

Decision Trees

Oliver Zhao

1 Description

Decision Trees operate on the notion of entropy, defined as

$$H(T) = -p_{pos}\log_2 p_{pos} - p_{neg}\log_2 p_{neg}. \quad (1.1)$$

Decision Trees consist of different nodes that contain decision thresholds for a given attribute at . Based on this threshold, the data set T is divided into subsets T_i . Each sequential layer of nodes leads to more divisions, ultimately resulting in leaves. All training examples in a given leaf are classified as the same class.

In order to calculate the weighted average of the entropies of the subsets T_i for a given attribute at , we first need to calculate the probability that a randomly drawn training sample is in T_i , defined as

$$P_i = \frac{|T_i|}{|T|}. \quad (1.2)$$

Then the weighted average of the entropies of the subsets can be calculated as $H(T, at)$, where

$$H(T, at) = \sum_i P_i \cdot H(T_i). \quad (1.3)$$

In order to examine how much information is *gained* $I(T, at)$ through the addition of an attribute, we compare the entropy before and after the attribute has been considered, where

$$I(T, at) = H(T) - H(T, at). \quad (1.4)$$

While the decision threshold for a given attribute is simple for discrete attributes, an infinite number of thresholds may be chosen for continuous attributes. The number of thresholds for continuous attributes may be narrowed down by ordering the values of a given attribute at in ascending order. Candidate thresholds $\theta_1, \theta_2, \dots$, are located between attribute values with opposite class labels, as any other additional thresholds between these candidate thresholds yield the same outcomes.

