

ECE 271

Digital Logic Design Final Project

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1 Project Description

The purpose of this project was to design and implement a digital logic design that incorporated the NES controller, the PS/2 Keyboard, and the VCR remote as inputs to a system that produced outputs using some of the following devices: a seven segment display, VGA output, LEDs, audio waves, or DC motors. Each input option has its own communication protocol that is processed by a driver to produce an output that can be used in one or more of the output devices. An overall description diagram is then shown in **Figure 1** and a hardware diagram is shown in **Figure 2**.

- **Inputs:** NES Controller, PS/2 Keyboard, and VCR remote.
- **Outputs:** Seven Segment Display, VGA output, Square wave audio output, and a L293D DC Motor.

1.1 Project Deliverables

- Supports communication protocols for the NES Controller, PS/2 Keyboard, and VCR Remote.
- Supports output devices: Seven Segment Display, VGA, LM386N-4 Audio IC, and L293D DC Motor.
- Allows the user to control input flow to certain outputs. For example, the seven segment display can use input from both the NES Controller and the VCR Remote.

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Fall 2019 Design Project

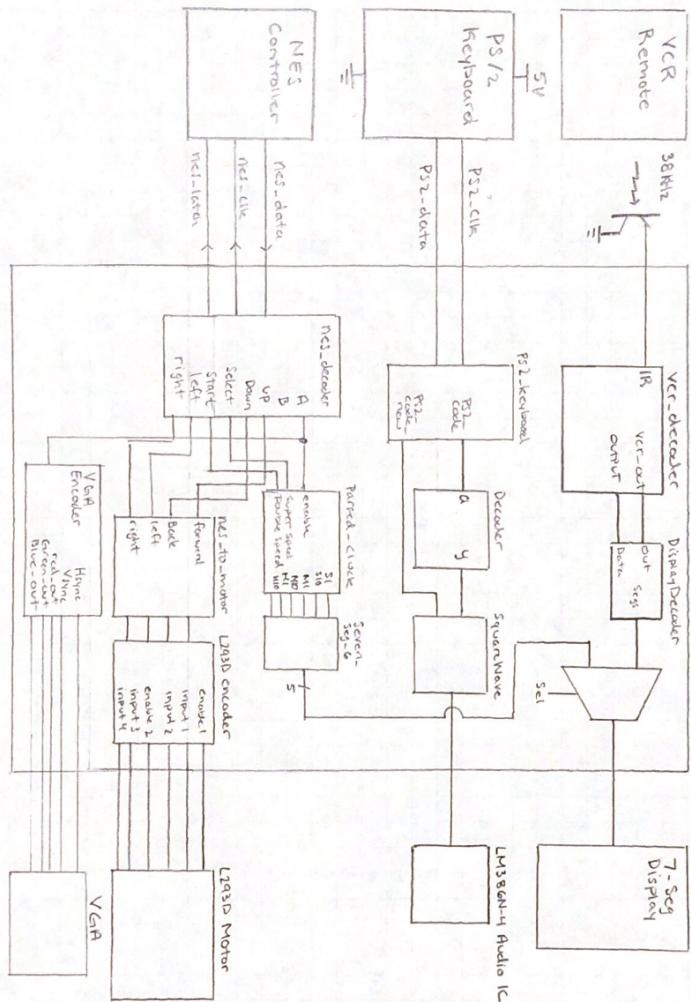


Figure 1: Top Level Diagram for the project. The Diagram shows all the Functional Units used in the project and how they are connected from input to output.

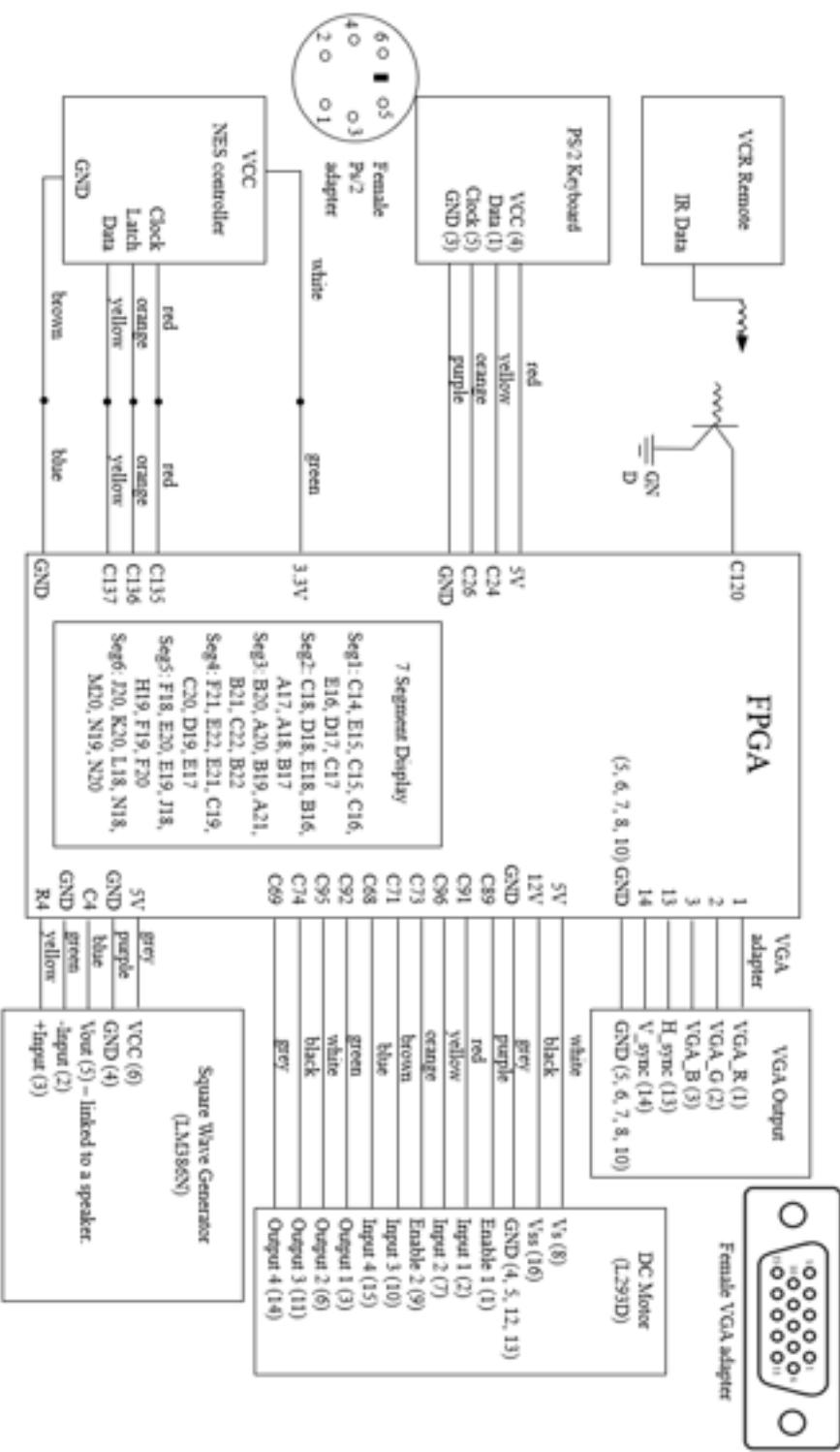


Figure 2: The hardware diagram shows which pins are used on the FPGA, module boards, and relevant supply voltages for the different pieces of hardware used in the system.

2 High Level Description

This section provides a Top level introduction to the project. The input and output specifications are provided below, as well as a toplevel diagram in **Figure 3**, and the simulation results in **Figure 4**.

- **Inputs:** The Top Level of the project has 7 inputs: switch1, switch2, system_reset_button, nes_data, clock_50MHz, ps2_clk, and ps2_data.
- **switch1:** switch1 is used to enable the square wave generator unit connected to the PS2 Keyboard.
- **switch2:**
- **system_reset_button:** system_reset_button is an active high signal used to reset the nes_decoder, vga_encoder, and parsed_clock Functional Units.
- **nes_data:** the input signal from the NES Controller into the nes_decoder Functional Unit.
- **clock_50MHz:** the internal clock on the FPGA that is used generate all the other clock signals used in the top level.
- **ps2_clk:** the clock signal driving the ps2_keyboard Functional Unit.
- **ps2_data:** the input signal from the PS2 Keyboard into the ps2_keyboard functional unit.

- **Outputs:** The Top level has outputs going to the NES Controller, the seven segment pins in the FPGA, the L293D DC Controller, the square wave generator, and the VGA pins.

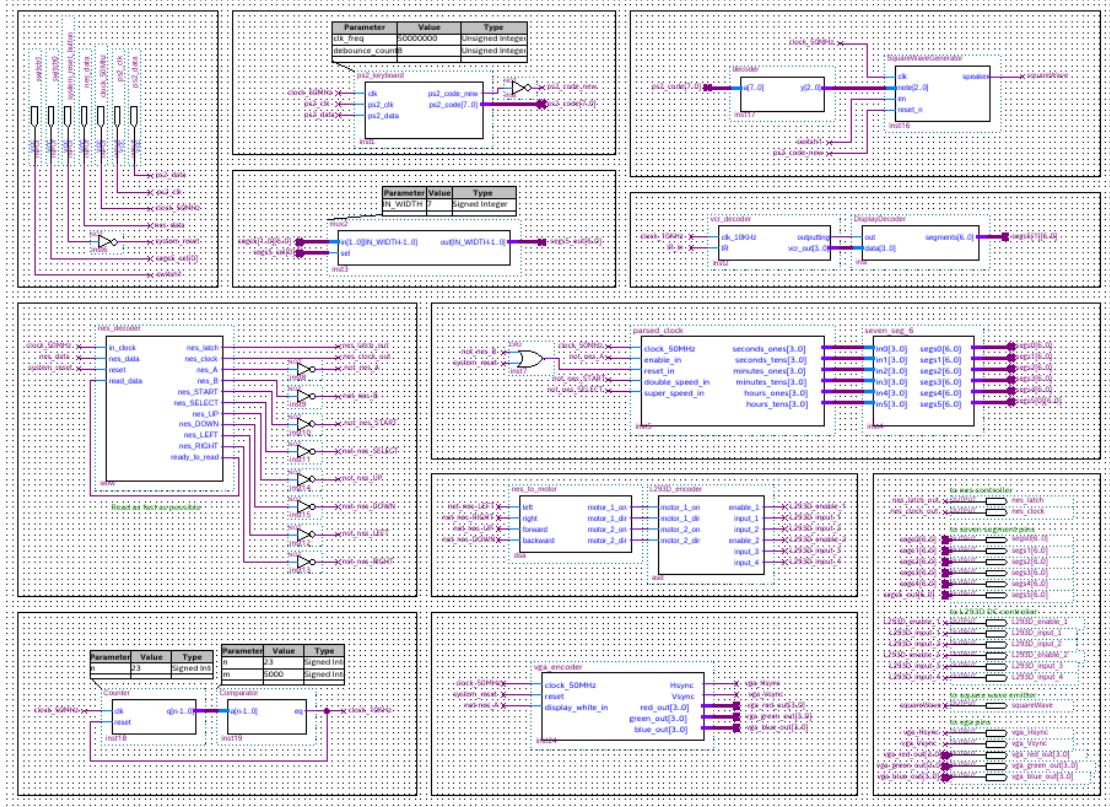
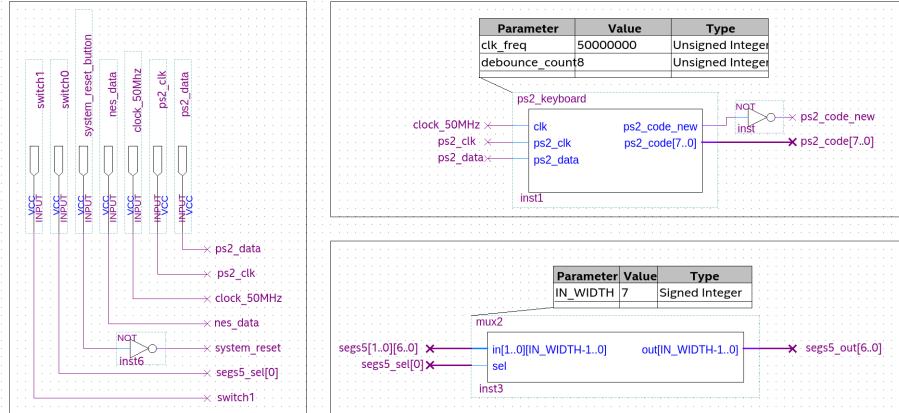
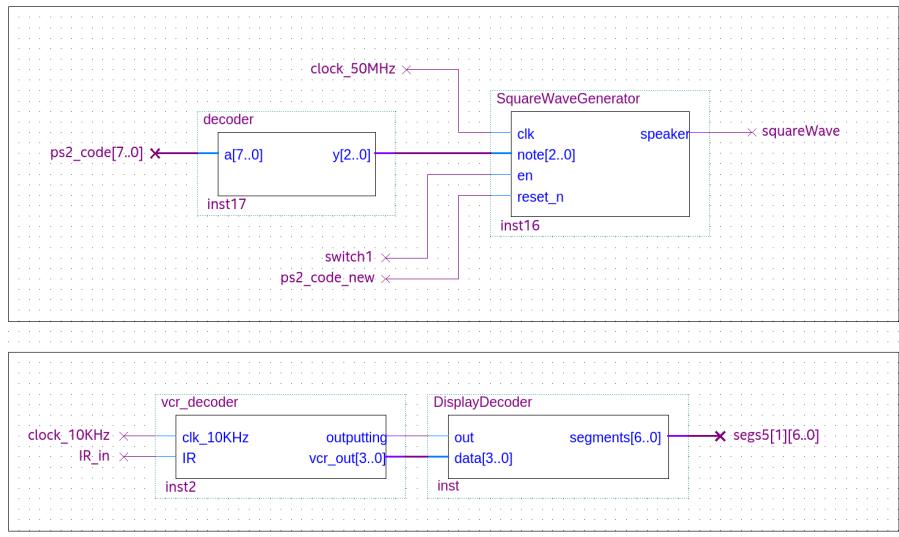


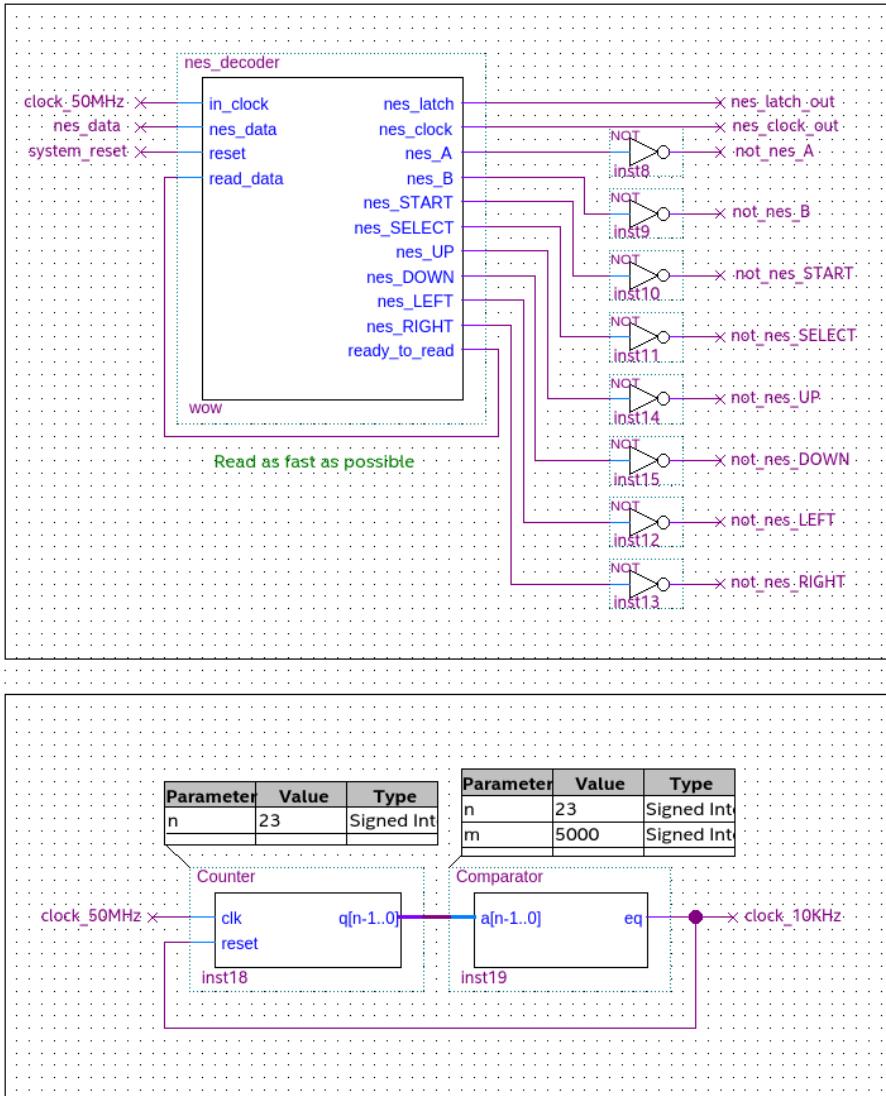
Figure 3: The top level design for the project.



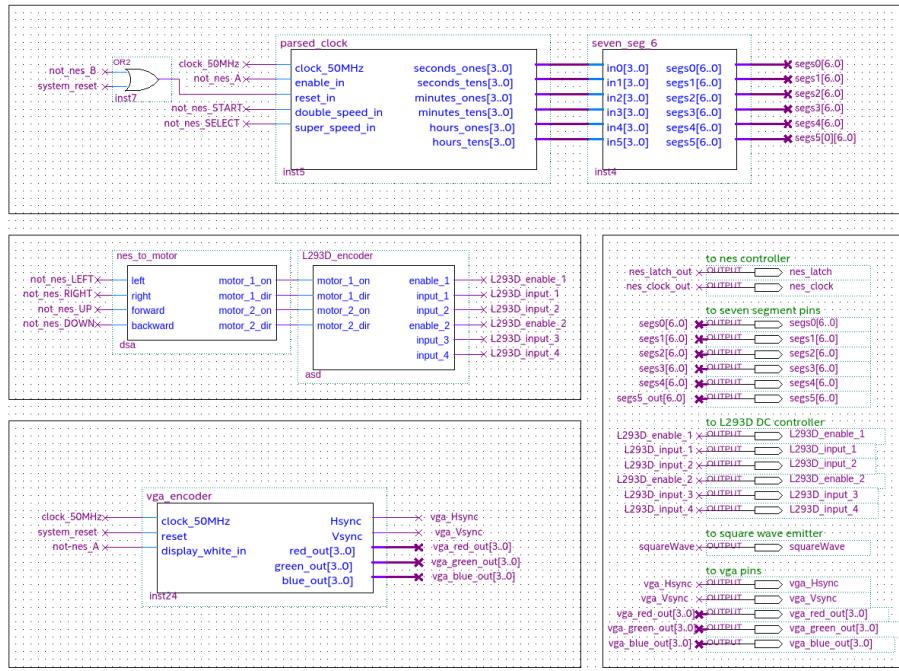
(a) Block 1 of top level. Includes the inputs to the Top Level of the design, the ps2_keyboard Functional unit, and the Multiplexer Functional Unit that controls input to the seven segment display.



(a) Block 2 of top level. Includes the decoder for the ps2_keyboard functional unit, the square wave generator functional unit, the vcr_decoder functional unit, and the DisplayDecoder functional unit.



(a) Block 3 of top level. Includes the nes_decoder functional unit and the Counter and Comparator functional units used to generate the clock signal for the vcr_decoder



(a) Block 4 of top level. Includes the `parsed_clock`, `seven_seg_6`, `nes_to_motor`, `L293D_Encoder`, and `vga_encoder` functional units. In addition, it includes the outputs for the Top Level of the project.

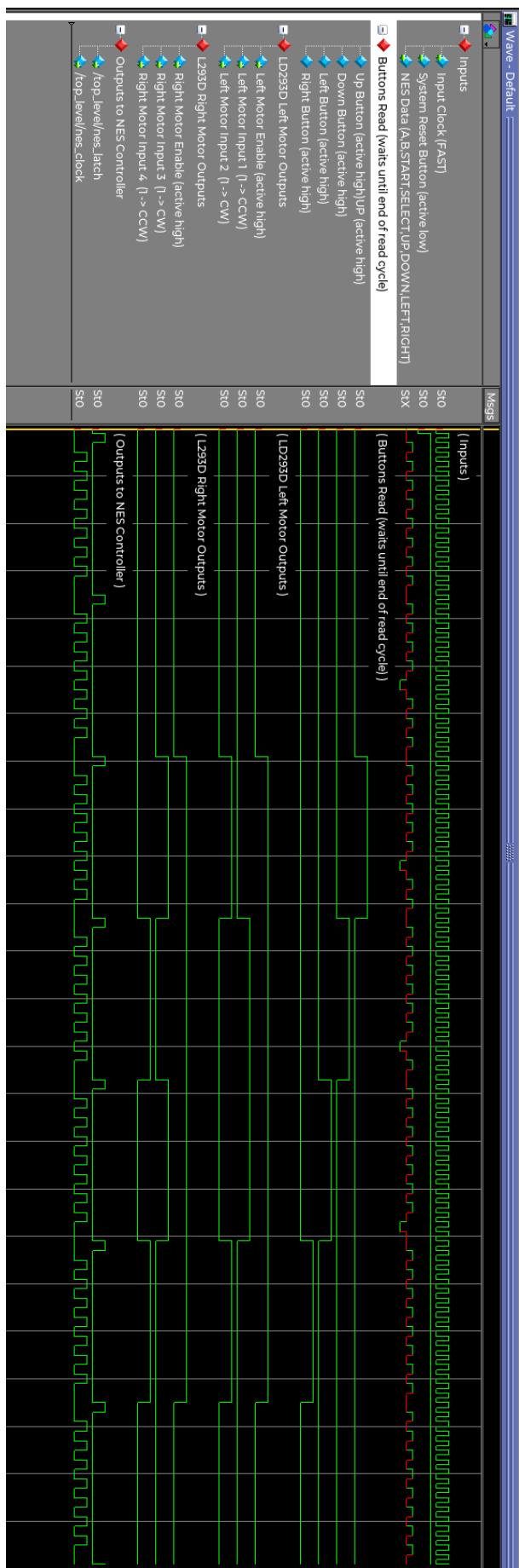


Figure 8: The simulation results for the L293D DC Motor in the Top Level.

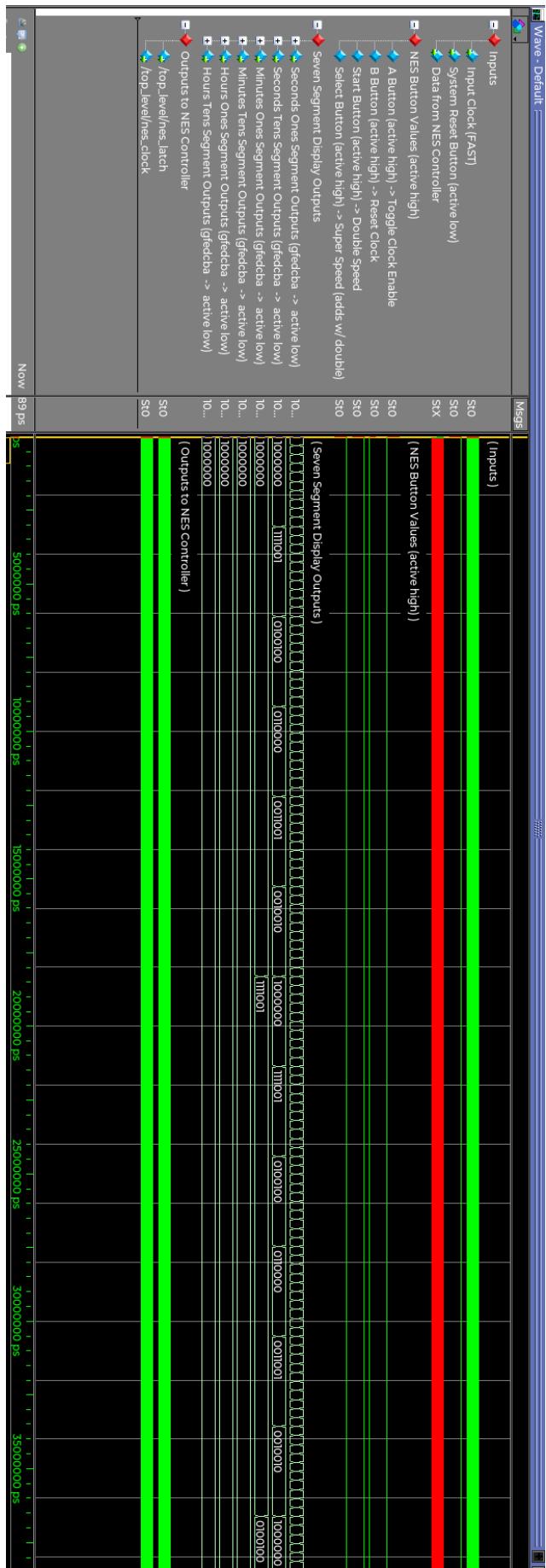


Figure 9: The simulation results for the NES Controller to seven segment display in Top Level.

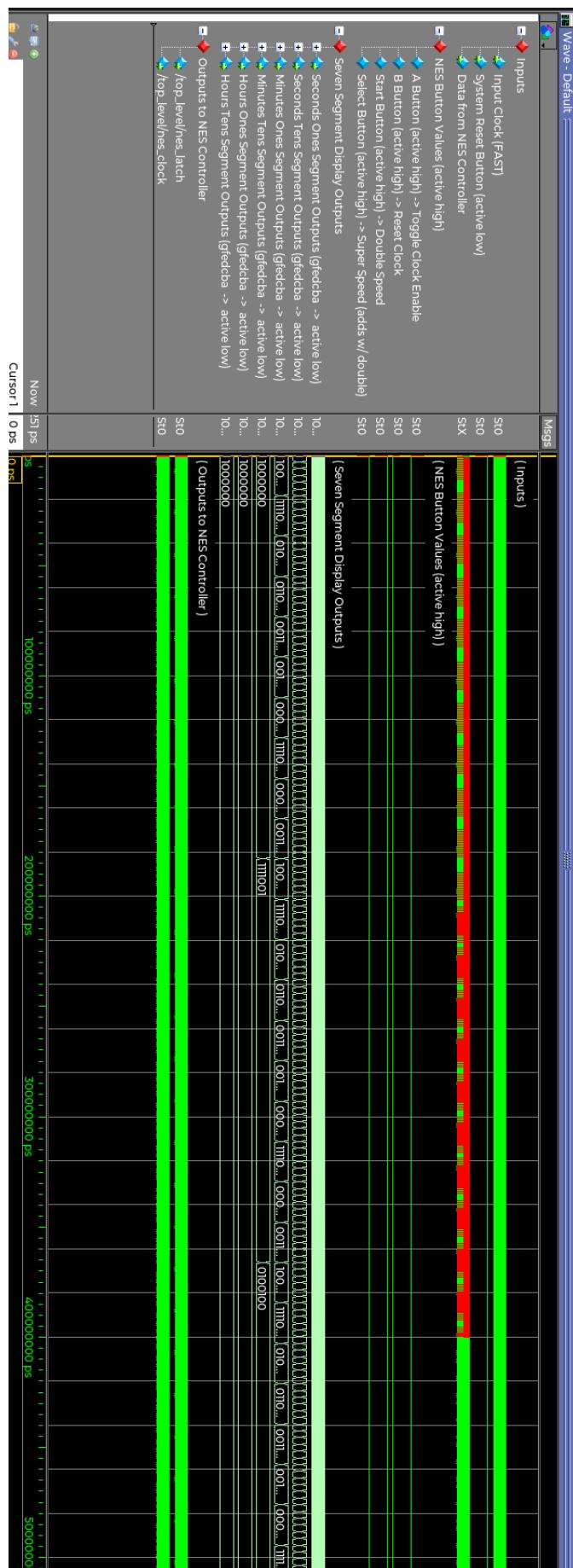


Figure 10: The simulation results for the NES Controller to seven segment display in Top Level.

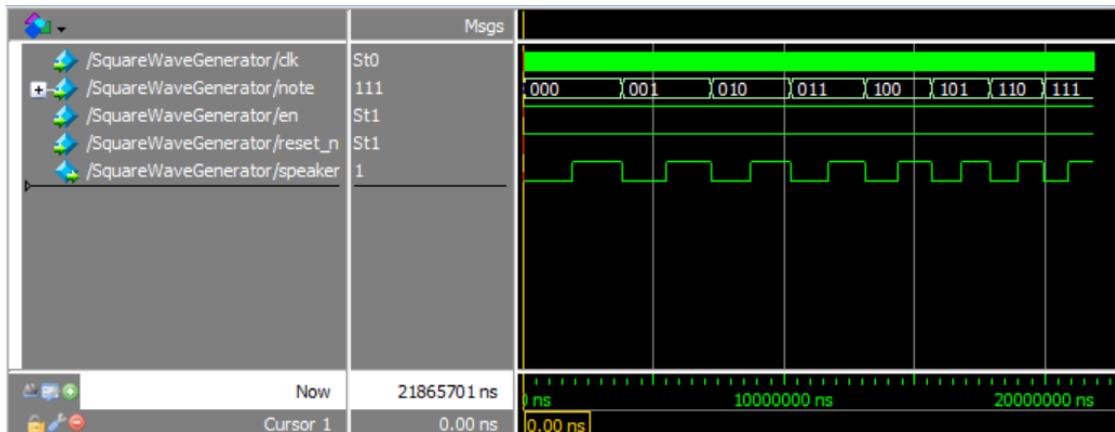


Figure 11: The simulation results for the PS2 Keyboard to the LM386N-4 Audio IC in Top Level.

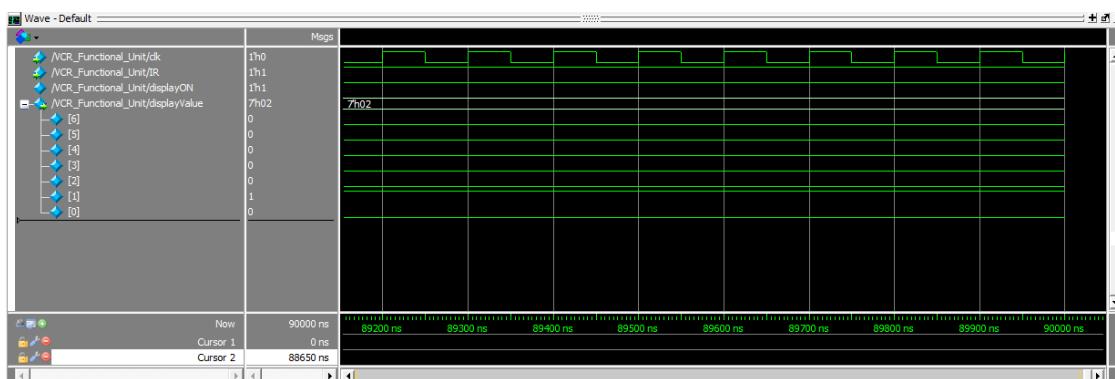


Figure 12: The Simulation results for Top Level VCR output with expected value of 6.

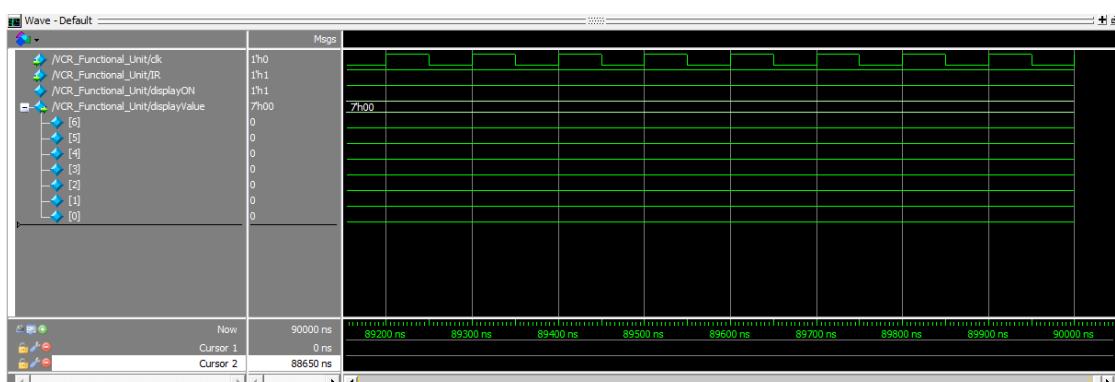


Figure 13: The Simulation results for Top Level VCR output with expected value of 8.

The following subsections will discuss the inputs, outputs, designs, and simulation results of all elements of the design at two levels of scrutiny: functional units and individual blocks of digital logic.

2.1 decoder Functional Unit

The decoder block decodes the data from the PS/2 keyboard to the three-bit data. To match the keys in keyboard from a to t with the piano notes from middle C to the upper octave C, the hexadecimal code of the keyboard is converted to 3-bit data as shown in the simulation. The logic symbol follows in **Figure 15**. The simulation results follow in **Figure 16**.

- **Inputs:** The decoder block has one input, $a[7..0]$. It indicates the input 8-bit data, which is the make code for keys on the keyboard.
- **Outputs:** The decoder block has one output, $y[2..0]$. It is converted from 8-bit to 3-bit data and is used to determine the note to generate.

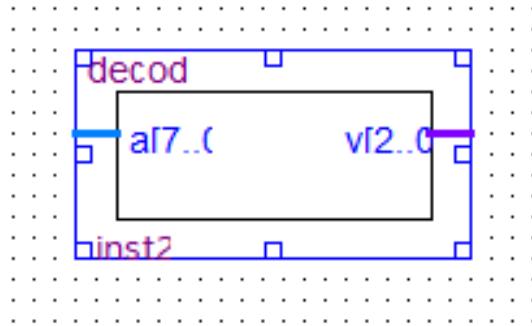


Figure 14: The block symbol of the decoder functional unit used in the final design.



Figure 15: The simulation results for the decoder module.

2.2 seven_seg_6 Functional Unit

The seven_seg_6 module takes in six 4-bit binary values and converts them into the signals required to display each number (which will never exceed 9 in this design) on the FPGA's seven segment display. In this design, these inputs come directly from the parsed_clock module that is controlled by the nes controller, and all but the most significant bit of these seven segment data lines go directly to the FPGA's seven segment display. In this design, either the most significant bit of the parsed_clock OR the output of the vcr_decoder are displayed on the seven segment display's most leftmost digit, depending on the state of the switch0 design input (determined by the mux2 submodule of the vcr_decoder module). A block diagram follows in **Figure 17**. The logic symbol follows in **Figure 18**. The simulation results follow in **Figure 19**.

- Inputs:** Six 4-bit binary value inputs from the parsed_clock module that describe the one's and ten's places of the seconds, minutes, and hours of the clock. These values never exceed 59 seconds, 59 minutes, and 23 hours, so each place can only be 0-9 and failure of the sevenseg submodules due to overflow is impossible.
- Outputs:** Six 7-bit outputs describing how to display each input on a seven segment display. All but the most significant bit of these seven segment data lines go directly to the FPGA's seven segment display. In this design, either the most significant bit of the parsed_clock OR the output of the vcr_decoder are displayed on the seven segment display's most leftmost digit, depending on the state of the switch0 design input (based by the mux2 submodule of the vcr_decoder module).

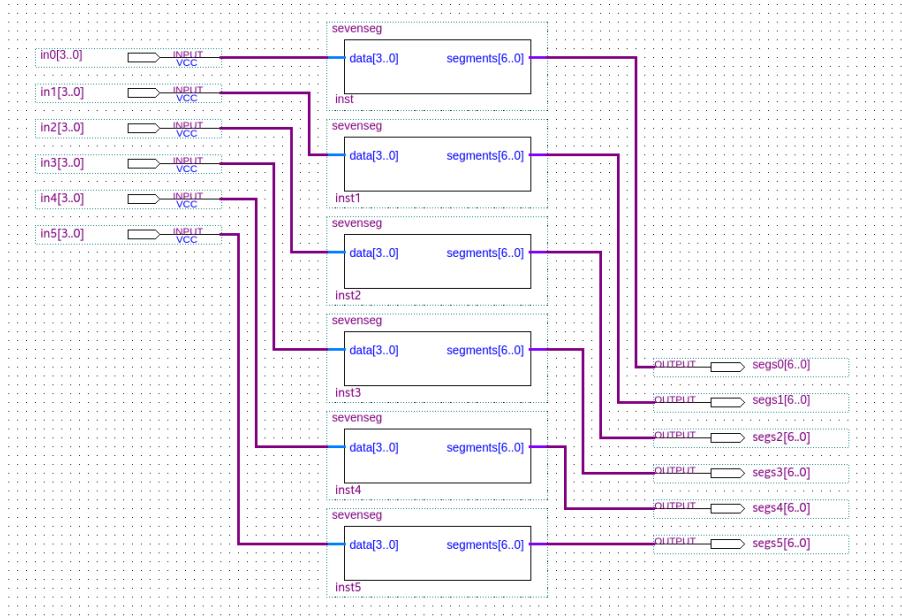


Figure 16: The logic design of the seven_seg_6 functional unit used in the final design.

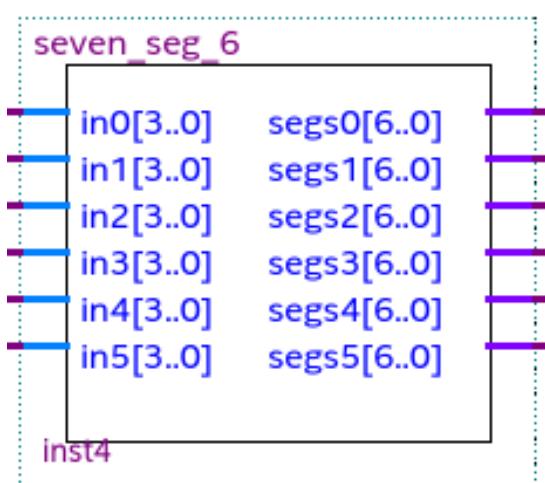
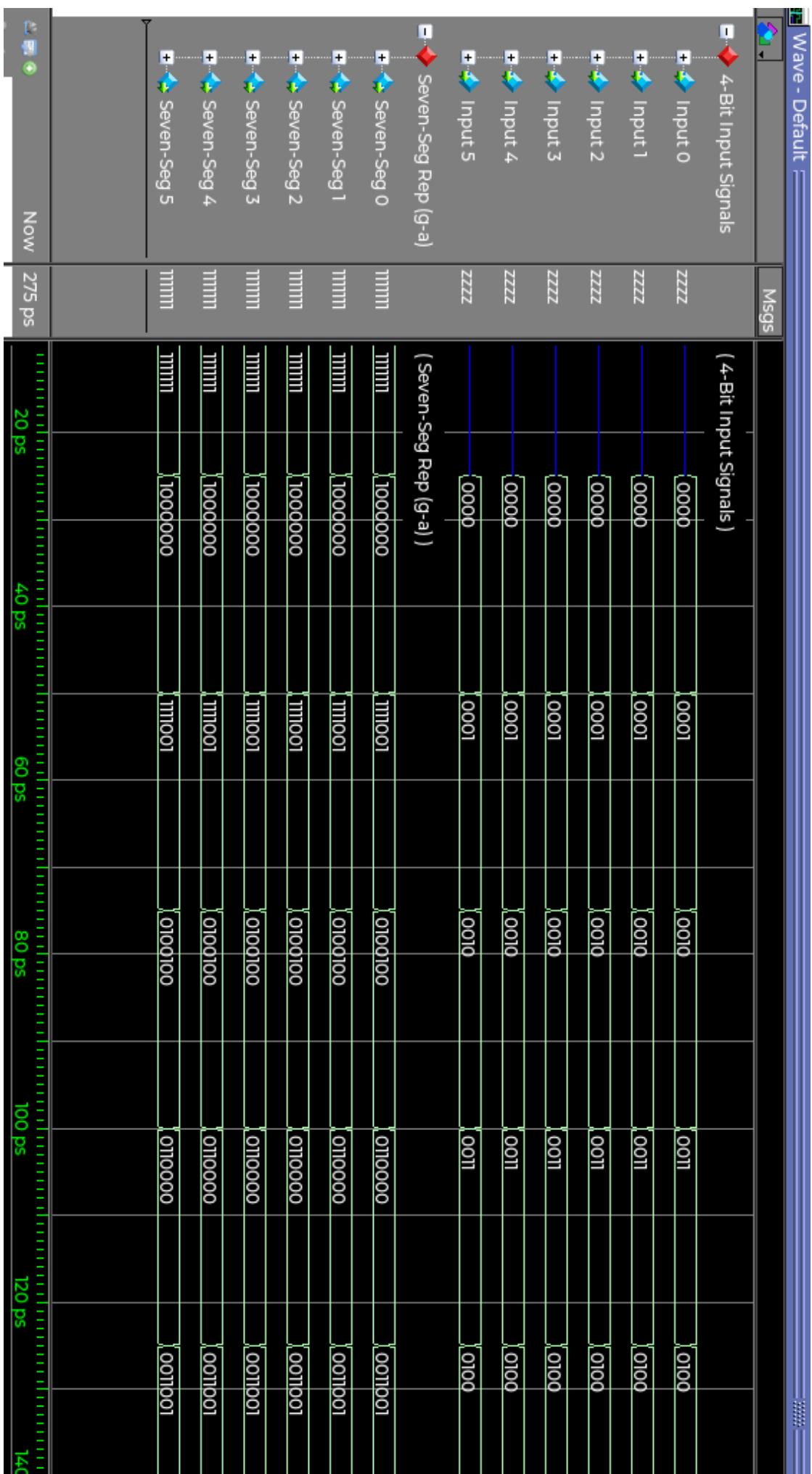


Figure 17: The block symbol of the `seven_seg_6` functional unit used in the final design.



2.2.1 sevenseg Component Block

The sevenseg submodule converts a single 4-bit value between 0 and 9 into a 7-bit output describing how to display the input on a seven segment display. In this design, six of these sevenseg blocks are used in the seven_seg_6 module. The logic symbol follows in **Figure 20**. The simulation results follow in **Figure 21**.

- **Inputs:** A single 4-bit value between 0 and 9 to be converted in to a seven segment representation (data[3:0]).
- **Outputs:** A 7-bit output describing how to display the input value on a seven segment display (segments[6:0]).

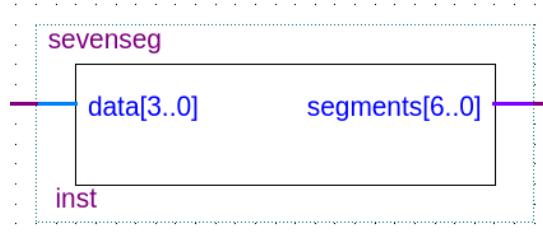


Figure 19: The block symbol of the sevenseg module used in the seven_seg_6 functional unit.

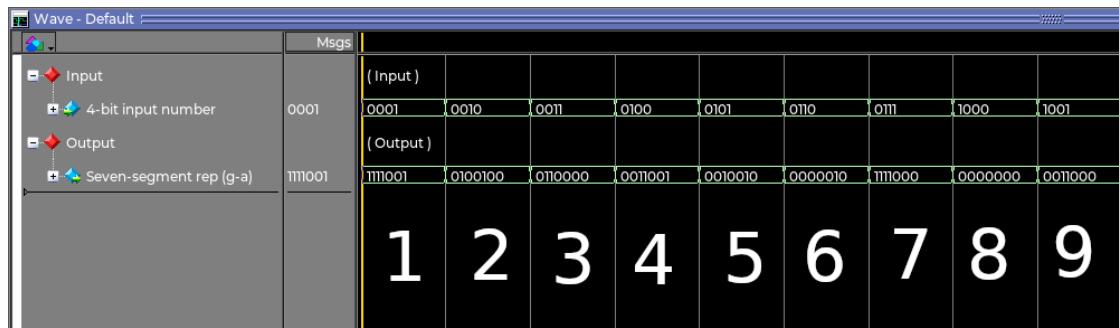


Figure 20: The simulation results for the sevenseg module used in the seven_seg_6 functional unit.

2.3 L293D_encoder Functional Unit

The L293D_encoder functional unit converts internal system values describing how two motors should be driven to data in the format of the L293D DC motor controller. It is connected to these outputs, and takes its inputs from the nes_to_motor module. The logic symbol follows in **Figure 22**. The simulation results follow in **Figure 23**.

- Inputs:** Whether motors 1 (left) and 2 (right) should be spinning (motor_1_on and motor_2_on); and which direction each motor should spin if also enabled, where logic high correlates to clockwise motion (motor_1_dir and motor_2_dir for each motor, respectively).
- Outputs:** The signals that the L293D DC motor controller takes in as inputs: enable_1 and enable_2 that describe whether motor 1 (left) and motor 2 (right) should be run; input_1 and input_2 which are always opposite signals describing the direction of rotation of the first (left) motor (where input_1 high and input_2 low correlates with clockwise rotation, for example); and input_3 and input_4 which are always opposite signals describing the direction of rotation of the second (right) motor (where input_1 high and input_2 low correlates with clockwise rotation, for example).

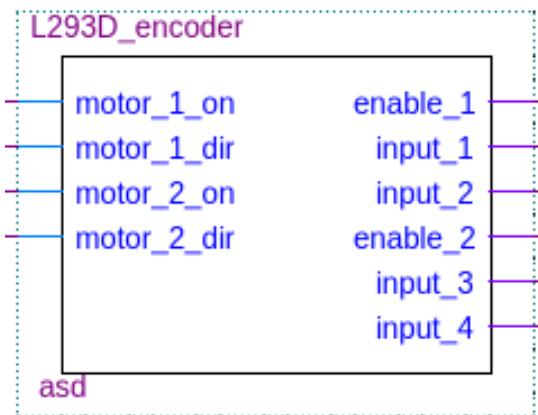


Figure 21: The block symbol of the L293D_encoder functional unit used in the final design.

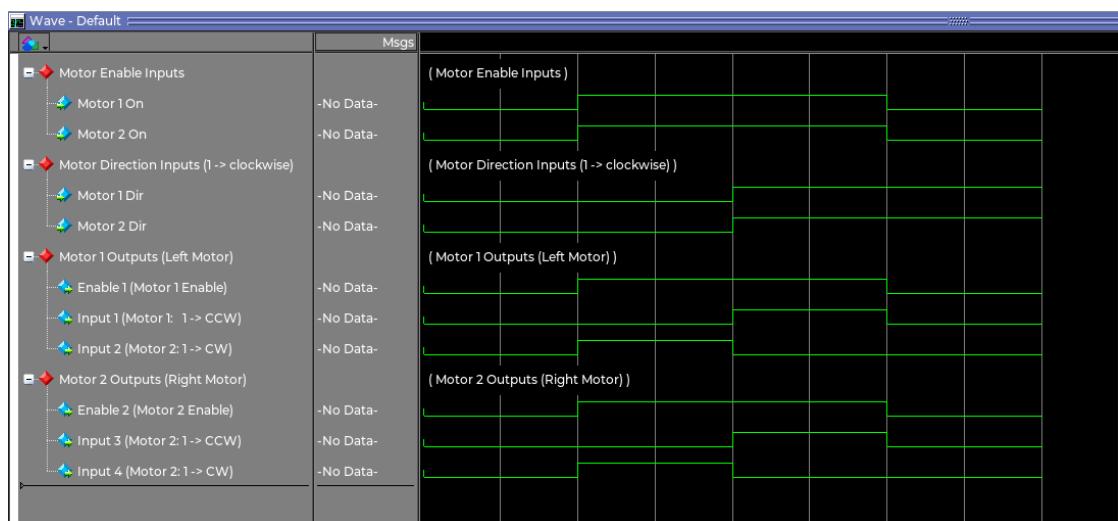


Figure 22: The simulation results for the L293D_encoder module.

2.4 Counter Functional Unit

The Counter Functional Unit increments a counter on every rising edge of the input clock signal. This is used to generate a 10 KHz clock signal to drive the vcr_decoder Functional Unit. The logic symbol follows in **Figure 24**. The simulation results follow in **Figure 25**.

- **Inputs:** The Counter Functional Unit has 2 inputs: clk and reset. clk is the 50 MHz FPGA clock that is used to drive the counter. reset is an input signal that resets the counter to 0.
- **Outputs:** The Counter Functional Unit has 1 output: q. q is a 23-bit value with the current value of the counter.

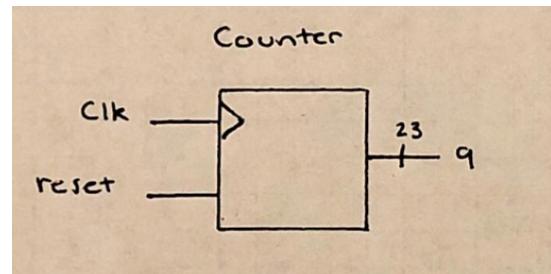


Figure 23: The block symbol of the Counter functional unit used in the final design.

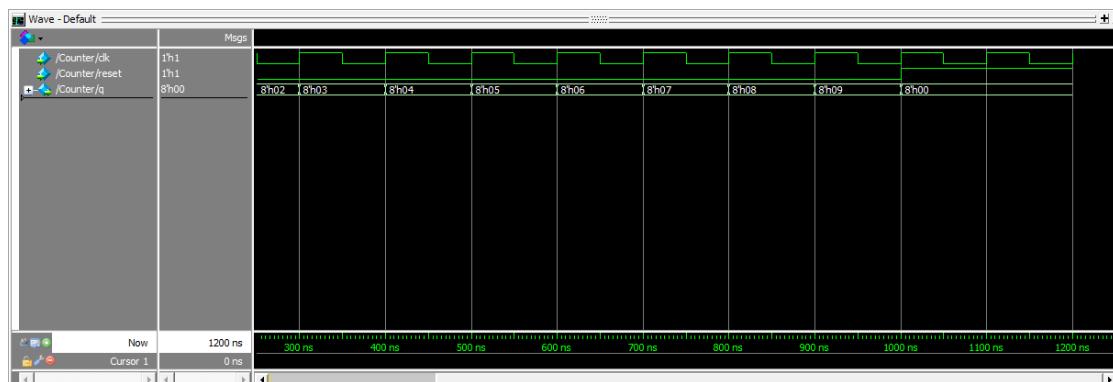


Figure 24: The simulation results for the Counter module.

2.5 vga_encoder Functional Unit

Intro text. A block diagram follows in **Figure 26**. The logic symbol follows in **Figure 27**.

- **Inputs:** Input text.
- **Outputs:** Output text.

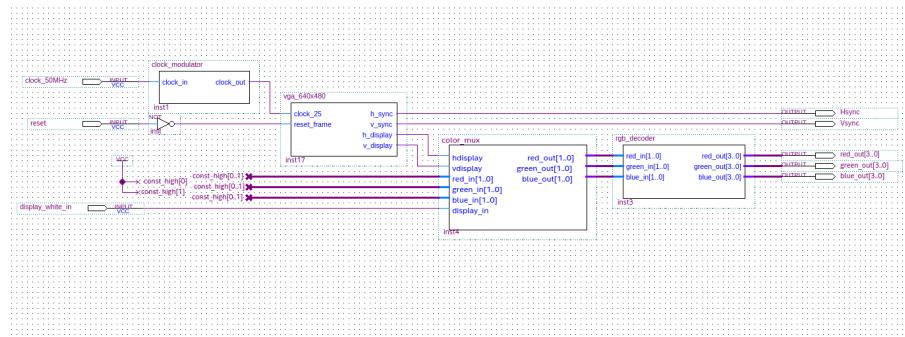


Figure 25: The logic design of the vga_encoder functional unit used in the final design.

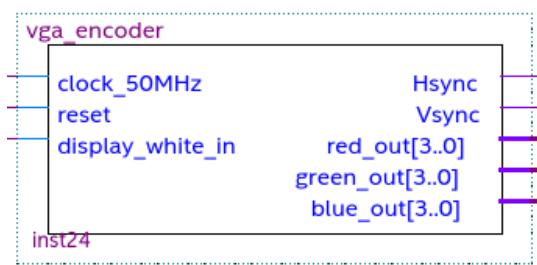


Figure 26: The block symbol of the vga_encoder functional unit used in the final design.

2.6 vcr_decoder Functional Unit

The vcr_decoder module converts an IR signal sent from a VCR remote into a decimal value between 0 and 9. The logic symbol follows in **Figure 28**.

- **Inputs:** The vcr_decoder module has two inputs, clk and IR. clk is a 10 KHz clock signal that is used to drive the module. IR is the Infrared signal coming from the VCR remote that will be translated by the module.
- **Outputs:** The vcr_decoder module has a single output, displayValue, which is the 0-9 representing the IR signal that was received by the module as input.

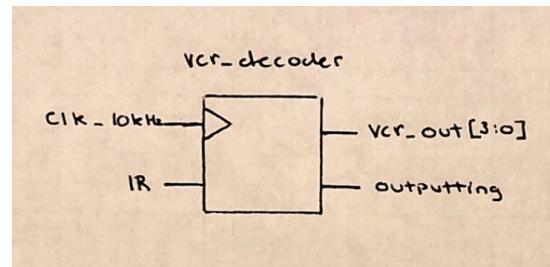


Figure 27: The block symbol of the vcr_decoder functional unit used in the final design.

2.6.1 mux2 Component Block

The mux2 individual block is used to choose whether the seven segment display shows the output of the nes decoder functional unit or the vcr_decoder functional unit.

- **Inputs:** The mux2 individual block has 2 inputs: sel and in. in is the input signal which is 2 bits wide. sel is used to select which of the values goes to the output.
- **Outputs:** The mux2 individual block has 1 output: out. This is the value that is selected by the sel input signal.

2.6.2 ReadState Component Block

The ReadState Individual Block is used to implement the READ state within the vcr_decoder Module. The logic symbol follows in **Figure 29**.

- **Inputs:** The ReadState Individual Block has 3 inputs: clk, IR, and start. clk is a 10 KHz clock that drives the ReadState block. IR is the infrared signal generated by the VCR remote on a given button push. Start is a control signal for the ReadState Individual Block. When start is 1, the block will operate.
- **Outputs:** The ReadState Individual Block has 2 outputs: pushOutput and outputValue. pushOutput is a control signal that is used to communicate that the ReadState block is ready to output the value of outputValue. outputValue is the 32-bit value that identifies the IR signal that received by the block.

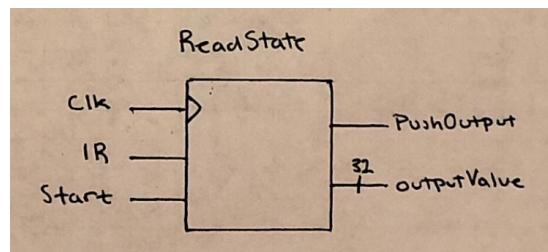


Figure 28: The block symbol of the ReadState module used in the vcr_decoder functional unit.

2.6.3 ShiftRegister Component Block

The ShiftRegister Individual Block is used to store the 32-bit IR signal value bit by bit as it is read in by the ReadState Module. The logic symbol follows in **Figure 30**. The simulation results follow in **Figure 31**.

- Inputs:** The ShiftRegister Individual Block has five inputs. The first input is a clock signal, clk. On every rising edge of this clock signal, a new bit is shifted into the register. The second input is sin. This is the bit that is being shifted into the register. the third input is d. d is a 32-bit value which can be used to fully load the shift register. The fourth input is load. When load is 1, the value stored at d is shifted into the register. The final input is reset, which clears the shift register's contents
- Outputs:** The ShiftRegister Individual Block has 2 outputs, q and sout. q is a 32-bit value that represents all the bits that have been shifted into the register. sout is the most significant bit in q.

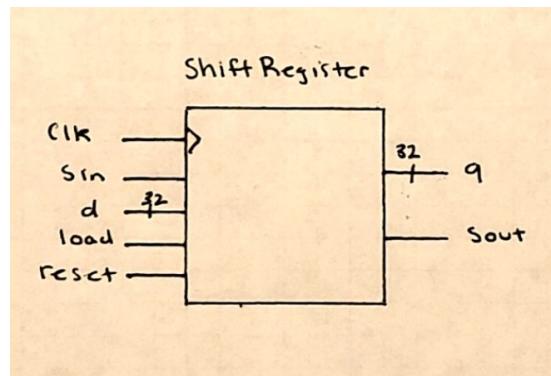


Figure 29: The block symbol of the ShiftRegister module used in the vcr_decoder functional unit.

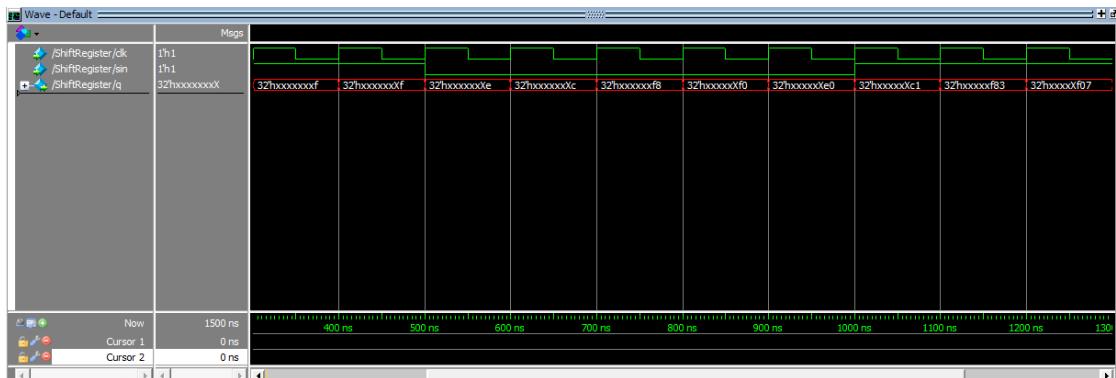


Figure 30: The simulation results for the ShiftRegister module used in the vcr_decoder functional unit.

2.6.4 signalDecoder Component Block

The SignalDecoder Individual Block is used to convert the 32-bit value generated by the ReadState Individual Block into a 4-bit value between 0 and 15 that indicated which button on the VCR remote was pressed.

- **Inputs:** The SignalDecoder Individual Block takes a single 32-bit input that corresponds to the complete IR signal that was read in by the ReadState Individual Block.
- **Outputs:** The SignalDecoder Individual Block outputs a 4-bit value between 0 and 15.

2.7 ps2_keyboard Functional Unit

PS/2 is an interface for keyboards and mice to PC via a 6-pin Mini-DIN connector. The system must provide the keyboard or mouse with 5V source and ground connections. Communication occurs over two wires, a clock line and a data line. The clock has a frequency between 10 kHz and 16.7 kHz. The data has a start bit, which is set as logic low, one byte of data, a parity bit, and a stop bit, which is set as logic high. Each bit is read on the falling edge of the clock signal. In the schematics, ps2_data and ps2_clk first synchronized and debounced. The data signal is then loaded to a shift register on falling edges of the PS/2 clock so that the flip flops can store the data. When the data transmission is finished and the clock remains high for more than 55us, the time longer than half of the worst-case PS/2 clock period, idle counter sends logic high to the AND gate. If there is no error and the signal from the idle counter is high, ps2_code_new becomes logic high indicating that the block is ready for the next signal. The ps2_code[7..0] gets ps2_word[8..1] because flip flops in that position contain the data. In the simulation, the waves indicate clock with 50MHz, ps2_clk, ps2_data, ps2_code_new, and ps2_code[7..0] in sequence. The signals for ps2_clk and ps2_data are gotten from the csv file provided. After ps2_word[10..0] stores the signal of ps2_data at the falling edge of the ps2_clk, ps2_code_new becomes 1 and ps2_word[8..1] is sent to ps2_code[7..0] if there is no error. The simulation figures below shows the simulation of pushing the keys of a, s, d, f, w, e, r, and t. The keys in PS/2 Keyboard have make code in hexadecimal. The code for the keys used in this project is 0x1C, 0x1B, 0x23, 0x2B, 0x1D, 0x24, 0x2D, and 0x2C respectively. The codes are shown in the simulation in the binary format. A block diagram follows in **Figure 32**. The logic symbol follows in **Figure 33**. The simulation results follow in **Figure 34**.

- **Inputs:** The PS/2 keyboard module has three inputs, clk, ps2_data, ps2_clk. The clk is the clock signal of 50MHz, ps2_clk is the clock signal sent from the PS/2 keyboard to read the data, and the ps2_data is the data sent from PS/2 keyboard.
- **Outputs:** The PS/2 keyboard module has two outputs, ps2_code[7..0], ps2_code_new. The ps2_code[7..0] is the make code data for keys on the keyboard, and ps2_code_new indicates whether the module is ready for the next data or not.

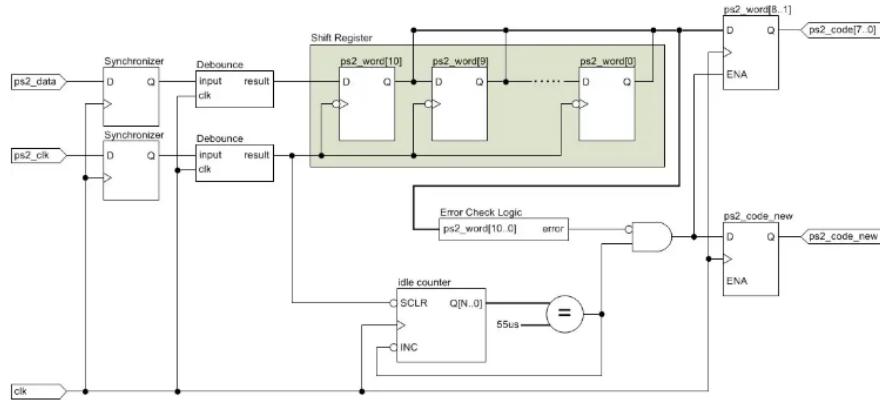


Figure 31: The logic design of the ps2_keyboard functional unit used in the final design.

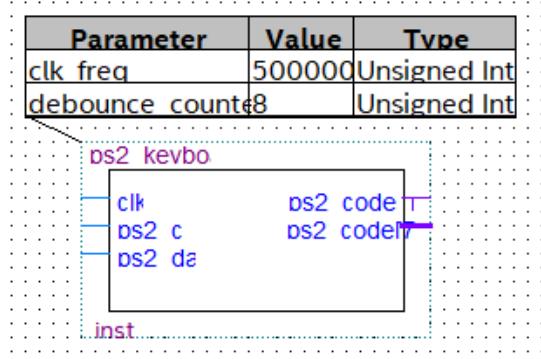


Figure 32: The block symbol of the ps2_keyboard functional unit used in the final design.

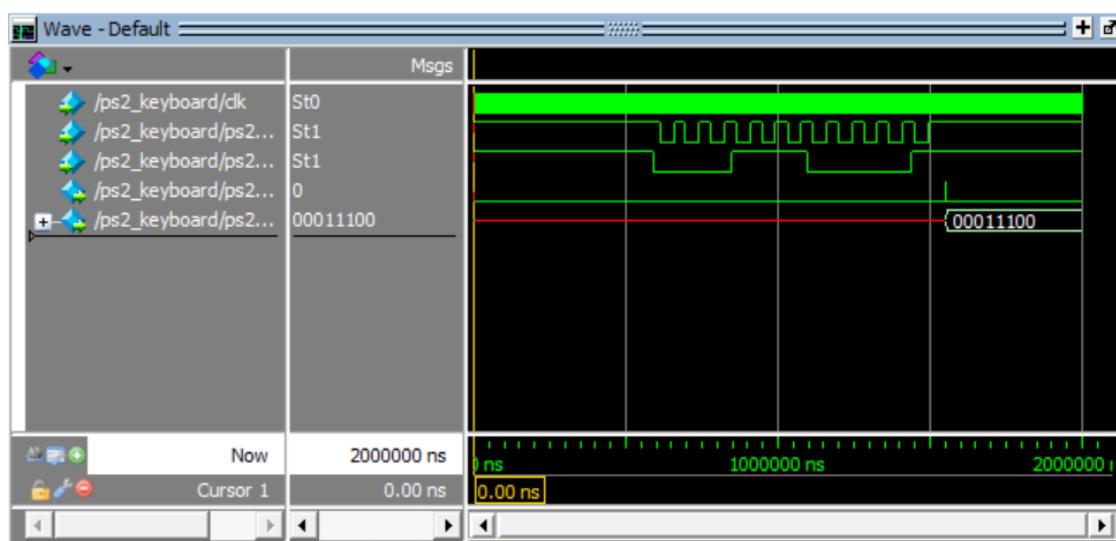


Figure 33: The simulation results for the ps2_keyboard module.

2.7.1 debounce Component Block

When using mechanical switches, the signals often rebound, or bounce, off one another before settling into a stable state. The debounce component is used for successfully sending the data in a stable state. Two flip flops in the design check whether the data changes or not via the XOR gate. If the data changes, the counter block receives the signal to reset the counter. If not, the counter increases until it reaches the specified time and enables the output register. According to simulation, when the data remains stable for 40 ns, the data is sent to the last flip flop and the result signal is updated. A block diagram follows in extbfFigure 35. The simulation results follow in **Figure 36**.

- **Inputs:** The debounce block has one input: button. It indicates the input from the keyboard.
- **Outputs:** The debounce block has one output: result. It has the debounced value of the button.

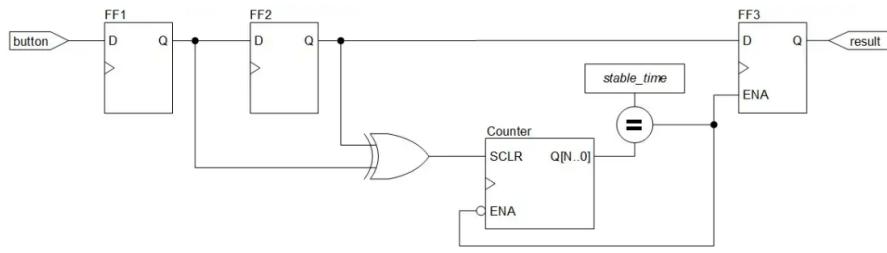


Figure 34: The logic design of the debounce module used in the ps2_keyboard functional unit.

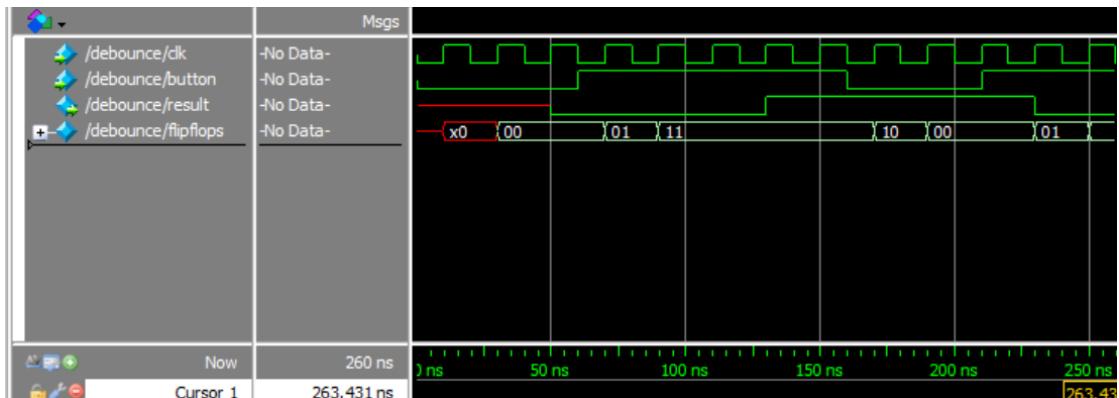


Figure 35: The simulation results for the debounce module used in the ps2_keyboard functional unit.

2.8 nes_decoder Functional Unit

The nes_decoder module interfaces with inputs from and outputs to the nes controller hardware to parse the states (active low) of the eight buttons on the controller. The logic symbol follows in **Figure 37**. The simulation results follow in **Figure 38**.

- **Inputs:** An input clock (at 50MHz for this design) which determines how quickly the system reads the nes inputs; an nes_data input that is the serialized data from the nes controller which describes the buttons pushed at any given moment; a reset signal that sets the system back to a default state; and a read_data input that, when driven high while the system is ready to read, starts the reading process. The nes_data input is the only input connected to the nes controller.
- **Outputs:** Two outputs (nes_latch and nes_clock) that are sent to the nes controller and signal to the controller to start sending the first or next button states along nes_data, respectively; ready_to_read, which is driven high by the module after the system has completed an input reading period and is ready for another round of reading; and eight outputs describing the most recently read states of each of the buttons on the nes controller (active low, they are the A, B, Start, Select, Up, Down, Left, and Right Buttons).

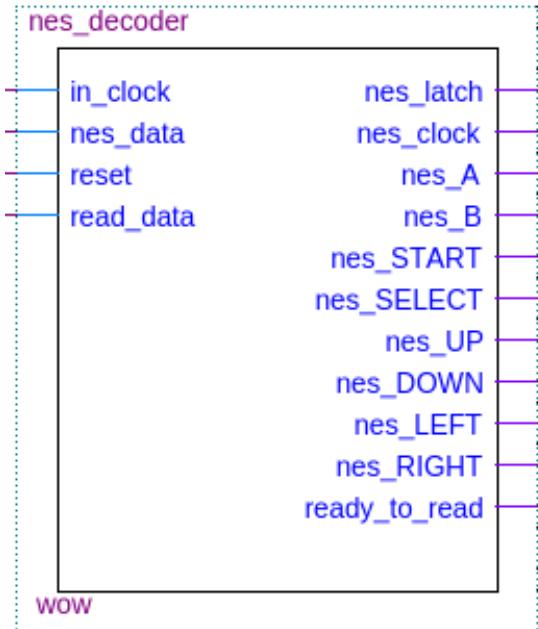


Figure 36: The block symbol of the nes_decoder functional unit used in the final design.

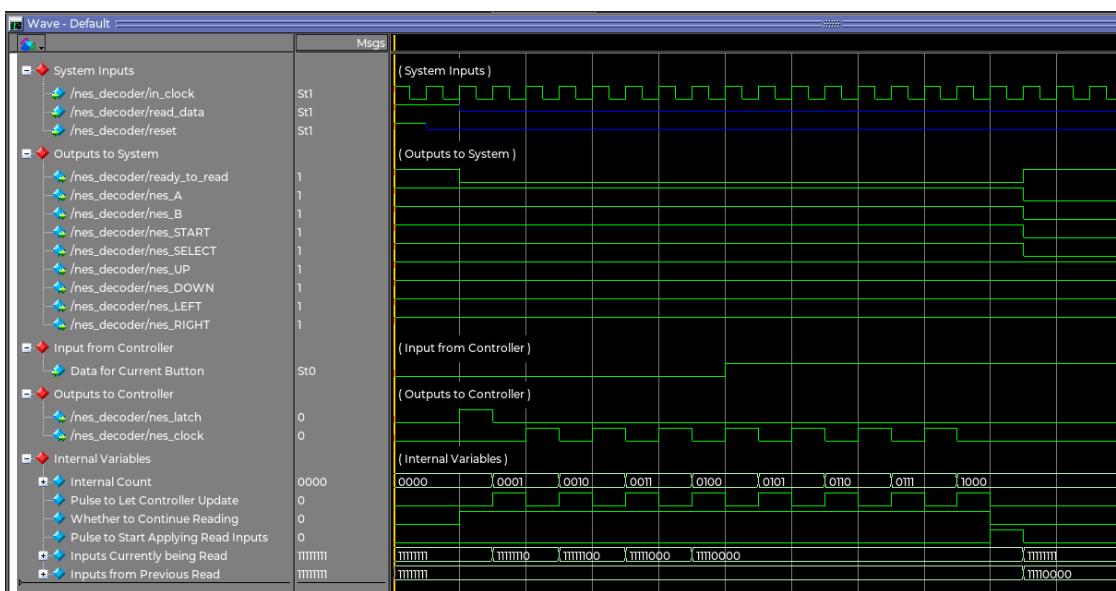


Figure 37: The simulation results for the nes_decoder module.

2.9 parsed_clock Functional Unit

The parsed_clock module takes in a clock and some control signals that start, modify the speed of, and reset a clock that is accurate to 1Hz. These outputs are parsed into seconds, minutes, and hours (in decimal notation) to match the typical clock format of (HH.MM.SS). The inputs come from the nes_decoder and the FPGA's internal pins, and the outputs all go to the seven_seg_6 (six-digit seven segment display decoder) module in the design. A block diagram follows in **Figure 39**. The logic symbol follows in **Figure 40**. The simulation results follow in **Figure 41**.

- Inputs:** A 50Mhz clock from the FPGA's internal pins; a reset signal from either the active-high button state of the B button on the nes controller or the overall system_reset signal that is the active-high button state of a button on the FPGA itself; and four more active-high button states from the nes controller (A Button acting as the start (toggle) enable signal of the clock, Start Button acting as the double-speed mode input of the parsed clock while held, and the Select Button acting as the super-speed mode input of the parsed clock while held).
- Outputs:** Six 4-bit binary value outputs describing the one's and ten's places of the seconds, minutes, and hours of the parsed clock. These values never exceed 59 seconds, 59 minutes, and 23 hours, so overflow is impossible. These outputs all directly lead to the seven_seg_6 module that converts these 4-bit values into seven segment encoded values.

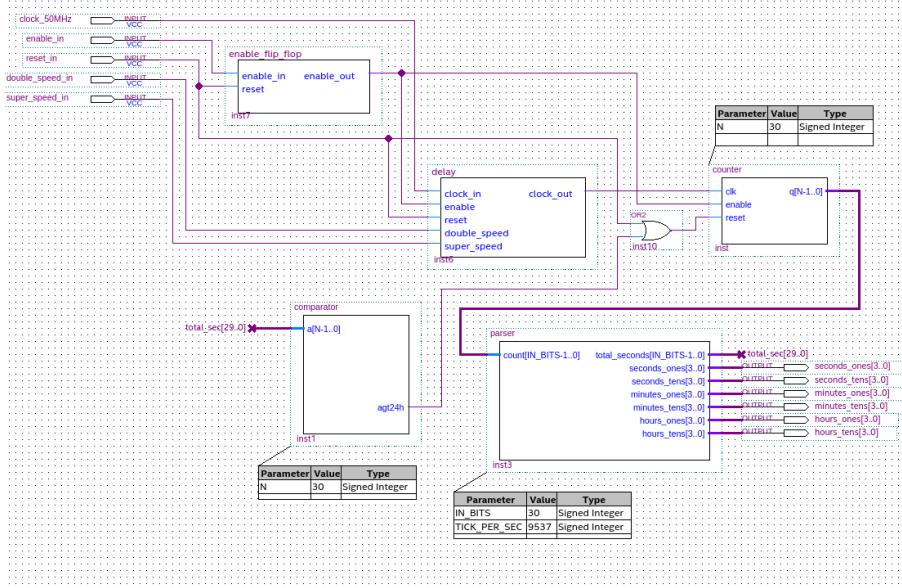


Figure 38: The logic design of the parsed_clock functional unit used in the final design.

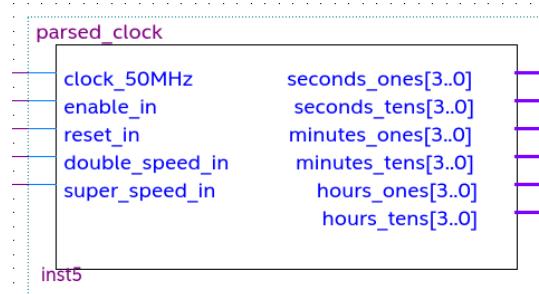


Figure 39: The block symbol of the parsed_clock functional unit used in the final design.



Figure 40: The simulation results for the parsed_clock module.

2.9.1 enable_flip_flop Component Block

The enable_flip_flop submodule acts to toggle whether the clock is enabled (should count). It does this by taking in an enable input from the design, and on the positive edge of this enable, toggling its enable_out output. It can be reset. The logic symbol follows in **Figure 42**. The simulation results follow in **Figure 43**.

- **Inputs:** An input enable_in that, on its rising edge, toggles the outputted enable value of the module; and a reset input that resets the flip_flop to logic low.
- **Outputs:** An output that represents whether the clock should count or not (the submodule's enable value). This goes to the delay and counter blocks.

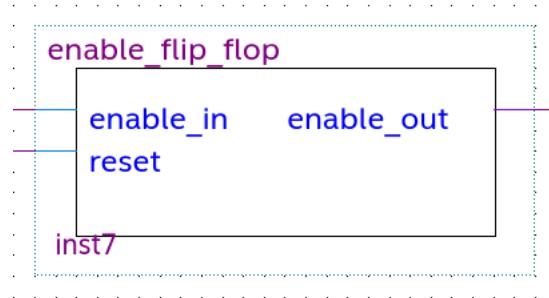


Figure 41: The block symbol of the enable_flip_flop module used in the parsed_clock functional unit.



Figure 42: The simulation results for the enable_flip_flop module used in the parsed_clock functional unit.

2.9.2 delay Component Block

The delay submodule, by default, slows an input clock down by a factor of 1/2 to the 10. This is so that an input clock of 50MHz (as in this design) is slowed to a frequency that is easier converted to 1Hz later on through division. This submodule also allows for 4 modes of speed (MEGA, Super, Double, and Normal speeds). MEGA is 2048, Super is 1024, and Double is 2 times as fast as the Normal speed. This is controlled by the values of two speed inputs that act as a select signal between these options. A block diagram follows in extbfFigure 44. The logic symbol follows in **Figure 45**. The simulation results follow in **Figure 46**.

- Inputs:** An input clock to be slowed (50Mhz in this design); an active-high enable that allows the submodule to propagate signal; a reset signal to reset all flip_flops to 1 (such that the first signal overflows and sends all held values to 0); and two inputs (double_speed and super_speed) that combine as a select signal to choose between four possible output clock speeds (MEGA 1,1 , Super 1,0 , Double 0,1 , and Normal 0,0 speeds for the select signal super_speed, double_speed).
- Outputs:** A clock that is 1/2 to the 10 slower than the input clock in normal mode, somewhat faster depending on the speed mode selected (described above).

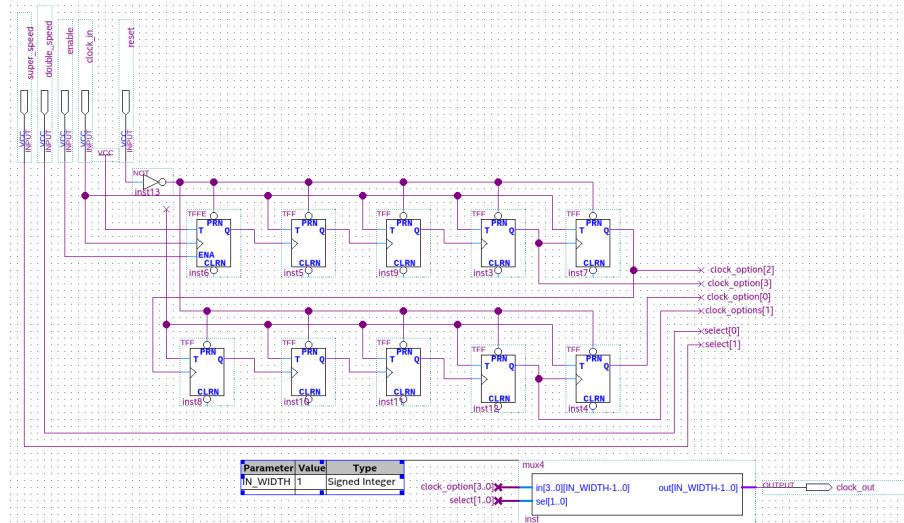


Figure 43: The logic design of the delay module used in the parsed_clock functional unit.

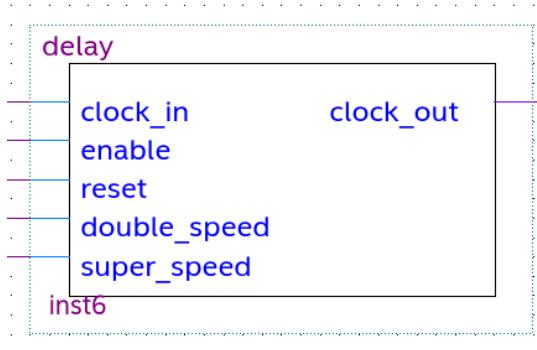


Figure 44: The block symbol of the delay module used in the parsed_clock functional unit.

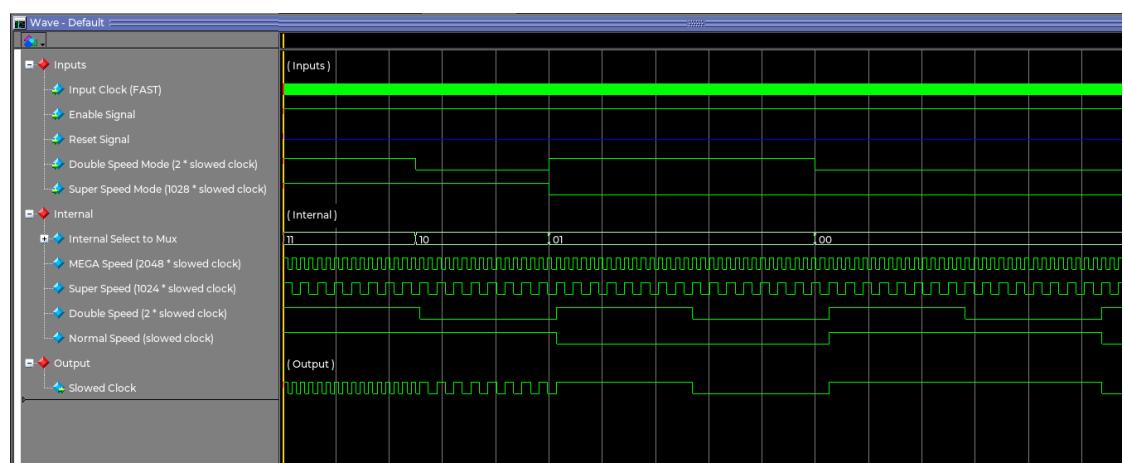


Figure 45: The simulation results for the delay module used in the parsed_clock functional unit.

2.9.3 mux4 Component Block

The mux4 submodule is a 4-option mux (where each option in this design is a one-wide clock speed option). This accounts for the select signals in the delay block. The logic symbol follows in **Figure 47**. The simulation results follow in **Figure 48**.

- **Inputs:** Four one-bit options to send to the output (the speed options of the delay block); and a 2-bit select signal that maps select values 11, 10, 01, and 00 to sending clock_options 3, 2, 1, and 0.
- **Outputs:** One 1-bit output from the 4 options presented in the inputs, selected by the select signal. This is also the output of the delay block.

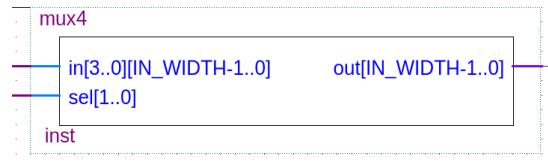


Figure 46: The block symbol of the mux4 module used in the parsed_clock functional unit.



Figure 47: The simulation results for the mux4 module used in the parsed_clock functional unit.

2.9.4 counter Component Block

The counter submodule is a simple one-by counter that increments its output q on every clock cycle. It has a default max width of q of 30-bits and can be reset and enabled via its inputs. The logic symbol follows in **Figure 49**. The simulation results follow in **Figure 50**.

- **Inputs:** A clock signal (clk) on which to increment the count held in the q output; a reset signal which sets the q output back to 0; and an enable signal that determines whether the counter should react to the clock.
- **Outputs:** The count output held in the output q, with a default maximum width of 30-bits.

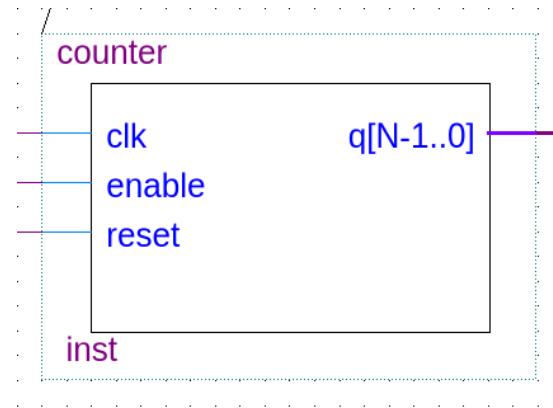


Figure 48: The block symbol of the counter module used in the parsed_clock functional unit.

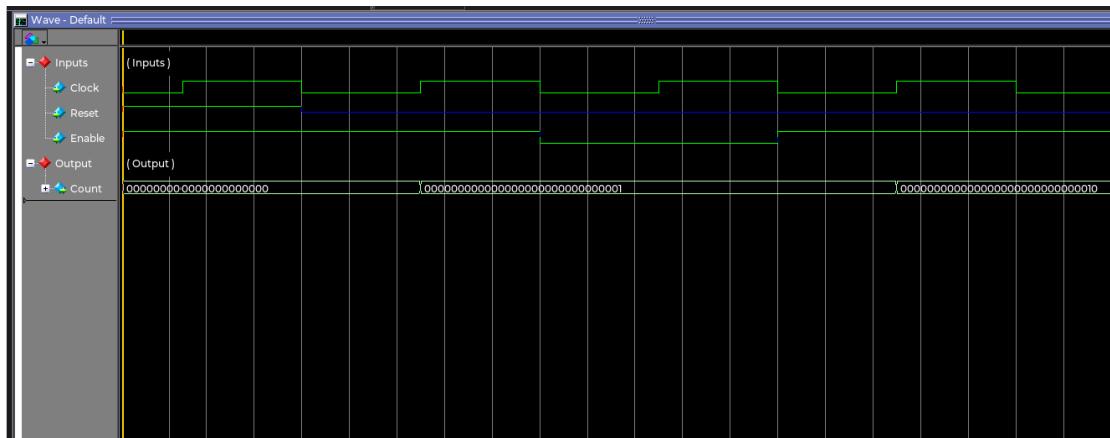


Figure 49: The simulation results for the counter module used in the parsed_clock functional unit.

2.9.5 parser Component Block

The parser submodule takes in a binary value up to 30-bits wide of slowed clock ticks, divides it by the number of clock ticks per second (9537 in this design, due to the delay block), and parses it into seconds, minutes, and hours (in decimal notation) to match the typical clock format of (HH.MM.SS). The logic symbol follows in **Figure 51**. The simulation results follow in **Figure 52**.

- Inputs:** The count of clock ticks of the parsed_clock module, outputted by the counter submodule.
- Outputs:** The total seconds counted so far (used for resetting at 24 hours), and six 4-bit binary value outputs describing the one's and ten's places of the seconds, minutes, and hours of the parsed clock.

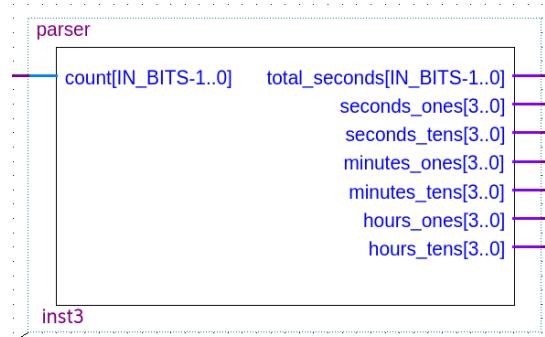


Figure 50: The block symbol of the parser module used in the parsed_clock functional unit.

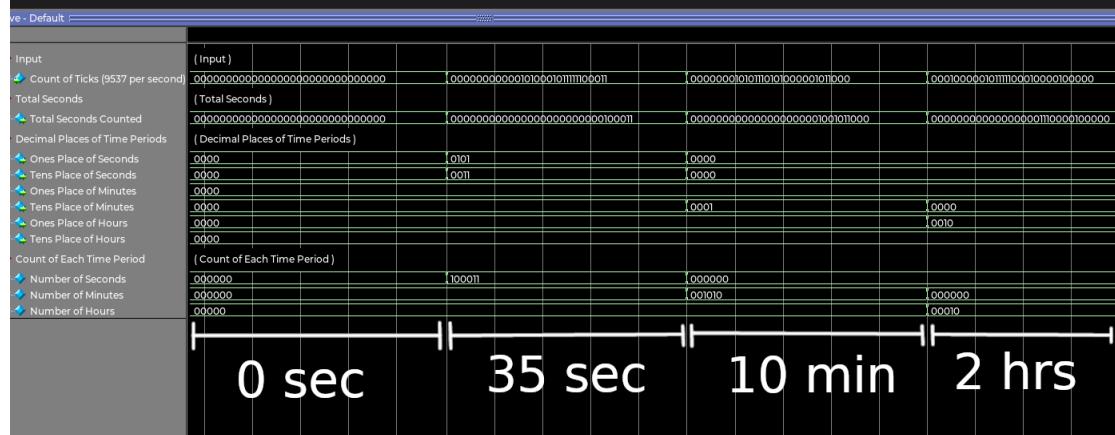


Figure 51: The simulation results for the parser module used in the parsed_clock functional unit.

2.9.6 comparator Component Block

The comparator submodule takes in the total seconds counted by the parsed clock since the last reset, and sends a signal to reset the system when it is greater than or equal to the number of seconds in 24 hours. This prevents the clock from outputting values over what is possible in the typical clock format (HH.MM.SS). The logic symbol follows in **Figure 53**. The simulation results follow in **Figure 54**.

- **Inputs:** The total seconds counted by the parsed clock since the last reset (default max width of 30-bits, called a).
- **Outputs:** Whether the total seconds input (a) is greater than or equal to the number of seconds in a day ($60 * 60 * 24 = 3600$).

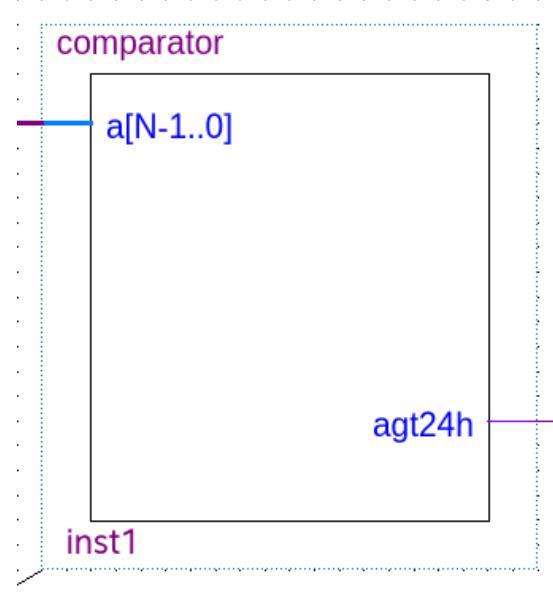


Figure 52: The block symbol of the comparator module used in the parsed_clock functional unit.

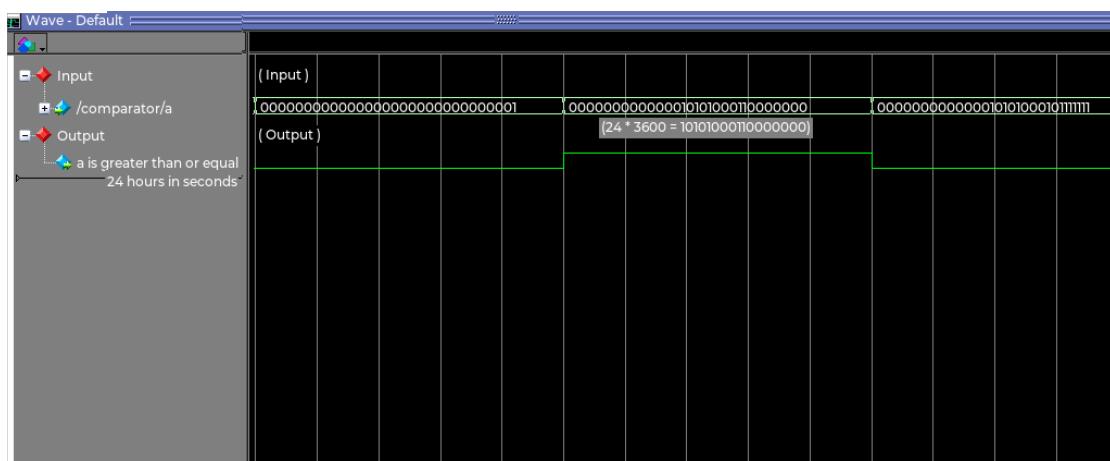


Figure 53: The simulation results for the comparator module used in the parsed_clock functional unit.

2.10 SquareWaveGenerator Functional Unit

Square Wave Generator generates square wave and it is used to generate tones in the piano in this project. When ps2_code[7..0] is read from the PS/2 Keyboard functional unit, a decoder decodes the data into three-digit binary data. The SquareWaveGenerator block receives the data and converts it into the square wave with specific Hz that indicates notes in the piano.

- **Inputs:** The square wave generator schematic has three inputs, clk_50MHz, ps2_code[7..0], en. The clk_50MHz is the clock with a frequency of 50MHz, ps2_code[7..0] is the 8-bit data sent from PS/2 keyboard, and en is the switch that allows the SquareWaveGenerator block to send a data to output signal sqWave.
- **Outputs:** The square wave generator schematic has one output, sqWave. It shows the square wave with a specific Hz to generate the tone in the piano.

2.10.1 SquareWaveGenerator Component Block

The square wave generator block converts eight types of 3-bit data from 0b000 to 0b111 into a square wave. In the SystemVerilog file, the internal counter `div_cnt` is compared to `max_count` which indicates the period taken to reach specific hz. If `div_cnt` reaches `max_count`, `tmp_clk` changes to make a square wave. The `en` signal determines whether the `tmp_clk` is sent to speaker or not. To make it clear, `max_count` for middle C is 95419 because the period for 262Hz is 3816973ns. Considering that the clock has the frequency of 50MHz, the signal is read in every 20ns and the square wave should be changed after it passes half of the period. Therefore, after calculating $3816973/20/2=95419$. The `max_count` for other notes is also derived from this calculation. The notes from the middle C to the C with next octave have the frequency of 262 Hz, 294 Hz, 330 Hz, 350 Hz, 392 Hz, 440 Hz, 494 Hz, and 523 Hz in sequence. This means that each note has the period of 381673 ns, 3401360 ns, 3030303 ns, 2857142 ns, 2551020 ns, 2272727 ns, 2024291 ns, and 1912045 ns respectively. When they are simulated in the period, the square wave changes only once at the half of the period as shown below. The logic symbol follows in **Figure 55**. The simulation results follow in **Figure 56**.

- Inputs:** The SquareWaveGenerator block has four inputs, `clk`, `note[2..0]`, `en`, and `reset`. The `clk` is the clock with a frequency of 50MHz, and `note[2..0]` is the decoded data from the decoder to determine the note to generate. The `en` and `reset` performs as a switch for the block.
- Outputs:** The SquareWaveGenerator block has one input, `speaker`. It shows the square wave generated from the block.

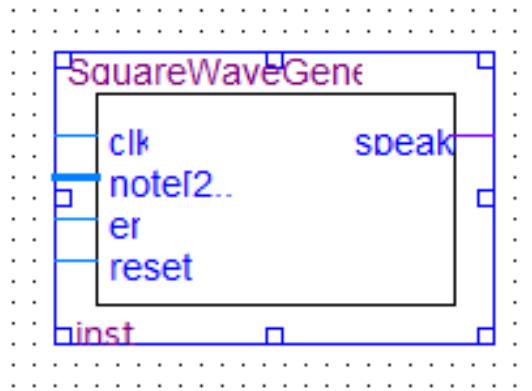


Figure 54: The block symbol of the SquareWaveGenerator module used in the SquareWaveGenerator functional unit.

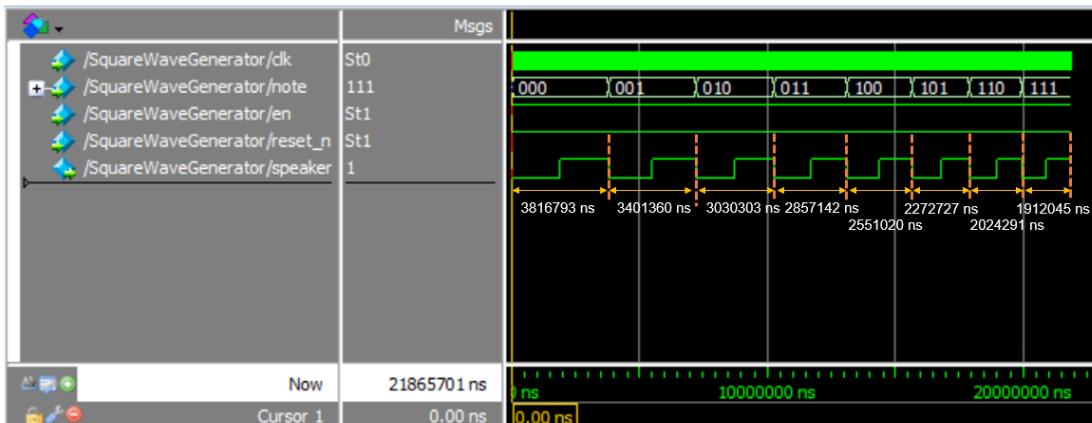


Figure 55: The simulation results for the SquareWaveGenerator module used in the SquareWaveGenerator functional unit.

2.10.2 decoder Component Block

The decoder block decodes the data from the PS/2 keyboard to the three-bit data. To match the keys in keyboard from a to t with the piano notes from middle C to the upper octave C, the hexadecimal code of the keyboard is converted to 3-bit data as shown in the simulation. The logic symbol follows in [Figure 57](#). The simulation results follow in [Figure 58](#).

- **Inputs:** The decoder block has one input, $a[7..0]$. It indicates the input 8-bit data, which is the make code for keys on the keyboard.
 - **Outputs:** The decoder block has one output, $y[2..0]$. It is converted from 8-bit to 3-bit data and is used to determine the note to generate.

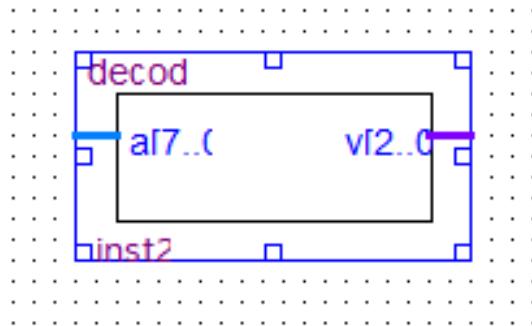


Figure 56: The block symbol of the decoder module used in the SquareWaveGenerator functional unit.



Figure 57: The simulation results for the decoder module used in the SquareWaveGenerator functional unit.

2.11 nes_to_motor Functional Unit

The nes_to_motor module converts nes button states coming from the nes_decoder module and converts them to the signals used internally in the L293D_encoder module to interface with the L293D DC motor controller. This is a module completely internal to the design that converts between the output and input signal conventions of other modules. The logic symbol follows in **Figure 59**. The simulation results follow in **Figure 60**.

- Inputs:** Four active-high inputs describing that a system of two motors (like a tank) should turn left (left), turn right (right), drive forward (forward), or drive backward (backward), respectively. In this design, these inputs come from the inverted left, right, up, and down button states of the nes controller.
- Outputs:** Whether motors 1 (left) and 2 (right) should be spinning (motor_1_on and motor_2_on); and which direction each motor should spin if also enabled, where logic high correlates to clockwise motion and low to counterclockwise (motor_1_dir and motor_2_dir for each motor, respectively).

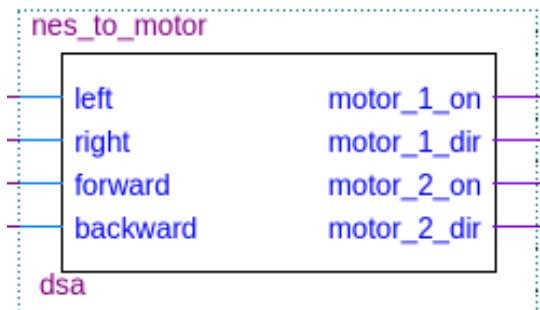


Figure 58: The block symbol of the nes_to_motor functional unit used in the final design.

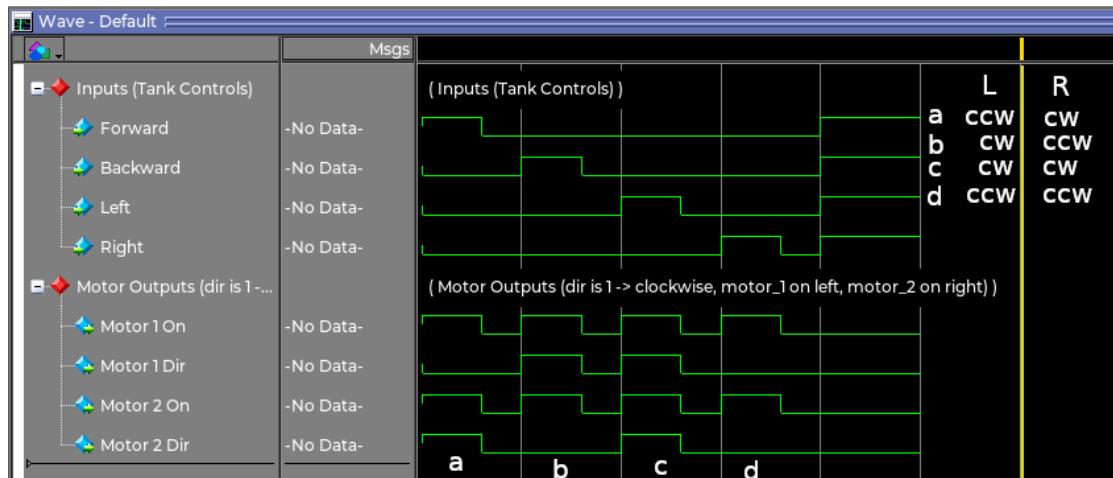


Figure 59: The simulation results for the nes_to_motor module.

2.12 Comparator Functional Unit

The Comparator Functional Unit is used to create a clock that operates at 10 KHz, to drive the vcr_decoder Functional Unit. The FPGA clock is 50 MHz so in order to create a 10 KHz clock, we only want a rising edge every 5000 cycles of the FPGA clock. The logic symbol follows in **Figure 61**. The simulation results follow in **Figure 62**.

- **Inputs:** The Comparator Functional Unit has a single input: a. a is a 23-bit value that is the output of the Counter Functional Unit
- **Outputs:** The Comparator Functional Unit has a single output: eq. eq is one if the input value, a, is equal to 5000.

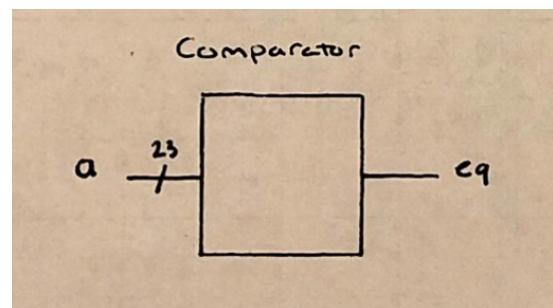


Figure 60: The block symbol of the Comparator functional unit used in the final design.



Figure 61: The simulation results for the Comparator module.

2.13 DisplayDecoder Functional Unit

The DisplayDecoder Module converts a 4-bit input value into a display value on the seven segment display of the FPGA. The DisplayDecoder is able to output a hexadecimal display value between 0 and F.

- **Inputs:** The DisplayDecoder module takes a 4-bit binary value input, data, as its only input.
- **Outputs:** The DisplayDecoder module outputs a 7-bit binary value that is used to activate specific segments in the FPGA seven segment display.

2.14 DisplaysDecoder Functional Unit

The DisplayDecoder Module converts a 4-bit input value into a display value on the seven segment display of the FPGA. The DisplayDecoder is able to output a hexadecimal display value between 0 and F. A block diagram of the unit follows in **Figure A** and the simulation results for the unit follows in **Figure B**.

- Inputs:** The DisplayDecoder module takes a 4-bit binary value input, data, as its only input.
- Outputs:** The DisplayDecoder module outputs a 7-bit binary value that is used to activate specific segments in the FPGA seven segment display.

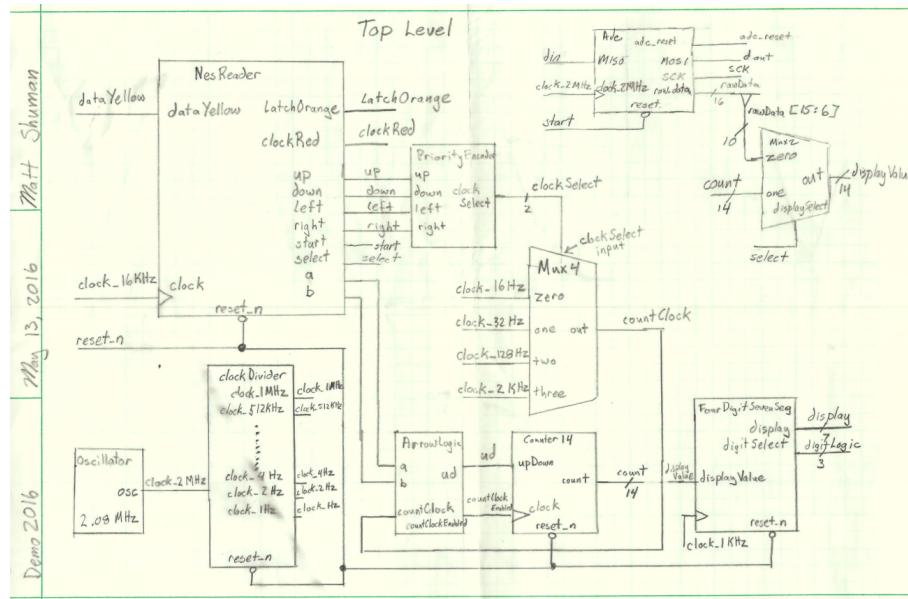


Figure 62: The logic design of the DisplayDecoder functional unit used in the final design.

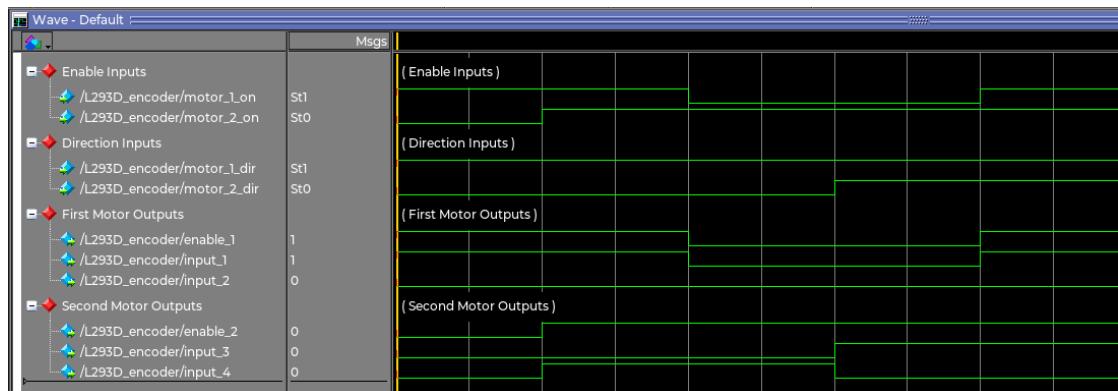


Figure 63: The simulation results for the DisplayDecoder Individual Unit.

2.15 vcr_decoder Functional Unit

The vcr_decoder module converts an IR signal sent from a VCR remote into a decimal value between 0 and 9. A block diagram of the unit follows in **Figure A**. A state diagram describing the unit as well as the simulation results for the unit follow in **Figure B**, and the details for each individual block comprising the unit follow after.

2.16 vcr_decoder Functional Unit

The vcr_decoder module converts an IR signal sent from a VCR remote into a decimal value between 0 and 9. A block diagram of the unit follows in **Figure A**, the simulation results for the unit follows in **Figure B**, and the details for each individual block comprising the unit follow after.

- Inputs:** The vcr_decoder module two inputs, clk and IR. clk is a 10 KHz clock signal that is used to drive the module. IR is the Infrared signal coming from the VCR remote that will be translated by the module.
- Outputs:** The vcr_decoder module has a single output, displayValue, which is the 0-9 representing the IR signal that was received by the module as input.

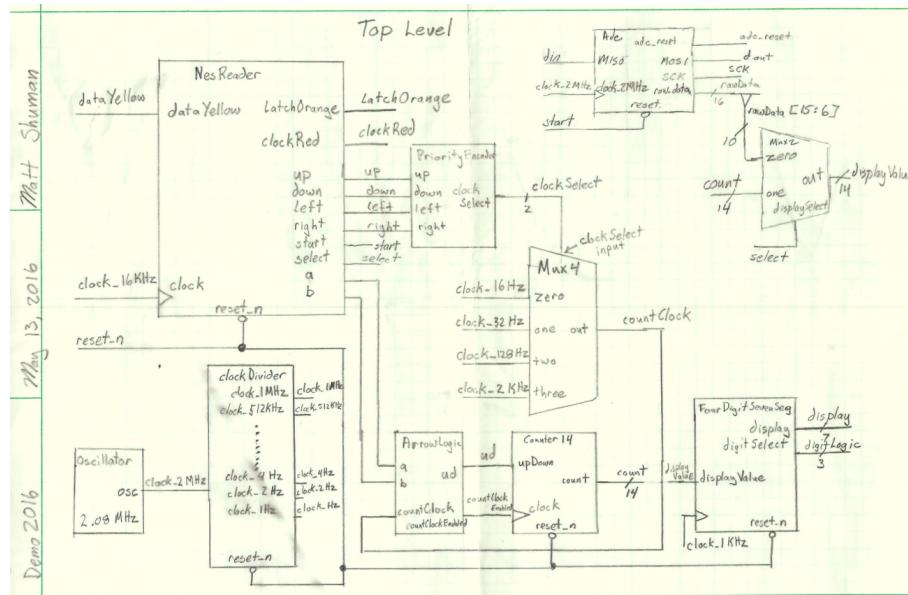


Figure 64: The logic design of the vcr_decoder functional unit used in the final design.

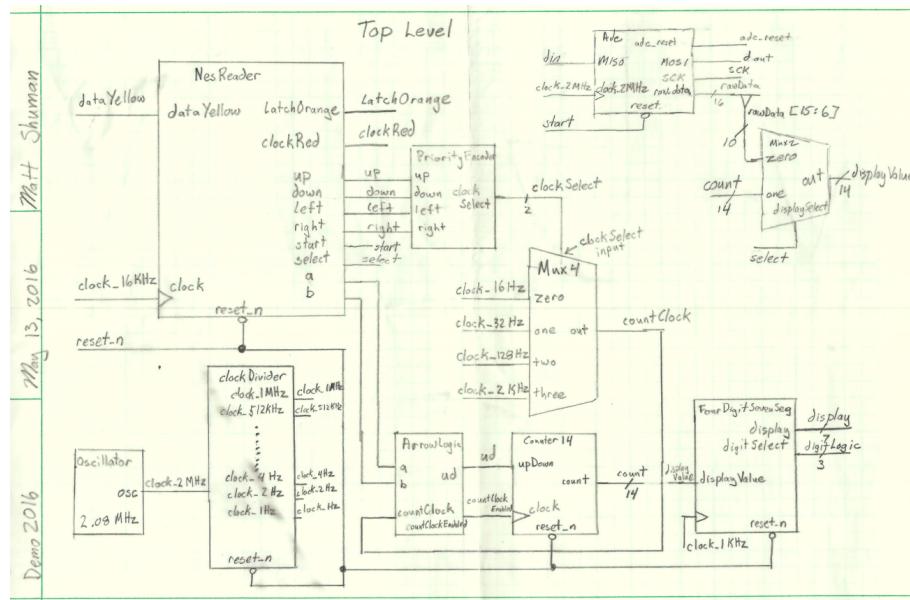


Figure 65: The State Diagram for the vcr_decoder functional unit used in the final design.

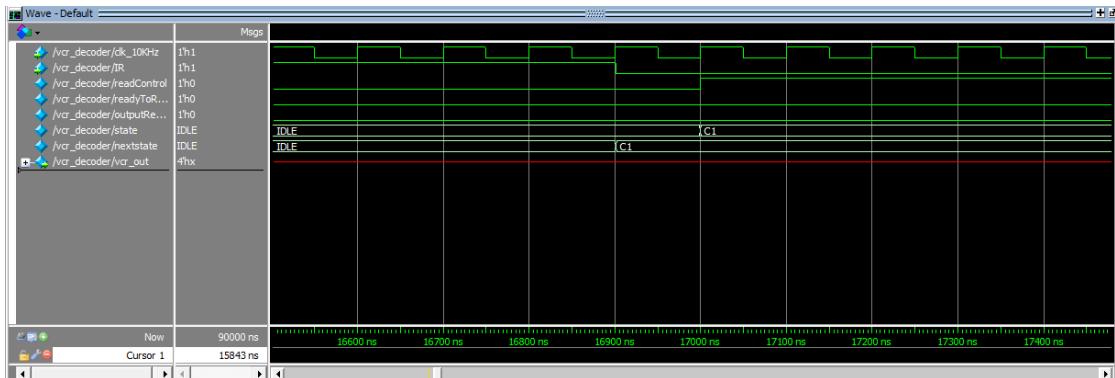


Figure 66: Simulation results of the vcr_decoder Functional Unit showing the state transition from the IDLE state to the C1 control state following the first time the IR signal goes to a logic LOW.

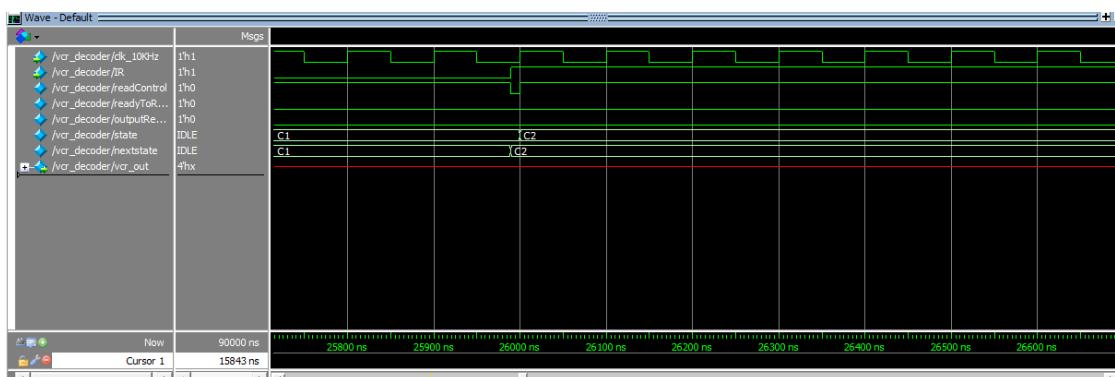


Figure 67: Simulation results of the vcr_decoder Functional Unit showing the state transition from the C1 control state to the C2 control state.

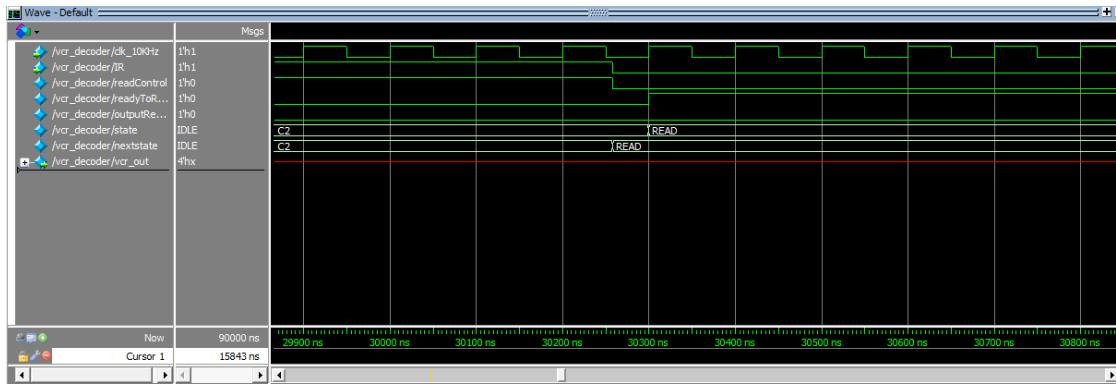


Figure 68: Simulation results of the vcr_decoder Functional Unit showing the transition from the C2 control state to the READ state, indicating that it is currently reading a 32-bit IR signal corresponding the button on the VCR remote that was pressed.

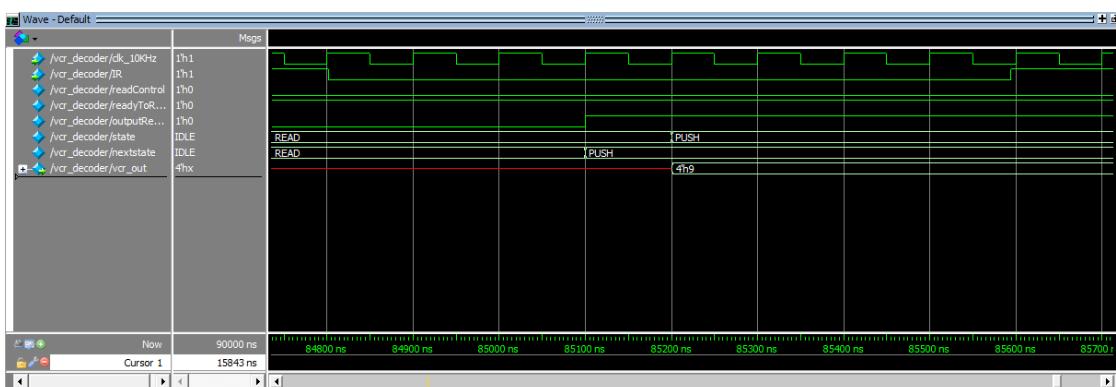


Figure 69: Simulation results of the vcr_decoder Functional Unit showing the transition from the READ state to the PUSH state indicating that the full 32-bit input value has been processed and an output value is produced.

2.16.1 ReadState Individual Block

The ReadState Individual Block is used to implement the READ state within the vcr_decoder Module. The block diagram (**Figure C**), State Diagram, and simulation results **Figure D** are provided below.

- **Inputs:** inputs
- **Outputs:** outputs

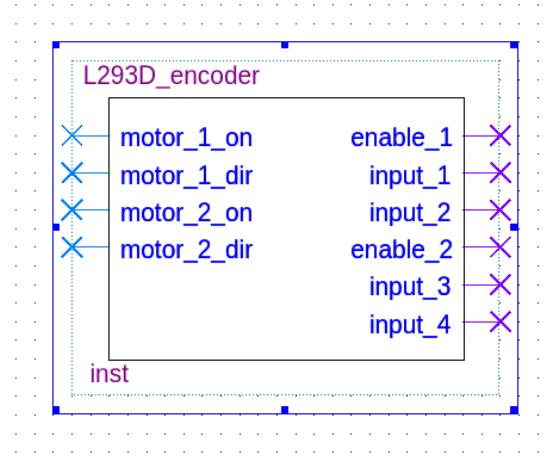


Figure 70: The block symbol of the ReadState individual block used in the vcr_decoder functional unit.

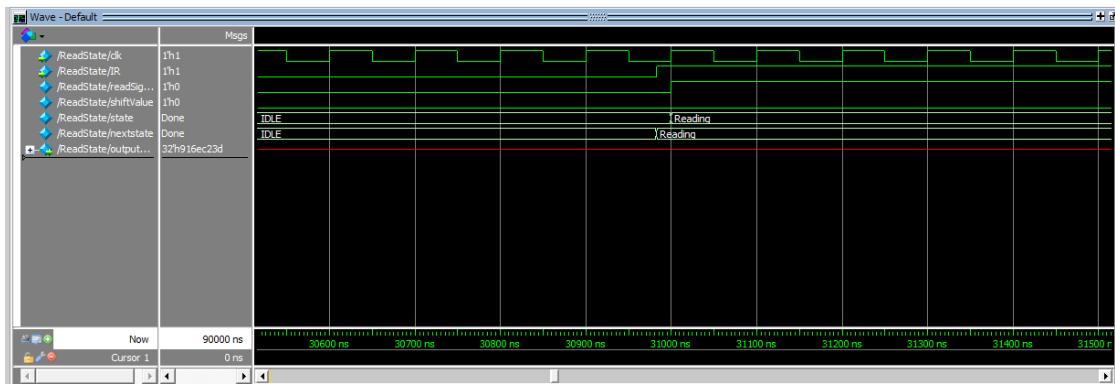


Figure 71: Simulation results of the ReadState individual block used in the vcr_decoder functional unit. The simulation shows the transition from the IDLE state to the Reading State within the ReadState Module. This transition is in response to the initial HIGH IR signal that represents the 32-bit value encoding the button that was pressed.

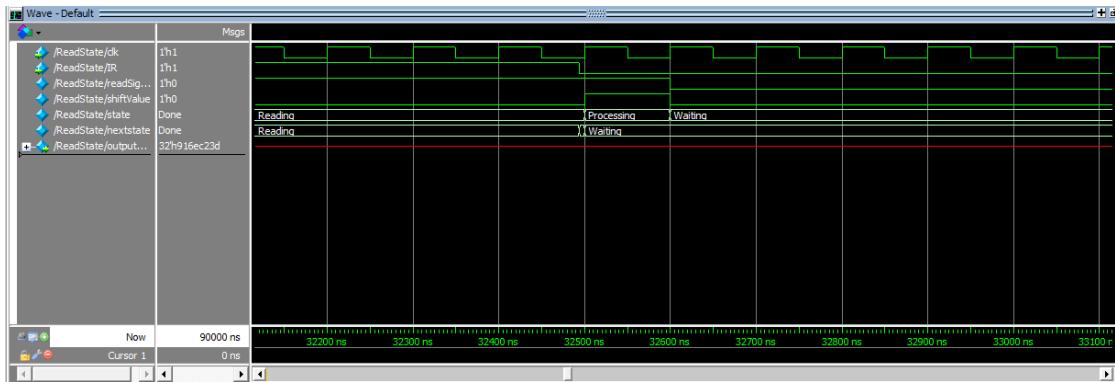


Figure 72: Simulation results of the ReadState individual block used in the vcr_decoder functional unit. The simulation shows Processing State of the ReadState Module. When the state machine is in the Reading state, that means it is actively reading a HIGH signal for IR. As seen in this waveform, when IR goes LOW again, the state machine switches to the Processing state in which it checks the length of the signal to see if it is a logic 1 or a logic 0. The 1 or 0 is then shifted into the shift register on the rising edge of the shiftValue signal, as seen in the waveform. The state machine then switches into the Waiting state, while it waits for IR to go HIGH again.

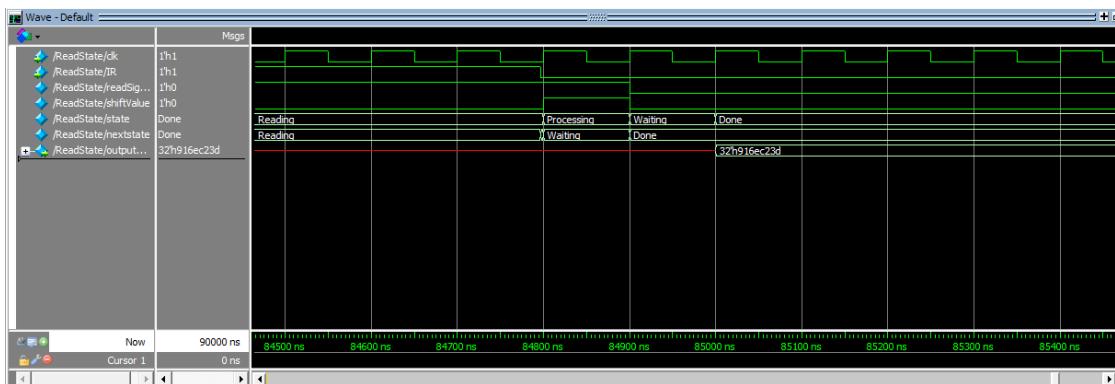


Figure 73: Simulation results of the ReadState individual block used in the vcr_decoder functional unit. The simulation shows the transition from the reading, Processing, Waiting cycle to the Done state in which it outputs the 32-bit hexadecimal value identified by the IR signal input. In each Waiting state, the state machine will check if 32-bits have been read into the shift register. If so, the state machine will switch to the Done state and output the value for the IR signal that it received as input. In addition, it will drive an output signal outputReady HIGH. This signal is used by the vcr_decoder module, to know when to output a result.

2.16.2 SignalDecoder Individual Block

The SignalDecoder Individual Block is used to convert the 32-bit value generated by the ReadState Individual Block into a 4-bit value between 0 and 15 that indicated which button on the VCR remote was pressed. The input and output specifications follow, as well as the block diagram (**Figure C**), and simulation results **Figure D** for the individual block.

- Inputs:** The SignalDecoder Individual Block takes a single 32-bit input that corresponds to the complete IR signal that was read in by the ReadState Individual Block
- Outputs:** The SignalDecoder Individual Block outputs a 4-bit value between 0 and 15.

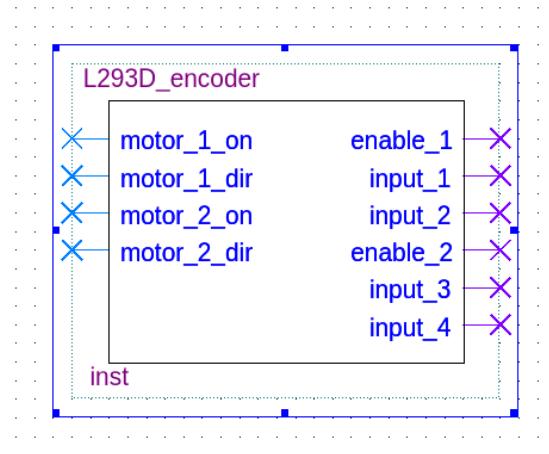


Figure 74: The block symbol of the (NAME) individual block used in the (NAME) functional unit.



Figure 75: The simulation results of the SignalDecoder individual block used in the vcr_decoder functional unit.

2.16.3 ShiftRegister Individual Block

The ShiftRegister Individual Block is used to store the 32-bit IR signal value bit by bit as it is read in by the ReadState Module. The input and output specifications follow, as well as the block diagram (**Figure C**), and simulation results **Figure D** for the individual block.

- **Inputs:** Inputs
- **Outputs:** Output

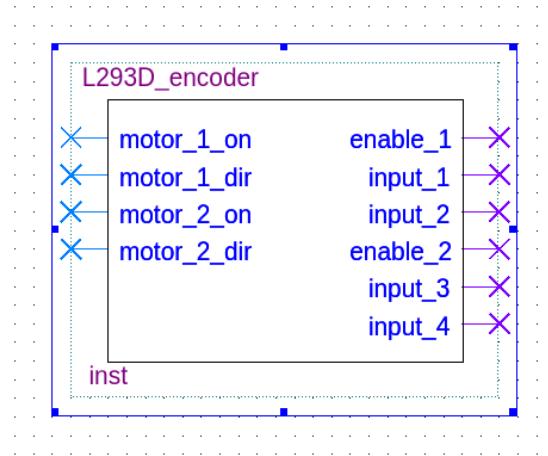


Figure 76: The block symbol of the ShiftRegister individual block used in the vcr_decoder functional unit.

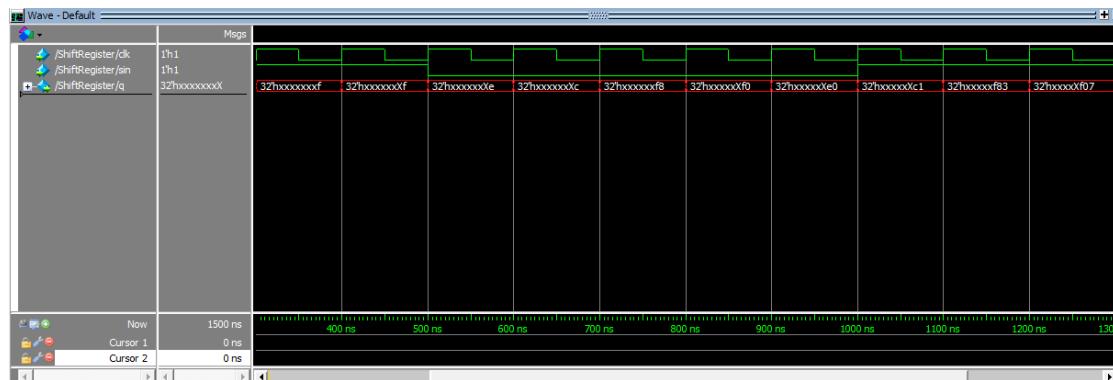


Figure 77: The simulation results of the ShiftRegister individual block used in the vcr_decoder functional unit.

A SystemVerilog Files

This appendix will list the SystemVerilog code used for each block used in the design project.

A.1 decoder

decoder.sv

```
1 module decoder(input logic[7:0]a,
2                  output logic [2:0] y);
3
4     always_comb
5         case(a)
6             8'h1C: y = 3'b000;
7             8'h1B: y = 3'b001;
8             8'h23: y = 3'b010;
9             8'h2B: y = 3'b011;
10            8'h1D: y = 3'b100;
11            8'h24: y = 3'b101;
12            8'h2D: y = 3'b110;
13            8'h2C: y = 3'b111;
14            default: y = 3'bxxx;
15
16        endcase
17
18    endmodule
```

A.2 seven_seg_6

A.2.1 Component Blocks of seven_seg_6 Unit

sevenseg.sv

```
1 module sevenseg(input   logic [3:0] data,
2                   output  logic [6:0] segments);
3
4     always_comb
5         case(data)
6             //          gfe_dcba
7             0:      segments = 7'b100_0000;
8             1:      segments = 7'b111_1001;
9             2:      segments = 7'b010_0100;
10            3:      segments = 7'b011_0000;
11            4:      segments = 7'b001_1001;
12            5:      segments = 7'b001_0010;
13            6:      segments = 7'b000_0010;
14            7:      segments = 7'b111_1000;
15            8:      segments = 7'b000_0000;
16            9:      segments = 7'b001_1000;
17            default: segments = 7'b111_1111;
18        endcase
19
20    endmodule
```

A.3 L293D_encoder

L293D_encoder.sv

```
1  /* Takes input as 4-bit register describing whether
2   each motor is on and its direction */
3
4
5  module L293D_encoder (
6      input logic      motor_1_on,      // whether the first motor should spin
7                  motor_1_dir,     // the direction of spin (0 is back, 1 is forward)
8
9      motor_2_on,      // whether the second motor should spin
10     motor_2_dir,     // the direction of spin (0 is back, 1 is forward)
11
12    output logic     enable_1,       // pin 1 - enable for inputs 1 and 2
13        input_1,        // pin 2 - input 1 (forward for motor 1)
14        input_2,        // pin 7 - input 2 (backward for motor 1)
15
16        enable_2,       // pin 9 - enable for inputs 3 and 4
17        input_3,        // pin 10 - input 3 (forward for motor 2)
18        input_4,        // pin 15 - input 4 (backward for motor 2)
19  );
20
21  always_comb begin
22      enable_1    <= motor_1_on;
23      input_1     <= (motor_1_on && (motor_1_dir));
24      input_2     <= (motor_1_on && ~(motor_1_dir));
25
26      enable_2    <= motor_2_on;
27      input_3     <= (motor_2_on && (motor_2_dir));
28      input_4     <= (motor_2_on && ~(motor_2_dir));
29  end
30
31 endmodule
```

A.4 Counter

Counter.sv

```
1  module Counter #(parameter n = 23)
2      (input logic clk,
3       input logic reset,
4       output logic [n-1:0] q);
5
6  always_ff @(posedge clk, posedge reset)
7      if (reset) q <= 0;
8      else q <= q+1;
9 endmodule
```

A.5 vga_encoder

A.5.1 Component Blocks of vga_encoder Unit

vga_640x480.sv

```
1
2  module vga_640x480  (input  logic clock_25, reset_frame,
3                      output logic h_sync, v_sync, h_display, v_display);
4
5  // Parameters
6  localparam line   = 800;    // complete line
7  localparam screen = 525;    // complete screen
8
```

```

9      localparam h_front_porch    = 16;
10     localparam h_sync_dur       = 96;
11     localparam h_back_porch    = 48;
12     localparam h_active_dur    = 640;
13
14     localparam v_front_porch    = 10;
15     localparam v_sync_dur       = 2;
16     localparam v_back_porch    = 33;
17     localparam v_active_dur    = 480;
18
19     localparam h_sync_start     = h_front_porch; // time h sync starts (after)
20     localparam h_sync_end       = h_front_porch + h_sync_dur; // time h sync ends (after)
21     localparam h_active_start   = h_front_porch + h_sync_dur + h_back_porch;
22
23     localparam v_sync_start     = v_front_porch; // time h sync starts (after)
24     localparam v_sync_end       = v_front_porch + v_sync_dur; // time h sync ends (after)
25     localparam v_active_start   = v_front_porch + v_sync_dur + v_back_porch;
26
27     reg [9:0] h_count; // current column
28     reg [9:0] v_count; // current row
29
30
31 // Sync Signals
32 assign h_sync = ~((h_count >= h_sync_start) && (h_count < h_sync_end));
33 assign v_sync = ~((v_count >= v_sync_start) && (v_count < v_sync_end));
34
35
36 // Display Signal - when pixels can display
37 assign h_display = h_count >= h_active_start;
38 assign v_display = v_count >= v_active_start;
39
40
41 // Flip flop for incrementing
42 always_ff @(posedge clock_25)
43 begin
44
45     if (clock_25)
46         begin
47             v_count <= (v_count >= screen) ? 0 : ((h_count >= line) ? v_count + 1: v_count);
48             h_count <= (clock_25 && (h_count >= line | v_count >= screen)) ? 0 :
49             h_count + 1;
50         end
51
52 //         if (clock_25 || reset_frame)
53 //             begin
54 //                 if (h_count >= line) // end of line
55 //                     begin
56 //                         h_count = 0;
57 //                         v_count = v_count + 1;
58 //                     end
59 //                 else
60 //                     begin
61 //                         h_count = h_count + 1;
62 //                         v_count = v_count;
63 //                     end
64 //
65 //                 if (v_count >= screen || reset_frame) // end of screen or reset
66 //                     begin
67 //                         h_count = 0;
68 //                         v_count = 0;
69 //                     end
70 //             end

```

```

71
72         end
73
74     endmodule
    
```

rgb_decoder.sv

```

1  module rgb_decoder (input  logic [1:0] red_in ,
2                      input  logic [1:0] green_in ,
3                      input  logic [1:0] blue_in ,
4
5                          output logic [3:0] red_out ,
6                          output logic [3:0] green_out ,
7                          output logic [3:0] blue_out );
8
9      always_comb
10     begin
11         red_out = red_in * 85;
12         green_out = green_in * 85;
13         blue_out = blue_in * 85;
14     end
15
16 endmodule
    
```

clock_modulator.sv

```

1  module clock_modulator (input  logic clock_in ,
2                           output logic clock_out );
3
4     logic count = 0;
5
6     always_ff @(posedge clock_in)
7     begin
8         if (clock_in)      count <= count+1;
9     end
10
11    always_comb
12    begin
13        if (count == 1)   clock_out = 1;
14        else              clock_out = 0;
15    end
16
17 endmodule
    
```

A.6 vcr_decoder

```
vcr_decoder.sv

1 //VCR Decoder Module
2 module vcr_decoder(input logic clk_10KHz, //input clock with 10KHz frequency
3                      input logic IR, //input IR signal from VCR remote
4                      output logic outputting,
5                      output logic[3:0] vcr_out); //output value for vcr signal
6
7 //declare states
8 typedef enum logic [2:0] {IDLE, C1, C2, READ, PUSH} statetype;
9 statetype state, nextstate;
10
11 //Internal
12 logic stateReset = 0; //value to reset state machine to IDLE
13 logic readControl = 0; //TRUE when reading a control signal
14 logic [8:0]controlCounter = 0; //counter for length of control signal
15 logic controlLength = 0; //length of control signal
16 logic readyToRead = 0; //set to 1 to activate the ReadState state machine
17 logic outputReady = 0; //set to 1 when ReadState is ready to output 32 bit value
18 logic [31:0] tempOutput = 0; //gets output from ReadState state machine module
19 logic [3:0] temp_vcr_out = 0; //gets output from SignalDecoder module
20
21 logic init = 1; //used to initialize state to IDLE
22
23
24 //READ State Machine
25 /*This module reads each pulse of the IR signal and outputs a 32-bit value when
26 32 bits have been read into the shift register*/
27 ReadState reader(
28                 .clk(clk_10KHz),
29                 .IR(IR),
30                 .start(readyToRead),
31                 .pushOutput(outputReady),
32                 .outputValue(tempOutput)
33 );
34
35 //Signal Decoder
36 //takes 32-bit value and converts it to a 4 bit value between 0 and 15
37 SignalDecoder decoder(
38                     .signal(tempOutput),
39                     .value(temp_vcr_out)
40 );
41
42
43 //State register
44 always_ff@(posedge clk_10KHz, posedge stateReset)
45 begin
46
47     //if reading a control signal, increment counter with the clock to count length of
48     if(readControl)
49         controlCounter <= controlCounter + 1;
50     else
51         controlCounter <= 0;
52
53     //Then either reset the state to IDLE or move to the next state
54     if(stateReset || init)
55         state <= IDLE; //set state to IDLE
56     else
57         state <= nextstate;
58
59 end
60
```

```

61
62    //next state logic
63    always_comb
64        begin
65            case(state)
66                IDLE:
67                    begin
68                        init = 0;
69                        outputReady = 0;
70                        readyToRead = 0;
71                        if(!IR) //IR signal goes low for first control signal
72                            nextstate = C1;
73                        else //otherwise just stay in IDLE
74                            nextstate = IDLE;
75
76                        readControl = 0; //Not reading control signal
77                    end
78                C1:
79                    begin
80                        readControl = 1; //start reading the control signal
81                        readyToRead = 0;
82                        if(IR) begin //IR goes high signalling end of first control signal and start of second
83                            if(controlCounter > 80 && controlCounter < 110) begin //good control signal
84                                nextstate = C2; //move to next control state
85                                readControl = 0; //No longer reading control signal
86                            end
87                            else begin
88                                nextstate = IDLE; //if bad control signal, move back to IDLE
89                                readControl = 0; //No longer reading control signal
90                            end
91                        end
92                        else //otherwise just stay in C1
93                            nextstate = C1;
94                    end
95                C2:
96                    begin
97                        readControl = 1; //start reading control signal
98                        readyToRead = 0;
99                        if(!IR) begin //IR signal goes low signalling end of second control signal
100                            if(controlCounter > 35 && controlCounter < 50) begin
101                                nextstate = READ;
102                                readControl = 0;
103                            end
104                            else begin
105                                nextstate = IDLE;
106                                readControl = 0;
107                            end
108                        end
109                        else
110                            nextstate = C2;
111                    end
112                READ:
113                    begin
114                        readyToRead = 1; //activate ReadState state machine module
115                        if(outputReady) //when ready to output move to PUSH state
116                            nextstate = PUSH;
117                        else
118                            nextstate <= READ; //Otherwise just stay in READ
119                    end
120                PUSH:
121                    begin
122                        outputting = 1;
123                        vcr_out = temp_vcr_out; //Set output of vcr_decoder module

```

```

124         end
125     default:
126     begin
127         nextstate = IDLE; //default state is IDLE
128     end
129     endcase
130   end
131
132 endmodule

```

A.6.1 Component Blocks of vcr_decoder Unit

ReadState.sv

```

1 ///////////////////////////////////////////////////////////////////
2 //READ State Machine//
3 ///////////////////////////////////////////////////////////////////
4 module ReadState(input logic clk,
5                   input logic IR, //VCR signal
6                   input logic start, //input signal to activate the ReadState state machine
7                   output logic pushOutput, //output signal that a full 32 bit value is ready
8                   output logic [31:0] outputValue); //32 bit output value
9
10 //declare states
11 typedef enum logic [2:0] {Reading, Processing, Waiting, IDLE, Done} statetype;
12 statetype state, nextstate;
13
14 //Internal
15 logic readReset = 0; //resets state machine to waiting
16 logic readSignal = 0; //TRUE when reading a logic HIGH
17 logic [8:0]signalCounter = 0; //Measures length of HIGH signal
18 logic value = 0; //value 1 or 0 based on HIGH signal length
19 logic shiftValue = 0; //when TRUE a new bit will be shifted into the shift register
20 logic [8:0]bitCounter = 0; //counts the number of bits being read
21 logic [31:0] tempSignalValue; //will temporarily store the output value
22 logic [31:0] signalValue; //stores shift register values
23 logic init = 1; //used to set the initial state to IDLE
24
25 //Shift Register
26 ShiftRegister shiftReg(
27                         .clk(shiftValue), //shift register clock is shiftValue
28                         .reset(readReset), //reset shift register
29                         .sin(value), //shifts current signal value in
30                         .q(signalValue) //output is 32 bits value for entire signal
31 );
32
33 //State Register
34 always_ff@(posedge clk, posedge readReset, posedge shiftValue)
35 begin
36
37     if(start) begin
38
39         //if reading signal, increment clock
40         if(readSignal)
41             signalCounter <= signalCounter + 1;
42         else
43             signalCounter <= 0;
44
45         //If bit is being added shift register, increment the bit counter
46         if(shiftValue)
47             bitCounter <= bitCounter + 1;
48
49         //Then either reset, or move to the next state

```

```

51         if(readReset || init)
52             state <= IDLE;
53         else
54             state <= nextstate;
55     end
56
57     end
58
59 //Next State Logic
60 always_comb
61 begin
62     case(state)
63         IDLE: //Initial state where no IR is being read
64         begin
65             init = 0;
66             pushOutput = 0;
67             readSignal = 0;
68             readReset = 0;
69             shiftValue = 0;
70
71             if(IR) //when IR goes high, switch to reading state
72                 nextstate <= Reading;
73             else
74                 nextstate <= IDLE;
75         end
76         Waiting: //Low signal between processing and Reading
77         begin
78             shiftValue = 0;
79             readReset = 0; //while waiting, not resetting read signal
80             readSignal = 0; //while waiting, not reading signal
81
82             if(bitCounter == 64)
83                 nextstate <= Done;
84             else if(IR)
85                 nextstate <= Reading;
86             else
87                 nextstate <= Waiting;
88         end
89         Reading:
90         begin
91             readSignal = 1; //counting signal length
92
93             if(!IR) //when IR signal goes low again, move to processing state
94                 nextstate <= Processing;
95             else if(IR)
96                 nextstate <= Reading;
97             else
98                 nextstate <= IDLE;
99         end
100        Processing:
101        begin
102            if(signalCounter <= 18 && signalCounter > 12) begin //logic 1
103                value = 1; //store value
104                shiftValue = 1; //shift into register
105                nextstate <= Waiting;
106            end
107            else if(signalCounter <= 9 && signalCounter >= 1) begin //logic 0
108                value = 0; //store value
109                shiftValue = 1; //shift into register
110                nextstate <= Waiting;
111            end
112            else begin
113                readReset = 1;

```

```

114                     nextstate <= IDLE;
115                 end
116             end
117         Done:
118             begin
119                 tempSignalValue = signalValue;
120                 outputValue = tempSignalValue;
121                 pushOutput = 1;
122             end
123         endcase
124     end
125
126 endmodule

```

ShiftRegister.sv

```

1 ///////////////////////////////////////////////////////////////////
2 //Shift Register Module//
3 ///////////////////////////////////////////////////////////////////
4 module ShiftRegister #(parameter N=32)
5     (input logic clk,
6      input logic reset, load,
7      input logic sin,
8      input logic [N-1:0]d,
9      output logic [N-1:0]q,
10     output logic sout);
11
12    always_ff@(posedge clk, posedge reset)
13        if(reset) q <= 0;
14        else if(load) q <= d;
15        else q <= {q[N-2:0], sin};
16
17    assign sout = q[N-1];
18
19 endmodule

```

mux2.sv

```

1 // mux2 module
2
3 module mux2 #(parameter IN_WIDTH = 7)                                // Width of each input option
4
5     (input logic [1:0] [IN_WIDTH-1:0] in,                           // 2, (IN_WIDTH-1)-bit inputs (sel)
6      input logic sel,                                         // input sel that selects between
7
8      output logic [IN_WIDTH-1:0] out);                         // (IN_WIDTH-1)-bit output based on sel
9
10
11 // Whenever an input or select changes, reassign output
12 always @ (in or sel) begin
13
14     out <= in[sel];
15
16 end
17

```

endmodule

SignalDecoder.sv

```

1 ///////////////////////////////////////////////////////////////////
2 // Signal Decoder ///////////////////////////////////////////////////////////////////
3 ///////////////////////////////////////////////////////////////////
4 module SignalDecoder(input logic [31:0]signal,
5                      output logic [3:0] value);
6
7     always_comb
8         case(signal)
9             32'h916E926D : value = 0;

```

```
9      32'h916E02FD : value = 1;
10     32'h916E827D : value = 2;
11     32'h916E62BD : value = 3;
12     32'h916EC23D : value = 4;
13     32'h916E22DD : value = 5;
14     32'h916EA25D : value = 6;
15     32'h916E629D : value = 7;
16     32'h916EE21D : value = 8;
17     32'h916E12ED : value = 9;
18     default : value = 15;
19   endcase
20 endmodule
```

A.7 ps2_keyboard

ps2_keyboard.sv

```
1 module ps2_keyboard #(parameter clk_freq = 50_000_000,
2                           debounce_counter_size = 8)
3                           (input logic clk,           //system clock
4                           input logic ps2_clk,      //clock signal from PS/2 keyboard
5                           input logic ps2_data,     //data signal from PS/2 keyboard
6                           output logic ps2_code_new, //flag that new PS/2 code is available
7                           output logic [7:0] ps2_code); // code received from PS/2
8
9   logic [1:0] sync_ffs;    //synchronizer flip-flops for PS/2 signals
10  logic ps2_clk_int;       //debounced clock signal from PS/2 keyboard
11  logic ps2_data_int;     //debounced data signal from PS/2 keyboard
12  logic [10:0] ps2_word;  //stores the ps2 data word
13  logic error;           //validate parity, start, and stop bits
14  logic [2778:0] count_idle; //counter to determine PS/2 is idle
15
16  always_ff @(posedge clk)
17    begin
18      sync_ffs[0] <= ps2_clk;
19      sync_ffs[1] <= ps2_data;
20    end
21
22  //input clock
23  //input signal to be debounced
24  //debounced signal
25  always_ff @(posedge clk)
26    begin
27      ps2_clk_int <= sync_ffs[0];
28      ps2_data_int <= sync_ffs[1];
29    end
30
31
32  //input PS2 data
33  always_ff @(negedge ps2_clk_int)
34    begin
35      ps2_word <= {ps2_data_int, ps2_word[10:1]};
36    end
37
38  //verify that parity, start, and stop bits are all correct
39  assign error = ~ (~ps2_word[0] && ps2_word[10] && (ps2_word[9] ^ ps2_word[8] ^
40      ps2_word[7] ^ ps2_word[6] ^ ps2_word[5] ^ ps2_word[4] ^ ps2_word[3] ^
41      ps2_word[2] ^ ps2_word[1]));
42
43  //determine if PS2 port is idle (i.e. last transaction is finished) and output result
44  always_ff @ (posedge clk)
45    begin
46      if(ps2_clk_int == 0) //low PS2 clock, PS/2 is active
47          count_idle <= 2779'b0; //reset idle counter
48      else //PS2 clock has been high less than a half clock period (<55us)
49          count_idle <= count_idle + 2779'b1; //continue counting
50
51      if(count_idle == 2750 && error == 0) //idle threshold reached and no errors detected
52        begin
53            ps2_code_new <= 1'b1; //set flag that new PS/2 code is available
54            ps2_code <= ps2_word[8:1]; //output new PS/2 code
55        end
56      else //PS/2 port active or error detected
57          ps2_code_new <= 1'b0; //set flag that PS/2 transaction is in progress
58    end
59
60 endmodule
```

A.7.1 Component Blocks of ps2_keyboard Unit

debounce.sv

```
1 module debounce #(counter_size = 19)
2             (input logic clk,           //input clock
3              input logic button,    //input signal to be debounced
4              output logic result); //debounced signal
5
6 logic [1:0] flipflops;   //input flip flops
7 logic counter_set;
8 logic [0:counter_size] counter_out = 0; //counter output
9
10 always_ff @(posedge clk)
11 begin
12     flipflops[0] <= button;
13     flipflops[1] <= flipflops[0];
14     counter_set <= (flipflops[0] ^ flipflops[1]); //sync reset to zero
15     if (counter_set == 1) counter_out <= 0;
16     else if (counter_out[counter_size] == 1) counter_out <= counter_out + 1'b1;
17     else result <= flipflops[1];
18 end
19 endmodule
```

A.8 nes_decoder

nes_decoder.sv

```
1
2 module nes_decoder (input logic nes_data, // the current button data coming from controller
3                         in_clock, // will synchronize output to the positive edge
4                         read_data, // will read the data on the positive edge
5                         reset, // does nothing so far
6
7                         output logic nes_latch, // sent to controller, begins process of reading
8                         nes_clock, // sent to controller, tells controller to start reading
9
10                        output logic nes_A, // A button output, active low
11                        nes_B, // B button output, active low
12                        nes_START, // START button output, active low
13                        nes_SELECT, // SELECT button output, active low
14                        nes_UP, // UP button output, active low
15                        nes_DOWN, // DOWN button output, active low
16                        nes_LEFT, // LEFT button output, active low
17                        nes_RIGHT, // RIGHT button output, active low
18
19                        output logic ready_to_read); // output telling system whether the module is ready to read
20
21
22 // Parameter
23 localparam NUM_BUTTONS = 8;
24
25 // Internal
26 logic [3:0] count = 3'b0000;
27 logic pause = 0;
28 logic next = 0;
29 logic apply = 0;
30 logic [NUM_BUTTONS-1:0] tmp_buttons = {NUM_BUTTONS{1'b1}};
31 logic [NUM_BUTTONS-1:0] prev_input = {NUM_BUTTONS{1'b1}};
32 logic tmp_ready = 0;
33
34 // Start reading process if latch, read until all buttons read, apply after
35 always_ff @(posedge in_clock, posedge read_data, posedge reset) begin
36
37     if (reset) begin
38         /* On reset, set to default values */
39
40         tmp_ready = 1;
41         nes_latch = 0;
42         nes_clock = 0;
43         tmp_buttons = {NUM_BUTTONS{1'b1}};
44         prev_input = {NUM_BUTTONS{1'b1}};
45         next = 0;
46         apply = 0;
47         count = 0;
48         tmp_ready = 1;
49
50     end
51     else if (read_data) begin
52         /* On start (read_data) if the system is ready to read (ready_to_read),
53          * send nes_latch signal to controller to start reading process, signal system
54          * is no longer ready to read, and set that it should read the next value. */
55
56         if (tmp_ready) begin
57             nes_latch = 1;
58             tmp_ready = 0;
59             count = 0;
60             tmp_buttons = {NUM_BUTTONS{1'b1}};
```

```

61           next          = 1;
62       end
63
64   end
65   else if (pause) begin
66     /* In between each read (after each [next] case where a button is read),
67      * either send the system to the apply state or to the next button read
68      * depending on if we have read all buttons; gives nes_clock time to be 0. */
69
70     next          = (count < NUM_BUTTONS);
71     nes_clock    = (count < NUM_BUTTONS);
72     apply         = ~(count < NUM_BUTTONS);
73     pause         = 0;
74
75   end
76   else if (next) begin
77     /* Read the next button and set its place in the tmp_button reg. */
78
79     // Set pulsed items to 0
80     nes_latch    = 0;
81     nes_clock    = 0;
82
83     // Read data into current button
84     tmp_buttons[count] = nes_data;
85
86     // Trigger next execution logic (pause)
87     pause = 1;
88
89     // Increment count
90     count = (count < NUM_BUTTONS) ? count + 1 : 0;
91
92   end
93   else if (apply) begin
94     /* Apply state, send out the buttons read so far by the decoder
95      * to prev_input to be sent to the outputs. */
96
97     prev_input    = tmp_buttons;
98     tmp_buttons  = {NUM_BUTTONS{1'b1}};
99     apply         = 0;
100    tmp_ready    = 1;
101
102  end
103
104 end
105
106 always_comb begin
107
108     nes_A          = prev_input[0];
109     nes_B          = prev_input[1];
110     nes_START      = prev_input[2];
111     nes_SELECT     = prev_input[3];
112     nes_UP         = prev_input[4];
113     nes_DOWN       = prev_input[5];
114     nes_LEFT       = prev_input[6];
115     nes_RIGHT      = prev_input[7];
116     ready_to_read  = tmp_ready;
117
118 end
119
120 endmodule

```

A.9 parsed_clock

A.9.1 Component Blocks of parsed_clock Unit

parser.sv

```
1 module parser #(parameter IN_BITS=30, TICK_PER_SEC=9537)
2     (input logic [IN_BITS-1:0] count,
3      output logic [IN_BITS-1:0] total_seconds,
4      output logic [3:0] seconds_ones,
5      output logic [3:0] seconds_tens,
6      output logic [3:0] minutes_ones,
7      output logic [3:0] minutes_tens,
8      output logic [3:0] hours_ones,
9      output logic [3:0] hours_tens);
10
11    reg [5:0] seconds;
12    reg [5:0] minutes;
13    reg [4:0] hours;
14
15    always_comb
16        begin
17            total_seconds = count / TICK_PER_SEC;
18
19            seconds = total_seconds % 60;
20            seconds_ones = seconds % 10;
21            seconds_tens = seconds / 10;
22
23            minutes = (total_seconds / 60) % 60;
24            minutes_ones = minutes % 10;
25            minutes_tens = minutes / 10;
26
27            hours = (total_seconds / 3600) % 24;
28            hours_ones = hours % 10;
29            hours_tens = hours / 10;
30        end
31
32    endmodule
```

comparator.sv

```
1 module comparator #(parameter N=30)
2     (input logic [N-1:0] a, b,
3      output logic eq, neq, lt, lte, gt, gte, agt24h);
4
5     assign eq = (a == b);
6     assign neq = (a != b);
7     assign lt = (a < b);
8     assign lte = (a <= b);
9     assign gt = (a > b);
10    assign gte = (a >= b);
11
12    assign agt24h = (a >= 24*3600);
13
14 endmodule
```

mux4.sv

```
1 // mux4 module
2
3 module mux4 #(parameter IN_WIDTH = 1) // Width of each input option
4
5     (input logic [3:0] [IN_WIDTH-1:0] in, // 4, 4-bit inputs (select 00, 01,
6      input logic [1:0] sel, // input sel that selects between
7      output logic [IN_WIDTH-1:0] out); // 4-bit output based on input sel
```

```

10 // Whenever an input or select changes, reassign output
11 always @ (in or sel) begin
12
13     out <= in[sel];
14
15 end
16
17 endmodule

```

counter.sv

```

1 module counter #(parameter N=30)
2             (input logic clk, reset, enable,
3              output logic [N-1:0] q);
4
5 always_ff@(posedge clk, posedge reset)
6 begin
7     if(reset)      q <= 0;
8     else if(enable) q <= q+1;
9 end
10
11 endmodule

```

A.10 SquareWaveGenerator

A.10.1 Component Blocks of SquareWaveGenerator Unit

decoder.sv

```
1 module decoder(input logic[7:0]a,
2                  output logic [2:0] y);
3
4     always_comb
5         case(a)
6             8'h1C: y = 3'b000;
7             8'h1B: y = 3'b001;
8             8'h23: y = 3'b010;
9             8'h2B: y = 3'b011;
10            8'h1D: y = 3'b100;
11            8'h24: y = 3'b101;
12            8'h2D: y = 3'b110;
13            8'h2C: y = 3'b111;
14            default: y = 3'bxxx;
15
16        endcase
17
18 endmodule
```

SquareWaveGenerator.sv

```
1 module SquareWaveGenerator(input logic clk,
2                             input logic [2:0] note,
3                             input logic en,
4                             input logic reset_n,
5                             output logic speaker);
6
7     logic tmp_clk;
8
9     logic [20:0] div_cnt, max_count;
10    /*initial begin
11        tmp_clk=0;
12        div_cnt=0;
13    end */
14
15    //select correct frequency based on input note
16    always_comb
17        begin
18
19            case (note)
20                3'b000: max_count = 95419; //C(middle)
21                3'b001: max_count = 85034; //D
22                3'b010: max_count = 75757; //E
23                3'b011: max_count = 71428; //F
24                3'b100: max_count = 63775; //G
25                3'b101: max_count = 56818; //A
26                3'b110: max_count = 50607; //B
27                3'b111: max_count = 47800; //C
28
29        endcase
30    end
31
32    always_ff @ (posedge(clk), negedge(reset_n), posedge(en))
33        begin
34            if (!reset_n)
35                begin
36                    tmp_clk <= 0;
37                    div_cnt <= 0;
38                end
39            else
39                begin
```

```
40      if (div_cnt >= max_count)
41          begin
42              tmp_clk <= ~tmp_clk;
43              div_cnt <= 21'b0;
44          end
45      else
46          div_cnt <= div_cnt + 1;
47      end
48      if (en) speaker <= tmp_clk;
49      else speaker <= 0;
50  end
51
52
53 endmodule
```

A.11 nes_to_motor

nes_to_motor.sv

```
1  module nes_to_motor (input logic      forward,
2                           backward,
3                           left,
4                           right,
5
6                           output logic     motor_1_on,
7                           motor_1_dir,
8                           motor_2_on,
9                           motor_2_dir);
10
11 // Internal (NO DOUBLE INPUTS)
12 logic int_forward = 0;
13 logic int_backward = 0;
14 logic int_left = 0;
15 logic int_right = 0;
16
17 always_comb begin
18
19     int_forward = forward && (forward ^ backward ^ left ^ right);
20     int_backward = backward && (forward ^ backward ^ left ^ right);
21     int_left = left && (forward ^ backward ^ left ^ right);
22     int_right = right && (forward ^ backward ^ left ^ right);
23
24     motor_1_on = int_left || int_right || int_forward || int_backward;
25     motor_1_dir = int_backward || int_left;
26
27     motor_2_on = int_left || int_right || int_forward || int_backward;
28     motor_2_dir = int_forward || int_left;
29
30 end
31
32
33 endmodule
```

A.12 Comparator

Comparator.sv

```
1  module Comparator #(parameter n = 23, m = 5000)
2           (input logic [n-1:0] a,
3            output logic eq);
4
5
6  assign eq = (a == m);
7
8 endmodule
```

A.13 DisplayDecoder

DisplayDecoder.sv

```
1 //Seven Segment Display Decoder
2 module DisplayDecoder(input logic [3:0] data,
3                       input logic out,
4                       output logic [6:0] segments);
5
6   always_comb
7     if(out) begin
8       case(data) // abc_defg
9         0: segments = 7'b100_0000;
10        1: segments = 7'b111_1001;
```

```
10          2: segments = 7'b010_0100;
11          3: segments = 7'b011_0000;
12          4: segments = 7'b001_1001;
13          5: segments = 7'b001_0010;
14          6: segments = 7'b000_0010;
15          7: segments = 7'b111_1000;
16          8: segments = 7'b000_0000;
17          9: segments = 7'b001_1000;
18      default: segments = 7'b111_1111;
19      endcase
20  end
21  else
22      segments = 7'b111_1111;
23 endmodule
```

B Simulation Files (Do Scripts)

This appendix will list the Do Scripts used to simulate each block used in the design project.

B.1 decoder

```
decoder_sim.do  
vsim work.decoder  
  
add wave a  
add wave y  
  
restart -f  
force a 00011100  
run 20 ns  
  
force a 00011011  
run 20 ns  
  
force a 00100011  
run 20 ns  
  
force a 00101011  
run 20 ns  
  
force a 00011101  
run 20 ns  
  
force a 00100100  
run 20 ns  
  
force a 00101101  
run 20 ns  
  
force a 00101100  
run 20 ns
```

B.2 seven_seg_6

```
seven_seg_6.do  
vsim design-project.seven_seg_6  
add wave -position insertpoint sim:/seven_seg_6/*  
  
force in0 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
force in1 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
force in2 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
force in3 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
force in4 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
force in5 10#0 25, 10#1 50, 10#2 75, 10#3 100, 10#4 125, 10#5 150, 10#6 175, 10#7 200  
  
run 275
```

B.2.1 Component Blocks of seven_seg_6 Unit

```
sevenseg.do  
vsim design-project.sevenseg  
add wave -position insertpoint sim:/sevenseg/*
```

```
force -freeze sim:/sevenseg/data 0000 0
run 50

force -freeze sim:/sevenseg/data 0001 0
run 50

force -freeze sim:/sevenseg/data 0010 0
run 50

force -freeze sim:/sevenseg/data 0011 0
run 50

force -freeze sim:/sevenseg/data 0100 0
run 50

force -freeze sim:/sevenseg/data 0101 0
run 50

force -freeze sim:/sevenseg/data 0110 0
run 50

force -freeze sim:/sevenseg/data 0111 0
run 50

force -freeze sim:/sevenseg/data 1000 0
run 50

force -freeze sim:/sevenseg/data 1001 0
run 50
```

B.3 L293D_encoder

```
L293D_encoder.do
vsim design-project.L293D_encoder

add wave -position insertpoint sim:/L293D_encoder/motor_1_on
add wave -position insertpoint sim:/L293D_encoder/motor_2_on

add wave -position insertpoint sim:/L293D_encoder/motor_1_dir
add wave -position insertpoint sim:/L293D_encoder/motor_2_dir

add wave -position insertpoint sim:/L293D_encoder/enable_1
add wave -position insertpoint sim:/L293D_encoder/input_1
add wave -position insertpoint sim:/L293D_encoder/input_2

add wave -position insertpoint sim:/L293D_encoder/enable_2
add wave -position insertpoint sim:/L293D_encoder/input_3
add wave -position insertpoint sim:/L293D_encoder/input_4

force -freeze motor_1_on    0 0, 1 100, 0 {300}
force -freeze motor_2_on    0 0, 1 100, 0 {300}
force -freeze motor_1_dir   0 0, 1 {200}
force -freeze motor_2_dir   0 0, 1 {200}

run 400
```

B.4 Counter

```
CounterTest.do
vsim work.Counter

add wave clk
add wave reset
add wave q

force clk 1 0, 0 50 {50 ns} -r 100
force reset 1 0, 0 10, 1 1000

run 1200
```

B.5 vga_encoder

B.5.1 Component Blocks of vga_encoder Unit

```
vga_640x480_sim.do
vsim work.vga_640x480

add wave clock_25
add wave reset_frame

add wave h_sync
add wave v_sync
add wave h_display
add wave v_display

restart -f
force clock_25 0 0, 1 {20ns} -r {40ns}
```

```

force reset_frame 0
run 10ns

force reset_frame 1
run 38400ns

clock_modulator_sim.do
vsim work.clock_modulator

add wave clock_in
add wave clock_out

restart -f
force clock_in 0 0, 1 {10 ns} -r 20ns
run 100ns

vga_640x480_sim_Vsync.do
vsim work.vga_640x480

add wave clock_25
add wave reset_frame

add wave h_sync
add wave v_sync
add wave h_display
add wave v_display

restart -f
force clock_25 0 0, 1 {20ns} -r {40ns}
force reset_frame 0
run 10ns

force reset_frame 1
run 18240000ns

color_mux_sim.do
vsim work.color_mux

add wave hdisplay
add wave vdisplay
add wave display_in
add wave blue_in
add wave green_in
add wave red_in

add wave blue_out
add wave green_out
add wave red_out

restart -f
force hdisplay 0
force vdisplay 0
force display_in 0

force blue_in 11
force green_in 11
force red_in 11
run 10ns

```

```

force hdisplay 1
run 10ns

force vdisplay 1
run 10ns

force hdisplay 0
run 10ns

force display_in 1
force hdisplay 0
force vdisplay 0
run 10ns

force hdisplay 1
run 10ns
force vdisplay 1
run 10ns
force hdisplay 0
run 10ns

rgb_decoder_sim.do
vsim work.rgb_decoder

add wave red_in
add wave green_in
add wave blue_in

add wave red_out
add wave green_out
add wave blue_out

restart -f
force red_in 00
force green_in 01
force blue_in 10
run 20ns

force red_in 01
force green_in 10
force blue_in 11
run 20ns

force red_in 00
force green_in 00
force blue_in 00
run 20ns

force red_in 11
force green_in 11
force blue_in 11
run 20ns

```

B.6 vcr_decoder

```
vcr_decoder_Sim_4.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 26010.0, 0 30236.0, 1 30982.999999999996, 0 32494.99999999999

run 90000

vcr_decoder_Sim_0.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 26001.999999999996, 0 30257.0, 1 31009.999999999996, 0 32500.99999999999

run 90000

vcr_decoder_Sim_3.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 25972.0, 0 30258.0, 1 31024.999999999996, 0 32520.99999999999

run 90000

vcr_decoder_Sim_1.do
vsim work.vcr_decoder
```

```

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 26005.999999999996, 0 30261.999999999996, 1 31042.999999999996

run 90000

vcr_decoder_Sim_9.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 25989.0, 0 30258.0, 1 30994.0, 0 32501.000000000004, 1 33250.000000000004

run 90000

vcr_decoder_Sim_5.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 25979.0, 0 30260.999999999996, 1 31010.999999999996, 0 32501.000000000004

run 90000

```

B.6.1 Component Blocks of vcr_decoder Unit

```

ReadState_Sim_2.do
vsim work.ReadState

add wave clk
add wave IR

```

```

add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 30982.999999999996, 0 32519.0, 1 33262.0, 0 33666.0, 1 34408.99999999999

run 90000

    ReadState_Sim_3.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31024.99999999996, 0 32520.99999999993, 1 33242.99999999999, 0 33666.0

run 90000

    ReadState_Sim_9.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 33269.0, 0 33664.0, 1 34434.99999999999, 0 34810.99999999999, 1 35578.0

run 90000

    shiftRegisterTest.do
vsim work.ShiftRegister

add wave clk
add wave sin
add wave q

force clk 1 0, 0 {50 ns} -r 100
force sin 1 0, 0 500, 1 1000

```

```

run 1500
    ReadState_Sim_8.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31016.0, 0 32518.0, 1 33296.0, 0 33664.0, 1 34456.0, 0 34807.0, 1 355

run 90000
    ReadState_Sim_7.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31017.999999999996, 0 32500.0, 1 33308.0, 0 33664.0, 1 34433.0, 0 34807.0

run 90000
    ReadState_Sim_0.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31009.999999999996, 0 32500.0, 1 33239.0, 0 33663.0, 1 34417.0, 0 34807.0

run 90000
    ReadState_Sim_4.do
vsim work.ReadState

```

```

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 30982.999999999996, 0 32494.999999999996, 1 33248.0, 0 33663.0, 1 3441

run 90000

      ReadState_Sim_5.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31010.999999999996, 0 32520.0, 1 33271.99999999999, 0 33667.0, 1 3441

run 90000

      signalDecoder.do
vsim work.SignalDecoder

add wave signal
add wave value

force signal 916E926D 0, 916E02FD 100, 916E827D 200, 916E62BD 300, 916EC23D 400, 916E2

run 1000

      ReadState_Sim_1.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31042.999999999996, 0 32500.0, 1 33287.0, 0 33668.0, 1 34448.0, 0 348

```

```

run 90000
    ReadState_Sim_6.do
vsim work.ReadState

add wave clk
add wave IR
add wave readSignal
add wave shiftValue
add wave state
add wave nextstate
add wave outputValue

force clk 1 0, 0 {50 ns} -r 100
force start 1 0

force IR 0 1, 1 31009.99999999996, 0 32520.99999999993, 1 33319.0, 0 33668.0, 1 344

run 90000
    vcr_decoder_Sim_7.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 26005.99999999996, 0 30237.0, 1 31017.99999999996, 0 325

run 90000
    vcr_decoder_Sim_6.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16899.9999999962, 1 25987.99999999996, 0 30239.99999999996, 1 31009

run 90000
    vcr_decoder_Sim_8.do
vsim work.vcr_decoder

```

```

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 26019.999999999996, 0 30258.0, 1 31016.0, 0 32518.0, 1 332

run 90000

vcr_decoder_Sim_2.do
vsim work.vcr_decoder

add wave clk_10KHz
add wave IR
add wave readControl
add wave readyToRead
add wave outputReadyadd wave state
add wave nextstate
add wave vcr_out

force clk 1 0, 0 {50 ns} -r 100
force stateReset 1 0, 0 100

force IR 1 0, 0 16901.0, 1 25990.0, 0 30239.0, 1 30982.999999999996, 0 32519.0, 1 332

run 90000

```

B.7 ps2_keyboard

```
ps2_keyboard_sim_3.do
vsim work.ps2_keyboard
# Do file for E

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {847 us}
force ps2_keyboard/ps2_data 0 @ {930 us}
force ps2_keyboard/ps2_data 1 @ {1099 us}
force ps2_keyboard/ps2_data 0 @ {1181 us}
force ps2_keyboard/ps2_data 1 @ {1350 us}

run 2000us

ps2_keyboard_sim.do
vsim work.ps2_keyboard
# Do file for A

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data
```

```

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {847 us}
force ps2_keyboard/ps2_data 0 @ {1097 us}
force ps2_keyboard/ps2_data 1 @ {1439 us}

run 2000us

```

B.7.1 Component Blocks of ps2_keyboard Unit

```

debounce_sim.do
vsim work.debounce

add wave clk
add wave button
add wave result

add wave flipflops

restart -f
force clk 0 0, 1 {10 ns} -r 20ns
force button 0
run 60 ns

force button 1
run 100 ns

```

```

force button 0
run 50ns
force button 1
run 50ns

ps2_keyboard_sim_5.do

vsim work.ps2_keyboard
# Do file for R

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {680 us}
force ps2_keyboard/ps2_data 0 @ {763 us}
force ps2_keyboard/ps2_data 1 @ {848 us}
force ps2_keyboard/ps2_data 0 @ {1014 us}
force ps2_keyboard/ps2_data 1 @ {1099 us}
force ps2_keyboard/ps2_data 0 @ {1181 us}
force ps2_keyboard/ps2_data 1 @ {1350 us}

run 2000us

ps2_keyboard_sim_2.do

vsim work.ps2_keyboard
# Do file for D

```

```

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {680 us}
force ps2_keyboard/ps2_data 0 @ {846 us}
force ps2_keyboard/ps2_data 1 @ {1097 us}
force ps2_keyboard/ps2_data 0 @ {1181 us}
force ps2_keyboard/ps2_data 1 @ {1432 us}

run 2000us

ps2_keyboard_sim_7.do
vsim work.ps2_keyboard
# Do file for T

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0

```

```

force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {847 us}
force ps2_keyboard/ps2_data 0 @ {1013 us}
force ps2_keyboard/ps2_data 1 @ {1097 us}
force ps2_keyboard/ps2_data 0 @ {1180 us}
force ps2_keyboard/ps2_data 1 @ {1430 us}

run 2000us

ps2_keyboard_sim_6.do
vsim work.ps2_keyboard
# Do file for S

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}

```

```

force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {680 us}
force ps2_keyboard/ps2_data 0 @ {846 us}
force ps2_keyboard/ps2_data 1 @ {929 us}
force ps2_keyboard/ps2_data 0 @ {1097 us}
force ps2_keyboard/ps2_data 1 @ {1350 us}

run 2000us

ps2_keyboard_sim_4.do
vsim work.ps2_keyboard
# Do file for F

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

```

```

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}
force ps2_keyboard/ps2_data 1 @ {680 us}
force ps2_keyboard/ps2_data 0 @ {846 us}
force ps2_keyboard/ps2_data 1 @ {932 us}
force ps2_keyboard/ps2_data 0 @ {1014 us}
force ps2_keyboard/ps2_data 1 @ {1099 us}
force ps2_keyboard/ps2_data 0 @ {1180 us}
force ps2_keyboard/ps2_data 1 @ {1350 us}

run 2000us

ps2_keyboard_sim_9.do
vsim work.ps2_keyboard
# Do file for W

add wave ps2_keyboard/clk
add wave ps2_keyboard/ps2_clk
add wave ps2_keyboard/ps2_data

add wave ps2_keyboard/ps2_code_new
add wave ps2_keyboard/ps2_code

restart -f
force ps2_keyboard/ps2_clk 1 @ 0
force ps2_keyboard/ps2_clk 0 @ {615us}
force ps2_keyboard/ps2_clk 1 @ {659us}
force ps2_keyboard/ps2_clk 0 @ {698us}
force ps2_keyboard/ps2_clk 1 @ {742us}
force ps2_keyboard/ps2_clk 0 @ {782us}
force ps2_keyboard/ps2_clk 1 @ {826us}
force ps2_keyboard/ps2_clk 0 @ {865us}
force ps2_keyboard/ps2_clk 1 @ {910us}
force ps2_keyboard/ps2_clk 0 @ {949us}
force ps2_keyboard/ps2_clk 1 @ {993us}
force ps2_keyboard/ps2_clk 0 @ {1033us}
force ps2_keyboard/ps2_clk 1 @ {1077us}
force ps2_keyboard/ps2_clk 0 @ {1117us}
force ps2_keyboard/ps2_clk 1 @ {1161us}
force ps2_keyboard/ps2_clk 0 @ {1200us}
force ps2_keyboard/ps2_clk 1 @ {1244us}
force ps2_keyboard/ps2_clk 0 @ {1284us}
force ps2_keyboard/ps2_clk 1 @ {1328us}
force ps2_keyboard/ps2_clk 0 @ {1367us}

force ps2_keyboard/ps2_clk 1 @ {1411us}
force ps2_keyboard/ps2_clk 0 @ {1451us}
force ps2_keyboard/ps2_clk 1 @ {1495us}

force -freeze sim:ps2_keyboard/clk 0 0, 1 {10 ns} -r 20ns

force ps2_keyboard/ps2_data 1 @ 0
force ps2_keyboard/ps2_data 0 @ {595 us}

```

```
force ps2_keyboard/ps2_data 1 @ {681 us}
force ps2_keyboard/ps2_data 0 @ {763 us}
force ps2_keyboard/ps2_data 1 @ {848 us}
force ps2_keyboard/ps2_data 0 @ {1097 us}
force ps2_keyboard/ps2_data 1 @ {1350 us}
```

```
run 2000us
```

B.8 nes_decoder

```
nes_decoder.do
vsim design-project.nes_decoder

add wave -position insertpoint sim:/nes_decoder/in_clock
add wave -position insertpoint sim:/nes_decoder/read_data
add wave -position insertpoint sim:/nes_decoder/reset
add wave -position insertpoint sim:/nes_decoder/nes_*
add wave -position insertpoint sim:/nes_decoder/ready_to_read
add wave -position insertpoint sim:/nes_decoder/count
add wave -position insertpoint sim:/nes_decoder/tmp_buttons
add wave -position insertpoint sim:/nes_decoder/prev_input
add wave -position insertpoint sim:/nes_decoder/pause
add wave -position insertpoint sim:/nes_decoder/next
add wave -position insertpoint sim:/nes_decoder/apply
add wave -position insertpoint sim:/nes_decoder/tmp_ready

force -freeze in_clock 1 0, 0 {25} -r 50
force -freeze nes_data 0 0, 1 250 -r 500
force -freeze read_data 0 0, 1 10, 0 {20}
force -freeze reset 1 0, 0 {10}

run 900
```

B.9 parsed_clock

```
parsed_clock.do
vsim design-project.parsed_clock

add wave -position insertpoint sim:/parsed_clock/clock_50MHz
add wave -position insertpoint sim:/parsed_clock/enable_in
add wave -position insertpoint sim:/parsed_clock/reset_in
add wave -position insertpoint sim:/parsed_clock/double_speed_in
add wave -position insertpoint sim:/parsed_clock/super_speed_in

add wave -position insertpoint sim:/parsed_clock/total_sec

add wave -position insertpoint sim:/parsed_clock/seconds_ones
add wave -position insertpoint sim:/parsed_clock/seconds_tens
add wave -position insertpoint sim:/parsed_clock/minutes_ones
add wave -position insertpoint sim:/parsed_clock/minutes_tens
add wave -position insertpoint sim:/parsed_clock/hours_ones
add wave -position insertpoint sim:/parsed_clock/hours_tens

force -freeze clock_50MHz 0 0, 1 1us -r {2us}
force -freeze enable_in 0 0, 1 1us, 0 {2us}
force -freeze reset_in 1 0, 0 {1us}

force -freeze double_speed_in 1 0, 0 50000000us, 1 75000000us, 0 {100000000us}
force -freeze super_speed_in 1 0, 0 75000000us

run 150000000us
```

B.9.1 Component Blocks of parsed_clock Unit

counter.do

```

vsim design-project.counter
add wave -position insertpoint sim:/counter/*
force -freeze sim:/counter/clk 0 0, 1 {25 ps} -r 50
force -freeze sim:/counter/reset 1 0 -cancel 50
force -freeze sim:/counter/enable 1 0 -cancel 100
run 100
force -freeze sim:/counter/enable 0 0 -cancel 50
run 50
force -freeze sim:/counter/enable 1 0
run 150

parser.do

vsim design-project.parser
add wave -position insertpoint sim:/parser/*
force -freeze sim:/parser/count 0 0
run 50

force -freeze sim:/parser/count 101000101111100011 0
run 50

force -freeze sim:/parser/count 10101110101000001011000 0
run 50

force -freeze sim:/parser/count 100000101111100010000100000 0
run 50

enable_flip_flop.do

vsim design-project.enable_flip_flop

add wave -position insertpoint sim:/enable_flip_flop/enable_in
add wave -position insertpoint sim:/enable_flip_flop/reset
add wave -position insertpoint sim:/enable_flip_flop/enable_out

force -freeze enable_in      0 0,      1 50      -r {100}
force -freeze reset          1 0,      0 {10}

run 400

delay.do

vsim design-project.delay
add wave -position insertpoint sim:/delay/clock_in
add wave -position insertpoint sim:/delay/enable
add wave -position insertpoint sim:/delay/reset
add wave -position insertpoint sim:/delay/double_speed
add wave -position insertpoint sim:/delay/super_speed
add wave -position insertpoint sim:/delay/select
add wave -position insertpoint sim:/delay/clock_option
add wave -position insertpoint sim:/delay/clock_out

force -freeze sim:/delay/clock_in 0 0, 1 {50 ps} -r 100
force -freeze sim:/delay/enable 1 0
force -freeze sim:/delay/reset 1 0 -cancel 200
force -freeze sim:/delay/double_speed 1 0, 0 25000, 1 50000, 0 {100000}
force -freeze sim:/delay/super_speed 1 0, 0 50000

run 200000

mux4.do

```

```
vsim design-project.mux4
add wave -position insertpoint sim:/mux4/*
force -freeze {in[0]} 0000 {0}
force -freeze {in[1]} 0011 {0}
force -freeze {in[2]} 1100 {0}
force -freeze {in[3]} 1111 {0}
force -freeze sel 00 0, 01 50, 10 100, 11 {150}
run 200
comparator.do
vsim design-project.comparator
add wave -position insertpoint sim:/comparator/*
force -freeze sim:/comparator/a 0 0
run 100
force -freeze sim:/comparator/a 0010101000110000000 0
run 100
force -freeze sim:/comparator/a 0010101000101111111 0
run 100
```

B.10 SquareWaveGenerator

B.10.1 Component Blocks of SquareWaveGenerator Unit

SquareWaveGenerator_sim.do

vsim work.SquareWaveGenerator

```
add wave clk  
add wave note  
add wave en  
add wave reset_n
```

```
add wave speaker
```

```
restart -f  
force clk 0 0, 1 {10 ns} -r 20ns  
force reset_n 0  
force en 1  
run 20ns
```

```
force reset_n 1  
force note 000  
run 3816793 ns
```

```
force note 001  
run 3401360 ns
```

```
force note 010  
run 3030303 ns
```

```
force note 011  
run 2857142 ns
```

```
force note 100  
run 2551020 ns
```

```
force note 101  
run 2272727 ns
```

```
force note 110  
run 2024291 ns
```

```
force note 111  
run 1912045 ns
```

decoder_sim.do

```
vsim work.decoder
```

```
add wave a  
add wave y
```

```
restart -f  
force a 00011100  
run 20 ns
```

```
force a 00011011  
run 20 ns
```

```
force a 00100011
```

```
run 20 ns  
force a 00101011  
run 20 ns  
force a 00011101  
run 20 ns  
force a 00100100  
run 20 ns  
force a 00101101  
run 20 ns  
force a 00101100  
run 20 ns
```

B.11 nes_to_motor

```
nes_to_motor.do  
vsim design-project.nes_to_motor  
add wave -position insertpoint sim:/nes_to_motor/forward  
add wave -position insertpoint sim:/nes_to_motor/backward  
add wave -position insertpoint sim:/nes_to_motor/left  
add wave -position insertpoint sim:/nes_to_motor/right  
add wave -position insertpoint sim:/nes_to_motor/motor_1_on  
add wave -position insertpoint sim:/nes_to_motor/motor_1_dir  
add wave -position insertpoint sim:/nes_to_motor/motor_2_on  
add wave -position insertpoint sim:/nes_to_motor/motor_2_dir  
  
force -freeze forward 1 0, 0 30, 1 {200}  
force -freeze backward 0 0, 1 50, 0 80, 1 {200}  
force -freeze left 0 0, 1 100, 0 130, 1 {200}  
force -freeze right 0 0, 1 150, 0 180, 1 {200}  
  
run 250
```

B.12 Comparator

```
ComparatorTest.do  
vsim work.Comparator  
  
add wave a  
add wave eq  
  
force a 32 0, 1388 100, 4999 200, 1388 300  
  
run 500
```

B.13 DisplayDecoder

```
DisplayDecoderTest.do  
vsim work.DisplayDecoder  
  
add wave data  
add wave segments  
  
force data 0 0, 1 100, 2 200, 3 300, 4 400, 5 500, 6 600, 7 700, 8 800, 9 900  
  
run 1000
```