view_frames Result

Recorded at time: 1595247438.136

world

Broadcaster: /virtual_joint_broadcaster_0
Average rate: 10.194 Hz
Most recent transform: 1595247438.230 (-0.094 sec old)
Buffer length: 4.905 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1595247438.136 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

base

link_1

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_2

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_3

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_4

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_5

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_6

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1595247438.083 (0.053 sec old)
Buffer length: 4.900 sec

link_7

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1595247438.136 sec old)
Buffer length: 0.000 sec

tool0