Follow me behavior (detection part) install of your source files

Version for ENSE3 students: local install, no shared online repository

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Follow me behavior (perception part):

- Open a terminal to download the source files needed for the rest of the labs:

  1. `cd ~/ros2_ws/src`
  2. `git clone https://gricad-gitlab.univ-grenoble-alpes.fr/tp_ros2/follow_me.git`
  3. `git clone https://gricad-gitlab.univ-grenoble-alpes.fr/tp_ros2/action.git`
  4. You should see two new folders : follow_me and action, in addition to the previously downloaded smooth_teleop and tutorial_ros folders from Lab1.

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Follow me behavior (perception part):

1.

2. The follow_me git repository's files must be in the folder ~/ros2_ws/src/follow_me/

3. Right click the follow_me folder, and select open => open with => visual studio code
   - ➢ The **header** files are located in ~/ros2_ws/src/follow_me/**include**
     - ➢ Open datmo.h
   - ➢ The **source** files are located in
   - ➢ ~/ros2_ws/src/follow_me/**src**
     - ➢ Open detection_node.cpp (main file)
     - ➢ Open datmo.cpp (to implement your functions)

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