

Sesam User Course

JScript in GeniE command input
Parametric modelling

Revised: 1 July 2009

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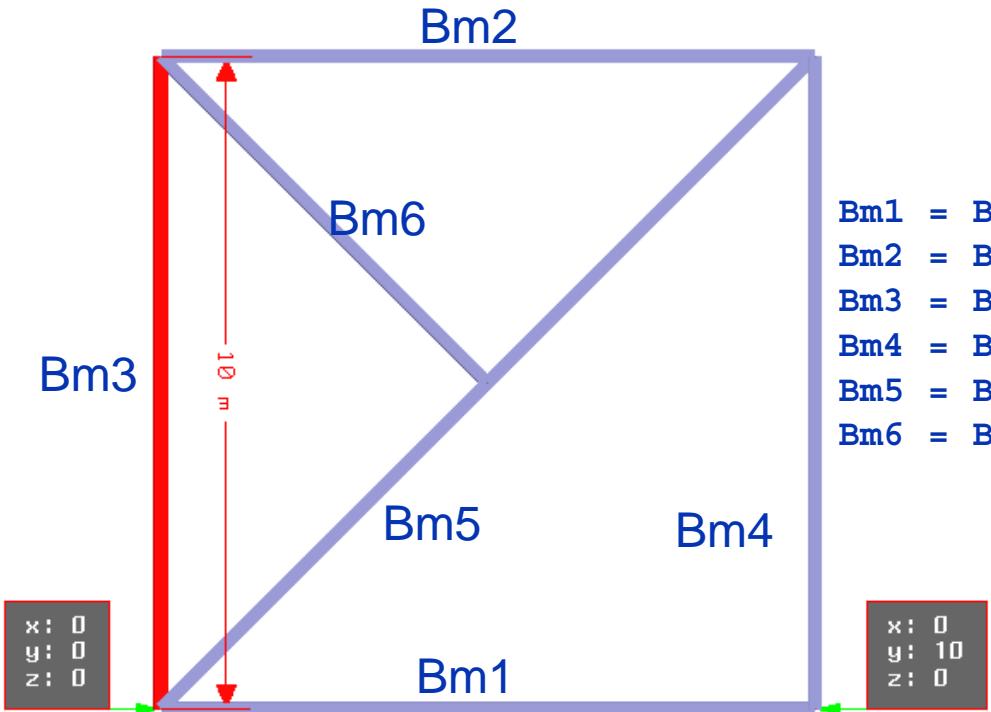
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- Some of the content require that you have access to the file “Frame.js”

Applications of JScript in GeniE

- Develop custom engineering applications
 - Script that controls GeniE and other programs
- Perform standard operations
 - Setting up a new workspace
 - Set code check parameters
 - Reporting
- Create models
 - Well organized model
 - Steady progress
 - Robust against changes
 - Parametric modeling
- Extensive model updates
 - Efficient
 - Quality control
- Distributed loads
 - Load intensity as JScript

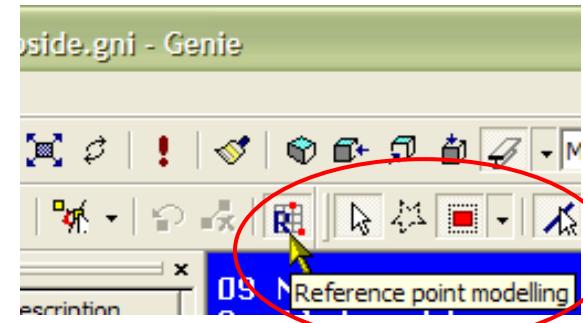
Parametric models in GeniE

- Can be combination of variables and reference point modelling



```
Bm1 = Beam(Point(0m,0m,0m),Point(0m,10m,0m));  
Bm2 = Bm1.copyTranslate(Vector3d(0m,0m,10m));  
Bm3 = Beam(Bm1.end1,Bm2.end1);  
Bm4 = Beam(Bm1.end2,Bm2.end2);  
Bm5 = Beam(Bm3.end1,Bm4.end2);  
Bm6 = Beam(Bm3.end2,Bm5.project(Bm3.end2));
```

The journal file refers to beam ends rather than explicit coordinate values

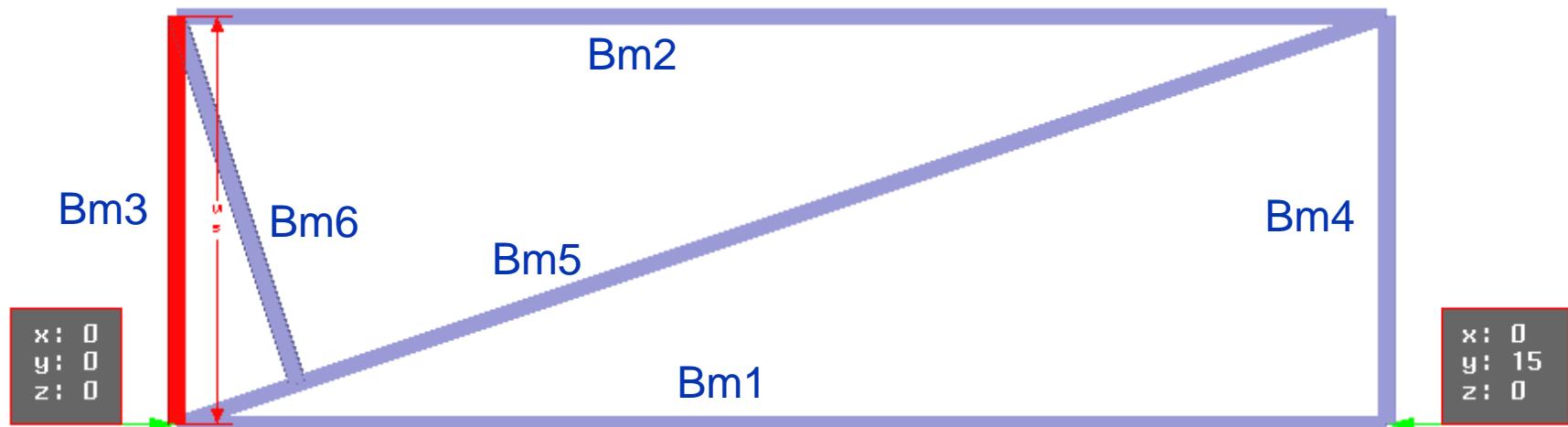


Parametric models in GeniE

- Modify input parameters and re-run journal file

- New length of Bm1: 15 m
- New copy vector: 5 m

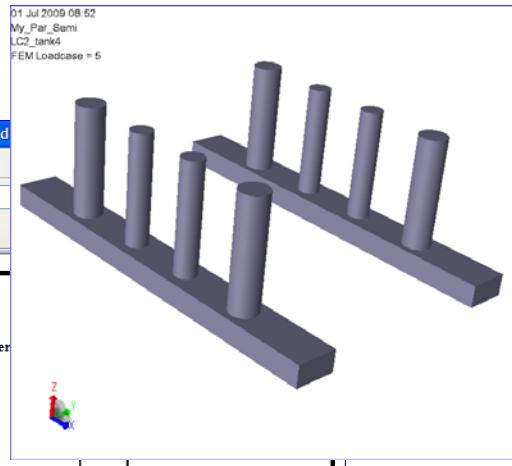
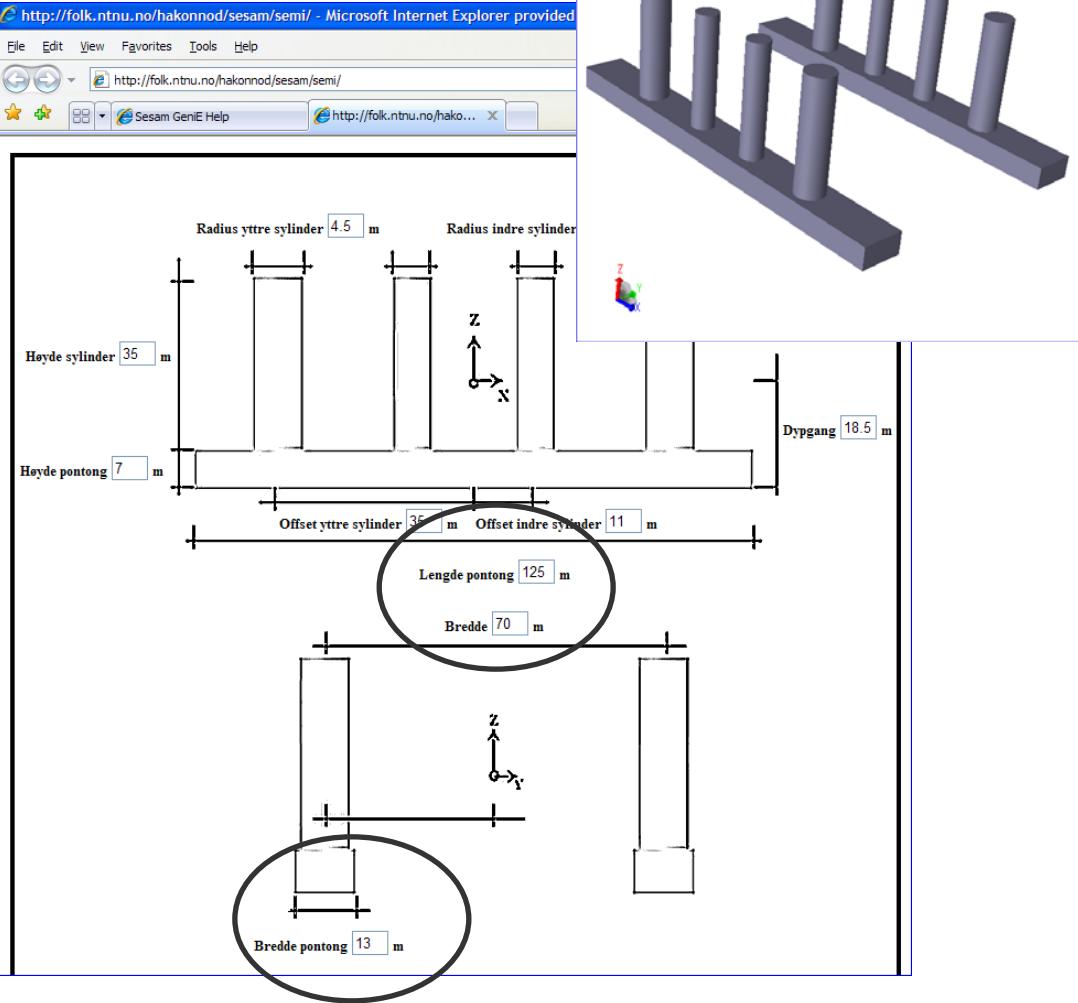
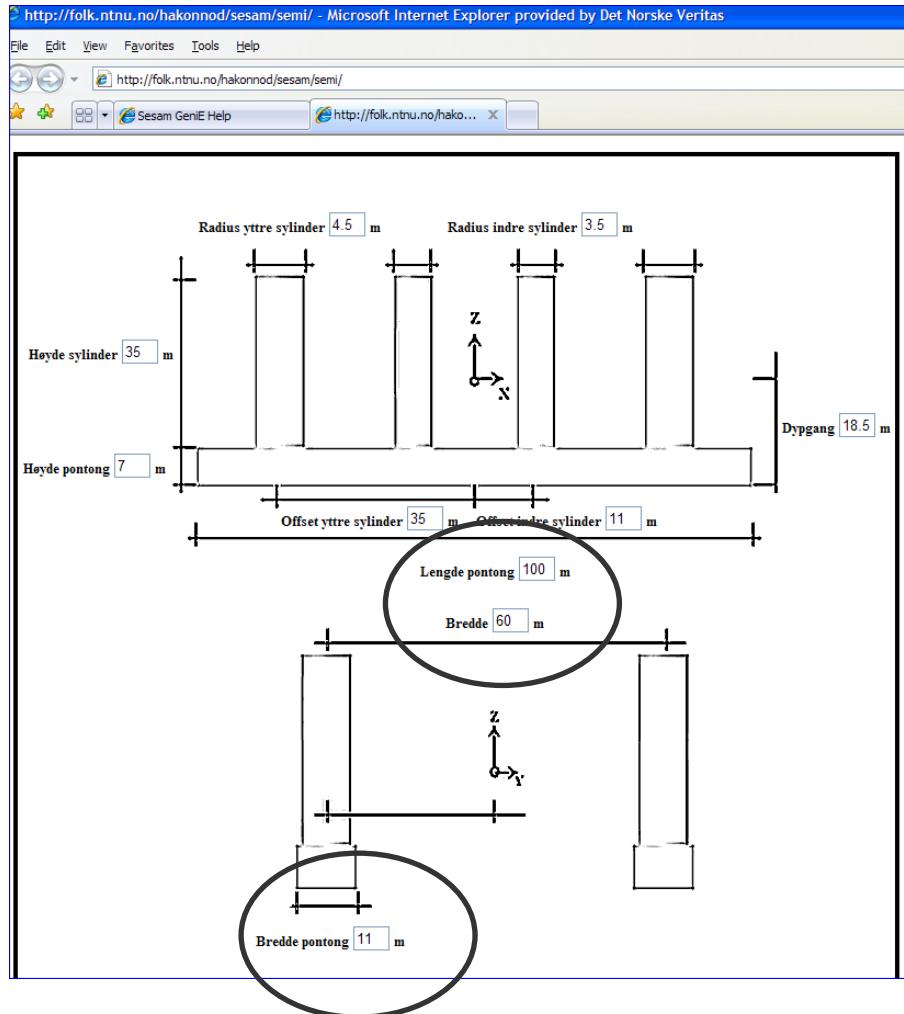
```
Bm1 = Beam(Point(0m, 0m, 0m), Point(0m, 15m, 0m));
Bm2 = Bm1.copyTranslate(Vector3d(0m, 0m, 5m));
Bm3 = Beam(Bm1.end1, Bm2.end1);
Bm4 = Beam(Bm1.end2, Bm2.end2);
Bm5 = Beam(Bm3.end1, Bm4.end2);
Bm6 = Beam(Bm3.end2, Bm5.project(Bm3.end2));
```



- New model automatically created
- Much more advanced models may be created
- GeniE comes with wizards using this feature
- 'Clean' js-file (File > Export > Genie journal file) loses reference point

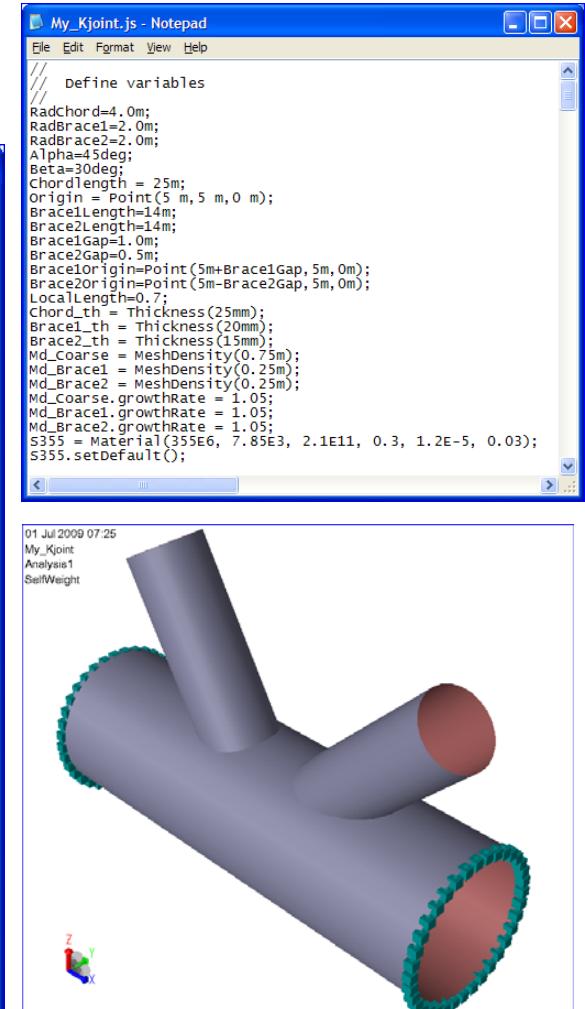
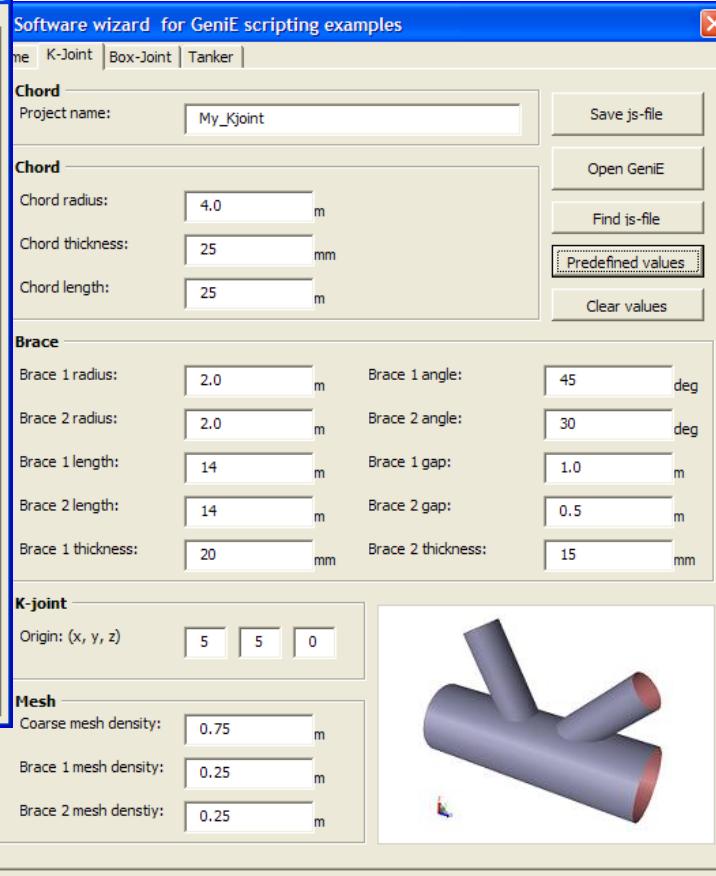
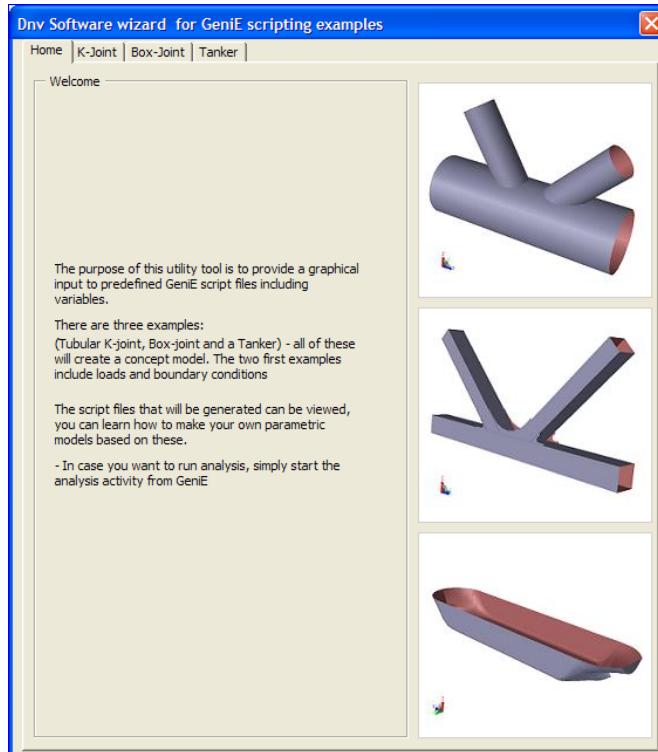
Custom Engineering Application

■ Example on student use at a university



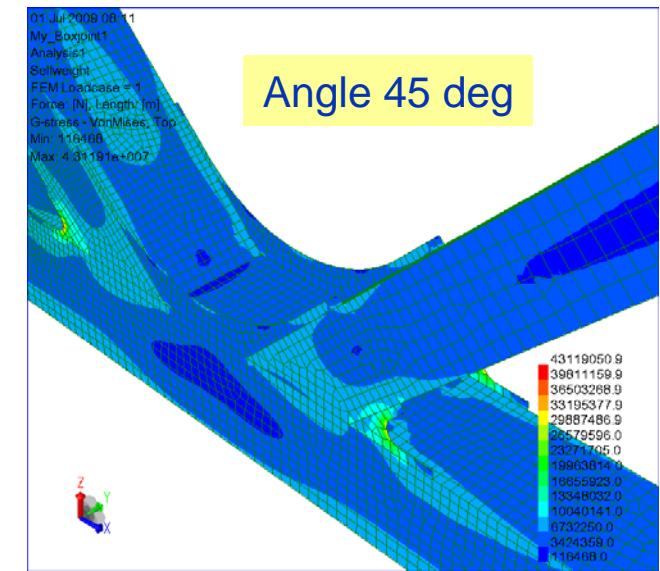
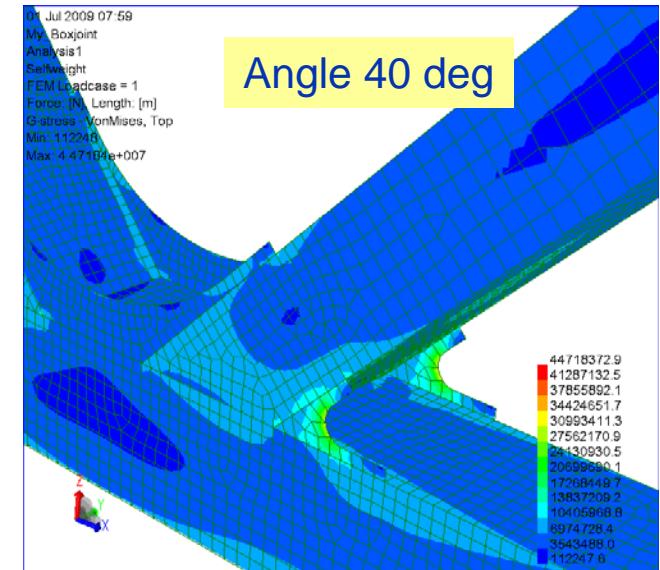
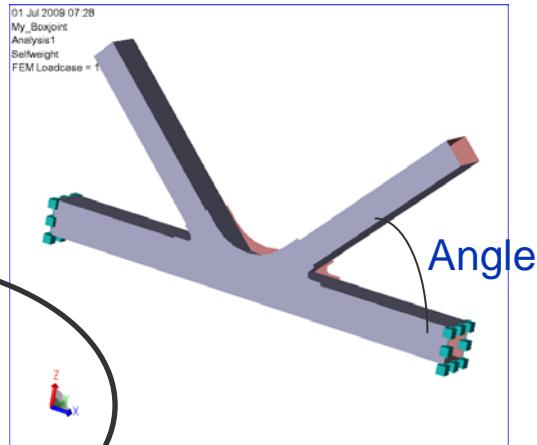
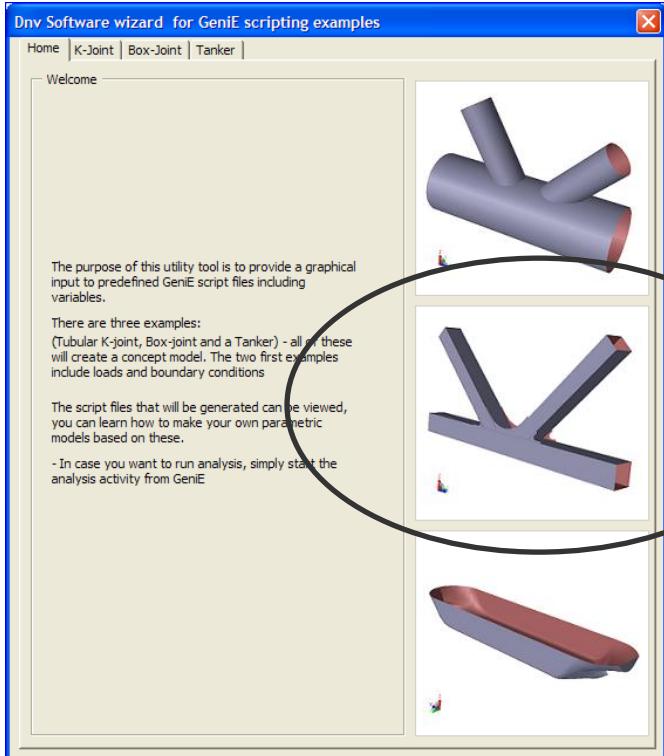
Custom Engineering Application

■ Parametric models available from Excel VBA



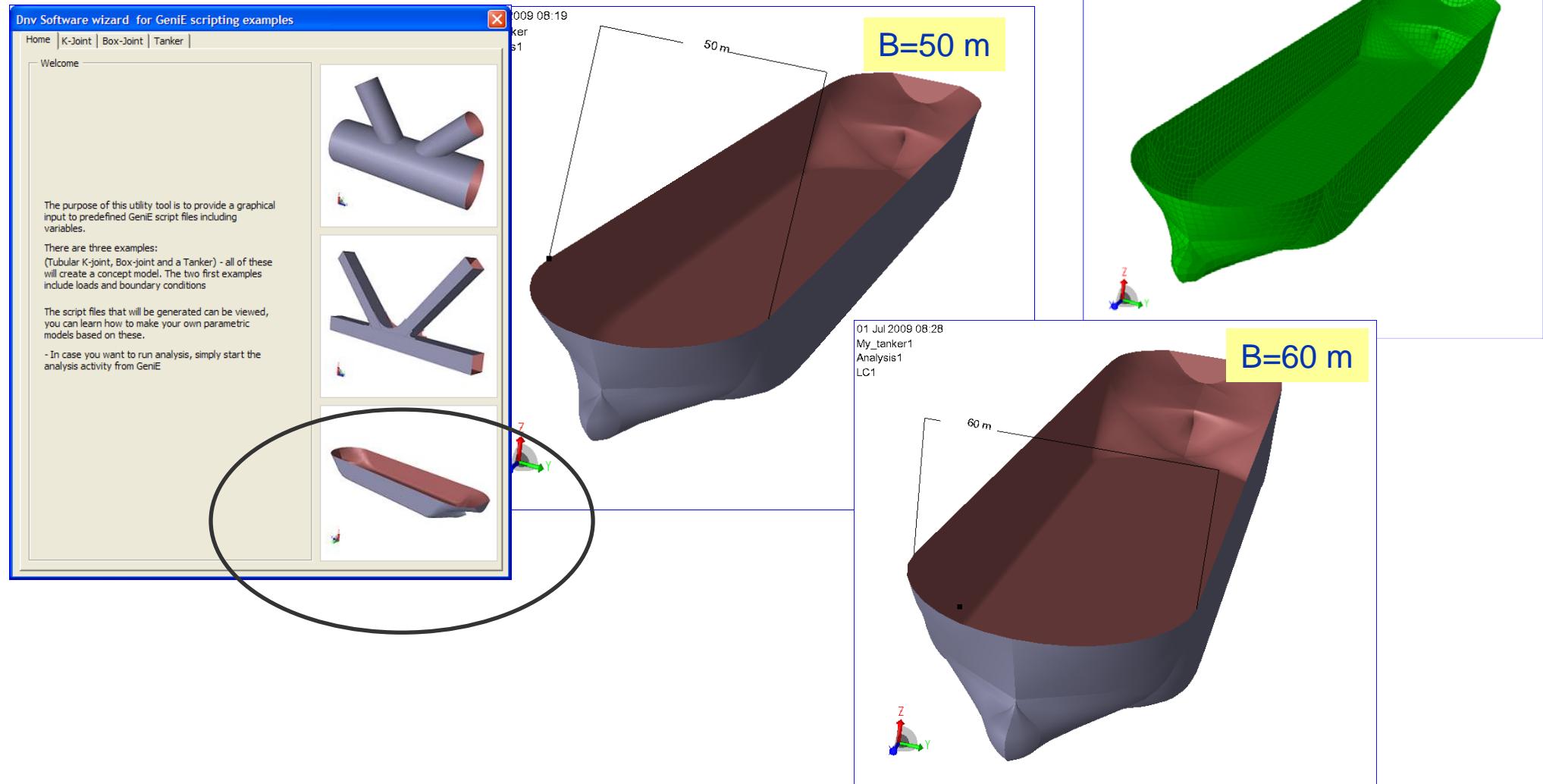
Custom Engineering Application

■ Parametric models available from Excel VBA



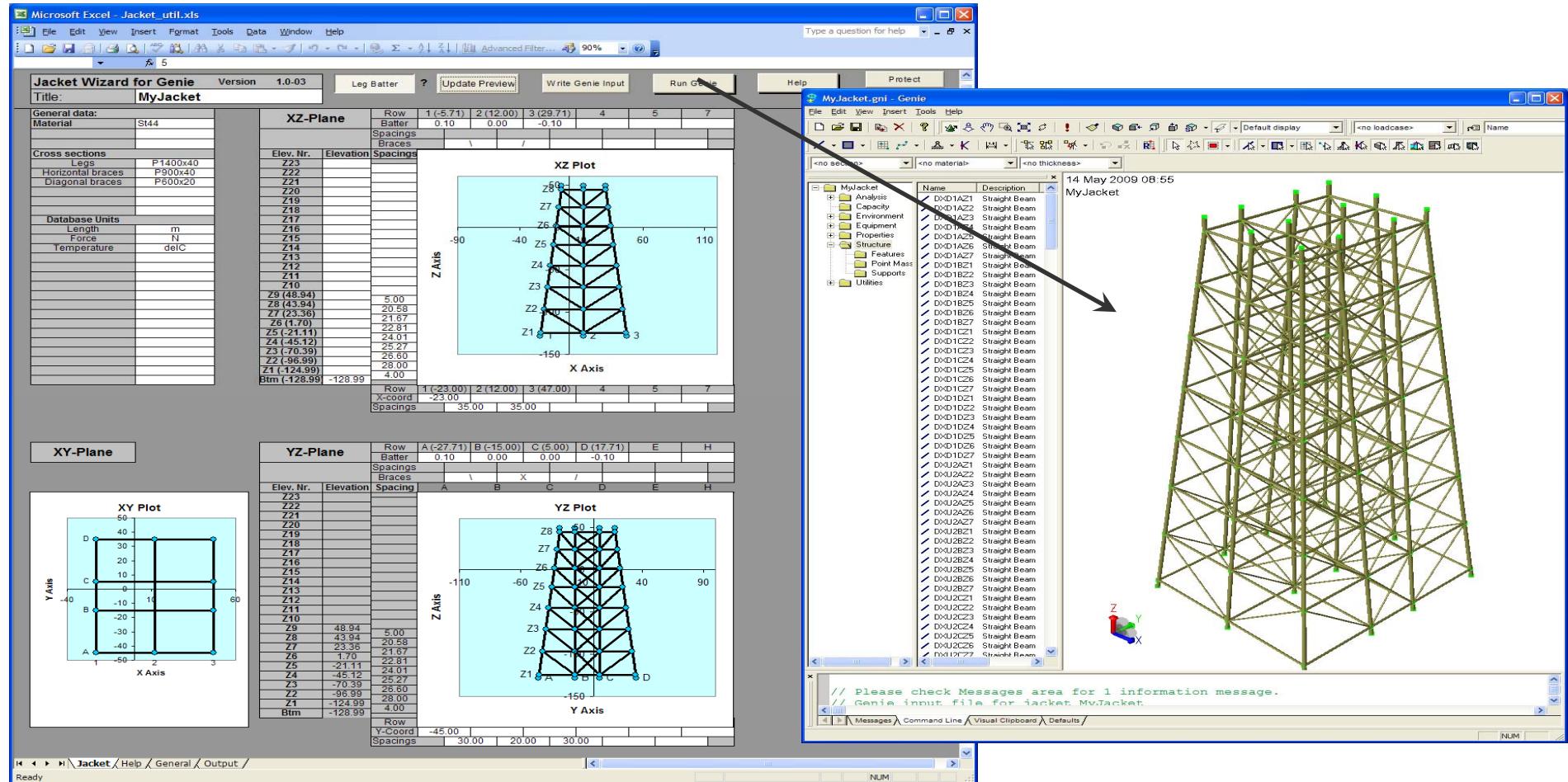
Custom Engineering Application

■ Parametric models available from Excel VBA



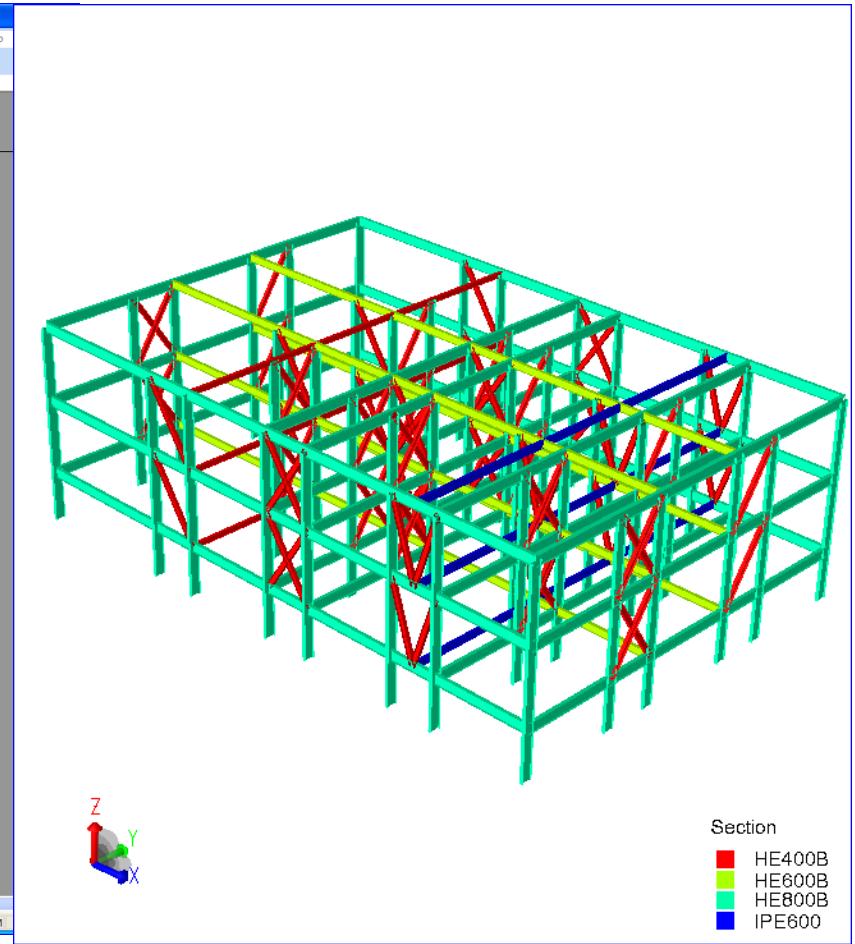
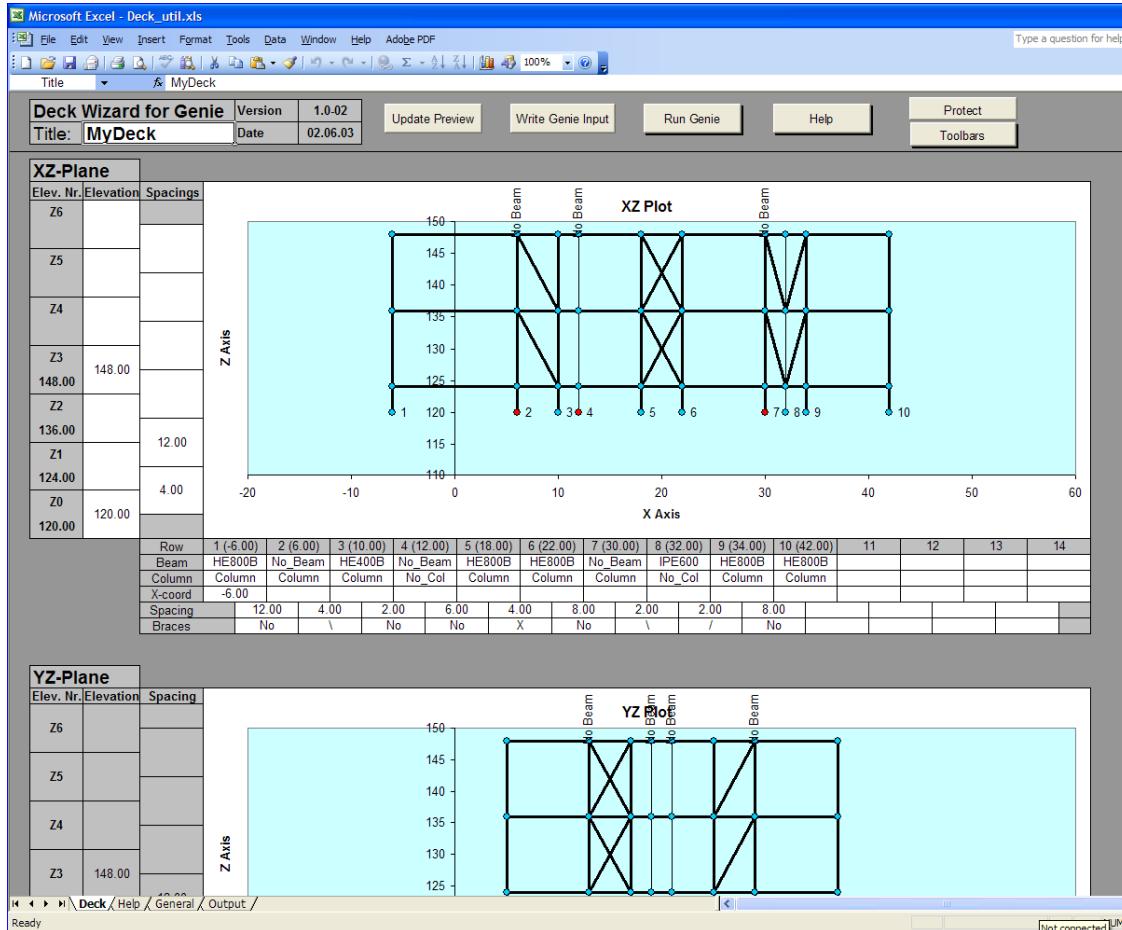
Custom Engineering Application

- Parametric models as part of the GeniE installation – jacket
 - Help -> Help Topics > Wizard templates



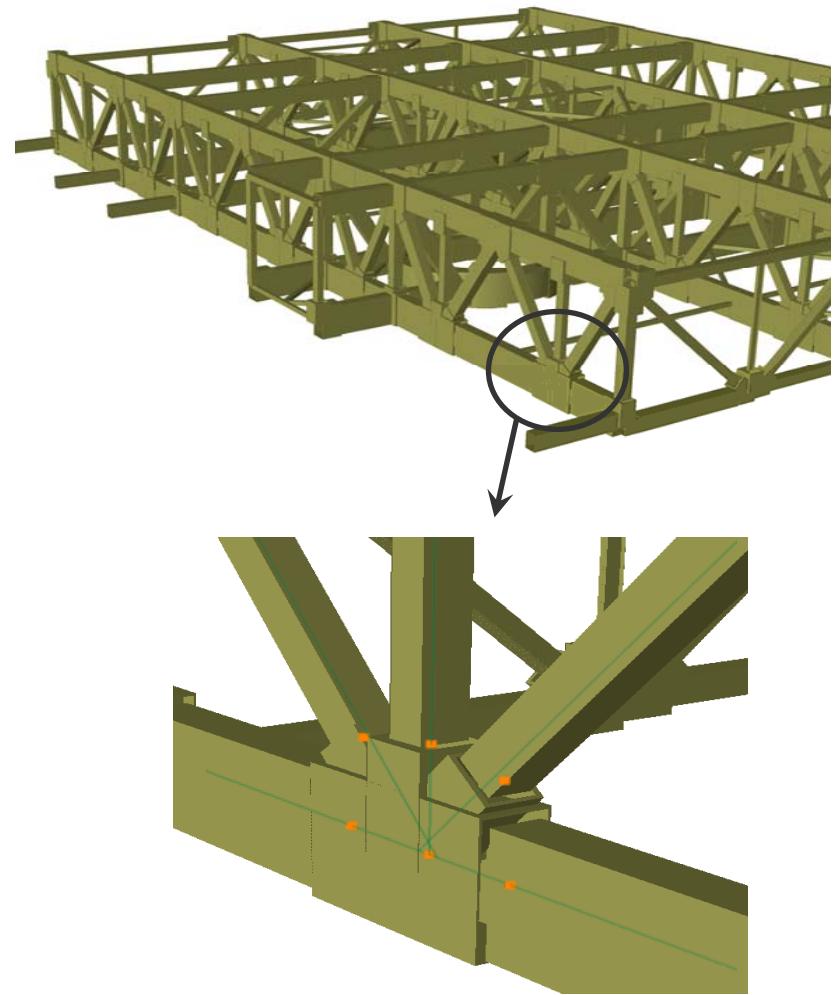
Custom Engineering Application

- Parametric models as part of the GeniE installation – topside
 - Help -> Help Topics > Wizard templates



Parametric models in GeniE

- Example: Extensive model update
 - Apply reinforcement and offset for gusset plates at all beam ends
- Make a function to
 - divide each beam into segments
 - set segment cross sections
 - set beam end offsets
- Call the function for each beam using tabulated data from drawings
- Faster, easier to check, more fun than manually editing hundreds of beams



Using a function to update the beam ends

```
// First list the beams to be updated          // Then call a user function to do the update
// in an array                                //
var Bea = new Array();                         DiagonalProp (Bea,End1_Offset,End2_Offset,
Bea[1] = Dx1A1;                             Main_Section,End1_X_center,End2_X_center,End
Bea[2] = Dx1C1;                             1_Section,End2_Section);
Bea[3] = Dx1E1;                            //
Bea[4] = Dx1G1;                            //
// and many more
//
// Define eccentricities and
// offsets for these beams
//
End1_X_center = 0.15 m;      =>      These data were listed in tables on the drawings
End2_X_center = 0.16 m;
End1_Offset = 1.837 m;
End2_Offset = 2.102 m;
Main_Section = D39;
End1_Section = Node_Diagonal_X;
End2_Section = Node_Diagonal_X;
```

DiagonalProp – function to update beams

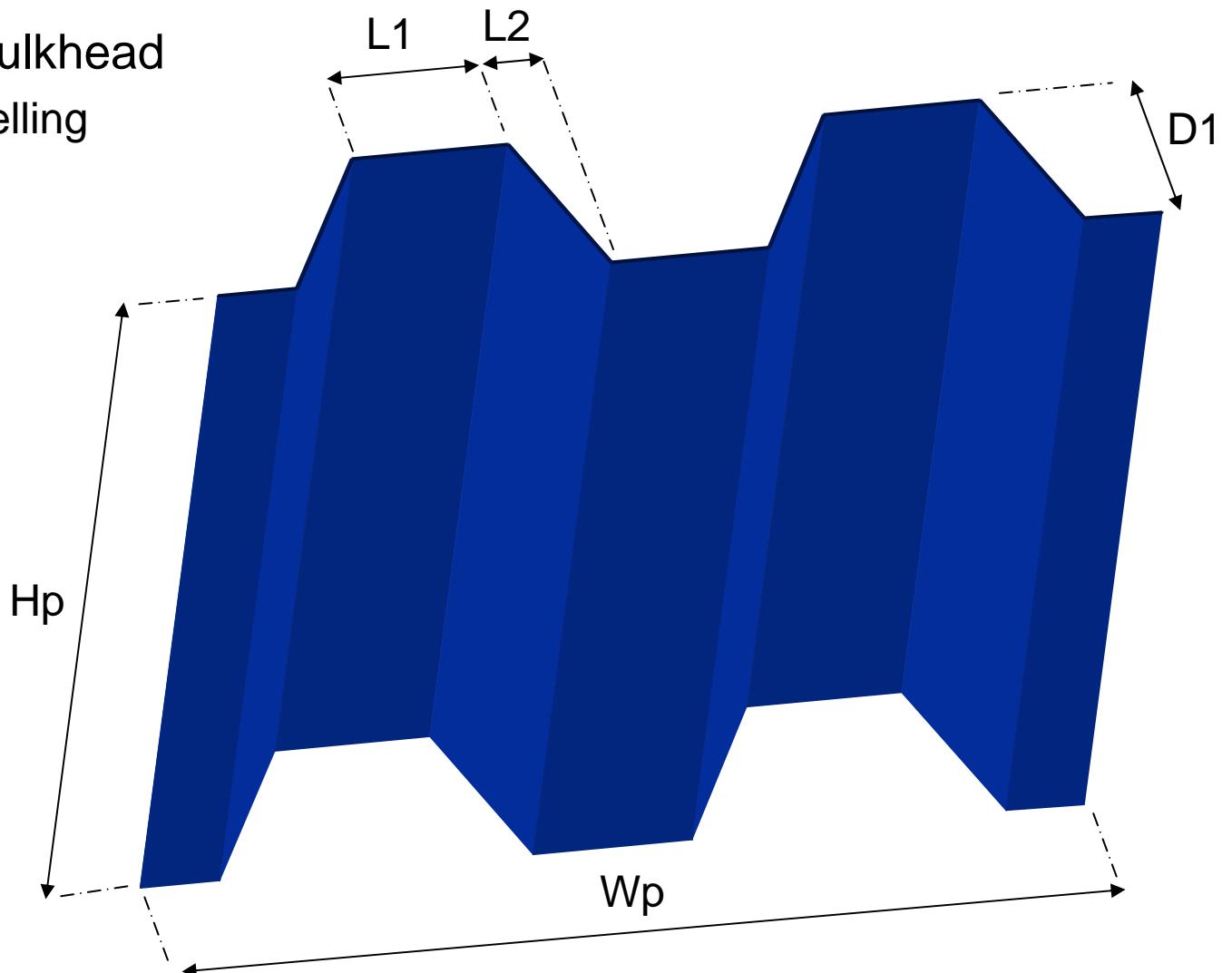
```
function DiagonalProp (Bea,End1_Offset,End2_Offset,Main_Section,  
End1_X_center,End2_X_center, End1_Section,End2_Section) {  
var NumBeam = Bea.length;  
for (i = 1; i < NumBeam ; i++) {  
    Bea[i].section = Main_Section;  
    //  
    // Eccentricities modelled by EndOffset  
    //  
    if ( End1_X_center != 0. m )  
        { Bea[i].setEndOffset(1,  
        Vector3d(End1_X_center, 0 m,0 m));  
    }  
    if ( End2_X_center != 0. m )  
        { Bea[i].setEndOffset(2,  
        Vector3d(End2_X_center, 0 m,0 m));  
    }  
// Continue on next page...
```

DiagonalProp – function continued...

```
// Set End1 Offset and/or End2 offset
// The beam is divided at relative position Lsegment / Lbeam
if ( End1_Offset != 0. m) {
    Bea[i].divideSegmentAt (1,(End1_Offset / Bea[i].length()));
    Bea[i].SetSegmentSection(1, End1_Section);
    if ( End2_Offset != 0. m) {
        Bea[i].divideSegmentAt
        (2,((Bea[i].getSegmentLength(2)-End2_Offset)/Bea[i].getSegmentLength(2)));
        Bea[i].SetSegmentSection(3, End2_Section);
    }
}
.... and similar for End2...
```

Parametric modelling - example

- Making a corrugated bulkhead
 - Reference point modelling and variables
 - Pure scripting



Parametric Modelling by Reference Point



MANAGING RISK

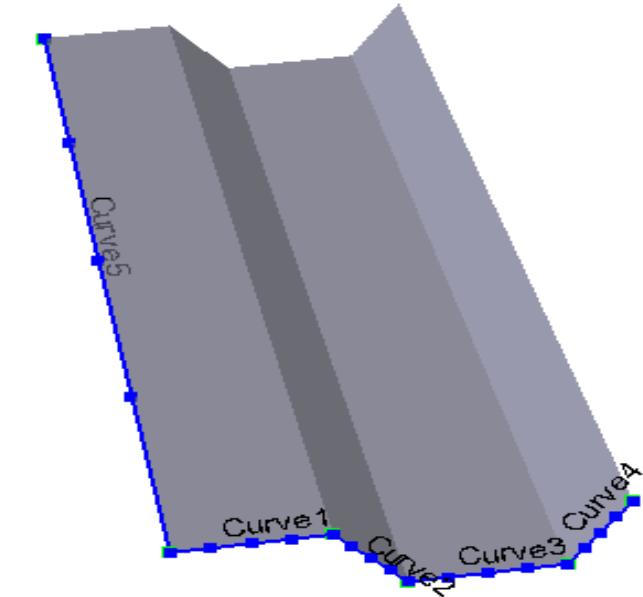


- Reference point modelling will journal
 - relative to other structure - Point1 = Curve1.curvePoint(1);
 - not actual coordinates - Point2 = Point(1 m,0.4 m,0 m);

- Reference point modelling can be used to make parametric models

// Read the measurements from a journal file or define yourself

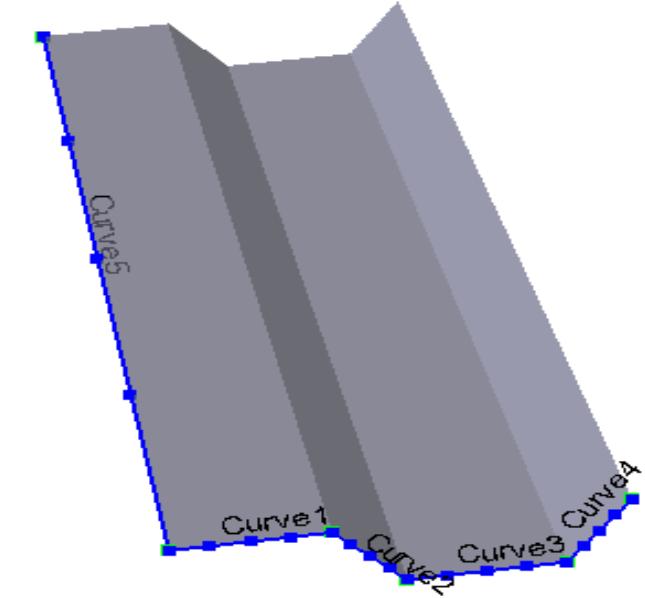
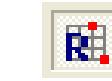
```
Hp = 6.23 m; // Height of plate  
Wp = 12.32 m; // Width of plate  
L1 = 700 mm; // Length of sub panel  
L2 = 300 mm; // Length of corrugation  
D1 = 400 mm; // Depth of corrugation
```



Parametric Modelling by Reference Point

// Then model interactively using reference point modelling

```
Point1 = Point(0,0,0);
Point2 = Point1.copyTranslate(Vector3d(L1,0,0));
Point3 = Point2.copyTranslate(Vector3d(L2,D1,0));
Point4 = Point3.copyTranslate(Vector3d(L1,0,0));
Point5 = Point4.copyTranslate(Vector3d(L2,-D1,0));
Curve1 = GuideLine(Point1, Point2, 3);
Curve2 = GuideLine(Point2, Point3, 3);
Curve3 = GuideLine(Point3, Point4, 3);
Curve4 = GuideLine(Point4, Point5, 3);
Point6 = Point1.copyTranslate(Vector3d(0,0,HP));
Curve5 = GuideLine(Point1, Point6, 3);
PI1 = SweepCurve(Curve1, Curve5);
PI2 = SweepCurve(Curve2, Curve5);
PI3 = SweepCurve(Curve3, Curve5);
```



Parametric modelling by scripting

- Start with a section defining input parameter values:

```
Hp = 6.23 m; // Height of plate  
Wp = 12.32 m; // Width of plate  
L1 = 700 mm; // Length of sub panel  
L2 = 300 mm; // Length of corrugation  
D1 = 400 mm; // Depth of corrugation
```

Parametric modelling by scripting

- Then use the parameter names in GeniE commands to create your model

```
var i = 0; // Counter for sub panels  
var j = 0; // Counter for corrugations = 4 sub panels  
var Curves = new Array(); // Guide curves at the base of the plate  
// Create sub panels  
do {  
    var StartP = (L1+L2)*2*j; // Start point for the next corrugation  
    if ( PartNr == 1 ) { Curves[i] = GuideLine(Point(StartP,0,0), Point((StartP+L1),0,0), 3);  
        rename(Curves[i], "Line_"+i);  
        LengthPlate = LengthPlate + L1;  
        PartNr = 2;}
```

- To update the model you only need to enter new parameter values

GeniE & JScript – what you need to know

■ Basic JScript

- Operators, data types, control flow, functions and objects

■ Basic GeniE commands

- GeniE objects, their functions and properties
- The commands you get when you work interactively

■ GeniE utility commands

- `ds1=DynamicSet(LimitInPlane(ZPlane3d(0));`
- `for(var sect in ModelObjects)`
- `if(a.supportsType(typeSection))`

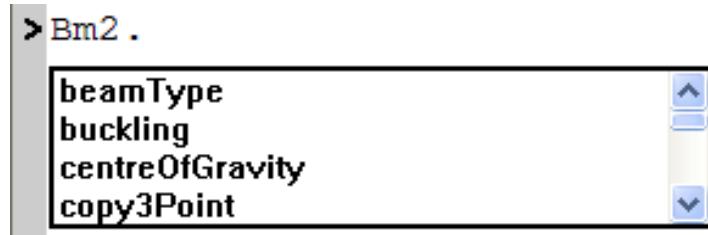
■ Practical applications

- Creating objects
- Setting and getting object properties
- Addressing subsets of your model
- Addressing objects by their name
- Creating your own functions

- JScript – Microsoft Developers network
 - [http://msdn.microsoft.com/en-us/library/hbxc2t98\(VS.85\).aspx](http://msdn.microsoft.com/en-us/library/hbxc2t98(VS.85).aspx)
- GeniE Help – Volume 6 and JScript Commands
 - Overview
 - The GeniE commands
 - Example:
 - Beam (three methods to create a beam)
 - Class Hierarchy
 - The GeniE objects and properties
 - Example:
 - NamedObject
 - Transformable
 - BasicConcept
 - BasicBeam
 - StraigthBeam

Documentation of GeniE JScript

- Run GeniE from GUI – look at the journal
- Use the Command window – tab completion



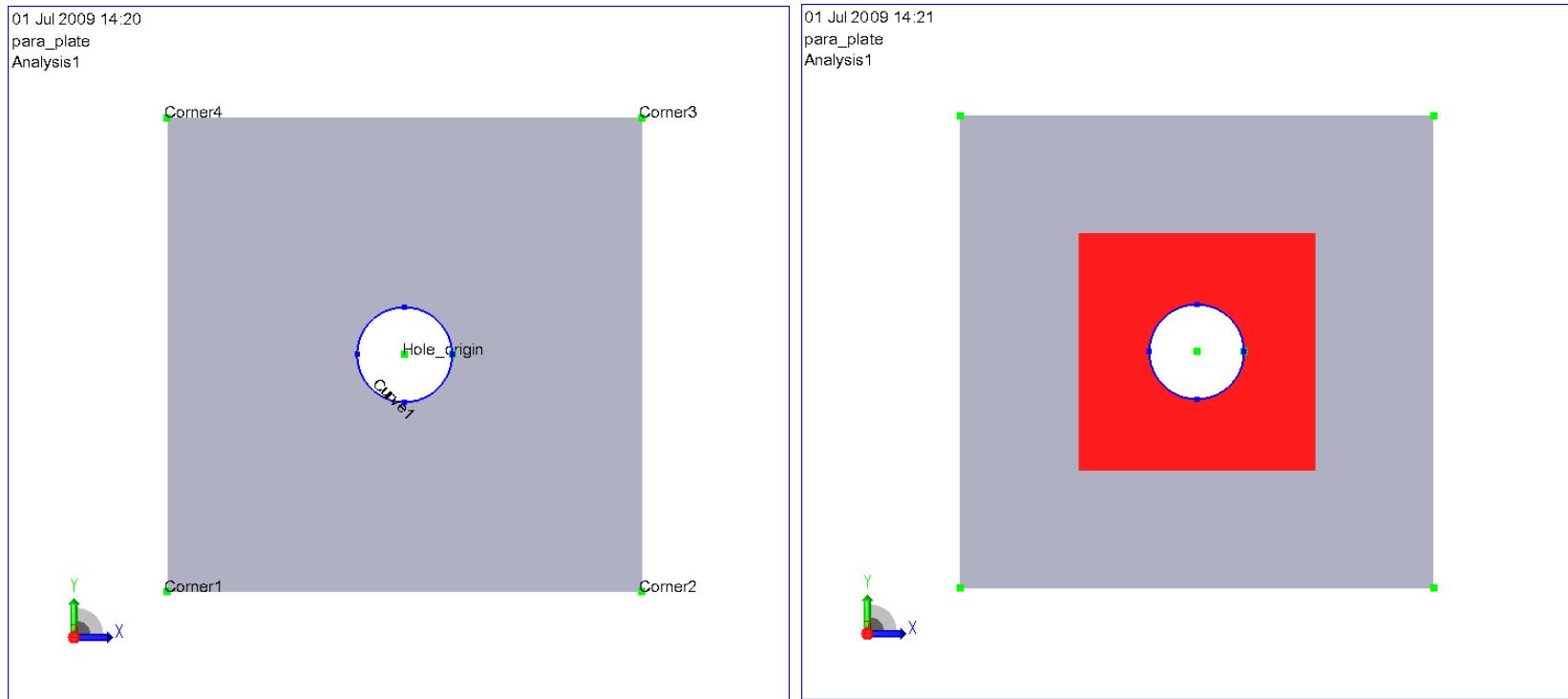
- Open the folder with GeniE Help files;
C:\Program Files\DNVS\GeniE\Help\jscript
in file explorer and search for word in file

Developing Scripts

- Use an editor to type the script file (Input.js)
- Then read the script into GeniE by
 - File > Read Command file
 - File > Recent Command files
 - Copy/Paste from editor to the GeniE command window
- Once you have tried a chunk of commands all variables, objects and functions will reside in the workspace until you close the workspace and create a new. To be sure use a new workspace each time you test your script.
- While developing your scriptfile you may
 - do things interactively in GeniE to get the command syntax
 - use the Command window > Tab completion to see available functions for your objects

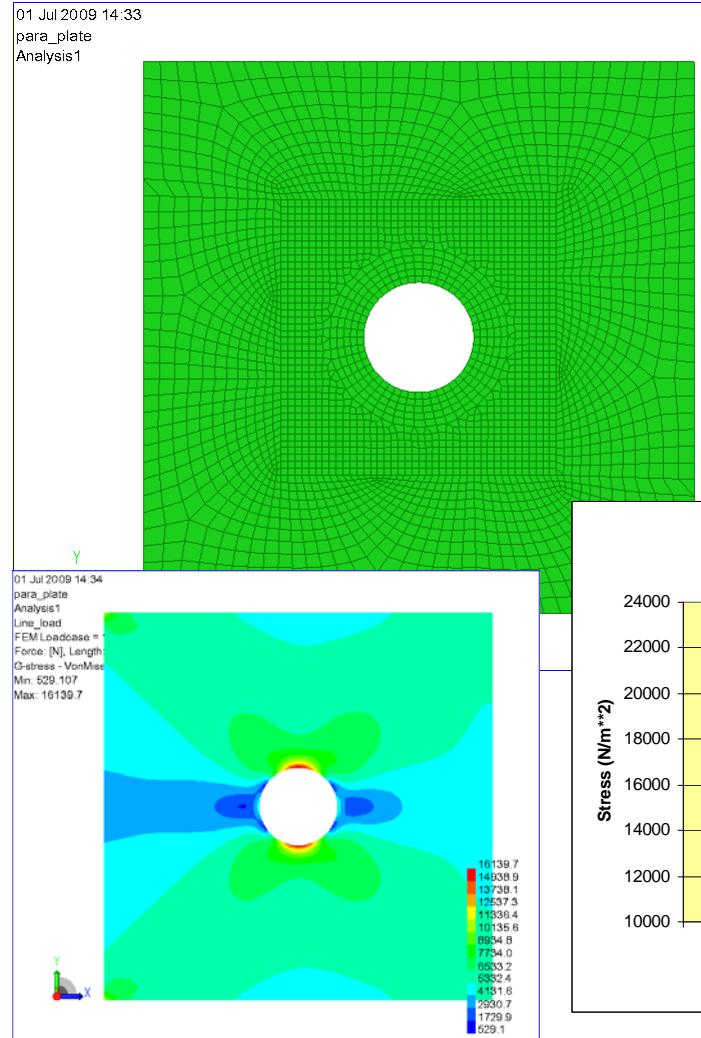
A practical example

- Make a plate with a variable hole – check the VonMises stresses for $R=0.5\text{m}$, 1.0m , 1.5m and 2.0 m
- The inner part has a refined mesh and is based on paver meshing
- This example includes the parametric input file “Param_plate_in.js”

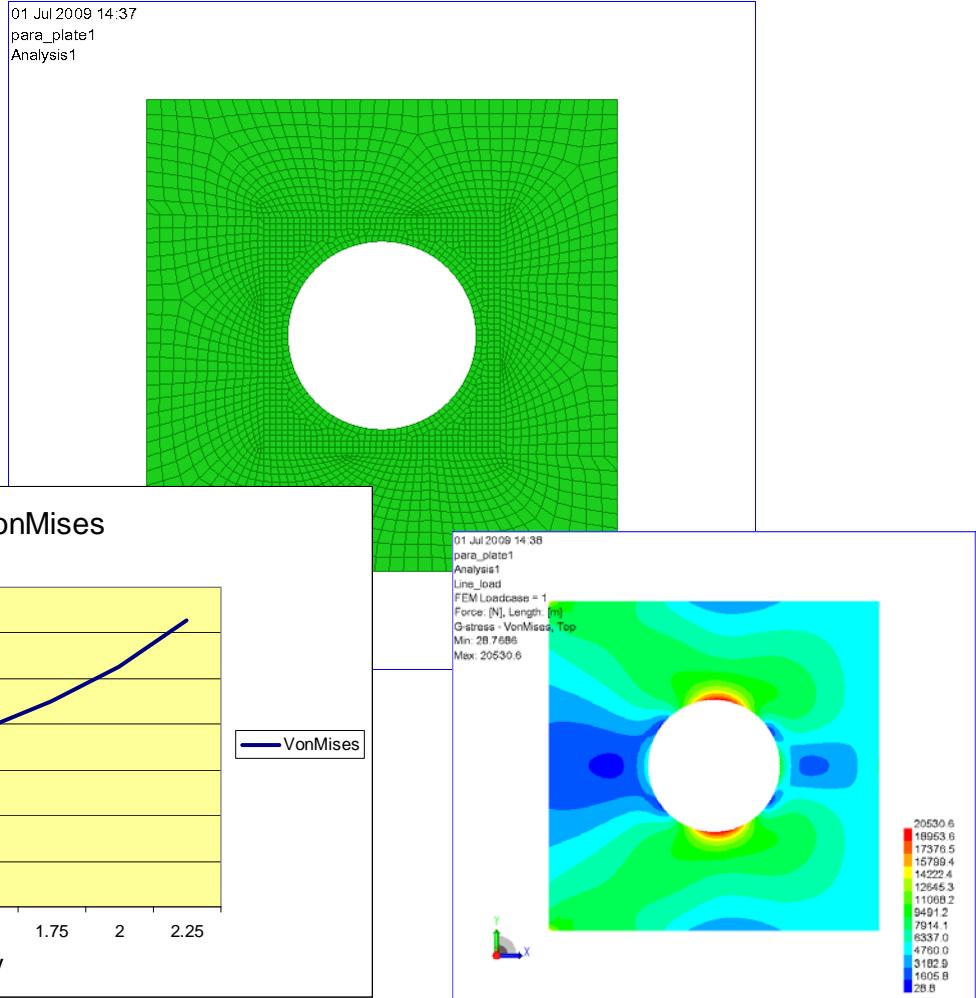


A practical example

- Radius 1.0 m -> VonMises 16139 N/m²



- Radius 2.0 m -> VonMises 20531 N/m²



A practical example

■ Follow the hints in the shown js-file - 1

```
Param_plate_in.js - Notepad
File Edit Format View Help

//*****
// TASK: TO DEFINE A PLATE WITH A HOLE TO SEE THE EFFECT OF VONMISES STRESSES WHEN MODIFYING THE HOLE RADIUS
// LOOK AT THE STRESSES FOR A RADIUS RANGING 0.5M, 1.0M, 1.5M AND 2.0 M
// THE RADIUS CAN NOT BE SET LARGER THAN 2.25 M UNLESS MODIFYING THE REFINED MESH ZONE
//*****


// Define variables
// Hole radius
Radius = 1.00m;
// Plate extension
Corner1 =Point(0m,0m,0m);
Corner2 =Point(10m,0m,0m);
Corner3 =Point(10m,10m,0m);
Corner4 =Point(0m,10m,0m);
// Position of plate origin
Hole_origin = Point(5m, 5m, 0m);
// Define the extent of the refined mesh zone
Distx1 = 2.5m;
Distx2 = 7.5m;
Disty1= 2.5m;
Disty2 = 7.5m;
// Make the plate
P11 = Plate(Corner1,Corner2,Corner3,Corner4);
// Create circle line used to cut plate and cut the plate
Point1 = Hole_origin.copyTranslate(Vector3d(Radius,0,0));
Curve1 = Guidelinecircle(Hole_origin, Point1, Corner4);
P12 = P11.divide(Curve1);
Delete(P12);
//
```

A practical example

■ Follow the hints in the shown js-file - 2

```
Param_plate_in.js - Notepad
File Edit Format View Help
Delete(p12);
// Divide the plate into refined mesh zone
// P12 = P11.divide(xPlane3d(DistX1));
P13 = P12.divide(xPlane3d(DistX2));
P14 = P12.divide(yPlane3d(DistY1));
P15 = P14.divide(yPlane3d(DistY2));
P11.join(P12);
P11.join(P13);
P11.join(P15);
P11.simplifyTopology();
// Define boundary conditions
// Sc1 = supportCurve(Modelcurve(Point(0 m,10 m,0 m), Point(0 m,5 m,0 m), Point(0 m,0 m,0 m)));
Sc1.localSystemRule = ConstantLocalSystem(LocalSystem(Vector3d(1 m,0 m,0 m), Vector3d(0 m,0 m,1 m)));
// Define mesh settings
// Md_fine = MeshDensity(0.125);
Md_fine.growthRate = 1.05;
Md_coarse = MeshDensity(0.5);
Md_coarse.growthRate = 1.05;
// Apply mesh settings
P14.meshDensity = Md_fine;
P11.meshDensity = Md_coarse;
// Define mesh rules and user paver meshing for internal part and mesh it first - use linearized edge meshing
GenieRules.Meshing.elementType = mp2ndorder;
GenieRules.Meshing.edgeMeshstrategy = LinearDistributionEdge;
Paver = MeshoptionFace();
Paver.meshstrategy = AdvancingFrontQuadMesher;
P14.meshoption = Paver;
//
```

A practical example

■ Follow the hints in the shown js-file – 2

```
// Define mesh priorities and mesh the fine zone first
//
Mesh_pri = MeshPriority();
Mesh_pri.addMeshPriority();
Mesh_pri.meshPriority(1).add(P14);
//
// Define analysis
//
Analysis1 = Analysis(true);
Analysis1.add(MeshActivity());
Analysis1.add(LinearAnalysis());
Analysis1.add(LoadResultsActivity());
Analysis1.step(1).meshPriority = Mesh_pri;
//
// Define properties and apply
//
S_355 = MaterialLinear(355000000 Pa, 7850 Kg/m3, 2.1e+011 Pa, 0.3, 1.2e-005 delc^-1, 0.03 N*s/m, 510000000 Pa);
Th_plate = Thickness(20mm);
P11.thickness = Th_plate;
P14.thickness = Th_plate;
P11.material = S_355;
P14.material = S_355;
//
// Define a line load
//
Line_load = LoadCase(Analysis1);
LLoad1 = LineLoad(Line_load, FootprintLine(corner2, corner3), Component1dLinear(Vector3d(100, 0 N/m, 0 N/m), Vector3d(100, 0 N/m, 0 N/m)));
//
// To run analysis manually start or to remove the comments // in the line below
//
//Analysis1.execute();
```

■ You can “cheat” by using the file “Param_plate_in.js”

For the advanced users

- The rest of this handout includes documentation for the advanced user who wants to learn how to make parametric models by pure scripting.

Basic JScript

- All commands end with a semicolon ;

- Comments

- /* Here is a block of comments
 - Another comment line
 - */
 - // Here is a single comment

- Print

- MyVariable = "Hello there";
 - Print("MyVariable = " + MyVariable);

- Operators

- + addition,
 - * multiplication,
 - ++ increment,
 - decrement

- Logical:

- < Less,
 - == Equal,
 - && And,
 - ! Not,

Variables and data types

- `var MyBeam`
 // Declaration of a new variable
- `var MyBeam, MyPlate`
 // Declaration of two new variables
- `var MyBeam = Beam(Point(1,0,24), Point(13,1,18));`
 // declaration and initialization
- JScript is a loosely typed language
 - Variables have no predetermined type
 - JScript variables get a type that corresponds to the type of value they contain

Basic JScript data types

■ Primary Data Types

- String
- Number
- Boolean

■ Composite

- Object
- Array

■ Special

- Null
- Undefined

GeniE data types

- All engineering objects have types
 - StraightBeam, Plate, SupportPoint, PointLoad + many more
 - Print(Bm1.supportsType(typeStraightBeam));
-> 1 (1 true, 0 is false)
- General GeniE types
 - Length, Mass, Vector3D, LocalSystem, Double and some more
 - Type Length & Mass support toDouble and toString
 - Radius = 2.34 m
 - Math.pow(Radius.toDouble(),2)

GeniE data types - some examples:

- Print(Bm2.end1.x());
 -> 5 m // that is, x is of type length
- Number versus Length
 - Point(3,4,5); // three numbers converted to lengths
 - Point(3+5.8, 4, 5); // adding two numbers is OK
 - Point(3m+5.8mm, 4, 5); // adding two lengths is OK
 - Point(3m+5.8, 4, 5); // adding a length + number gives error
 type + floating point
 - Point(3m*1.2, 4, 5); // Length * number is OK
 - Point(3m+Length(5.8), 4, 5);
 // The function Length will convert (5.8) to length
- GeniE can interprete several input formats
 - Point(3,4,5);
 - Point(Length(3)+5.8mm,4,5);
- Optional functions to change type - parseFloat, parseInt

Understanding the structure of GeniE commands

■ Native GeniE commands - Object notation

■ Create:

```
Bm1 = Beam(Point(4 m,20 m,0 m), Point(4 m,0 m,0 m));
```

(Beam is a constructor function to create an instance, Bm1, of the straigthBeam class)

■ Set property:

```
Bm1.section = W200X100;
```

■ Get property:

```
Print(Bm1.section.flangeThickness());
```

■ Use copy method:

```
Bm11 = Bm1.copyTranslate(Vector3d(0 m,0 m,1 m));
```

■ Setting and looking up properties

```
Bm1.setEndOffset(2,Bm2.localSystem.xVector.normalise()*(-1.3));
```

Basic JScript within GeniE commands

■ The GeniE command interpreter will recognize

- basic GeniE commands
- basic JScript commands
- a mix of GeniE and JScript commands

■ Examples

```
Bm114 = Bm94.copyTranslate  
(Vector3d( 2.3 m , 0.3 m ,10 m));
```

```
Bm114 = Bm94.copyTranslate  
(Vector3d( 2.3 ,L1 + 0.3 m , Bm2.end1.x()/4));
```

```
Bm115 = Beam(Point1,Point2);
```

```
Bm115 = Beam(Point(Math.abs(Math.pow (Bm62.end1.y.toDouble(), 2)),H1,1200  
mm),Bm62.end2()));
```

When the interpreter finds a number not followed by an operator it will interprete the next word as a unit.

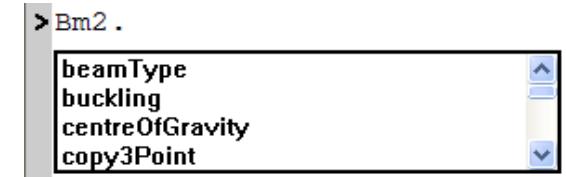
The number will get type from the unit.

■ Object names versus variable names

```
// Creating beams in a loop...
for (i = 1;i<(Floors+1); i++) {
// Get a point by it's name
End1 = GetNamedObject("Point"+i);
End2 = GetNamedObject("Point"+(i+1));
aBeam = Beam(End1,End2);
// The beam name is now the same as the variable "aBeam"
aBeam.section = I600;
aBeam.material = St44;
// Give the beam a unique name "Leg"+i
Rename(aBeam, "Leg"+i);
Print (GetNamedObject("Leg"+i).section.name());
Print (Leg1.section.name()); // but not Print("Leg"+i... }
Note, we can not type
"Leg"+i = Beam(End1,End2);
```

Exercise - objects and properties

- Read in the frame.js
- Type in the command window: Bm2. - and press the Tab key
- Study the properties and functions of Bm2
- Look up the StraigthBeam in Help - Class hierarchy:
- ModelObject
 - NamedObject
 - Transformable
 - BasicConcept
 - BasicBeam
 - StraightBeam
 - Print the cross section of Bm2
 - Print(Bm2.section.diameter());
 - Set end1 x-offset of Bm2 equal half the diameter of Bm3



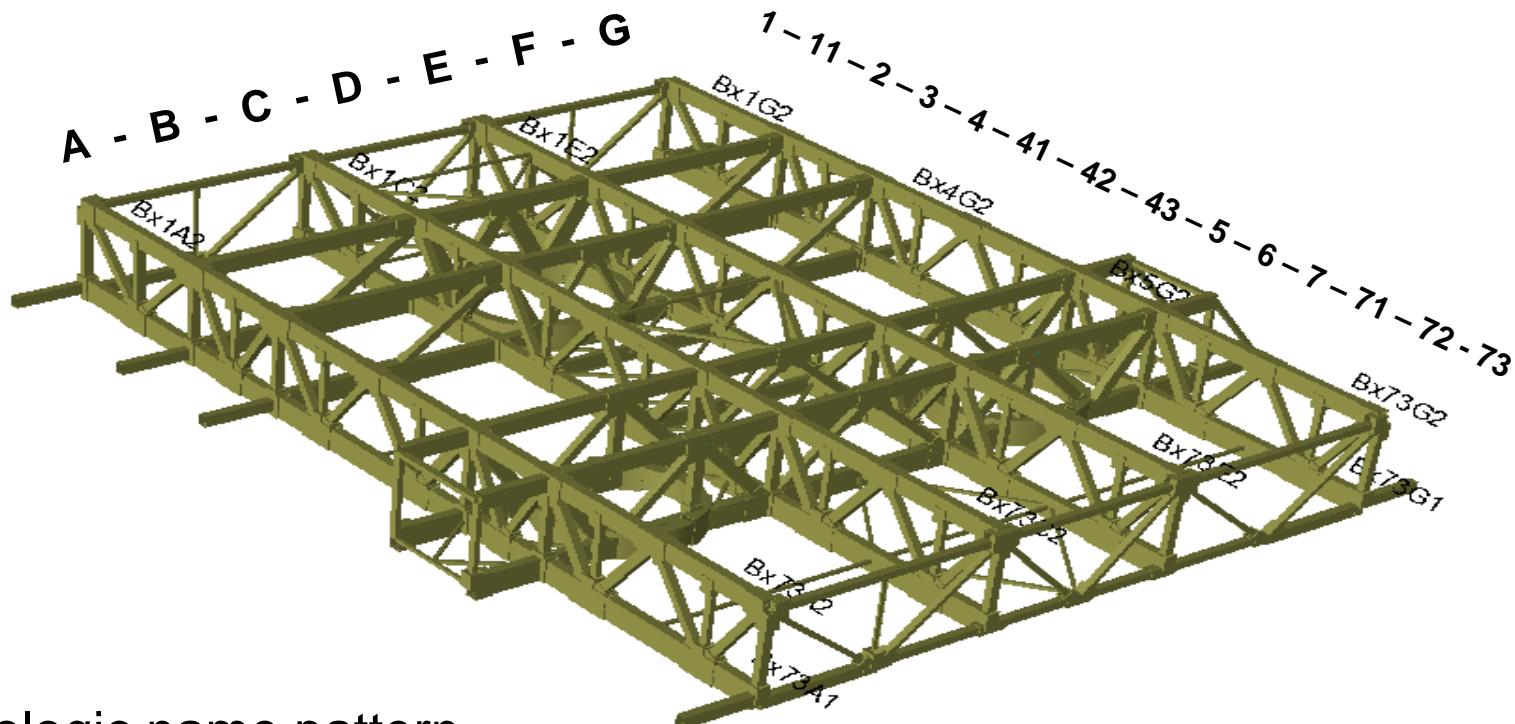
```
Bm2.setEndOffset(1,Vector3d(Bm3.section.diameter()/2.0,0.0,0.0));
```

Accessing the objects in a model

■ You can access objects by

- by name
 - Genie has no name pattern suitable for programming
 - You can define your own
- by name sets
 - Static sets
 - Dynamic sets
 - In scripted input it is easy to add objects to sets as they are created
- by some of its properties
 - Limit... functions
 - SupportType function

A naming pattern for structures



- Topologic name pattern
- Name increments in X,Y and Z direction
 - Beam Bx4G2
 - Beam in X direction at X-axis 4, Y-axis G, Z-axis 2
 - Type + X-name + Y-name + Z-name

Topologic name pattern

- Make a name from four sub strings Nam1, Nam2, Nam3 & Nam4 denoting:

Object type	X-direction	Y-direction	Z-direction
Nam1	Nam2	Nam3	Nam4

- Decide on a notation for type and make arrays of names in X,Y and Z direction

Nam1 = "P" // Point	Nam2[0] = "1";	Nam3[0] = "A";	Nam4[0] = "1";
Nam1 = "Bx" // Beam in Xdir	Nam2[1] = "11";	Nam3[1] = "B";	Nam4[1] = "2";
Nam1 = "By" // Beam in Ydir	Nam2[2] = "2";	Nam3[2] = "C";	Nam4[2] = "3";
Nam1 = "Bz" // Beam in Zdir	Nam2[3] = "3";	Nam3[3] = "D";	Nam4[3] = "4";
Nam1 = "Dx" // Beam diagonal in XZdir	Nam2[4] = "4";	Nam3[4] = "E";	Nam4[4] = "5";
Nam1 = "Dy" // Beam diagonal in YZdir	Nam2[5] = "41";	Nam3[5] = "F";	Nam4[5] = "6";
.....	Nam2[6] = "42";	Nam3[6] = "G";	Nam4[6] = "7";
	Nam2[7] = "43";	Nam3[7] = "H";	Nam4[7] = "8";
	Nam2[8] = "5";	Nam3[8] = "I";	Nam4[8] = "9";
	Nam2[9] = "6";	Nam3[9] = "J";	

- Now you can build a name; "By" + Nam2[5] + Nam3[2] + Nam4[1] => "By41C2"

Topologic name pattern

- Make a function to build a name from the sub strings

- function GetName (N1,N2,N3,N4) { return(N1 +Nam2[N2] +Nam3[N3] +Nam4[N4]); }

- And a function to get an object by its name:

- function GetObjectByName (N1,N2,N3,N4) {
return(GetNamedObject(GetName(N1,N2,N3,N4))); }

- Now you have a naming pattern suitable for programming:

```
for (i = 0;i< NumX ; i++) {  
    for (j = 0;j< NumY ; j++) {  
        for (k = 0; k < NumZ ; k++) {  
            var Bms1 = new Array();  
            Bms1[i] = Beam(GetObjectByName("P",i,j,k),  
                           GetObjectByName("P",i+1,j,k));  
            Bms1[i].name = GetName("BmX",i,j,k);  
            .....  
        }  
    }  
}
```

Dynamic sets

- A Dynamic set uses a query to identify its members.
- Dynamic sets are continuously updated when new objects are created
- Example: All objects in a Plane:

`dset1=DynamicSet(LimitInPlane(ZPlane3d(0)));`

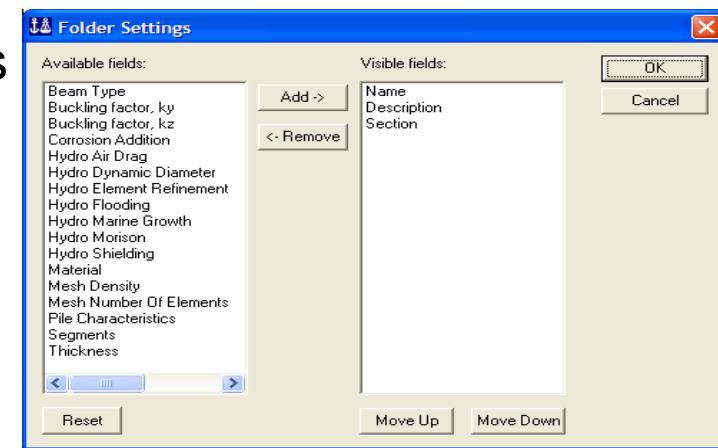
- Example:
Set comprising beams in plane Z=0.0
with flange Width < 0.2 m

`dset1=DynamicSet(LimitInPlane(ZPlane3d(0)) && LimitLower("Width",0.2m));`

- You can query Genie objects about their properties

`LimitLower("Width",0.2m)` is a query for Beams with
section flange Width < 0.2 m

- The properties you can query are listed in the
Fields dialogue for the object type in the browser.
E.g. for Structure:



Dynamic sets - more examples

- Set comprising objects along a line that also belongs to a named set:
`dset2 = DynamicSet(LimitAnd(LimitInSet(Frame_A),LimitLine(Point4,Point7)));`
- Set comprising beams in plane Z=0.0 with Section I200:
`dset1=DynamicSet(LimitInPlane(ZPlane3d(0)) && LimitString("Section","I200",true));`
- `dset1 = DynamicSet(LimitLower("Diameter",0.7m));`
- `dset1 = DynamicSet(LimitString("Name","Bm.*",true));`
When the boolean is true LimitString supports regular expression e.g:
 - . => (dot) Matches any single character
 - * => Repeats the previous item zero or more times
 - | => Match the part on either side of the |
 - ? => Makes the preceding item optional
- Examples:
 - `Bm.*` => Matches all objects named Bm<something>
 - `Bm7|Bm7.*` or `Bm7.*?` => Matches Bm7, Bm72, Bm78, Bm786 etc.

Then use the set you created...

```
dset1.setBeamOffset(Vector3d(0 m,0 m,.3 m));
```

- Objects in dset1 that do not support setBeamOffset will be ignored.

Exercise - Limit-functions

- Read the frame.js
- Use Tab in the command window to see all variants of the Limit... functions
- Or in GeniE help...

Class hierarchy:

ModelObject

- + NamedObject
 - + AbstractLimit

Direct Known Subclasses:

LimitAnd , LimitBox , LimitInSet , LimitLine , LimitNot , LimitNumber , LimitOr
, LimitPlane , LimitString +++

- Use the Limit... functions to extract various subsets of the frame model

Sort beams in sets based on section

- Put beams in named sets based on the section name:

```
for(var sect in ModelObjects) {    if(sect.supportsType(typeSection)) {  
    newSet=Set();  
    for(var bm in ModelObjects) {  
        if (bm.supportsType(TypeStraightBeam) ||  
        bm.supportsType(TypeCurvedBeam)) {  
            if(bm.section.name==sect.name) {  
                newSet.add(bm);  
            } } }  
    newSet.name="Set_"+sect.name;  
} }
```

- or accessing the beams directly...

```
for(var a in ModelObjects)  
{ if(a.supportsType(typeStraightBeam))  
    Print(a.Length); }
```

Exercise - GeniE beam objects

- Read the frame.js journal
- Print the section name of beams in the command window by
 - Name – GetNamedObject
 - When to use GetNamedObject and when to use name directly?
 - Elevation – LimitInPlane
 - Objects that have cross section – if(thisObject.supportsType(typeSection))
 - Cross section = OD610X8
- Hint:

```
for(var a in ModelObjects)
  { if(a.supportsType(typeStraightBeam) && a.section.name=="OD610X8")
    Print(a.name()+" "+a.section.name());}
```
- Use the Vector3D to find the distance between two beam ends

```
Print(Vector3D(Point1,Point2).length());
```

Controlling program flow

■ If ...else

Example; Creating braces in the jacket wizard

```
for (i = 0; i < (NrxBrace); i++) { Thisbrace = xBrace[i];  
    if (Thisbrace == "braceup") { BraceUpX(i); }  
    else if (Thisbrace == "bracedown") { BraceDownX(i); }  
    else if (Thisbrace == "xbrace") { BraceUpX(i); BraceDownX(i); }  
    else if (Thisbrace == "kbrace") { Print("K-Brace not implemented"); }  
}  
  
// xBrace[i] is an array of the braces to be created  
// BraceUpX(i), BraceDownX(i) etc. are functions that create braces
```

■ do ...while

```
var i = 1;  
do {  
    Print( GetNamedObject("Bm"+i).end1.z);  
    i++;  
} while (i < 10);
```

for...

```
// Create an array of points on a circle
var myPoints = new Array(NrPoints);
var NrPoints = 36;    // Number of points
var Rad = 10.0;      // Radius
var X,Y;              // X,Y coordinate
//
for(var icount = 0; icount < NrPoints; icount++)
{ X=Rad*Math.cos(icount*10*Math.PI/180);
  Y=Rad*Math.sin(icount*10*Math.PI/180);
  myPoints[icount]=Point(X,Y,0);
  myPoints[icount].name="Point"+icount;
}
```

```
// ( GetObjectByName and GetName are user defined functions)
// Creating beams
// Stepping in X, Y and Z direction
for (i = 0;i< NumX-1 ; i++) {
    for (j = 0;j< NumY-1 ; j++)  {
        for (k = 0; k < NumZ-1 ; k++) {
            var aBeam ;
            aBeam = Beam(GetObjectByName(0,i,j,k), GetObjectByName(0,i+1,j,k));
            aBeam.section = Box1400;
            aBeam.material = S275;
            Rename(aBeam,GetName(1,i,j,k));
        }
    }
}
```

for...in

■ Set X-coordinate of some points

```
var MyPoints = new Array();
MyPoints[0] = Point(0, 0, 1.0);
MyPoints[1] = Point(0, 0, 2.0);
MyPoints[2] = Point(0, 0, 3.0);
//
for (var MyPoint in MyPoints) { MyPoint.x = 2m; }
```

■ Print length of all straight beams

```
for(var a in ModelObjects)
{ if(a.supportsType(typeStraightBeam))
    Print(a.Length); }
```

■ JScript built-in functions

GetObject

```
MyBook = GetObject("C:\\TestDir\\TestBook.xls");
```

```
Elevation1 = Length(MyBook.Worksheets ("sheet1").Range("C8").Value);
```

- Works for COM objects e.g. Microsoft Office documents

■ GeniE Functions

```
End1 = GetNamedObject("MainLegP"+i);
```

```
ReadCommandFile("Input.js");
```

Plus many more...

Most GeniE commands are functions that the various objects support

e.g. the copyTranslate function for a plate

```
Pl5 = Pl1.copyTranslate(Vector3d(2 m,0 m,6.23 m));
```

User defined functions

■ Example:

```
// Function to transform a vector in local coordinate system to global coordinates  
function VecTra(LocX, LocY, LocZ, LocalCoordSys)
```

```
    // Input is local vector X,Y,Z and localsystem
```

```
    // Returns global X,Y,Z vector
```

```
{
```

```
    return GlobalVector = LengthVector3D(
```

```
        LocalCoordSys.xVector.normalise()*LocX +
```

```
        LocalCoordSys.yVector.normalise()*LocY+
```

```
        LocalCoordSys.zVector.normalise()*LocZ);
```

```
}
```

```
// Example - move beam end in beams local coordinates
```

```
Bm1 = Beam(Point(2.5 m,0 m,0 m), Point(7.5 m,7.5 m,0 m));
```

```
MyCord = Bm1.localSystem();
```

```
Bm1.setEndOffset(2,VecTra(1 m ,1 m ,0 m , MyCord));
```

More user defined functions

```
// Function to make a name by adding four strings from
// name arrays Nam2[ ], Nam3[ ], Nam4[ ],
function GetName (N1,N2,N3,N4) { return(N1+Nam2[N2] +Nam3[N3] +Nam4[N4]); }

// then use GetName to name some points
function MakePoints (NumX, NumY, NumZ, Step)
{   var i, j, k, aPoint; // Stepping in X, Y and Z direction
    for (i = 0;i< NumX ; i++)
    { for (j = 0;j< NumY; j++)
        { for (k = 0; k < NumZ; k++)
            {   X1 = i * Step;
                Y1 = j * Step;
                Z1 = k * 0.6 * Step;
                aPoint = Point(X1, Y1, Z1);
                aPoint.name = GetName("Point",i,j,k);
            }
        }
    }
}
```

JScript objects – the Math object

■ JScript Math object - methods

abs , acos , asin , atan , atan2 , ceil , cos , exp , floor , log , max , min ,
pow , random , round , sin , sqrt , tan

■ Example:

```
Xcoord = (-1)*Math.abs( Math.sqrt( Math.abs(Math.pow(Radius1.toDouble(),2) -  
Math.pow(Length(YCord-Elev2).toDouble() ,2)))) +  
Length(Radius1 + WidePlat).toDouble;
```

if your variable is of type “Length” you must use toDouble when you use it as input to the Math functions.

Length(myMeasure) - converts to length

myMeasure.toDouble – converts to number

Working with Office documents from GenIE

```
MyBook = GetObject("C:\\WorkSpace\\MyWorkbook.xls");
// Note regexp escape sequence \\ to get \ in path
MyBook.Worksheets("sheet1").Activate;
MyBook.Windows(1).Visible="True";
// Writing an Array to EXCEL
var MyData = new Array();
MyData[1] = 100;
MyData[2] = 200;
MyData[3] = 300;
MyData[4] = 400;
NumberOfData = MyData.length;
```

Working with Office documents from GeniE

```
// Write data from GeniE to a Excel sheet
Row = 5;
Col = 3;
//
for (i = 1;i< NumberOfData; i++)
{
    MyBook.ActiveSheet.Cells((Row-1),Col).Offset(i,0).Value = MyData[i];
}
//
// Read some data back to GeniE
aText = MyBook.Worksheets("sheet1").Cells(7,5).value;
```

User defined JScript objects

- Defining a Frame class with a function to calculate area

```
class Frame {  
    constructor function Frame(w,h) {width=w;height=h;}  
    function frame_area() {return width*height;}  
    var width;  
    var height;  
}
```

```
frame1 = new Frame(4.0, 6.0);
```

```
Print(frame1.frame_area());
```

```
-> 24.000000
```

User defined objects - Point and Line class

■ Example:

A class for a line object in two dimensions with a function to find the point of intersection with another line

```
// Define a class for a point in the X,Y plane
class Point2d {
    constructor function Point2d(x,y) {m_x=Length(x);m_y=Length(y);}
    function X() {return m_x;}
    function Y() {return m_y;}
    var m_x,m_y;
}
```

and the Line class...

```
class Line2d {  
    var m_start,m_end;  
    constructor function Line2d(start,end) {m_start=start;m_end=end;}  
    function Start() {return m_start;}  
    function End() {return m_end;}  
    function intersect(other) {  
        ua1 = (other.End().X() - other.Start().X()) * (Start().Y() - other.Start().Y()) - (other.End().Y() - other.Start().Y()) * (Start().X() - other.Start().X());  
        ua2 = (other.End().Y() - other.Start().Y()) * (End().X() - Start().X()) - (other.End().X() - other.Start().X()) * (End().Y() - Start().Y());  
        ua = ua1 / ua2;  
        x = Start().X() + ua * (End().X() - Start().X());  
        y = Start().Y() + ua * (End().Y() - Start().Y());  
        return new Point2d(x,y);  
    }  
}
```

Creating two line objects...

```
// Creating two line objects and a point at the intersection  
l1=new Line2d(new Point2d(0,10m),new Point2d(5m,0));  
l2=new Line2d(new Point2d(10m,0),new Point2d(0,5m));  
p=l1.intersect(l2);
```

Generating reports

- To get a template for report journal do
 - File > Create Report
 - and make sure “Journal Report Generation” is checked
 - This will give you something like:

```
Case_11.add(ChapterStructure());  
Case_11.element(1).add(TableBeamCoordinate());  
Case_11.element(1).add(TableBeamProperty());  
Case_11.element(1).add(TableBeamHydroProperty());  
Case_11.element(1).add(TableBeamEccentricity());
```

Adding figures to a report

```
// Make a function plotResult to plot VonMises stresses for "loadcasein" on a set "setin"  
// returns a plot Figure object  
  
function plotResult(loadcasein,setin) {  
    // Delete "Demo_ModelView" if it exists  
    for(var object in ModelObjects) {  
        if(object.supportsType(typeModelView) && object.name() == "Demo_ModelView")  
        { Delete(object); }  
    }  
    ModelView_temp = ModelView();  
    ModelView_temp.addElement(DisplayConfiguration ("Results - with Mesh", moPaper));  
    ModelView_temp.addElement(ResultPresentation());  
    ModelView_temp.resultPresentation.resultComponent = rsStress;  
    ModelView_temp.resultPresentation.calculationType = rsVonMises;  
    // Continue...
```

Reports - continued...

```
ModelView_temp.resultPresentation.optionMinmax = false;  
ModelView_temp.resultPresentation.optionValues = false;  
ModelView_temp.name = "Demo_ModelView";  
ModelView_temp.addElement(VisibleModel());  
myloadcase = GetNamedObject(loadcasein.name());  
myloadcase.setCurrent();  
if( setin.supportsType(typeSet)) {  
    Demo_ModelView.visibleModel.include(setin);  
    Demo_ModelView.activate(); }  
Graphics.fitModel();  
var Plottitle = "Loadcase " + loadcasein.name() + " - Part " + setin.name() + " - Von Mises  
Stresses";  
var Plotfile = loadcasein.name() + setin.name() + ".jpg";  
Graphics.savefig(Plotfile);  
var NewPlot = Figure(Plottitle , Plotfile);  
return NewPlot;  
}
```

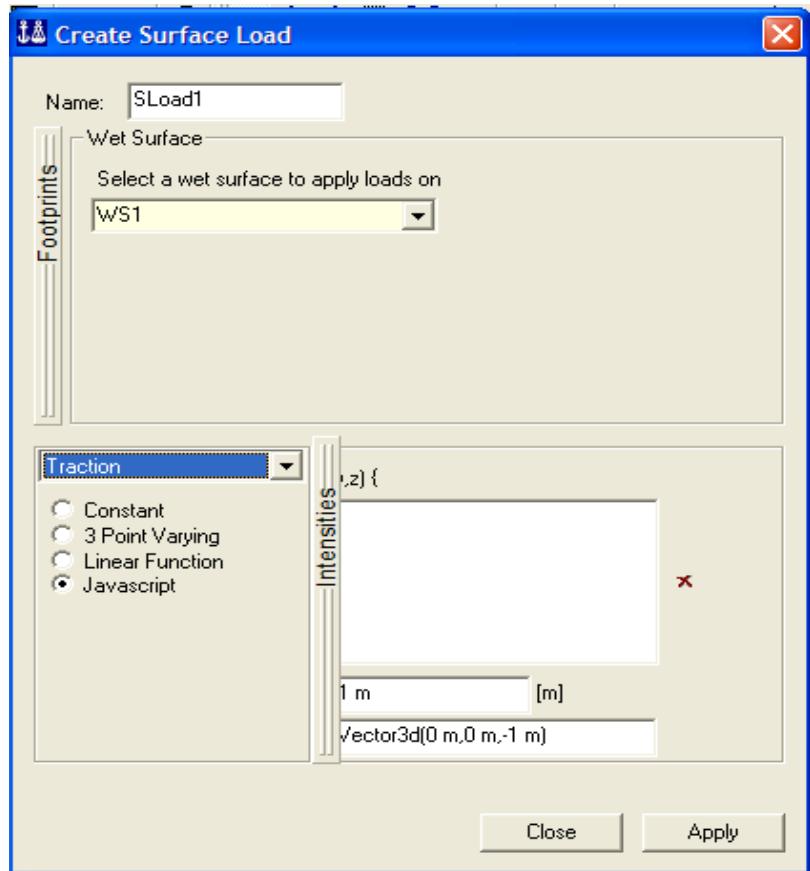
Using the function plotResult

```
// Using the function plotResult to make a report
//
Case_1 = Report("Case_1");
Case_1.add(ChapterStructure());
Case_1.element(1).add(TablePlateCoordinate());
Case_1.element(1).add(TablePlateProperty());
Case_1.element(1).add(TableSupportBoundary());
Case_1.add(plotResult(Operation,UpperDeck));
Case_1.add(plotResult(Storm,UpperDeck));
Case_1.saveAs("Case_1.doc", mrWordXML);
```

- Once you have the predefined plot functions adding plots to the report is easy

Load Intensity by JScript

- The intensity of line and surface loads may be given by a JScript function
- E.g. GeniE menu; Insert > Explicit Load > Surface Load...



- The dialogue takes a JScript function as input
- The function for surface loads may use the current x, y & z coordinate as input
- ```
pressureFunction(x y z)
{ return your_function...; }
```
- The function for line loads may use the relative length along the line as input
- ```
component1Dfunction(param)
{ return your_function...; }
```

Load Intensity by JScript - Examples

■ Line Component Load:

```
return Vector3d(1N/m,x*2N/m2,0);
```

- //input x,y,z, all of type Length
- //output type Vector3d(ForcePerLength,ForcePerLength,ForcePerLength)

■ Line Component Load - Parametric:

```
return Vector3d(1N/m,param*2N/m,0);
```

- //input t, of type Number (unitless)
- //output type
Vector3d(ForcePerLength,ForcePerLength,ForcePerLength)

■ Line Temperature Load:

```
return 1deIC*y.toDouble();
```

- //input x,y,z, all of type Length
- //output TempDiff

■ Line Temperature Load - Parametric:

```
return param*10deIC;
```

- //input t, of type Number (unitless)
- //output type TempDiff

Load Intensity by JScript - Examples

■ Surface Pressure:

```
return z*1 G * 1025 kg/m3;  
    - //input x,y,z, all of type Length  
    - //output type ForcePerArea
```

■ Surface Component Load:

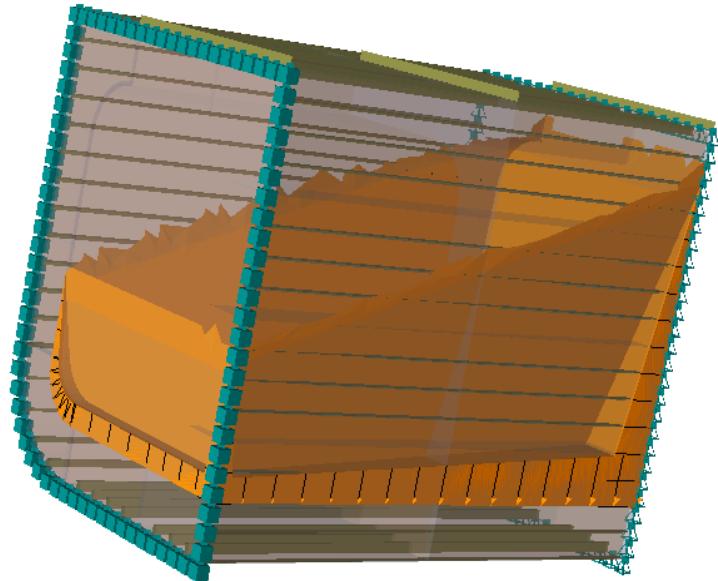
```
return Vector3d(1N/m2,x*2N/m3,0);  
    - //input x,y,z, all of type Length  
    - //output type Vector3d(ForcePerArea,ForcePerArea,ForcePerArea)
```

■ Surface Traction - Example function:

```
- return 15N/m2*Math.cos(x.toDouble());  
    - //input x,y,z, all of type Length  
    - //output type ForcePerArea
```

Load Intensity by JScript - Example

```
/* Function for generating a hydrostatic pressure in a compartment for  
20 deg. heel about x-axis and 4.5 m draught at origin  
- Define a wet surface.  
- Insert a pressure load on the wet surface  
- Set intensity to Javascript and paste the script below into the script window in the  
pressure dialogue  
*/  
  
HeelAngle = 20 ;  
Draught = 4.5 m;  
//  
HeelAngleRad =(HeelAngle*Math.PI)/180;  
Zlocal=(z*Math.cos(HeelAngleRad)) -  
(y*Math.sin(HeelAngleRad));  
if ( Zlocal < Draught)  
{  
return 1 G * 1025 kg/m3 * (Draught - Zlocal);  
}  
else return 0;
```



Some limitations

- GeniE has limited JScript functions for object name handling
(from Bm3 to Bm34 step 3)
Automatic naming of new objects (next beam-name)
- JScript does not support file operations
 - but you can read and write to Excel etc.
- Custom dialogues and buttons
 - May be available in future versions
 - New .net based scripting is under evaluation
- Read input data to user functions from GeniE by cursor selection

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