



DATS_6203_10: Final Project

Photo Coloring
by: Group 4



Outline

- Dataset & Literature review
- GAN - Method based on color space
- GAN - Method based on image translation
- Result & Conclusion
- Limitation & Improvement

Introduction

- Photo Coloring

gray pictures



color pictures



- Applications: restoring old images, 2D animation..
- Main method: Generative Adversarial Network - Method based on color space
- Additional method: Conditional Adversarial Networks - Method based on image translation

Dataset Description

- Flickr1024 - A large-scale stereo image dataset consisting 1024 high-quality image pairs and covering diverse scenarios like animals, building, lands, plants.
- <https://yingqianwang.github.io/Flickr1024/>
- size: 2.64GB

Literature Review

Image colorization: <https://arxiv.org/abs/1803.05400>

Deep Convolutional GAN: <https://arxiv.org/abs/1511.06434>

Image to Image translation:

https://openaccess.thecvf.com/content_cvpr_2017/papers/Isola_Image-To-Image_Translation_With_CVPR_2017_paper.pdf

GANs - Method based on color space

- GAN: G: Generative; A: Adversarial(discriminator); N: network.
- Photo transformation: LAB color space
 - ❖ L: Lightness - gray photo
 - ❖ A: Green-Red tradeoff
 - ❖ B: Blue-Yellow tradeoff
 - ❖ Input: L channel sequence, Output: a, b channel sequence

Data Preprocessing

Package - Open CV

- Use `cv2.imread()` to read to photo
- Resize to (256, 256) - Due to computation power limitation and training time
- Tranform color space for BGR to LAB

Model

Conv2d(1, 32)
BatchNorm2d(32)
ReLU()

Conv2d(32, 64)
BatchNorm2d(64)
ReLU()

Conv2d(64, 128)
BatchNorm2d(128)
ReLU()

Conv2d(128, 128)
BatchNorm2d(128)
ReLU()

Conv2d(128, 128)
BatchNorm2d(128)
ReLU()

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BatchNorm2d(128)
ReLU()

Conv2d(128, 128)
BatchNorm2d(128)
ReLU()

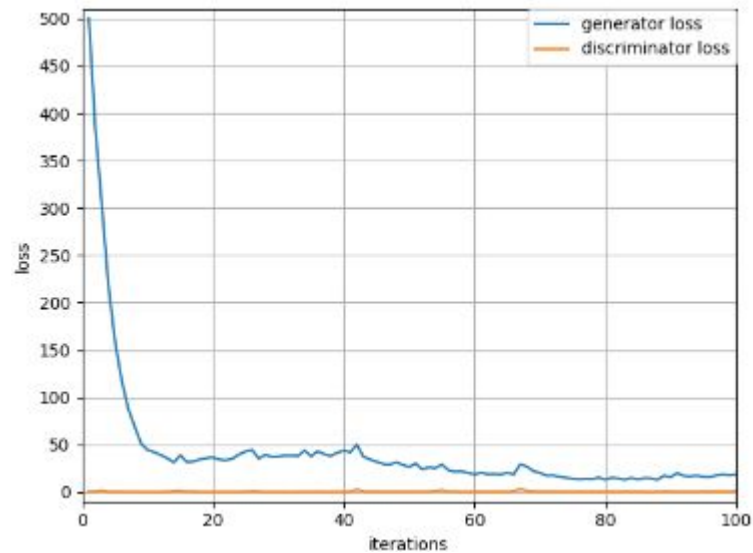
Conv2d(128, 128)
BatchNorm2d(128)
ReLU()

ConvTranspose2d(128, 64)
BatchNorm2d(64)
ReLU()
ConvTranspose2d(64, 32)
BatchNorm2d(32)
ReLU()
Conv2d(32, 2)
Tanh()

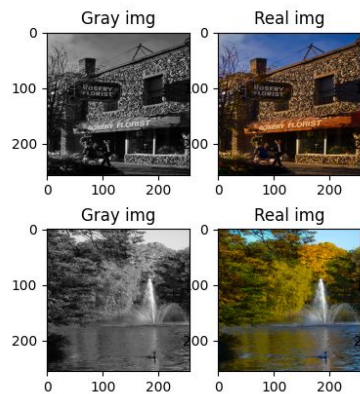
Training process

- Loss function - Cross entropy
 - Generator loss: cross entropy loss of generated images + MSE of ab channels
 - Discrimination loss: (loss of generated images + loss of real images) / 2
- Flip label generated images - 1 and real images - 0 (works)
- Soft and Noisy label: Using a random number between 0 and 0.1 to represent 0 labels (real images) and a random number between 0.9 and 1.0 to represent 1 labels (generated images) when training the discriminator. (works)

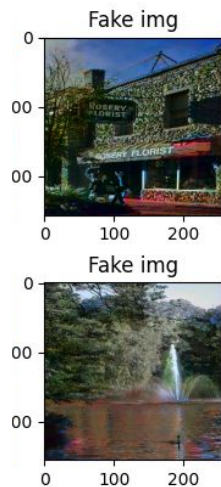
Loss function



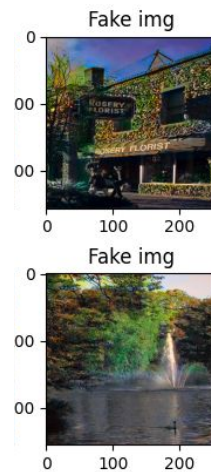
Results



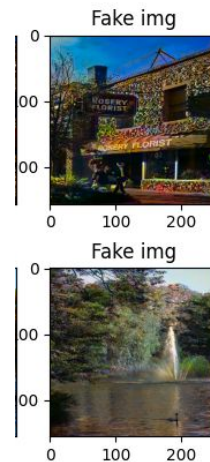
training of 100 epochs:



training of 200 epochs:



training of 300 epochs:



Conditional GANs

- predict pixels from pixels
- learn a mapping from observed image x and random noise vector z

- The objective of a conditional GAN: $G^* = \arg \min_G \max_D \mathcal{L}_{cGAN}(G, D) + \lambda \mathcal{L}_{L1}(G).$

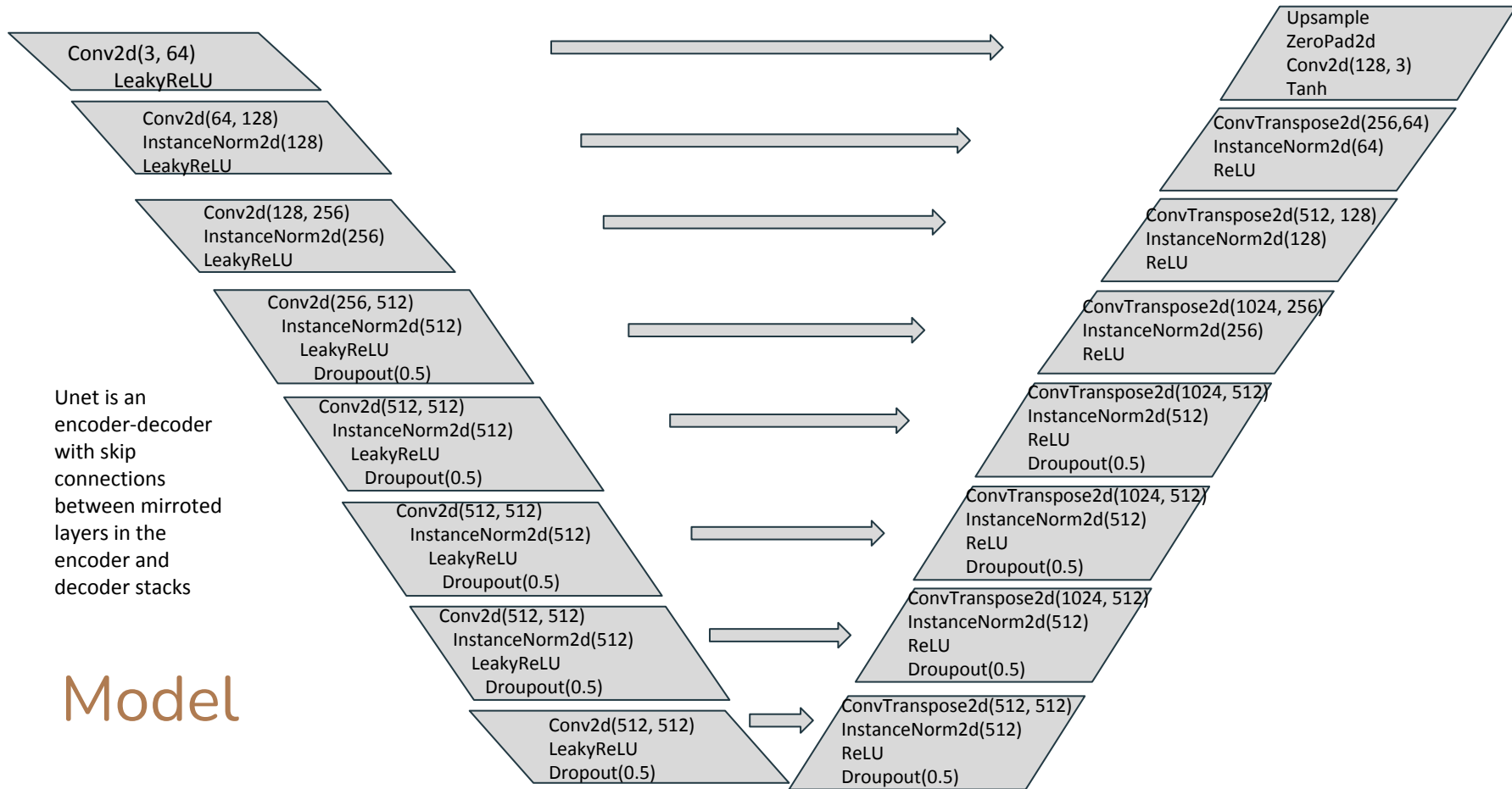
$$\mathcal{L}_{cGAN}(G, D) = \mathbb{E}_{x,y} [\log D(x, y)] + \mathbb{E}_{x,z} [\log(1 - D(x, G(x, z)))],$$

$$\mathcal{L}_{L1}(G) = \mathbb{E}_{x,y,z} [\|y - G(x, z)\|_1].$$

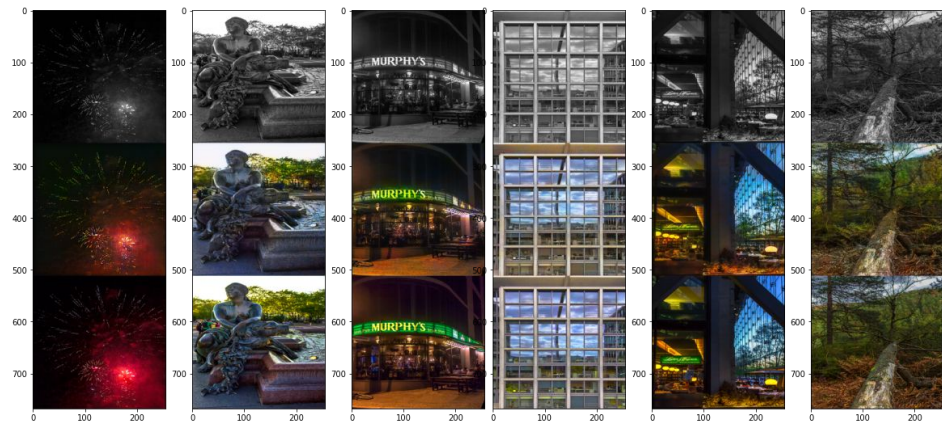
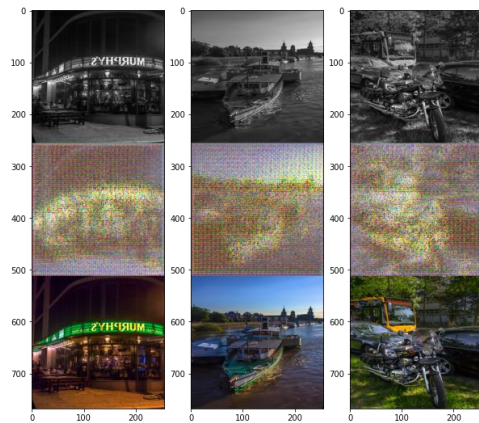
- Markovian discriminator(PatchGAN): only penalizes structure at the scale of patches

Data Preprocessing

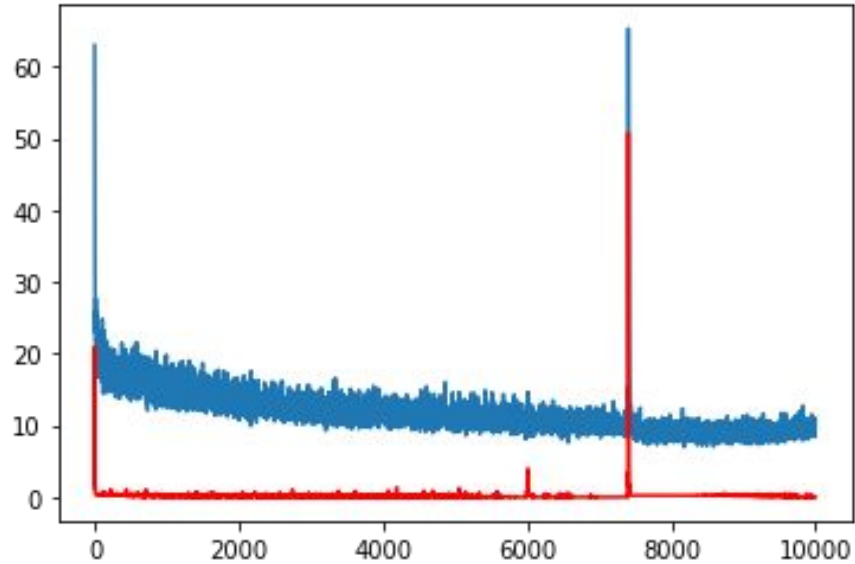
- Read the image from google drive
- Use `cv2.cvtColor` to convert BGR to RGB.
- To get the color image, so we turn the data into image format. We used `Image.fromarray()` to get the image-format RGB dataset.
- Use `cv2.cvtColor` again to finish the process from BGR-RGB-Gary (make sure it has three channels).
- Transformed both of them into tensors.



Results



Loss plot of P2P

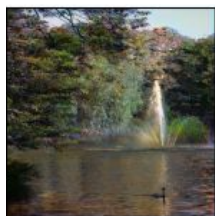
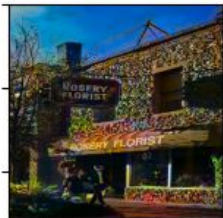


Performance Comparison

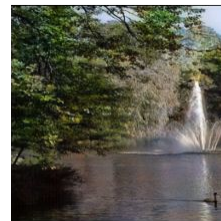


Performance Comparison

L*a*b* GAN



Pix2Pix GAN



Conclusion

- Automatically colorizing grayscale images using GAN to an acceptable visual degree
- The model was able to consistently produce better looking (qualitatively) images than real images
- The Pix2Pix performs better in general. And GAN based on L*a*b* performs better on the image that is similar to training set.
- Mis-colorization was a frequent occurrence with images containing high levels of textured details-- didn't learn enough from human photos

Limation

- The dataset does not include enough person images. The result is not good on person.
- The training process is very slow.
- And the game between Generator and Discriminator is not balance. Usually, D perform better.

Improvement

- Adding person images into training
- Speeding the training process, eg more powerful GPU, better machine computing powers
- Changing generator structures to be balanced with discriminator
- Seeking a better quantitative metric to measure performance -- all evaluations were qualitative
- Application in coloring videos: With further training and improvement, we can turn the black and white movies into color movies.

Q & A