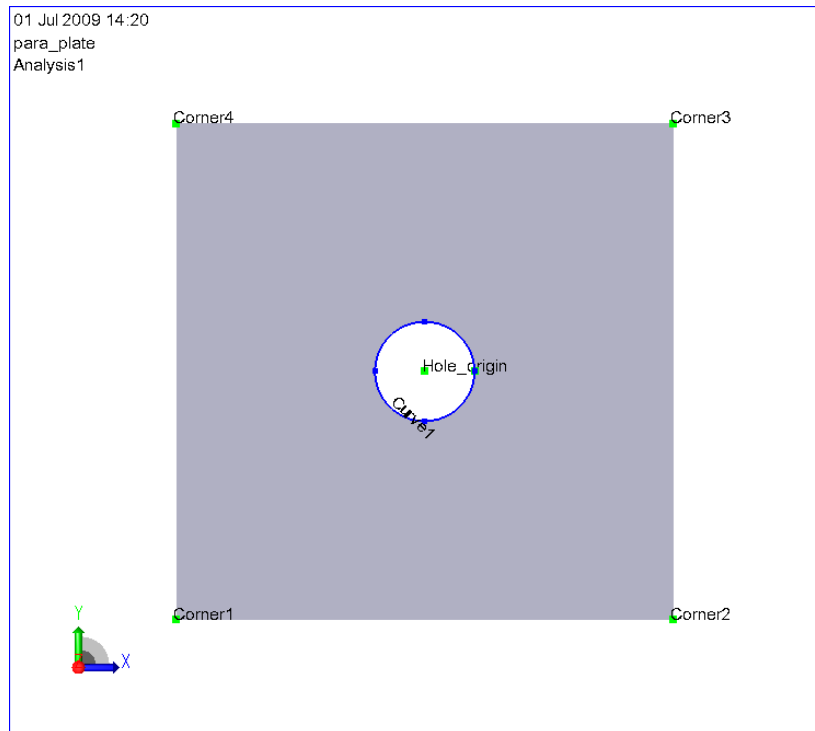
- Open the folder with GeniE Help files;  
*C:\Program Files\DNVS\GeniE\Help\jscript*  
in file explorer and search for word in file

- Use an editor to type the script file (Input.js)
- Then read the script into GeniE by
  - File > Read Command file
  - File > Recent Command files
  - Copy/Paste from editor to the GeniE command window
- Once you have tried a chunk of commands all variables, objects and functions will reside in the workspace until you close the workspace and create a new. To be sure use a new workspace each time you test your script.
- While developing your scriptfile you may
  - do things interactively in GeniE to get the command syntax
  - use the Command window > Tab completion to see available functions for your objects



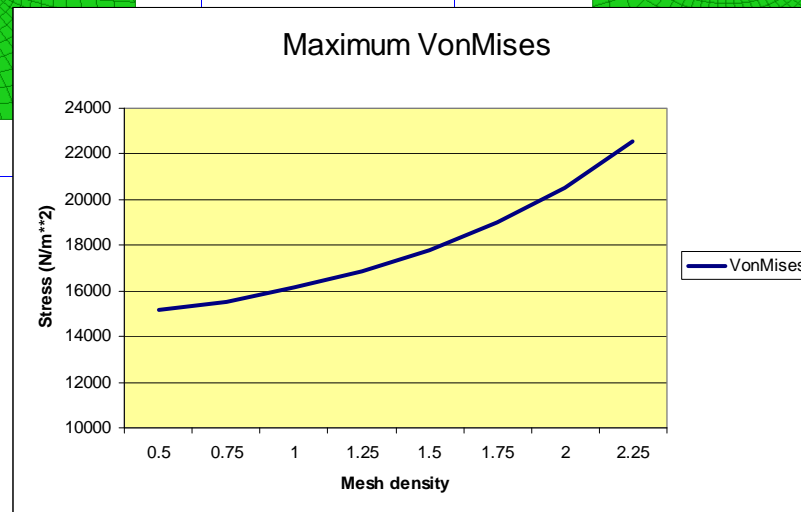
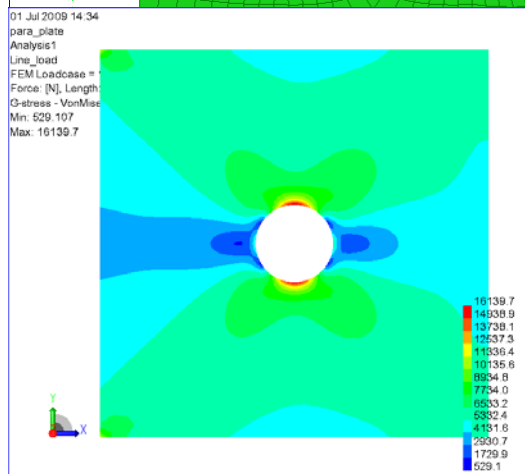
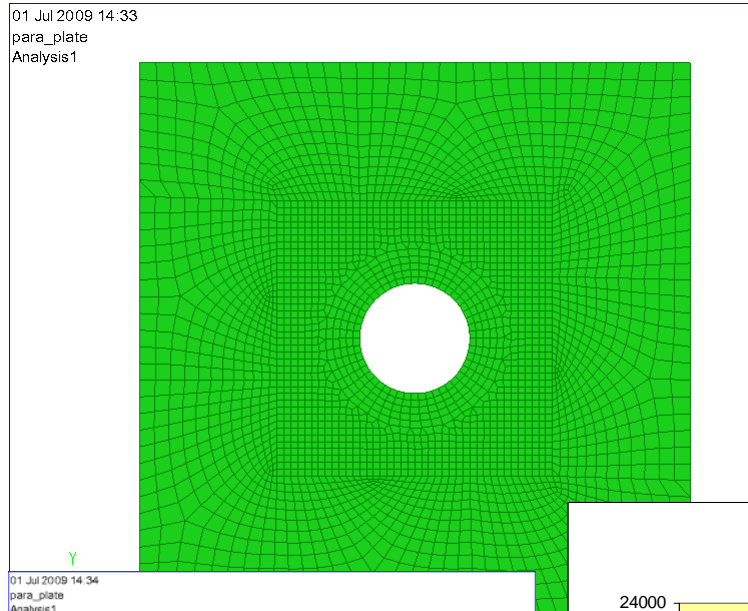
# A practical example

- Make a plate with a variable hole – check the VonMises stresses for  $R=0.5\text{m}$ ,  $1.0\text{m}$ ,  $1.5\text{m}$  and  $2.0\text{m}$
- The inner part has a refined mesh and is based on paver meshing
- This example includes the parametric input file “Param\_plate\_in.js”

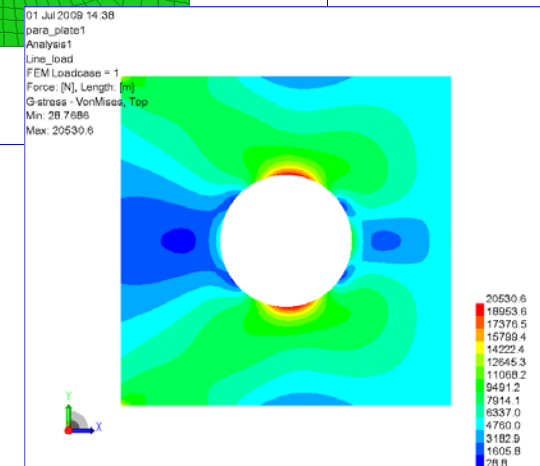
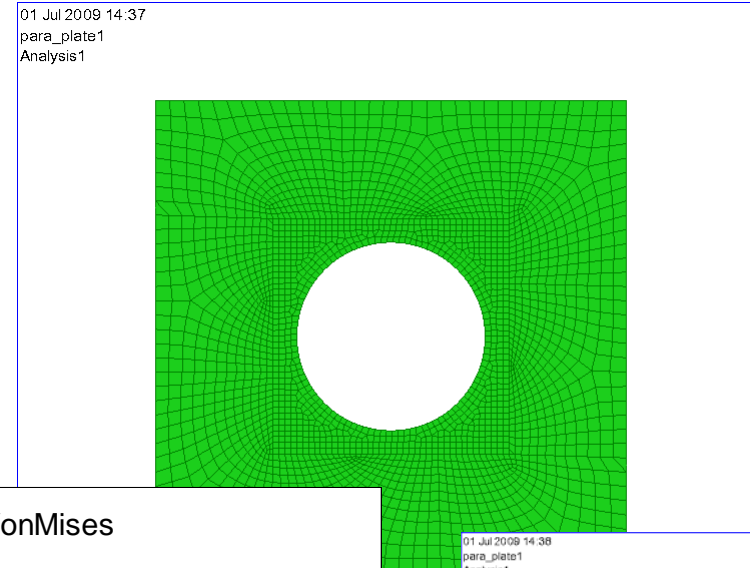


# A practical example

■ Radius 1.0 m -> VonMises 16139 N/m<sup>2</sup>



■ Radius 2.0 m -> VonMises 20531 N/m<sup>2</sup>



# A practical example

## ■ Follow the hints in the shown js-file - 1

```
Param_plate_in.js - Notepad
File Edit Format View Help

*****
TASK: TO DEFINE A PLATE WITH A HOLE TO SEE THE EFFECT OF VONMISES STRESSES WHEN MODIFYING THE HOLE RADIUS
LOOK AT THE STRESSES FOR A RADIUS RANGING 0.5M, 1.0M, 1.5M AND 2.0 M
THE RADIUS CAN NOT BE SET LARGER THAN 2.25 M UNLESS MODIFYING THE REFINED MESH ZONE
*****

// Define variables
// Hole radius
Radius = 1.00m;
// Plate extension
Corner1 =Point(0m,0m,0m);
Corner2 =Point(10m,0m,0m);
Corner3 =Point(10m,10m,0m);
Corner4 =Point(0m,10m,0m);
// Position of plate origin
Hole_origin = Point(5m, 5m, 0m);
// Define the extent of the refined mesh zone
DistX1 = 2.5m;
DistX2 = 7.5m;
DistY1= 2.5m;
DistY2 = 7.5m;
// Make the plate
P11 = Plate(Corner1,Corner2,Corner3,Corner4);
// Create circle line used to cut plate and cut the plate
Point1 = Hole_origin.copyTranslate(Vector3d(Radius,0,0));
Curve1 = GuideCircle(Hole_origin, Point1, Corner4);
P12 = P11.divide(Curve1);
Delete(P12);
```

# A practical example

## ■ Follow the hints in the shown js-file - 2

```
Param_plate_in.js - Notepad
File Edit Format View Help
Delete(P12);
// Divide the plate into refined mesh zone
P12 = P11.divide(XPlane3d(DistX1));
P13 = P12.divide(XPlane3d(DistX2));
P14 = P12.divide(YPlane3d(DistY1));
P15 = P14.divide(YPlane3d(DistY2));
P11.join(P12);
P11.join(P13);
P11.join(P15);
P11.simplifyTopology();
// Define boundary conditions
Sc1 = SupportCurve(ModelCurve(Point(0 m,10 m,0 m), Point(0 m,5 m,0 m), Point(0 m,0 m,0 m)));|
Sc1.localSystemRule = ConstantLocalSystem(LocalSystem(Vector3d(1 m,0 m,0 m), Vector3d(0 m,0 m,1 m)));
// Define mesh settings
Md_fine = MeshDensity(0.125);
Md_fine.growthRate = 1.05;
Md_coarse = MeshDensity(0.5);
Md_coarse.growthRate = 1.05;
// Apply mesh settings
P14.meshDensity = Md_fine;
P11.meshDensity = Md_coarse;
// Define mesh rules and user paver meshing for internal part and mesh it first - use linearized edge meshing
GenieRules.Meshing.elementType = mp2ndorder;
GenieRules.Meshing.edgeMeshStrategy = LinearDistributionEdge;
Paver = MeshOptionFace();
Paver.meshStrategy = AdvancingFrontQuadMesher;
P14.meshOption = Paver;
```

# A practical example

## ■ Follow the hints in the shown js-file – 2

```
// Define mesh priorities and mesh the fine zone first
//
Mesh_pri = MeshPriority();
Mesh_pri.addMeshPriority();
Mesh_pri.meshPriority(1).add(P14);
//
// Define analysis
//
Analysis1 = Analysis(true);
Analysis1.add(MeshActivity());
Analysis1.add(LinearAnalysis());
Analysis1.add(LoadResultsActivity());
Analysis1.step(1).meshPriority = Mesh_pri;
//
// Define properties and apply
//
S_355 = MaterialLinear(355000000 Pa, 7850 Kg/m^3, 2.1e+011 Pa, 0.3, 1.2e-005 de/c^1, 0.03 N*s/m, 510000000 Pa);
Th_plate = Thickness(20mm);
P11.thickness = Th_plate;
P14.thickness = Th_plate;
P11.material = S_355;
P14.material = S_355;
//
// Define a line load
//
Line_load = LoadCase(Analysis1);
LLoad1 = LineLoad(Line_load, FootprintLine(Corner2, Corner3), Component1dLinear(Vector3d(100, 0 N/m, 0 N/m), Vector3d(100, 0 N/m, 0 N/m)));
//
// To run analysis manually start or to remove the comments // in the line below
//Analysis1.execute();
```

## ■ You can “cheat” by using the file “Param\_plate\_in.js”

# For the advanced users

- The rest of this handout includes documentation for the advanced user who wants to learn how to make parametric models by pure scripting.

- All commands end with a semicolon ;
- Comments
  - /\* Here is a block of comments
  - Another comment line
  - \*/
  - // Here is a single comment
- Print
  - MyVariable = "Hello there";
  - Print("MyVariable = " + MyVariable
  - );

## ■ Operators

- |    |                 |    |              |
|----|-----------------|----|--------------|
| +  | addition,       | -  | subtraction, |
| *  | multiplication, | /  | division     |
| ++ | increment,      | -- | decrement    |

### Logical:

- |    |        |    |             |
|----|--------|----|-------------|
| <  | Less,  | >  | Greater,    |
| == | Equal, | != | Inequality, |
| && | And,   |    | Or          |
| !  | Not,   |    |             |

- `var MyBeam`  
    `// Declaration of a new variable`
- `var MyBeam, MyPlate`  
    `// Declaration of two new variables`
- `var MyBeam = Beam(Point(1,0,24), Point(13,1,18));`  
    `// declaration and initialization`
- JScript is a loosely typed language  
    Variables have no predetermined type  
    JScript variables get a type that corresponds to the type of value they contain



- Primary Data Types

- String
- Number
- Boolean

- Composite

- Object
- Array

- Special

- Null
- Undefined

## ■ All engineering objects have types

- StraightBeam, Plate, SupportPoint, PointLoad + many more
- `Print(Bm1.supportsType(typeStraightBeam));`  
    -> 1      (1 true, 0 is false)

## ■ General GeniE types

- Length, Mass, Vector3D, LocalSystem, Double and some more
- Type Length & Mass support `toDouble` and `toString`
  - Radius = 2.34 m
  - `Math.pow(Radius.toDouble(),2)`

# GeniE data types - some examples:

- `Print(Bm2.end1.x());`  
    `-> 5 m`                      `// that is, x is of type length`
- Number versus Length
  - `Point(3,4,5);`                      `// three numbers converted to lengths`
  - `Point(3+5.8, 4, 5);`              `// adding two numbers is OK`
  - `Point(3m+5.8mm, 4, 5);` `// adding two lengths is OK`
  - `Point(3m+5.8, 4, 5);`              `// adding a length + number gives error`  
        type + floating point
  - `Point(3m*1.2, 4, 5);`              `// Length * number is OK`
  - `Point(3m+Length(5.8), 4, 5);`  
        `// The function Length will convert (5.8) to length`
- GeniE can interpret several input formats
  - `Point(3,4,5);`
  - `Point(Length(3)+5.8mm,4,5);`
- Optional functions to change type - `parseFloat`, `parseInt`

# Understanding the structure of GeniE commands

- Native GeniE commands - Object notation

- Create:

```
Bm1 = Beam(Point(4 m,20 m,0 m), Point(4 m,0 m,0 m));
```

(Beam is a constructor function to create an instance, Bm1, of the straightBeam class)

- Set property:

```
Bm1.section = W200X100;
```

- Get property:

```
Print(Bm1.section.flangeThickness());
```

- Use copy method:

```
Bm11 = Bm1.copyTranslate(Vector3d(0 m,0 m,1 m));
```

- Setting and looking up properties

```
Bm1.setEndOffset(2,Bm2.localSystem.xVector.normalise()*(-1.3));
```

- The GeniE command interpreter will recognize

- basic GeniE commands
- basic JScript commands
- a mix of GeniE and JScript commands

- Examples

```
Bm114 = Bm94.copyTranslate  
(Vector3d( 2.3 m , 0.3 m ,10 m));
```

```
Bm114 = Bm94.copyTranslate  
(Vector3d( 2.3 ,L1 + 0.3 m , Bm2.end1.x()/4));
```

```
Bm115 = Beam(Point1,Point2);
```

```
Bm115 = Beam(Point(Math.abs(Math.pow (Bm62.end1.y.toDouble(), 2)),H1,1200  
mm),Bm62.end2());
```

When the interpreter finds a number not followed by an operator it will interpret the next word as a unit.

The number will get type from the unit.

## ■ Object names versus variable names

// Creating beams in a loop...

```
for (i = 1;i<(Floors+1); i++) {
```

// Get a point by it's name

```
End1 = GetNamedObject("Point"+i);
```

```
End2 = GetNamedObject("Point"+(i+1));
```

```
aBeam = Beam(End1,End2);
```

// The beam name is now the same as the variable "aBeam"

```
aBeam.section = I600;
```

```
aBeam.material = St44;
```

// Give the beam a unique name "Leg"+i

```
Rename(aBeam, "Leg"+i);
```

```
Print (GetNamedObject("Leg"+i).section.name());
```

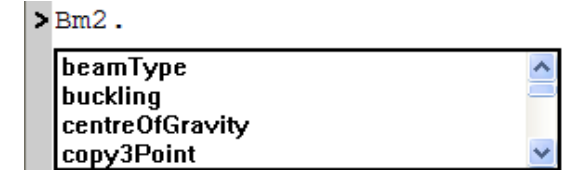
```
Print (Leg1.section.name()); // but not Print("Leg"+i... }
```

Note, we can not type

```
"Leg"+i = Beam(End1,End2);
```

# Exercise - objects and properties

- Read in the frame.js
- Type in the command window: Bm2. - and press the Tab key
- Study the properties and functions of Bm2
- Look up the StraightBeam in Help - Class hierarchy:
- ModelObject
  - NamedObject
    - Transformable
      - BasicConcept
        - BasicBeam
          - StraightBeam
- Print the cross section of Bm2
  - Print(Bm2.section.diameter());
- Set end1 x-offset of Bm2 equal half the diameter of Bm3



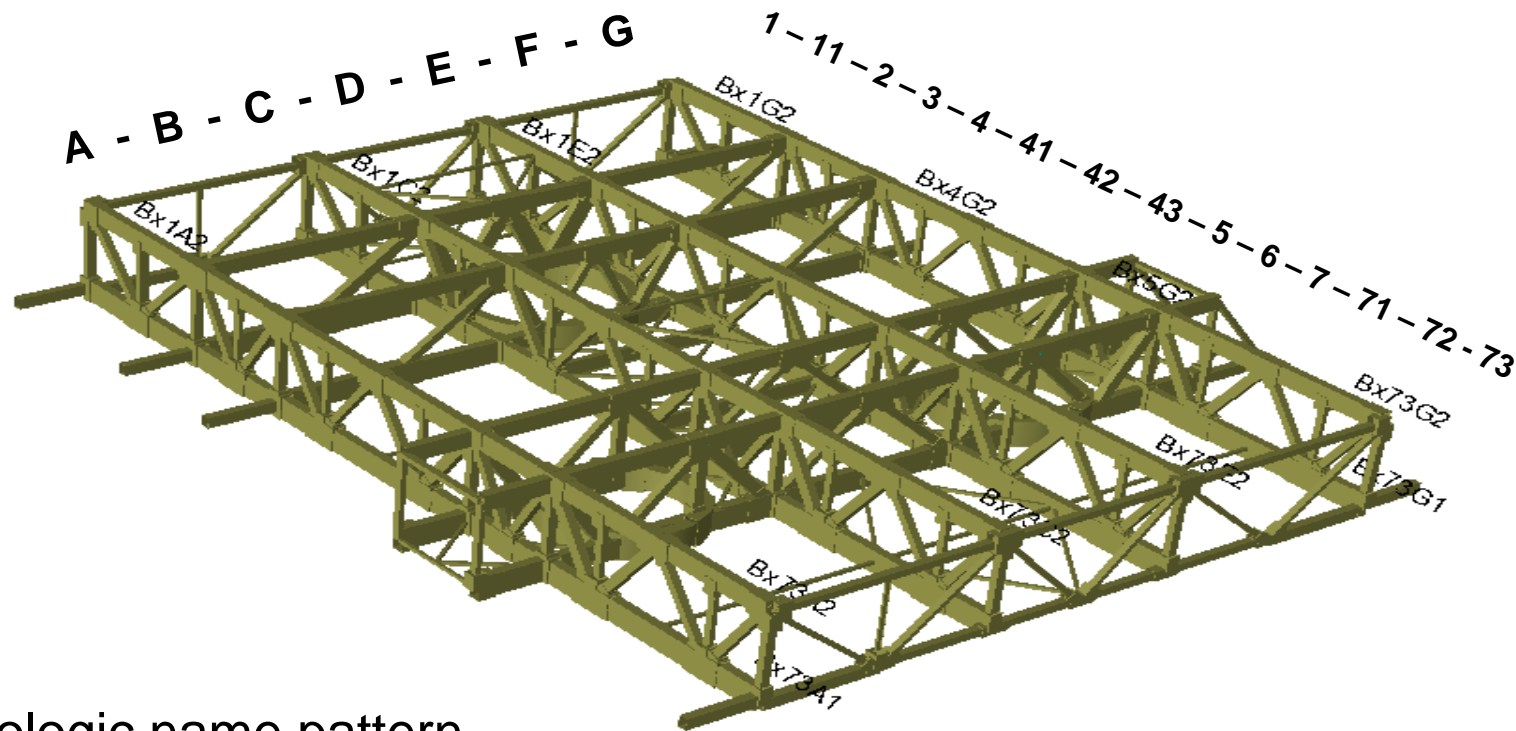
```
Bm2.setEndOffset(1,Vector3d(Bm3.section.diameter()/2.0,0.0,0.0));
```



## ■ You can access objects by

- by name
  - Genie has no name pattern suitable for programming
  - You can define your own
- by name sets
  - Static sets
  - Dynamic sets
  - In scripted input it is easy to add objects to sets as they are created
- by some of it's properties
  - Limit... functions
  - SupportType function

# A naming pattern for structures



- Topologic name pattern
- Name increments in X,Y and Z direction
  - Beam Bx4G2
  - Beam in X direction at X-axis 4, Y-axis G, Z-axis 2
  - Type + X-name + Y-name + Z-name

- Make a name from four sub strings Nam1, Nam2, Nam3 & Nam4 denoting:

Object type	X-direction	Y-direction	Z-direction
Nam1	Nam2	Nam3	Nam4

- Decide on a notation for type and make arrays of names in X,Y and Z direction

Nam1 = "P" // Point	Nam2[0] = "1";	Nam3[0] = "A";	Nam4[0] = "1";
Nam1 = "Bx" // Beam in Xdir	Nam2[1] = "11";	Nam3[1] = "B";	Nam4[1] = "2";
Nam1 = "By" // Beam in Ydir	Nam2[2] = "2";	Nam3[2] = "C";	Nam4[2] = "3";
Nam1 = "Bz" // Beam in Zdir	Nam2[3] = "3";	Nam3[3] = "D";	Nam4[3] = "4";
Nam1 = "Dx" // Beam diagonal in XZdir	Nam2[4] = "4";	Nam3[4] = "E";	Nam4[4] = "5";
Nam1 = "Dy" // Beam diagonal in YZdir	Nam2[5] = "41";	Nam3[5] = "F";	Nam4[5] = "6";
.....	Nam2[6] = "42";	Nam3[6] = "G";	Nam4[6] = "7";
	Nam2[7] = "43";	Nam3[7] = "H";	Nam4[7] = "8";
	Nam2[8] = "5";	Nam3[8] = "I";	Nam4[8] = "9";
	Nam2[9] = "6";	Nam3[9] = "J";	

- Now you can build a name; "By" + Nam2[5] + Nam3[2] + Nam4[1] => "By41C2"

- Make a function to build a name from the sub strings
  - `function GetName (N1,N2,N3,N4) { return( N1 +Nam2[N2] +Nam3[N3] +Nam4[N4]); }`
- And a function to get an object by its name:
  - `function GetObjectByName (N1,N2,N3,N4) {  
return(GetNamedObject(GetName(N1,N2,N3,N4))); }`
- Now you have a naming pattern suitable for programming:

```
for (i = 0;i< NumX ; i++) {  
    for (j = 0;j< NumY ; j++) {  
        for (k = 0; k < NumZ ; k++) {  
            var Bms1 = new Array();  
            Bms1[j] = Beam(GetObjectByName("P",i,j,k),  
GetObjectByName("P",i+1,j,k));  
            Bms1[j].name = GetName("BmX",i,j,k);  
            .....
```

- A Dynamic set uses a query to identify its members.
- Dynamic sets are continuously updated when new objects are created
- Example: All objects in a Plane:

```
dset1=DynamicSet(LimitInPlane(ZPlane3d(0)));
```

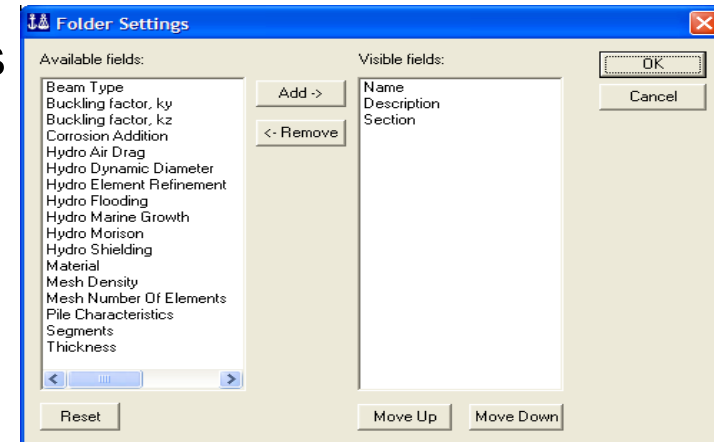
- Example:  
Set comprising beams in plane Z=0.0  
with flange Width < 0.2 m

```
dset1=DynamicSet(LimitInPlane(ZPlane3d(0)) && LimitLower("Width",0.2m));
```

- You can query Genie objects about their properties

LimitLower("Width",0.2m ) is a query for Beams with  
section flange Width < 0.2 m

- The properties you can query are listed in the  
Fields dialogue for the object type in the browser.  
E-g. for Structure:



# Dynamic sets - more examples

- Set comprising objects along a line that also belongs to a named set:  
`dset2 = DynamicSet(LimitAnd(LimitInSet(Frame_A),LimitLine(Point4,Point7)));`
- Set comprising beams in plane Z=0.0 with Section I200:  
`dset1=DynamicSet(LimitInPlane(ZPlane3d(0)) && LimitString("Section","I200",true));`
- `dset1 = DynamicSet(LimitLower("Diameter",0.7m));`
- `dset1 = DynamicSet(LimitString("Name","Bm.*",true));`  
When the boolean is true LimitString supports regular expression e.g:
  - .           => (dot) Matches any single character
  - \*           => Repeats the previous item zero or more times
  - |           => Match the part on either side of the |
  - ?           => Makes the preceding item optional
- Examples:
  - Bm.\*                               => Matches all objects named Bm<something>
  - Bm7|Bm7.\* or Bm7.\*?           => Matches Bm7, Bm72, Bm78, Bm786 etc.

Then use the set you created...

```
dset1.setBeamOffset(Vector3d(0 m,0 m,.3 m));
```

- Objects in dset1 that do not support setBeamOffset will be ignored.

# Exercise - Limit-functions

- Read the frame.js
- Use Tab in the command window to see all variants of the Limit... functions
- Or in GeniE help...
  - Class hierarchy:
    - ModelObject
      - + NamedObject
        - + AbstractLimit
  - Direct Known Subclasses:
    - LimitAnd ,LimitBox ,LimitInSet ,LimitLine , LimitNot ,LimitNumber , LimitOr ,LimitPlane ,LimitString +++
- Use the Limit... functions to extract various subsets of the frame model

# Sort beams in sets based on section

- Put beams in named sets based on the section name:

```
for(var sect in ModelObjects) {    if(sect.supportsType(typeSection)) {  
    newSet=Set();  
    for(var bm in ModelObjects) {  
        if (bm.supportsType(TypeStraightBeam) ||  
            bm.supportsType(TypeCurvedBeam)) {  
            if(bm.section.name==sect.name) {  
                newSet.add(bm);  
            } } }  
    newSet.name="Set_"+sect.name;  
} }
```

- or accessing the beams directly...

```
for(var a in ModelObjects)  
{ if(a.supportsType(typeStraightBeam))  
    Print(a.Length); }
```



- Read the frame.js journal
- Print the section name of beams in the command window by
  - Name – GetNamedObject
    - When to use GetNamedObject and when to use name directly?
  - Elevation – LimitInPlane
  - Objects that have cross section – `if(thisObject.supportsType(typeSection))`
  - Cross section = OD610X8
- Hint:

```
for(var a in ModelObjects)
{ if(a.supportsType(typeStraightBeam) && a.section.name=="OD610X8")
  Print(a.name()+" "+a.section.name());}
```
- Use the Vector3D to find the distance between two beam ends

```
Print(Vector3D(Point1,Point2).length());
```

## ■ If ...else

Example; Creating braces in the jacket wizard

```
for (i = 0; i < (NrXBrace); i++) { Thisbrace = xBrace[i];  
    if (Thisbrace == "braceup") { BraceUpX(i); }  
    else if (Thisbrace == "bracedown") { BraceDownX(i); }  
    else if (Thisbrace == "xbrace") { BraceUpX(i); BraceDownX(i); }  
    else if (Thisbrace == "kbrace") { Print("K-Brace not implemented"); }  
}
```

// xBrace[i] is an array of the braces to be created

// BraceUpX(i), BraceDownX(i) etc. are functions that create braces

- do ...while

```
var i = 1;  
do {  
    Print( GetNamedObject("Bm"+i).end1.z);  
    i++;  
} while (i < 10);
```

# for...

```
// Create an array of points on a circle
var myPoints = new Array(NrPoints);
var NrPoints = 36;    // Number of points
var Rad = 10.0;       // Radius
var X,Y;              // X,Y coordinate
//
for(var icount = 0; icount < NrPoints; icount++)
{ X=Rad*Math.cos(icount*10*Math.PI/180);
  Y=Rad*Math.sin(icount*10*Math.PI/180);
  myPoints[icount]=Point(X,Y,0);
  myPoints[icount].name="Point"+icount;
}
```

```
// ( GetObjectByName and GetName are user defined functions)
// Creating beams
// Stepping in X, Y and Z direction
    for (i = 0; i < NumX-1 ; i++) {
        for (j = 0; j < NumY-1 ; j++) {
            for (k = 0; k < NumZ-1 ; k++) {
                var aBeam ;
                aBeam = Beam(GetObjectByName(0,i,j,k), GetObjectByName(0,i+1,j,k));
                aBeam.section = Box1400;
                aBeam.material = S275;
                Rename(aBeam, GetName(1,i,j,k));
            }
        }
    }
```

- Set X-coordinate of some points

```
var MyPoints = new Array();  
MyPoints[0] = Point(0, 0, 1.0);  
MyPoints[1] = Point(0, 0, 2.0);  
MyPoints[2] = Point(0, 0, 3.0);  
//  
for (var MyPoint in MyPoints) { MyPoint.x = 2m; }
```

- Print length of all straight beams

```
for(var a in ModelObjects)  
    { if(a.supportsType(typeStraightBeam))  
        Print(a.Length); }
```

## ■ JScript built-in functions

GetObject

```
MyBook = GetObject("C:\\TestDir\\TestBook.xls");
```

```
Elevation1 = Length(MyBook.Worksheets ("sheet1").Range("C8").Value);
```

-Works for COM objects e.g. Microsoft Office documents

## ■ GeniE Functions

```
End1 = GetNamedObject("MainLegP"+i);
```

```
ReadCommandFile("Input.js");
```

Plus many more...

Most GeniE commands are functions that the various objects support  
e.g. the copyTranslate function for a plate

```
Pl5 = Pl1.copyTranslate(Vector3d(2 m,0 m,6.23 m));
```

## ■ Example:

// Function to transform a vector in local coordinate system to global coordinates

```
function VecTra(LocX, LocY, LocZ, LocalCoordSys)
```

```
    // Input is local vector X,Y,Z and localsystem
```

```
    // Returns global X,Y,Z vector
```

```
{
```

```
    return GlobalVector = LengthVector3D(  
        LocalCoordSys.xVector.normalise()*LocX +  
        LocalCoordSys.yVector.normalise()*LocY +  
        LocalCoordSys.zVector.normalise()*LocZ);
```

```
}
```

// Example - move beam end in beams local coordinates

```
Bm1 = Beam(Point(2.5 m,0 m,0 m), Point(7.5 m,7.5 m,0 m));
```

```
MyCord = Bm1.localSystem();
```

```
Bm1.setEndOffset(2,VecTra(1 m ,1 m ,0 m , MyCord));
```



```
// Function to make a name by adding four strings from  
// name arrays Nam2[ ], Nam3[ ], Nam4[ ],  
function GetName (N1,N2,N3,N4) { return(N1+Nam2[N2] +Nam3[N3] +Nam4[N4]); }
```

```
// then use GetName to name some points  
function MakePoints (NumX, NumY, NumZ, Step)  
{  
    var i, j, k, aPoint; // Stepping in X, Y and Z direction  
    for (i = 0;i< NumX ; i++)  
    { for (j = 0;j< NumY; j++)  
        { for (k = 0; k < NumZ; k++)  
            {  
                X1 = i * Step;  
                Y1 = j * Step;  
                Z1 = k * 0.6 * Step;  
                aPoint = Point(X1, Y1, Z1);  
                aPoint.name = GetName("Point",i,j,k);  
            }  
        }  
    }  
}
```

## ■ JScript Math object - methods

abs , acos , asin , atan , atan2 , ceil , cos , exp , floor , log , max , min ,  
pow , random , round , sin , sqrt , tan

## ■ Example:

```
Xcoord = (-1)*Math.abs( Math.sqrt( Math.abs(Math.pow(Radius1.toDouble(),2) -  
Math.pow(Length(YCord-Elev2).toDouble() ,2)))) +  
Length(Radius1 + WidePlat).toDouble;
```

if your variable is of type “Length” you must use toDouble when you use it as input to the Math functions.

Length(myMeasure) - converts to length

myMeasure.toDouble – converts to number

```
MyBook = GetObject("C:\\WorkSpace\\MyWorkbook.xls");  
// Note regexp escape sequence \\ to get \ in path  
MyBook.Worksheets("sheet1").Activate;  
MyBook.Windows(1).Visible="True";  
// Writing an Array to EXCEL  
var MyData = new Array();  
MyData[1] = 100;  
MyData[2] = 200;  
MyData[3] = 300;  
MyData[4] = 400;  
NumberOfData = MyData.length;
```

```
// Write data from GeniE to a Excel sheet
Row = 5;
Col = 3;
//
for (i = 1;i< NumberOfData; i++)
{
    MyBook.ActiveSheet.Cells((Row-1),Col).Offset(i,0).Value = MyData[i];
}
//
// Read some data back to GeniE
aText = MyBook.Worksheets("sheet1").Cells(7,5).value;
```

- Defining a Frame class with a function to calculate area

```
class Frame {  
    constructor function Frame(w,h) {width=w;height=h;}  
    function frame_area() {return width*height;}  
    var width;  
    var height;  
}
```

```
frame1 = new Frame(4.0, 6.0);
```

```
Print(frame1.frame_area());
```

```
-> 24.000000
```

## ■ Example:

A class for a line object in two dimensions with a function to find the point of intersection with another line

```
// Define a class for a point in the X,Y plane
```

```
class Point2d {  
    constructor function Point2d(x,y) {m_x=Length(x);m_y=Length(y);}  
    function X() {return m_x;}  
    function Y() {return m_y;}  
    var m_x,m_y;  
}
```

# and the Line class...

```
class Line2d {  
    var m_start,m_end;  
    constructor function Line2d(start,end) {m_start=start;m_end=end;}  
    function Start() {return m_start;}  
    function End() {return m_end;}  
    function intersect(other) {  
        ua1 = (other.End().X() - other.Start().X()) * (Start().Y() - other.Start().Y()) - (other.End().Y() -  
            other.Start().Y()) * (Start().X() - other.Start().X());  
        ua2 = (other.End().Y() - other.Start().Y()) * (End().X() - Start().X()) - (other.End().X() -  
            other.Start().X()) * (End().Y() - Start().Y());  
        ua = ua1 / ua2;  
        x = Start().X() + ua * (End().X() - Start().X());  
        y = Start().Y() + ua * (End().Y() - Start().Y());  
        return new Point2d(x,y);  
    }  
}
```

# Creating two line objects...

```
// Creating two line objects and a point at the intersection  
l1=new Line2d(new Point2d(0,10m),new Point2d(5m,0));  
l2=new Line2d(new Point2d(10m,0),new Point2d(0,5m));  
p=l1.intersect(l2);
```



- To get a template for report journal do
  - File > Create Report
  - and make sure “Journal Report Generation” is checked
  - This will give you something like:

```
Case_11.add(ChapterStructure());  
Case_11.element(1).add(TableBeamCoordinate());  
Case_11.element(1).add(TableBeamProperty());  
Case_11.element(1).add(TableBeamHydroProperty());  
Case_11.element(1).add(TableBeamEccentricity());
```

# Adding figures to a report

```
// Make a function plotResult to plot VonMises stresses for "loadcasein" on a set "setin"
// returns a plot Figure object
function plotResult(loadcasein,setin) {
    // Delete "Demo_ModelView" if it exists
    for(var object in ModelObjects) {
        if(object.supportsType(typeModelView) && object.name()=="Demo_ModelView")
            { Delete(object); }
    }
    ModelView_temp = ModelView();
    ModelView_temp.addElement(DisplayConfiguration ("Results - with Mesh", moPaper));
    ModelView_temp.addElement(ResultPresentation());
    ModelView_temp.resultPresentation.resultComponent = rsStress;
    ModelView_temp.resultPresentation.calculationType = rsVonMises;
// Continue...
```

# Reports - continued...

```
ModelView_temp.resultPresentation.optionMinmax = false;
ModelView_temp.resultPresentation.optionValues = false;
ModelView_temp.name = "Demo_ModelView";
ModelView_temp.addElement(VisibleModel());
myloadcase = GetNamedObject(loadcasein.name);
myloadcase.setCurrent();
if( setin.supportsType(typeSet)) {
    Demo_ModelView.visibleModel.include(setin);
    Demo_ModelView.activate(); }
Graphics.fitModel();
var Plottitle = "Loadcase " + loadcasein.name() + " - Part " + setin.name() + " - Von Mises
    Stresses";
var Plotfile = loadcasein.name() + setin.name() + ".jpg";
Graphics.saveImage(Plotfile);
var NewPlot = Figure(Plottitle , Plotfile);
return NewPlot;
}
```

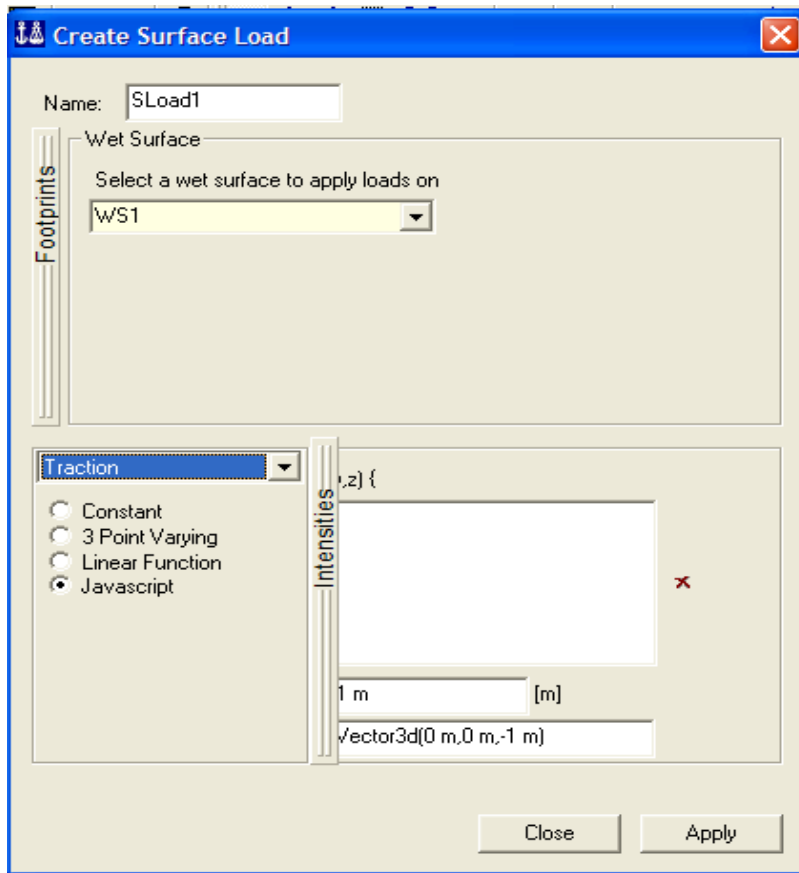
# Using the function plotResult

```
// Using the function plotResult to make a report
//
Case_1 = Report("Case_1");
Case_1.add(ChapterStructure());
Case_1.element(1).add(TablePlateCoordinate());
Case_1.element(1).add(TablePlateProperty());
Case_1.element(1).add(TableSupportBoundary());
Case_1.add(plotResult(Operation,UpperDeck));
Case_1.add(plotResult(Storm,UpperDeck));
Case_1.saveAs("Case_1.doc", mrWordXML);
```

- Once you have the predefined plot functions adding plots to the report is easy

# Load Intensity by JScript

- The intensity of line and surface loads may be given by a JScript function
- E.g. GeniE menu; Insert > Explicit Load > Surface Load...



- The dialogue takes a JScript function as input
- The function for surface loads may use the current x, y & z coordinate as input
- `pressureFunction(x y z)`  
`{ return your_function...}`
- The function for line loads may use the relative length along the line as input
- `component1Dfunction(param)`  
`{ return your_function...}`

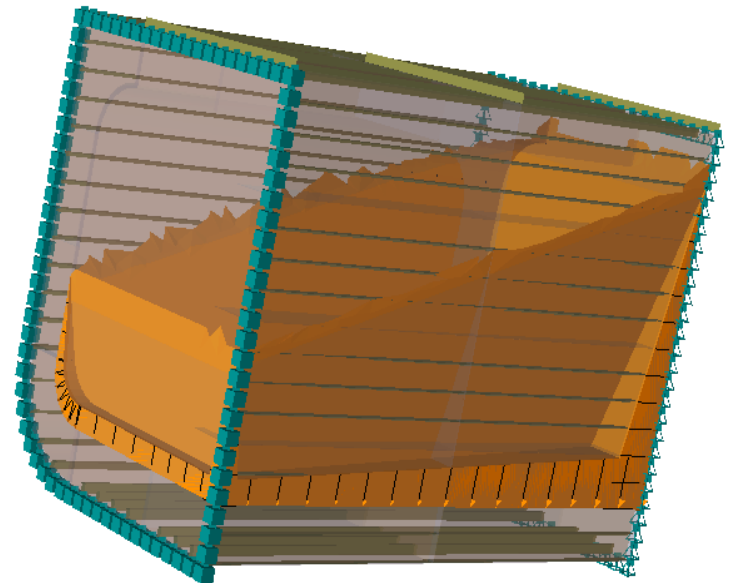
- Line Component Load:  
return Vector3d(1N/m,x\*2N/m<sup>2</sup>,0);
  - //input x,y,z, all of type Length
  - //output type Vector3d(ForcePerLength,ForcePerLength,ForcePerLength)
- Line Component Load - Parametric:  
return Vector3d(1N/m,param\*2N/m,0);
  - //input t, of type Number (unitless)
  - //output type  
Vector3d(ForcePerLength,ForcePerLength,ForcePerLength)
- Line Temperature Load:  
return 1delC\*y.toDouble();
  - //input x,y,z, all of type Length
  - //output TempDiff
- Line Temperature Load - Parametric:  
return param\*10delC;
  - //input t, of type Number (unitless)
  - //output type TempDiff

- Surface Pressure:  
return  $z * 1 \text{ G} * 1025 \text{ kg/m}^3$ ;
  - //input x,y,z, all of type Length
  - //output type ForcePerArea
  
- Surface Component Load:  
return Vector3d(1N/m<sup>2</sup>,x\*2N/m<sup>3</sup>,0);
  - //input x,y,z, all of type Length
  - //output type Vector3d(ForcePerArea,ForcePerArea,ForcePerArea)
  
- Surface Traction - Example function:
  - return 15N/m<sup>2</sup>\*Math.cos(x.toDouble());
  - //input x,y,z, all of type Length
  - //output type ForcePerArea

# Load Intensity by JScript - Example

```
/* Function for generating a hydrostatic pressure in a compartment for  
  20 deg. heel about x-axis and 4.5 m draught at origin  
- Define a wet surface.  
- Insert a pressure load on the wet surface  
- Set intensity to Javascript and paste the script below into the script window in the  
  pressure dialogue
```

```
*/  
HeelAngle = 20 ;  
Draught = 4.5 m;  
//  
HeelAngleRad =(HeelAngle*Math.PI)/180;  
Zlocal=(z*Math.cos(HeelAngleRad)) -  
  (y*Math.sin(HeelAngleRad));  
if ( Zlocal < Draught)  
{  
  return 1 G * 1025 kg/m3 * (Draught - Zlocal);  
}  
else return 0;
```





- GeniE has limited JScript functions for object name handling  
( from Bm3 to Bm34 step 3 )  
Automatic naming of new objects ( next beam-name )
- JScript does not support file operations
  - but you can read and write to Excel etc.
- Custom dialogues and buttons
  - May be available in future versions
  - New .net based scripting is under evaluation
- Read input data to user functions from GeniE by cursor selection



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