

Clustering

□ Given $N \times d$ data matrix: X

- Each row is one sample, x_n

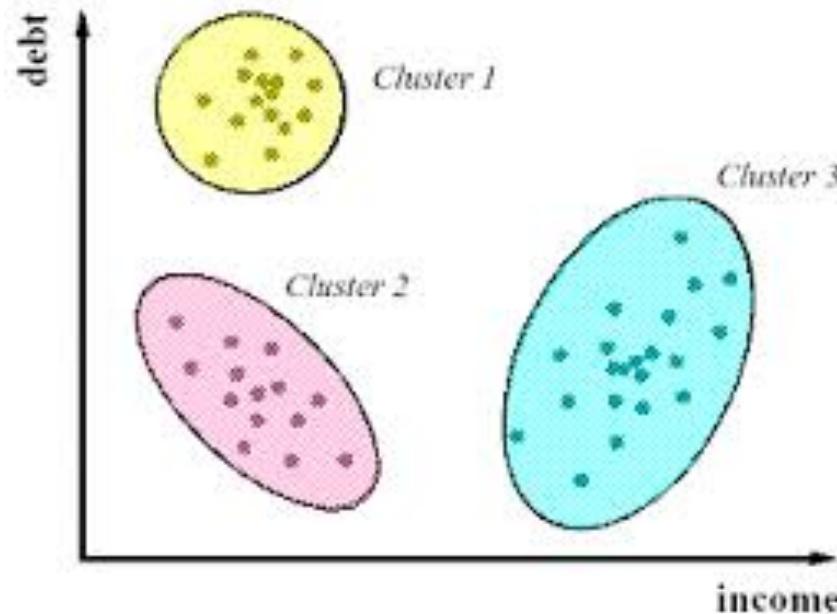
□ Problem: Group data into K clusters

□ Mathematically:

- Assign each sample to a cluster
- Assign $\sigma_n \in \{1, \dots, K\}$: Cluster label for each sample

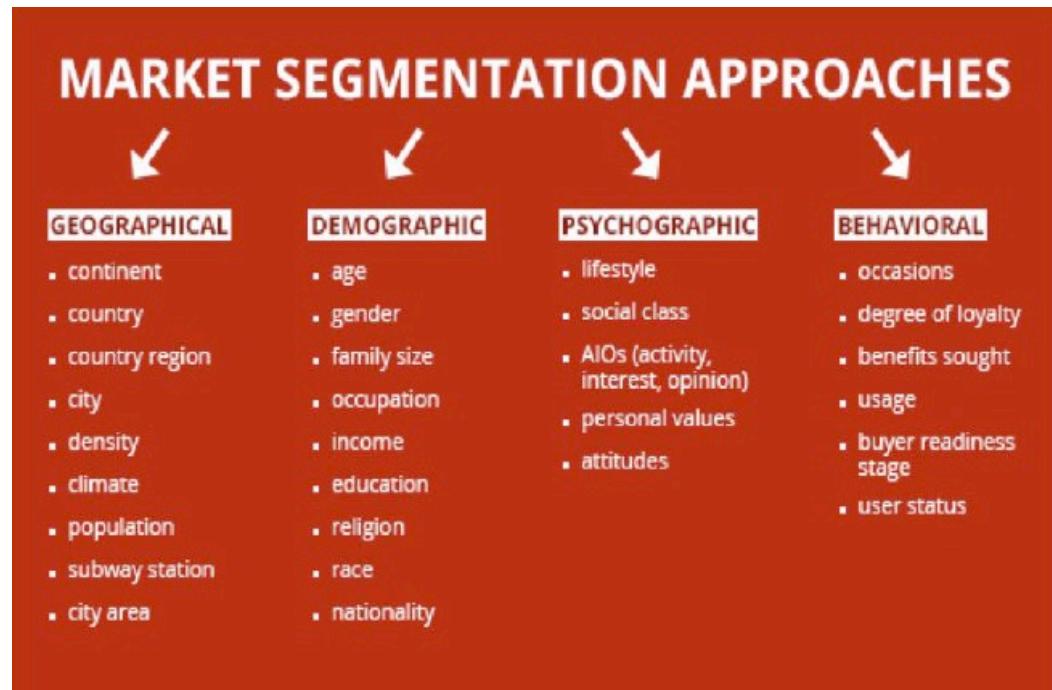
□ Want samples in same cluster to be “close”

- $\|x_n - x_m\|$ is small when $\sigma_n = \sigma_m$



Clustering

- ❑ Clustering has many applications
 - Any time you want to segment data
 - Uncovering latent discrete variables
- ❑ Examples:
 - Segmenting sections of an image
 - Segmenting customers in market data

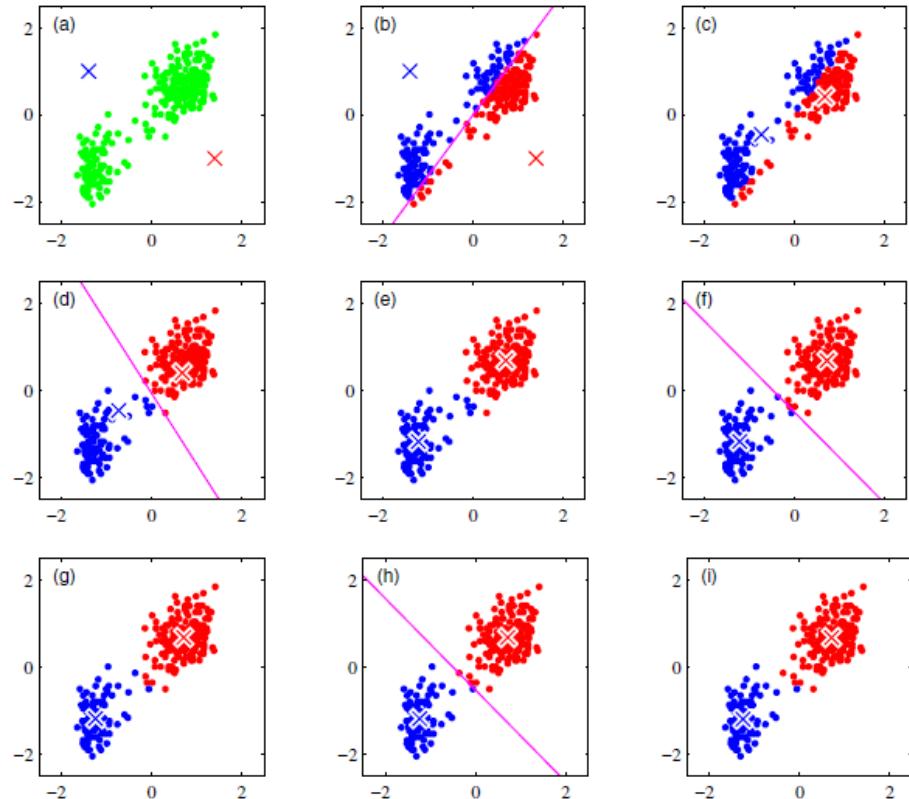


From: Market segmentation possibilities in the tourism market context of South Africa

K-means

- ❑ A simple iterative algorithm to determine:
 - μ_i = mean of each cluster (hence, the name K-means)
 - $\sigma_n \in \{1, \dots, K\}$ = cluster that data point x_n belongs to
 - Minimize: $J = \sum_{i=1}^K \sum_{n \in C_i} \|x_n - \mu_i\|^2$ (MSE of all samples in C_i from its center)
- ❑ Step 0: Start with guess at σ_n or μ_i
- ❑ Step 1: Update mean of each cluster: μ_i = average of x_n in C_i (centroid rule)
- ❑ Step 2: Update cluster membership: $\sigma_n = \arg \min_i \|x_n - \mu_i\|^2$ (nearest neighbor rule)
- ❑ Return to step 1

K-Means illustrated



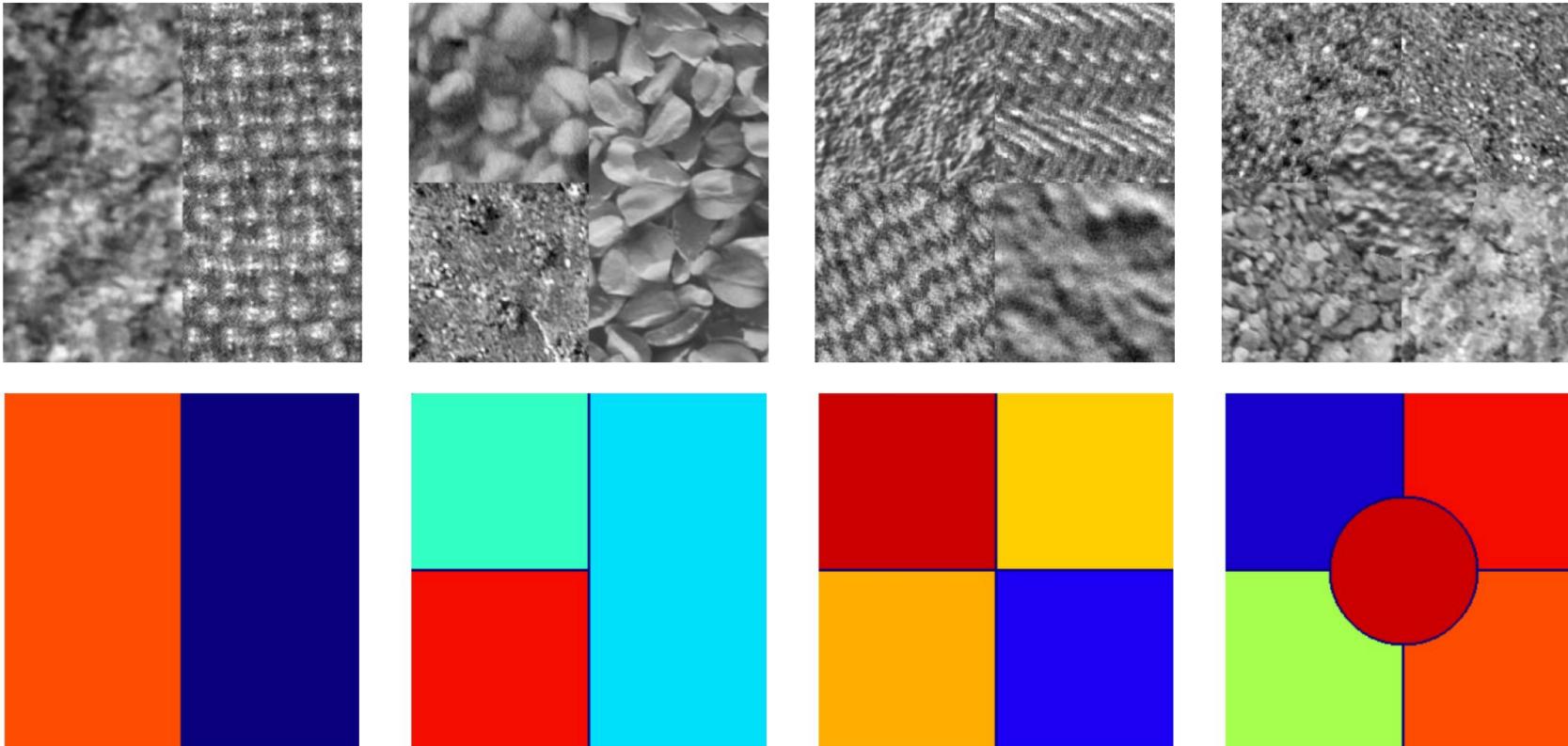
- ❑ From Bishop, Chapter 9.
- ❑ K-Means on “old faithful” data set

Image Segmentation Based on Color



- ❑ Also from Bishop.
- ❑ Use K-means on the RGB values (dimension = 3)

Image segmentation based on texture



Texture at each pixel is usually described by some statistics of the neighborhood surrounding the pixel.

Convergence

- ❑ Will always converge to a “local” minima of cost function

$$J = \sum_{i=1}^K \sum_{n=1}^N r_{ni} \|x_n - \mu_i\|^2$$

- Subject to $r_{ni} = 0$ or 1 and $\sum_i r_{ni} = 1$

- ❑ K-means alternately decreases J

- Proof on board

- ❑ But, can get stuck in a local minima

- May need good selection of initial condition

Distance measures

❑ Distance measures

- How to measure **similarity** between samples?
- Above algorithms used squared distance $\|x_n - x_m\|$

❑ Many possibilities

- What features to use?
- Should you normalize entries?
- What distance metric should you use?

Initialization

❑ Initialization:

- Final limit of K-means depends on initial condition
- May obtain poor clustering with bad initial condition

❑ Possible solutions:

- K-means++: <http://ilpubs.stanford.edu:8090/778/1/2006-13.pdf>
- Provides good initial condition based on data
- Multiple initial starts