Scientific Methods and Communication Conference 2017

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The effect of limb position on myoelectric prosthetic control using linear regression

Group 7404

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Myoelectric prosthetics



The effect of limb position on myoelectric prosthetic control using linear regression

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Myoelectric prosthetics

Variations in limb positions lower accuracy [1]

[1] Fougner et al. IEEE TNSRE (2011)



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- ► Myoelectric prosthetics
- Variations in limb positions lower accuracy [1]
- Classification [1] vs regression [2]

[1] Fougner et al. IEEE TNSRE (2011) [2] Hahne et al. IEEE TNSRE (2014)



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- ► Myoelectric prosthetics
- Variations in limb positions lower accuracy [1]
- Classification [1] vs regression [2]
- Test performance of linear regression- based control across different limb positions

[1] Fougner et al. IEEE TNSRE (2011) [2] Hahne et al. IEEE TNSRE (2014)



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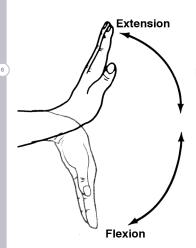
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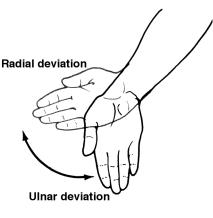
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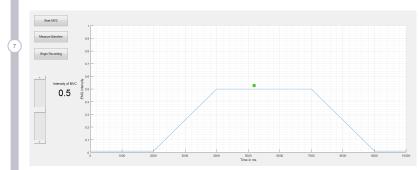
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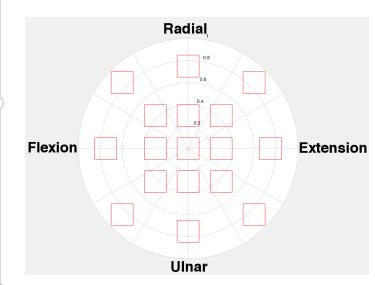
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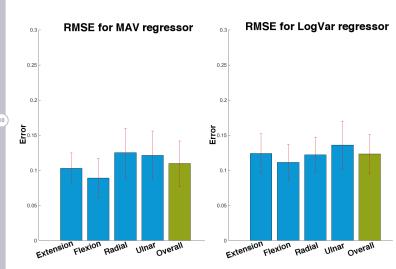
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Significant difference between MAV and LogVar (p = 0.0007)

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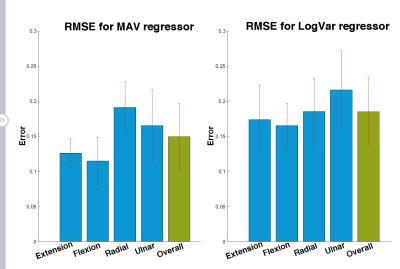
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Significant difference between MAV and LogVar (p = 0.00082)

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- ➤ Significant difference between MAV training and MAV test data (p = 0.0002)
- ➤ Significant difference between LogVar training and LogVar test data (p = 0.0002)



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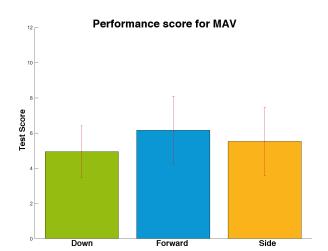
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No significant difference between limb positions (p = 0.16)

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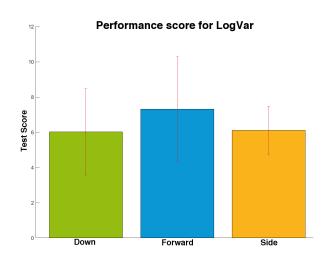
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No significant difference between limb positions (p = 0.56)

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No significant difference between MAV and LogVar (p = 0.13)

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 No significant difference in performance across limb positions



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 No significant difference in performance across limb positions

No correlation between offline and online test



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 No significant difference in performance across limb positions

- ▶ No correlation between offline and online test
- No significant difference in performance between the MAV and LogVar feature



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 No significant difference in performance across limb positions

- ► No correlation between offline and online test
- No significant difference in performance between the MAV and LogVar feature
- ► Large potential in linear regression-based myoelectric prosthetic control



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- Test subjects and Mikkel Birkedal

Thank you

