

Computational imaging on MultiCore Fibers.

LINMA2120 - Applied mathematics seminar

O. Leblanc.

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O. Leblanc*



L. Jacques*



M. Hofer†



H. Rigneault†



S. Sivankutty‡

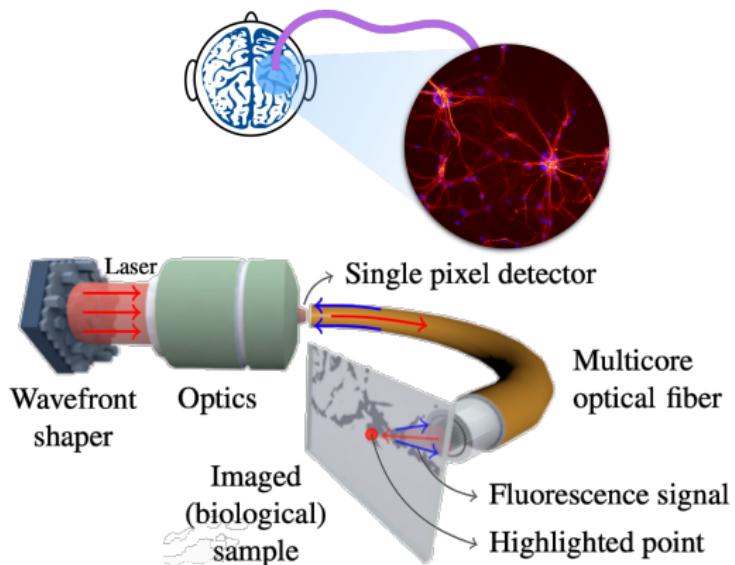
* ISPGGroup, ICTEAM, UCLouvain, Belgium

† Institut Fresnel, Marseille France

‡ CNRS, Université de Lille

Context

Context - Lensless endoscopy



O. Leblanc



L. Jacques



M. Hoffer



H. Rigneault



S. Sivankutty

Outline

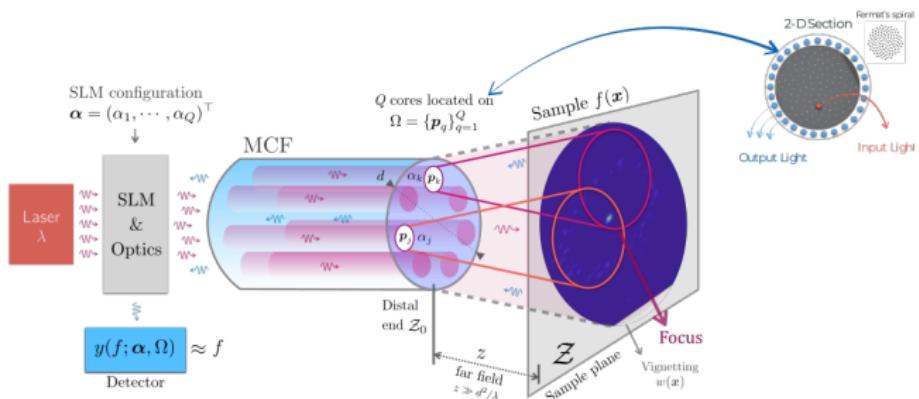
1. Context
2. Existing models: Raster Scanning (RS) and Speckle Illuminations (SI)
3. Interferometric MCF Imaging

Existing models: Raster Scanning (RS) and Speckle Illuminations (SI)

Outline

1. Context
2. Existing models: Raster Scanning (RS) and Speckle Illuminations (SI)
 - 2.1 Raster scanning
 - 2.2 Speckle illumination
3. Interferometric MCF Imaging

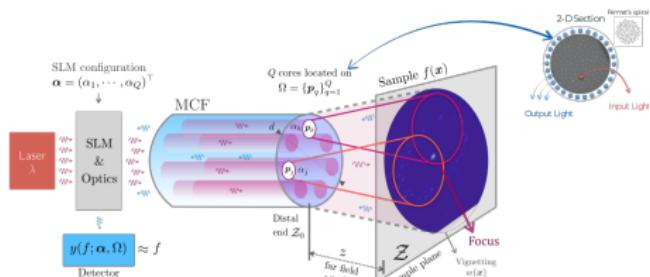
Raster scanning (RS) mode



The diagram illustrates the convolution operation in RS mode. It shows three images: a grayscale input image x , a circular mask φ (highlighted in red), and a resulting grayscale output image y . The operation is represented by the equation $x * \varphi = y$.

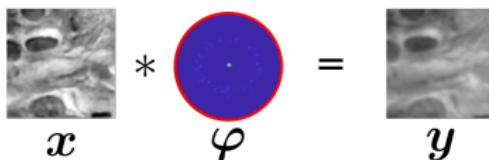
RS mode

Forward model: $\mathbf{y} = \varphi * \mathbf{x}$.
 → Deconvolution problem!



Drawbacks:

- ▶ $M = N$.
- ▶ φ spatially varying.



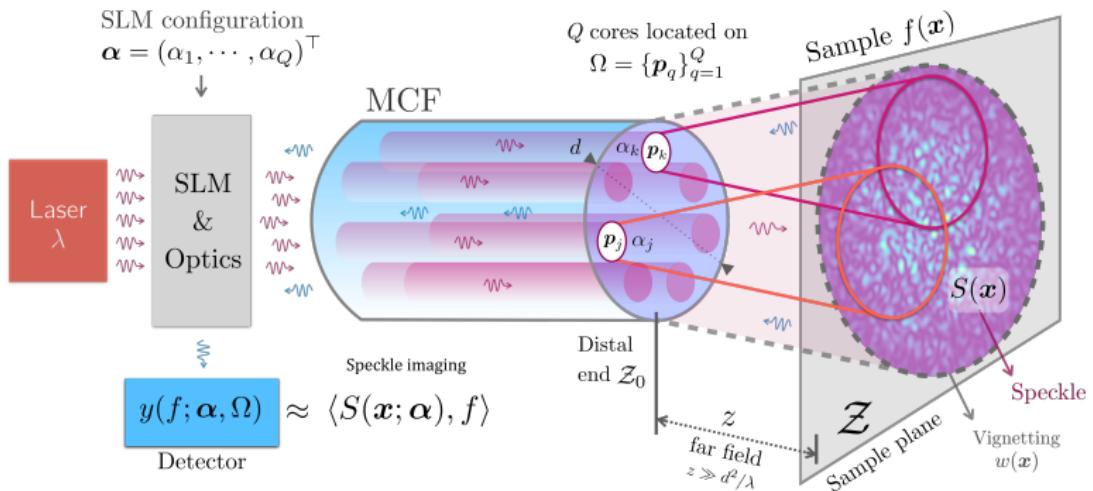
Outline

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2. Existing models: Raster Scanning (RS) and Speckle Illuminations (SI)
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Speckle illumination



Steph. Guérit



Classical Compressive Sensing

$$y_m = \mathbf{a}_m^\top \mathbf{x}$$

$$y_m = \mathbf{a}_m^\top \mathbf{x} = \langle \mathbf{a}_m, \mathbf{x} \rangle$$

Classical Compressive Sensing

$$\begin{matrix} \mathbf{y} \\ \mathbf{x} \end{matrix} = \boxed{\mathbf{A}}_{M \times N} \begin{matrix} \mathbf{x} \\ \mathbf{x} \end{matrix}$$

The diagram illustrates the mathematical model of Classical Compressive Sensing. On the left, a vertical vector \mathbf{y} is shown as a stack of colored blocks (green, blue, red, yellow, orange). An equals sign follows. In the center is a matrix \mathbf{A} with dimensions $M \times N$, represented by a grid of colored blocks (green, blue, red, yellow, orange) with a dashed border. To the right of the matrix is a vertical vector \mathbf{x} consisting of N stacked boxes. Ellipses between the second and third boxes indicate intermediate values.

Condition: a_{mn} are iid random variables (e.g., $a_{mn} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$).

Speckle illumination: model

The m -th single pixel observation is the integration of the m -th speckle pattern \mathbf{s}_m illuminating the sample \mathbf{f} :

$$y_m = \mathbf{s}_m^\top \mathbf{f} + n_m.$$



Classical compressive sensing model (Guerit et al.)

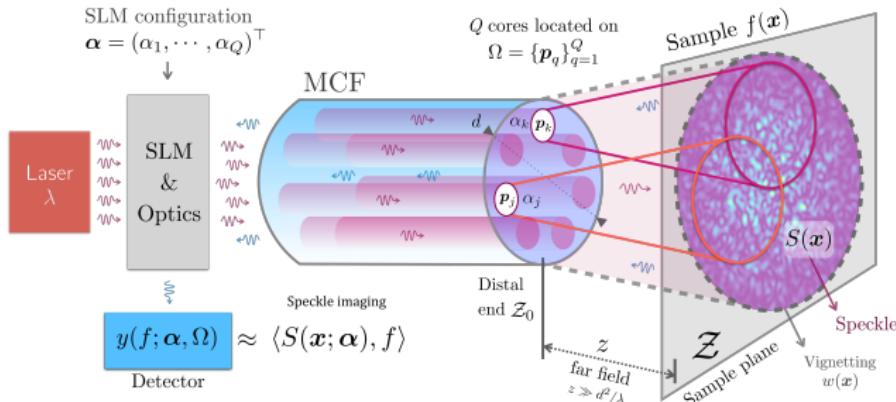
$$\mathbf{y} = \mathbf{S}\mathbf{f} + \mathbf{n}$$

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} \frac{1}{2} \|\mathbf{y} - \mathbf{S}\mathbf{f}\|_2^2 + \mathcal{R}(\mathbf{f})$$

Compressive imaging \Rightarrow number of observations $M \ll N$ image resolution.

Assumption: all coefficients in \mathbf{S} are i.i.d. random variables.

A closer look to sensing model



Generating a N pixels speckle from only Q random coefficients $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_Q) \dots$

Why would this behave as a random gaussian waveform?

Interferometric MCF Imaging

Overview

Mathematical modeling



SLM configuration
 $\alpha = (\alpha_1, \dots, \alpha_Q)^\top$



$$y(f; \alpha, \Omega) \approx \alpha^* \mathcal{T}[w f] \alpha$$

Low structure



Inverse problem
& optimisation



Theoretical guarantees



Q cores located on
 $\Omega = \{p_q\}_{q=1}^Q$

Sample $f(x)$

Speckle

Vignetting
 $w(x)$

Sample plane

Distal end Z_0

z
 $far field$
 $z \gg d^2/\lambda$

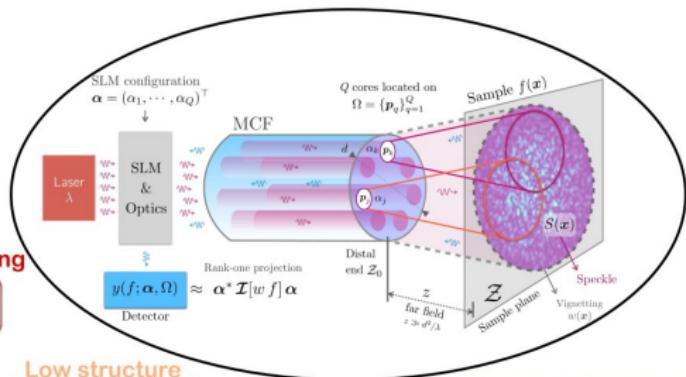
Proof of concept



Mathematical modeling

Mathematical modeling

$$y_m = g(f; \boldsymbol{\alpha}_m) ?$$



Low structure

?

Inverse problem
& optimisation

?

Theoretical guarantees

?

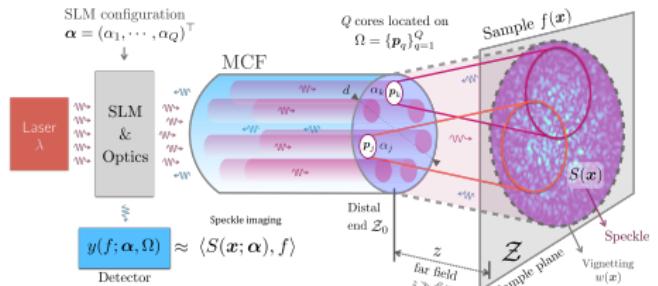
Proof of concept

?

Interferometric imaging

Classical compressive sensing model

$$y_{\alpha} = \int_{\mathbb{R}^2} S_{\alpha}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} = \langle S_{\alpha}, f \rangle$$



Speckles are interferences (Under far-field approximation)

$$E_q(\mathbf{x}) = \alpha_q \sqrt{w(\mathbf{x})} e^{\frac{2\pi i}{\lambda z} \mathbf{p}_q^\top \mathbf{x}}, \quad w(\mathbf{x}) = \frac{|\hat{E}_0(\frac{\mathbf{x}}{\lambda z})|^2}{(\lambda z)^2} \quad (\text{Rayleigh-Sommerfeld})$$

$$S(\mathbf{x}; \boldsymbol{\alpha}) \propto w(\mathbf{x}) \left| \sum_{q=1}^Q \alpha_q e^{\frac{2\pi i}{\lambda z} \mathbf{p}_q^\top \mathbf{x}} \right|^2 = \frac{w(\mathbf{x})}{\text{Field of view}} \sum_{j,k=1}^Q \alpha_j \alpha_k^* e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top \mathbf{x}}$$

Hence (noiseless)

$$\begin{aligned} y_{\alpha} &= \sum_{j,k=1}^Q \alpha_j \alpha_k^* \left[\int_{\mathbb{R}^2} e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top \mathbf{x}} w(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} \right] \\ &= \boldsymbol{\alpha}^* \mathcal{I}_{\Omega} [wf] \boldsymbol{\alpha} = \langle \boldsymbol{\alpha} \boldsymbol{\alpha}^*, \mathcal{I}_{\Omega} [wf] \rangle \end{aligned}$$

Interferometric imaging

Writing $f^\circ := wf$ we have

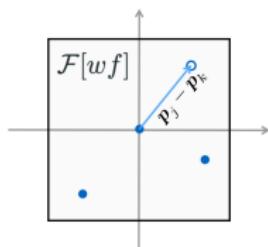
$$y_\alpha = \alpha^* \mathcal{I}_\Omega[f^\circ] \alpha$$

with the interferometric matrix $\mathcal{I}_\Omega[f^\circ] \in \mathbb{C}^{Q \times Q}$ s.t.

$$(\mathcal{I}_\Omega[f^\circ])_{j,k} := \int_{\mathbb{R}^2} e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top} f^\circ(\mathbf{x}) d\mathbf{x}$$

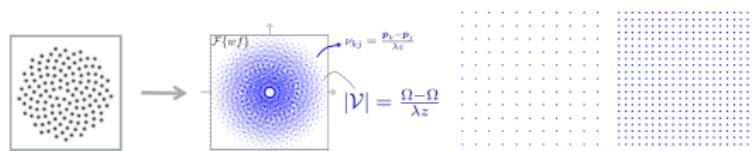
Observation: denser Fourier sampling if

$$|\{\mathbf{p}_j - \mathbf{p}_k : \forall 1 \leq j, k \leq Q\}| \simeq Q^2$$



Fourier plane

- ▶ Lattices are bad core arrangements
- ▶ Fermat's spiral is not bad



$$\begin{aligned}\mathbf{y} &= \{\boldsymbol{\alpha}_m^* \mathcal{I}_\Omega[f^\circ] \boldsymbol{\alpha}_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[f^\circ]\end{aligned}$$

Two-component sensing!

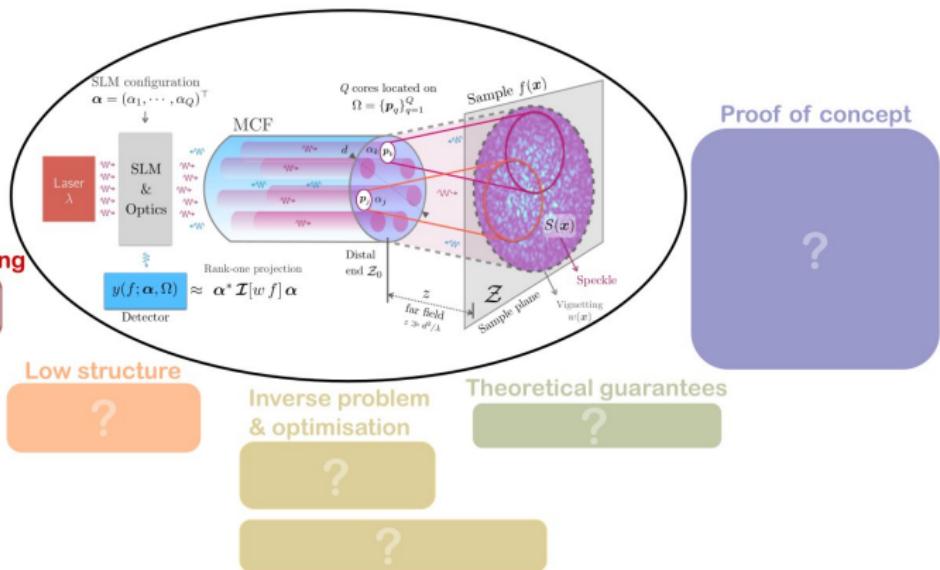
\mathcal{A} : Symmetric rank-one projections of a matrix.

\mathcal{I}_Ω : Partial Fourier sensing with replacement.

Mathematical model

Mathematical modeling

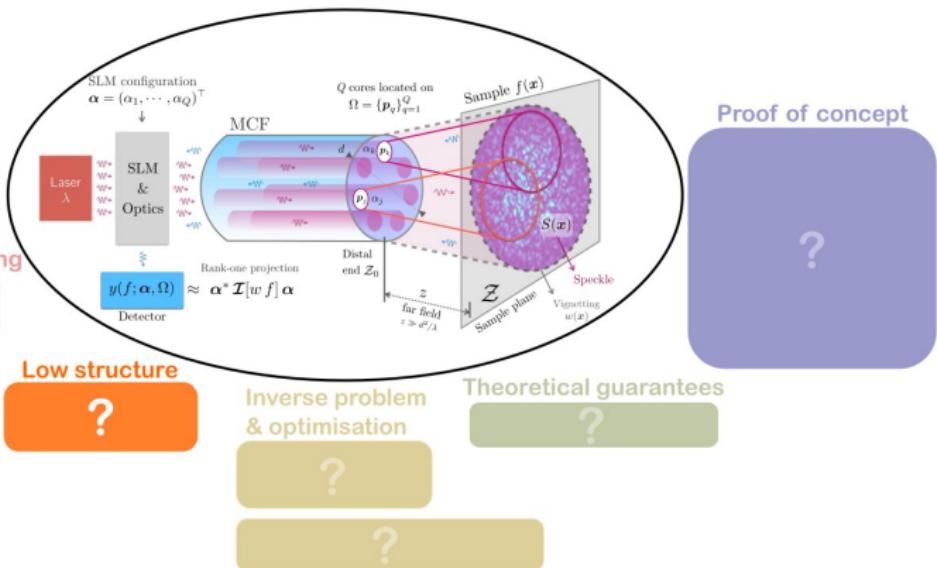
$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Low structure & complexity

Mathematical modeling

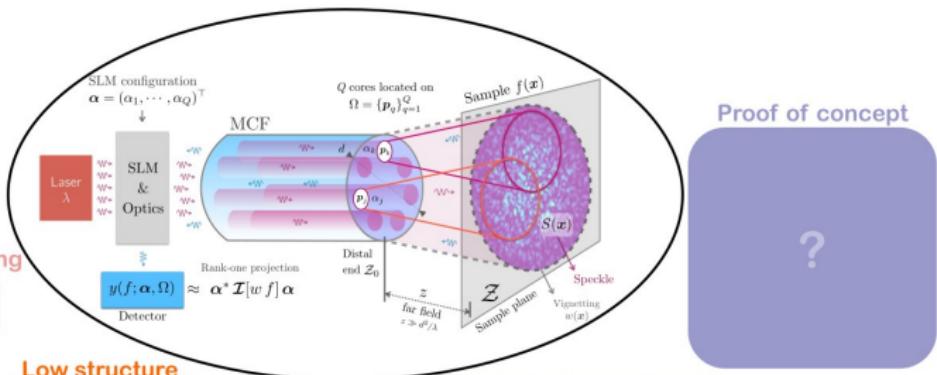
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Low structure & complexity

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Low structure



Inverse problem
& optimisation



Theoretical guarantees



Proof of concept



Properties of $\mathcal{I}_\Omega[f^\circ]$

$$(\mathcal{I}_\Omega[f^\circ])_{j,k} := \int_{\mathbb{R}^2} e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top \mathbf{x}} f^\circ(\mathbf{x}) d\mathbf{x}$$

- ▶ Constant diagonal $(\mathcal{I}_\Omega[f^\circ])_{q,q} = \int_{\mathbb{R}^2} f^\circ(\mathbf{x}) d\mathbf{x} = \langle f^\circ \rangle, \quad \forall q \in [Q]$
- ▶ Hermitian $(\mathcal{I}_\Omega[f^\circ])_{j,k} = (\mathcal{I}_\Omega[f^\circ])_{k,j}^*$

$\Rightarrow Q \times Q$ matrix with only $Q(Q - 1)/2$ degrees of freedom.

Possible structural models on $\mathcal{I}_\Omega[f^\circ]$

Given $\mathcal{I}_\Omega[f^\circ]$

$$(\mathcal{I}_\Omega[f^\circ])_{j,k} := \int_{\mathbb{R}^2} e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top \mathbf{x}} f^\circ(\mathbf{x}) d\mathbf{x}$$

- If $f^\circ(\mathbf{x}) = \sum_i^K \rho_i \delta(\mathbf{x} - \mathbf{x}_i) \Rightarrow f^\circ \in \Sigma_K$, $\mathcal{I}_\Omega[f^\circ]$ is low-rank

$$(\mathcal{I}_\Omega[f^\circ])_{j,k} = \int_{\mathbb{R}^2} e^{\frac{2\pi i}{\lambda z} (\mathbf{p}_j - \mathbf{p}_k)^\top \mathbf{x}} \sum_i^K \rho_i \delta(\mathbf{x} - \mathbf{x}_i) d\mathbf{x}$$

$$\mathcal{I}_\Omega[f^\circ] = \sum_i^K \rho_i \mathbf{u}(\mathbf{x}_i) \mathbf{u}^*(\mathbf{x}_i), \quad \mathbf{u}(\mathbf{x})_j := e^{i 2\pi \mathbf{p}_j^\top \mathbf{x}}.$$

Possible structural models on $\mathcal{I}_\Omega[f^\circ]$

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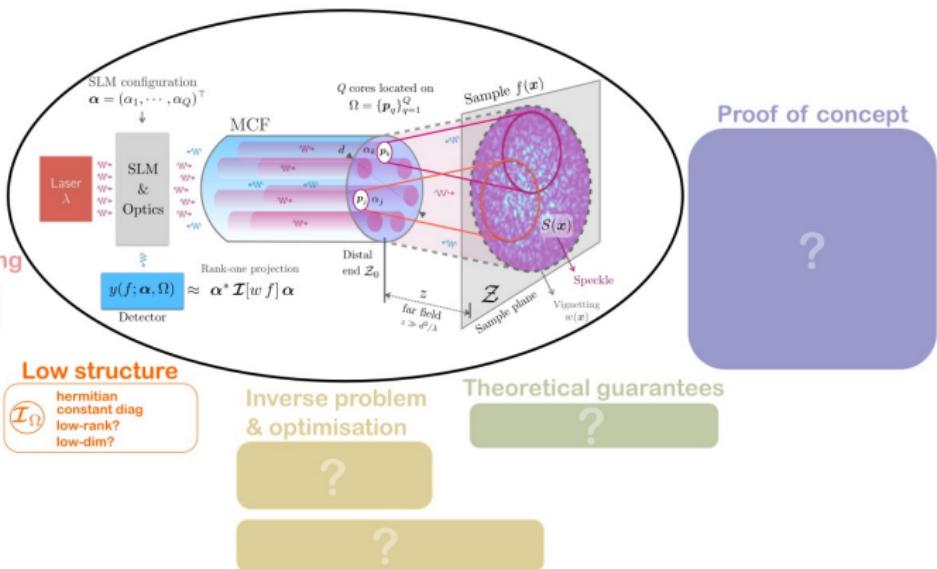
- f° sparse in Ψ (dictionary), $f^\circ(\mathbf{x}) = \sum_i \rho_i \psi_i(\mathbf{x})$
 $\Rightarrow \mathcal{I}_\Omega[f^\circ]$ belongs to a subspace.

$$\mathcal{I}_\Omega[f^\circ] = \frac{1}{Q} \sum_i \rho_i \mathcal{I}_\Omega[\psi_i]$$

Low structure & complexity

Mathematical modeling

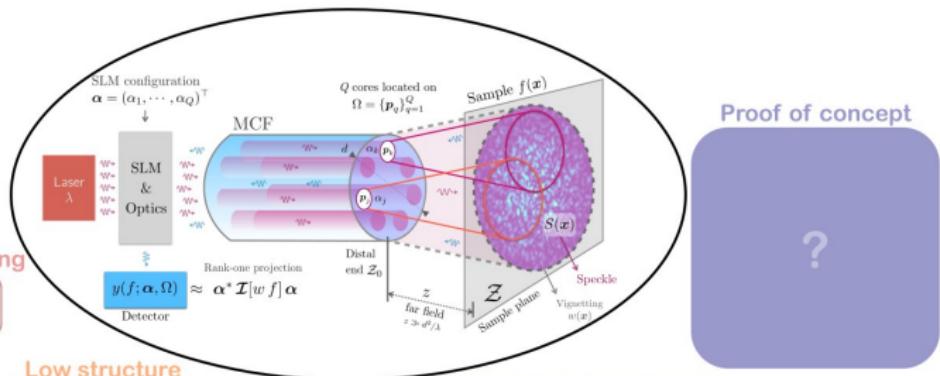
$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Inverse problem & optimisation

Mathematical modeling

$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Low structure



hermitian
constant diag
low-rank?
low-dim?

Inverse problem & optimisation



Theoretical guarantees

Two-step strategies

Strategy

1. SROPs : $\mathbf{y} \rightarrow \mathcal{I}_\Omega[f^\circ]$
2. Partial Fourier sampling : $\mathcal{I}_\Omega[f^\circ] \rightarrow f^\circ$

1.

- Deterministic schemes

Two-step strategies

- ▶ Deterministic schemes

► Deterministic schemes

$$\begin{array}{ccc}
 \boxed{\text{--- } 1 \text{ --- } 1 \text{ ---}}^* & \left[\begin{array}{c|c} \mathcal{I}_{q,q} & \mathcal{I}_{q,r} \\ \hline \mathcal{I}_{r,q} & \mathcal{I}_{r,r} \end{array} \right] & \left[\begin{array}{c} 1 \\ \hline 1 \end{array} \right] \\
 \alpha^* & \mathcal{I}_\Omega[f^\circ] & \alpha
 \end{array}$$

$$y_1 = \mathcal{I}_{q,q} + \mathcal{I}_{r,r} + 2\Re\{\mathcal{I}_{q,r}\}$$

- Deterministic schemes

$$\begin{array}{ccc}
 \boxed{\text{--- i --- 1 ---}}^* & \left[\begin{array}{c|c} \mathcal{I}_{q,q} & \mathcal{I}_{q,r} \\ \hline \mathcal{I}_{r,q} & \mathcal{I}_{r,r} \end{array} \right] & \left[\begin{array}{c} \text{i} \\ \hline 1 \end{array} \right] \\
 \alpha^* & \mathcal{I}_\Omega[f^\circ] & \alpha \\
 y_2 = \mathcal{I}_{q,q} + \mathcal{I}_{r,r} + 2\Im\{\mathcal{I}_{q,r}\}
 \end{array}$$

► Deterministic schemes

$$y_1 = \mathcal{I}_{q,q} + \mathcal{I}_{r,r} + 2\Re\{\mathcal{I}_{q,r}\}$$

$$y_2 = \mathcal{I}_{q,q} + \mathcal{I}_{r,r} + 2\Im\{\mathcal{I}_{q,r}\}$$

$$\begin{aligned} y_1 + i y_2 &= (1+i)(\mathcal{I}_{q,q} + \mathcal{I}_{r,r}) + 2\mathcal{I}_{q,r} \\ &= 2(1+i)\hat{f}(0) + 2\mathcal{I}_{q,r} \end{aligned}$$

$$\Rightarrow M = Q(Q-1) + 1$$

Two-step strategies

- ▶ Deterministic schemes

- ▶ **Inverse problem**

$f^\circ \in \Sigma_K \Rightarrow \mathcal{I}_\Omega$ is rank- K .

Solve

$$\arg \min_{\mathcal{I}} \|\mathcal{I}\|_* \quad \text{s.t.} \quad \|\mathbf{y} - \mathcal{A}(\mathcal{I})\|_1 \leq \varepsilon$$

Upper bound on the reconstruction error

$$\|\hat{\mathcal{I}} - \mathcal{I}_0\|_F \leq C \frac{\|\mathcal{I}_0 - (\mathcal{I}_0)_K\|_*}{\sqrt{K}} + D \frac{\varepsilon}{M}.$$

Single-step strategy

Basis Pursuit DeNoising in ℓ_1 -norm (BPDN $_{\ell_1}$)

How to get a \hat{f} from $\mathbf{y} = \mathcal{A} \circ \mathcal{I}_{\Omega}[f^{\circ}]$?

Discretise $f^{\circ} \rightarrow \mathbf{f} \in \mathbb{R}^{N_1 \times N_1}$

The interferometric matrix becomes

$$\mathcal{I}_{\Omega}[f^{\circ}] \approx \mathcal{T}\mathbf{F}\mathbf{f}$$

Let us rewrite

$$\mathcal{B} := \mathcal{A} \circ \mathcal{I}_{\Omega} \text{ s.t. } \mathbf{y} = \mathcal{B}\mathbf{f}$$

Solve

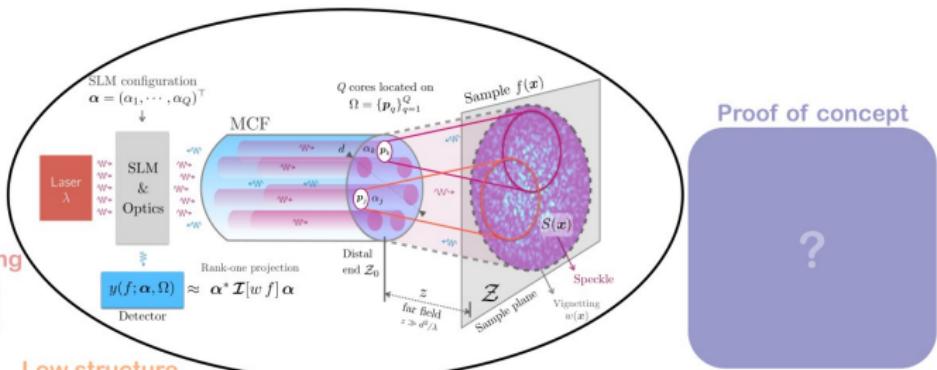
$$\hat{\mathbf{f}} = \arg \min_{\mathbf{u}} \|\mathbf{u}\|_1 \quad \text{s.t. } \|\mathbf{y} - \mathcal{B}\mathbf{u}\|_1 \leq \epsilon \quad (\text{BPDN}_{\ell_1})$$

Here we leverage low structure directly on f° !

Inverse problem & optimisation

Mathematical modeling

$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Low structure



hermitian
constant diag
low-rank?
low-dim?

Inverse problem & optimisation

Two-step

1. $\mathbf{y} \rightarrow \mathcal{I}_\Omega[f^*]$
2. $\mathcal{I}_\Omega[f^*] \rightarrow f^*$

Single-step

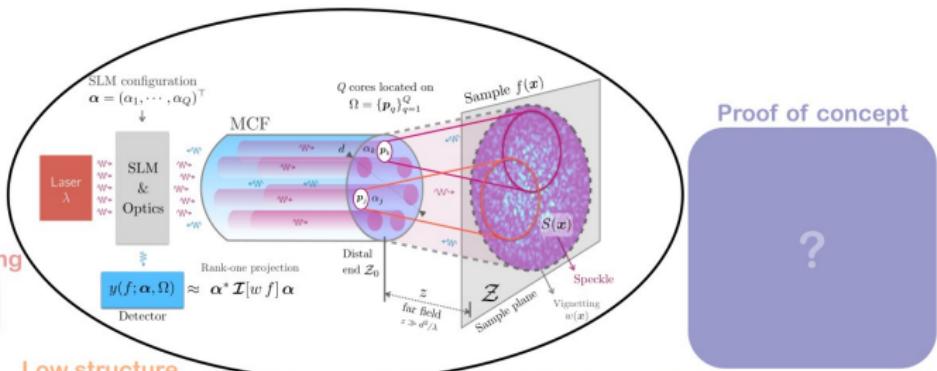
$$\hat{f} \in \arg \min_u \|u\|_1 \text{ s.t. } \|\mathbf{y} - \mathcal{A} \circ \mathcal{I}_\Omega[u]\|_1 \leq \epsilon$$

Theoretical guarantees

Recovery guarantees

Mathematical modeling

$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Proof of concept

?

Low structure



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Inverse problem & optimisation

Two-step

1. $\mathbf{y} \rightarrow \mathcal{I}_\Omega[f^*]$
2. $\mathcal{I}_\Omega[f^*] \rightarrow f^*$

Single-step

$$f \in \arg \min_u \|u\|_1 \text{ s.t. } \|\mathbf{y} - \mathcal{A} \circ \mathcal{I}_\Omega[u]\|_1 \leq \epsilon$$

Theoretical guarantees

?

Objective

Show

$$\hat{\mathbf{f}} \in \arg \min_{\mathbf{u}} \|\mathbf{u}\|_1 \quad \text{s.t. } \|\mathbf{y} - \mathcal{A}(\mathcal{I}_{\Omega}[\mathbf{u}])\|_1 \leq \epsilon \quad (\text{BPDN}_{\ell_1})$$

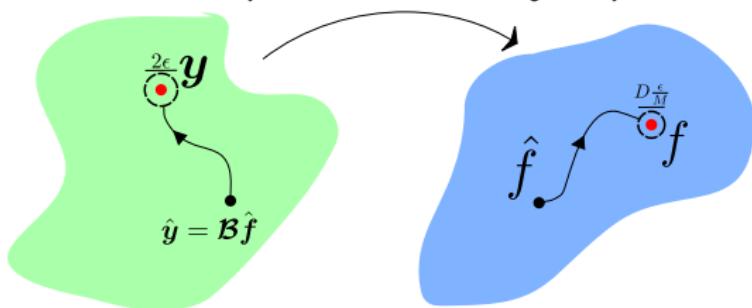
satisfies

$$\|\mathbf{f} - \hat{\mathbf{f}}\|_2 \leq C \frac{\|\mathbf{f} - \mathbf{f}_K\|_1}{\sqrt{K}} + D \frac{\epsilon}{m}.$$

Prove the RIP- ℓ_2/ℓ_1

$$\tilde{A}\|\mathbf{u}\| \leq \frac{1}{M}\|\mathcal{A}(\mathcal{I}_{\Omega}[\mathbf{u}])\|_1 \leq \tilde{B}\|\mathbf{u}\|$$

Measurement space **Object space**



Objective

Show

$$\hat{\mathbf{f}} \in \arg \min_{\mathbf{u}} \|\mathbf{u}\|_1 \quad \text{s.t. } \|\mathbf{y} - \mathcal{A}(\mathcal{I}_\Omega[\mathbf{u}])\|_1 \leq \epsilon \quad (\text{BPDN}_{\ell_1})$$

satisfies

$$\|\mathbf{f} - \hat{\mathbf{f}}\|_2 \leq C \frac{\|\mathbf{f} - \mathbf{f}_K\|_1}{\sqrt{K}} + D \frac{\epsilon}{m}.$$

- ▶ Assume RIP- ℓ_2/ℓ_2 for visibility sampling

$$(1 - \delta) \|\mathbf{u}\|^2 \leq \|\mathcal{I}_\Omega[\mathbf{u}]\|_F^2 \leq (1 + \delta) \|\mathbf{u}\|^2$$

- ▶ Prove RIP- ℓ_2/ℓ_1 for SROPs

$$A \|\mathcal{I}_\Omega\|_F \leq \frac{1}{M} \|\mathcal{A}(\mathcal{I}_\Omega)\|_1 \leq B \|\mathcal{I}_\Omega\|_F$$

- ▶ Combine the two RIPs and get

$$\tilde{A} \|\mathbf{u}\| \leq \frac{1}{M} \|\mathcal{A}(\mathcal{I}_\Omega[\mathbf{u}])\|_1 \leq \tilde{B} \|\mathbf{u}\|$$

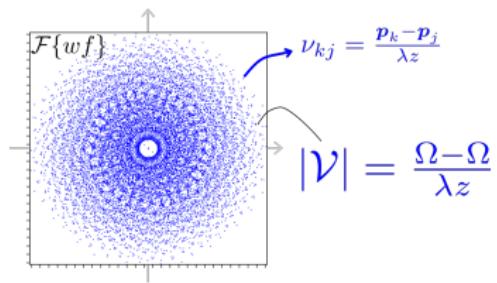
Assumption (inspired by partial Fourier sensing in CS¹)

$$(1 - \delta)\|\mathbf{u}\|^2 \leq \|\mathcal{I}_\Omega[\mathbf{u}]\|_F^2 \leq (1 + \delta)\|\mathbf{u}\|^2$$

with the condition

$$|\mathcal{V}_0| = Q(Q - 1) \geq \delta^{-2} K \log(N, K, \delta)$$

We need randomness in the sampling
 But deterministic visibility set...
 Hopefully, we have good reasons think this
 assumption is not too bad!



¹E. J. Candès, J. K. Romberg, and T. Tao, “Robust uncertainty principles: Exact signal reconstruction from highly incomplete frequency information,” IEEE Transactions on Information Theory, vol. 52, no. 2, pp. 489–509, 2006.

Recovery guarantees - Proving the RIP- ℓ_2/ℓ_1

$$A\|\mathcal{I}_\Omega\|_F \leq \frac{1}{M}\|\mathcal{A}(\mathcal{I}_\Omega)\|_1 \leq B\|\mathcal{I}_\Omega\|_F$$

If $M > CK \log\left(\frac{12eN}{K}\right)$ and \mathcal{A} satisfies

$$\mathbb{P}\left[\left|\frac{1}{\sqrt{M}}\|\mathcal{A}(\mathcal{I})\|_1 - \|\mathcal{I}\|_F\right| > t\|\mathcal{I}\|_F\right] \leq Ce^{-cM} \quad (1)$$

$\Rightarrow \mathcal{A}$ satisfies RIP- ℓ_2/ℓ_1 w.h.p.

Prove (1) in two-steps

Recovery guarantees - Proving the RIP- ℓ_2/ℓ_1

If $M > CK \log\left(\frac{12eN}{K}\right)$ and \mathcal{A} satisfies

$$\mathbb{P} \left[\left| \frac{1}{\sqrt{M}} \|\mathcal{A}(\mathcal{I})\|_1 - \|\mathcal{I}\|_F \right| > t \|\mathcal{I}\|_F \right] \leq Ce^{-cM} \quad (1)$$

$\Rightarrow \mathcal{A}$ satisfies RIP- ℓ_2/ℓ_1 w.h.p.

Prove (1) in two-steps

$$1. \mathbb{P} [|\|\mathcal{A}(\mathcal{I})\|_1 - \mathbb{E} \|\mathcal{A}(\mathcal{I})\|_1| > t] \leq 2 \exp \left(-cM \min \left(\frac{t^2}{4\kappa^2}, \frac{t}{2\kappa} \right) \right)$$

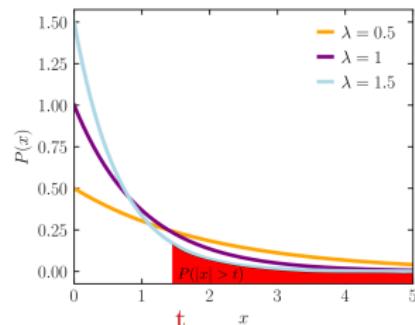
$$\|\mathcal{A}(\mathcal{I})\|_1 = \sum_{m=1}^M |\boldsymbol{\alpha}_m^* \mathcal{I} \boldsymbol{\alpha}_m| = \sum_{m=1}^M |\xi_m|$$

$$\|\mathcal{A}(\mathcal{I})\|_1 - \mathbb{E} \|\mathcal{A}(\mathcal{I})\|_1 = \sum_{m=1}^M |\xi_m| - \mathbb{E} |\xi_m| = \sum_{m=1}^M |\tilde{\xi}_m|$$

Recall $\boldsymbol{\alpha}$ is a r.v. $\Rightarrow \tilde{\xi}$ is a r.v. too.

$\tilde{\xi}_m$ is **subexponential!** Property of a subexponential r.v.

$$\mathbb{P} [|\tilde{\xi}| > t] \leq 2 \exp \left(-cM \min \left(\frac{t^2}{4\kappa^2}, \frac{t}{2\kappa} \right) \right)$$



Recovery guarantees - Proving the RIP- ℓ_2/ℓ_1

If $M > CK \log\left(\frac{12eN}{K}\right)$ and \mathcal{A} satisfies

$$\mathbb{P} \left[\left| \frac{1}{\sqrt{M}} \|\mathcal{A}(\mathcal{I})\|_1 - \|\mathcal{I}\|_F \right| > t \|\mathcal{I}\|_F \right] \leq Ce^{-cM} \quad (1)$$

$\Rightarrow \mathcal{A}$ satisfies RIP- ℓ_2/ℓ_1 w.h.p.

Prove (1) in two-steps

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$$(1-t)\mathbb{E} \|\mathcal{A}(\mathcal{I})\|_1 \leq \frac{1}{\sqrt{M}} \|\mathcal{A}(\mathcal{I})\|_1 \leq (1+t)\mathbb{E} \|\mathcal{A}(\mathcal{I})\|_1$$

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Objective

Show

$$\hat{\mathbf{f}} \in \arg \min_{\mathbf{u}} \|\mathbf{u}\|_1 \quad \text{s.t. } \|\mathbf{y} - \mathcal{A}(\mathcal{I}_\Omega[\mathbf{u}])\|_1 \leq \epsilon \quad (\text{BPDN}_{\ell_1})$$

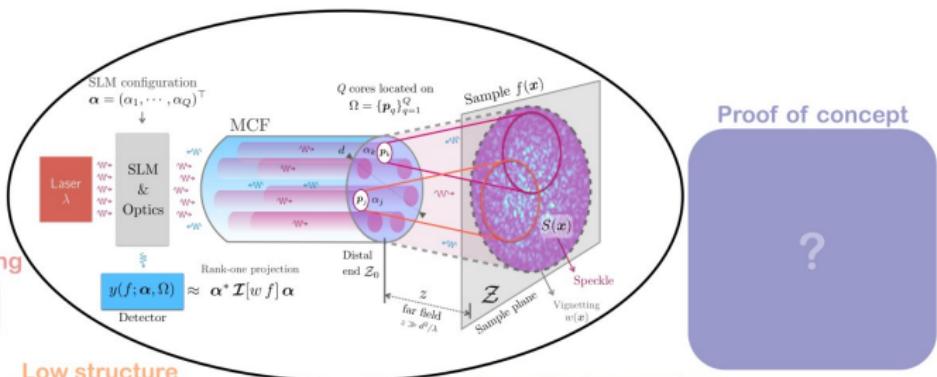
satisfies

$$\|\mathbf{f} - \hat{\mathbf{f}}\|_2 \leq C \frac{\|\mathbf{f} - \mathbf{f}_K\|_1}{\sqrt{K}} + D \frac{\epsilon}{m}.$$

Recovery guarantees

Mathematical modeling

$$\begin{aligned} \mathbf{y} &= \{\alpha_m^* \mathcal{I}_\Omega[w f] \alpha_m\}_{m=1}^M \\ &= \mathcal{A} \circ \mathcal{I}_\Omega[w f] \end{aligned}$$



Low structure



hermitian
constant diag
low-rank?
low-dim?

Inverse problem & optimisation

Two-step

1. $\mathbf{y} \rightarrow \mathcal{I}_\Omega[f^*]$
2. $\mathcal{I}_\Omega[f^*] \rightarrow f^*$

Single-step

$$\hat{f} \in \arg \min_u \|u\|_1 \text{ s.t. } \|\mathbf{y} - \mathcal{A} \circ \mathcal{I}_\Omega[u]\|_1 \leq \epsilon$$

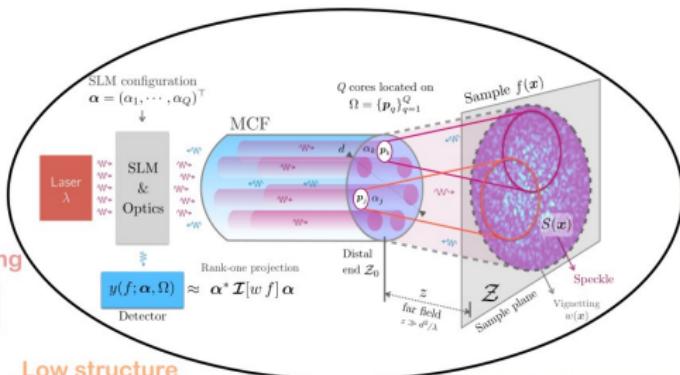
Theoretical guarantees

$$\left\| f - \hat{f} \right\|_2 \leq C \frac{\|f - f_K\|_1}{\sqrt{K}} + D \frac{\epsilon}{m}$$

Proof of concept

Mathematical modeling

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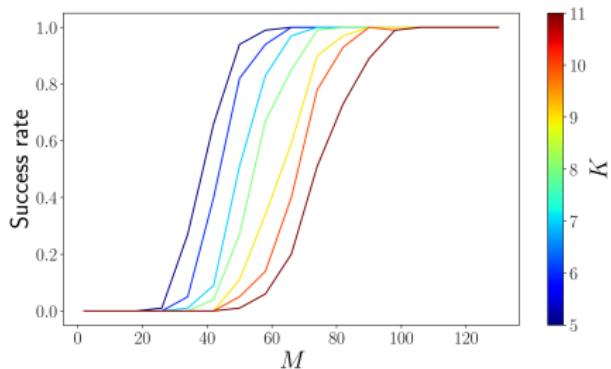
Simulation results

K = sparsity of f , $f \in \Sigma_K$.

$|\mathcal{V}|$ = cardinality of the visibility set in the Fourier space, grows with Q .

M = number of measurements.

$$\hat{\mathbf{f}} = \arg \min_{\mathbf{u}} \|\mathbf{y} - \mathcal{B}\mathbf{u}\|_2 \quad \text{s.t.} \quad \|\mathbf{u}\|_1 \leq K \quad (\text{LASSO})$$



Success if SNR > 40dB.

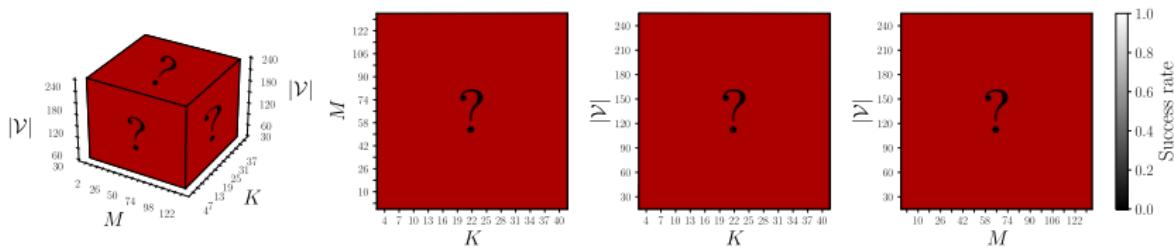
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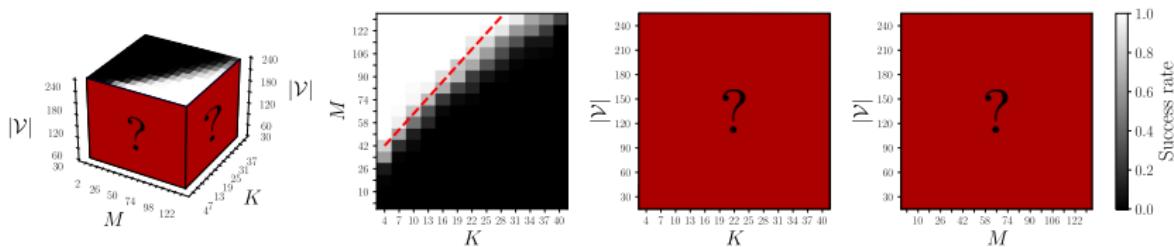
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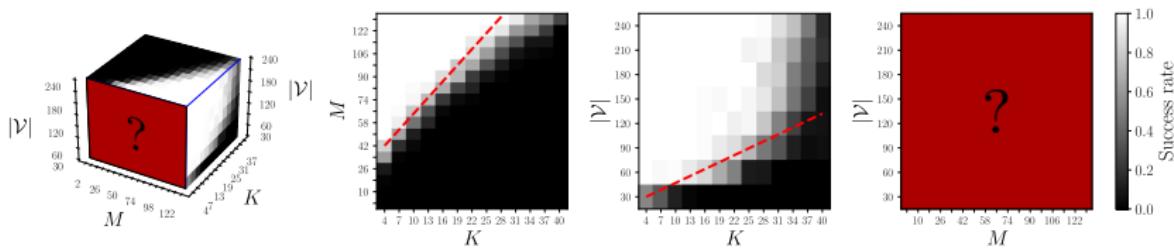
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$$|\mathcal{V}_0| = Q(Q-1) \geq \delta^{-2} K \log(N, K, \delta)$$

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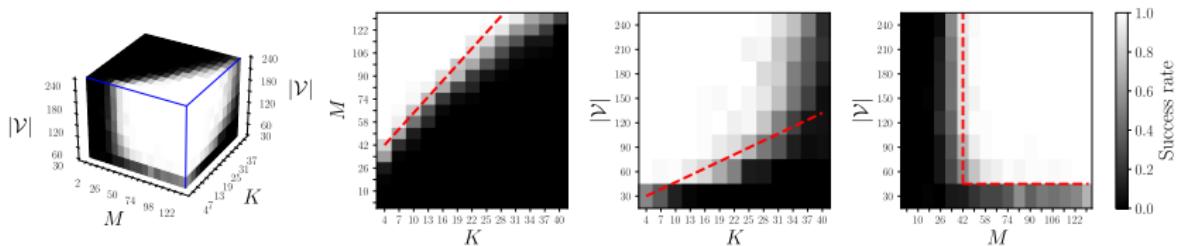
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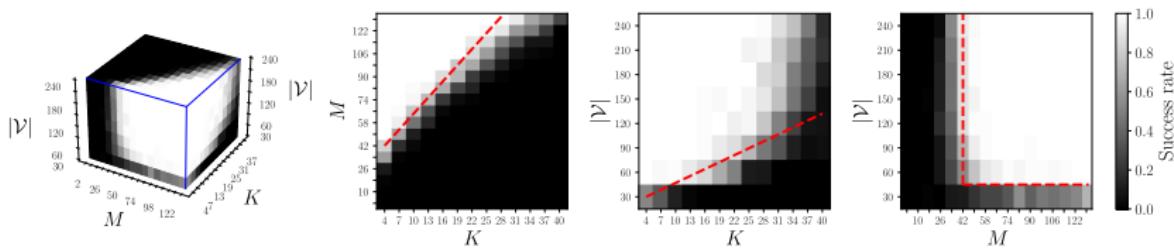
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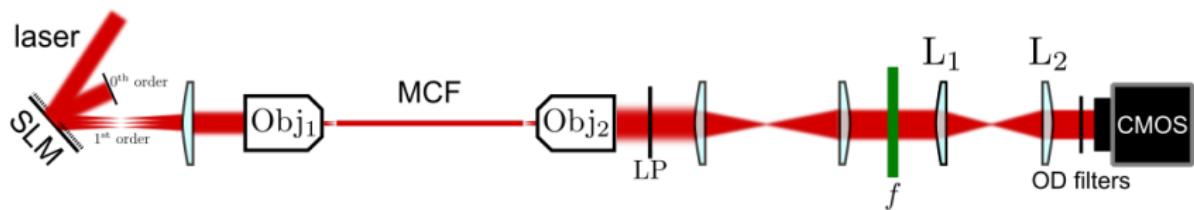
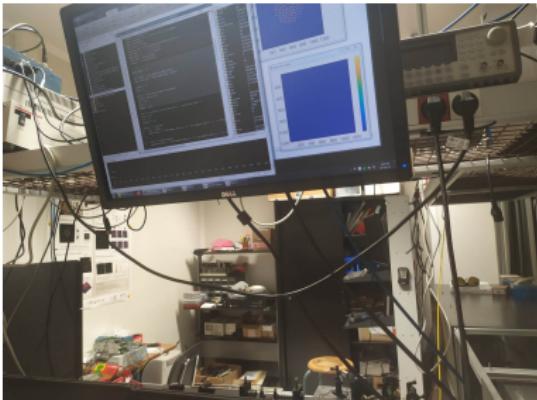
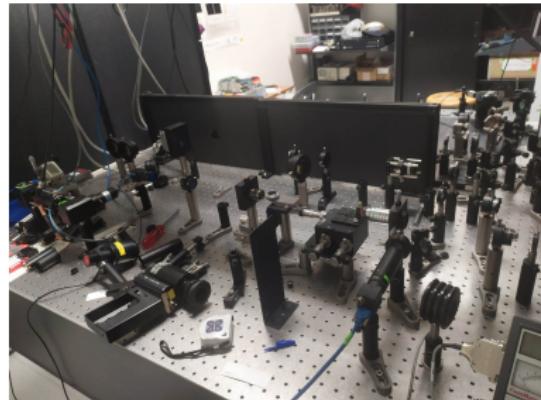
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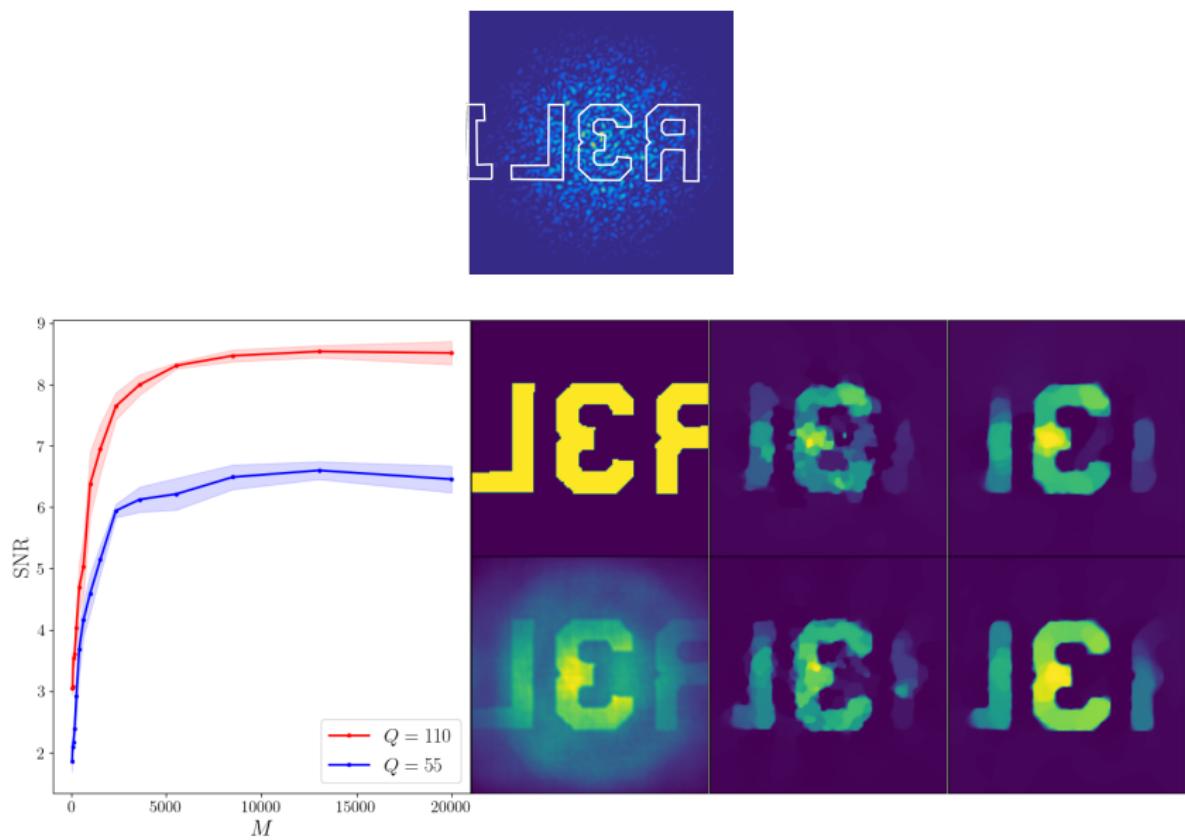


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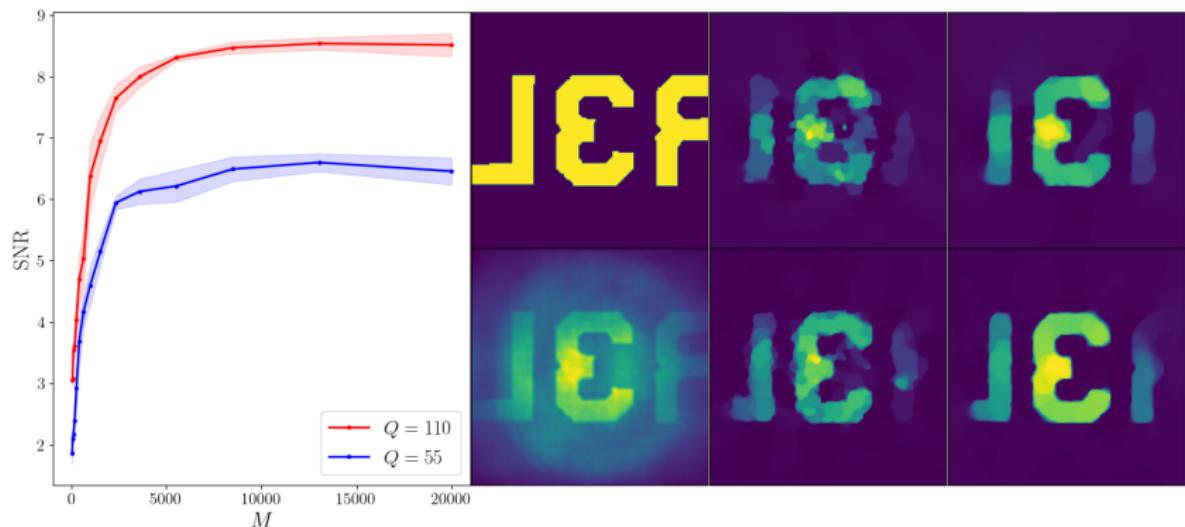
Experimental results



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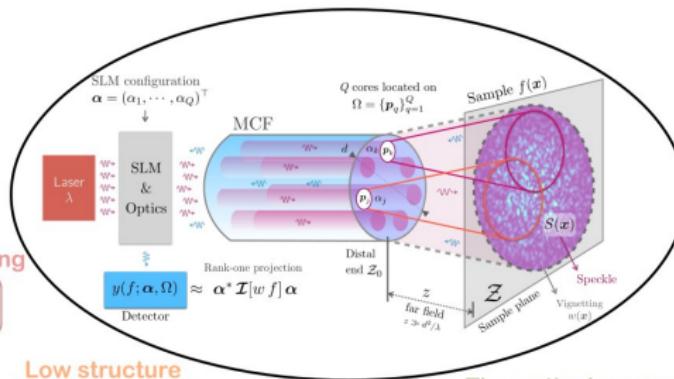


Why such a small SNR?

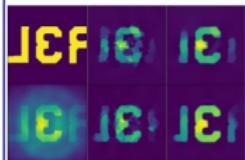
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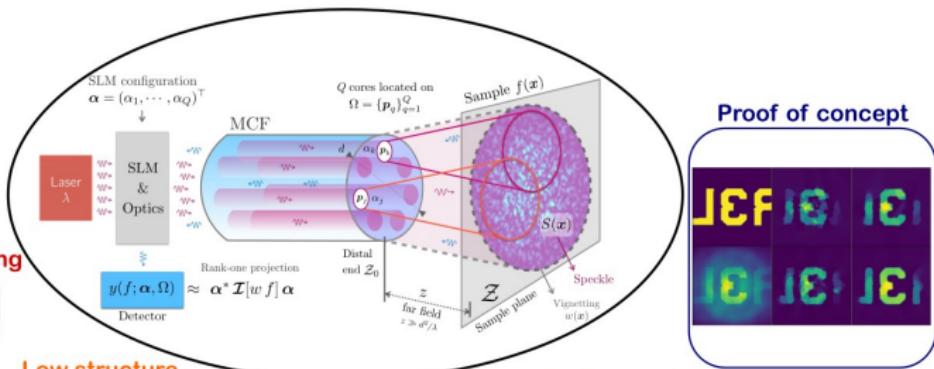
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Conclusion

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Until now

- ▶ New interferometric model for MCF-LI.
- ▶ Theoretical guarantees.
- ▶ Simulated and experimental results.

Perspectives

- ▶ Extension to 3D imaging.
- ▶ Experiments in endoscopic conditions.
- ▶ Acceleration of the sensing using mirrors.
- ▶ Manage twisting.

Thank you!