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## Traveling Salesman with Perl, R and Google Maps

2017-07-15 BY GENE

tl;dr: ggplot-nyc & googlemap-nyc & TSP-Map (the Dancer app)

One day I decided to glue-together a couple cool <u>Perl</u> modules and the visualization capabilities of <u>R</u> to generate a map of locations and the computed path of a <u>traveling salesman</u> (TSP) – who in this case is a restaurant critic.

The prerequisite is to have <u>MongoDB</u> installed and loaded with the freely available restaurant test data at <a href="https://www.w3resource.com/mongodb-exercises">https://www.w3resource.com/mongodb-exercises</a>/retaurants.zip.

With that data loaded (with `mongoimport –db test –collection restaurants –drop –file restaurants.json`), the first thing is that the program loads essential perl pragmas and <u>CPAN</u> modules:

```
#!/usr/bin/env perl
use strict;
use warnings;
use YAML;
use MongoDB;
```

```
use Algorithm::TravelingSalesman::BitonicTour;
use Math::Geometry::Planar;
use Statistics::R;
```

Next, handy variables are declared and initialized. This includes getting the MongoDB database configuration with <u>YAML</u> and using it to instantiate a new mongo client object:

```
my $borough = shift | | 'Manhattan'; # Also: Queens, Brooklyn, Bronx, etc.
my $grade = shift || 'A';
my \$score = shift // 70;
my $config = shift || 'creds.yaml';
my $cfg = YAML::LoadFile($config);
my $client = MongoDB::MongoClient->new(
 host
        => $cfg->{mongo}{dbhost},
 db_name => $cfg->{mongo}{dbname},
 username => $cfg->{mongo}{dbuser},
 password => $cfg->{mongo}{dbpass},
);
Here is creds.yaml by the way:
mongo:
    dbhost: 'mongodb://localhost'
    dbuser: gene
    dbpass: abc123
    dbname: admin
```

With those set, a database query can be made to select the restaurants to inspect:

The next set of steps is the traveling-salesman logic. The selected restaurant address coordinates are added, the TSP algorithm is solved and the resulting polygon centroid ("center of gravity") of the points is found:

```
my $tsp = Algorithm::TravelingSalesman::BitonicTour->new;
my %coord_name; # Index of coordinates to restaurant names
while ( my $doc = $docs->next) {
    my @point = @{ $doc->{address}{coord} };
    $coord name{ join ',', @point } = $doc->{name};
    $tsp->add point(@point);
}
my ( undef, @coords ) = $tsp->solve;
my $i = 0; # Counter
print "Optimal path:\n";
for my $coord (@coords) {
    my $key = join ',', @$coord;
    printf "\t%d. %s [%s]\n", ++$i, $coord name{$key}, $key;
}
my $polygon = Math::Geometry::Planar->new;
$polygon->points( [ @coords[ 1 .. $#coords ] ] );
my $centroid = $polygon->centroid;
```

Now the coordinates are mapped with R, to a PNG file, with the excellent ggmap package:

```
my $R = Statistics::R->new();

$R->run( 'library(ggmap)' );

my $file = "$0.png";

$R->run( "png('$file')" );
```

Next, some R variables are declared (i.e. latitude/longitude vectors and the data.frame to plot):

```
$R->set( 'X', [ map { $_->[0] } @coords ] );
$R->set( 'Y', [ map { $_->[1] } @coords ] );
$R->run( 'df <- data.frame(X, Y)' );
$R->run( "names(df) <- c('lon','lat')" );</pre>
```

Now, the map is generated based on the polygon centroid computed earlier:

```
$R->run( "center <- c( $centroid->[0], $centroid->[1] )" );
$R->run( "centroid <- get_googlemap( center = center, zoom = 12 )" );

my $gg_cmd = 'ggmap( centroid, aes(lon, lat) )';
$gg_cmd .= ' + geom_point( data = df, colour = "darkred" )';
$gg_cmd .= ' + geom_path( data = df, color = "darkgray", size = 0.5 )';
$R->run($gg_cmd);
```

Finally, the R graphics device is closed and the perl-R session is stopped:

```
$R->run( 'dev.off()' );
$R->stop();
```

Here is the output of the program for Manhattan grade-A restaurants with a rating of 70 or higher:

## Optimal path:

```
    Brothers Fish Market [-73.9435296,40.8361392]
    Murals On 54/Randolphs'S [-73.9782725,40.7624022]
```

- 3. Mars Cafe [-73.9850196,40.7524629]
- 4. Midtown Buffet [-73.987977,40.755195]
- 5. B.B. Kings [-73.9889479,40.7568894]
- 6. Cafe R [-73.9897851,40.7487912]
- 7. Concrete Restaurant [-73.9934047,40.7544014]
- 8. West 79Th Street Boat Basin Cafe [-74.0163793,40.7167671]
- 9. Wonton Noodle Garden [-73.9983631,40.7158265]
- 10. Live Bait Bar & Restaurant [-73.9883909,40.740735]
- 11. Gandhi [-73.9864626,40.7266739]
- 12. Bella Napoli [-73.984758,40.7457939]
- 13. East Japanese Restaurant [-73.981843,40.741207]
- 14. Two Boots Grand Central [-73.9772294,40.7527262]
- 15. Everyday Gourmet Deli [-73.976478,40.7504097]
- 16. Bistro Caterers [-73.9747277,40.7536114]
- 17. La Trattoria [-73.970671,40.7515735]

```
    18. Baluchi'S Indian Food [-73.94981,40.780043]
    19. Lexington Restaurant [-73.941892,40.7982236]
    20. Brothers Fish Market [-73.9435296,40.8361392]
```

And here is the map that is produced:



(I can't seem to figure out how to make the map larger, yet. And adding get\_googlemap(..., size = c(x,y)) is not the answer. Grrrr)

**UPDATE**: I have found a much better way to render a map! (<u>Updated code</u> <u>here</u>.)

This code throws out R in favor of the perl module <a href="https://example.code.ncbe.new"><u>HTML::GoogleMaps::V3</u></a>. Instead of generating a small PNG, the new code makes an HTML file with a handy Google Map.

Ok. After the code above, up to the TSP algorithm solving, we find the path centroid as before:

```
my ( undef, @coords ) = $tsp->solve;

# Find the path polygon centroid
my $polygon = Math::Geometry::Planar->new;
$polygon->points( [ @coords[ 1 .. $#coords ] ] );
```

```
my $centroid = $polygon->centroid;
Next comes the beginning of the updated logic:
my $map = HTML::GoogleMaps::V3->new( height => 800, width => 800 );
$map->zoom(12);
$map->center($centroid);
Then we add markers to this map, for each optimal coordinate in order. Also the
path is added to the map:
for my $coord (@coords) {
    my $point = join ',', $coord->[1], $coord->[0]; # Google maps wants la
    my $key = join ',', @$coord;
    $coord_name{$key} =~ s/'/^/g; # Single quotes conflict with the marker
    $map->add_marker(
        point => $coord,
        html => qq | <div id="content"><h3 id="firstHeading" class="firstHea
    );
}
# Add a path for all but the last (redundant) coordinate.
$map->add_polyline( points => [ @coords[ 0 .. $#coords - 1 ] ] );
Finally we print-out the resulting HTML to save to a file:
my ($head, $map_div) = $map->onload_render;
print qq|<html><head><title>Test</title>$head</head>|;
print qq|<body onload="html googlemaps initialize()">$map div</body></html>
This is run as:
```

Here is a screenshot of the resulting map:

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\$ open googlemap.html

\$ perl googlemap-nyc > googlemap.html



Note: Although not reflected here, the <u>updated code</u> includes output of the optimal path, directions to each waypoint, and the driving directions for the whole route! Here is a screenshot of the route driving directions map:



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