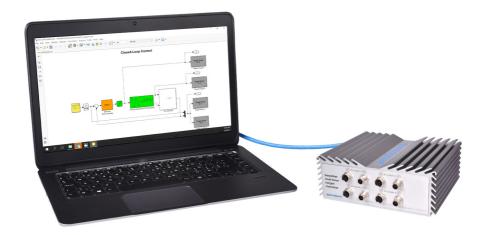
baseline real-time target machine

Quick Start Guide



Download the full documentation from our customer portal: speedgoat.com/login



Four simple steps for setting up your Baseline real-time target machine and connecting it to a development computer

Speedgoat Customer Portal - Log in at speedgoat.com/login to:

- . Download software and documentation for your Speedgoat hardware
 - Check the status of your warranty and service packages



Install software on the development computer

1. Type ver at the MATLAB command prompt to verify that you have at least the following MathWorks products installed on your development computer:

- MATLAB®
- Simulink®
- MATLAB Coder™
- Simulink Coder™
- Simulink Real-Time™

2. MEX and C compiler (required for code generation)

- Install a supported C-compiler for Simulink Real-Time. The required compiler version is dependent on your MATLAB release - see www.mathworks.com/support/compilers for details.
- · Run MATLAB as Administrator.
- Set the default compiler by typing mex -setup at the MATLAB command prompt.

3. Install the Speedgoat library for Simulink Real-Time

- Download the Speedgoat library from the Speedgoat Customer Portal and unzip.
- Within MATLAB navigate to the root folder of the downloaded library.
- Run speedgoat_setup at the MATLAB command prompt and follow the instructions
- Once the installation process has finished, restart MATLAB.



4. Add MathWorks Updates

MathWorks provides updates with improvements for specific MATLAB releases. Updates for your release
will be available in the Speedgoat Customer Portal, under Downloads -> Support. It's important that they
are all downloaded and installed.

Once the Speedgoat library has been installed, complete documentation is available from within MATLAB. Just type <code>speedgoat</code> at the MATLAB command prompt.



Connect your target machine

Your target machine is ready to use out of the box:

- Connect the provided AC/DC power supply to the rear 'Power Input' connection.
- Connect the supplied Ethernet cable between the target machine 'Host Link' connection and the development computer.
- Connect a monitor (recommended but not required) using the 'DisplayPort' connection.
- The target machine will power on automatically. If needed, power can be controlled via the small power button on the front.



To establish communications between the development computer and target machine, Windows and MATLAB network settings must be configured. Your target machine comes preconfigured for the version of MATLAB you requested, and for a direct connection to the development computer. See the Software Configuration Guide at speedgoat.com/help for more information.

Preconfigured target machine TCP/IP settings

Target IP address 192.168.7.1 Port 22222

Subnet mask 255.255.255.0 Gateway 255.255.255.255



Configure Windows network settings

 In the Windows 'Network and Sharing Center' on the development computer, configure the 'Internet Protocol Version 4 Properties' for your Ethernet controller as follows:

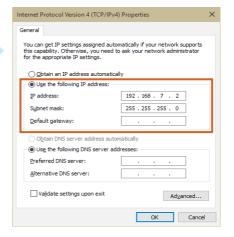
IP address: 192.168.7.2

Subnet mask: 255.255.255.0



Configure MATLAB network settings

- Open Simulink Real-Time Explorer by typing slrtexplr at the MATLAB command prompt on the development computer.
- In the Targets area select "Properties" for the default target, and open the "Host-to-Target communication" section. Configure as follows and save:





- Test host-target communication by typing slrtpingtarget at the MATLAB command prompt.
- You can now perform a system test using the Simulink test model available from the Customer Portal.
 More information about system testing and any required hardware connections is available in the test documentation shipped with your target machine.



Resources

Online documentation: speedgoat.com/help
Support email: support@speedgoat.com
Sales email: sales@speedgoat.com
Telephone: +41 26 670 7550 (General)
+1 508 233 2650 (USA)

+49 5139 97780 51 (Germany)



