



The module expects a 10 microsecond pulse of HIGH on TRIG pin to send out the sound waves.

Then, to get time taken for sound to be received, we use `pulseIn(EchoPin, HIGH);` (TIME IS IN MICROSECONDS)

Divide duration by 2 to get time taken for sound wave to reach the object in microseconds μs

Speed of sound is 343 m s^{-1} which is 34300 cm s^{-1}
which is $0.0343 \text{ cm } \mu s^{-1}$

So total distance in cm is $0.0343 \left(\frac{\text{duration}}{2} \right)$

ALTERNATIVE - VL6180X ToF light Sensor. More accurate and allows readings at closer distances from wall.
Accurate in approx. range 5mm - 100mm.
Could maybe try to combine with longer range VL53L0X (50mm - 1200mm)