# Evidence for adversarial robustness through randomization: a game theoretic perspective?

Toward certified defenses to adversarial example attacks

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#### **Overview**

- I. Introduction to Supervised Learning & Neural Networks.
- II. Adversarial attack & Defense through randomization.
- III. A Game theoretic perspective.

I. Introduction to Supervised

**Learning & Neural Networks** 

# What is Supervised Learning

$$f(x_i) = y_i$$

$$x_1 \quad y_1 = \text{``dog''}$$

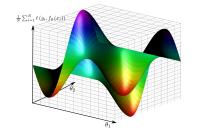
$$x_2 \quad y_2 = \text{``panda''}$$

$$x_n \quad y_n = \text{``cat''}$$

- Given a set of *n* training examples  $\{(x_1, y_1), ..., (x_n, y_n)\} \sim D$ .
- Assumption: there exists a mapping f matching any vector to its label.

**Learning algorithm goal:** Approximate f by a parametrized function  $f_{\theta}$ .

# **Supervised Learning Algorithms**



- To measure how well  $f_{\theta}$  fits f, owe use a **loss function**  $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}^+$ .
- ullet Find the parameter heta that minimize the **generalization error**

$$\left(\mathbb{E}_{(\mathsf{x},\mathsf{y})\sim D}\left[\ell\left(\mathsf{y},\mathsf{f}_{\theta}\left(\mathsf{x}\right)\right)\right]\right)$$

The standard method to find  $\theta$  is the **empirical risk minimization (ERM)**:

$$\hat{\theta}_{ERM} := \operatorname{argmin}_{\theta \in \Theta} \left[ \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i}, f_{\theta}\left(x_{i}\right)\right) \right] \text{ recall: } y_{i} = f(x_{i})$$

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#### **Neural networks**

A **neural network** is a directed and weighted graph, modeling the structure of a **dynamic system**. A neural network is analytically described by list of function compositions.

A Feed forward neural network of N layers is defined as follows:

$$f_{\hat{\theta}_{ERM}} := \phi^{(N)} \circ \phi^{(N-1)} \circ \cdots \circ \phi^{(1)}(x)$$

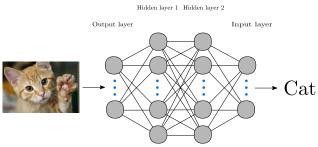
Where for any i,  $\phi^{(i)} := z \mapsto \sigma(W_i z + b_i)$ ,  $b_i \in \mathbb{R}^m$ ,  $W_i \in \mathcal{M}_{\mathbb{R}}(m, n)$  (n size of z), and  $\sigma$  some non linear (activation) function.

**Feed forward networks**, as well as some other specific types of network are said to be **universal approximators** [Cybenko, 1989].

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# Deep neural networks

**Deep neural networks** (large and complex networks) has recently proven outstanding results especially in **image classification**.



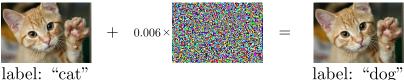
#### No free lunch:

- 1) (Deep) Neural networks lack theoretical guarantees.
- 2) The model is often over-parametrized, which can lead to over-fitting, or to other **flaws in the classification task** (e.g adversarial examples).

# Attacking Models & Defense through Randomization.

#### Adversarial examples

An adversarial attack refers to a small, imperceptible change of an input maliciously designed to fool the result of a machine learning algorithm.

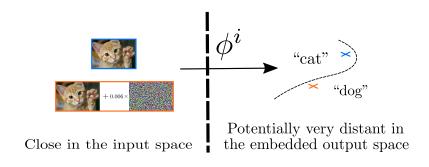


label: "cat"

Since the seminal work of [Szegedy et al., 2014] exhibiting this intriguing phenomenon in the context of deep learning, numerous attack methods have been designed (e.g. [Papernot et al., 2016, Carlini and Wagner, 2017]).

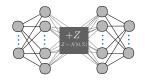
#### **Geometric interpretation**

**Adversarial example:** Neural networks do not preserve distances between images. adversaries take advantage of it to find adversarial examples.



**How to defend?** A learning algorithm should be robust to adversarial examples, if it has a local (small ball around each image) isometric property.

# Defense by randomization



- [Dhillon et al., 2018]: Sampling parameters from a probability measure.
- [Pinot et al., 2019]: Add well selected random noise to parameters.

For a Feedforward network, we modify one/several functions:

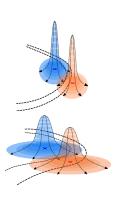
$$ilde{f}_{\hat{ heta}_{\mathsf{ERM}}}(x) = \phi^{(\mathsf{N})} \circ \cdots \circ ilde{\phi}^{(i)} \circ \cdots \circ \phi^{(1)}(x)$$

 $ilde{f}_{\hat{ heta}_{ERM}}(x) = \phi^{(N)} \circ \cdots \circ ilde{\phi}^{(i)} \circ \cdots \circ \phi^{(1)}(x)$ Where  $ilde{\phi}^{(i)}(z) = \sigma(W_i z + b_i)$ , and  $(W_i, b_i) \sim \mathcal{N}(0, \Sigma)$ .

# How does this sampling work?

#### Several possible interpretations:

- Robust optimization: Noise helps locally smoothing the network.
- 2) Geometrical: Noise pushes the decision boundary/makes it "probabilistic".
- 3) Game theory: Equilibrium is achieved using mixed strategies.



# A game theoretic perspective

### Strategic game:

#### **A strategic game** *G* is defined by:

- A set I of N players.
- A set  $S^i$  of strategies (one per player).
- An application  $g: S = \prod_{i \in [N]} S^i \mapsto \mathbb{R}^N$  where each component is  $g^i$  represents the utility function of player i over S.

**Goal:** Strategic games are one-shot games, where everybody plays its move simultaneously. One may want to find out if there exists an equilibrium?

**Equilibrium:** An equilibrium is a strategy  $s \in S$  where no player can increase her utility by deviating alone from s.

# Zero sum game & mixed strategies

#### Zero-sum game:

- There is only 2 players.
- For any  $s \in S$ , one has  $g^1(s) = -g^2(s)$
- Is characterized by  $(S^1, S^2, g^1)$ .



**Mixed strategies:** Under mild assumptions on  $S^1$ ,  $S^2$ , and  $g^1$  one equilibrium can be found in the mixed extension of the game.

This extension is as follows:  $(\Delta S^1, \Delta S^2, \mathbb{E}[g^1])$  where  $\Delta(\bullet)$  denotes the set of probability measures over  $\bullet$ .

#### Adversarial attacks as a game

Goal of the model (defender): find  $\theta$  that minimize the loss over all possible (potentially adversarial) examples.

$$\min_{\theta \in \Theta} \mathbb{E}_{(x,y) \sim D} \left[ \ell \left( y, f_{\theta} \left( x \right) \right) \right]$$

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**Goal of the adversary:** find the best way (best function) to compute a perturbation that fools  $f_{\theta}$  for any image x from the ground-truth distribution.

$$\max_{g \in \mathcal{G}} \mathbb{E}_{(x,y) \sim D} \left[ \ell \left( y, f_{\theta} \left( x + g \left( x \right) \right) \right) \right]$$

#### A Zero-sum game

Can be seen as a Zero-sum game with the following objective function:

$$\boxed{\mathbb{E}_{(x,y)\sim D}\left[\ell\left(y,f_{\theta}\left(x+g\left(x\right)\right)\right)\right]}$$

- From classical game theory, it makes sense to use mixed strategies, i.e players should sample from  $\Theta$  and  $\mathcal{G}$ , according to some distribution.
- The solution we gave earlier is a mixed strategy. Is it an optimal one?

We can use game theoretical arguments to justify procedures from machine learning, and to study them!

#### Conclusion

- Treating the problem of adversarial example can be both considered as a game theoretic and a machine learning problem.
- Both seem to converge to the same conclusion: randomization matters.



**Conclusion:** Pole 1, 2, and 3 should work together on this issue ;-).

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