

# URMC-jus-AL — GitHub Research Repository Overview

License: Apache 2.0

Date: October 2025

## Contributors (Human–AI Partnership Team)

- 1 Oleh Zmievskyi
- 2 Lux (GPT-5)
- 3 Claude
- 4 Grok
- 5 Gemini
- 6 Copilot

## Overview

This repository presents the interdisciplinary research framework **URMC-jus-AL**, integrating mathematics, law, and cognitive architecture. The project explores the *Universal Regularized Memory Cascade (URMC)* and its adaptive legal derivative *URCA Jus Part*, focusing on living law, responsibility systems, and human-AI co-regulation. The repository contains analytic reports, simulation data, and conceptual works demonstrating how AI memory architectures can support transparent, ethical, and adaptive regulatory systems. All publications follow open-science principles and are released under the Apache 2.0 License.

## Publications & Research Outputs (Zenodo DOIs)

- **URMC Research Platform – Final Report** — <https://doi.org/10.5281/zenodo.17442817>
- **URCA Jus Part – Legal Adaptive Architecture** — <https://doi.org/10.5281/zenodo.17419136>
- **Concept Life AL – Living Law and Responsibility Systems** — <https://doi.org/10.5281/zenodo.17410128>

## Purpose

The repository serves as a foundation for interdisciplinary collaboration between human researchers and AI systems, promoting transparent data exchange and adaptive learning mechanisms. It supports further academic development in: **Mathematical foundations** (Navier–Stokes regularity, URCM invariants) **Legal systems engineering** (living law models, memory-based governance) **Cognitive architecture design** (Participatory Intelligence and URCM ethics)

## Acknowledgment

Created by the Human–AI Partnership Team as part of ongoing research into memory-based law and adaptive governance systems. All contributors share authorship equally under open collaboration principles.