



COMP9993 20T3 Research Project C

Deep Learning for Improved Bronchial Tree Segmentation in CT Images

Student

- Oleg Kufirin, z5216713

Supervisor:

- Erik Meijering

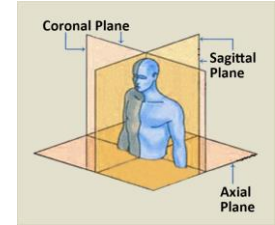
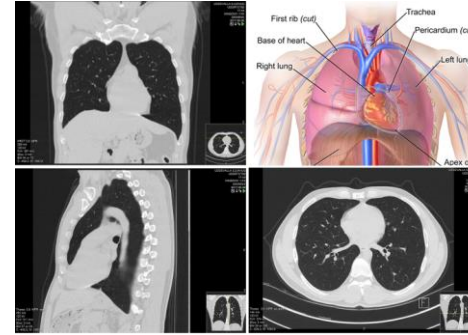
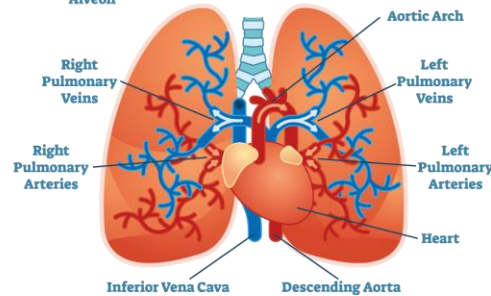
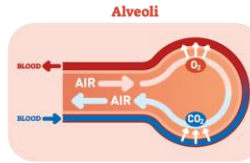
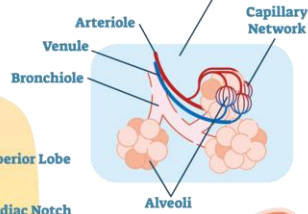
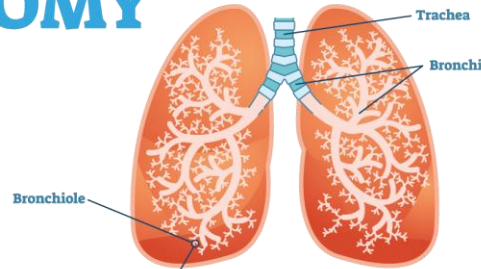
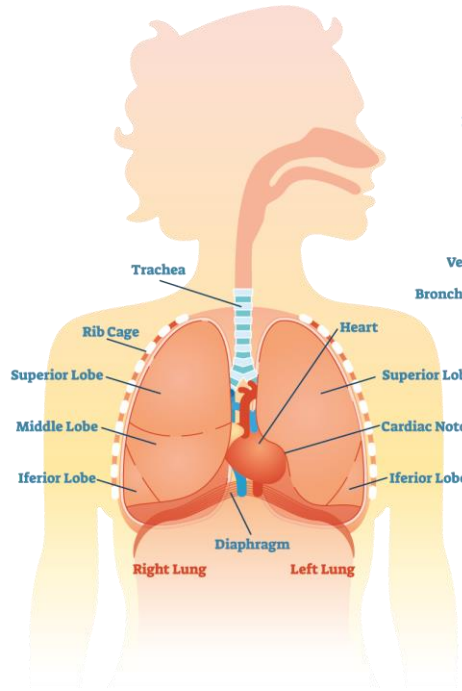
Assessor:

- Daniel Moses

09/12/2020

Background information

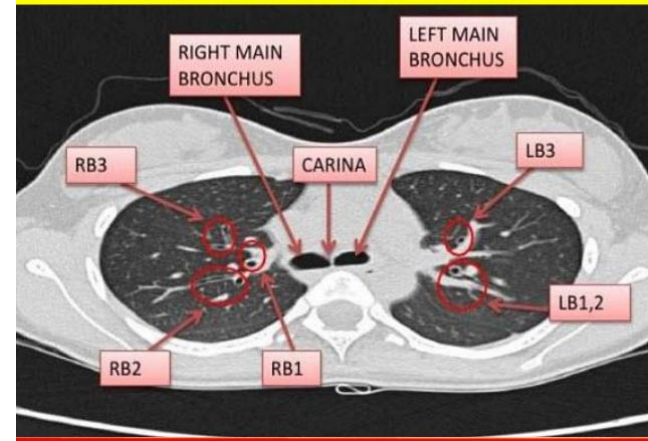
LUNGS ANATOMY



<https://www.ipradiologrounds.com/hicc-primer/image-reconstruction/>

<https://glassboxmedicine.com/2020/03/05/automatic-interpretation-of-chest-ct-scans-with-machine-learning/>

CT Chest Anatomy- Bronchial tree

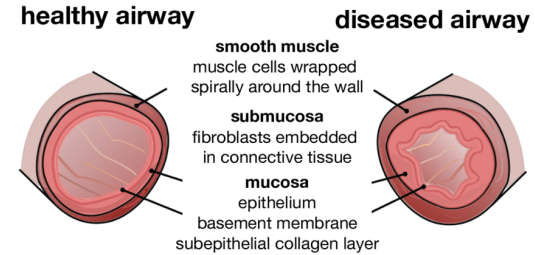


<https://www.slideshare.net/feezone/ct-chest-fundamentals>

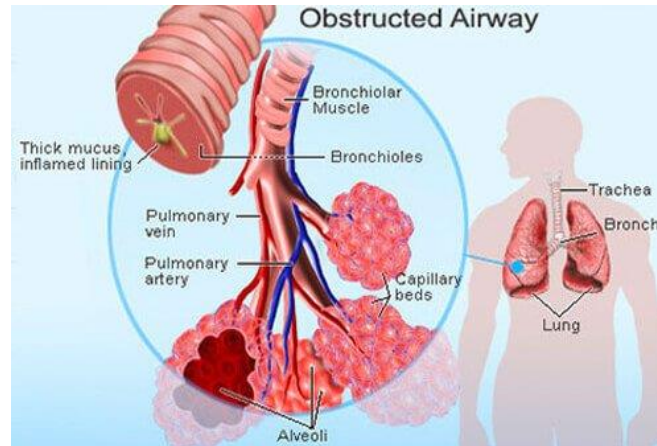
Motivation

Top 5 Lung Diseases That Affect the Airways:

- Asthma
 - Bronchitis
 - Emphysema
 - COPD (Chronic Obstructive Pulmonary Disease)
 - Cystic Fibrosis
- + COVID-19



https://www.researchgate.net/figure/Schematic-of-the-airway-wall-Small-airways-consist-of-three-distinct-layers-the-mucosa_fig1_261038942



https://www.arhhealth.com/content/1/asthma_lung_inflammation

Virtual bronchoscopy



https://www.researchgate.net/figure/Picture-disclose-virtual-bronchoscopy-in-patient-with-tracheal-web_fig2_308770802

Overview of the baseline method

Computerised Analysis of the Bronchovascular Anatomy of the Lung on Multidetector CT Studies (D. Moses, 2018)

Central Bronchial Tree Segmentation

Isosurface
construction and
projection

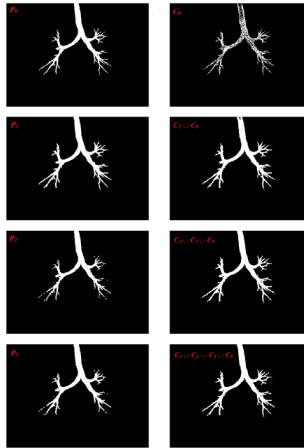
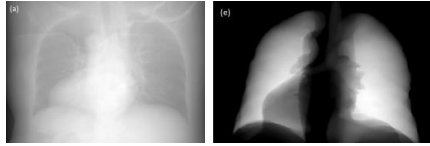


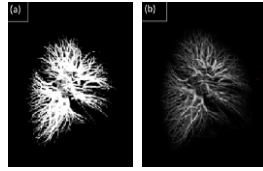
Figure 4-4: Isosurface projection sequence showing P_0 and $(G_0 \cup G_1 \cup \dots \cup G_i) \subset B_{\text{iso}}$ during the first 4 iterations.

Peripheral Vessel Centerline Identification

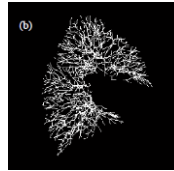
Lung segmentation:
thresholding and
component analysis



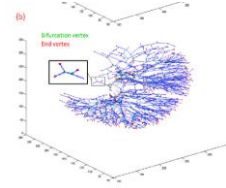
Hessian filtering



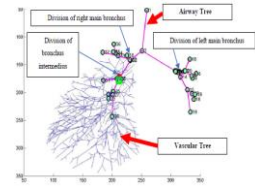
Skeletonisation



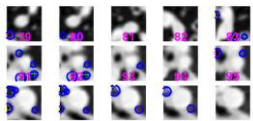
Graph
Construction



Tree
Construction



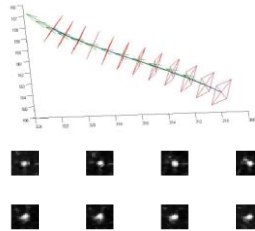
Hough transform,
hierarchical
clustering for
dark circles
=> veins –
arteries
classification



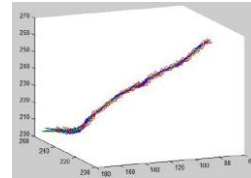
Hough transform,
hierarchical
clustering for
bright circles,
stitching,
interpolation



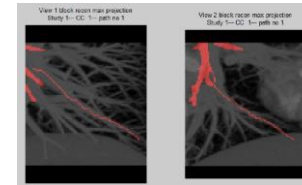
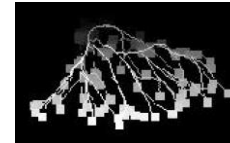
Derivative of the
centerline
spline: cross
–sectional
img.



B-spline
approximation



Tracing paths



Vector Field:
Distance Map +
Diameter Map =
Composite Map

Peripheral Bronchial Tree Identification

Circular Hough transform

Ring filtering

Hierarchical clustering

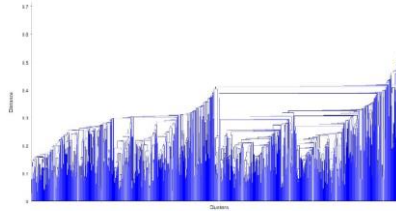
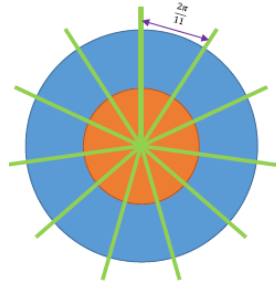
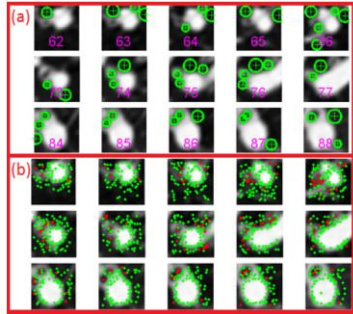
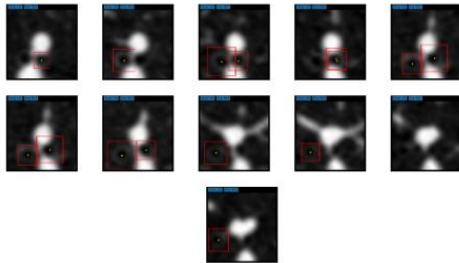


Figure 6-12: Dendrogram showing the results of the hierarchical clustering algorithm with a tolerance of 0.15 and shortest distance measure applied to the training data set with ring filter parameters of $\beta=0.0$ and $\gamma=0.1$.



CNN
(transfer learned)

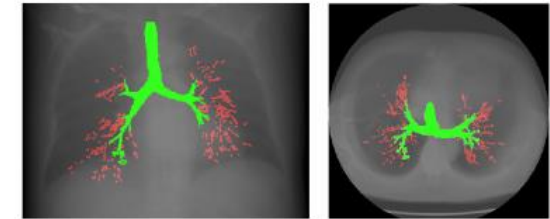
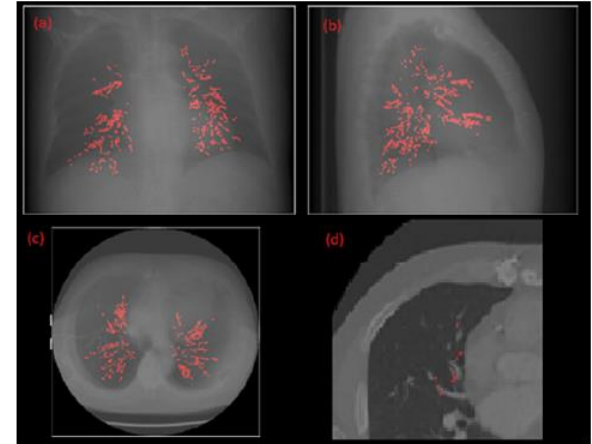
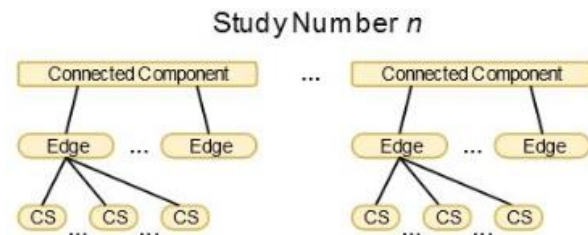


Figure 6-13: Fusion of detected central bronchial tree (green) and peripheral bronchial centre points (red), which shows their spatial relationship within the lung. Note that the peripheral bronchial points extend much more distally than central bronchial tree.

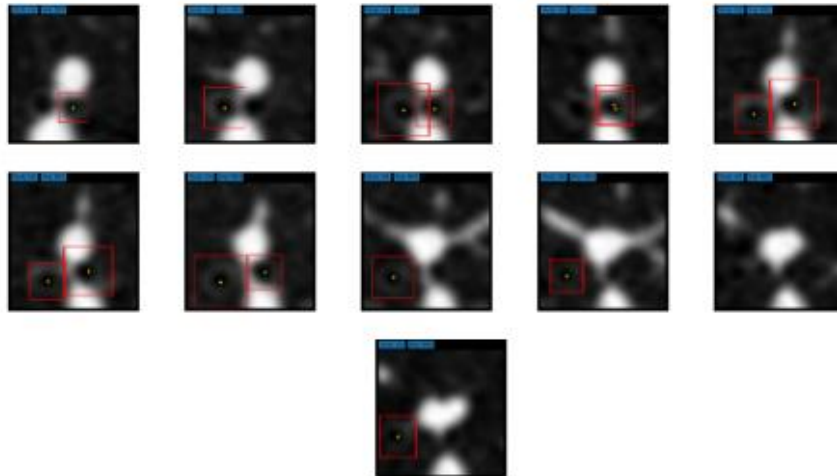
Data set

- 11 studies
- 145,575 data files in “.mat” format. Size 161x161 pixels
- Each cross-section is indexed by study no., image no. within a study, connected component no., edge no., cross-sectional image no.
- Global 3D coordinates of each voxel are stored
- Local 2D coordinates of the bounding boxes of located bronchi are stored

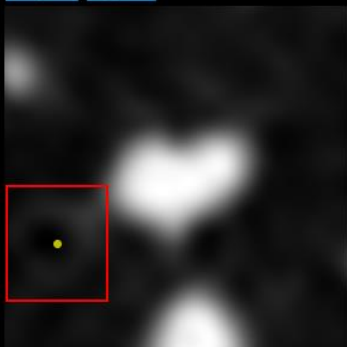
Study No	No images	No edges	Edges>50% detection
200	26327	2055	62
201	21652	1749	57
202	7527	470	20
203	9874	738	61
204	14334	1134	134
205	11450	878	163
206	12221	889	41
207	12640	929	27
208	13267	989	72
209	7302	591	80
210	8981	686	44
Total	145575	11108	761



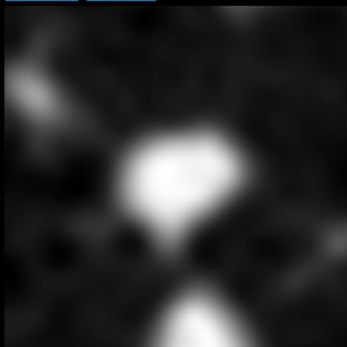
Samples from random edge



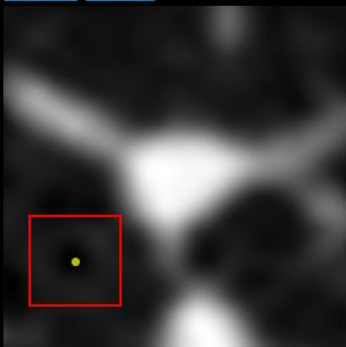
Study: 204 Img: 3070



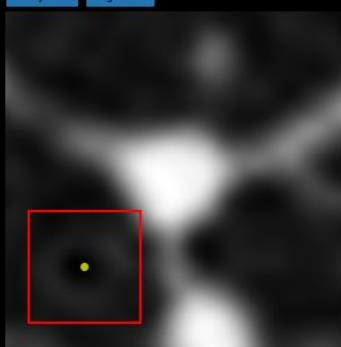
Study: 204 Img: 3071



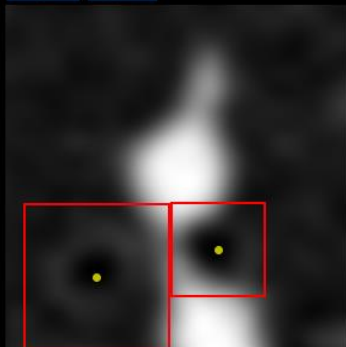
Study: 204 Img: 3072



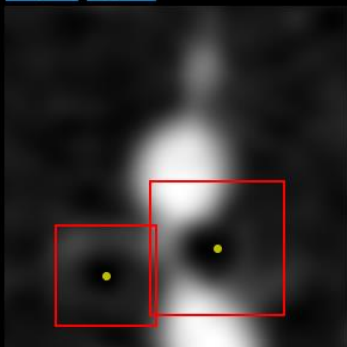
Study: 204 Img: 3073



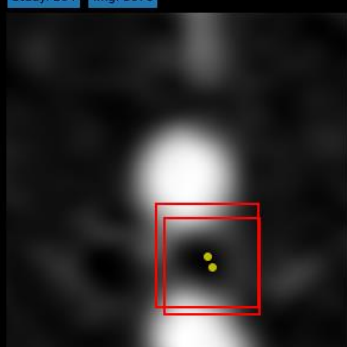
Study: 204 Img: 3074



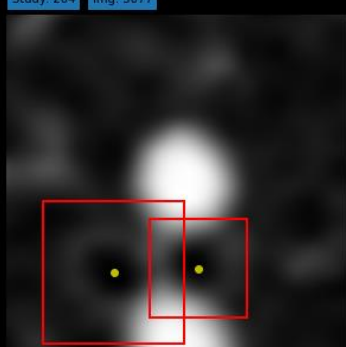
Study: 204 Img: 3075



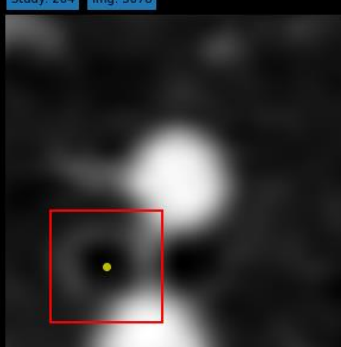
Study: 204 Img: 3076



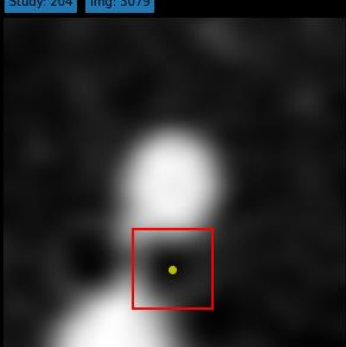
Study: 204 Img: 3077



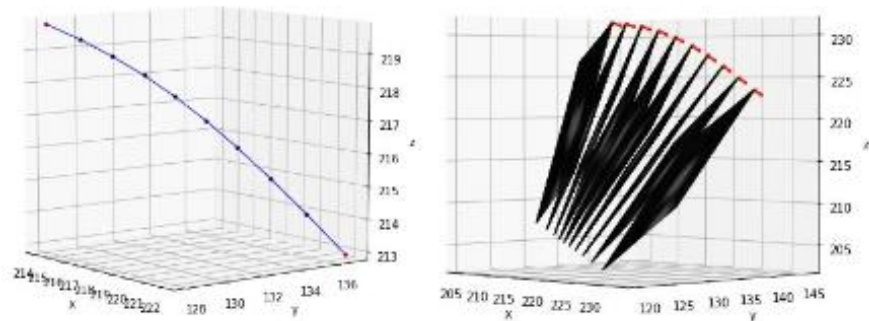
Study: 204 Img: 3078



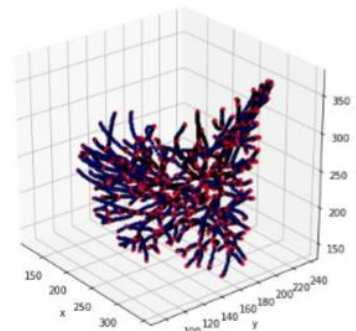
Study: 204 Img: 3079



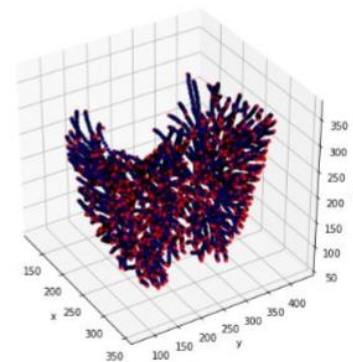
3D visualisation of a vessel edge



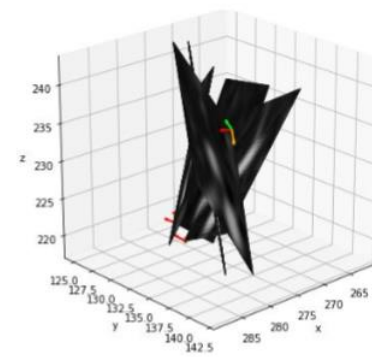
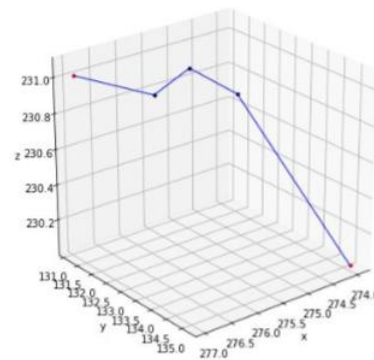
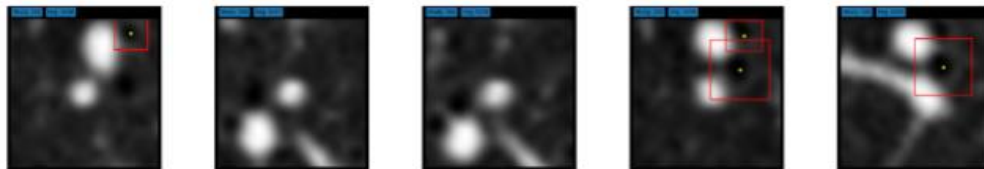
3D con. component



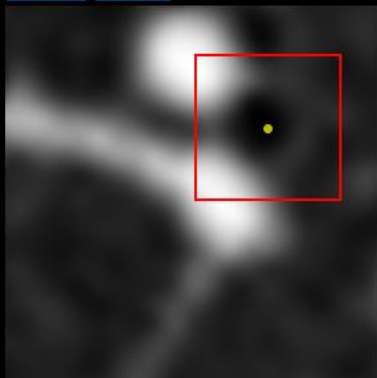
3D study



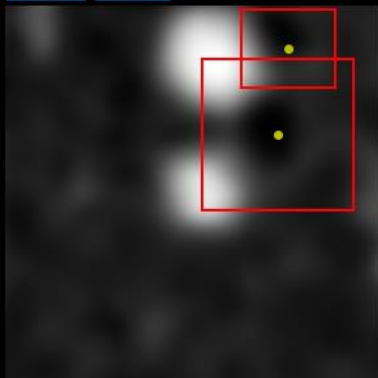
Inconsistent sampling – random flips



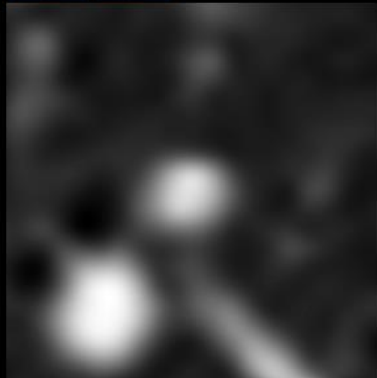
Study: 204 Img: 5234



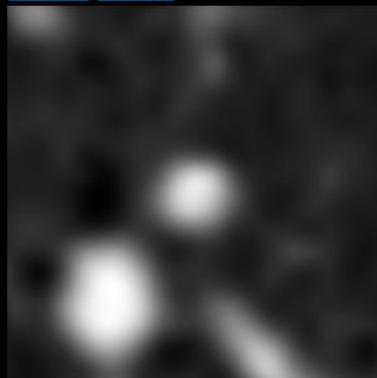
Study: 204 Img: 5235



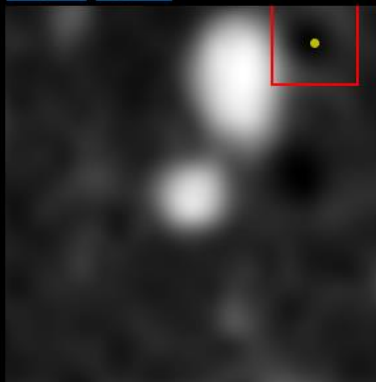
Study: 204 Img: 5236



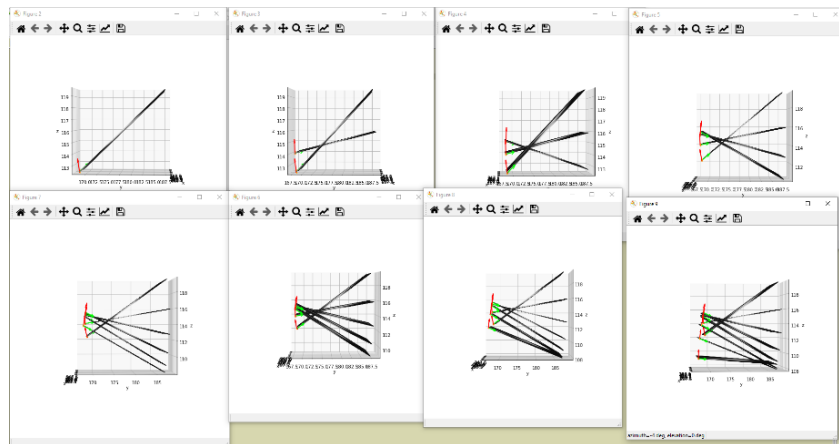
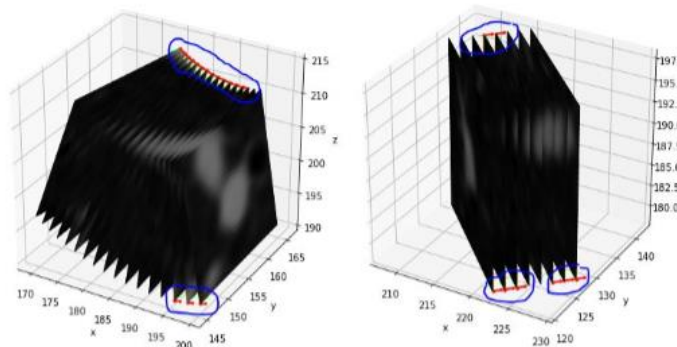
Study: 204 Img: 5237



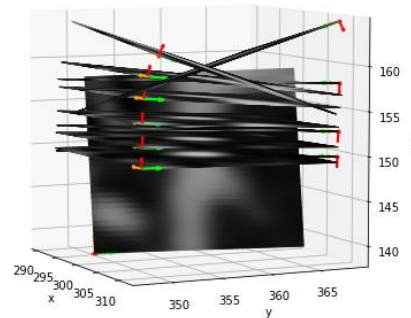
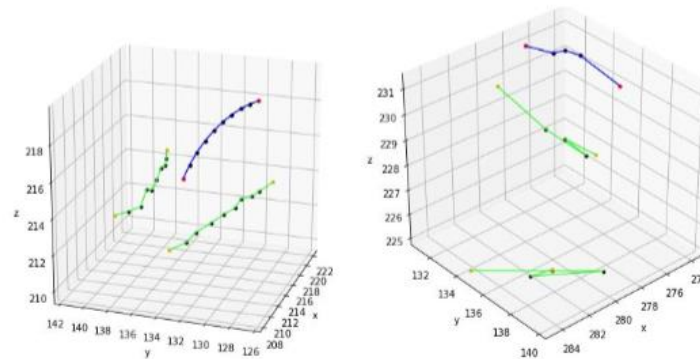
Study: 204 Img: 5238



Inconsistent sampling

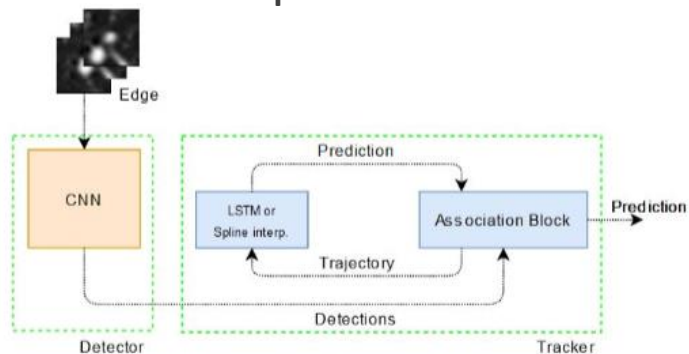


Parallelism of vessels and bronchi



Method

Proposed workflow



Input: sequence of cross-sectional images belonging to one edge

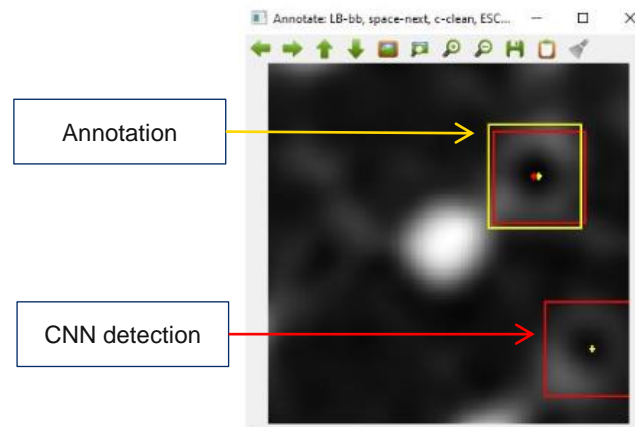
Output: set of bronchi trajectories

CNN: as in the baseline method (transfer-learned SSD)

Association block: coordinate-based mapping (e.g., Hungarian algorithm)

Prediction block: RNN or spline fitting – area of research

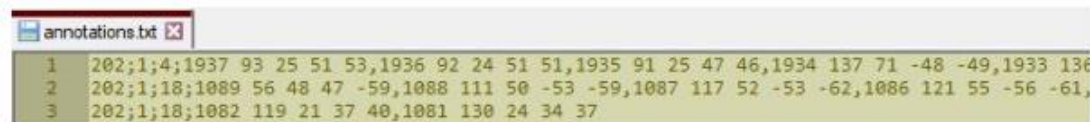
Annotation tool



Labelled edges with > 50% of detection

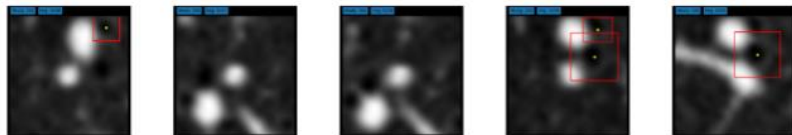
Annotated 663 edges by the author ~ 2 weeks

Length of annotated segments is ~1 to 30



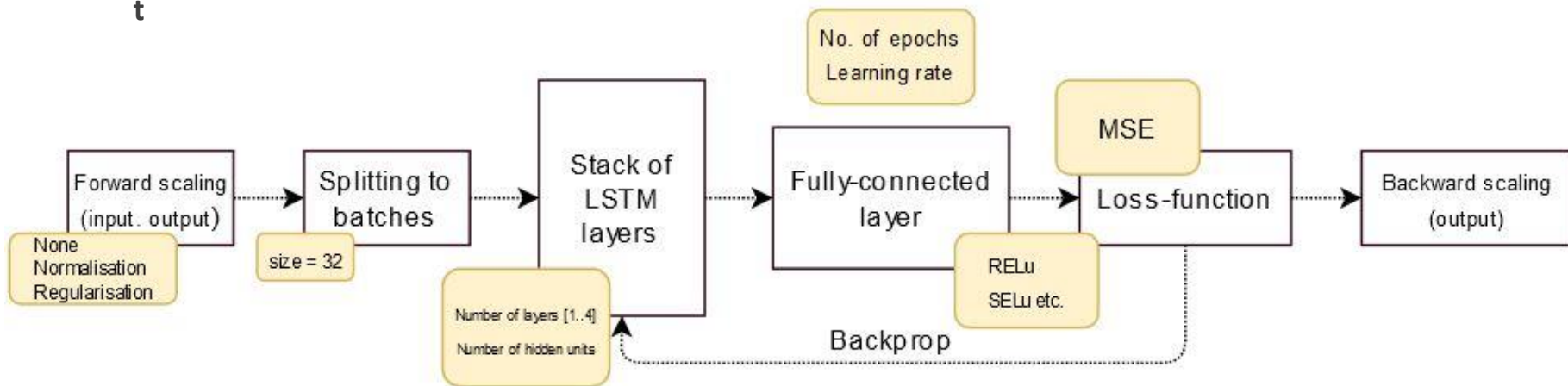
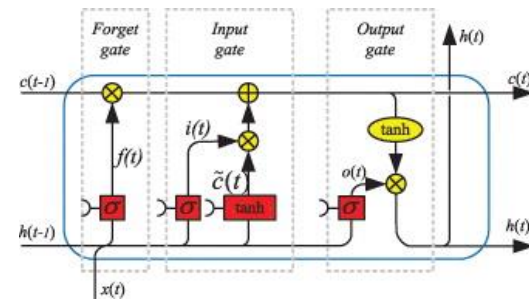
Method: LSTM

View input as a temporal sequence



Length = 3,5,7,9

LSTM cell



Method: B-spline approximation

1. Fit a piecewise polynomial curve of degree n to a sequence of points in 3D
2. Get polynomial coefficients. We know analytical expression now
3. Get 3D plane of the next cross-sectional image
4. Find the intersection point(s) of the line and the plane

We will use $n=2$ (line) for simplicity.

Line-plane intersection is unique and easy to find in algebraic form.

$$d = \frac{(p_0 - l_0) \cdot n}{l \cdot n}$$

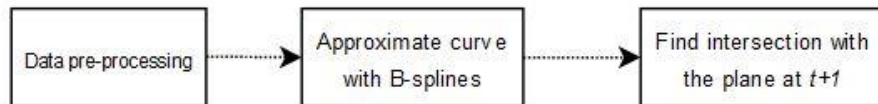
$$l_0 + l \cdot d$$

p_0 - a point on the plane

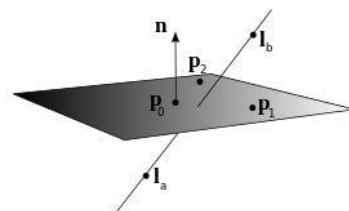
l_0 - a point on the line

n - a normal vector to the plane

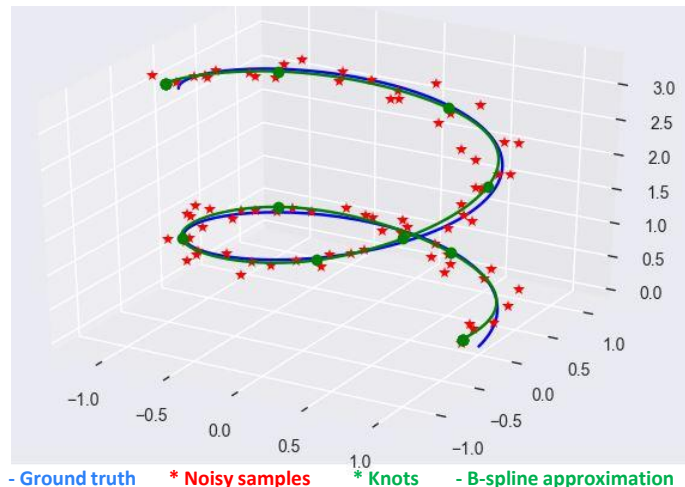
l - a vector in the direction of the line



Line – plane intersection



Example



- Ground truth * Noisy samples * Knots - B-spline approximation

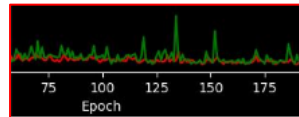
Results: LSTM

Varying input/output scaling

Input Scaling	Output Scaling	Train Loss	Val Loss	Train Loss (last 20)	Val Loss (last 20)	Epochs
None	None	60.73	72.7	76.61	86.59	700
Norm	None	12,57	41,4	15,04	42,37	200
Std	None	3,71	14,76	4,82	17,54	200
None	Norm	47,11	87,03	59,64	81,07	200
None	Std	124,09	385,47	121,14	381,13	200
Norm	Norm	2,66	2,69	3,46	4,32	200
Std	Std	68,49	320,34	69,02	321,06	200
Norm	Std	70,08	322,61	71,33	324,65	200
Std	Norm	2,27	3,11	2,92	3,64	200

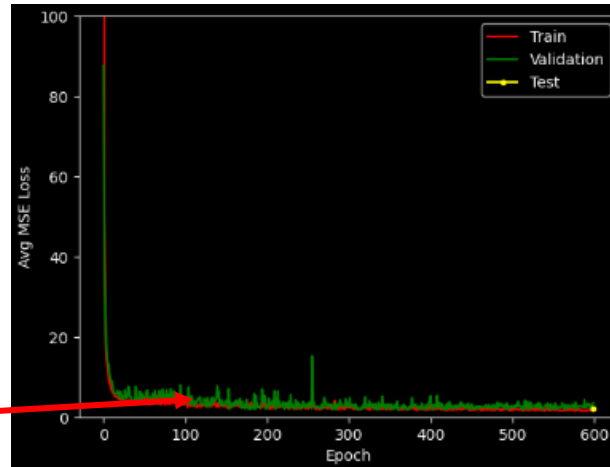
Results with the best parameters

Train Loss	Val Loss	Train Loss (last 20)	Val Loss (last 20)	Test Loss
1.69	3.49	1.65	2.78	2.22

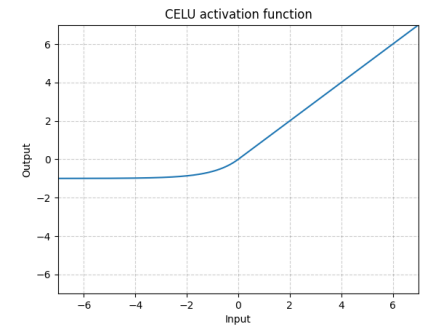
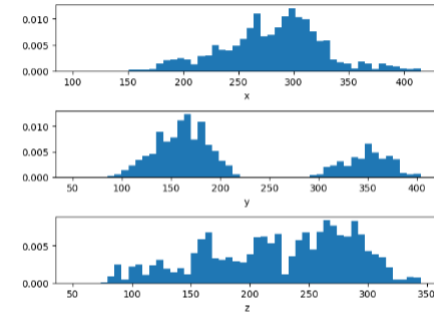


Optimal parameters:

1. Number of LSTM layers = 1
2. Number of hidden units in LSTM = 32
3. Activation function CELU
4. Sequence length = 9
5. Epochs = 200
6. Learning rate = 0.005



Input histograms



$$\text{CELU}(x) = \max(0, x) + \min(0, \alpha * (\exp(x/\alpha) - 1))$$

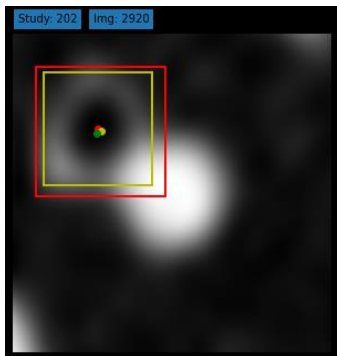
Results: B-spline approximation

Averaged across 3617 sub-sequences

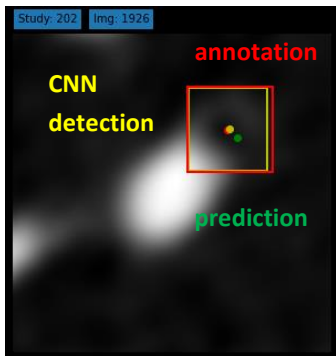
Sequence Length	MSE Loss
3	0.81
5	0.91
7	1.69
9	2.98

1% of points exceeded MSE 2.2 which is the MSE of the deep learning method

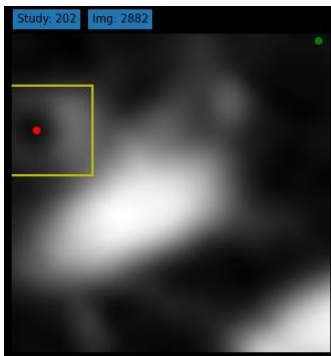
MSE = 0.0402



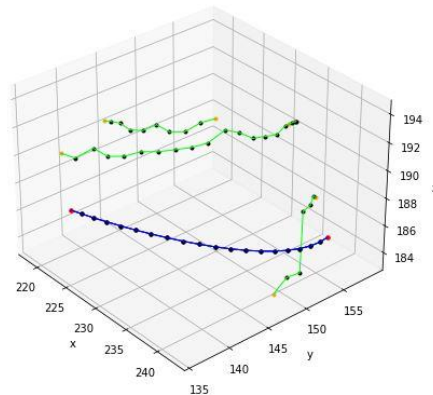
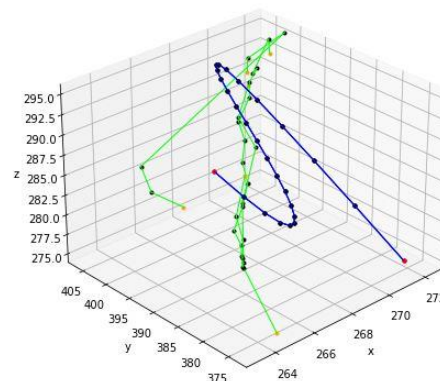
MSE = 0.2223



MSE = 116.89



Edges with high MSE



Discussion

Deep learning: MSE 2.22

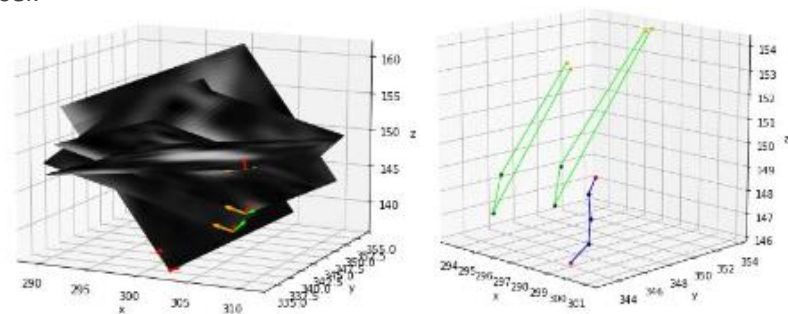
B-spline approximation: MSE 0.81

Deep Learning

- DL require substantial amount of training data – possibly not enough annotated data. Only small number of bronchial branches has been labelled
Many examples of branches from different spatial locations are needed.
- Annotation has been preformed by the author, who is not a radiologist. Bias, mistakes.
- Inconsistent sampling. Since the sampled cross-sectional patches may intersect each other at different angles, bronchi spotted at time-stamp t may lie behind the bronchi spotted at time $t+1$
- Presence of residual bronchi captured in 2D cross-sectional patches, that do not run parallel to the tracked vessel centreline. Additional algorithm has to be implemented to identify and keep only pairing bronchi to the tracked vessel.

Potential benefits of RNN if one can collect enough consistent data:

- Capture a different level of non-linearity at various bronchi generations.
- Automatically learn the direction of branches based on their spatial locations.
- Such model would allow not only more accurate estimate for tracking, but also use of the model for synthetic data generation



The vessel trajectory is nearly linear, and the bronchi trajectories are almost U-shaped

Discussion

- Sampling mechanism of cross-sectional images from the baseline method has to be improved to create consistent samples.
- Alternatively, the inconsistent samples have to be removed manually or automatically, but that might be a grand challenge to do.

B-spline approximation

- The spline method showed robust and accurate results where the geometry of branches is approximately linear since we used linear splines for simplicity.
- To overcome the issue with inconsistent sampling, we find an intersection of the fitted spline with the plane of the next cross-sectional image.
- The method can be improved by using quadratic or cubical splines; however, finding multiple intersections with a plane in 3D might not be a simple task to do.
- The downside of the method is the pre-defined assumption of curves' shapes, i.e. linear, quadratic etc. without the ability to generalize.

Recommendations for improvements and future research

- The process of generating new labelled data based on the outputs of the trained standalone CNN involves the only one trained person and observation of images without context. It would be beneficial to look at each image and its neighbors from the same edge as well have a better-designed protocol.
- Process the data in a hierarchical manner as opposed to a random draw of individual cross-sections or branches. This way, we could benefit from the inclusion of contextual and structural information. Algorithms based on convolutional LSTM or graph neural networks would be a good choice.
- Sampling in 3D (cubes or spheres) as opposed to 2D.
- Focus on bifurcation points. The challenge is that cross-sectional images of bronchi at bifurcation look different from a ring-shaped single bronchus.

Thank you!