Follow me behavior
(detection part)
install of your source files

Version for ENSE3 students: local install, no shared online repository

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Follow me behavior (perception part):

- Open a terminal to download the source files needed for the rest of the labs:

1. `cd ~/ros2_ws/src`
2. `git clone https://gricad-gitlab.univ-grenoble-alpes.fr/tp_ros2/follow_me.git`
3. `git clone https://gricad-gitlab.univ-grenoble-alpes.fr/tp_ros2/smooth_teleop.git`
4. `git clone https://gricad-gitlab.univ-grenoble-alpes.fr/tp_ros2/action.git`
5. You should see three new folders : follow_me, action, and smooth_teleop, containing the source files.

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Follow me behavior (perception part):

1. The follow_me git repository's files must be in the folder ~/ros2_ws/src/follow_me/
2. Right click the follow_me folder, and select open => open with => visual studio code
    - The **header** files are located in ~/ros2_ws/src/follow_me/**include**
        - Open datmo.h
    - The **source** files are located in
    - ~/ros2_ws/src/follow_me/**src**
        - Open detection_node.cpp (main file)
        - Open datmo.cpp (to implement your functions)

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