

# Confidence Intervals

Christos Dimitrakakis

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# Outline

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Simple Hypothesis Tests

## Mean estimation

Estimating a mean

Concentration inequalities

## Exercises

Subgaussianity

Conditional probability

Hypothesis testing

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# Simple hypothesis tests

- ▶ Consider  $n$  hypotheses,  $H_1, \dots, H_n \in \mathcal{H}$
- ▶ Each hypothesis corresponds to a model  $P(x|H_i)$  giving a probability value to every possible data  $x \in X$ .
- ▶ Given specific data  $x$ , we want to select the most likely model.

## Maximum Likelihood

Pick the model with the highest likelihood:

- ▶  $\hat{H} = \arg \max_{H_i} P(x|H_i)$

## Maximum A Posteriori

- ▶ Given prior  $P(H_i)$
- ▶ Pick  $\hat{H} = \arg \max_{H_i} P(H_i|x)$
- ▶ We use Bayes's theorem to calculate the posterior  $P(H_i|x)$ .
- ▶ When  $P(H_i)$  is uniform, it is the same as maximum likelihood.

# The Theorem of Bayes

- ▶ Given some probability space  $(P, \Omega, \Sigma)$ .
- ▶  $P$  is a probability measure on  $\Omega$
- ▶  $\Omega$  is the outcome space.
- ▶  $\Sigma$  is a collection of subsets of  $\Omega$ , corresponding to events.
- ▶ Let  $\{H_i\}$  be a partition of  $\Omega$ , i.e.

$$H_i \cup H_j = \emptyset \quad \forall i \neq j, \quad \bigcup_i H_i = \Omega.$$

Then, for any event  $A \in \Sigma$ ,  $A \subset \Omega$ ,

$$P(H_i|A) = \frac{P(A|H_i)P(H_i)}{\sum_j P(A|H_j)P(H_j)}$$

# Proof of Bayes's theorem

Note that  $P(H_i \cap A) = P(H_i|A)P(A) = P(A|H_i)P(H_i)$ . Rearranging,

$$P(H_i|A) = \frac{P(A|H_i)P(H_i)}{P(A)}.$$

Since  $\{H_i\}$  is a partition,

$$P(A) = P\left(\bigcup_i A \cap H_i\right) = \sum_i P(A \cap H_i) = \sum_i P(A|H_i)P(H_i)$$

## Extensions

- We can use any non-negative scoring function  $f_h(x)$ :

$$P(h|x) = \frac{f_h(x)P(h)}{\sum_{h' \in \mathcal{H}} f_{h'}(x)P(h')}$$

- For infinite  $\mathcal{H}$  we can use this notation:

$$P(B|x) = \frac{\int_B f_h(x)dP(h)}{\int_{\mathcal{H}} f_h(x)dP(h)}, \quad B \subset \mathcal{H}.$$

# Null Hypothesis Tests

- ▶ Consider a model  $H_0$  such that  $P(x|H_0)$  is known.
- ▶ We need to compare against an **unknown** alternative.
- ▶ We calculate a **statistic**  $s : X \rightarrow \mathbb{R}$  to partition  $X$  in  $S_0, S_1$  i.e.

$$S_0 = \{x : s(x) \leq \theta\}, \quad S_1 = \{x : s(x) > \theta\}$$

- ▶ Then  $P(S_0|H_0) = 1 - \alpha$ ,  $P(S_1|H_0) = \alpha$  for some  $\alpha$
- ▶ We tune  $\theta$  to achieve the desired  $\alpha$ .
- ▶ If  $x \in S_0$ , we accept  $H_0$ , otherwise we reject it.

## Example statistics

- ▶ Likelihood test:  $s(x) = P(x|H_0)$ ,
- ▶ Mean test:  $s(x) = |x - \mathbb{E}[x|H_0]|^2$ .

# Likelihood test

- ▶ We can use  $s(x) = P(x|H_0)$ .
- ▶ Now we can choose a threshold  $\theta$  so that:

$$S_1 = \{x : s(x) \geq \theta\}$$

## Example: Laplace distribution

- ▶ Density:  $f(x|\mu, \lambda) = \frac{1}{2\lambda} e^{-\frac{1}{\lambda}|x-\mu|}$
- ▶  $H_0: x \sim \text{Laplace}(0, 1)$ .
- ▶  $f(x|0, 1) \geq \theta$  means  $|x| \leq \ln(1/2\theta)$ . So

$$P(S_1|H_0) = \int_{-\infty}^{-\ln(1/2\theta)} e^{-x} dx = 1/2\theta.$$

- ▶ Consequently,  $\theta = 1/2(1 - \alpha)$ , i.e. we accept  $H_0$  if  $|x| \leq \ln(4 - 4\alpha)$

# Bernoulli test

- ▶  $H_0$ : The coin tosses are fair
- ▶ Then the probability of any sequence  $x = x_1, \dots, x_T$  is  $2^{-T}$ .
- ▶ The expected number of heads is  $T/2$ .
- ▶ Statistic  $s(x) = \sum_t x_t$ .
- ▶ Select interval  $S = [cT, (1 - c)T]$ .
- ▶ There is some  $c \in [0, 1/2]$  so that  $P(S|H_0) = 1 - \alpha$
- ▶ To calculate  $c$  we can use the inverse CDF of  $s$ .

# p values

## How to use $p$ values

- ▶ First select a significance threshold  $\alpha$ .
- ▶ Collect the data, obtain the  $p$  value
- ▶ If  $p \leq \alpha$ , reject the null hypothesis  $H_0$ .
- ▶ This ensures that, if  $H_0$  is true, the probability of rejecting it is exactly  $\alpha$ !  
(Because  $p$  is uniform in  $[0, 1]$  under  $H_0$ )

## Problems with $p$ values

- ▶ They do not measure quality of fit on the data.
- ▶ Not robust to model misspecification.
- ▶ They ignore effect sizes.
- ▶ They do not consider prior information.
- ▶ They do not represent the probability of having made an error
- ▶ The null-rejection error probability is the same irrespective of the amount of data (by design).

## Hypothesis testing

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# Mean estimation

- ▶ Data  $D = x_1, \dots, x_T$
- ▶ i.i.d samples  $x_t \sim P$
- ▶ Expectation  $\mathbb{E}_P(x_t) = \mu,$
- ▶ Empirical mean:

$$\hat{\mu}(D) = \frac{1}{T} \sum_{t=1}^T x_t.$$

## The error of the empirical mean

Since the data  $D$  is random, what is the probability that our estimate is far away from  $\mu$ ?

$$\mathbb{P}[|\hat{\mu}(D) - \mu| > \epsilon] \leq \delta.$$

This means that the probability that our error is larger than  $\epsilon$  is at most  $\delta$ , with  $\epsilon, \delta > 0$ .

## Two methods:

- ▶ Distribution-specific confidence intervals
- ▶ Concentration inequalities

# Distribution-specific intervals

## Bernoulli

If  $x_t \sim \text{Bernoulli}(\mu)$ , then the distribution of  $\hat{\mu}$  is given by the Binomial distribution.

## Binomial

Let  $n_t = \sum_{i=1}^t x_i$ , where  $x_t \sim \text{Bernoulli}(\mu)$ . Then  $n_t$  has a binomial distribution with parameter  $\mu$  and  $t$  trials, i.e.  $n_t \sim \text{Binomial1}(\mu, t)$ , and its probability function is

$$\mathbb{P}(n_t = k) = \binom{t}{k} \mu^k (1 - \mu)^{1-k}$$

# Markov's Inequality

If  $x \geq 0$

$$\mathbb{P}(x \geq u) \leq \frac{\mathbb{E}[x]}{u}$$

## Proof

$$\mathbb{E}[x] = \int_0^\infty xp(x)dx \tag{1}$$

$$= \int_0^u xp(x)dx + \int_u^\infty xp(x)dx \tag{2}$$

$$\geq \int_u^\infty up(x)dx \tag{3}$$

$$= u \mathbb{P}(x \geq u) \tag{4}$$

# Chernoff bound

The Chernoff bound uses the fact that if  $x \geq y$  is true, then  $f(x) \geq f(y)$  for any monotonic increasing function  $f$ . In particular:

$$\mathbb{P}(x - \mu \geq u) = \mathbb{P}(e^{\lambda(x-\mu)} \geq e^{\lambda u}) \leq \frac{\mathbb{E}[e^{\lambda(x-\mu)}]}{e^{\lambda u}}$$

- ▶ This follows directly from Markov's inequality.
- ▶ Tuning  $\lambda$  gives us the tightest bound.
- ▶ An example is a bound on the tail of the normal distribution, given next.

## Normal tail bound

### Moment generating function

If  $x \sim \text{Normal}(\mu, \sigma^2)$  then

$$\mathbb{E}[e^{\lambda x}] = e^{\mu\lambda + \sigma^2\lambda^2/2} \quad (5)$$

## Proof

$$\begin{aligned} \mathbb{E}[e^{\lambda x}] &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{\lambda x} e^{-\frac{|x-\mu|^2}{2\sigma^2}} dx \\ &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{\lambda x - \frac{|x-\mu|^2}{2\sigma^2}} dx \\ &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{\lambda(\sqrt{2}\sigma y + \mu) - y^2} dy \end{aligned}$$

where  $y = (x - \mu)/(\sqrt{2}\sigma)$ , so  $x = \sqrt{2}\sigma y + \mu$ .

## Normal tail bound

If  $x_t \sim \text{Normal}(\mu, 1)$ , then

$$\mathbb{P}(|x_t - \mu| > \epsilon) \leq 2e^{-\epsilon^2/2}$$

Confidence Intervals

# Normal bound

We can use the above tail bound to prove a bound on the error of the empirical estimate  $\hat{\mu}$  of a normal with mean  $\mu$  after observing  $T$  samples.

- ▶  $\hat{\mu} \sim \text{Normal}(\mu, 1/T)$ .
- ▶ For any  $c > 0$ ,  $\mathbb{V}[cx] = c\mathbb{V}[x] \Rightarrow T\hat{\mu} \sim \text{Normal}(T\mu, 1)$ . So:

$$\mathbb{P}(|T\hat{\mu} - T\mu| \geq \epsilon) \leq 2e^{-\epsilon^2/2} \quad \text{from the tail bound} \quad (6)$$

$$\mathbb{P}(|\hat{\mu} - \mu| \geq \epsilon/T) \leq 2e^{-\epsilon^2/2} \quad \text{as } a \geq b \Leftrightarrow ca \geq cb \text{ for } c > 0 \quad (7)$$

$$\mathbb{P}(|\hat{\mu} - \mu| \geq u) \leq 2e^{-T^2u^2/2} \quad \text{where } u = \epsilon/T \quad (8)$$

Can we prove something more general? Yes!

# Subgaussian random variables

## Definition (Subgaussianity)

$x$  is  $\sigma$ -subgaussian if  $\mathbb{E}[\exp(\lambda x)] \leq \exp(\lambda^2 \sigma^2 / 2)$ ,  $\forall \lambda \geq 0$ .

## Theorem (Subgaussian bound)

If  $x$  is  $\sigma$ -subgaussian then, for all  $\epsilon \geq 0$ ,

$$\mathbb{P}(x \geq \epsilon) \leq \exp\left(\frac{\epsilon^2}{2\sigma^2}\right) \quad (9)$$

## Proof.

Using a Chernoff bound, and the definition of subgaussianity,

$$\begin{aligned} \mathbb{P}(x \geq \epsilon) &= \mathbb{P}(\exp(\lambda x) \geq \exp(\lambda \epsilon)) \leq \mathbb{E}[\exp(\lambda x)] \exp(-\lambda \epsilon) \\ &\leq \exp\left(\frac{\lambda^2 \sigma^2}{2} - \lambda \epsilon\right). \end{aligned}$$

Finally, set  $\lambda = \epsilon/\sigma^2$ .



# Application of subgaussian bounds

- ▶ If  $x$  is  $\sigma$  subgaussian then  $\mathbb{E}[x] = 0$ ,  $\mathbb{V}[x] \leq \sigma^2$
- ▶  $cX$  is  $|c|\sigma$  subgaussian for all  $c \in \mathbb{R}$ .
- ▶ If  $x_1, x_2$  are  $\sigma_1, \sigma_2$  subgaussian then

$x_1 + x_2$  is  $\sqrt{\sigma_1^2 + \sigma_2^2}$  subgaussian.

The above facts lead to the following corollary:

## Corollary

If  $x_t - \mu$  are independent  $\sigma$  subgaussian and

$$\hat{\mu} = \frac{1}{T} \sum_{t=1}^T x_t$$

$$\mathbb{P}(\hat{\mu} \geq \mu + \epsilon) \leq \exp\left(-\frac{n\epsilon^2}{2\sigma^2}\right)$$

# Hoeffding bound

- If  $x \in [a, b]$  then it is  $(b - a)/2$  subgaussian. This directly leads to the following inequality:<sup>1</sup>

## Hoeffding Inequality

For any sequence of independent (but not identical) rv's  $x_1, \dots, x_T$ , with  $x_t \in [a_t, b_t]$ , and consider the sum  $s_T = \sum_{t=1}^T x_t$ , which is also random. Then

$$\mathbb{P}(s_T \geq \mathbb{E}[s_t] + \epsilon) \leq \exp\left(-\epsilon^2 / \sum_t (b_t - a_t)^2\right).$$

## Corollary

For any sequence of independent rv's  $x_1, \dots, x_T$ , with  $x_t \in [0, 1]$ , with expectation  $\mathbb{E}[x_t] = \mu$  it holds for the empirical mean  $\hat{\mu}_T = \frac{1}{T} \sum_{t=1}^T x_t$ :

$$\mathbb{P}(|\mu - \hat{\mu}_T| \geq \epsilon) \leq 2 \exp(-2T\epsilon^2)$$

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<sup>1</sup>There other ways of proving it, but this is the easiest given the previous development

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# Subgaussianity

Prove the following statements:

- ▶ [easy] If  $x$  is  $\sigma$  subgaussian, then  $cx$  is  $c\sigma$  subgaussian
- ▶ [medium] If  $x_i$  are  $\sigma$  subgaussian then  $\sum_i x_i$  is  $\sqrt{\sum_i \sigma_i^2}$  subgaussian
- ▶ [hard] if  $\mathbb{E}[x] = 0$  and  $x \in [a, b]$  then  $x$  is  $(b - a)/2$  subgaussian.

# Bayesian Reasoning

You are tested for COVID and found negative. The doctor says that the probability of a false positive (i.e. that the probability that the test is positive if you do not have COVID) is  $1/10$  and the probability of a negative test if you have COVID is  $1/5$ . The prevalence of COVID in the population is  $1/10$ . What is the probability that you actually have COVID?

# A statistical test

- ▶ We have data  $x_t$  and the sample mean  $\hat{\mu}_T = \frac{1}{T} \sum_{t=1}^T x_t$ .
- ▶ The null hypothesis  $H_0$  is that  $x_t \sim \text{Bernoulli}(1/2)$ .
- ▶ The alternative  $H_1$  is that  $x_t \sim \text{Bernoulli}(\mu)$ , with  $\mu \neq 1/2$ .
- ▶ You have a statistical test which, for any significance level  $\alpha \in [0, 1]$ , returns  $S_1$  when  $H_0$  with probability  $\alpha$ . This is implemented by choosing a threshold  $\tau$  so that

$$\mathbb{P}(|\hat{\mu}_T - 0.5| \geq \tau \mid H_0) = \alpha.$$

However, this tells us nothing about  $\mathbb{P}(S_0 \mid H_1)$ . Using Hoeffding's inequality, show for which values of  $\mu \neq \frac{1}{2}$ , we have that  $\mathbb{P}(S_0 \mid H_1) \leq \alpha$ , i.e.

$$\mathbb{P}(|\hat{\mu}_T - 0.5| < \tau \mid \mu) \leq \alpha$$

Hint: Define  $\Delta = |\mu - \frac{1}{2}|$ . Show that, this holds when  $\Delta > \sqrt{\ln(2/\alpha)/2T} + \tau$ .